view_frames Result Recorded at time: 75.665 odom Broadcaster: /gazebo Average rate: 10.204 Hz Most recent transform: 75.659 (0.006 sec old) Buffer length: 4.900 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (75.665 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (75.665 sec old) Most recent transform: 75.600 (0.065 sec old) Most recent transform: 75.600 (0.065 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 4.900 sec right_wheel left_wheel Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (75.665 sec old) Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (75.665 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (75.665 sec old)
Buffer length: 0.000 sec

camera_rgbd_frame

tower

Broadc

Average rate: 10000.000 Hz

Most recent transform: 0.000 (75.665 sec old)
Buffer length: 0.000 sec