

HW2

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Problem 1: Softmax

Using the definition of softmax, we know that $\hat{p}(y = c_1 | \mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x})}{\sum_{y=1}^2 \exp(\mathbf{w}_y \cdot \mathbf{x})}$ and

$\hat{p}(y = c_2 | \mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}_{c_2} \cdot \mathbf{x})}{\sum_{y=1}^2 \exp(\mathbf{w}_y \cdot \mathbf{x})}$. This allows to compute the log-odds in the as following:

$$\begin{aligned} \log\left(\frac{\hat{p}(y = c_1 | \mathbf{x}; \mathbf{W})}{\hat{p}(y = c_2 | \mathbf{x}; \mathbf{W})}\right) &= \log(\hat{p}(y = c_1 | \mathbf{x}; \mathbf{W})) - \log(\hat{p}(y = c_2 | \mathbf{x}; \mathbf{W})) \\ &= \log\left(\frac{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x})}{\sum_{y=1}^2 \exp(\mathbf{w}_y \cdot \mathbf{x})}\right) - \log\left(\frac{\exp(\mathbf{w}_{c_2} \cdot \mathbf{x})}{\sum_{y=1}^2 \exp(\mathbf{w}_y \cdot \mathbf{x})}\right) \\ &= \mathbf{w}_{c_1} \cdot \mathbf{x} - \log\left(\sum_{y=1}^2 \exp(\mathbf{w}_y \cdot \mathbf{x})\right) - \mathbf{w}_{c_2} \cdot \mathbf{x} + \log\left(\sum_{y=1}^2 \exp(\mathbf{w}_y \cdot \mathbf{x})\right) \\ &= \mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x} \\ &= \mathbf{w}_{c_1}^T \mathbf{x} - \mathbf{w}_{c_2}^T \mathbf{x} \\ &= (\mathbf{w}_{c_1}^T - \mathbf{w}_{c_2}^T) \mathbf{x} \\ &= \mathbf{v} \mathbf{x} \quad \text{where} \quad \mathbf{v} = \mathbf{w}_{c_1}^T - \mathbf{w}_{c_2}^T \end{aligned}$$

From this, we know that we can model the log-odds with the following linear function:

$$\log\left(\frac{\hat{p}(y = c_1|\mathbf{x}; \mathbf{W})}{\hat{p}(y = c_2|\mathbf{x}; \mathbf{W})}\right) = \mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x}$$

$$\frac{\hat{p}(y = c_1|\mathbf{x}; \mathbf{W})}{\hat{p}(y = c_2|\mathbf{x}; \mathbf{W})} = \exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})$$

$$\frac{\hat{p}(y = c_1|\mathbf{x}; \mathbf{W})}{1 - \hat{p}(y = c_1|\mathbf{x}; \mathbf{W})} = \exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})$$

$$\frac{1 - \hat{p}(y = c_1|\mathbf{x}; \mathbf{W})}{\hat{p}(y = c_1|\mathbf{x}; \mathbf{W})} = \frac{1}{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})}$$

$$\frac{1}{\hat{p}(y = c_1|\mathbf{x}; \mathbf{W})} = 1 + \frac{1}{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})}$$

$$\frac{1}{\hat{p}(y = c_1|\mathbf{x}; \mathbf{W})} = \frac{1 + \exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})}{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})}$$

$$\hat{p}(y = c_1|\mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})}{1 + \exp(\mathbf{w}_{c_1} \cdot \mathbf{x} - \mathbf{w}_{c_2} \cdot \mathbf{x})}$$

$$\hat{p}(y = c_1|\mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x})\exp(-\mathbf{w}_{c_2} \cdot \mathbf{x})}{1 + \exp(\mathbf{w}_{c_1} \cdot \mathbf{x})\exp(-\mathbf{w}_{c_2} \cdot \mathbf{x})}$$

$$\hat{p}(y = c_1|\mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x})}{\exp(\mathbf{w}_{c_1} \cdot \mathbf{x}) + \exp(\mathbf{w}_{c_2} \cdot \mathbf{x})}$$

Problem 2

To show that the softmax model as stated in (1) is *overparametrized* we can write the probabilities as follows:

$$p(y = 1|\mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}'_1)}{1 + \sum_{y=1}^{C-1} \exp(\mathbf{w}'_y \cdot \mathbf{x})}$$

where $\exp(\mathbf{w}'_i) = \exp(\mathbf{w}_i)\exp(-\mathbf{w}_C) \quad \forall i \neq C$ and

$$\exp(\mathbf{w}'_C) = \exp(\mathbf{w}_C)\exp(-\mathbf{w}_C) = 1$$

$$p(y = 2|\mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}'_2)}{1 + \sum_{y=1}^{C-1} \exp(\mathbf{w}'_y \cdot \mathbf{x})}$$

\vdots

$$p(y = C - 1|\mathbf{x}; \mathbf{W}) = \frac{\exp(\mathbf{w}'_{C-1})}{1 + \sum_{y=1}^{C-1} \exp(\mathbf{w}'_y \cdot \mathbf{x})}$$

Using the fact that the probabilities from 1 to C must sum to one, we get:

$$\begin{aligned} p(y = C|\mathbf{x}; \mathbf{W}) &= 1 - \sum_{c=1}^{C-1} p(y = c|\mathbf{x}; \mathbf{W}) \\ &= 1 - \frac{\sum_{c=1}^{C-1} \exp(\mathbf{w}'_c \cdot \mathbf{x})}{1 + \sum_{y=1}^{C-1} \exp(\mathbf{w}'_y \cdot \mathbf{x})} \\ &= \frac{1}{1 + \sum_{c=1}^{C-1} \exp(\mathbf{w}'_c \cdot \mathbf{x})} \end{aligned}$$

This expression shows that we can write $p(y = c|\mathbf{x}; \mathbf{W})$ for any c by using $C - 1$ parameter vectors, where we interpret each vector parameter as a difference with respect to our base category.

Problem 3

In order to show that \mathbf{H} is a positive definite matrix, we have to start with the solution of the maximum likelihood problem for the logistic regression

$$\operatorname{argmin}_{\mathbf{w}} \log p(\mathbf{y}|\mathbf{X}; \mathbf{w}) = - \sum_{i=1}^d y_i \log \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) + (1 - y_i) \log(1 - \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i))$$

$$\text{where } \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) = \frac{1}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}$$

It will be helpful to compute first the following derivatives:

$$\begin{aligned} \frac{\delta}{\delta w_0} \log \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) &= \frac{1}{\sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i)} \frac{\delta}{\delta w_0} \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) \\ &= \frac{(1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i))^{-2} \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}{(1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i))^{-1}} \\ &= \frac{\exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} \end{aligned}$$

$$\begin{aligned} \frac{\delta}{\delta w_j} \log \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) &= \frac{1}{\sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i)} \frac{\delta}{\delta w_j} \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) \\ &= \frac{\exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i) x_{ij}}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} \end{aligned}$$

$$\text{and define } \gamma_i \equiv \frac{1}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} = \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i).$$

Similarly,

$$\begin{aligned} \frac{\delta}{\delta w_0} \log(1 - \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i)) &= \frac{\delta}{\delta w_0} \log \left(\frac{\exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} \right) \\ &= \frac{\delta}{\delta w_0} \left[-w_0 - \mathbf{w} \cdot \mathbf{x}_i - \log(1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)) \right] \\ &= -1 - \frac{\exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} \\ &= -\frac{1}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} \\ &= -\gamma_i \end{aligned}$$

$$\begin{aligned}
\frac{\delta}{\delta w_j} \log(1 - \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i)) &= \frac{\delta}{\delta w_j} \log \left(\frac{\exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} \right) \\
&= \frac{\delta}{\delta w_j} \left[-w_0 - \mathbf{w} \cdot \mathbf{x}_i - \log(1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)) \right] \\
&= -x_{ij} - \frac{\exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} x_{ij} \\
&= -\frac{x_{ij}}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)} \\
&= -\gamma_i x_{ij}
\end{aligned}$$

Now, taking the derivatives with respect to w_0 and w_j in our original function, we get:

$$\begin{aligned}
\frac{\delta}{\delta w_0} \log p(\mathbf{y}|\mathbf{X}; \mathbf{w}) &= - \sum_{i=1}^d y_i \frac{\delta}{\delta w_0} \log \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) + (1 - y_i) \frac{\delta}{\delta w_0} \log(1 - \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i)) = 0 \\
&= - \sum_{i=1}^d y_i (1 - \gamma_i) + (1 - y_i)(-\gamma_i) = 0 \\
&= - \sum_{i=1}^d y_i - \gamma_i = 0 \\
&= \sum_{i=1}^d \gamma_i - y_i = 0
\end{aligned}$$

$$\begin{aligned}
\frac{\delta}{\delta w_j} \log p(\mathbf{y}|\mathbf{X}; \mathbf{w}) &= - \sum_{i=1}^d y_i \frac{\delta}{\delta w_j} \log \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i) + (1 - y_i) \frac{\delta}{\delta w_j} \log(1 - \sigma(w_0 + \mathbf{w} \cdot \mathbf{x}_i)) = 0 \\
&= - \sum_{i=1}^d (y_i - \gamma_i) x_{ij} = 0 \\
&= \sum_{i=1}^d (\gamma_i - y_i) x_{ij} = 0
\end{aligned}$$

We can rewrite all the derivatives different from w_0 in matrix notation considering the following:

$$\boldsymbol{\gamma} = \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_3 \\ \vdots \\ \gamma_d \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_d \end{pmatrix}, \quad \mathbf{X} = \begin{pmatrix} x_{11} & x_{12} & \cdots & x_{1d} \\ x_{21} & x_{22} & \cdots & x_{2d} \\ x_{31} & x_{32} & \cdots & x_{3d} \\ \vdots & \ddots & \ddots & \vdots \\ x_{d1} & x_{d2} & \cdots & x_{dd} \end{pmatrix}$$

Therefore, the gradient for our problem becomes $\nabla L = \frac{\delta}{\delta \mathbf{w}} \log p(\mathbf{y}|\mathbf{X}; \mathbf{w}) = (\boldsymbol{\gamma} - \mathbf{y})^T \mathbf{X}$, which is equivalent to $\nabla L = \mathbf{X}^T (\boldsymbol{\gamma} - \mathbf{y})$.

Now, we want to compute the second derivatives with respect to some $w_k \neq w_j$. Before continuing, it will be useful to compute $\frac{\delta}{\delta w_k} \gamma_i$. We know from our previous calculations that

$$\frac{\delta}{\delta w_k} \log \gamma_i = (1 - \gamma_i) x_{ik}.$$

We also know that, in general, $\delta \log x = \frac{\delta x}{x}$, which implies that $\delta x = x \delta \log x$.

Therefore, $\frac{\delta}{\delta w_k} \gamma_i = \gamma_i (1 - \gamma_i) x_{ik}$.

With this information, the second derivative with respect to w_k becomes:

$$\begin{aligned} \frac{\delta^2}{\delta w_j \delta w_k} \log p(\mathbf{y}|\mathbf{X}; \mathbf{w}) &= \sum_{i=1}^d \frac{\delta}{\delta w_k} \gamma_i x_{ij} \\ &= \sum_{i=1}^d \gamma_i (1 - \gamma_i) x_{ik} x_{ij} \quad \text{this is a quadratic form} \\ &= \mathbf{a}_k^T \mathbf{R} \mathbf{a}_j > 0 \end{aligned}$$

where $\mathbf{a}_k = [x_{1k}, x_{2k}, \dots, x_{dk}]^T$,

$$\mathbf{R} = \begin{pmatrix} \gamma_1(1 - \gamma_1) & 0 & 0 & \cdots & 0 \\ 0 & \gamma_2(1 - \gamma_2) & 0 & \cdots & 0 \\ 0 & 0 & \gamma_3(1 - \gamma_3) & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \gamma_d(1 - \gamma_d) \end{pmatrix}$$

Here, \mathbf{a}_k and \mathbf{a}_j represent columns of our matrix \mathbf{X} . In particular, the expression $\mathbf{a}_k^T \mathbf{R} \mathbf{a}_j$ gives us the derivative for the k th- j th entry. Thus, the Hessian matrix can be expressed as $\mathbf{H} = \mathbf{X}^T \mathbf{R} \mathbf{X}$.

To incorporate the constant, we only have to take the dimensions into account as follows

$$\underset{(d+1) \times (d+1)}{\mathbf{H}} = \underset{(d+1) \times d}{\mathbf{X}^T} \times \underset{d \times d}{\mathbf{R}} \times \underset{d \times (d+1)}{\mathbf{X}}$$

One way of showing that \mathbf{H} is positive definite is to rewrite it as $\mathbf{H} = \mathbf{A}^T \mathbf{A}$ for some matrix \mathbf{A} with independent columns.

The first step to show this is to make sure that all the entries in \mathbf{R} , $\gamma_i(1 - \gamma_i)$, are greater than zero.

Recall that $\gamma_i = \frac{1}{1 + \exp(-w_0 - \mathbf{w} \cdot \mathbf{x}_i)}$, which implies that $0 \leq \gamma_i \leq 1$ and $0 \leq (1 - \gamma_i) \leq 1$, so $0 \leq \gamma_i(1 - \gamma_i) \leq 1$. This means that we can take the square root of all the elements in \mathbf{R} and rewrite the Hessian as follows

$$\mathbf{H} = \mathbf{X}^T \mathbf{R}^{1/2} \mathbf{R}^{1/2} \mathbf{X} \quad \text{since } \mathbf{R}^{1/2} \text{ is a diagonal matrix it is true that } \mathbf{R}^{1/2} = (\mathbf{R}^{1/2})^T \\ = (\mathbf{R}^{1/2} \mathbf{X})^T (\mathbf{R}^{1/2} \mathbf{X})$$

Given that the columns of $\mathbf{R}^{1/2}$ are linearly independent, then, by definition, any linear combination of the columns is independent, in particular $\mathbf{R}^{1/2} \mathbf{X}$. Therefore, the matrix \mathbf{H} is a positive definite matrix.

Finally, we can use the Newton-Raphson method to approximate the log-loss function around a minimum

$$\begin{aligned} \mathbf{w}_{t+1} &= \mathbf{w}_t + \mathbf{H}^{-1} \frac{\delta}{\delta \mathbf{w}} \log p(X; \mathbf{w}) \\ &= \mathbf{w}_t + (\mathbf{X}^T \mathbf{R} \mathbf{X})^{-1} \mathbf{X}^T (\boldsymbol{\gamma} - \mathbf{y}) \\ &= (\mathbf{X}^T \mathbf{R} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{R} (\mathbf{X} \mathbf{w}_t + \mathbf{R}^{-1} (\boldsymbol{\gamma} - \mathbf{y})) \\ &= (\mathbf{X}^T \mathbf{R} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{R} \mathbf{z}_t \\ &\quad \text{where } \mathbf{z}_t = (\mathbf{X} \mathbf{w}_t + \mathbf{R}^{-1} (\boldsymbol{\gamma} - \mathbf{y})) \end{aligned}$$

The solution for \mathbf{w}_{t+1} looks very similar to the optimal solution to least squares problem. In fact, it can be shown that it is the optimal solution for the following problem:

$$\underset{\mathbf{w}}{\operatorname{argmin}} = \sum_{i=1}^d \gamma_i (1 - \gamma_i) (z_i - \mathbf{w} \cdot \mathbf{x}_i)^2$$

Therefore, in each iteration we are computing the global minimum given that the loss function for this problem is convex.

Problem 4

In this problem, we will represent the label for y_i by an indicator vector t_i . For example, if t_1 refers to $c = 1$, then $t_1^T = [1, 0, \dots, 0]$.

Therefore, t_i represents a basis vector for a class c , containing a 1 at the j th position and 0 elsewhere. These vectors will be useful later to compute the derivatives.

Before we continue, let's define \hat{p}_i as a vector of probabilities for the i th row as $\hat{p}_i = \hat{p}(y_i | \mathbf{x}_i; \mathbf{W})$ and $a_i = \mathbf{w}_i \cdot \mathbf{x}_i$. This last definition allows us to rewrite the softmax model as follows:

$$\hat{p}(y_i = c|\mathbf{x}_i; \mathbf{W}) \frac{\exp(a_c)}{\sum_{y=1}^C \exp(a_y)}$$

We have to rewrite now our cost function in terms of the log-loss as follows

$$\begin{aligned} \mathbf{W}^* = \operatorname{argmin}_{\mathbf{W}} J(\mathbf{x}_i, y_i, \mathbf{W}) &= -\frac{1}{N} \sum_{i=1}^N t_i \log \hat{p}(y_i|\mathbf{x}_i; \mathbf{W}) + \lambda \sum_i \sum_j \mathbf{w}_{ij}^2 \\ &= -\frac{1}{N} \sum_{i=1}^N t_i \log \hat{p}_i + \lambda \sum_i \sum_j \mathbf{w}_{ij}^2 \end{aligned}$$

First, let's take the derivative of the log-loss function \mathbf{J} with respect to \hat{p}_i .

$$\begin{aligned}
(1) \quad \frac{\delta J}{\delta \hat{p}_i} &= -\frac{1}{N} \frac{t_i}{\hat{p}_i} \\
(2) \quad \frac{\delta \hat{p}_i}{\delta a_k} &= \begin{cases} \frac{\exp(a_i)}{\sum_{y=1}^C \exp(a_y)} - \left(\frac{\exp(a_i)}{\sum_{y=1}^C \exp(a_y)} \right)^2 & \text{if } i = k \\ -\frac{\exp(a_i)\exp(a_k)}{\left(\sum_{y=1}^C \exp(a_y) \right)^2} & \text{if } i \neq k \end{cases} \\
&= \begin{cases} \hat{p}_i(1 - \hat{p}_i) & \text{if } i = k \\ \hat{p}_i\hat{p}_k & \text{if } i \neq k \end{cases} \\
(3) \quad \frac{\delta J}{\delta a_i} &= \sum_{k=1}^C \frac{\delta J}{\delta \hat{p}_k} \frac{\delta \hat{p}_k}{\delta a_i} \\
&= \frac{\delta J}{\delta \hat{p}_i} \frac{\delta \hat{p}_i}{\delta a_i} - \sum_{k \neq i} \frac{\delta J}{\delta \hat{p}_k} \frac{\delta \hat{p}_k}{\delta a_i} \\
&= -\frac{1}{N} \frac{t_i}{\hat{p}_i} \hat{p}_i(1 - \hat{p}_i) + \frac{1}{N} \sum_{k \neq i} \frac{t_k}{\hat{p}_k} \hat{p}_k \hat{p}_i \\
&= -\frac{1}{N} t_i(1 - \hat{p}_i) + \frac{1}{N} \sum_{k \neq i} t_k \hat{p}_i \\
&= -\frac{1}{N} t_i(1 - \hat{p}_i) + \frac{1}{N} \hat{p}_i \sum_{k \neq i} t_k \\
&= \frac{1}{N} \left[\hat{p}_i \sum_{k \neq i} t_k - t_i(1 - \hat{p}_i) \right] \\
&= \frac{1}{N} \left[\hat{p}_i \left(\sum_{k \neq i} t_k + t_i \right) - t_i \right] \\
&= \frac{1}{N} \left[\hat{p}_i \left(\sum_k t_k \right) - t_i \right] \quad \text{where } \sum_k t_k = 1 \\
&= \frac{1}{N} \left[\hat{p}_i - t_i \right]
\end{aligned}$$

$$\begin{aligned}
 (4) \quad \frac{\delta J}{\delta w_{ij}} &= \sum_{i=1}^N \frac{\delta J}{\delta a_i} \frac{\delta a_i}{\delta w_{ij}} + \lambda \sum_i \sum_j \frac{\delta}{\delta w_{ij}} w_{ij}^2 \\
 &= \frac{1}{N} \sum_{i=1}^N \left[\hat{p}_i - t_i \right] \frac{\delta a_i}{\delta w_{ij}} + 2\lambda w_{ij} \\
 &= \frac{1}{N} \sum_{i=1}^N \left[\hat{p}_i - t_i \right] x_{ij} + 2\lambda w_{ij} \\
 &= \frac{1}{N} \sum_{i=1}^N \left[\hat{p}_i - t_i \right] x_{ij} + 2\lambda \sum_{i=1}^N w_{ij} \\
 &= \frac{1}{N} (\mathbf{X}^T (\hat{\mathbf{p}} - \mathbf{t})) + 2\lambda \mathbf{W} \mathbf{t}_i \\
 &= \frac{1}{N} (\mathbf{X}^T (\hat{\mathbf{p}} - \mathbf{t})) + 2\lambda \mathbf{w}_i
 \end{aligned}$$

$$\hat{\mathbf{p}} = \begin{pmatrix} \hat{p}_{11} & \hat{p}_{12} & \cdots & \hat{p}_{1C} \\ \hat{p}_{21} & \hat{p}_{22} & \cdots & \hat{p}_{2C} \\ \hat{p}_{31} & \hat{p}_{32} & \cdots & \hat{p}_{3C} \\ \vdots & \ddots & \ddots & \vdots \\ \hat{p}_{N1} & \hat{p}_{N2} & \cdots & \hat{p}_{NC} \end{pmatrix}, \quad \mathbf{t} = \begin{pmatrix} t_{11} & t_{12} & \cdots & t_{1C} \\ t_{21} & t_{22} & \cdots & t_{2C} \\ t_{31} & t_{32} & \cdots & t_{3C} \\ \vdots & \ddots & \ddots & \vdots \\ t_{N1} & t_{N2} & \cdots & t_{NC} \end{pmatrix}, \quad \mathbf{X} = \begin{pmatrix} x_{11} & x_{12} & \cdots & x_{1N} \\ x_{21} & x_{22} & \cdots & x_{2N} \\ x_{31} & x_{32} & \cdots & x_{3N} \\ \vdots & \ddots & \ddots & \vdots \\ x_{N1} & x_{N2} & \cdots & x_{NN} \end{pmatrix}$$

$$\mathbf{W} = \begin{pmatrix} w_{11} & w_{12} & \cdots & w_{1N} \\ w_{21} & w_{22} & \cdots & w_{2N} \\ w_{31} & w_{32} & \cdots & w_{3N} \\ \vdots & \ddots & \ddots & \vdots \\ w_{N1} & w_{N2} & \cdots & w_{NN} \end{pmatrix}$$

Therefore, we can write the equation for the stochastic gradient descent as follows

$$\mathbf{w}_{t+1} = \eta_t \frac{1}{N} (\mathbf{X}^T (\hat{\mathbf{p}} - \mathbf{t})) + 2\lambda \mathbf{w}_t$$