

G8R

Generated by Doxygen 1.9.1

Chapter 1

Hierarchical Index

1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

ClockState	??
Debug	??
Encoder	??
EurorackClock	??
Gates	??
InputHandler	??
LEDController	??
LEDs	??
MIDIHandler	??
Mode	??
Mode0	??
Mode1	??
Mode2	??
ModeSelector	??
Pin	??
AnalogInputPin	??
InputPin	??
OutputPin	??
Gate	??
LED	??
PWMPin	??
ResetButton	??
SPDTSwitch	??

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

AnalogInputPin	??
ClockState	??
Debug	??
Encoder	??
EurorackClock	??
Gate	??
Gates	??
InputHandler	??
InputPin	??
LED	??
LEDController	??
LEDs	??
MIDIHandler	??
Mode	??
Mode0	??
Mode1	??
Mode2	??
ModeSelector	
Mode	Selector Singleton. This class is responsible for managing the different modes of the device. It provides methods to add modes, set the current mode, and handle mode selection
OutputPin	??
Pin	??
PWMPin	??
ResetButton	??
SPDTSwitch	??

Chapter 3

File Index

3.1 File List

Here is a list of all files with brief descriptions:

include/Constants.h	??
include/Debug.h	??
include/Encoder.h	??
include/EurorackClock.h	??
include/Gate.h	??
include/Gates.h	??
include/InputHandler.h	??
include/LED.h	??
include/LEDController.h	??
include/LEDs.h	??
include/MIDIHandler.h	??
include/Mode.h	??
include/Mode0.h	??
include/Mode1.h	??
include/Mode2.h	??
include/ModeSelector.h	??
include/Pin.h	??
include/ResetButton.h	??
include/SPDTSwitch.h	??
src/Debug.cpp	??
src/Encoder.cpp	??
src/EurorackClock.cpp	??
src/Gate.cpp	??
src/Gates.cpp	??
src/InputHandler.cpp	??
src/LED.cpp	??
src/LEDController.cpp	??
src/LEDs.cpp	??
src/main.cpp	??
src/MIDIHandler.cpp	??
src/Mode.cpp	??
src/Mode0.cpp	??
src/Mode1.cpp	??
src/Mode2.cpp	??
src/ModeSelector.cpp	??
src/Pin.cpp	??
src/ResetButton.cpp	??
src/SPDTSwitch.cpp	??

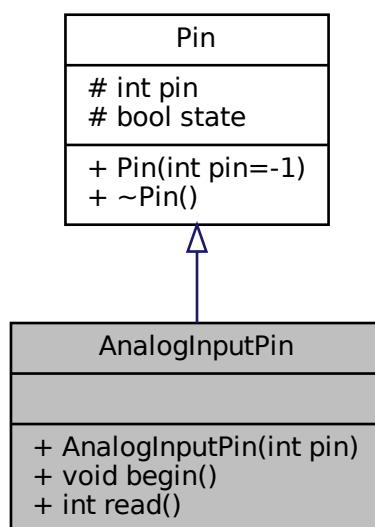
Chapter 4

Class Documentation

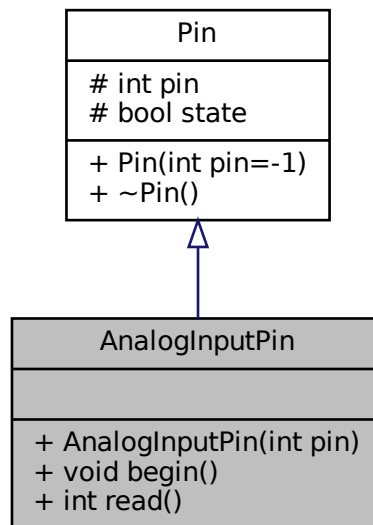
4.1 AnalogInputPin Class Reference

```
#include <Pin.h>
```

Inheritance diagram for AnalogInputPin:



Collaboration diagram for AnalogInputPin:



Public Member Functions

- [AnalogInputPin](#) (int [pin](#))
- void [begin](#) ()
- int [read](#) ()

Additional Inherited Members

4.1.1 Constructor & Destructor Documentation

4.1.1.1 AnalogInputPin()

```
AnalogInputPin::AnalogInputPin (  
    int pin )
```

4.1.2 Member Function Documentation

4.1.2.1 begin()

```
void AnalogInputPin::begin ( )
```

4.1.2.2 read()

```
int AnalogInputPin::read ( )
```

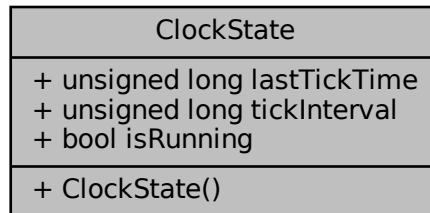
The documentation for this class was generated from the following files:

- include/[Pin.h](#)
- src/[Pin.cpp](#)

4.2 ClockState Struct Reference

```
#include <EurorackClock.h>
```

Collaboration diagram for ClockState:



Public Member Functions

- [ClockState](#) ()

Public Attributes

- unsigned long [lastTickTime](#)
- unsigned long [tickInterval](#)
- bool [isRunning](#)

4.2.1 Constructor & Destructor Documentation

4.2.1.1 ClockState()

```
ClockState::ClockState ( ) [inline]
```

4.2.2 Member Data Documentation

4.2.2.1 isRunning

```
bool ClockState::isRunning
```

4.2.2.2 lastTickTime

```
unsigned long ClockState::lastTickTime
```

4.2.2.3 tickInterval

```
unsigned long ClockState::tickInterval
```

The documentation for this struct was generated from the following file:

- include/[EurorackClock.h](#)

4.3 Debug Class Reference

```
#include <Debug.h>
```

Collaboration diagram for Debug:

Debug
+ static bool isEnabled
+ static void print(const char *file, int line, const char *func, const String &message)

Static Public Member Functions

- static void [print](#) (const char *file, int line, const char *func, const String &message)

Static Public Attributes

- static bool [isEnabled](#) = false

4.3.1 Member Function Documentation

4.3.1.1 print()

```
void Debug::print (
    const char * file,
    int line,
    const char * func,
    const String & message ) [static]
```

4.3.2 Member Data Documentation

4.3.2.1 isEnabled

```
bool Debug::isEnabled = false [static]
```

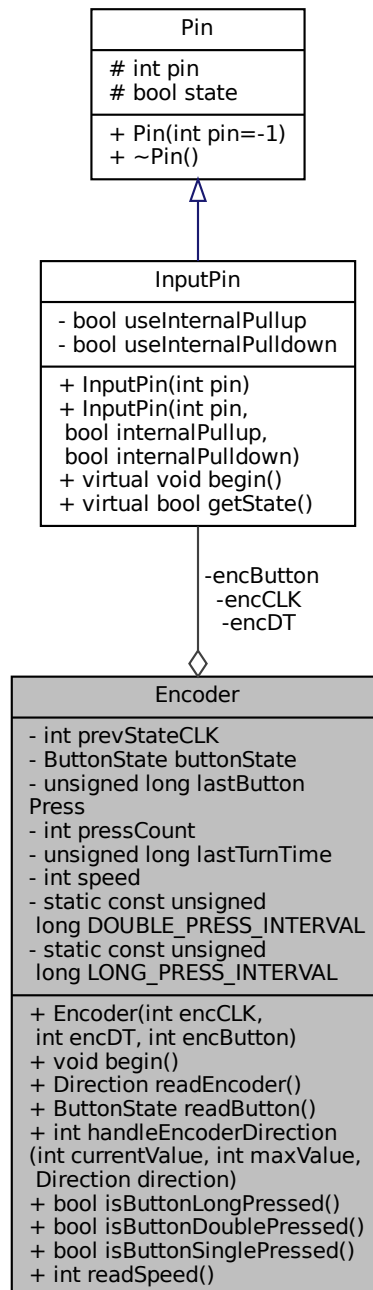
The documentation for this class was generated from the following files:

- include/[Debug.h](#)
- src/[Debug.cpp](#)

4.4 Encoder Class Reference

```
#include <Encoder.h>
```

Collaboration diagram for Encoder:



Public Types

- enum [Direction](#) { [NONE](#) , [CW](#) , [CCW](#) }
- enum [ButtonState](#) { [OPEN](#) , [PRESSED](#) }

Public Member Functions

- [Encoder](#) (int [encCLK](#), int [encDT](#), int [encButton](#))
- void [begin](#) ()
- [Direction](#) [readEncoder](#) ()
- [ButtonState](#) [readButton](#) ()
- int [handleEncoderDirection](#) (int currentValue, int maxValue, [Direction](#) direction)
- bool [isButtonLongPressed](#) ()
- bool [isButtonDoublePressed](#) ()
- bool [isButtonSinglePressed](#) ()
- int [readSpeed](#) ()

Private Attributes

- [InputPin](#) [encCLK](#)
- [InputPin](#) [encDT](#)
- [InputPin](#) [encButton](#)
- int [prevStateCLK](#)
- [ButtonState](#) [buttonState](#)
- unsigned long [lastButtonPress](#)
- int [pressCount](#)
- unsigned long [lastTurnTime](#)
- int [speed](#)

Static Private Attributes

- static const unsigned long [DOUBLE_PRESS_INTERVAL](#) = 500
- static const unsigned long [LONG_PRESS_INTERVAL](#) = 1000

4.4.1 Member Enumeration Documentation

4.4.1.1 ButtonState

```
enum Encoder::ButtonState
```

Enumerator

OPEN	
PRESSED	

4.4.1.2 Direction

```
enum Encoder::Direction
```

Enumerator

NONE	
CW	
CCW	

4.4.2 Constructor & Destructor Documentation

4.4.2.1 Encoder()

```
Encoder::Encoder (
    int  encCLK,
    int  encDT,
    int  encButton )
```

4.4.3 Member Function Documentation

4.4.3.1 begin()

```
void Encoder::begin ( )
```

4.4.3.2 handleEncoderDirection()

```
int Encoder::handleEncoderDirection(
    int  currentValue,
    int  maxValue,
    Direction direction )
```

4.4.3.3 isButtonDoublePressed()

```
bool Encoder::isButtonDoublePressed ( )
```


4.4.3.4 isButtonLongPressed()

```
bool Encoder::isButtonLongPressed ( )
```

4.4.3.5 isButtonSinglePressed()

```
bool Encoder::isButtonSinglePressed ( )
```

4.4.3.6 readButton()

```
Encoder::ButtonState Encoder::readButton ( )
```

4.4.3.7 readEncoder()

```
Encoder::Direction Encoder::readEncoder ( )
```

4.4.3.8 readSpeed()

```
int Encoder::readSpeed ( )
```

4.4.4 Member Data Documentation

4.4.4.1 buttonState

```
ButtonState Encoder::buttonState [private]
```

4.4.4.2 DOUBLE_PRESS_INTERVAL

```
const unsigned long Encoder::DOUBLE_PRESS_INTERVAL = 500 [static], [private]
```

4.4.4.3 encButton

```
InputPin Encoder::encButton [private]
```

4.4.4.4 encCLK

```
InputPin Encoder::encCLK [private]
```

4.4.4.5 encDT

```
InputPin Encoder::encDT [private]
```

4.4.4.6 lastButtonPress

```
unsigned long Encoder::lastButtonPress [private]
```

4.4.4.7 lastTurnTime

```
unsigned long Encoder::lastTurnTime [private]
```

4.4.4.8 LONG_PRESS_INTERVAL

```
const unsigned long Encoder::LONG_PRESS_INTERVAL = 1000 [static], [private]
```

4.4.4.9 pressCount

```
int Encoder::pressCount [private]
```

4.4.4.10 prevStateCLK

```
int Encoder::prevStateCLK [private]
```

4.4.4.11 speed

```
int Encoder::speed [private]
```

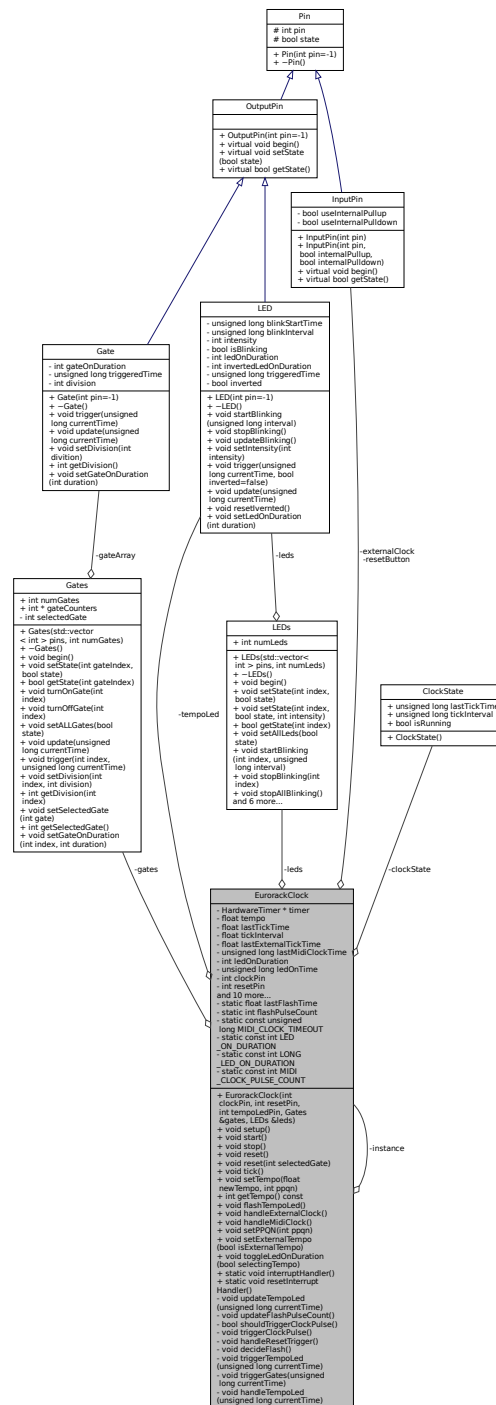
The documentation for this class was generated from the following files:

- [include/Encoder.h](#)
- [src/Encoder.cpp](#)

4.5 EurorackClock Class Reference

```
#include <EurorackClock.h>
```

Collaboration diagram for EurorackClock:



Public Member Functions

- [EurorackClock](#) (int [clockPin](#), int [resetPin](#), int [tempoLedPin](#), [Gates](#) &[gates](#), [LEDs](#) &[leds](#))
- void [setup](#) ()
- void [start](#) ()
- void [stop](#) ()
- void [reset](#) ()

- void [reset](#) (int selectedGate)
- void [tick](#) ()
- void [setTempo](#) (float newTempo, int [ppqn](#))
- int [getTempo](#) () const
- void [flashTempoLed](#) ()
- void [handleExternalClock](#) ()
- void [handleMidiClock](#) ()
- void [setPPQN](#) (int [ppqn](#))
- void [setExternalTempo](#) (bool [isExternalTempo](#))
- void [toggleLedOnDuration](#) (bool selectingTempo)

Static Public Member Functions

- static void [interruptHandler](#) ()
- static void [resetInterruptHandler](#) ()

Private Member Functions

- void [updateTempoLed](#) (unsigned long currentTime)
- void [updateFlashPulseCount](#) ()
- bool [shouldTriggerClockPulse](#) ()
- void [triggerClockPulse](#) ()
- void [handleResetTrigger](#) ()
- void [decideFlash](#) ()
- void [triggerTempoLed](#) (unsigned long currentTime)
- void [triggerGates](#) (unsigned long currentTime)
- void [handleTempoLed](#) (unsigned long currentTime)

Private Attributes

- [ClockState](#) [clockState](#)
- HardwareTimer * [timer](#)
- [LED](#) [tempoLed](#)
- [InputPin](#) [externalClock](#)
- [InputPin](#) [resetButton](#)
- [Gates](#) & [gates](#)
- [LEDs](#) & [leds](#)
- float [tempo](#)
- float [lastTickTime](#)
- float [tickInterval](#)
- float [lastExternalTickTime](#)
- unsigned long [lastMidiClockTime](#)
- int [ledOnDuration](#) = [LONG_LED_ON_DURATION](#)
- unsigned long [ledOnTime](#) = 0
- int [clockPin](#)
- int [resetPin](#)
- int [ppqn](#)
- bool [isRunning](#)
- bool [isExternalTempo](#)
- bool [isMidiClock](#)
- bool [timeToFlash](#)
- bool [resetTriggered](#)
- float [externalTempo](#)
- int [lastClockState](#)
- unsigned long [lastClockTime](#)
- int [tickCount](#)

Static Private Attributes

- static [EurorackClock](#) * [instance](#) = nullptr
- static float [lastFlashTime](#) = 0
- static int [flashPulseCount](#) = 0
- static const unsigned long [MIDI_CLOCK_TIMEOUT](#) = 1000
- static const int [LED_ON_DURATION](#) = 10
- static const int [LONG_LED_ON_DURATION](#) = 50
- static const int [MIDI_CLOCK_PULSE_COUNT](#) = 24

4.5.1 Constructor & Destructor Documentation

4.5.1.1 EurorackClock()

```
EurorackClock::EurorackClock (
    int clockPin,
    int resetPin,
    int tempoLedPin,
    Gates & gates,
    LEDs & leds )
```

4.5.2 Member Function Documentation

4.5.2.1 decideFlash()

```
void EurorackClock::decideFlash ( ) [private]
```

4.5.2.2 flashTempoLed()

```
void EurorackClock::flashTempoLed ( )
```

4.5.2.3 getTempo()

```
int EurorackClock::getTempo ( ) const
```

4.5.2.4 handleExternalClock()

```
void EurorackClock::handleExternalClock ( )
```

4.5.2.5 handleMidiClock()

```
void EurorackClock::handleMidiClock ( )
```

4.5.2.6 handleResetTrigger()

```
void EurorackClock::handleResetTrigger ( ) [private]
```

4.5.2.7 handleTempoLed()

```
void EurorackClock::handleTempoLed (
    unsigned long currentTime ) [private]
```

4.5.2.8 interruptHandler()

```
static void EurorackClock::interruptHandler ( ) [inline], [static]
```

4.5.2.9 reset() [1/2]

```
void EurorackClock::reset ( )
```

4.5.2.10 reset() [2/2]

```
void EurorackClock::reset (
    int selectedGate )
```

4.5.2.11 resetInterruptHandler()

```
static void EurorackClock::resetInterruptHandler ( ) [inline], [static]
```

4.5.2.12 setExternalTempo()

```
void EurorackClock::setExternalTempo (
    bool isExternalTempo )
```

4.5.2.13 setPPQN()

```
void EurorackClock::setPPQN (
    int ppqn )
```

4.5.2.14 setTempo()

```
void EurorackClock::setTempo (
    float newTempo,
    int ppqn )
```

4.5.2.15 setup()

```
void EurorackClock::setup ( )
```

4.5.2.16 shouldTriggerClockPulse()

```
bool EurorackClock::shouldTriggerClockPulse ( ) [private]
```

4.5.2.17 start()

```
void EurorackClock::start ( )
```


4.5.2.18 stop()

```
void EurorackClock::stop ( )
```

4.5.2.19 tick()

```
void EurorackClock::tick ( )
```

4.5.2.20 toggleLedOnDuration()

```
void EurorackClock::toggleLedOnDuration (
    bool selectingTempo )
```

4.5.2.21 triggerClockPulse()

```
void EurorackClock::triggerClockPulse ( ) [private]
```

4.5.2.22 triggerGates()

```
void EurorackClock::triggerGates (
    unsigned long currentTime ) [private]
```

4.5.2.23 triggerTempoLed()

```
void EurorackClock::triggerTempoLed (
    unsigned long currentTime ) [private]
```

4.5.2.24 updateFlashPulseCount()

```
void EurorackClock::updateFlashPulseCount ( ) [private]
```

4.5.2.25 updateTempoLed()

```
void EurorackClock::updateTempoLed (
    unsigned long currentTime ) [private]
```

4.5.3 Member Data Documentation

4.5.3.1 clockPin

```
int EurorackClock::clockPin [private]
```

4.5.3.2 clockState

```
ClockState EurorackClock::clockState [private]
```

4.5.3.3 externalClock

```
InputPin EurorackClock::externalClock [private]
```

4.5.3.4 externalTempo

```
float EurorackClock::externalTempo [private]
```

4.5.3.5 flashPulseCount

```
int EurorackClock::flashPulseCount = 0 [static], [private]
```

4.5.3.6 gates

```
Gates& EurorackClock::gates [private]
```

4.5.3.7 instance

```
EurorackClock * EurorackClock::instance = nullptr [static], [private]
```

4.5.3.8 isExternalTempo

```
bool EurorackClock::isExternalTempo [private]
```

4.5.3.9 isMidiClock

```
bool EurorackClock::isMidiClock [private]
```

4.5.3.10 isRunning

```
bool EurorackClock::isRunning [private]
```

4.5.3.11 lastClockState

```
int EurorackClock::lastClockState [private]
```

4.5.3.12 lastClockTime

```
unsigned long EurorackClock::lastClockTime [private]
```

4.5.3.13 lastExternalTickTime

```
float EurorackClock::lastExternalTickTime [private]
```

4.5.3.14 lastFlashTime

```
float EurorackClock::lastFlashTime = 0 [static], [private]
```

4.5.3.15 lastMidiClockTime

```
unsigned long EurorackClock::lastMidiClockTime [private]
```

4.5.3.16 lastTickTime

```
float EurorackClock::lastTickTime [private]
```

4.5.3.17 LED_ON_DURATION

```
const int EurorackClock::LED_ON_DURATION = 10 [static], [private]
```

4.5.3.18 ledOnDuration

```
int EurorackClock::ledOnDuration = LONG_LED_ON_DURATION [private]
```

4.5.3.19 ledOnTime

```
unsigned long EurorackClock::ledOnTime = 0 [private]
```

4.5.3.20 leds

```
LEDs& EurorackClock::leds [private]
```

4.5.3.21 LONG_LED_ON_DURATION

```
const int EurorackClock::LONG_LED_ON_DURATION = 50 [static], [private]
```

4.5.3.22 MIDI_CLOCK_PULSE_COUNT

```
const int EurorackClock::MIDI_CLOCK_PULSE_COUNT = 24 [static], [private]
```

4.5.3.23 MIDI_CLOCK_TIMEOUT

```
const unsigned long EurorackClock::MIDI_CLOCK_TIMEOUT = 1000 [static], [private]
```

4.5.3.24 ppqn

```
int EurorackClock::ppqn [private]
```

4.5.3.25 resetButton

```
InputPin EurorackClock::resetButton [private]
```

4.5.3.26 resetPin

```
int EurorackClock::resetPin [private]
```

4.5.3.27 resetTriggered

```
bool EurorackClock::resetTriggered [private]
```

4.5.3.28 tempo

```
float EurorackClock::tempo [private]
```

4.5.3.29 tempoLed

```
LED EurorackClock::tempoLed [private]
```

4.5.3.30 tickCount

```
int EurorackClock::tickCount [private]
```

4.5.3.31 tickInterval

```
float EurorackClock::tickInterval [private]
```

4.5.3.32 timer

```
HardwareTimer* EurorackClock::timer [private]
```

4.5.3.33 timeToFlash

```
bool EurorackClock::timeToFlash [private]
```

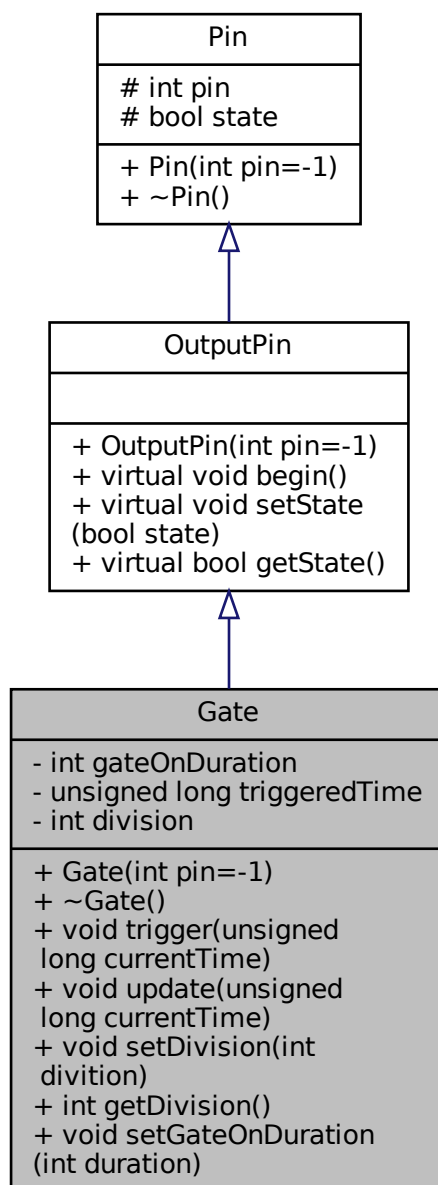
The documentation for this class was generated from the following files:

- [include/EurorackClock.h](#)
- [src/EurorackClock.cpp](#)

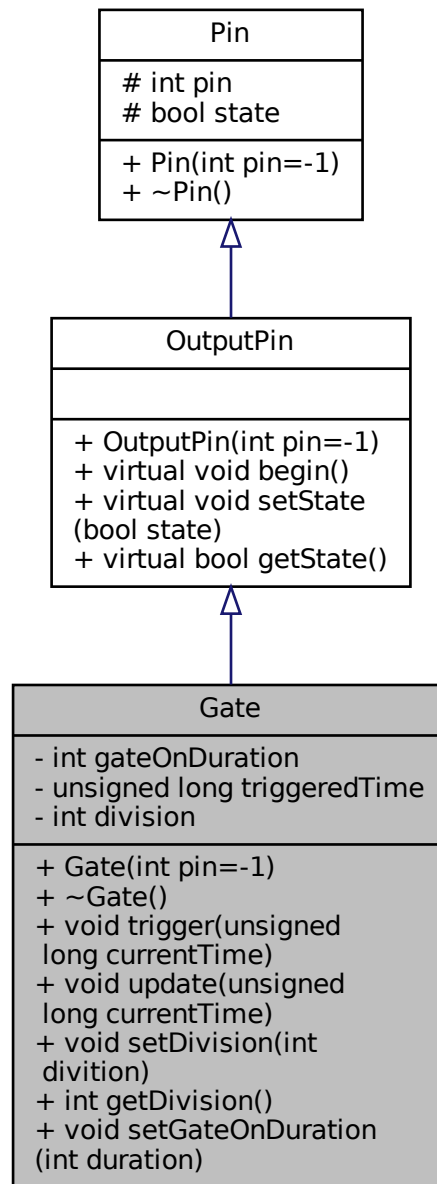
4.6 Gate Class Reference

```
#include <Gate.h>
```

Inheritance diagram for Gate:



Collaboration diagram for Gate:



Public Member Functions

- [Gate](#) (int [pin](#)=-1)
- [~Gate](#) ()
- void [trigger](#) (unsigned long currentTime)
- void [update](#) (unsigned long currentTime)
- void [setDivision](#) (int division)
- int [getDivision](#) ()
- void [setGateOnDuration](#) (int duration)

Private Attributes

- int `gateOnDuration` = 10
- unsigned long `triggeredTime` = 0
- int `division` = `internalPPQN`

Additional Inherited Members

4.6.1 Constructor & Destructor Documentation

4.6.1.1 Gate()

```
Gate::Gate (
    int pin = -1 )
```

4.6.1.2 ~Gate()

```
Gate::~~Gate ( )
```

4.6.2 Member Function Documentation

4.6.2.1 getDivision()

```
int Gate::getDivision ( )
```

4.6.2.2 setDivision()

```
void Gate::setDivision (
    int division )
```

4.6.2.3 setGateOnDuration()

```
void Gate::setGateOnDuration (
    int duration )
```

4.6.2.4 trigger()

```
void Gate::trigger (
    unsigned long currentTime )
```

4.6.2.5 update()

```
void Gate::update (
    unsigned long currentTime )
```

4.6.3 Member Data Documentation

4.6.3.1 division

```
int Gate::division = internalPPQN [private]
```

4.6.3.2 gateOnDuration

```
int Gate::gateOnDuration = 10 [private]
```

4.6.3.3 triggeredTime

```
unsigned long Gate::triggeredTime = 0 [private]
```

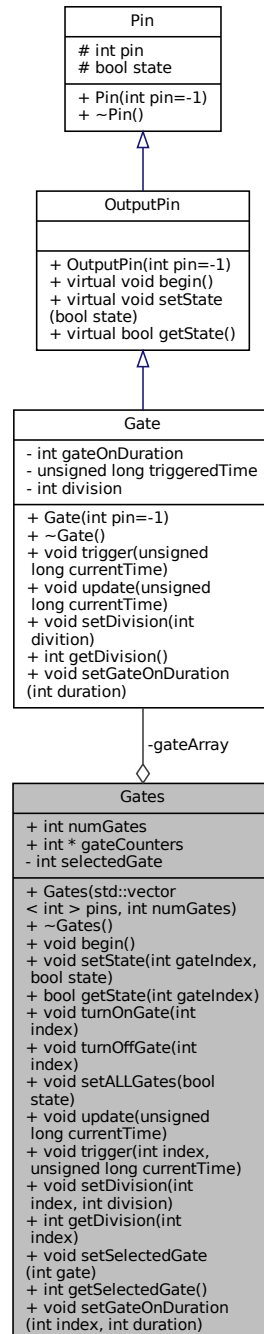
The documentation for this class was generated from the following files:

- [include/Gate.h](#)
- [src/Gate.cpp](#)

4.7 Gates Class Reference

```
#include <Gates.h>
```

Collaboration diagram for Gates:



Public Member Functions

- [Gates](#) (`std::vector<int> pins`, `int numGates`)

- [~Gates](#) ()
- void [begin](#) ()
- void [setState](#) (int gateIndex, bool state)
- bool [getState](#) (int gateIndex)
- void [turnOnGate](#) (int index)
- void [turnOffGate](#) (int index)
- void [setALLGates](#) (bool state)
- void [update](#) (unsigned long currentTime)
- void [trigger](#) (int index, unsigned long currentTime)
- void [setDivision](#) (int index, int division)
- int [getDivision](#) (int index)
- void [setSelectedGate](#) (int gate)
- int [getSelectedGate](#) ()
- void [setGateOnDuration](#) (int index, int duration)

Public Attributes

- int [numGates](#)
- int * [gateCounters](#)

Private Attributes

- [Gate](#) * [gateArray](#)
- int [selectedGate](#)

4.7.1 Constructor & Destructor Documentation

4.7.1.1 Gates()

```
Gates::Gates (
    std::vector< int > pins,
    int numGates )
```

4.7.1.2 ~Gates()

```
Gates::~Gates ( )
```

4.7.2 Member Function Documentation

4.7.2.1 begin()

```
void Gates::begin ( )
```

4.7.2.2 getDivision()

```
int Gates::getDivision (
    int index )
```

4.7.2.3 getSelectedGate()

```
int Gates::getSelectedGate ( )
```

4.7.2.4 getState()

```
bool Gates::getState (
    int gateIndex )
```

4.7.2.5 setALLGates()

```
void Gates::setALLGates (
    bool state )
```

4.7.2.6 setDivision()

```
void Gates::setDivision (
    int index,
    int division )
```

4.7.2.7 setGateOnDuration()

```
void Gates::setGateOnDuration (
    int index,
    int duration )
```

4.7.2.8 setSelectedGate()

```
void Gates::setSelectedGate (
    int gate )
```

4.7.2.9 setState()

```
void Gates::setState (
    int gateIndex,
    bool state )
```

4.7.2.10 trigger()

```
void Gates::trigger (
    int index,
    unsigned long currentTime )
```

4.7.2.11 turnOffGate()

```
void Gates::turnOffGate (
    int index )
```

4.7.2.12 turnOnGate()

```
void Gates::turnOnGate (
    int index )
```

4.7.2.13 update()

```
void Gates::update (
    unsigned long currentTime )
```

4.7.3 Member Data Documentation

4.7.3.1 gateArray

```
Gate* Gates::gateArray [private]
```

4.7.3.2 gateCounters

```
int* Gates::gateCounters
```

4.7.3.3 numGates

```
int Gates::numGates
```

4.7.3.4 selectedGate

```
int Gates::selectedGate [private]
```

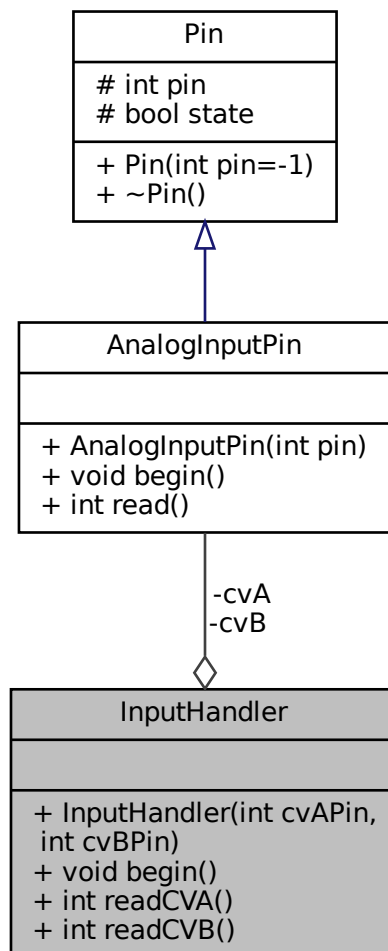
The documentation for this class was generated from the following files:

- [include/Gates.h](#)
- [src/Gates.cpp](#)

4.8 InputHandler Class Reference

```
#include <InputHandler.h>
```

Collaboration diagram for InputHandler:



Public Member Functions

- [InputHandler](#) (int cvAPin, int cvBPin)
- void [begin](#) ()
- int [readCVA](#) ()
- int [readCVB](#) ()

Private Attributes

- [AnalogInputPin](#) cvA
- [AnalogInputPin](#) cvB

4.8.1 Constructor & Destructor Documentation

4.8.1.1 InputHandler()

```
InputHandler::InputHandler (
    int cvAPin,
    int cvBPin )
```

4.8.2 Member Function Documentation

4.8.2.1 begin()

```
void InputHandler::begin ( )
```

4.8.2.2 readCVA()

```
int InputHandler::readCVA ( )
```

4.8.2.3 readCVB()

```
int InputHandler::readCVB ( )
```

4.8.3 Member Data Documentation

4.8.3.1 cvA

```
AnalogInputPin InputHandler::cvA [private]
```

4.8.3.2 cvB

```
AnalogInputPin InputHandler::cvB [private]
```

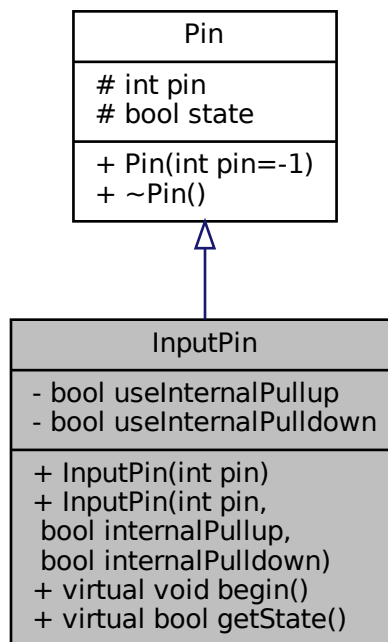
The documentation for this class was generated from the following files:

- [include/InputHandler.h](#)
- [src/InputHandler.cpp](#)

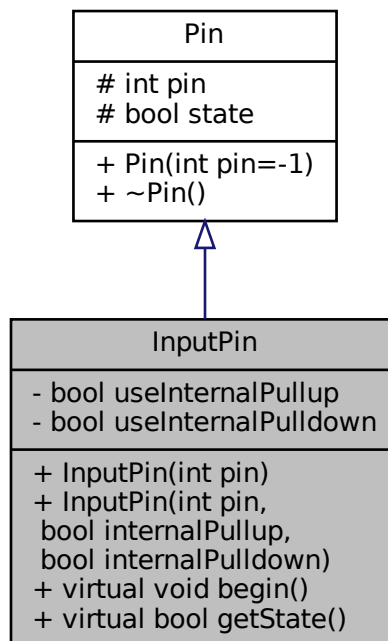
4.9 InputPin Class Reference

```
#include <Pin.h>
```

Inheritance diagram for InputPin:



Collaboration diagram for InputPin:



Public Member Functions

- `InputPin` (int `pin`)
- `InputPin` (int `pin`, bool `internalPullup`, bool `internalPulldown`)
- virtual void `begin` ()
- virtual bool `getState` ()

Private Attributes

- bool `useInternalPullup`
- bool `useInternalPulldown`

Additional Inherited Members

4.9.1 Constructor & Destructor Documentation

4.9.1.1 InputPin() [1/2]

```
InputPin::InputPin (
    int pin )
```

4.9.1.2 InputPin() [2/2]

```
InputPin::InputPin (
    int pin,
    bool internalPullup,
    bool internalPulldown )
```

4.9.2 Member Function Documentation

4.9.2.1 begin()

```
void InputPin::begin ( ) [virtual]
```

4.9.2.2 getState()

```
bool InputPin::getState ( ) [virtual]
```

4.9.3 Member Data Documentation

4.9.3.1 useInternalPulldown

```
bool InputPin::useInternalPulldown [private]
```

4.9.3.2 useInternalPullup

```
bool InputPin::useInternalPullup [private]
```

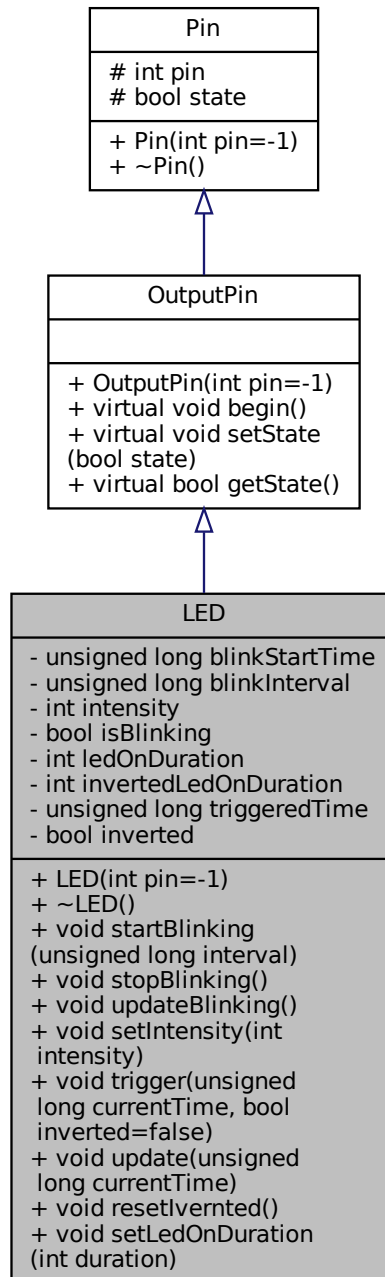
The documentation for this class was generated from the following files:

- [include/Pin.h](#)
- [src/Pin.cpp](#)

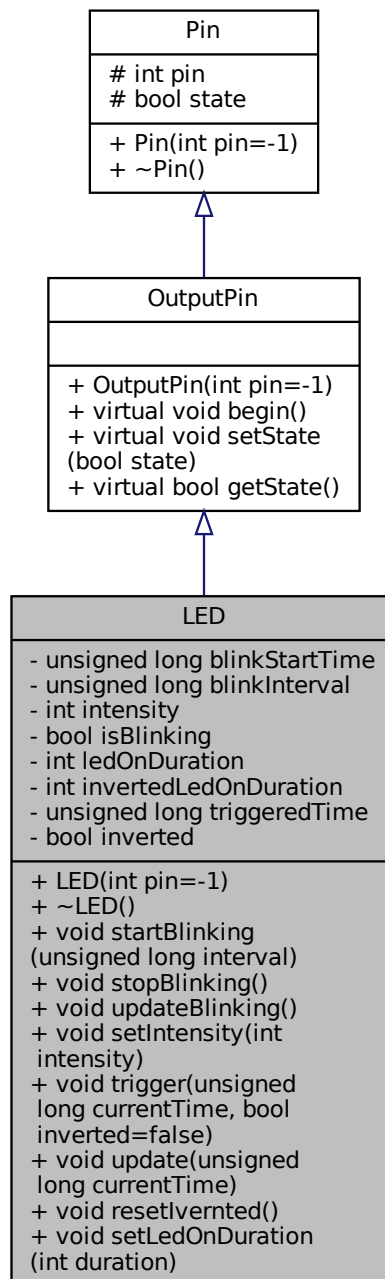
4.10 LED Class Reference

```
#include <LED.h>
```

Inheritance diagram for LED:



Collaboration diagram for LED:



Public Member Functions

- [LED](#) (int `pin`=-1)
- [~LED](#) ()
- void [startBlinking](#) (unsigned long interval)
- void [stopBlinking](#) ()
- void [updateBlinking](#) ()

- void `setIntensity` (int `intensity`)
- void `trigger` (unsigned long `currentTime`, bool `inverted`=false)
- void `update` (unsigned long `currentTime`)
- void `resetIvernted` ()
- void `setLedOnDuration` (int `duration`)

Private Attributes

- unsigned long `blinkStartTime`
- unsigned long `blinkInterval`
- int `intensity` = 255
- bool `isBlinking`
- int `ledOnDuration` = 25
- int `invertedLedOnDuration` = 40
- unsigned long `triggeredTime` = 0
- bool `inverted` = false

Additional Inherited Members

4.10.1 Constructor & Destructor Documentation

4.10.1.1 LED()

```
LED::LED (
    int pin = -1 )
```

4.10.1.2 ~LED()

```
LED::~~LED ( )
```

4.10.2 Member Function Documentation

4.10.2.1 resetIvernted()

```
void LED::resetIvernted ( )
```

4.10.2.2 `setIntensity()`

```
void LED::setIntensity (
    int intensity )
```

4.10.2.3 `setLedOnDuration()`

```
void LED::setLedOnDuration (
    int duration )
```

4.10.2.4 `startBlinking()`

```
void LED::startBlinking (
    unsigned long interval )
```

4.10.2.5 `stopBlinking()`

```
void LED::stopBlinking ( )
```

4.10.2.6 `trigger()`

```
void LED::trigger (
    unsigned long currentTime,
    bool inverted = false )
```

4.10.2.7 `update()`

```
void LED::update (
    unsigned long currentTime )
```

4.10.2.8 `updateBlinking()`

```
void LED::updateBlinking ( )
```


4.10.3 Member Data Documentation

4.10.3.1 blinkInterval

```
unsigned long LED::blinkInterval [private]
```

4.10.3.2 blinkStartTime

```
unsigned long LED::blinkStartTime [private]
```

4.10.3.3 intensity

```
int LED::intensity = 255 [private]
```

4.10.3.4 inverted

```
bool LED::inverted = false [private]
```

4.10.3.5 invertedLedOnDuration

```
int LED::invertedLedOnDuration = 40 [private]
```

4.10.3.6 isBlinking

```
bool LED::isBlinking [private]
```

4.10.3.7 ledOnDuration

```
int LED::ledOnDuration = 25 [private]
```

4.10.3.8 triggeredTime

```
unsigned long LED::triggeredTime = 0 [private]
```

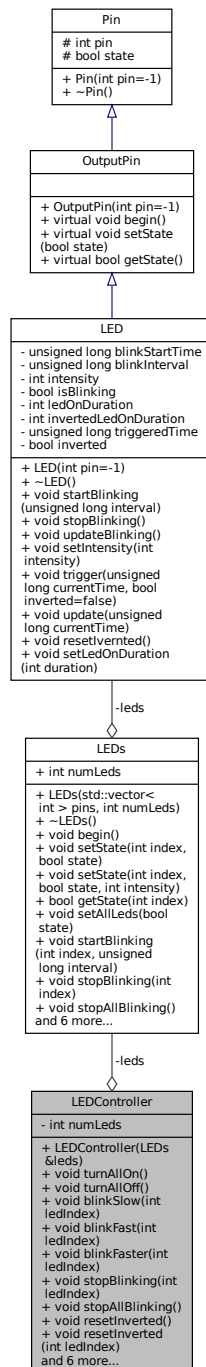
The documentation for this class was generated from the following files:

- [include/LED.h](#)
- [src/LED.cpp](#)

4.11 LEDController Class Reference

```
#include <LEDController.h>
```

Collaboration diagram for LEDController:



Public Member Functions

- [LEDController](#) ([LEDs](#) &[leds](#))
- void [turnAllOn](#) ()
- void [turnAllOff](#) ()
- void [blinkSlow](#) (int ledIndex)
- void [blinkFast](#) (int ledIndex)

- void [blinkFaster](#) (int ledIndex)
- void [stopBlinking](#) (int ledIndex)
- void [stopAllBlinking](#) ()
- void [resetInverted](#) ()
- void [resetInverted](#) (int ledIndex)
- int [getNumLeds](#) ()
- void [update](#) ()
- void [clearAndResetLEDs](#) ()
- void [clearLEDs](#) ()
- void [updateBlinking](#) ()
- void [setState](#) (int ledIndex, bool state)

Private Attributes

- [LEDs](#) & [leds](#)
- int [numLeds](#)

4.11.1 Constructor & Destructor Documentation

4.11.1.1 LEDController()

```
LEDController::LEDController (  
    LEDs & leds )
```

4.11.2 Member Function Documentation

4.11.2.1 blinkFast()

```
void LEDController::blinkFast (  
    int ledIndex )
```

4.11.2.2 blinkFaster()

```
void LEDController::blinkFaster (  
    int ledIndex )
```

4.11.2.3 blinkSlow()

```
void LEDController::blinkSlow (
    int ledIndex )
```

4.11.2.4 clearAndResetLEDs()

```
void LEDController::clearAndResetLEDs ( )
```

4.11.2.5 clearLEDs()

```
void LEDController::clearLEDs ( )
```

4.11.2.6 getNumLeds()

```
int LEDController::getNumLeds ( )
```

4.11.2.7 resetInverted() [1/2]

```
void LEDController::resetInverted ( )
```

4.11.2.8 resetInverted() [2/2]

```
void LEDController::resetInverted (
    int ledIndex )
```

4.11.2.9 setState()

```
void LEDController::setState (
    int ledIndex,
    bool state )
```

4.11.2.10 stopAllBlinking()

```
void LEDController::stopAllBlinking ( )
```

4.11.2.11 stopBlinking()

```
void LEDController::stopBlinking (
    int ledIndex )
```

4.11.2.12 turnAllOff()

```
void LEDController::turnAllOff ( )
```

4.11.2.13 turnAllOn()

```
void LEDController::turnAllOn ( )
```

4.11.2.14 update()

```
void LEDController::update ( )
```

4.11.2.15 updateBlinking()

```
void LEDController::updateBlinking ( )
```

4.11.3 Member Data Documentation

4.11.3.1 leds

```
LEDs& LEDController::leds [private]
```

4.11.3.2 numLeds

```
int LEDController::numLeds [private]
```

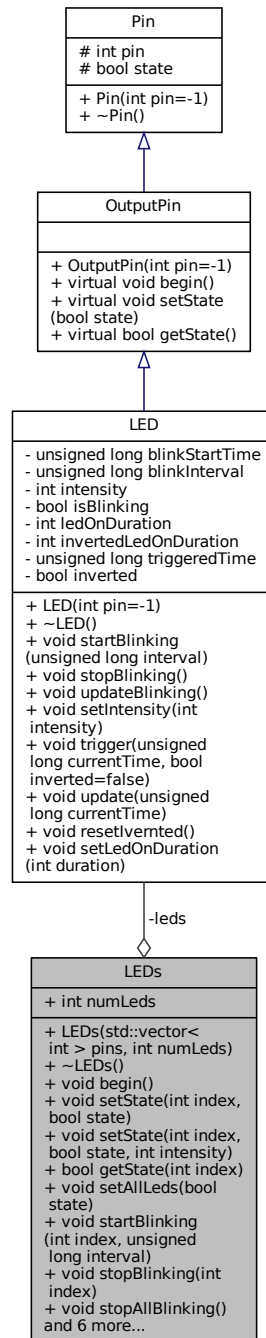
The documentation for this class was generated from the following files:

- [include/LEDController.h](#)
- [src/LEDController.cpp](#)

4.12 LEDs Class Reference

```
#include <LEDs.h>
```

Collaboration diagram for LEDs:



Public Member Functions

- **LEDs** (`std::vector< int > pins`, `int numLeds`)
- **~LEDs** ()
- `void begin ()`
- `void setState (int index, bool state)`
- `void setState (int index, bool state, int intensity)`

- bool `getState` (int index)
- void `setAllLeds` (bool state)
- void `startBlinking` (int index, unsigned long interval)
- void `stopBlinking` (int index)
- void `stopAllBlinking` ()
- void `updateBlinking` ()
- void `setIntensity` (int index, int *intensity*)
- void `setAllintensity` (int *intensity*)
- void `update` (unsigned long currentTime)
- void `trigger` (int index, unsigned long currentTime, bool inverted=false)
- void `resetInverted` (int index)

Public Attributes

- int `numLeds`

Private Attributes

- LED * `leds`

4.12.1 Constructor & Destructor Documentation

4.12.1.1 LEDs()

```
LEDs::LEDs (
    std::vector< int > pins,
    int numLeds )
```

4.12.1.2 ~LEDs()

```
LEDs::~~LEDs ( )
```

4.12.2 Member Function Documentation

4.12.2.1 begin()

```
void LEDs::begin ( )
```

4.12.2.2 getState()

```
bool LEDs::getState (
    int index )
```

4.12.2.3 resetInverted()

```
void LEDs::resetInverted (
    int index )
```

4.12.2.4 setAllintensity()

```
void LEDs::setAllintensity (
    int intensity )
```

4.12.2.5 setAllLeds()

```
void LEDs::setAllLeds (
    bool state )
```

4.12.2.6 setIntensity()

```
void LEDs::setIntensity (
    int index,
    int intensity )
```

4.12.2.7 setState() [1/2]

```
void LEDs::setState (
    int index,
    bool state )
```

4.12.2.8 setState() [2/2]

```
void LEDs::setState (
    int index,
    bool state,
    int intensity )
```

4.12.2.9 startBlinking()

```
void LEDs::startBlinking (
    int index,
    unsigned long interval )
```

4.12.2.10 stopAllBlinking()

```
void LEDs::stopAllBlinking ( )
```

4.12.2.11 stopBlinking()

```
void LEDs::stopBlinking (
    int index )
```

4.12.2.12 trigger()

```
void LEDs::trigger (
    int index,
    unsigned long currentTime,
    bool inverted = false )
```

4.12.2.13 update()

```
void LEDs::update (
    unsigned long currentTime )
```

4.12.2.14 updateBlinking()

```
void LEDs::updateBlinking ( )
```

4.12.3 Member Data Documentation

4.12.3.1 leds

```
LED* LEDs::leds [private]
```

4.12.3.2 numLeds

```
int LEDs::numLeds
```

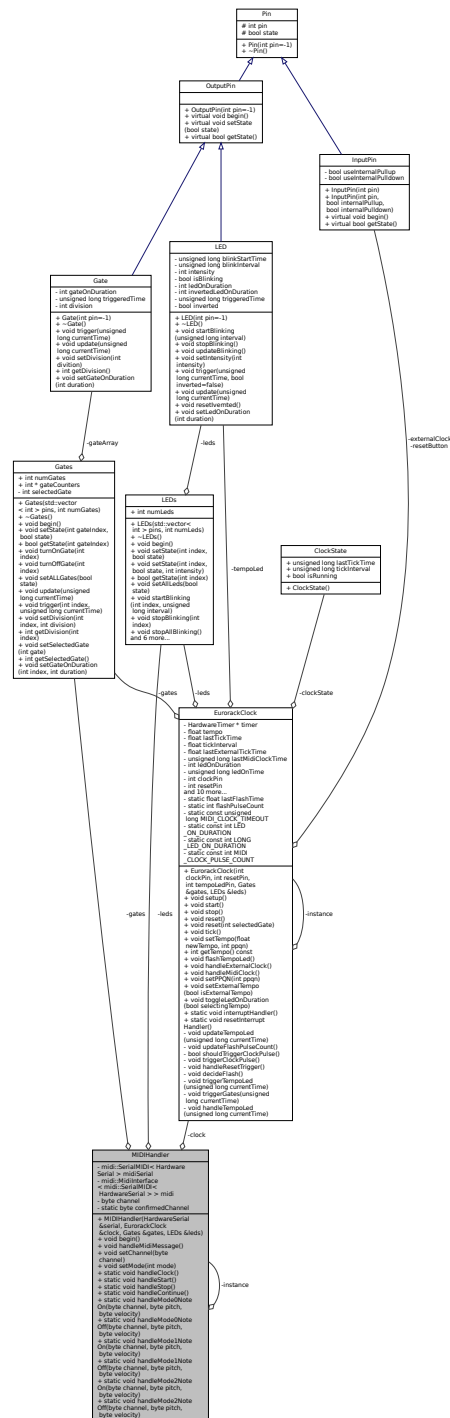
The documentation for this class was generated from the following files:

- [include/LEDs.h](#)
- [src/LEDs.cpp](#)

4.13 MIDIHandler Class Reference

```
#include <MIDIHandler.h>
```

Collaboration diagram for MIDIHandler:



Public Member Functions

- **MIDIHandler** (HardwareSerial &serial, **EurorackClock** &clock, **Gates** &gates, **LEDs** &leds)
- void **begin** ()
- void **handleMidiMessage** ()
- void **setChannel** (byte channel)
- void **setMode** (int mode)

Static Public Member Functions

- static void [handleClock](#) ()
- static void [handleStart](#) ()
- static void [handleStop](#) ()
- static void [handleContinue](#) ()
- static void [handleMode0NoteOn](#) (byte [channel](#), byte pitch, byte velocity)
- static void [handleMode0NoteOff](#) (byte [channel](#), byte pitch, byte velocity)
- static void [handleMode1NoteOn](#) (byte [channel](#), byte pitch, byte velocity)
- static void [handleMode1NoteOff](#) (byte [channel](#), byte pitch, byte velocity)
- static void [handleMode2NoteOn](#) (byte [channel](#), byte pitch, byte velocity)
- static void [handleMode2NoteOff](#) (byte [channel](#), byte pitch, byte velocity)

Private Attributes

- midi::SerialMIDI< HardwareSerial > [midiSerial](#)
- midi::MidiInterface< midi::SerialMIDI< HardwareSerial > > [midi](#)
- [Euro rackClock](#) & [clock](#)
- byte [channel](#) = 10
- [Gates](#) & [gates](#)
- [LEDs](#) & [leds](#)

Static Private Attributes

- static [MIDIHandler](#) * [instance](#) = nullptr
- static byte [confirmedChannel](#) = 9

4.13.1 Constructor & Destructor Documentation

4.13.1.1 MIDIHandler()

```
MIDIHandler::MIDIHandler (
    HardwareSerial & serial,
    Euro rackClock & clock,
    Gates & gates,
    LEDs & leds )
```

4.13.2 Member Function Documentation

4.13.2.1 begin()

```
void MIDIHandler::begin ( )
```

4.13.2.2 handleClock()

```
void MIDIHandler::handleClock ( ) [static]
```

4.13.2.3 handleContinue()

```
void MIDIHandler::handleContinue ( ) [static]
```

4.13.2.4 handleMidiMessage()

```
void MIDIHandler::handleMidiMessage ( )
```

4.13.2.5 handleMode0NoteOff()

```
void MIDIHandler::handleMode0NoteOff (
    byte channel,
    byte pitch,
    byte velocity ) [static]
```

4.13.2.6 handleMode0NoteOn()

```
void MIDIHandler::handleMode0NoteOn (
    byte channel,
    byte pitch,
    byte velocity ) [static]
```

4.13.2.7 handleMode1NoteOff()

```
void MIDIHandler::handleMode1NoteOff (
    byte channel,
    byte pitch,
    byte velocity ) [static]
```

4.13.2.8 handleMode1NoteOn()

```
void MIDIHandler::handleMode1NoteOn (
    byte channel,
    byte pitch,
    byte velocity ) [static]
```

4.13.2.9 handleMode2NoteOff()

```
void MIDIHandler::handleMode2NoteOff (
    byte channel,
    byte pitch,
    byte velocity ) [static]
```

4.13.2.10 handleMode2NoteOn()

```
void MIDIHandler::handleMode2NoteOn (
    byte channel,
    byte pitch,
    byte velocity ) [static]
```

4.13.2.11 handleStart()

```
void MIDIHandler::handleStart ( ) [static]
```

4.13.2.12 handleStop()

```
void MIDIHandler::handleStop ( ) [static]
```

4.13.2.13 setChannel()

```
void MIDIHandler::setChannel (
    byte channel )
```


4.13.2.14 setMode()

```
void MIDIHandler::setMode (
    int mode )
```

4.13.3 Member Data Documentation

4.13.3.1 channel

```
byte MIDIHandler::channel = 10 [private]
```

4.13.3.2 clock

```
EurorackClock& MIDIHandler::clock [private]
```

4.13.3.3 confirmedChannel

```
byte MIDIHandler::confirmedChannel = 9 [static], [private]
```

4.13.3.4 gates

```
Gates& MIDIHandler::gates [private]
```

4.13.3.5 instance

```
MIDIHandler * MIDIHandler::instance = nullptr [static], [private]
```

4.13.3.6 leds

```
LEDs& MIDIHandler::leds [private]
```

4.13.3.7 midi

```
midi::MidiInterface<midi::SerialMIDI<HardwareSerial> > MIDIHandler::midi [private]
```

4.13.3.8 midiSerial

```
midi::SerialMIDI<HardwareSerial> MIDIHandler::midiSerial [private]
```

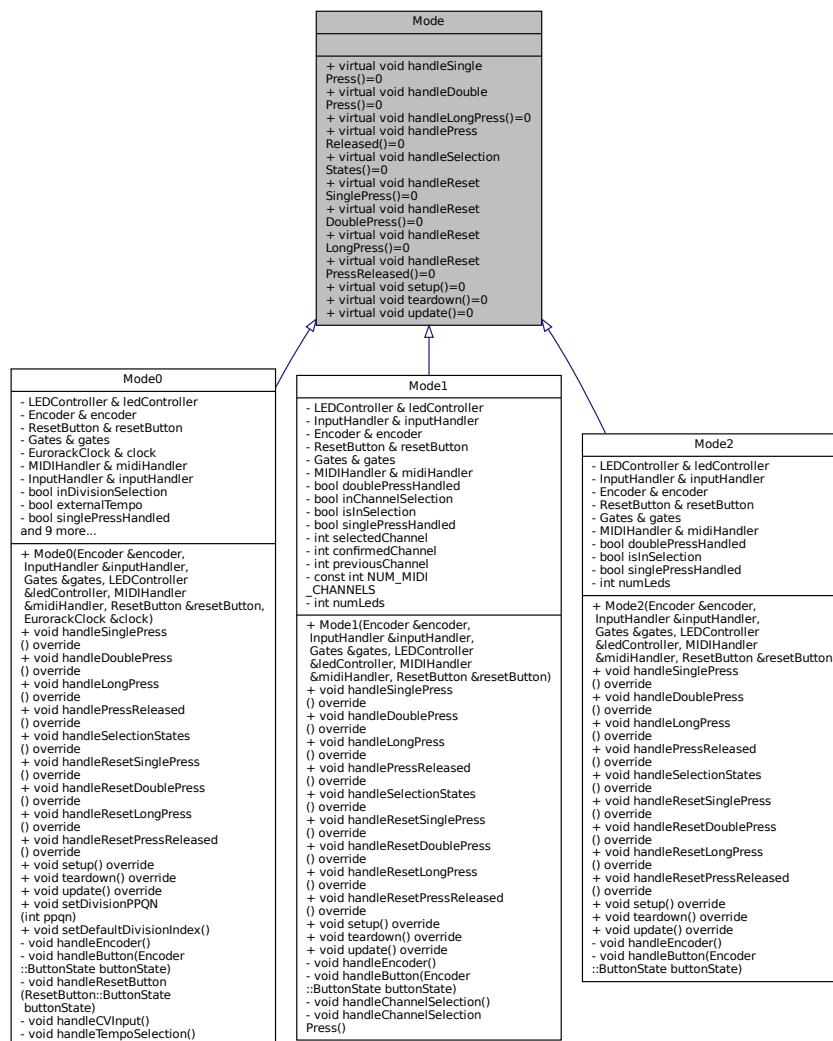
The documentation for this class was generated from the following files:

- include/MIDIHandler.h
- src/MIDIHandler.cpp

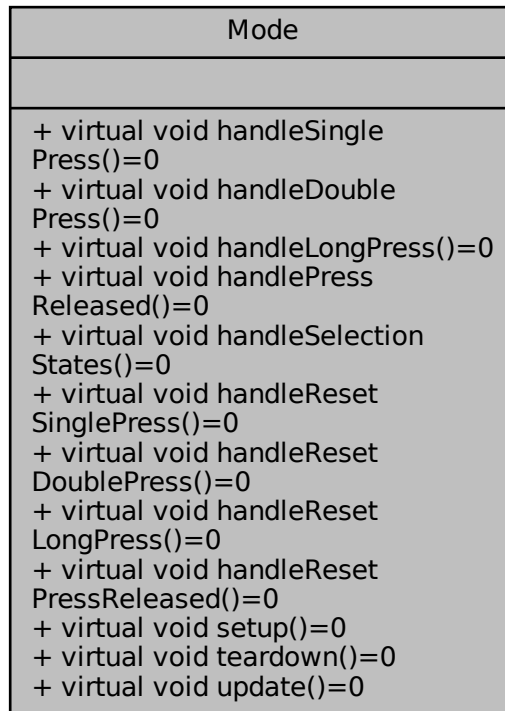
4.14 Mode Class Reference

```
#include <Mode.h>
```

Inheritance diagram for Mode:



Collaboration diagram for Mode:



Public Member Functions

- virtual void [handleSinglePress](#) ()=0
- virtual void [handleDoublePress](#) ()=0
- virtual void [handleLongPress](#) ()=0
- virtual void [handlePressReleased](#) ()=0
- virtual void [handleSelectionStates](#) ()=0
- virtual void [handleResetSinglePress](#) ()=0
- virtual void [handleResetDoublePress](#) ()=0
- virtual void [handleResetLongPress](#) ()=0
- virtual void [handleResetPressReleased](#) ()=0
- virtual void [setup](#) ()=0
- virtual void [teardown](#) ()=0
- virtual void [update](#) ()=0

4.14.1 Member Function Documentation

4.14.1.1 `handleDoublePress()`

```
virtual void Mode::handleDoublePress ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.2 `handleLongPress()`

```
virtual void Mode::handleLongPress ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.3 `handlePressReleased()`

```
virtual void Mode::handlePressReleased ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.4 `handleResetDoublePress()`

```
virtual void Mode::handleResetDoublePress ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.5 `handleResetLongPress()`

```
virtual void Mode::handleResetLongPress ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.6 `handleResetPressReleased()`

```
virtual void Mode::handleResetPressReleased ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.7 `handleResetSinglePress()`

```
virtual void Mode::handleResetSinglePress ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.8 `handleSelectionStates()`

```
virtual void Mode::handleSelectionStates ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.9 `handleSinglePress()`

```
virtual void Mode::handleSinglePress ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.10 `setup()`

```
virtual void Mode::setup ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.11 `teardown()`

```
virtual void Mode::teardown ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

4.14.1.12 `update()`

```
virtual void Mode::update ( ) [pure virtual]
```

Implemented in [Mode2](#), [Mode1](#), and [Mode0](#).

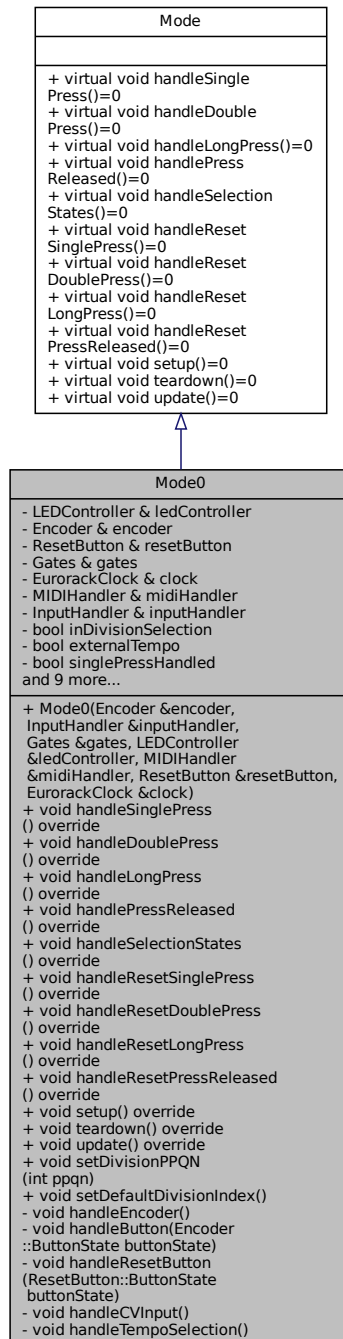
The documentation for this class was generated from the following file:

- [include/Mode.h](#)

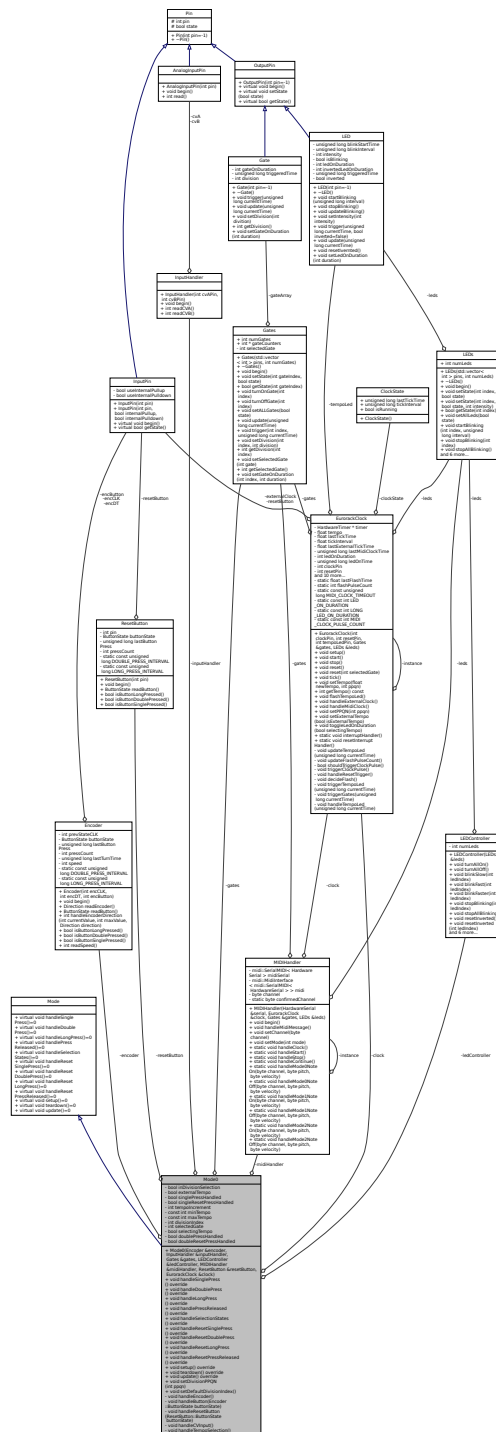
4.15 Mode0 Class Reference

```
#include <Mode0.h>
```

Inheritance diagram for Mode0:



Collaboration diagram for Mode0:



Public Member Functions

- `Model0` (`Encoder` &`encoder`, `InputHandler` &`inputHandler`, `Gates` &`gates`, `LEDController` &`ledController`, `MIDIHandler` &`midiHandler`, `ResetButton` &`resetButton`, `EurorackClock` &`clock`)
- void `handleSinglePress` () override
- void `handleDoublePress` () override
- void `handleLongPress` () override

- void [handlePressReleased](#) () override
- void [handleSelectionStates](#) () override
- void [handleResetSinglePress](#) () override
- void [handleResetDoublePress](#) () override
- void [handleResetLongPress](#) () override
- void [handleResetPressReleased](#) () override
- void [setup](#) () override
- void [teardown](#) () override
- void [update](#) () override
- void [setDivisionPPQN](#) (int ppqn)
- void [setDefaultDivisionIndex](#) ()

Private Member Functions

- void [handleEncoder](#) ()
- void [handleButton](#) ([Encoder::ButtonState](#) buttonState)
- void [handleResetButton](#) ([ResetButton::ButtonState](#) buttonState)
- void [handleCVInput](#) ()
- void [handleTempoSelection](#) ()

Private Attributes

- [LEDController](#) & [ledController](#)
- [Encoder](#) & [encoder](#)
- [ResetButton](#) & [resetButton](#)
- [Gates](#) & [gates](#)
- [EurorackClock](#) & [clock](#)
- [MIDIHandler](#) & [midiHandler](#)
- [InputHandler](#) & [inputHandler](#)
- bool [inDivisionSelection](#) = false
- bool [externalTempo](#) = false
- bool [singlePressHandled](#) = false
- bool [singleResetPressHandled](#) = false
- int [tempoIncrement](#) = 1
- const int [minTempo](#) = 20
- const int [maxTempo](#) = 340
- int [divisionIndex](#) = 24
- int [selectedGate](#) = 0
- bool [selectingTempo](#) = false
- bool [doublePressHandled](#) = false
- bool [doubleResetPressHandled](#) = false

4.15.1 Constructor & Destructor Documentation

4.15.1.1 Mode0()

```
Mode0::Mode0 (
    Encoder & encoder,
    InputHandler & inputHandler,
    Gates & gates,
    LEDController & ledController,
    MIDIHandler & midiHandler,
    ResetButton & resetButton,
    EurorackClock & clock )
```

4.15.2 Member Function Documentation

4.15.2.1 handleButton()

```
void Mode0::handleButton (
    Encoder::ButtonState buttonState ) [private]
```

4.15.2.2 handleCVInput()

```
void Mode0::handleCVInput ( ) [private]
```

4.15.2.3 handleDoublePress()

```
void Mode0::handleDoublePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.4 handleEncoder()

```
void Mode0::handleEncoder ( ) [private]
```

4.15.2.5 handleLongPress()

```
void Mode0::handleLongPress ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.6 handlePressReleased()

```
void Mode0::handlePressReleased ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.7 handleResetButton()

```
void Mode0::handleResetButton (
    ResetButton::ButtonState buttonState ) [private]
```

4.15.2.8 handleResetDoublePress()

```
void Mode0::handleResetDoublePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.9 handleResetLongPress()

```
void Mode0::handleResetLongPress ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.10 handleResetPressReleased()

```
void Mode0::handleResetPressReleased ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.11 handleResetSinglePress()

```
void Mode0::handleResetSinglePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.12 handleSelectionStates()

```
void Mode0::handleSelectionStates ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.13 handleSinglePress()

```
void Mode0::handleSinglePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.14 handleTempoSelection()

```
void Mode0::handleTempoSelection ( ) [private]
```

4.15.2.15 setDefaultDivisionIndex()

```
void Mode0::setDefaultDivisionIndex ( )
```

4.15.2.16 setDivisionPPQN()

```
void Mode0::setDivisionPPQN (
    int ppqn )
```

4.15.2.17 setup()

```
void Mode0::setup ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.18 teardown()

```
void Mode0::teardown ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.2.19 update()

```
void Mode0::update ( ) [override], [virtual]
```

Implements [Mode](#).

4.15.3 Member Data Documentation

4.15.3.1 clock

```
EurorackClock& Mode0::clock [private]
```

4.15.3.2 divisionIndex

```
int Mode0::divisionIndex = 24 [private]
```

4.15.3.3 doublePressHandled

```
bool Mode0::doublePressHandled = false [private]
```

4.15.3.4 doubleResetPressHandled

```
bool Mode0::doubleResetPressHandled = false [private]
```

4.15.3.5 encoder

```
Encoder& Mode0::encoder [private]
```

4.15.3.6 externalTempo

```
bool Mode0::externalTempo = false [private]
```

4.15.3.7 gates

```
Gates& Mode0::gates [private]
```

4.15.3.8 inDivisionSelection

```
bool Mode0::inDivisionSelection = false [private]
```

4.15.3.9 inputHandler

```
InputHandler& Mode0::inputHandler [private]
```

4.15.3.10 ledController

```
LEDController& Mode0::ledController [private]
```

4.15.3.11 maxTempo

```
const int Mode0::maxTempo = 340 [private]
```

4.15.3.12 midiHandler

```
MIDIHandler& Mode0::midiHandler [private]
```

4.15.3.13 minTempo

```
const int Mode0::minTempo = 20 [private]
```

4.15.3.14 resetButton

```
ResetButton& Mode0::resetButton [private]
```

4.15.3.15 selectedGate

```
int Mode0::selectedGate = 0 [private]
```

4.15.3.16 selectingTempo

```
bool Mode0::selectingTempo = false [private]
```

4.15.3.17 singlePressHandled

```
bool Mode0::singlePressHandled = false [private]
```

4.15.3.18 singleResetPressHandled

```
bool Mode0::singleResetPressHandled = false [private]
```

4.15.3.19 tempoIncrement

```
int Mode0::tempoIncrement = 1 [private]
```

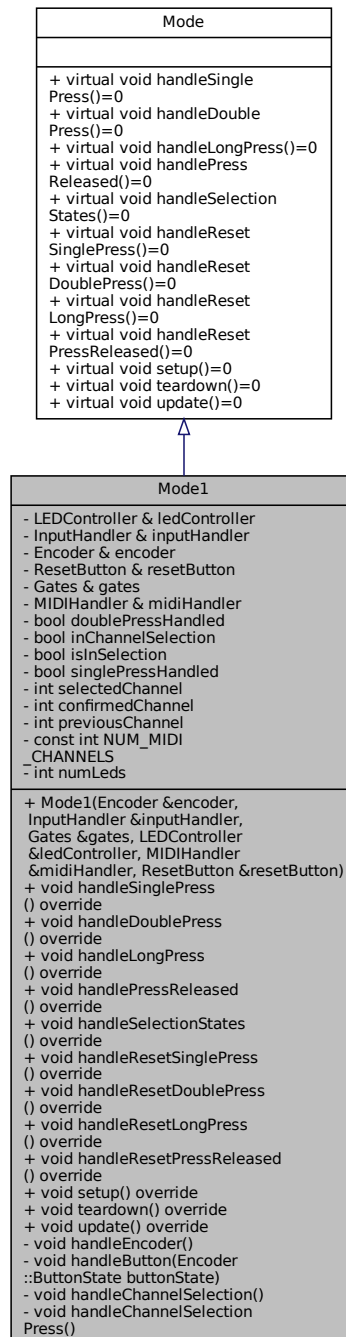
The documentation for this class was generated from the following files:

- [include/Mode0.h](#)
- [src/Mode0.cpp](#)

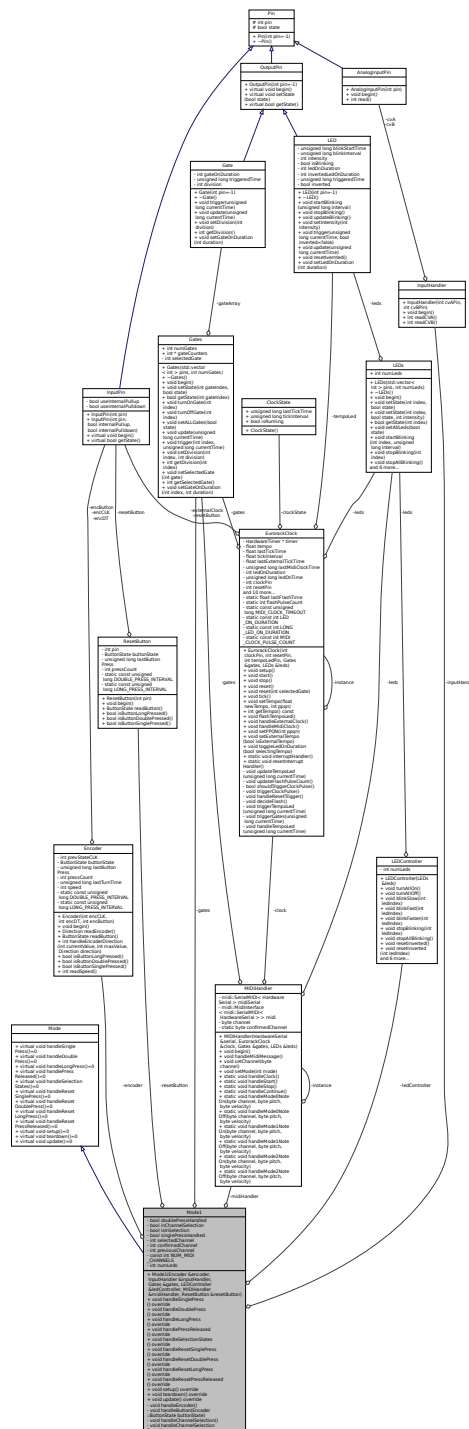
4.16 Mode1 Class Reference

```
#include <Mode1.h>
```

Inheritance diagram for Mode1:



Collaboration diagram for Mode1:



Public Member Functions

- `Model1 (Encoder &encoder, InputHandler &inputHandler, Gates &gates, LEDController &ledController, MIDIHandler &midiHandler, ResetButton &resetButton)`
- `void handleSinglePress ()` override
- `void handleDoublePress ()` override
- `void handleLongPress ()` override

- void [handlePressReleased](#) () override
- void [handleSelectionStates](#) () override
- void [handleResetSinglePress](#) () override
- void [handleResetDoublePress](#) () override
- void [handleResetLongPress](#) () override
- void [handleResetPressReleased](#) () override
- void [setup](#) () override
- void [teardown](#) () override
- void [update](#) () override

Private Member Functions

- void [handleEncoder](#) ()
- void [handleButton](#) ([Encoder::ButtonState](#) buttonState)
- void [handleChannelSelection](#) ()
- void [handleChannelSelectionPress](#) ()

Private Attributes

- [LEDController](#) & [ledController](#)
- [InputHandler](#) & [inputHandler](#)
- [Encoder](#) & [encoder](#)
- [ResetButton](#) & [resetButton](#)
- [Gates](#) & [gates](#)
- [MIDIHandler](#) & [midiHandler](#)
- bool [doublePressHandled](#) = false
- bool [inChannelSelection](#) = false
- bool [isInSelection](#) = false
- bool [singlePressHandled](#) = false
- int [selectedChannel](#) = 9
- int [confirmedChannel](#) = 9
- int [previousChannel](#) = -1
- const int [NUM_MIDI_CHANNELS](#) = 16
- int [numLeds](#) = 8

4.16.1 Constructor & Destructor Documentation

4.16.1.1 Mode1()

```
Model::Model (
    Encoder & encoder,
    InputHandler & inputHandler,
    Gates & gates,
    LEDController & ledController,
    MIDIHandler & midiHandler,
    ResetButton & resetButton )
```

4.16.2 Member Function Documentation

4.16.2.1 `handleButton()`

```
void Model::handleButton (
    Encoder::ButtonState buttonState ) [private]
```

4.16.2.2 `handleChannelSelection()`

```
void Model::handleChannelSelection ( ) [private]
```

4.16.2.3 `handleChannelSelectionPress()`

```
void Model::handleChannelSelectionPress ( ) [private]
```

4.16.2.4 `handleDoublePress()`

```
void Model::handleDoublePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.5 `handleEncoder()`

```
void Model::handleEncoder ( ) [private]
```

4.16.2.6 `handleLongPress()`

```
void Model::handleLongPress ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.7 handlePressReleased()

```
void Model::handlePressReleased ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.8 handleResetDoublePress()

```
void Model::handleResetDoublePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.9 handleResetLongPress()

```
void Model::handleResetLongPress ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.10 handleResetPressReleased()

```
void Model::handleResetPressReleased ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.11 handleResetSinglePress()

```
void Model::handleResetSinglePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.12 handleSelectionStates()

```
void Model::handleSelectionStates ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.13 handleSinglePress()

```
void Model::handleSinglePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.14 setup()

```
void Model::setup ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.15 teardown()

```
void Model::teardown ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.2.16 update()

```
void Model::update ( ) [override], [virtual]
```

Implements [Mode](#).

4.16.3 Member Data Documentation

4.16.3.1 confirmedChannel

```
int Model::confirmedChannel = 9 [private]
```

4.16.3.2 doublePressHandled

```
bool Model::doublePressHandled = false [private]
```

4.16.3.3 encoder

```
Encoder& Model::encoder [private]
```

4.16.3.4 gates

```
Gates& Model::gates [private]
```

4.16.3.5 inChannelSelection

```
bool Model::inChannelSelection = false [private]
```

4.16.3.6 inputHandler

```
InputHandler& Model::inputHandler [private]
```

4.16.3.7 isInSelection

```
bool Model::isInSelection = false [private]
```

4.16.3.8 ledController

```
LEDController& Model::ledController [private]
```

4.16.3.9 midiHandler

```
MIDIHandler& Model::midiHandler [private]
```

4.16.3.10 NUM_MIDI_CHANNELS

```
const int Model::NUM_MIDI_CHANNELS = 16 [private]
```

4.16.3.11 numLeds

```
int Model::numLeds = 8 [private]
```

4.16.3.12 previousChannel

```
int Model::previousChannel = -1 [private]
```

4.16.3.13 resetButton

```
ResetButton& Model::resetButton [private]
```

4.16.3.14 selectedChannel

```
int Model::selectedChannel = 9 [private]
```

4.16.3.15 singlePressHandled

```
bool Model::singlePressHandled = false [private]
```

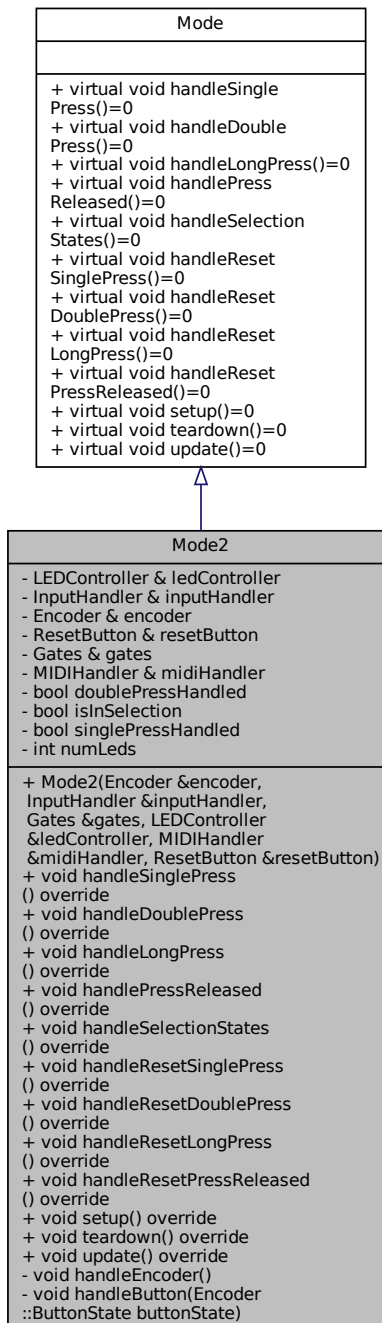
The documentation for this class was generated from the following files:

- [include/Model.h](#)
- [src/Model.cpp](#)

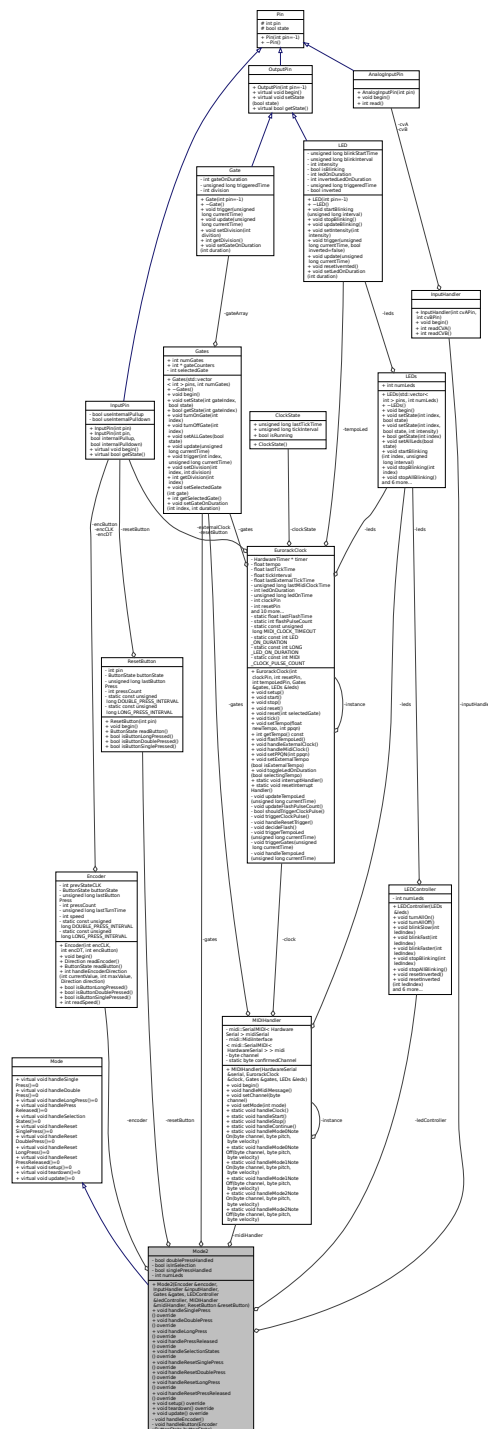
4.17 Mode2 Class Reference

```
#include <Mode2.h>
```

Inheritance diagram for Mode2:



Collaboration diagram for Mode2:



Public Member Functions

- `Mode2` (`Encoder &encoder`, `InputHandler &inputHandler`, `Gates &gates`, `LEDController &ledController`, `MIDIHandler &midiHandler`, `ResetButton &resetButton`)
- `void handleSinglePress ()` override
- `void handleDoublePress ()` override
- `void handleLongPress ()` override

- void `handlePressReleased` () override
- void `handleSelectionStates` () override
- void `handleResetSinglePress` () override
- void `handleResetDoublePress` () override
- void `handleResetLongPress` () override
- void `handleResetPressReleased` () override
- void `setup` () override
- void `teardown` () override
- void `update` () override

Private Member Functions

- void `handleEncoder` ()
- void `handleButton` (`Encoder::ButtonState` buttonState)

Private Attributes

- `LEDController` & `ledController`
- `InputHandler` & `inputHandler`
- `Encoder` & `encoder`
- `ResetButton` & `resetButton`
- `Gates` & `gates`
- `MIDIHandler` & `midiHandler`
- bool `doublePressHandled` = false
- bool `isInSelection` = false
- bool `singlePressHandled` = false
- int `numLeds` = 8

4.17.1 Constructor & Destructor Documentation

4.17.1.1 Mode2()

```
Mode2::Mode2 (  
    Encoder & encoder,  
    InputHandler & inputHandler,  
    Gates & gates,  
    LEDController & ledController,  
    MIDIHandler & midiHandler,  
    ResetButton & resetButton )
```

4.17.2 Member Function Documentation

4.17.2.1 `handleButton()`

```
void Mode2::handleButton (
    Encoder::ButtonState buttonState ) [private]
```

4.17.2.2 `handleDoublePress()`

```
void Mode2::handleDoublePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.3 `handleEncoder()`

```
void Mode2::handleEncoder ( ) [private]
```

4.17.2.4 `handleLongPress()`

```
void Mode2::handleLongPress ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.5 `handlePressReleased()`

```
void Mode2::handlePressReleased ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.6 `handleResetDoublePress()`

```
void Mode2::handleResetDoublePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.7 handleResetLongPress()

```
void Mode2::handleResetLongPress ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.8 handleResetPressReleased()

```
void Mode2::handleResetPressReleased ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.9 handleResetSinglePress()

```
void Mode2::handleResetSinglePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.10 handleSelectionStates()

```
void Mode2::handleSelectionStates ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.11 handleSinglePress()

```
void Mode2::handleSinglePress ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.12 setup()

```
void Mode2::setup ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.13 teardown()

```
void Mode2::teardown ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.2.14 update()

```
void Mode2::update ( ) [override], [virtual]
```

Implements [Mode](#).

4.17.3 Member Data Documentation

4.17.3.1 doublePressHandled

```
bool Mode2::doublePressHandled = false [private]
```

4.17.3.2 encoder

```
Encoder& Mode2::encoder [private]
```

4.17.3.3 gates

```
Gates& Mode2::gates [private]
```

4.17.3.4 inputHandler

```
InputHandler& Mode2::inputHandler [private]
```

4.17.3.5 isInSelection

```
bool Mode2::isInSelection = false [private]
```

4.17.3.6 ledController

```
LEDController& Mode2::ledController [private]
```

4.17.3.7 midiHandler

```
MIDIHandler& Mode2::midiHandler [private]
```

4.17.3.8 numLeds

```
int Mode2::numLeds = 8 [private]
```

4.17.3.9 resetButton

```
ResetButton& Mode2::resetButton [private]
```

4.17.3.10 singlePressHandled

```
bool Mode2::singlePressHandled = false [private]
```

The documentation for this class was generated from the following files:

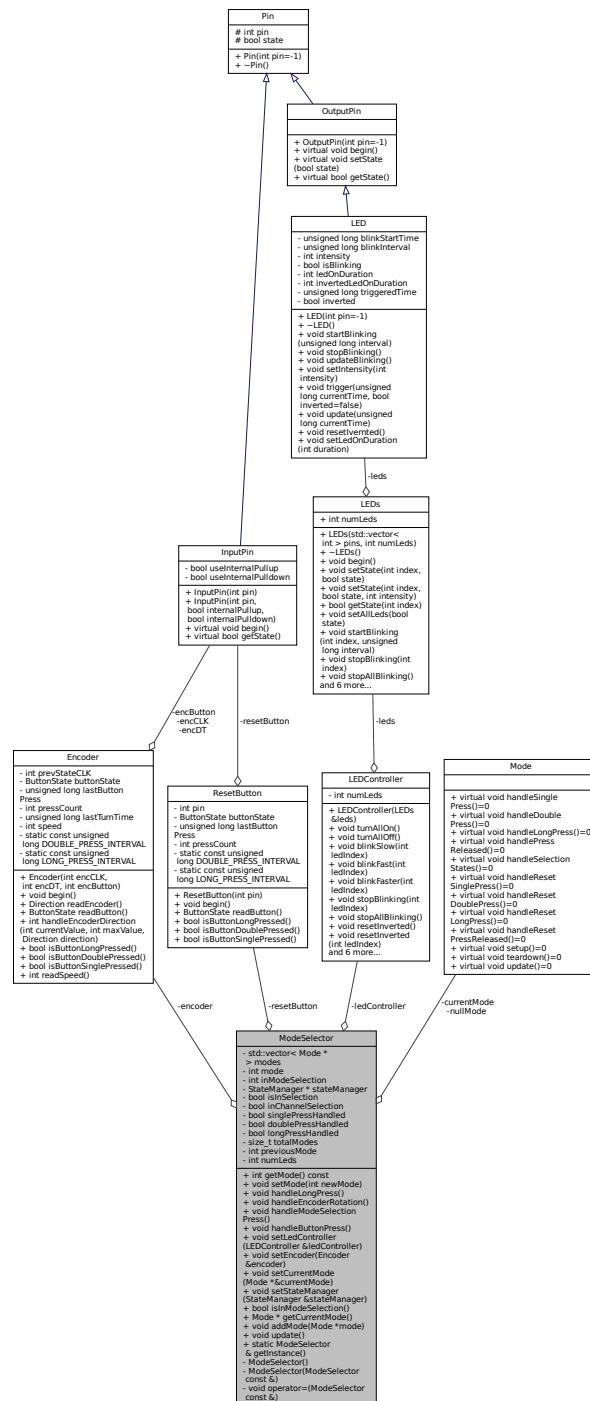
- include/Mode2.h
- src/Mode2.cpp

4.18 ModeSelector Class Reference

Mode Selector Singleton. This class is responsible for managing the different modes of the device. It provides methods to add modes, set the current mode, and handle mode selection.

```
#include <ModeSelector.h>
```

Collaboration diagram for ModeSelector:



Public Member Functions

- int [getMode](#) () const
- void [setMode](#) (int newMode)
- void [handleLongPress](#) ()
- void [handleEncoderRotation](#) ()
- void [handleModeSelectionPress](#) ()
- void [handleButtonPress](#) ()
- void [setLedController](#) (LEDController &ledController)
- void [setEncoder](#) (Encoder &encoder)
- void [setCurrentMode](#) (Mode *¤tMode)
- void [setStateManager](#) (StateManager &stateManager)
- bool [isInModeSelection](#) ()
- Mode * [getCurrentMode](#) ()
- void [addMode](#) (Mode *mode)
- void [update](#) ()

Static Public Member Functions

- static ModeSelector & [getInstance](#) ()

Private Member Functions

- [ModeSelector](#) ()
Constructor is private.
- [ModeSelector](#) (ModeSelector const &)
- void [operator=](#) (ModeSelector const &)

Private Attributes

- std::vector< Mode * > [modes](#)
- Mode * [nullMode](#) = nullptr
- Mode *& [currentMode](#)
- int [mode](#)
- int [inModeSelection](#) = false
- LEDController * [ledController](#)
- Encoder * [encoder](#)
- StateManager * [stateManager](#)
- ResetButton * [resetButton](#)
- bool [isInSelection](#)
- bool [inChannelSelection](#)
- bool [singlePressHandled](#)
- bool [doublePressHandled](#)
- bool [longPressHandled](#)
- size_t [totalModes](#) = modes.size()
- int [previousMode](#) = -1
- int [numLeds](#)

4.18.1 Detailed Description

[Mode](#) Selector Singleton. This class is responsible for managing the different modes of the device. It provides methods to add modes, set the current mode, and handle mode selection.

4.18.2 Constructor & Destructor Documentation

4.18.2.1 ModeSelector() [1/2]

```
ModeSelector::ModeSelector ( ) [private]
```

Constructor is private.

4.18.2.2 ModeSelector() [2/2]

```
ModeSelector::ModeSelector (
    ModeSelector const & ) [private]
```

4.18.3 Member Function Documentation

4.18.3.1 addMode()

```
void ModeSelector::addMode (
    Mode * mode )
```

4.18.3.2 getCurrentMode()

```
Mode * ModeSelector::getCurrentMode ( )
```

4.18.3.3 getInstance()

```
ModeSelector & ModeSelector::getInstance ( ) [static]
```

4.18.3.4 getMode()

```
int ModeSelector::getMode ( ) const
```


4.18.3.5 handleButtonPress()

```
void ModeSelector::handleButtonPress ( )
```

4.18.3.6 handleEncoderRotation()

```
void ModeSelector::handleEncoderRotation ( )
```

4.18.3.7 handleLongPress()

```
void ModeSelector::handleLongPress ( )
```

4.18.3.8 handleModeSelectionPress()

```
void ModeSelector::handleModeSelectionPress ( )
```

4.18.3.9 isInModeSelection()

```
bool ModeSelector::isInModeSelection ( )
```

4.18.3.10 operator=()

```
void ModeSelector::operator= (
    ModeSelector const & ) [private]
```

4.18.3.11 setCurrentMode()

```
void ModeSelector::setCurrentMode (
    Mode *& currentMode )
```

4.18.3.12 setEncoder()

```
void ModeSelector::setEncoder (
    Encoder & encoder )
```

4.18.3.13 setLedController()

```
void ModeSelector::setLedController (
    LEDController & ledController )
```

4.18.3.14 setMode()

```
void ModeSelector::setMode (
    int newMode )
```

4.18.3.15 setStateManager()

```
void ModeSelector::setStateManager (
    StateManager & stateManager )
```

4.18.3.16 update()

```
void ModeSelector::update ( )
```

4.18.4 Member Data Documentation

4.18.4.1 currentMode

```
Mode*& ModeSelector::currentMode [private]
```

4.18.4.2 doublePressHandled

```
bool ModeSelector::doublePressHandled [private]
```

4.18.4.3 encoder

```
Encoder* ModeSelector::encoder [private]
```

4.18.4.4 inChannelSelection

```
bool ModeSelector::inChannelSelection [private]
```

4.18.4.5 inModeSelection

```
int ModeSelector::inModeSelection = false [private]
```

4.18.4.6 isInSelection

```
bool ModeSelector::isInSelection [private]
```

4.18.4.7 ledController

```
LEDController* ModeSelector::ledController [private]
```

4.18.4.8 longPressHandled

```
bool ModeSelector::longPressHandled [private]
```

4.18.4.9 mode

```
int ModeSelector::mode [private]
```

4.18.4.10 modes

```
std::vector<Mode*> ModeSelector::modes [private]
```

4.18.4.11 nullMode

```
Mode* ModeSelector::nullMode = nullptr [private]
```

4.18.4.12 numLeds

```
int ModeSelector::numLeds [private]
```

4.18.4.13 previousMode

```
int ModeSelector::previousMode = -1 [private]
```

4.18.4.14 resetButton

```
ResetButton* ModeSelector::resetButton [private]
```

4.18.4.15 singlePressHandled

```
bool ModeSelector::singlePressHandled [private]
```

4.18.4.16 stateManager

```
StateManager* ModeSelector::stateManager [private]
```

4.18.4.17 totalModes

```
size_t ModeSelector::totalModes = modes.size() [private]
```

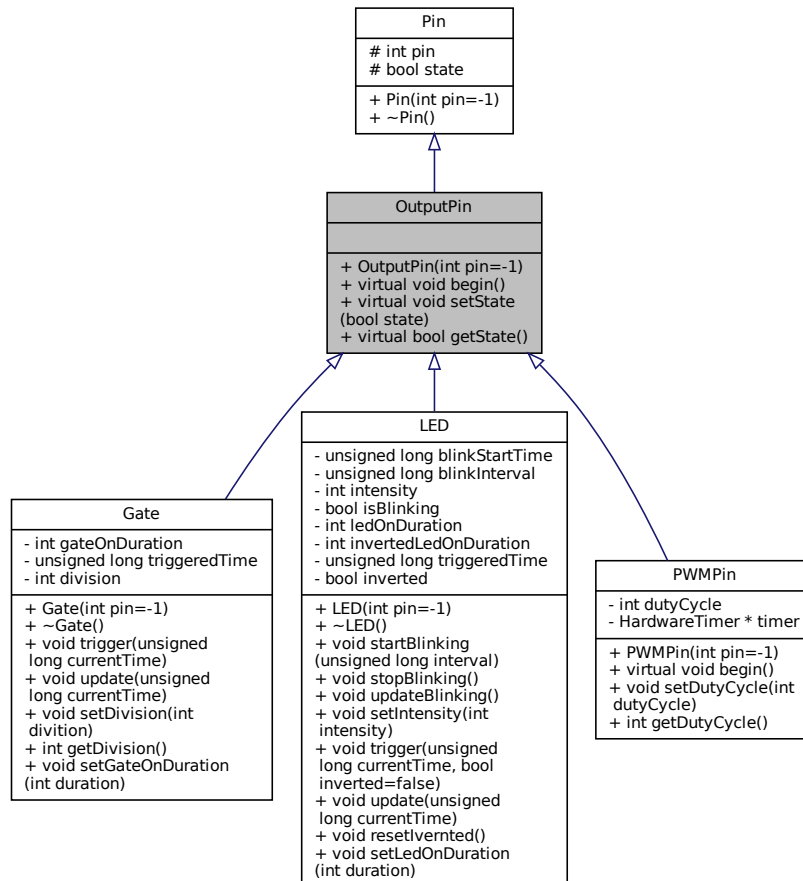
The documentation for this class was generated from the following files:

- [include/ModeSelector.h](#)
- [src/ModeSelector.cpp](#)

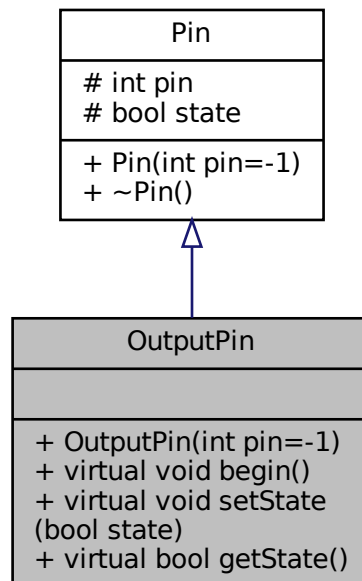
4.19 OutputPin Class Reference

```
#include <Pin.h>
```

Inheritance diagram for OutputPin:



Collaboration diagram for OutputPin:



Public Member Functions

- [OutputPin](#) (int [pin](#)=-1)
- virtual void [begin](#) ()
- virtual void [setState](#) (bool [state](#))
- virtual bool [getState](#) ()

Additional Inherited Members

4.19.1 Constructor & Destructor Documentation

4.19.1.1 OutputPin()

```
OutputPin::OutputPin (
    int pin = -1 )
```

4.19.2 Member Function Documentation

4.19.2.1 begin()

```
void OutputPin::begin ( ) [virtual]
```

Reimplemented in [PWMPin](#).

4.19.2.2 getState()

```
bool OutputPin::getState ( ) [virtual]
```

4.19.2.3 setState()

```
void OutputPin::setState (
    bool state ) [virtual]
```

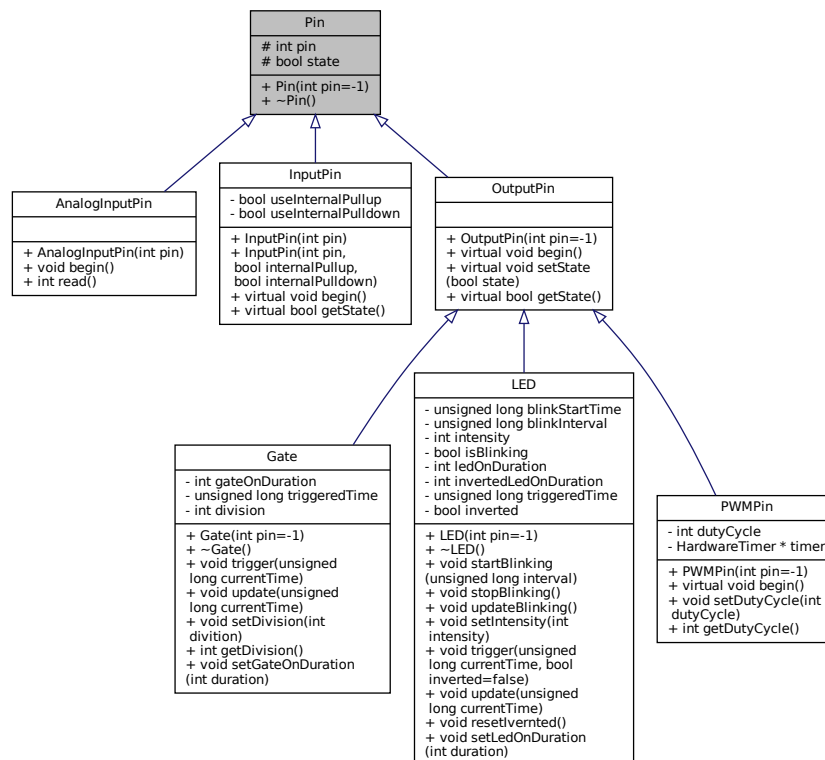
The documentation for this class was generated from the following files:

- [include/Pin.h](#)
- [src/Pin.cpp](#)

4.20 Pin Class Reference

```
#include <Pin.h>
```

Inheritance diagram for Pin:



Collaboration diagram for Pin:

Pin
int pin # bool state
+ Pin(int pin=-1) + ~Pin()

Public Member Functions

- [Pin](#) (int [pin](#)=-1)
- [~Pin](#) ()

Protected Attributes

- int [pin](#)
- bool [state](#)

4.20.1 Constructor & Destructor Documentation

4.20.1.1 Pin()

```
Pin::Pin (
    int pin = -1 )
```

4.20.1.2 ~Pin()

```
Pin::~~Pin ( )
```

4.20.2 Member Data Documentation

4.20.2.1 pin

```
int Pin::pin [protected]
```

4.20.2.2 state

```
bool Pin::state [protected]
```

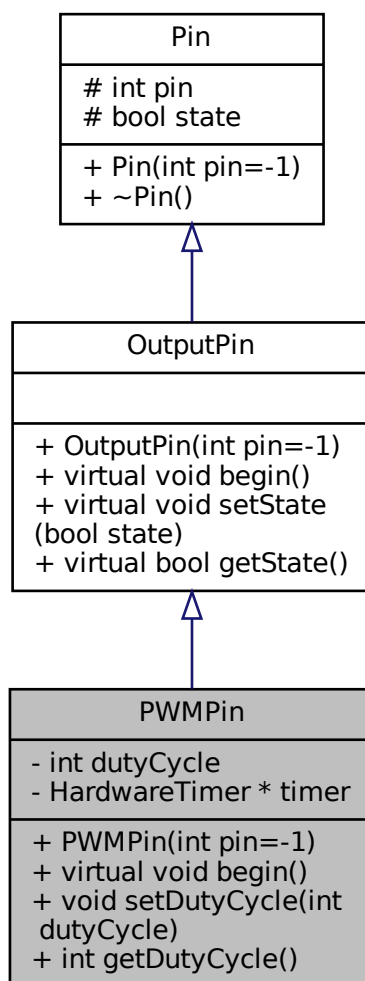
The documentation for this class was generated from the following files:

- include/[Pin.h](#)
- src/[Pin.cpp](#)

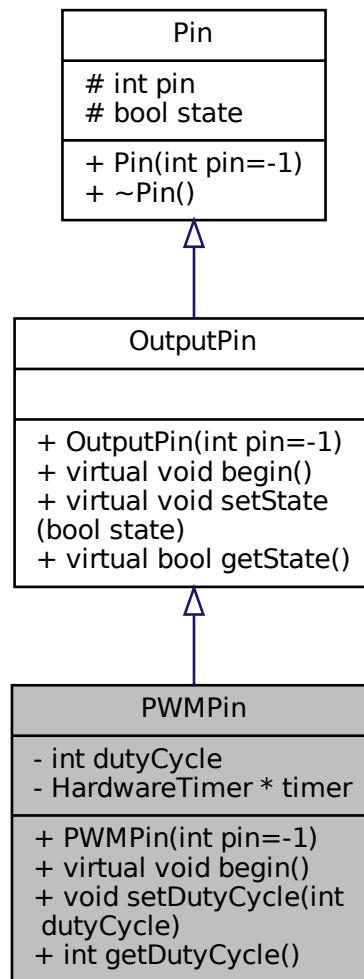
4.21 PWMPin Class Reference

```
#include <Pin.h>
```

Inheritance diagram for PWMPin:



Collaboration diagram for PWMPin:



Public Member Functions

- [PWMPin](#) (int [pin](#)=-1)
- virtual void [begin](#) ()
- void [setDutyCycle](#) (int [dutyCycle](#))
- int [getDutyCycle](#) ()

Private Attributes

- int [dutyCycle](#)
- HardwareTimer * [timer](#)

Additional Inherited Members

4.21.1 Constructor & Destructor Documentation

4.21.1.1 PWMPin()

```
PWMPin::PWMPin (
    int pin = -1 )
```

4.21.2 Member Function Documentation

4.21.2.1 begin()

```
void PWMPin::begin ( ) [virtual]
```

Reimplemented from [OutputPin](#).

4.21.2.2 getDutyCycle()

```
int PWMPin::getDutyCycle ( )
```

4.21.2.3 setDutyCycle()

```
void PWMPin::setDutyCycle (
    int dutyCycle )
```

4.21.3 Member Data Documentation

4.21.3.1 dutyCycle

```
int PWMPin::dutyCycle [private]
```

4.21.3.2 timer

```
HardwareTimer* PWMPin::timer [private]
```

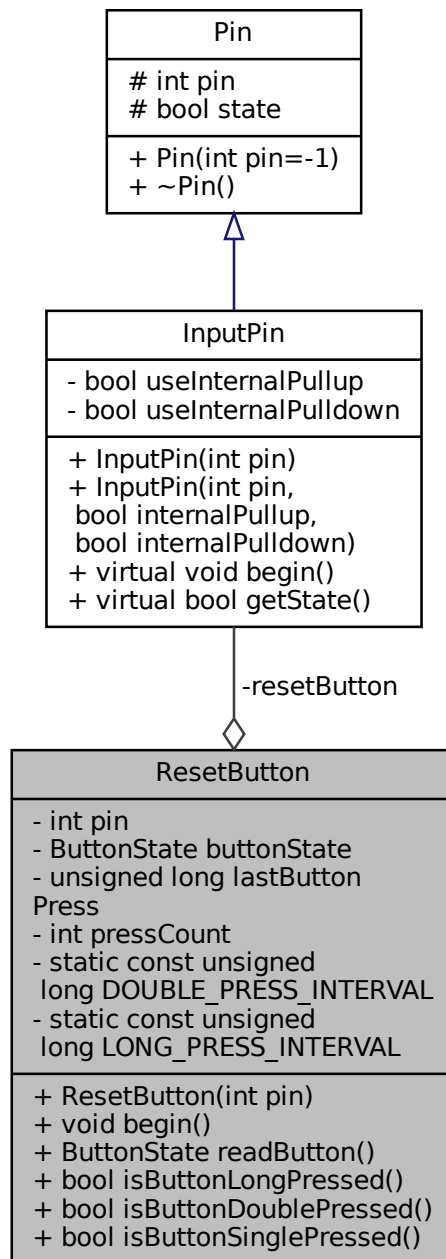
The documentation for this class was generated from the following files:

- [include/Pin.h](#)
- [src/Pin.cpp](#)

4.22 ResetButton Class Reference

```
#include <ResetButton.h>
```

Collaboration diagram for ResetButton:



Public Types

- enum [ButtonState](#) { [OPEN](#) , [PRESSED](#) }

Public Member Functions

- [ResetButton](#) (int [pin](#))

- void `begin` ()
- `ButtonState` `readButton` ()
- bool `isButtonLongPressed` ()
- bool `isButtonDoublePressed` ()
- bool `isButtonSinglePressed` ()

Private Attributes

- int `pin`
- `InputPin` `resetButton`
- `ButtonState` `buttonState`
- unsigned long `lastButtonPress`
- int `pressCount`

Static Private Attributes

- static const unsigned long `DOUBLE_PRESS_INTERVAL` = 500
- static const unsigned long `LONG_PRESS_INTERVAL` = 1000

4.22.1 Member Enumeration Documentation

4.22.1.1 ButtonState

enum `ResetButton::ButtonState`

Enumerator

OPEN	
PRESSED	

4.22.2 Constructor & Destructor Documentation

4.22.2.1 ResetButton()

```
ResetButton::ResetButton (
    int pin )
```

4.22.3 Member Function Documentation

4.22.3.1 begin()

```
void ResetButton::begin ( )
```

4.22.3.2 isButtonDoublePressed()

```
bool ResetButton::isButtonDoublePressed ( )
```

4.22.3.3 isButtonLongPressed()

```
bool ResetButton::isButtonLongPressed ( )
```

4.22.3.4 isButtonSinglePressed()

```
bool ResetButton::isButtonSinglePressed ( )
```

4.22.3.5 readButton()

```
ResetButton::ButtonState ResetButton::readButton ( )
```

4.22.4 Member Data Documentation

4.22.4.1 buttonState

```
ButtonState ResetButton::buttonState [private]
```

4.22.4.2 DOUBLE_PRESS_INTERVAL

```
const unsigned long ResetButton::DOUBLE_PRESS_INTERVAL = 500 [static], [private]
```


4.22.4.3 lastButtonPress

```
unsigned long ResetButton::lastButtonPress [private]
```

4.22.4.4 LONG_PRESS_INTERVAL

```
const unsigned long ResetButton::LONG_PRESS_INTERVAL = 1000 [static], [private]
```

4.22.4.5 pin

```
int ResetButton::pin [private]
```

4.22.4.6 pressCount

```
int ResetButton::pressCount [private]
```

4.22.4.7 resetButton

```
InputPin ResetButton::resetButton [private]
```

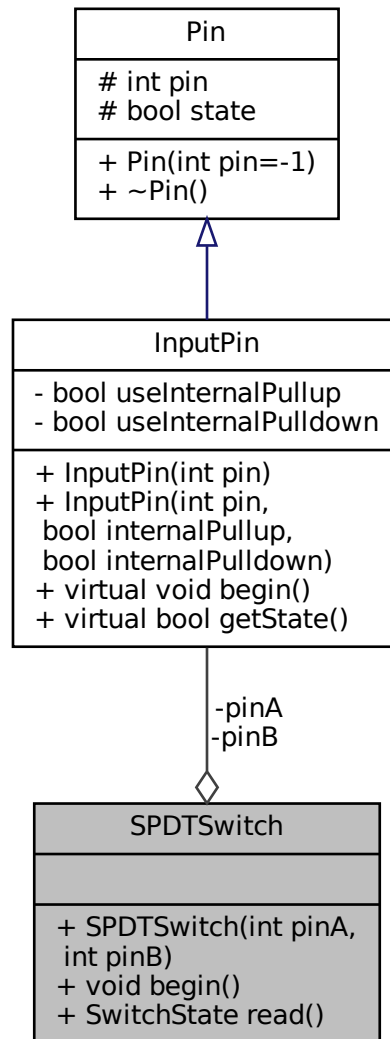
The documentation for this class was generated from the following files:

- [include/ResetButton.h](#)
- [src/ResetButton.cpp](#)

4.23 SPDTSwitch Class Reference

```
#include <SPDTSwitch.h>
```

Collaboration diagram for SPDTSwitch:



Public Member Functions

- [SPDTSwitch](#) (int [pinA](#), int [pinB](#))
- void [begin](#) ()
- [SwitchState](#) [read](#) ()

Private Attributes

- [InputPin](#) [pinA](#)
- [InputPin](#) [pinB](#)

4.23.1 Constructor & Destructor Documentation

4.23.1.1 SPDTSwitch()

```
SPDTSwitch::SPDTSwitch (
    int pinA,
    int pinB )
```

4.23.2 Member Function Documentation

4.23.2.1 begin()

```
void SPDTSwitch::begin ( )
```

4.23.2.2 read()

```
SwitchState SPDTSwitch::read ( )
```

4.23.3 Member Data Documentation

4.23.3.1 pinA

```
InputPin SPDTSwitch::pinA [private]
```

4.23.3.2 pinB

```
InputPin SPDTSwitch::pinB [private]
```

The documentation for this class was generated from the following files:

- [include/SPDTSwitch.h](#)
- [src/SPDTSwitch.cpp](#)

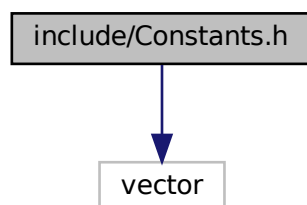
Chapter 5

File Documentation

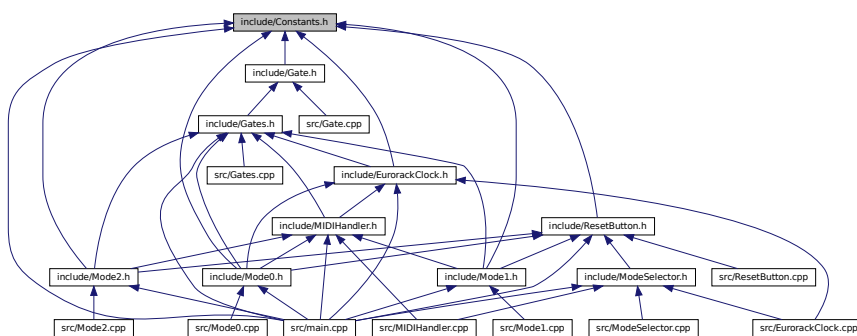
5.1 include/Constants.h File Reference

```
#include <vector>
```

Include dependency graph for Constants.h:



This graph shows which files directly or indirectly include this file:



Variables

- `std::vector< int >` [musicalIntervals](#)
- `const int` [musicalIntervalsSize](#)
Size of musical intervals array.
- `unsigned char` [internalPPQN](#)
Pulses per quarter note.

5.1.1 Variable Documentation

5.1.1.1 internalPPQN

```
unsigned char internalPPQN [extern]
```

Pulses per quarter note.

5.1.1.2 musicalIntervals

```
std::vector<int> musicalIntervals [extern]
```

5.1.1.3 musicalIntervalsSize

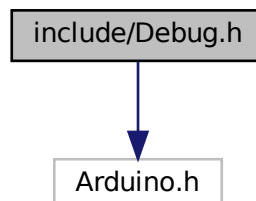
```
const int musicalIntervalsSize [extern]
```

Size of musical intervals array.

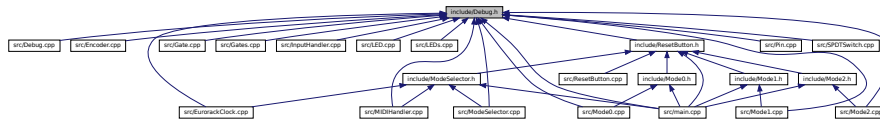
5.2 include/Debug.h File Reference

```
#include <Arduino.h>
```

Include dependency graph for Debug.h:



This graph shows which files directly or indirectly include this file:



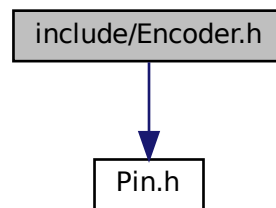
Classes

- class **Debug**

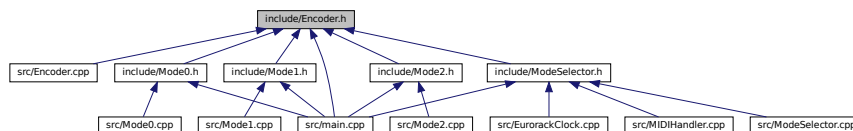
5.3 include/Encoder.h File Reference

```
#include "Pin.h"
```

Include dependency graph for Encoder.h:



This graph shows which files directly or indirectly include this file:



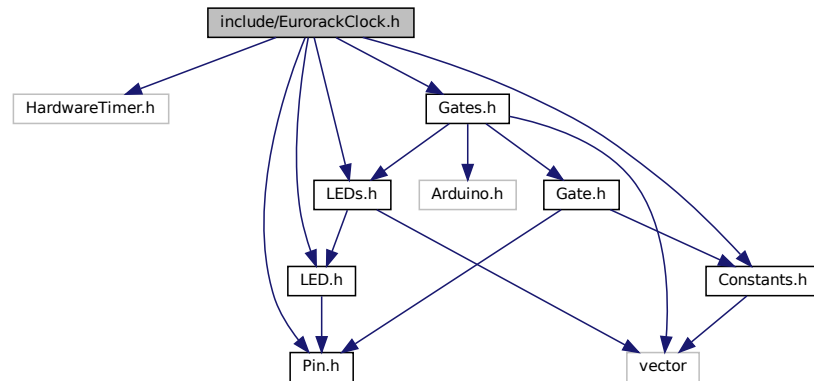
Classes

- class Encoder

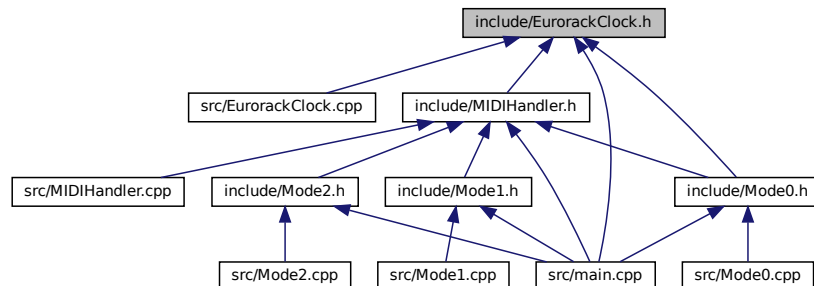
5.4 include/EurorackClock.h File Reference

```
#include <HardwareTimer.h>
#include "LED.h"
#include "Pin.h"
#include "Gates.h"
#include "LEDs.h"
#include "Constants.h"
```

Include dependency graph for EurorackClock.h:



This graph shows which files directly or indirectly include this file:

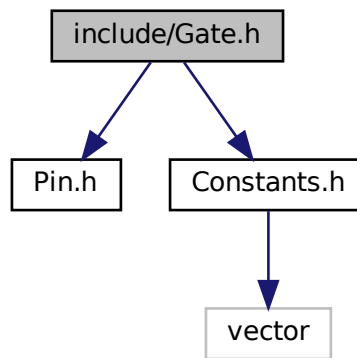


Classes

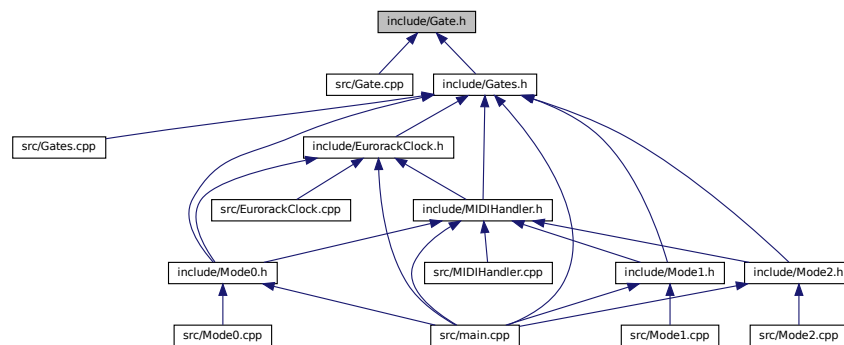
- struct [ClockState](#)
- class [EurorackClock](#)

5.5 include/Gate.h File Reference

```
#include "Pin.h"
#include "Constants.h"
Include dependency graph for Gate.h:
```



This graph shows which files directly or indirectly include this file:



Classes

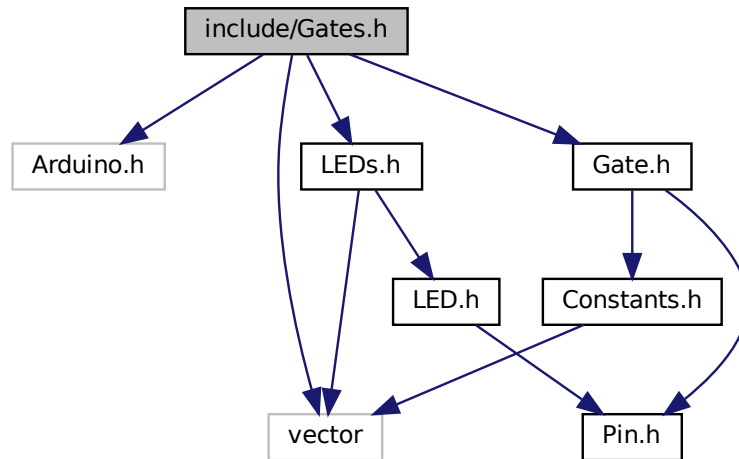
- class [Gate](#)

5.6 include/Gates.h File Reference

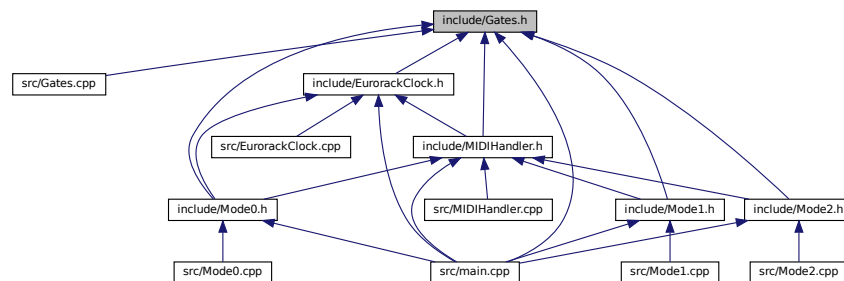
```
#include <Arduino.h>
#include "Gate.h"
#include "LEDs.h"
```

```
#include <vector>
```

Include dependency graph for Gates.h:



This graph shows which files directly or indirectly include this file:



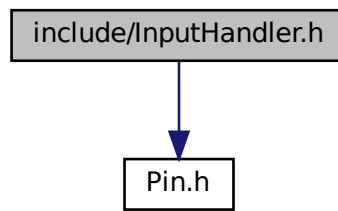
Classes

- class [Gates](#)

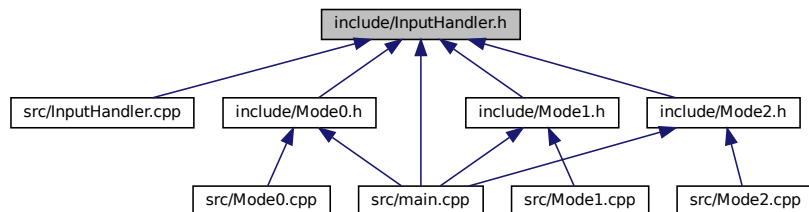
5.7 include/InputHandler.h File Reference

```
#include "Pin.h"
```

Include dependency graph for InputHandler.h:



This graph shows which files directly or indirectly include this file:



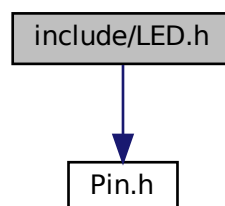
Classes

- class [InputHandler](#)

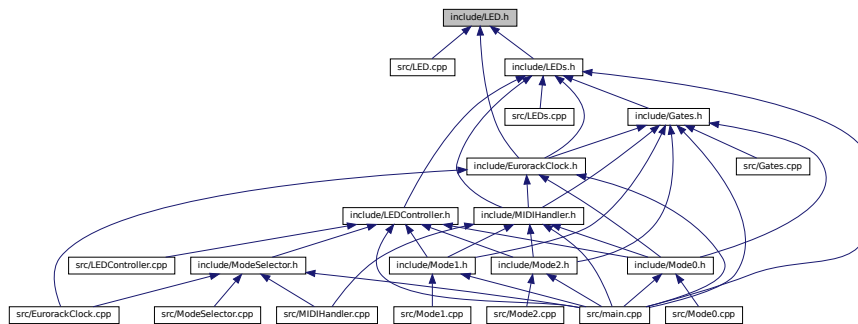
5.8 include/LED.h File Reference

```
#include "Pin.h"
```

Include dependency graph for LED.h:



This graph shows which files directly or indirectly include this file:



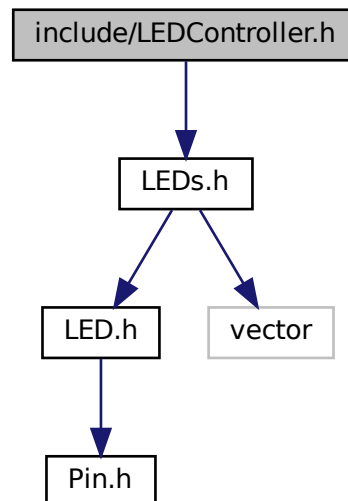
Classes

- class [LED](#)

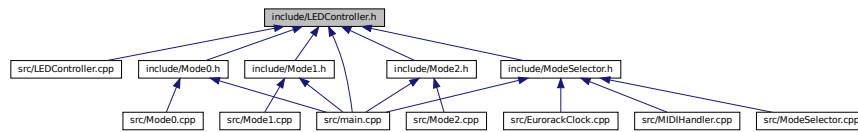
5.9 include/LEDController.h File Reference

```
#include "LEDs.h"
```

Include dependency graph for LEDController.h:



This graph shows which files directly or indirectly include this file:



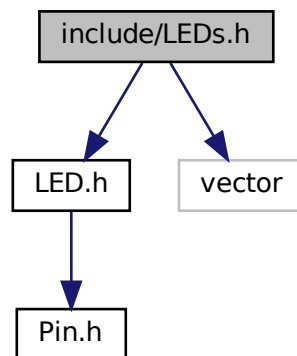
Classes

- class [LEDController](#)

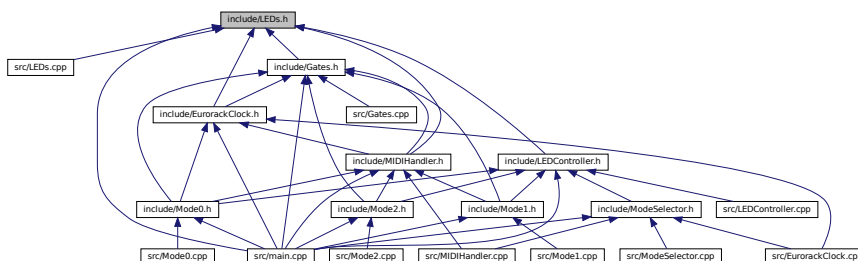
5.10 include/LEDs.h File Reference

```
#include "LED.h"
#include <vector>
```

Include dependency graph for LEDs.h:



This graph shows which files directly or indirectly include this file:



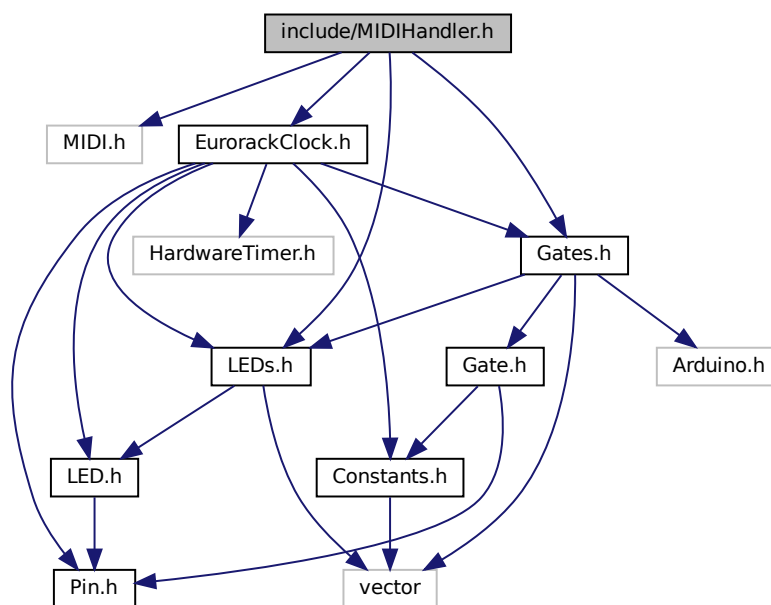
Classes

- class [LEDs](#)

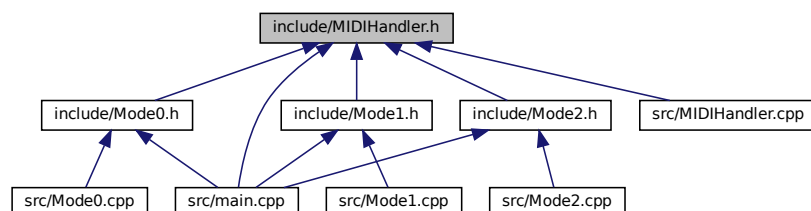
5.11 include/MIDIHandler.h File Reference

```
#include <MIDI.h>
#include "EurorackClock.h"
#include "Gates.h"
#include "LEDs.h"
```

Include dependency graph for MIDIHandler.h:



This graph shows which files directly or indirectly include this file:

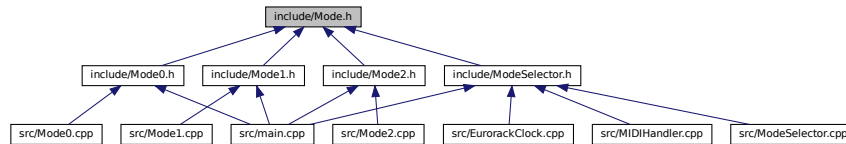


Classes

- class [MIDIHandler](#)

5.12 include/Mode.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

- class [Mode](#)

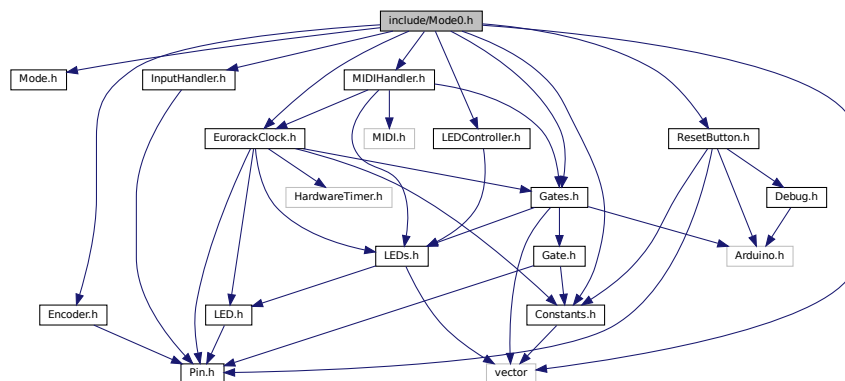
5.13 include/Mode0.h File Reference

```

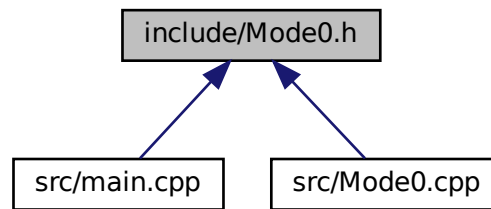
#include "Mode.h"
#include "Encoder.h"
#include "Gates.h"
#include "LEDController.h"
#include "EurorackClock.h"
#include "MIDIHandler.h"
#include "Constants.h"
#include "ResetButton.h"
#include "InputHandler.h"
#include <vector>

```

Include dependency graph for Mode0.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [Mode0](#)

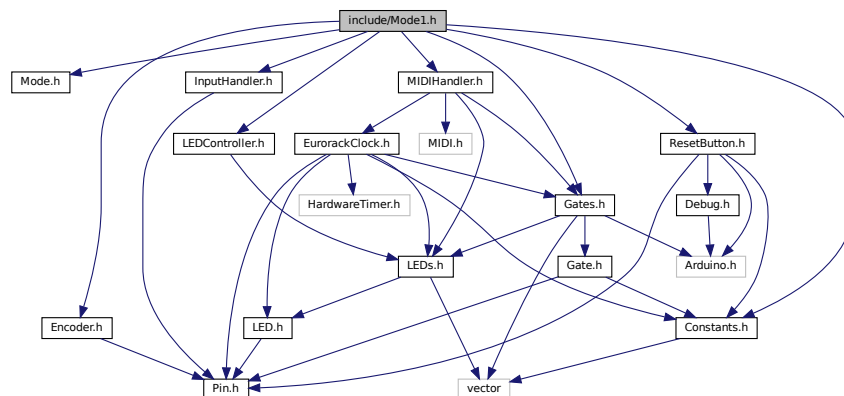
5.14 include/Mode1.h File Reference

```

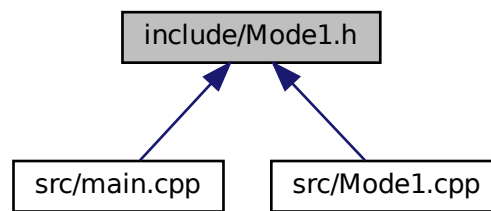
#include "Mode.h"
#include "Encoder.h"
#include "Gates.h"
#include "LEDController.h"
#include "MIDIHandler.h"
#include "Constants.h"
#include "ResetButton.h"
#include "InputHandler.h"

```

Include dependency graph for Mode1.h:



This graph shows which files directly or indirectly include this file:



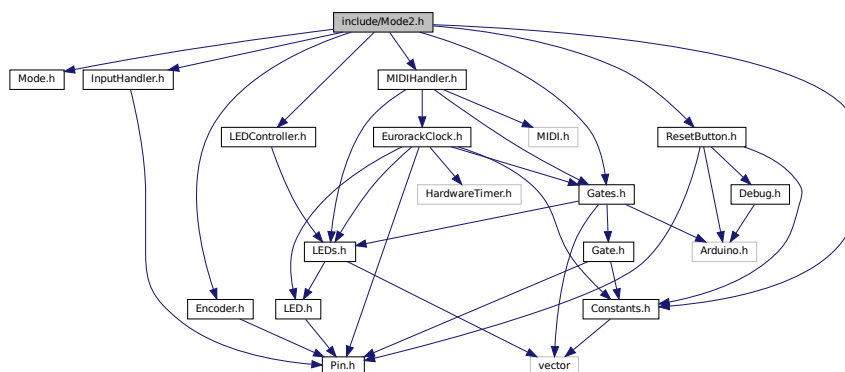
Classes

- class [Mode1](#)

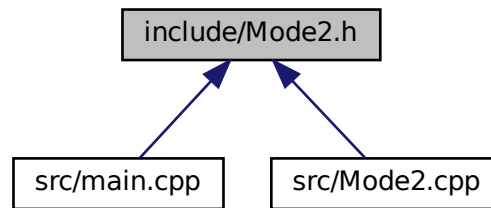
5.15 include/Mode2.h File Reference

```
#include "Mode.h"  
#include "LEDController.h"  
#include "Encoder.h"  
#include "Gates.h"  
#include "MIDIHandler.h"  
#include "Constants.h"  
#include "InputHandler.h"  
#include "ResetButton.h"
```

Include dependency graph for Mode2.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [Mode2](#)

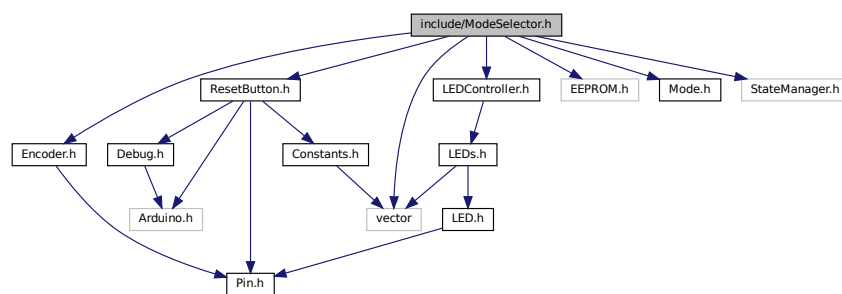
5.16 include/ModeSelector.h File Reference

```

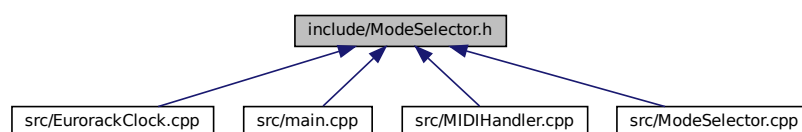
#include <vector>
#include <EEPROM.h>
#include "LEDController.h"
#include "Encoder.h"
#include "Mode.h"
#include "ResetButton.h"
#include "StateManager.h"

```

Include dependency graph for `ModeSelector.h`:



This graph shows which files directly or indirectly include this file:

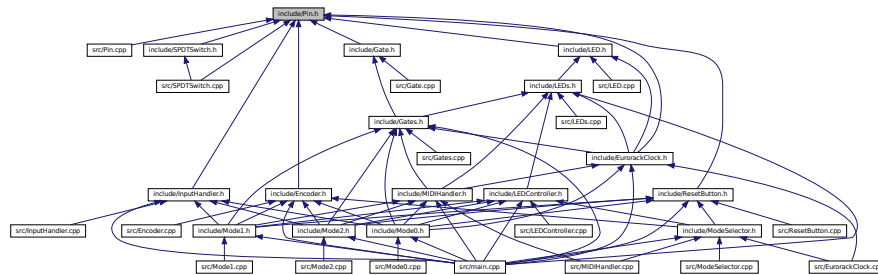


- class **ModeSelector**

Mode Selector Singleton. This class is responsible for managing the different modes of the device. It provides methods to add modes, set the current mode, and handle mode selection.

5.17 include/Pin.h File Reference

This graph shows which files directly or indirectly include this file:

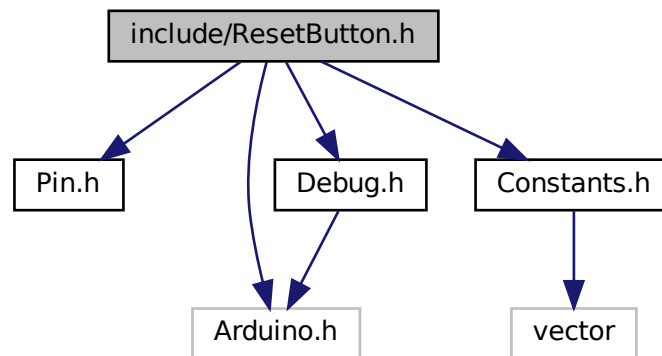


- class Pin
- class InputPin
- class AnalogInputPin
- class OutputPin
- class PWMPin

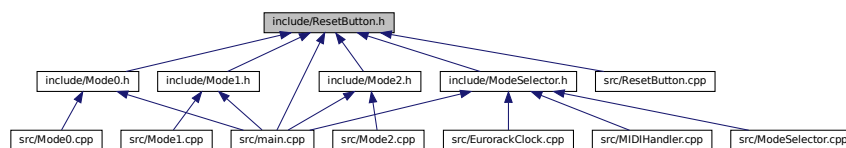
5.18 include/ResetButton.h File Reference

```
#include "Pin.h"
#include <Arduino.h>
#include "Debug.h"
#include "Constants.h"
```

Include dependency graph for ResetButton.h:



This graph shows which files directly or indirectly include this file:



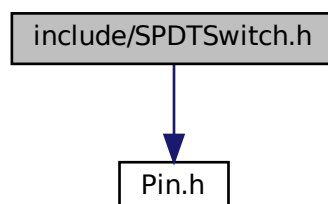
Classes

- class [ResetButton](#)

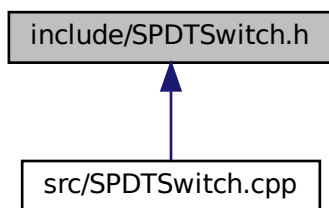
5.19 include/SPDTSwitch.h File Reference

```
#include "Pin.h"
```

Include dependency graph for SPDTSwitch.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [SPDTSwitch](#)

Enumerations

- enum [SwitchState](#) { [NEUTRAL](#) , [STATE_A](#) , [STATE_B](#) }

5.19.1 Enumeration Type Documentation

5.19.1.1 SwitchState

enum [SwitchState](#)

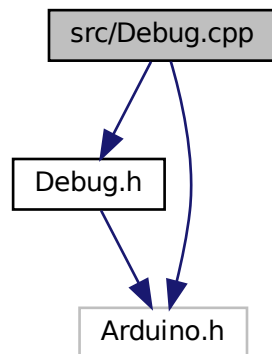
Enumerator

NEUTRAL	
STATE_A	
STATE_B	

5.20 src/Debug.cpp File Reference

```
#include "Debug.h"
#include <Arduino.h>
```

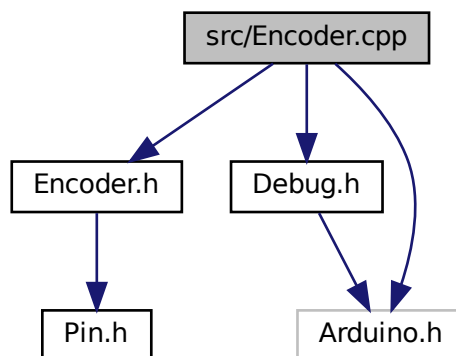
Include dependency graph for Debug.cpp:



5.21 src/Encoder.cpp File Reference

```
#include "Encoder.h"  
#include "Debug.h"  
#include <Arduino.h>
```

Include dependency graph for Encoder.cpp:



Macros

- `#define DEBUG_PRINT(message) Debug::print(__FILE__, __LINE__, __func__, String(message))`

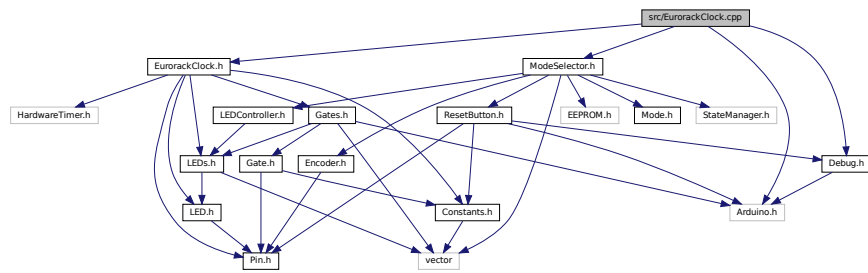
5.21.1 Macro Definition Documentation

5.21.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.22 src/EurorackClock.cpp File Reference

```
#include "EurorackClock.h"  
#include "Debug.h"  
#include <Arduino.h>  
#include "ModeSelector.h"  
Include dependency graph for EurorackClock.cpp:
```



Macros

- #define `DEBUG_PRINT`(message) `Debug::print(__FILE__, __LINE__, __func__, String(message))`

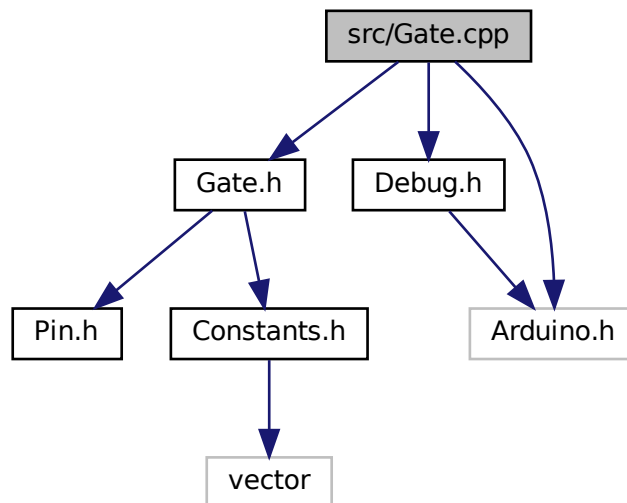
5.22.1 Macro Definition Documentation

5.22.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.23 src/Gate.cpp File Reference

```
#include "Gate.h"  
#include "Debug.h"  
#include <Arduino.h>  
Include dependency graph for Gate.cpp:
```



Macros

- `#define DEBUG_PRINT(message) Debug::print(__FILE__, __LINE__, __func__, String(message))`

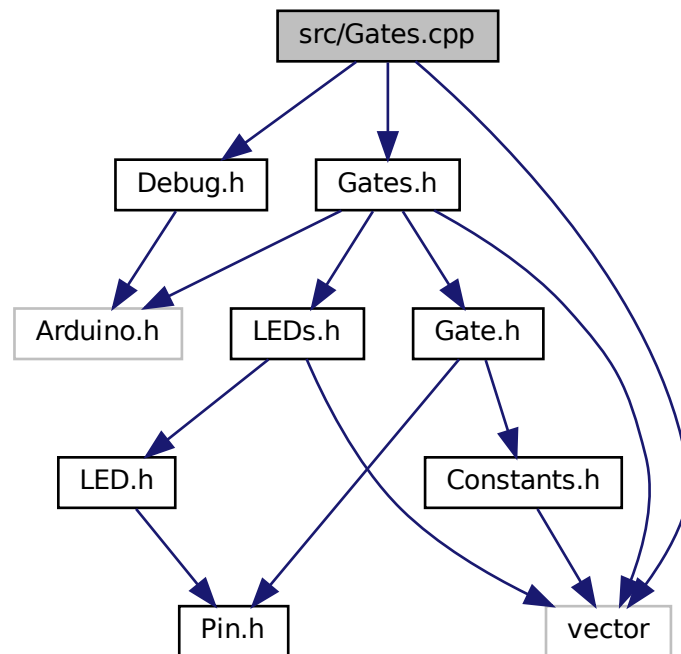
5.23.1 Macro Definition Documentation

5.23.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```


5.24 src/Gates.cpp File Reference

```
#include "Gates.h"
#include "Debug.h"
#include <vector>
Include dependency graph for Gates.cpp:
```



Macros

- `#define DEBUG_PRINT(message) Debug::print(__FILE__, __LINE__, __func__, String(message))`

5.24.1 Macro Definition Documentation

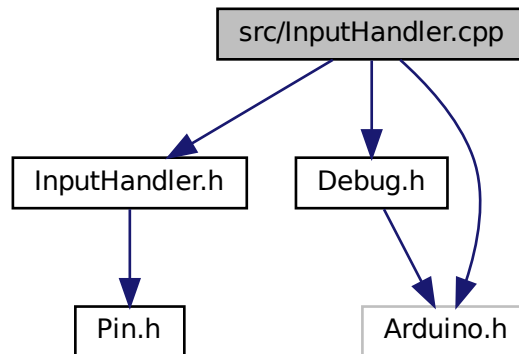
5.24.1.1 `DEBUG_PRINT`

```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.25 src/InputHandler.cpp File Reference

```
#include "InputHandler.h"  
#include "Debug.h"  
#include <Arduino.h>
```

Include dependency graph for InputHandler.cpp:



Macros

- #define `DEBUG_PRINT`(message) `Debug::print`(__FILE__, __LINE__, __func__, String(message))

5.25.1 Macro Definition Documentation

5.25.1.1 DEBUG_PRINT

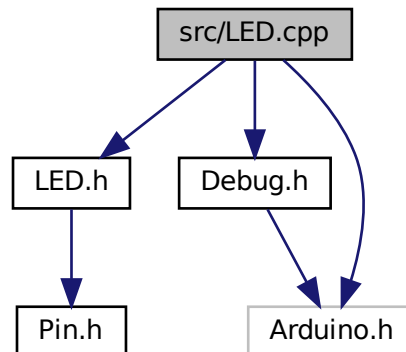
```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.26 src/LED.cpp File Reference

```
#include "LED.h"  
#include "Debug.h"
```

```
#include <Arduino.h>
```

Include dependency graph for LED.cpp:



Macros

- `#define DEBUG_PRINT(message) Debug::print(__FILE__, __LINE__, __func__, String(message))`

5.26.1 Macro Definition Documentation

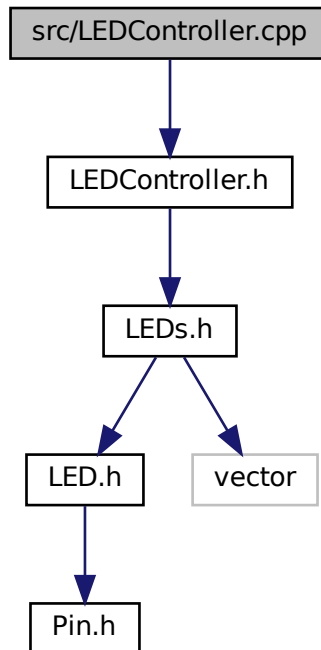
5.26.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.27 src/LEDController.cpp File Reference

```
#include "LEDController.h"
```

Include dependency graph for LEDController.cpp:



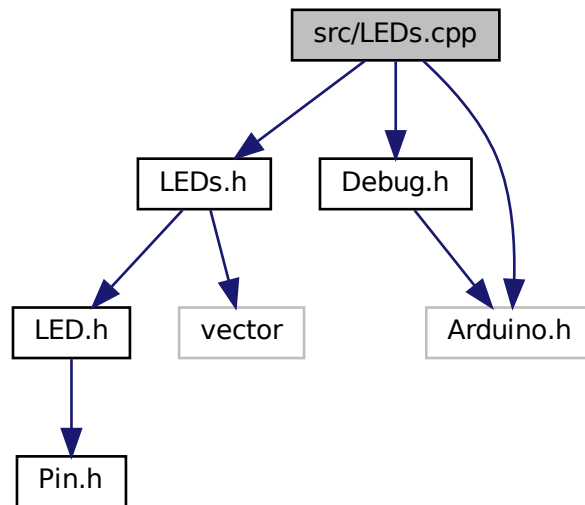
5.28 src/LEDs.cpp File Reference

```
#include "LEDs.h"
```

```
#include "Debug.h"
```

```
#include <Arduino.h>
```

Include dependency graph for LEDs.cpp:



Macros

- `#define DEBUG_PRINT(message) Debug::print(__FILE__, __LINE__, __func__, String(message))`

5.28.1 Macro Definition Documentation

5.28.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.29 src/main.cpp File Reference

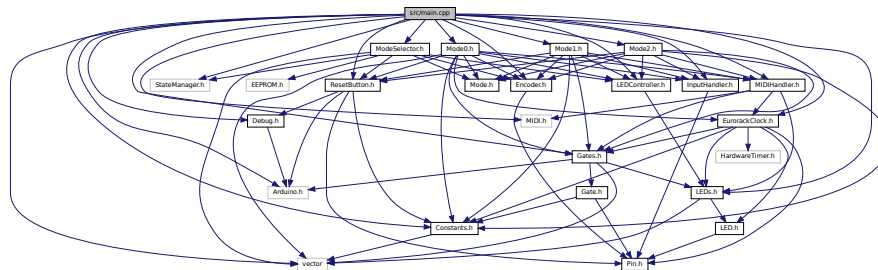
```
#include <Arduino.h>
#include <MIDI.h>
#include <vector>
#include "Gates.h"
#include "ModeSelector.h"
#include "LEDs.h"
#include "Debug.h"
#include "Encoder.h"
#include "MIDIHandler.h"
```

```

#include "EurorackClock.h"
#include "Constants.h"
#include "Mode0.h"
#include "Mode1.h"
#include "Mode2.h"
#include "LEDController.h"
#include "ResetButton.h"
#include "InputHandler.h"
#include "StateManager.h"

```

Include dependency graph for main.cpp:



Macros

- `#define DEBUG_PRINT(message) Debug::print(__FILE__, __LINE__, __func__, String(message))`
Macro for debug print.
- `#define RX_PIN PA3`
RX pin for MIDI communication.
- `#define TX_PIN PA2`
TX pin for MIDI communication.
- `#define ENCODER_PINA PB13`
Encoder pin A.
- `#define ENCODER_PINB PB14`
Encoder pin B.
- `#define ENCODER_BUTTON PB12`
Encoder button pin.
- `#define CLOCK_PIN PB10`
Clock pin.
- `#define RESET_PIN PB11`
Reset pin.
- `#define RESET_BUTTON PB15`
Reset button pin.
- `#define TEMPO_LED PA8`
Tempo LED pin.
- `#define CV_A_PIN PA4`
CV A pin.
- `#define CV_B_PIN PA5`
CV B pin.

Functions

- void `setup` ()
Setup function for the Arduino sketch.
- void `loop` ()
Main loop function for the Arduino sketch.

Variables

- `std::vector< int > pins` = {PA15, PB3, PB4, PB5, PB6, PB7, PB8, PB9}
Example pins for gates.
- `const int numPins` = pins.size()
Number of gate pins.
- `Gates gates` = `Gates(pins, numPins)`
Create an instance of `Gates`.
- `std::vector< int > ledPins` = {PA12, PA11, PB1, PB0, PA7, PA6, PA1, PA0}
Placeholder pin numbers for `LEDs`.
- `int numLedPins` = ledPins.size()
Number of `LED` pins.
- `LEDs leds` = `LEDs(ledPins, numLedPins)`
Create an instance of `LEDs`.
- `int encCLKPin` = `ENCODER_PINA`
Encoder CLK pin.
- `int encDTPin` = `ENCODER_PINB`
Encoder DT pin.
- `int encButtonPin` = `ENCODER_BUTTON`
Encoder button pin.
- `bool inModeSelection` = false
Flag for mode selection.
- `int intensity` = 255
Default intensity for `LEDs`.
- `bool isInSelection` = false
Flag to prevent multiple presses from being handled.
- `unsigned long lastFlashTime` = 0
Last flash time.
- `unsigned char internalPPQN` = 24
Pulses per quarter note.
- `std::vector< int > musicalIntervals` = {1, 2, 3, 4, 6, 8, 12, 16, 24, 32, 48, 64, 72, 96, 128, 144, 192, 288, 384, 576, 768, 1152, 1536}
- `const int musicalIntervalsSize` = musicalIntervals.size()
Size of musical intervals array.
- `int total_pages` = 16 / leds.numLeds
Calculate total pages based on number of `LEDs`.
- `int min_intensity` = 64
Set minimum intensity to 25% (64 out of 255)
- `int intensity_step` = (255 - min_intensity) / (total_pages - 1)
Calculate intensity step.
- `StateManager stateManager` = `StateManager()`
Instance of the `StateManager` class used to manage state of the device in EEPROM.
- `Encoder encoder` = `Encoder(encCLKPin, encDTPin, encButtonPin)`

- Instance of the [Encoder](#) class.*
 - [ResetButton](#) resetButton = [ResetButton](#)(RESET_BUTTON)
- Instance of the [ResetButton](#) class.*
 - [LEDController](#) ledController ([leds](#))
- Instance of the [LEDController](#) class.*
 - [EurorackClock](#) clock ([CLOCK_PIN](#), [RESET_PIN](#), [TEMPO_LED](#), [gates](#), [leds](#))
- Instance of the [EurorackClock](#) class.*
 - [MIDIHandler](#) midiHandler ([Serial2](#), [clock](#), [gates](#), [leds](#))
- Instance of the [MIDIHandler](#) class.*
 - [InputHandler](#) inputHandler = [InputHandler](#)([CV_A_PIN](#), [CV_B_PIN](#))
- Instance of the [InputHandler](#) class.*
 - [ModeSelector](#) & modeSelector = [ModeSelector::getInstance](#)()
- Instance of the [ModeSelector](#) class.*
 - [Mode](#) * currentMode = nullptr
- Pointer to the current mode.*
 - [Mode0](#) mode0 ([encoder](#), [inputHandler](#), [gates](#), [ledController](#), [midiHandler](#), [resetButton](#), [clock](#))
- Instance of [Mode0](#) class.*
 - [Mode1](#) mode1 ([encoder](#), [inputHandler](#), [gates](#), [ledController](#), [midiHandler](#), [resetButton](#))
- Instance of [Mode1](#) class.*
 - [Mode2](#) mode2 ([encoder](#), [inputHandler](#), [gates](#), [ledController](#), [midiHandler](#), [resetButton](#))
- Instance of [Mode2](#) class.*

5.29.1 Macro Definition Documentation

5.29.1.1 CLOCK_PIN

```
#define CLOCK_PIN PB10
```

Clock pin.

5.29.1.2 CV_A_PIN

```
#define CV_A_PIN PA4
```

CV A pin.

5.29.1.3 CV_B_PIN

```
#define CV_B_PIN PA5
```

CV B pin.

5.29.1.4 DEBUG_PRINT

```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

Macro for debug print.

5.29.1.5 ENCODER_BUTTON

```
#define ENCODER_BUTTON PB12
```

[Encoder](#) button pin.

5.29.1.6 ENCODER_PINA

```
#define ENCODER_PINA PB13
```

[Encoder](#) pin A.

5.29.1.7 ENCODER_PINB

```
#define ENCODER_PINB PB14
```

[Encoder](#) pin B.

5.29.1.8 RESET_BUTTON

```
#define RESET_BUTTON PB15
```

Reset button pin.

5.29.1.9 RESET_PIN

```
#define RESET_PIN PB11
```

Reset pin.

5.29.1.10 RX_PIN

```
#define RX_PIN PA3
```

RX pin for MIDI communication.

5.29.1.11 TEMPO_LED

```
#define TEMPO_LED PA8
```

Tempo [LED](#) pin.

5.29.1.12 TX_PIN

```
#define TX_PIN PA2
```

TX pin for MIDI communication.

5.29.2 Function Documentation

5.29.2.1 loop()

```
void loop ( )
```

Main loop function for the Arduino sketch.

This function is called repeatedly as long as the Arduino is powered on. It contains the main logic of the sketch. < Update the [ModeSelector](#)

< Update the [LEDController](#)'s blinking status

< If not in mode selection

< Update the current mode

< If in mode selection

< Teardown the current mode

< Get the new current mode from the [ModeSelector](#)

< Setup the new current mode

5.29.2.2 setup()

```
void setup ( )
```

Setup function for the Arduino sketch.

This function is called once when the sketch starts. It is used to initialize variables, input and output pin modes, and start using libraries. < Enable debugging

- < Initialize serial communication
- < Print debug message
- < Set the RESET_BUTTON pin to INPUT_PULLDOWN mode
- < Initialize the [MIDIHandler](#)
- < Set the [MIDIHandler](#) to listen to all channels
- < Start the clock
- < Set the tempo to 120 BPM with internal 4 PPQN
- < Initialize the EEPROM with default values
- < Add [Mode0](#) to the [ModeSelector](#)
- < Add [Mode1](#) to the [ModeSelector](#)
- < Add [Mode2](#) to the [ModeSelector](#)
- < Set the [LEDController](#) for the [ModeSelector](#)
- < Set the [Encoder](#) for the [ModeSelector](#)
- < Set the StateManager for the [ModeSelector](#)
- < Set the current mode for the [ModeSelector](#)
- < Get the current mode from the [ModeSelector](#)
- < Run the setup function for the current mode
- < Initialize [LED](#) pins
- < Initialize gate pins
- < Initialize encoder pins
- < Print debug message

5.29.3 Variable Documentation

5.29.3.1 clock

```
EurorackClock clock(CLOCK_PIN, RESET_PIN, TEMPO_LED, gates, leds) (  
    CLOCK_PIN ,  
    RESET_PIN ,  
    TEMPO_LED ,  
    gates ,  
    leds )
```

Instance of the [EurorackClock](#) class.

5.29.3.2 currentMode

```
Mode* currentMode = nullptr
```

Pointer to the current mode.

5.29.3.3 encButtonPin

```
int encButtonPin = ENCODER_BUTTON
```

[Encoder](#) button pin.

5.29.3.4 encCLKPin

```
int encCLKPin = ENCODER_PINA
```

[Encoder](#) CLK pin.

5.29.3.5 encDTPin

```
int encDTPin = ENCODER_PINB
```

[Encoder](#) DT pin.

5.29.3.6 encoder

```
Encoder encoder = Encoder(encCLKPin, encDTPin, encButtonPin)
```

Instance of the [Encoder](#) class.

5.29.3.7 gates

```
Gates gates = Gates(pins, numPins)
```

Create an instance of [Gates](#).

5.29.3.8 inModeSelection

```
bool inModeSelection = false
```

Flag for mode selection.

5.29.3.9 inputHandler

```
InputHandler inputHandler = InputHandler(CV_A_PIN, CV_B_PIN)
```

Instance of the [InputHandler](#) class.

5.29.3.10 intensity

```
int intensity = 255
```

Default intensity for [LEDs](#).

5.29.3.11 intensity_step

```
int intensity_step = (255 - min_intensity) / (total_pages - 1)
```

Calculate intensity step.

5.29.3.12 internalPPQN

```
unsigned char internalPPQN = 24
```

Pulses per quarter note.

5.29.3.13 isInSelection

```
bool isInSelection = false
```

Flag to prevent multiple presses from being handled.

5.29.3.14 lastFlashTime

```
unsigned long lastFlashTime = 0
```

Last flash time.

5.29.3.15 ledController

```
LEDController ledController(leds) (  
    leds )
```

Instance of the [LEDController](#) class.

5.29.3.16 ledPins

```
std::vector<int> ledPins = {PA12, PA11, PB1, PB0, PA7, PA6, PA1, PA0}
```

Placeholder pin numbers for [LEDs](#).

5.29.3.17 leds

```
LEDs leds = LEDs(ledPins, numLedPins)
```

Create an instance of [LEDs](#).

5.29.3.18 midiHandler

```
MIDIHandler midiHandler(Serial2, clock, gates, leds) (  
    Serial2 ,  
    clock ,  
    gates ,  
    leds )
```

Instance of the [MIDIHandler](#) class.

5.29.3.19 min_intensity

```
int min_intensity = 64
```

Set minimum intensity to 25% (64 out of 255)

5.29.3.20 mode0

```
Mode0 mode0(encoder, inputHandler, gates, ledController, midiHandler, resetButton, clock) (  
    encoder ,  
    inputHandler ,  
    gates ,  
    ledController ,  
    midiHandler ,  
    resetButton ,  
    clock )
```

Instance of [Mode0](#) class.

5.29.3.21 mode1

```
Mode1 mode1(encoder, inputHandler, gates, ledController, midiHandler, resetButton) (  
    encoder ,  
    inputHandler ,  
    gates ,  
    ledController ,  
    midiHandler ,  
    resetButton )
```

Instance of [Mode1](#) class.

5.29.3.22 mode2

```
Mode2 mode2(encoder, inputHandler, gates, ledController, midiHandler, resetButton) (  
    encoder ,  
    inputHandler ,  
    gates ,  
    ledController ,  
    midiHandler ,  
    resetButton )
```

Instance of [Mode2](#) class.

5.29.3.23 modeSelector

```
ModeSelector& modeSelector = ModeSelector::getInstance()
```

Instance of the [ModeSelector](#) class.

5.29.3.24 musicalIntervals

```
std::vector<int> musicalIntervals = {1, 2, 3, 4, 6, 8, 12, 16, 24, 32, 48, 64, 72, 96, 128, 144, 192, 288, 384, 576, 768, 1152, 1536}
```

5.29.3.25 musicalIntervalsSize

```
const int musicalIntervalsSize = musicalIntervals.size()
```

Size of musical intervals array.

5.29.3.26 numLedPins

```
int numLedPins = ledPins.size()
```

Number of [LED](#) pins.

5.29.3.27 numPins

```
const int numPins = pins.size()
```

Number of gate pins.

5.29.3.28 pins

```
std::vector<int> pins = {PA15, PB3, PB4, PB5, PB6, PB7, PB8, PB9}
```

Example pins for gates.

5.29.3.29 resetButton

```
ResetButton resetButton = ResetButton(RESET_BUTTON)
```

Instance of the [ResetButton](#) class.

5.29.3.30 stateManager

```
StateManager stateManager = StateManager()
```

Instance of the StateManager class used to manage state of the device in EEPROM.

5.29.3.31 total_pages

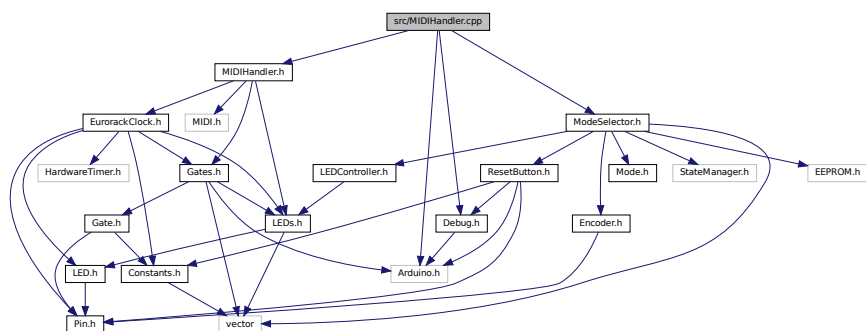
```
int total_pages = 16 / leds.numLeds
```

Calculate total pages based on number of [LEDs](#).

5.30 src/MIDIHandler.cpp File Reference

```
#include "MIDIHandler.h"
#include "Debug.h"
#include <Arduino.h>
#include "ModeSelector.h"
```

Include dependency graph for MIDIHandler.cpp:



Macros

- `#define DEBUG_PRINT(message)`

Macros

- #define `DEBUG_PRINT`(message) `Debug::print`(__FILE__, __LINE__, __func__, String(message))

5.32.1 Macro Definition Documentation

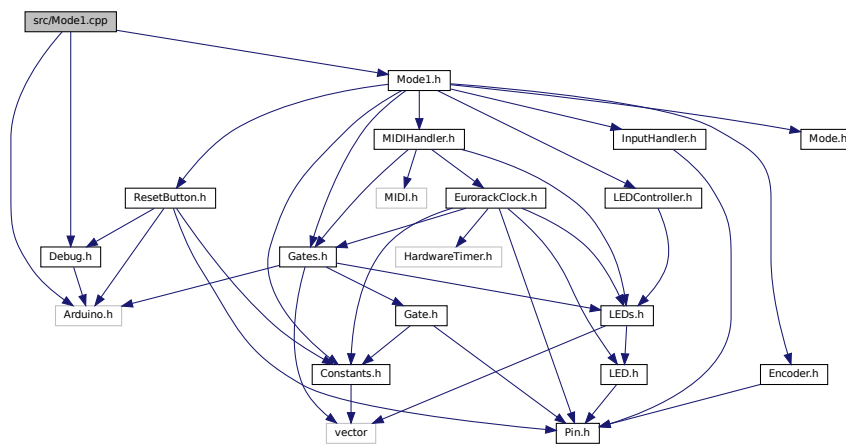
5.32.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.33 src/Mode1.cpp File Reference

```
#include "Model.h"
#include "Debug.h"
#include <Arduino.h>
```

Include dependency graph for Mode1.cpp:



Macros

- #define `DEBUG_PRINT`(message) `Debug::print`(__FILE__, __LINE__, __func__, String(message))

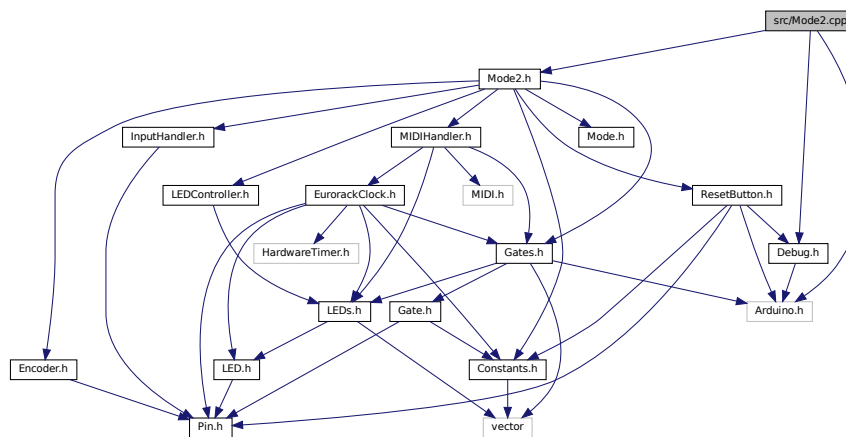
5.33.1 Macro Definition Documentation

5.33.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.34 src/Mode2.cpp File Reference

```
#include "Mode2.h"
#include "Debug.h"
#include <Arduino.h>
Include dependency graph for Mode2.cpp:
```



Macros

- #define `DEBUG_PRINT`(message)

5.34.1 Macro Definition Documentation

5.34.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(
    message )
```

Value:

```
{ \
    Debug::print(__FILE__, __LINE__, __func__, String(message)); \
    Serial.flush(); \
}
```

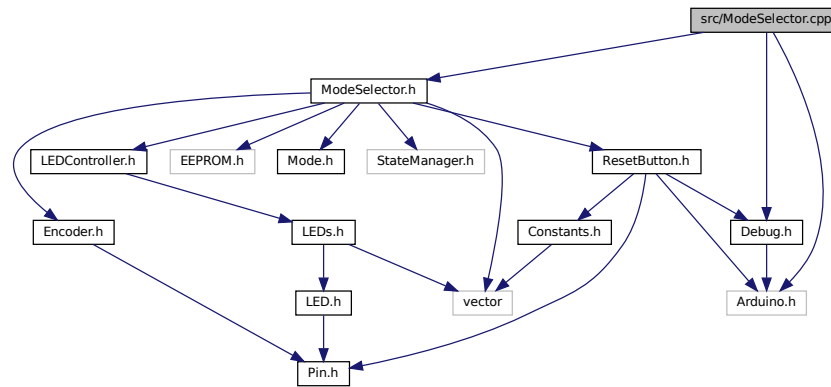
5.35 src/ModeSelector.cpp File Reference

```
#include "ModeSelector.h"
```

```
#include <Arduino.h>
```

```
#include "Debug.h"
```

Include dependency graph for ModeSelector.cpp:



Macros

- #define `DEBUG_PRINT`(message) `Debug::print(__FILE__, __LINE__, __func__, String(message))`

5.35.1 Macro Definition Documentation

5.35.1.1 DEBUG_PRINT

```
#define DEBUG_PRINT(
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

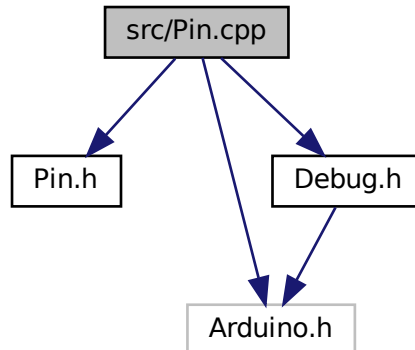
5.36 src/Pin.cpp File Reference

```
#include "Pin.h"
```

```
#include <Arduino.h>
```

```
#include "Debug.h"
```

Include dependency graph for Pin.cpp:



Macros

- `#define DEBUG_PRINT(message) Debug::print(__FILE__, __LINE__, __func__, String(message))`

5.36.1 Macro Definition Documentation

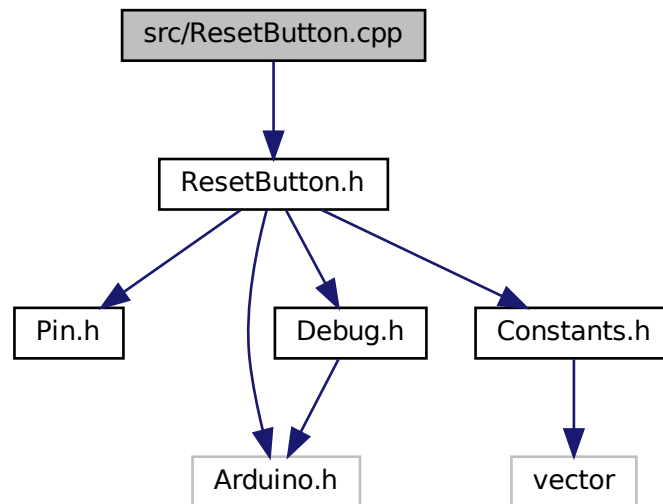
5.36.1.1 `DEBUG_PRINT`

```
#define DEBUG_PRINT(  
    message ) Debug::print(__FILE__, __LINE__, __func__, String(message))
```

5.37 src/ResetButton.cpp File Reference

```
#include "ResetButton.h"
```

Include dependency graph for ResetButton.cpp:



5.38 src/SPDTSwitch.cpp File Reference

```
#include "SPDTSwitch.h"
```

```
#include "Pin.h"
```

```
#include "Debug.h"
```

Include dependency graph for SPDTSwitch.cpp:

