

p -OBOP models of *Optimizing Weak Orders via MILP*

Juan A. Aledo, Concepción Domínguez, Juan de Dios Jaime-Alcántara, Mercedes Landete

Abstract

This supplementary material analyses the computational behaviour of two mixed-integer programming models for the p -OBOP introduced in the article *Optimizing Weak Orders via MILP*. We report detailed results for assignment-based and representative-based formulations, focusing on solving times and optimality gaps for different instances and values of p . In addition, we provide a counterexample showing that the sequence of optimal values of the p -OBOP as a function of p is not necessarily unimodal.

1 Comparison of p -OBOP models

This section analyses the computational behaviour of two families of equivalent mixed-integer programming formulations for the p -OBOP. On the one hand, we consider the formulations derived from model (2), which are based on assigning each item to exactly one of the p buckets. On the other hand, we study the formulations obtained from model (3), which rely on selecting representatives to define the bucket structure. Although all variants model the same optimisation problem, they differ in the structural constraints they incorporate and in whether certain binary variables are relaxed to the continuous domain $[0, 1]$.

Before presenting the results, we recall that the base ordering inequalities used throughout the analysis are:

$$x_{rs} + x_{sr} \geq 1 \quad \forall r, s \in [[n]] : r < s, \quad (1a)$$

$$x_{rs} + x_{st} \leq 1 + x_{rt} \quad \forall r, s, t \in [[n]] : r \neq s \neq t \neq r. \quad (1b)$$

1.1 Variants of the assignment-based model

The formulation of interest is the following:

$$\min f(\Pi, \mathbf{x}) \quad (2a)$$

$$\text{s.t. } \sum_{u=1}^p y_{ru} = 1 \quad \forall r \in [[n]], \quad (2b)$$

$$\sum_{r=1}^n y_{ru} \geq 1 \quad \forall u \in [[p]], \quad (2c)$$

$$y_{ru} + y_{su} \leq x_{rs} + x_{sr} \quad \forall r < s, \forall u, \quad (2d)$$

$$x_{sr} + \sum_{v=1}^u y_{rv} + \sum_{v=u+1}^p y_{sv} \leq 2 \quad \forall r \neq s, \forall u \in [[p-1]], \quad (2e)$$

$$x_{rs} \in \{0, 1\} \quad \forall r \neq s, \quad (2f)$$

$$y_{ru} \in \{0, 1\} \quad \forall r, u. \quad (2g)$$

Table 1 summarises the computational results for the variants obtained by augmenting model (2) with the base inequalities (1a) and (1b), as well as by optionally relaxing the binary variables \mathbf{x} to the continuous domain $[0, 1]$.

Instance	n	m	p	(2)		(2) + (1a)		(2) + (1b)		(2) + (1a) + (1b)		(2) + Relax \mathbf{x}		(2) + (1a) + Relax \mathbf{x}		(2) + (1b) + Relax \mathbf{x}		(2) + (1a) + (1b) + Relax \mathbf{x}	
				Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap
ED-10-02	51	9	2	4.59	0.00	10.01	0.00	1124.23	0.00	38.99	0.00	9.35	0.00	11.34	0.00	2680.83	0.00	3066.90	0.00
ED-10-03	54	10	2	5.19	0.00	7.83	0.00	1054.20	0.00	14.57	0.00	9.91	0.00	10.97	0.00	3202.51	0.00	3600	3.53
ED-10-11	50	11	2	7.39	0.00	9.85	0.00	1051.74	0.00	22.82	0.00	13.58	0.00	12.63	0.00	3486.87	0.00	3600	4.17
ED-10-14	62	15	2	8.90	0.00	9.85	0.00	3161.16	0.00	22.62	0.00	22.10	0.00	21.25	0.00	3600	117.32	3600	116.52
ED-10-15	52	14	2	8.23	0.00	10.66	0.00	1578.47	0.00	33.63	0.00	11.31	0.00	15.43	0.00	3600	14.23	3600	14.68
ED-15-20	122	4	2	25.31	0.00	22.16	0.00	3600	249.02	3600	25.44	2417.31	0.00	3600	4.97	3600	—	3600	—
ED-15-21	96	4	2	3.76	0.00	2.38	0.00	3600	278.45	3212.55	0.00	147.83	0.00	124.00	0.00	3600	—	3600	—
ED-15-22	112	4	2	6.06	0.00	4.28	0.00	3600	248.51	3600	44.75	325.79	0.00	976.62	0.00	3600	—	3600	—
ED-15-23	142	4	2	9.98	0.00	6.73	0.00	3600	285.59	3600	42.92	1398.02	0.00	1114.80	0.00	3600	—	3600	—
ED-15-24	91	4	2	3.16	0.00	1.83	0.00	3600	363.25	2169.20	0.00	63.17	0.00	142.08	0.00	3600	—	3600	—
ED-10-02	51	9	5	3600	269.43	3600	127.69	3600	84.64	42.90	0.00	3600	273.35	3600	198.51	3600	404.79	3600	229.71
ED-10-03	54	10	5	3600	208.06	3600	107.92	3600	175.98	160.25	0.00	3600	208.06	3600	182.37	3600	336.39	3600	368.91
ED-10-11	50	11	5	3600	198.60	3600	126.83	3600	70.60	11.42	0.00	3600	197.32	3600	225.44	3600	221.34	3600	272.88
ED-10-14	62	15	5	3600	286.95	3600	132.28	3600	87.52	3600	0.15	3600	266.93	3600	268.48	3600	457.14	3600	315.48
ED-10-15	52	14	5	3600	199.46	3600	90.75	3600	74.91	3015.40	0.00	3600	200.31	3600	187.88	3600	412.97	3600	279.67
ED-15-20	122	4	5	3600	763.11	3600	119.42	3600	84.80	3600	0.59	3600	763.11	3600	795.55	3600	—	3600	—
ED-15-21	96	4	5	3600	356.73	3600	26.36	3600	87.69	3600	8.64	3600	356.73	3600	337.02	3600	—	3600	213017.65
ED-15-22	112	4	5	3600	430.48	3600	23.40	3600	—	3600	11.16	3600	429.15	3600	394.22	3600	—	3600	—
ED-15-23	142	4	5	3600	741.91	3600	91.94	3600	88.04	3600	16.56	3600	741.91	3600	621.63	3600	—	3600	—
ED-15-24	91	4	5	3600	259.77	3600	28.21	3600	114.81	1342.87	0.00	3600	277.02	3600	280.64	3600	—	3600	330337.37

Table 1: Comparison of model (2) variants for the p -OBOP. The term “Relax \mathbf{x} ” denotes the relaxation of binary variables \mathbf{x} to the continuous domain $[0, 1]$.

As shown in Table 1, although all formulations are equivalent from a modeling perspective, their computational behavior varies considerably. The inclusion of additional structural constraints strongly influences both solving time and solution quality. In particular, the formulation that combines the transitivity constraints with the before-or-after constraints without relaxing the binary variables \mathbf{x} achieves the best overall performance. This variant consistently provides exact solutions within reasonable computation times, demonstrating a favorable balance between model strength and numerical efficiency in the resolution of the p -OBOP.

1.2 Variants of the representative-based model

Recall that the model is the following:

$$\min f(\Pi, \mathbf{x}) \quad (3a)$$

$$\text{s.t. } (1a) - (1b) \quad (3b)$$

$$\sum_{r=1}^n \alpha_r = p \quad (3c)$$

$$\beta_{rs} \leq \alpha_s \quad \forall r, s \in [[n]] : r < s, \quad (3d)$$

$$\sum_{s=r+1}^n \beta_{rs} + \alpha_r = 1 \quad \forall r \in [[n]], \quad (3e)$$

$$x_{rs} \geq \beta_{rs} \quad \forall r, s \in [[n]] : r < s, \quad (3f)$$

$$x_{sr} \geq \beta_{rs} \quad \forall r, s \in [[n]] : r < s, \quad (3g)$$

$$x_{rs} + x_{sr} + \alpha_r \leq 2 \quad \forall r, s \in [[n]] : r < s, \quad (3h)$$

$$x_{rs} \in \{0, 1\} \quad \forall r, s \in [[n]] : r \neq s, \quad (3i)$$

$$\alpha_r \in \{0, 1\} \quad \forall r \in [[n]], \quad (3j)$$

$$\beta_{rs} \in \{0, 1\} \quad \forall r, s \in [[n]] : r < s. \quad (3k)$$

We also considered the following valid inequality:

$$\beta_{rs} + \alpha_s \leq x_{rs} + x_{sr} \quad \forall r < s. \quad (4)$$

Including inequality (4) and removing constraints (3f) and (3g) yields an alternative formulation of the problem that is equivalent to the original one.

Building on these results, a second set of experiments was conducted to evaluate the impact of specific inequalities on the performance of model (3). In this case, the objective is to determine which combinations or substitutions of inequalities lead to stronger formulations and faster convergence.

Instance	<i>n</i>	<i>m</i>	<i>p</i>	(3)		(3) – (3f) – (3g) + (4)		(3) + (4)	
				Time	Gap	Time	Gap	Time	Gap
ED-10-02	51	9	2	995.41	0.00	1016.43	0.00	493.93	0.00
ED-10-03	54	10	2	196.27	0.00	869.89	0.00	366.32	0.00
ED-10-11	50	11	2	10.56	0.01	182.56	0.00	11.66	0.00
ED-10-14	62	15	2	11.27	0.00	21.31	0.00	12.07	0.00
ED-10-15	52	14	2	781.46	0.00	1172.56	0.00	889.97	0.00
ED-15-20	122	4	2	3600	23.02	3600	87.40	3600	23.02
ED-15-21	96	4	2	3600	32.54	3600	69.36	3600	29.61
ED-15-22	112	4	2	3600	37.40	3600	41.68	3600	37.41
ED-15-23	142	4	2	3600	–	3600	111.18	3600	23.15
ED-15-24	91	4	2	3600	32.42	3600	62.11	3600	61.43
ED-10-02	51	9	5	51.86	0.01	323.51	0.01	302.15	0.01
ED-10-03	54	10	5	6.01	0.00	47.08	0.00	34.54	0.00
ED-10-11	50	11	5	5.93	0.00	27.07	0.00	34.78	0.00
ED-10-14	62	15	5	11.00	0.00	71.60	0.00	66.62	0.00
ED-10-15	52	14	5	7.70	0.01	43.33	0.01	35.95	0.01
ED-15-20	122	4	5	3600	0.11	3600	3.40	3600	0.07
ED-15-21	96	4	5	3600	1.26	3600	2.75	3600	2.13
ED-15-22	112	4	5	3600	9.12	3600	98.29	3600	7.91
ED-15-23	142	4	5	3600	23.25	3600	46.12	3600	22.27
ED-15-24	91	4	5	95.49	0.00	3600	2.63	230.99	0.00
ED-10-02	51	9	20	3600	15.46	1015.58	0.00	433.73	0.00
ED-10-03	54	10	20	3600	4.59	860.85	0.00	342.96	0.00
ED-10-11	50	11	20	3600	15.78	181.26	0.00	21.13	0.00
ED-10-14	62	15	20	3600	0.60	21.28	0.00	12.96	0.00
ED-10-15	52	14	20	3600	10.19	1400.03	0.00	883.35	0.00
ED-15-20	122	4	20	3600	52.28	3600	87.40	3600	23.02
ED-15-21	96	4	20	2145.80	0.04	3600	69.36	3600	29.61
ED-15-22	112	4	20	3600	37.40	3600	41.68	3600	37.41
ED-15-23	142	4	20	3600	–	3600	111.18	3600	23.15
ED-15-24	91	4	20	3600	32.42	3600	62.11	3600	61.43

Table 2: Comparison of model (3) variants for the *p*-OBOP.

From Table 2, we observe that the inclusion of additional inequalities can substantially enhance the model’s performance, particularly for smaller values of *p*. In general, the strengthened formulations improve convergence and reduce the optimality gap, confirming the positive impact of incorporating well-chosen valid inequalities. Together with the previous analysis, these findings provide valuable insight into which modelling strategies, both in terms of constraint structure and variable relaxation,

yield the most effective formulations for the p -OBOP.

2 Behaviour of the p -OBOP model

A natural question arises as to whether the existence of optimal solutions for two distinct numbers of buckets implies the existence of an optimal solution for every intermediate number of buckets. The following example demonstrates that this property does not necessarily hold.

Example 1. Consider the following instance of the OBOP with 4 items, whose pairwise order matrix is shown in Figure 1.

$$\frac{1}{100} \begin{pmatrix} 50 & 55 & 90 & 100 \\ 45 & 50 & 20 & 80 \\ 10 & 80 & 50 & 65 \\ 0 & 20 & 35 & 50 \end{pmatrix}$$

Figure 1: Pairwise order matrix used in Example 1.

Solving this instance with model (2) for values of p ranging from 1 to 4 yields the optimal values shown in Figure 2.

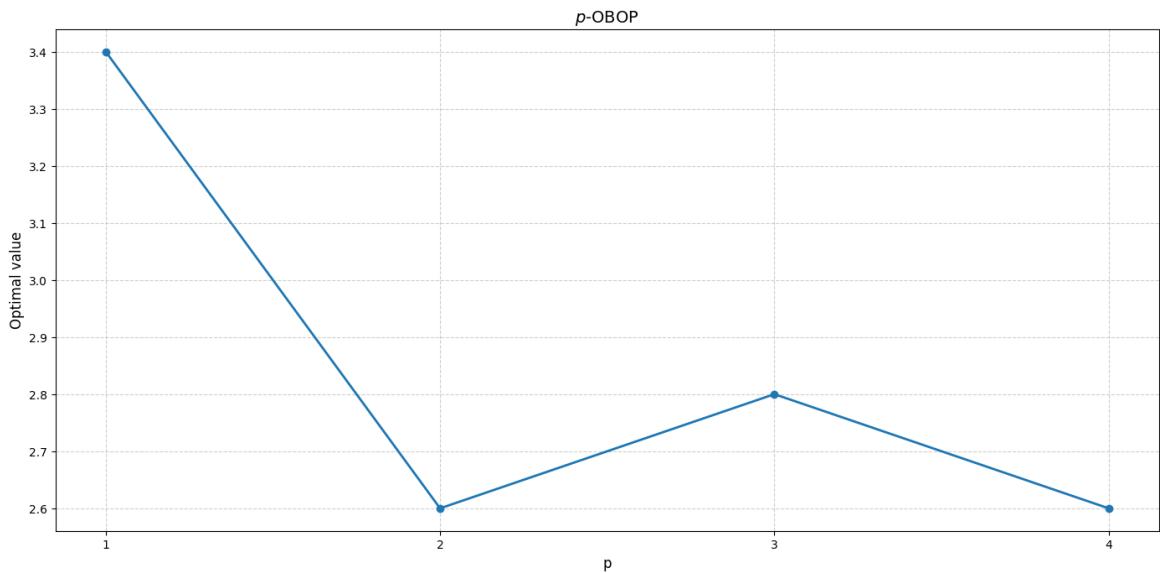


Figure 2: Optimal values of the p -OBOP for different values of p

This example illustrates that the curve of optimal values for the p -OBOP as a function of p is not necessarily unimodal. In particular, the existence of optimal solutions for $p = n - 1$ and $p = n + 1$ does not imply the existence of one for $p = n$.