

Gaussian Processes: An Introduction for Beginners

Juan José Giraldo Gutierrez

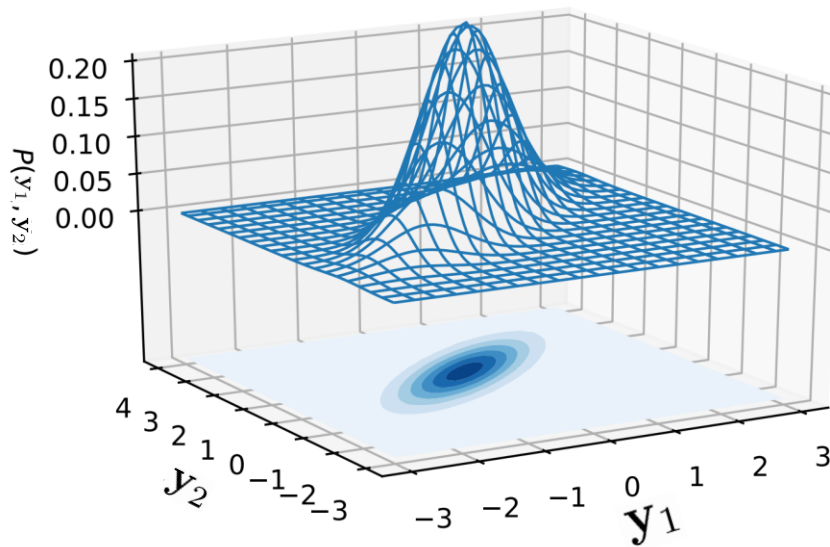
National Heart and Lung Institute
Imperial College London

Imperial College
London

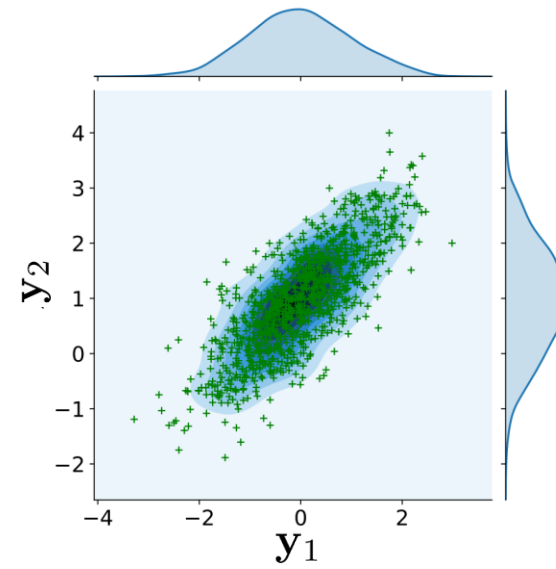


Multivariate Gaussian Distribution

$$\mathcal{N}(\mathbf{y}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{N/2}|\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{y} - \boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1}(\mathbf{y} - \boldsymbol{\mu})\right)$$



(a) 3-d bell curve

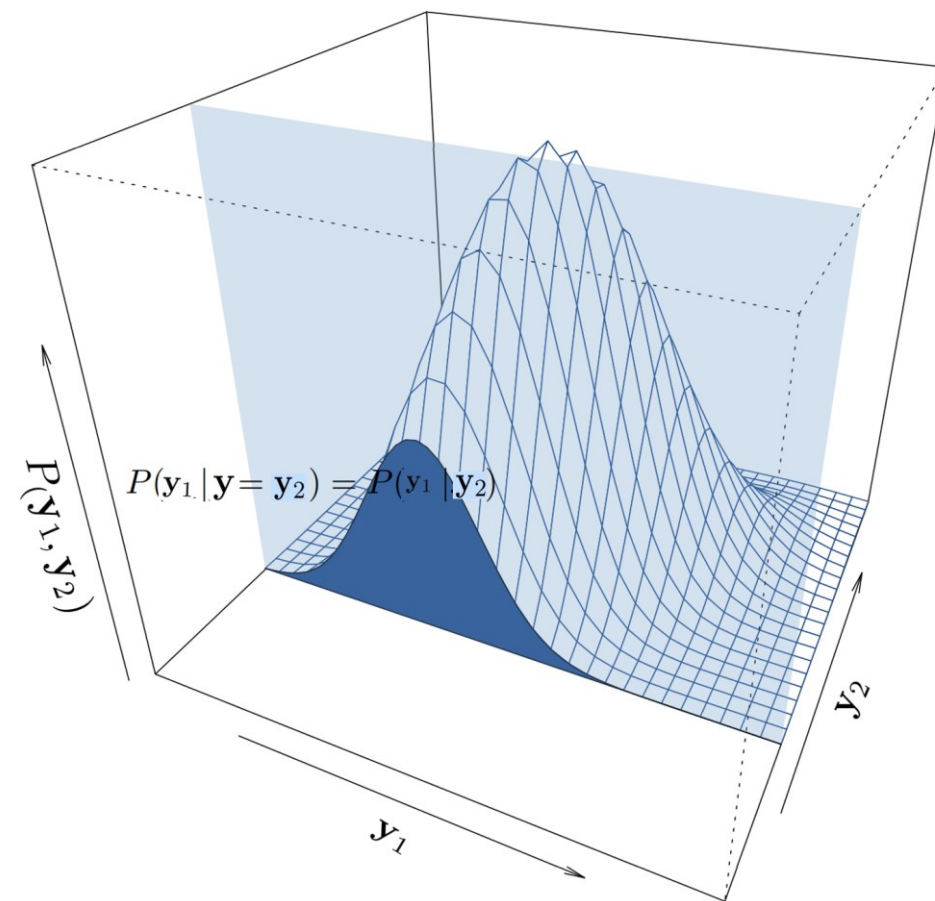


(b) 2-d ellipse contours

Conditioning Properties of a Gaussian Distribution

$$\mathcal{N} \left(\begin{bmatrix} \mathbf{y}_1 \\ \mathbf{y}_2 \end{bmatrix} \mid \begin{bmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{bmatrix}, \begin{bmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{bmatrix} \right)$$

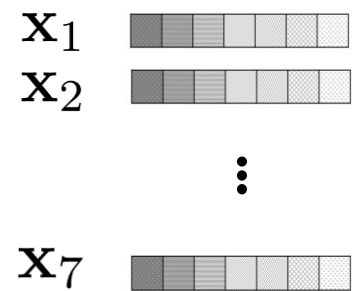
$$\mathcal{N}(\mathbf{y}_2 \mid \boldsymbol{\mu}_2 + \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} (\mathbf{y}_1 - \boldsymbol{\mu}_1), \boldsymbol{\Sigma}_{22} - \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} \boldsymbol{\Sigma}_{21}^{\top})$$



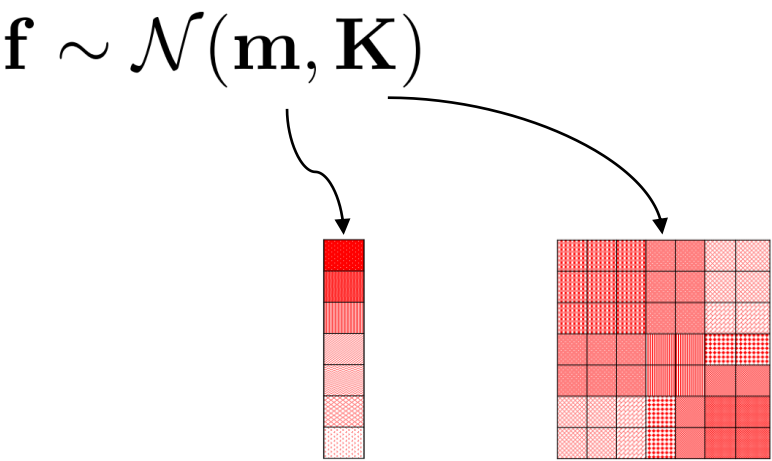
Gaussian Process

$$f(\mathbf{x}) \sim \mathcal{GP}(m(\mathbf{x}), k(\mathbf{x}, \mathbf{x}'))$$

If we evaluate a finite number
input observations:



We would end up with a
Multivariate Gaussian Distribution:



Bayesian Theorem for a Probabilistic Model

$$\underbrace{p(\mathbf{f}|\mathbf{y}, X)}_{\text{Posterior}} \propto \underbrace{p(\mathbf{y}|\mathbf{f}, X)}_{\text{Likelihood}} \underbrace{p(\mathbf{f}|X)}_{\text{Prior}}$$

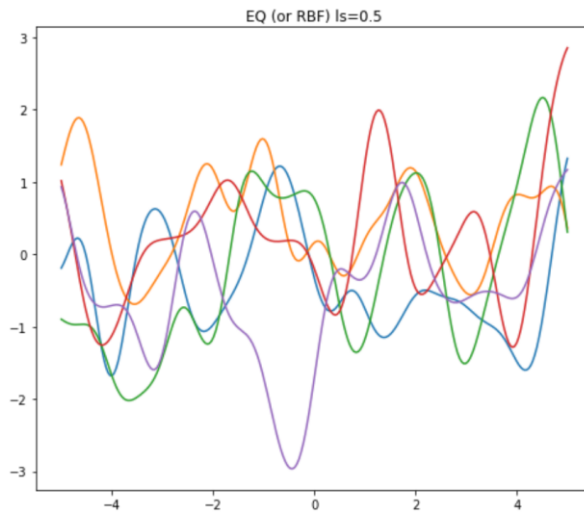
$$p(\mathbf{y}|\mathbf{f}, X) = \mathcal{N}(\mathbf{f}, \sigma_n^2 I) \quad p(\mathbf{f}|X) = \mathcal{N}(\mathbf{0}, K)$$

The Covariance (or Kernel) Matrix

$$p(\mathbf{f}|X) = \mathcal{N}(\mathbf{0}, K) \quad \text{where} \quad K := K(X, X)$$

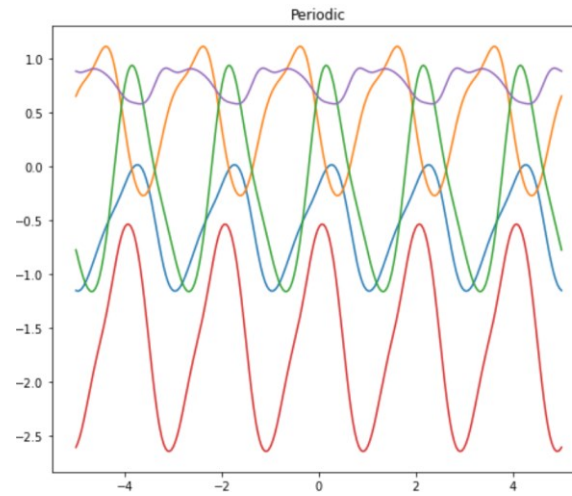
Exponentiated Quadratic

$$k(\mathbf{x}, \mathbf{x}') = \exp\left(-\frac{\|\mathbf{x} - \mathbf{x}'\|^2}{2\ell^2}\right)$$



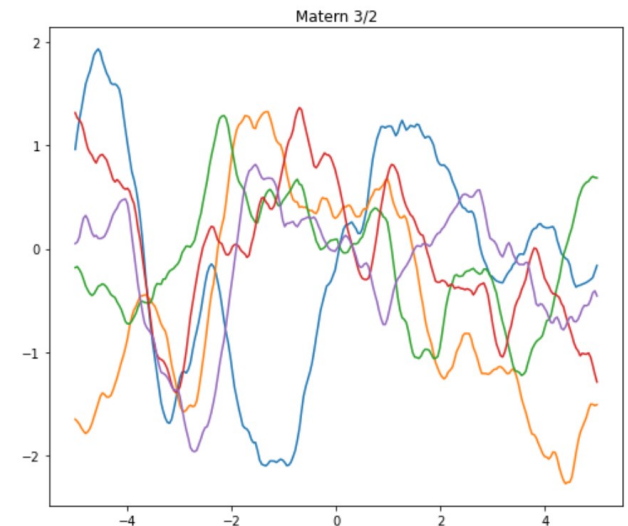
Periodic

$$k(\mathbf{x}, \mathbf{x}') = \exp\left(-\frac{2 \sin^2\left(\frac{\|\mathbf{x} - \mathbf{x}'\|}{2}\right)}{\ell^2}\right)$$



Matérn

$$k(\mathbf{x}, \mathbf{x}') = \left(1 + \frac{\sqrt{3}\|\mathbf{x} - \mathbf{x}'\|}{\ell}\right) \exp\left(-\frac{\sqrt{3}\|\mathbf{x} - \mathbf{x}'\|}{\ell}\right)$$



Fitting a Gaussian Process Model (with Gaussian Likelihood)

Marginal Likelihood:

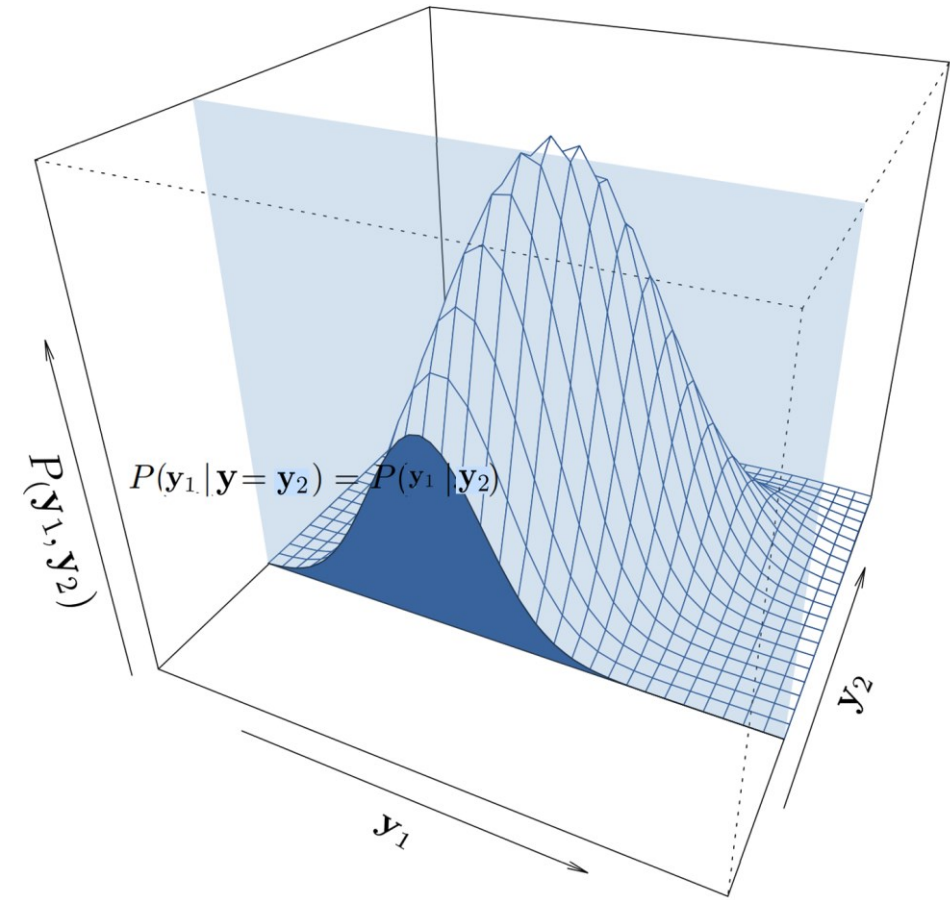
$$p(\mathbf{y}|X) = \int p(\mathbf{y}|\mathbf{f}, X)p(\mathbf{f}|X) d\mathbf{f}$$

Maximize the Log Marginal Likelihood:

$$\log p(\mathbf{y}|X) = -\frac{1}{2}\mathbf{y}^\top (K + \sigma_n^2 I)^{-1}\mathbf{y} - \frac{1}{2} \log |K + \sigma_n^2 I| - \frac{n}{2} \log 2\pi$$

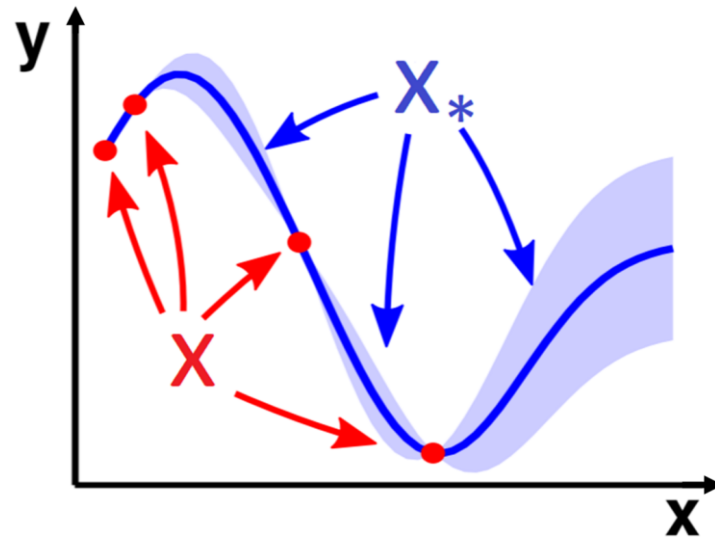
Recalling the Conditioning property (with zero mean)

$$\mathcal{N}\left(\begin{bmatrix} \mathbf{y}_1 \\ \mathbf{y}_2 \end{bmatrix} \mid \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{K}_{11} & \mathbf{K}_{12} \\ \mathbf{K}_{21} & \mathbf{K}_{22} \end{bmatrix}\right)$$



$$\mathcal{N}(\mathbf{y}_2 | \mathbf{K}_{21} \mathbf{K}_{11}^{-1} \mathbf{y}_1, \mathbf{K}_{22} - \mathbf{K}_{21} \mathbf{K}_{11}^{-1} \mathbf{K}_{21}^\top)$$

Making Predictions



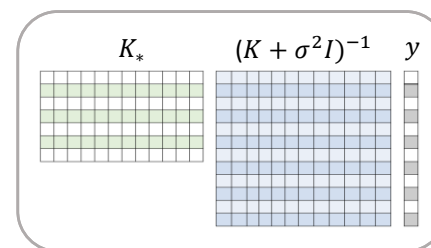
$$\begin{bmatrix} \mathbf{y} \\ \mathbf{f}_* \end{bmatrix} \sim \mathcal{N} \left(\mathbf{0}, \begin{bmatrix} K(\mathbf{X}, \mathbf{X}) + \sigma_n^2 I & K(\mathbf{X}, \mathbf{X}_*) \\ K(\mathbf{X}_*, \mathbf{X}) & K(\mathbf{X}_*, \mathbf{X}_*) \end{bmatrix} \right)$$

Making Predictions

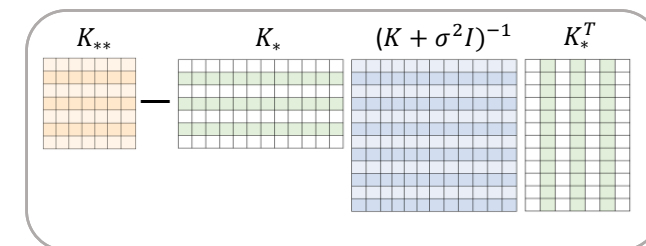
$$\begin{bmatrix} \mathbf{y} \\ \mathbf{f}_* \end{bmatrix} \sim \mathcal{N} \left(\mathbf{0}, \begin{bmatrix} K(\mathbf{X}, \mathbf{X}) + \sigma_n^2 I & K(\mathbf{X}, \mathbf{X}_*) \\ K(\mathbf{X}_*, \mathbf{X}) & K(\mathbf{X}_*, \mathbf{X}_*) \end{bmatrix} \right)$$

Apply **Conditional property** of a Multivariate Gaussian: $\mathcal{N}(\mathbf{y}_2 | \mathbf{K}_{21} \mathbf{K}_{11}^{-1} \mathbf{y}_1, \mathbf{K}_{22} - \mathbf{K}_{21} \mathbf{K}_{11}^{-1} \mathbf{K}_{21}^T)$

$$\boldsymbol{\mu}_* = K(\mathbf{X}_*, \mathbf{X}) (K(\mathbf{X}, \mathbf{X}) + \sigma_n^2 I)^{-1} \mathbf{y}$$



$$\boldsymbol{\Sigma}_* = K(\mathbf{X}_*, \mathbf{X}_*) - K(\mathbf{X}_*, \mathbf{X}) (K(\mathbf{X}, \mathbf{X}) + \sigma_n^2 I)^{-1} K(\mathbf{X}, \mathbf{X}_*)$$



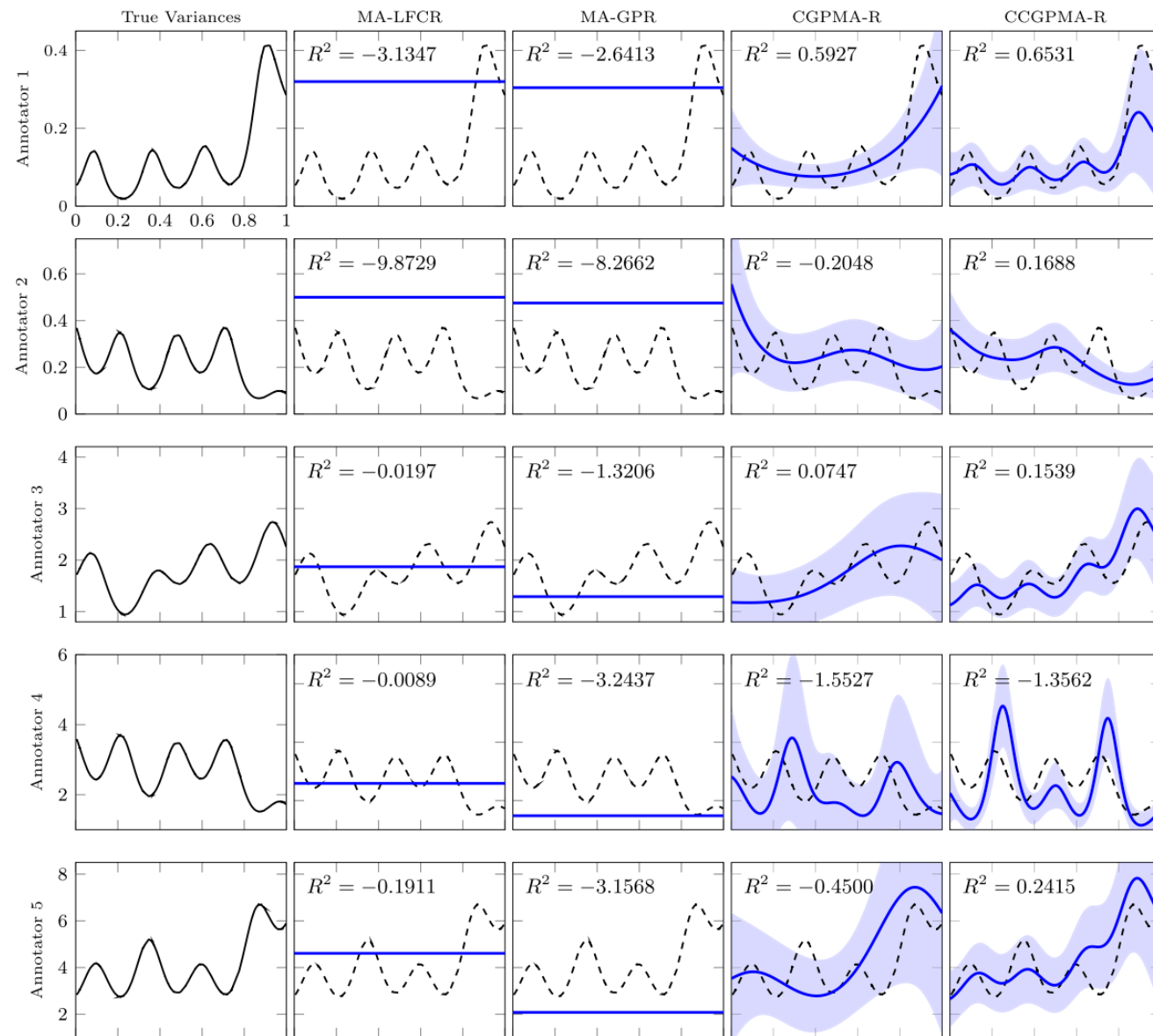
Important: The predictive (co)variance encodes the uncertainty of the prediction!!!!

Correlated Chained Gaussian Processes for Datasets With Multiple Annotators

J. Gil-González¹, Juan-José Giraldo, A. M. Álvarez-Meza, A. Orozco-Gutiérrez, and M. A. Álvarez²

$$p(\mathbf{Y}|\boldsymbol{\theta}) = \prod_{n=1}^N \prod_{r \in R_n} \mathcal{N}(y_n^r | y_n, v_n^r)$$

Check ref [5].



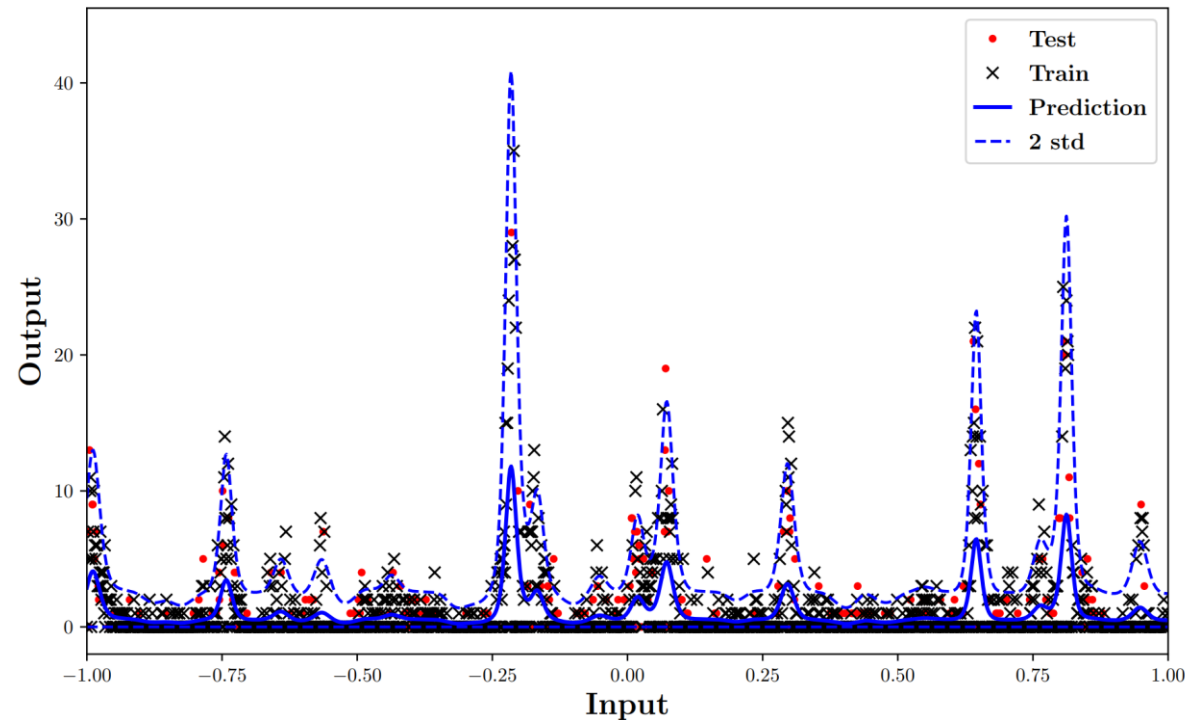
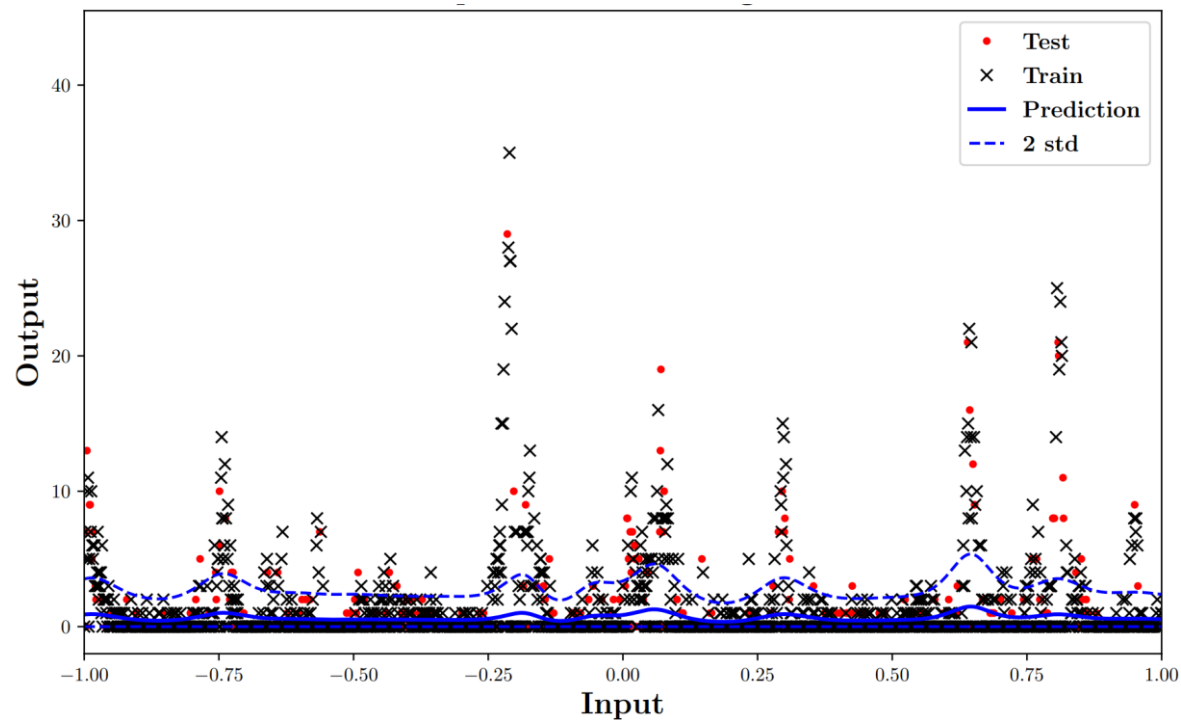
Correlated Chained Gaussian Processes for Modelling Citizens Mobility using a Zero-Inflated Poisson Likelihood

Juan-José Giraldo, Jie Zhang, and Mauricio A. Álvarez

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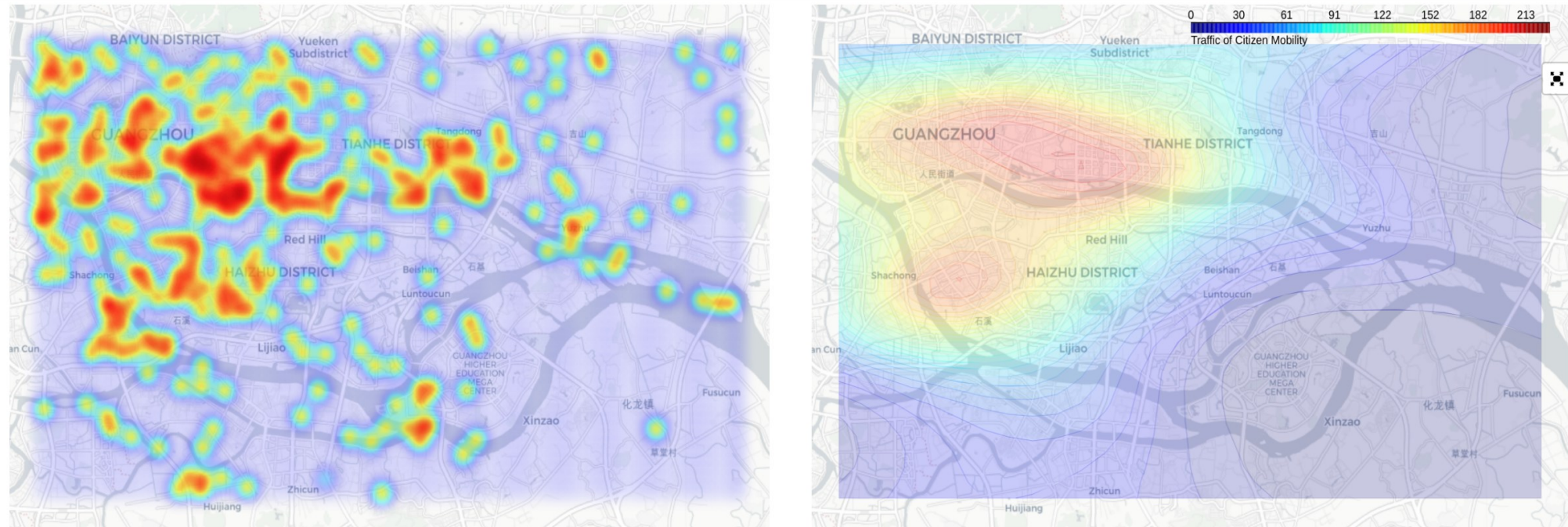
$$p(\mathbf{Y}|\boldsymbol{\theta}) = \prod_{n=1}^N p(y_n|\phi_n, \rho_n)$$

$$p(y_n|\phi_n, \rho_n) = \mathbf{1}_{y_n} \phi_n + (1 - \phi_n) \frac{\exp(-\rho_n) \rho_n^{y_n}}{y_n!}$$



Correlated Chained Gaussian Processes for Modelling Citizens Mobility using a Zero-Inflated Poisson Likelihood

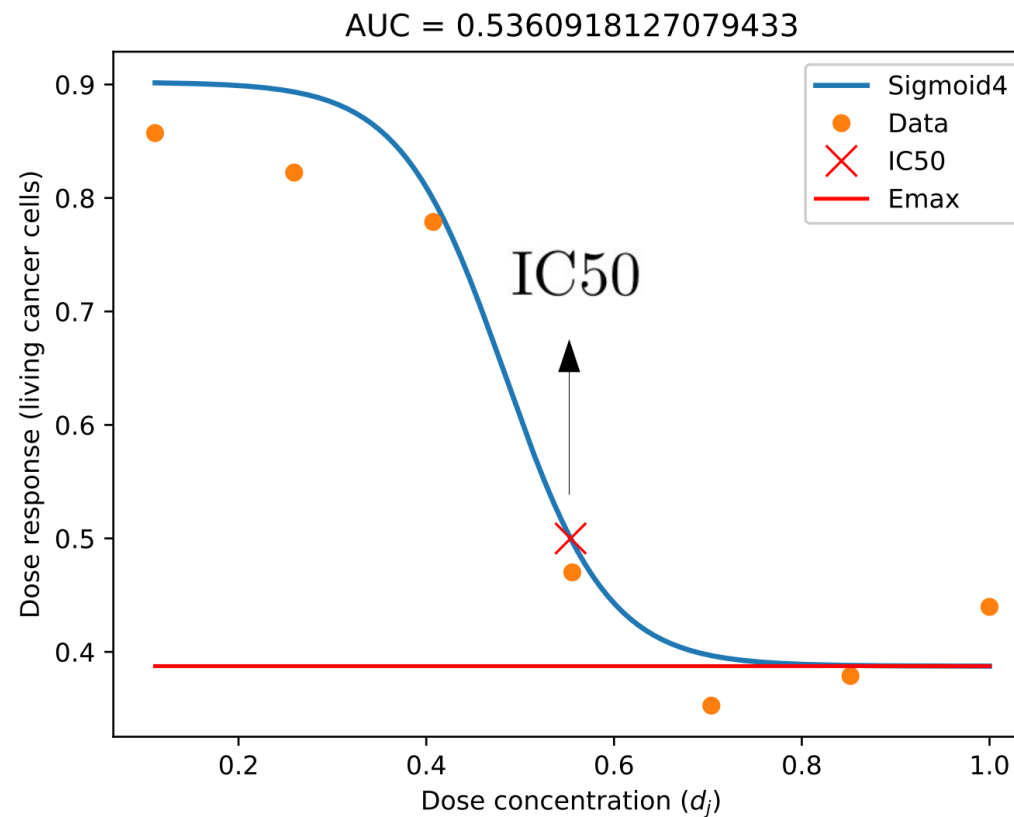
Juan-José Giraldo, Jie Zhang, and Mauricio A. Álvarez



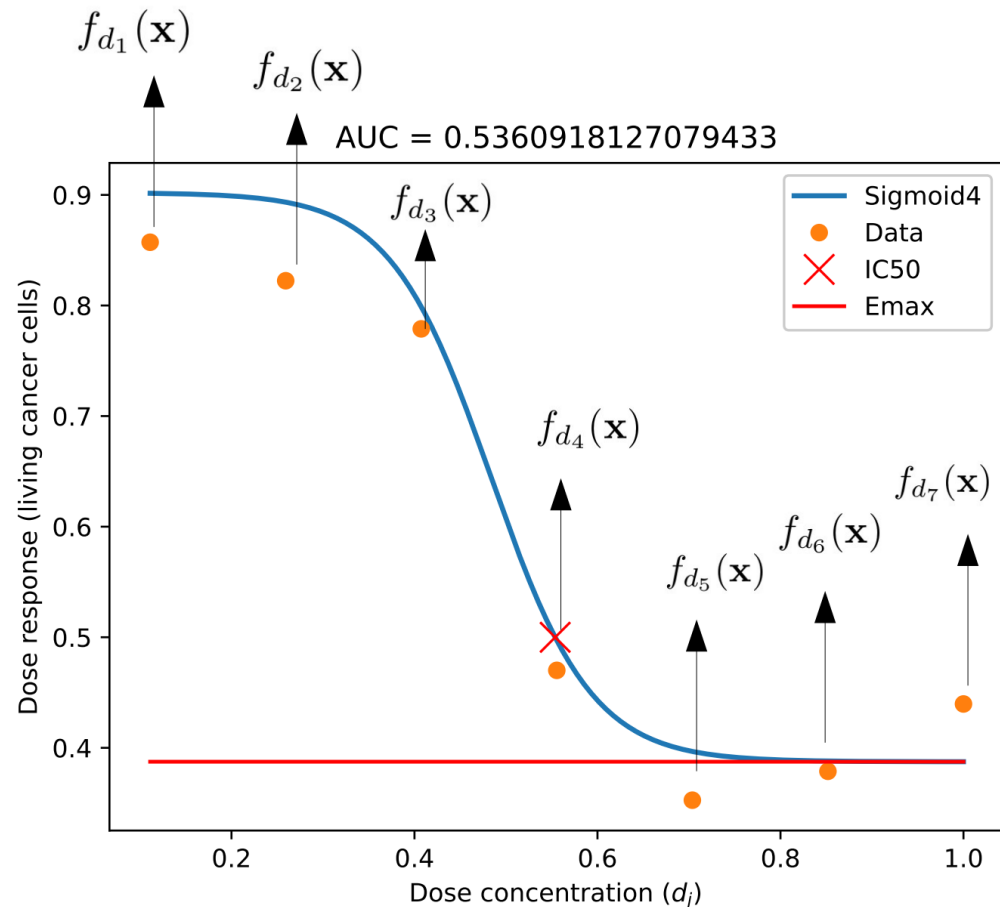
(c) Test Data Heatmap: Saturday, March 16 at 11:00 am (d) Prediction at 11:00 am using CCGP-VIK with ZI-Poisson

Applications of GP Models: Cancer Research

-Generally summary statistics of observed dose-responses like the drug concentration to achieve 50% cell viability (IC50) have been the main target used to train ML models.



Applications of GP Models: Multi-task Gaussian processes for drug response curves



$$f_{d_j}(\mathbf{x}) = \sum_{q=1}^Q w_{d_j,q} u_q(\mathbf{x})$$

$$u_q(\cdot) \sim \mathcal{GP}(0, k_q(\cdot, \cdot))$$

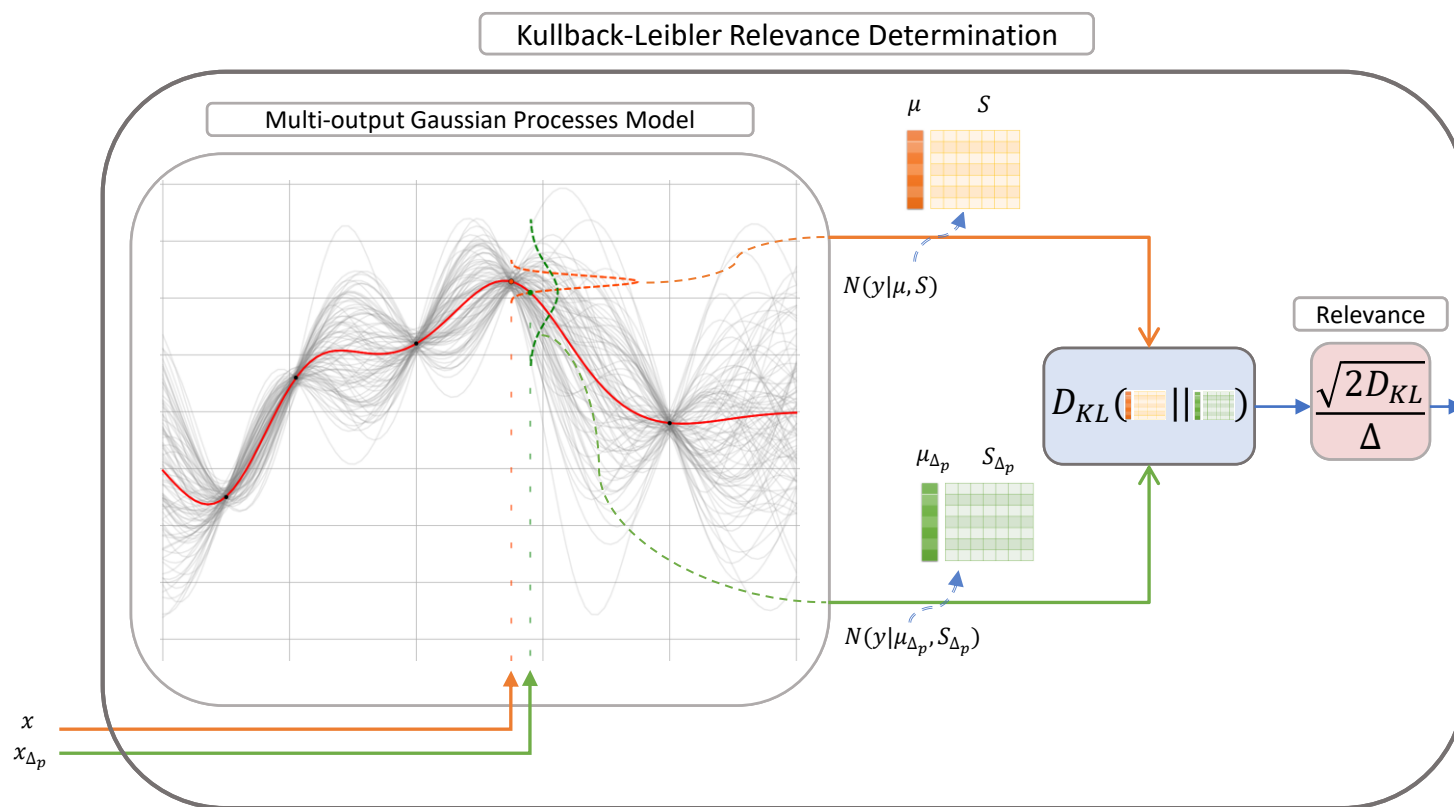
Genomics + drug-compounds:

$$\mathbf{x} \in \mathbb{R}^P$$

Applications of GP Models: Multi-task Gaussian processes for drug response curves

-In the interest of identifying genomic features as biomarkers that predict sensitivity in a disease like cancer, we would expect to find biomarkers that interact with the full DRC behavior.

-We propose to identify the biomarkers by means of a Kullback-Leibler relevance determination strategy.



Advantages of Gaussian Processes

- Gaussian Process models are **powerful tools** for: Regression and classification. 😊
- GPs typically have **fewer hyperparameters** compared to other machine learning models. 😊
- Powerful for **uncertainty quantification** tasks, particularly:
In settings with limited data and **complex relationships**. 😊

As research challenges, they may have limitations in terms of:

- Computational **scalability**. 🤔
- Particularly when working with **very large datasets or high-dimensional** feature spaces. 🤔

Bibliography

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- [3] David Duvenaud, James Robert Lloyd, Roger Grosse, Joshua B. Tenenbaum, and Zoubin Ghahramani, “Structure Discovery in Nonparametric Regression through Compositional Kernel Search”, arXiv:1302.4922v4
- [4] J-J. Giraldo, J. Zhang and M. Alvarez “Correlated Chained Gaussian Processes for Modelling Citizens Mobility Using a Zero-Inflated Poisson Likelihood”, IEEE Transactions on Intelligent Transportation Systems, 2022.
- [5] J. Gil-González , J-J. Giraldo, A. M. Álvarez-Meza, A. Orozco-Gutiérrez, and M. A. Álvarez , Correlated Chained Gaussian Processes for Datasets With Multiple Annotators, IEEE Transactions on Neural Networks and Learning Systems, 20223.
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j.giraldo-gutierrez@imperial.ac.uk