

9. Exercise sheet to Experimental Physics (WS 20/21)

Names: Joshua Detrois, Leo Knapp, Juan Provencio

Group: F

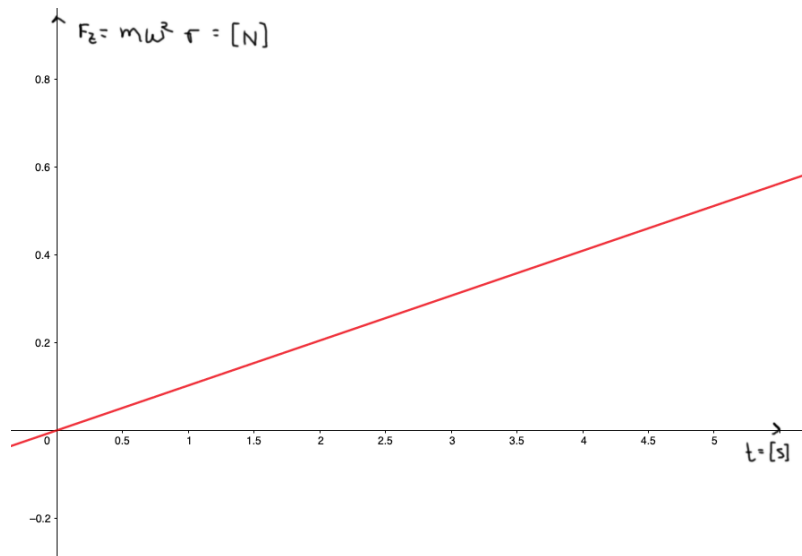
Points: ____/____/____ Σ ____

9.1 Exercise 1

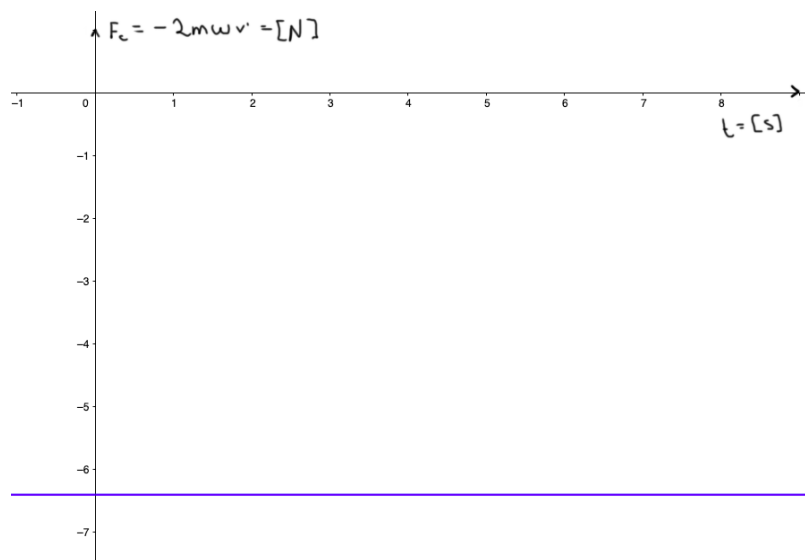
Given:

- $R = 5 \text{ m}$
- $\omega = 0.2 \text{ rad s}^{-1} \approx 0.032 \text{ s}^{-1}$
- $m = 100 \text{ kg}$
- $v' = 1 \text{ m s}^{-1}$
- $I = [0 \text{ s}, 5 \text{ s}]$

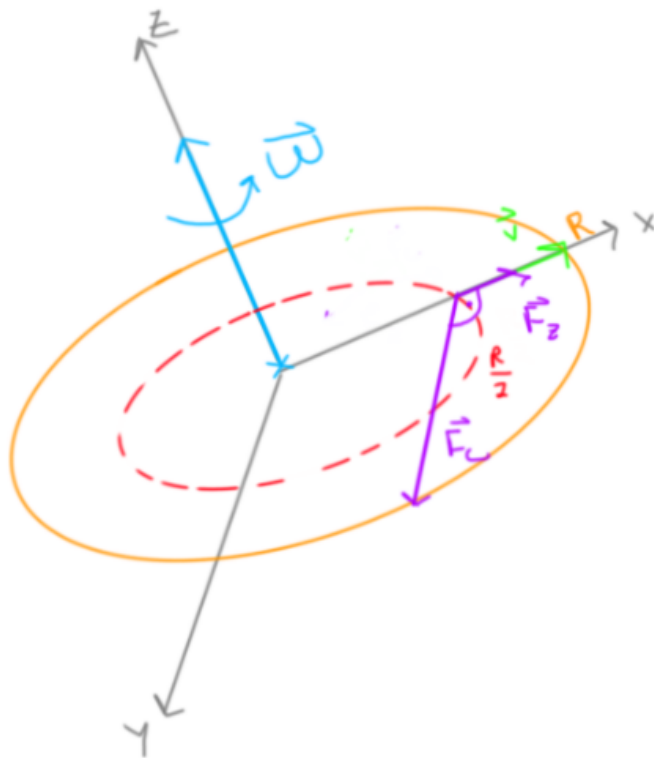
a) Sketch:



b) Sketch:



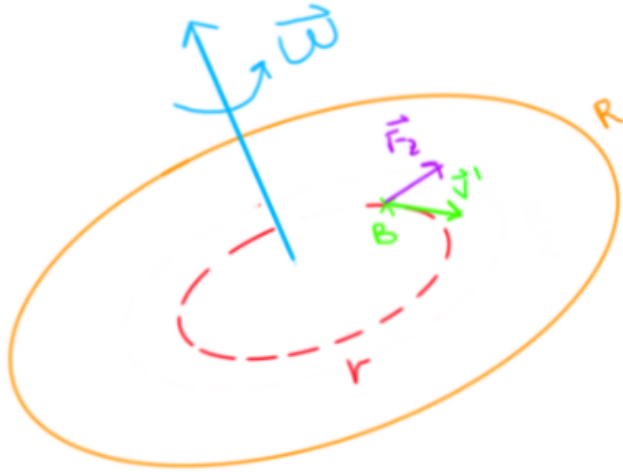
c) Sketch:



Given:

- $m = 50$ kg
- $r = 2$ m
- $v' = 0.4$ m s⁻¹

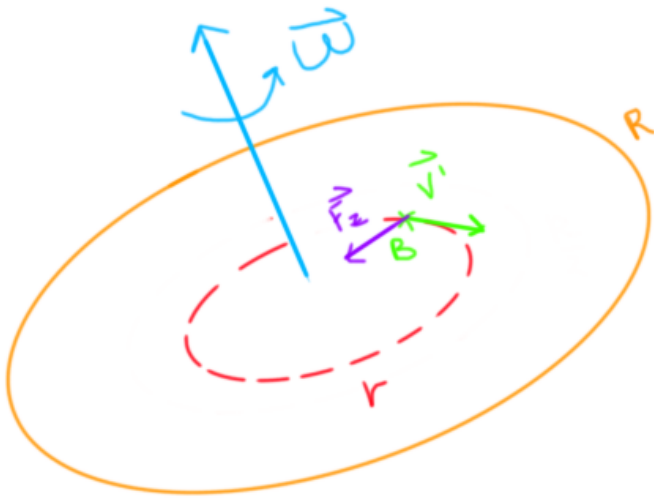
d) Sketch:



e)

$$F_z = \frac{mv'^2}{r} \quad (1)$$

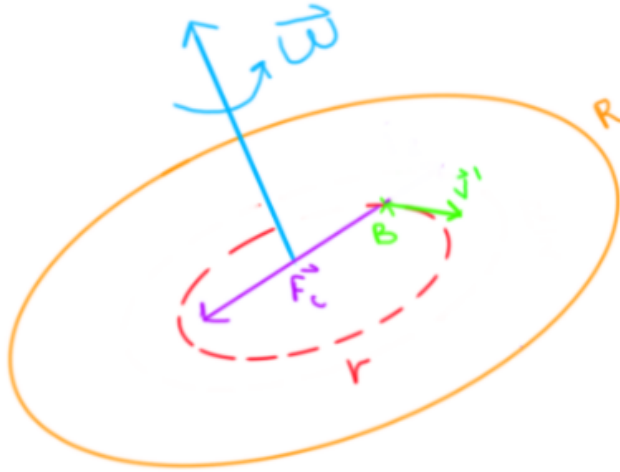
$$= 4 \text{ N} \quad (2)$$



f) Since we know the angle between the velocity and the angular velocity, we can use the formula:

$$\vec{F}_C = -2m\omega v' \quad (3)$$

$$= -8 \text{ N} \quad (4)$$



- g) From B's point of view, there's a total force of -4 N pulling him towards the center, since a part of the Coriolis Force counters the centrifugal force. However, for an observer outside of that frame of reference, it appears that Person B is walking with an angular velocity of $w' = \frac{v'}{r} = 0.2 \text{ s}^{-1}$ against the angular velocity of the spinning system, so it would appear that B is stationary and there are no forces acting upon them.

9.2 Exercise 2

Given.:

- $\mu > 0$

To solve this problem, we can use the fact that the angular momentum is preserved to solve this problem.

But first let's take a look at the forces involved here:

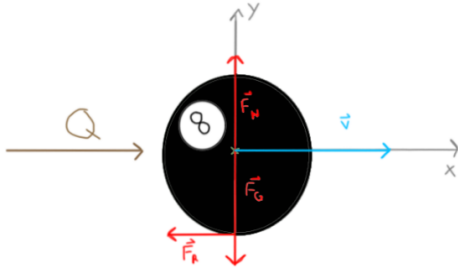
The vertical forces cancel each other out, so we know that

$$\sum F_y = 0 \quad (5)$$

$$F_g + F_N = 0 \quad (6)$$

$$F_g = -F_N \quad (7)$$

$$(8)$$



But there is a force acting against the movement of the ball, namely the friction against the table:

$$\sum F_x \neq 0 \quad (9)$$

$$ma = F_R \quad (10)$$

$$ma = \mu F_N \quad (11)$$

$$ma = -\mu mg \quad (12)$$

We can say that both at the beginning after the ball's been hit and at the end when it comes to a constant velocity without gliding, the angular momentum must be equal, so we use the formula:

$$L_0 = L_1 \quad (13)$$

$$rp = I\omega \quad (14)$$

$$rmv_0 = \frac{Iv_1}{r} \quad (15)$$

So that this condition is valid, we have to be able to use

$$\omega = \frac{v}{r} \quad (16)$$

which only happens when the ball isn't gliding anymore. Therefore, we need to calculate the time it takes the ball to stop gliding:

We know:

$$v = v_0 + at \quad | \quad a = -\mu g \quad (17)$$

$$v = v_0 - \mu gt \quad (18)$$

We also know that the sum of the torque is

$$\sum M = I\alpha \quad | \quad M = Fh \quad (19)$$

$$F = \mu mgr \quad (20)$$

$$I = \frac{2mr^2}{5} \quad (21)$$

$$\mu mgr = I\alpha \quad (22)$$

$$\mu mgr = \frac{2mr^2}{5}\alpha \quad (23)$$

$$\mu g = \frac{2r}{5}\alpha \quad (24)$$

$$\alpha = \frac{5\mu g}{2r} \quad (25)$$

In the next step, we can use this value for α to calculate the angular velocity of the ball, which we know to be

$$\omega = \omega_0 + \alpha t \quad | \quad \omega_0 = 0 \quad (26)$$

$$\omega = \frac{5\mu g}{2r}t \quad (27)$$

Now we can determine when the previously mentioned condition is valid:

$$\omega = \frac{v}{r} \quad (28)$$

$$\frac{5\mu g}{2r}t = \frac{v_0 - \mu gt}{r} \quad (29)$$

$$\mu g \left(\frac{5}{2} + 1 \right) t = v_0 \quad (30)$$

$$t = \frac{v_0}{\mu g \left(\frac{5}{2} + 1 \right)} \quad (31)$$

If we enter this time into our velocity, we get

$$v_1 = v_0 - at \quad (32)$$

$$= v_0 - \mu g \frac{v_0}{\mu g \left(\frac{5}{2} + 1 \right)} \quad (33)$$

$$= v_0 - \frac{2v_0}{7} \quad (34)$$

$$= \frac{5v_0}{7} \quad (35)$$

9.3 Exercise 3

a) Given:

- $M = -\kappa_D \varphi$
- $\kappa_D = \frac{\pi G R^4}{2L}$

- $T = 2\pi\sqrt{\frac{L}{g}}$

We know that

$$M = I\alpha \quad (36)$$

$$= I\ddot{\varphi} \quad (37)$$

So we get the equation of motion in relation to the angle φ :

$$I\ddot{\varphi} = -\kappa_D\varphi \quad (38)$$

$$\ddot{\varphi} = -\frac{\kappa_D\varphi}{I} \quad (39)$$

For the period length, we can use

$$L\ddot{\varphi} = g\varphi \quad (40)$$

$$\ddot{\varphi} = \frac{g\varphi}{L} \quad (41)$$

If we input these into our formula for the period length, we get

$$T = 2\pi\sqrt{\frac{L}{g}} \quad (42)$$

$$= 2\pi\sqrt{\frac{I}{\kappa_D}} \quad (43)$$

b) Given:

- $d = 2 \text{ mm}$
- $R = 1 \text{ mm}$
- $L = 2 \text{ m}$
- $D = 10 \text{ cm}$
- $r = 5 \text{ cm}^1$
- $h = 7 \text{ cm}$
- $\rho_{Fe} = 7.85 \text{ cm}^{-3}$
- $T = 1.86 \text{ s}$
- $m = \rho_{Fe}\pi r^2 h$

¹the choice of lowercase r is for convenience, since the exercise sheet already defined the Radius of the wire to be capital R

To calculate the shear modulus, we can substitute our value κ_D in the equation for the period length we just derived and solve for G

$$T = 2\pi \sqrt{\frac{I}{\kappa_D}} \quad (44)$$

$$= 2\pi \sqrt{\frac{I}{\frac{\pi G R^4}{2L}}} \quad (45)$$

$$\frac{T}{2\pi} = \sqrt{\frac{I}{\frac{\pi G R^4}{2L}}} \quad (46)$$

$$\left(\frac{T}{2\pi}\right)^2 = \frac{I}{\frac{\pi G R^4}{2L}} \quad (47)$$

$$\left(\frac{T}{2\pi}\right)^2 \frac{1}{2L} = \frac{I}{\pi G R^4} \quad (48)$$

$$\left(\frac{T}{2\pi}\right)^2 \frac{\pi R^4}{2LI} = \frac{1}{G} \quad (49)$$

$$G = \left(\frac{2\pi}{T}\right)^2 \frac{2LI}{\pi R^4} \quad (50)$$

By resubstituting the moment of inertia of the spinning cylinder $I = \frac{mr^2}{2}$, we get

$$G = \left(\frac{2\pi}{T}\right)^2 \frac{2Lmr^2}{2\pi R^4} \quad (51)$$

$$= \left(\frac{2\pi}{T}\right)^2 \frac{L\rho_{Fe}\pi r^2 h r^2}{\pi R^4} \quad (52)$$

$$= \left(\frac{2\pi}{T}\right)^2 \frac{L\rho_{Fe}r^4 h}{R^4} \quad (53)$$

$$= 7.84 \cdot 10^6 \text{ Pa} \quad (54)$$

c) Given:

- $D = 10 \text{ cm}$
- $R = 5 \text{ cm}$
- $L = 10 \text{ cm}$
- $\omega = 50\pi \text{ s}^{-1}$

For a rotating motion the power is

$$P = M\omega \quad (55)$$

and the torque given in the exercise is

$$M = -\kappa_D \varphi \quad (56)$$

Therefore, the angle is

$$\varphi = \frac{-M}{\kappa_D} \quad (57)$$

$$= \frac{-P}{\omega \kappa_D} \quad (58)$$

$$= \frac{-P}{\omega \frac{\pi G R^4}{2L}} \quad (59)$$

$$= \frac{-P 2L}{\omega \pi G R^4} \quad (60)$$

$$\approx 2.4 \text{ rad} \approx 137^\circ \quad (61)$$