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Algorithm 1: MS-MFS, as implemented in CASA
      Data: calibrated visibilities: V_{\nu}^{\text{obs}} \forall \nu
      Data: uv-sampling function and weights: [S_v], [W_v^{im}]
      Data: input: number of Taylor-terms N_t, number of scales N_s
      Data: input: image noise threshold, \sigma_{\text{thr}}, loop gain g
      Data: input: scale basis functions: I_s^{\text{shp}} \forall s \in \{0, N_s - 1\}
      Data: input: reference frequency v_0 to compute w_v = \left(\frac{v - v_0}{v_0}\right)
      Result: model coefficient images: I_t^m \ \forall t \in \{0, N_t - 1\}
      Result: intensity, spectral index and curvature: I_{v_0}^{m}, I_{\alpha}^{m}, I_{\beta}^{m}
  1 for t \in \{0, N_t - 1\}, q \in \{t, N_t - 1\} do
             Compute the spectral Hessian kernel I_{tq}^{psf} = \sum_{\nu} w_{\nu}^{t+q} I_{\nu}^{psf}
             for s \in \{0, N_s - 1\}, p \in \{s, N_s - 1\} do
 3
                    Compute scale-spectral kernels I_{sp}^{psf} = I_s^{shp} \star I_p^{shp} \star I_{tq}^{psf}
 5
             end
 6 end
 7 for s \in \{0, N_s - 1\} do
             Construct [\mathsf{H}_s^{\mathrm{peak}}] from mid(I_{s,s}^{\mathrm{psf}}) and compute [\mathsf{H}_s^{\mathrm{peak}^{-1}}]
10 Initialize the model I_t^{\text{m}} for all t \in \{0, N_t - 1\}
                                                                               /* Major Cycle */
11 repeat
             for t \in \{0, N_t\text{-}1\} do
12
                    Compute I_t^{\text{res}} = \sum_{\nu} w_{\nu}^t I_{\nu}^{\text{res}} from residual visibilities V_{\nu}^{\text{res}}
13
                    for s \in \{0, N_s-1\} do
14
                           Convolve with sth scale-function I_s^{\text{res}} = I_s^{\text{shp}} \star I_t^{\text{res}}
15
                    end
16
             end
17
             Calculate minor-cycle threshold f_{\text{limit}} from I_0^{\text{res}}
18
                                                                               /* Minor Cycle */
19
                    for s \in \{0, N_s-1\} do
20
                            foreach pixel do
21
                                   Construct I_s^{\text{rhs}}, an N_t \times 1 vector from I_s^{\text{res}} \ \forall \ t \in \{0, N_t\text{-}1\}
22
                                   Compute principal solution I_s^{\text{sol}} = [H_s^{\text{peak}^{-1}}]I_s^{\text{rhs}}
23
                                   Fill solution I_s^{\text{sol}} into model images \forall t: I_s^{\text{m,sol}}
24
25
                            end
                           Choose I_{p\atop t}^{m} = max\{I_{s\atop t=0}^{m,sol}, \forall s \in \{0, N_s-1\}\}
26
27
                    for t \in \{0, N_{\rm t} - 1\} do
28
                           Update the model image: I_t^{\text{m}} = I_t^{\text{m}} + g \left[ I_p^{\text{shp}} \star I_p^{\text{m}} \right]
29
                            for s \in \{0, N_s-1\} do
30
                                   Update the residual image: I_{\substack{s \ t}}^{\text{res}} = I_{\substack{s \ t}}^{\text{res}} - g \sum_{q=0}^{N_t-1} [I_{\substack{sp \ tq}}^{\text{psf}} \star I_{\substack{p \ t}}^{\text{m}}]
31
                           end
32
33
                    end
             until Peak residual in I_0^{\text{res}} < f_{\text{limit}}
34
             Compute model visibilities V_{\nu}^{\text{m}} from I_{t}^{\text{m}} \ \forall t \in \{0.N_{\text{t}} - 1\}
35
             Compute residual visibilities V_{\nu}^{\text{res}} = V_{\nu}^{\text{obs}} - V_{\nu}^{\text{m}}
36
37 until Peak residual in I_0^{\rm res} < \sigma_{\rm thr}
38 Restore the model Taylor-coefficients I_t^m \ \forall t \in \{0.N_t - 1\}
39 Calculate I_{v_0}^m, I_{\alpha}^m, I_{\beta}^m from I_t^m \ \forall t \in \{0.N_t - 1\}
40 If required, remove average primary beam: I_{\nu_0}^{\text{new}} = I_{\nu_0}^{\text{m}}/P_{\nu_0}; I_{\alpha}^{\text{new}} = I_{\alpha}^{\text{m}} - P_{\alpha}; I_{\beta}^{\text{new}} = I_{\beta}^{\text{m}} - P_{\beta}
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