TOSHIBA MOS MEMORY PRODUCTS

65,536 WORD×4 BIT DYNAMIC RAM SILICON MONOLITHIC N-CHANNEL SILICON GATE MOS TMM41464AP/AT/AZ-10, TMM41464AP/AT/AZ-12 TMM41464AP/AT/AZ-15

DESCRIPTION

The TMM41464AP/AT/AZ is N-channel dynamic RAM organized 65,536 words by 4 bit. The TMM41464 AP/AT/AZ utilizes TOSHIBA's N-channel/Silicon gate process technology as well as advanced circuit techniques to provide wide operating margins, both internally and to the system user.

Multiplexed address inputs permit the TMM41464AP/

pin PLCC and 20 pin ZIP. The package size provides high system bit densities and is compatible with widely available automated testing and insertion equipment. System oriented features include single power supply of 5V ± 10% tolerance, direct interfacing capability with high performance logic familes such as schottky TTL.

AT/AZ to be package in a standard 18 pin plastic DIP, 18

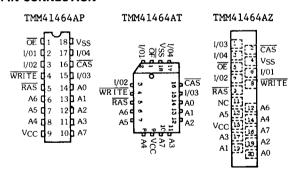
FEATURES

- 65,536 words by 4 bit organization
- Fast access time and cycle time

DEVICE	trac	tCAC	trc
TMM41464AP/AT/AZ-10	100ns	50ns	190ns
TMM41464AP/AT/AZ-12	120ns	60ns	220ns
TMM41464AP/AT/AZ-15	150ns	75ns	260ns

 Single power supply of 5V ± 10% with a built-in V_{BB} generator

PIN CONNECTION



PIN NAMES

A0 ~ A7	Address Inputs
CAS	Column Address Strobe
1/01 ~ 1/04	Data Input/Output
RAS	Row Address Strobe
WRITE	Read/Write Input
ŌĒ	Output Enable
Vcc	Power (+5V)
V _{SS}	Ground

Lower Power:

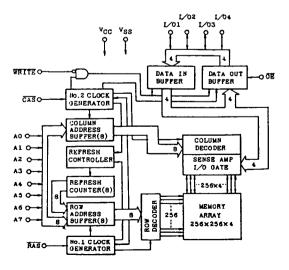
440mW MAX. Operating (TMM41464AP/AT/AZ-10) 396mW MAX. Operating (TMM41464AP/AT/AZ-12) 358mW MAX. Operating (TMM41464AP/AT/AZ-15) 28mW MAX. Standby

- Output unlatched at cycle end allows two-dimensional chip selection
- Read-Modify-Write, RAS only refresh, Hidden refresh, CAS before RAS refresh, and Page Mode capability
- All inputs and outputs TTL compatible
- 256 refresh cycles/4ms

Package

Plastic DIP : TMM41464AP Plastic Leaded Chip Carrier : TMM41464AT Plastic ZIP : TMM41464AZ

BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

ITEM	SYMBOL	RATING	UNITS	NOTES	
Input and Output Voltage	V _{IN} , V _{OUT}	−1 ~ 7	V		
Power Supply Voltage	V _{CC}	−1 ~ 7	V		
Operating Temperature	T _{OPR}	0 ~ 70	°C] 1	
Storage Temperature	T _{STG}	− 55 ~ 150	°C] '	
Soldering Temperature • Time	T _{SOLDER}	260•10	°C•sec]	
Power Dissipation	PD	1	W		
Short Circuit Output Current	LOUT	50	mA		

RECOMMENDED DC OPERATING CONDITIONS (Ta = $0 \sim 70^{\circ}$ C)

SYMBOL	PARAMETER	MIN.	TYP.	MAX.	UNITS	NOTES
Vcc	Supply Voltage	4.5	5.0	5.5	V	
VIH	Input High Voltage	2.4		6.5	V	2
VIL	Input Low Voltage	-1.0	-	0.8	V	

DC ELECTRICAL CHARACTERISTICS ($V_{CC} = 5V \pm 10\%$, $Ta = 0 \sim 70^{\circ}C$)

SYMBOL	PARAMETER	MIN.	MAX.	UNITS	NOTES	
	OPERATING CURRENT	TMM41464AP/AT/AZ-10	_	80		3, 4
I _{CC1}	Average Power Supply Operating Current (RAS, CAS Cycling: t _{RC} = t _{RC} MIN.)	TMM41464AP/AT/AZ-12		72 65	mA	
I _{CC2}	STANDBY CURRENT Power Supply Standby Current (RAS = CAS = Vih)					
	RAS ONLY REFRESH CURRENT	TMM41464AP/AT/AZ-10	_	70		
I _{CC3}	Average Power Supply Current, RAS Only Refresh Mode	TMM41464AP/AT/AZ-12	-	62	mA	3
.003		TMM41464AP/AT/AZ-15		55		
¹CC4	PAGE MODE CURRENT	TMM41464AP/AT/AZ-10		60		
	Average Power Supply Current, Page Mode (RAS = V _L , CAS Cycling: t _{PC} = t _{PC} MIN.)	TMM41464AP/AT/AZ-12	_	55	mA	3, 4
		TMM41464AP/AT/AZ-15	_	50		
	CAS BEFORE RAS REFRESH CURRENT	TMM41464AP/AT/AZ-10	_	70		
L _{CC5}	Average Power Supply Current, CAS Before RAS	TMM41464AP/AT/AZ-12	_	62	mA	3
.005	Mode (RAS, CAS Cycling, CAS Before RAS: t _{RC} = t _{RC} MIN.)	TMM41464AP/AT/AZ-15	_	55		
I _{†(L)}	INPUT LEAKAGE CURRENT Input Leakage Current, any input $(0V \le V_1N \le 6.5V$, All Other Pins Not Unter Test = 0V)				μΑ	
I _{O(L)}	OUTPUT LEAKAGE CURRENT (D _{OUT} is disabled, $0V \le V_{OUT} \le +5.5V$)	-10	10	μΑ		
V _{0H}	OUTPUT LEVEL Output "H" Level Voltage (IOUT=-5mA)	2.4	_	٧		
V _{OL}	OUTPUT LEVEL Output "L" Level Voltage (I _{OUT} = 4.2mA)		_	0.4	V	

ELECTRICAL CHARACTERISTICS AND RECOMMENDED AC OPERATING CONDITIONS

 $(V_{CC} = 5V \pm 10\%, Ta = 0 \sim 70^{\circ}C)$ (Notes 5, 6, 7)

0) (145.0)	PARAMETER	TMM41		TMM41- AT/A		TMM41 AT/A		UNITS	NOTES
SYMBOL	PARAMETER	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		<u> </u>
tee	Random Read or Write Cycle Time	190	-	220		260		ns	
t _{RC}	Read-Modify Write Cycle Time	260	_	300	_	355		ns	<u> </u>
t _{PC}	Page Mode Cycle Time	100	_	120	_	145		ns	L
t _{RAC}	Access Time from RAS		100		120		150	ns	8, 10
tcac	Access Time from CAS		50		60		75	ns	9,10
toff	Output Buffer Turn-off Delay	0	30	0	35	0	40	ns	11
t _T	Transition Time (Rise and Fall)	3	50	3	50	3	50	ns	7
tRP	RAS Precharge Time	80	_	90		100		ns	
tras	RAS Pulse Width	100	10,000	120	10,000	150	10,000	ns	ļ
tras	RAS Hold Time	50		60		75		ns	
tcsh	CAS Hold Time	100	_	120	_	150	_	ns	
tCAS	CAS Pulse Width	50	10,000	60	10,000	75	10,000	ns	
tRCD	RAS to CAS Delay Time	20	50	25	60	25	75	ns	13
tCRP	CAS to RAS Precharge Time	10	_	10		10		ns	
t _{CPN}	CAS Precharge Time	20	-	20		25		ns	
CPN	CAS Precharge Time	40		50	_	60	_	ns	
t _{CP}	(for Page Mode Cycle Only)	40			-		ļ	 	
tASR	Row Address Set-Up Time	0		0		0	<u> </u>	ns	
tRAH	Row Address Hold Time	10		15		15	<u> </u>	ns	
tASC	Column Address Set-Up Time	0		0		0	 _	ns	
t _{CAH}	Column Address Hold Time	20		25		35		ns	-
t _{AR}	Column Address Hold Time Reference to RAS	70		85		110	_	ns	_
tRCS	Read Command Set-Up Time	0	-	0		0		ns	
t _{RCH}	Read Command Hold Time Reference to CAS	0	_	0	_	0		ns	12
t _{RRH}	Read Command Hold Time Reference to RAS	10		15	_	20		ns	12
twch	Write Command Hold Time	30	_	35		45	_	ns	
twcn	Write Command Hold Time Reference to RAS	80	-	95	_	120	_	ns	
twp	Write Command Pulse Width	30	_	35	-	45		ns	
t _{RWL}	Write Command to RAS Lead Time	30		35		45		ns	
tCWL	Write Command to CAS Lead Time	30	_	35		45		ns	
tDS	Data-In Set-Up Time	0	_	0		0		ns	14
t _{DH}	Data-In Hold Time	30	_	35		45		ns	14
t _{DHR}	Data-In Hold Time Reference to RAS	80		95		120		ns	
t _{REF}	Refresh Period		4		4		4	ms	<u> </u>
twcs	Write Command Set-Up Time	0	_	0	_	0		ns	15
t CWD	CAS to WRITE Delay	85	_	100	_	120		ns	15
	RAS to WRITE Delay	135		160	_	195		ns	15
t _{RWD}	OE Access Time		25	_	30	-	40	ns	9,

ELECTRICAL CHARACTERISTICS AND RECOMMENDED AC OPERATING CONDITIONS (Continued)

SYMBOL	PARAMETER	TMM41464AP/ AT/AZ-10		TMM41464AP/ AT/AZ-12		TMM41464AP/ AT/AZ-15		1	NOTES
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
^t oed	OE to Data Delay	25	_	30	_	40		ns	
t _{OEZ}	Output Buffer Turn-Off Delay Time from OE	0	25	0	30	0	40	ns	
t _{OEH}	OE command Hold Time	25	_	30	_	40	-	ns	
t _{CHR}	CAS Hold Time for CAS Before RAS Refresh	30	_	30	-	30	-	ns	
t _{CSR}	CAS Set-Up Time for CAS Before RAS Refresh	10	_	10	_	10	_	ns	
t RPC	CAS Precharge to CAS Active Time	0	-	0		0	_	ns	
[†] CPT	CAS Precharge Time for CAS Before RAS Counter Test	20	_	25	-	35	-	ns	
tROH	OE Command Hold Time	10	_	10	_	10		ns	

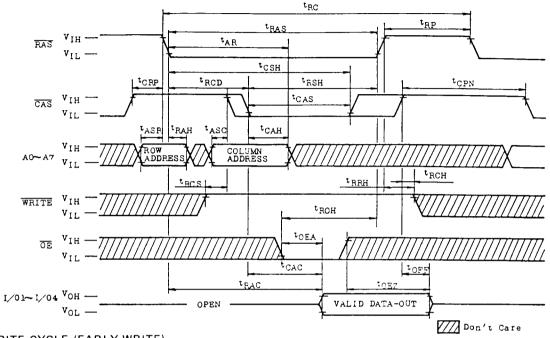
CAPACITANCE ($V_{CC} = 5V \pm 10\%$, f = 1MHz, $Ta = 0 \sim 70^{\circ}C$)

SYMBOL	PARAMETER	MIN.	MAX.	UNITS
C11	Input Capacitance (A0 ~ A7)		5	
CI2	Input Capacitance (RAS, CAS, WRITE, OE)		7	рF
Co	Input/Output Capacitance (I/01 ~ I/04)		7	

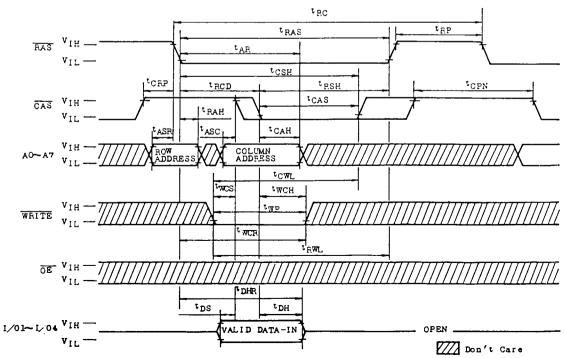
NOTES:

- Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device.
- 2. All voltage are referenced to Vss.
- 3. l_{CC1} , l_{CC3} , l_{CC4} , l_{CC5} depend on cycle rate.
- 4. I_{CC1}, I_{CC4} depend on output loading. Specified values are obtained with the output open.
- 5. An initial pause of 200 µs is required after power-up followed by any 8 RAS cycles before proper device operation is achieved. In case of using internal refresh counter, a minimum of 8 CAS Before RAS initialization cycles instead of 8 RAS cycles are required.
- 6. AC measurements assume $t_T = 5$ ns.
- 7. V_{IH} (min.) and V_{IL} (max.) are reference levels for measuring timing of input signals. Also, transition times are measured between V_{IH} and V_{IL} .
- 8. Assumes that $t_{RCD} \le t_{RCD}$ (max.). If t_{RCD} is greater than the maximum recommended value shown in this table, t_{RAC} will increase by the amount that t_{RCD} exceeds the value shown.
- 9. Assumes that $t_{RCD} \ge t_{RCD}$ (max.).
- 10. Measured with a load equivalent to 2 TTL loads and 100 pF.
- 11. t_{OFF} (max.) and t_{OEZ} (max.) define the time at which the output achieves the open circuit condition and is not referenced to output voltage levels.
- 12. Either t_{BCH} or t_{BBH} must be satisfied for a read cycle.
- 13. Operation within the t_{RCD} (max.) limit insures that t_{RAC} (max.) can be met. t_{RCD} (max.) is specified as a reference point only: If t_{RCD} is greater than the specified t_{RCD} (max.) limit, then access time is controlled exclusively by t_{CAC}.
- 14. These parameters are referenced to $\overline{\text{CAS}}$ leading edge in early write cycles and to $\overline{\text{WRITE}}$ leading edge in read-write or read-modify-write cycles.
- 15. twcs, t_{CWD} and t_{RWD} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If twcs ≥ twcs (min.), the cycle is an early write cycle and the input/output pin will remain open circuits (high impedance) throughout the entire cycle; If t_{CWD} ≥ t_{CWD} (min.) and t_{RWD} ≥ t_{RWD} (min.), the cycle is a read-write cycle or read-modify-write cycle and the data out will contain data read from the selected cell: If neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.

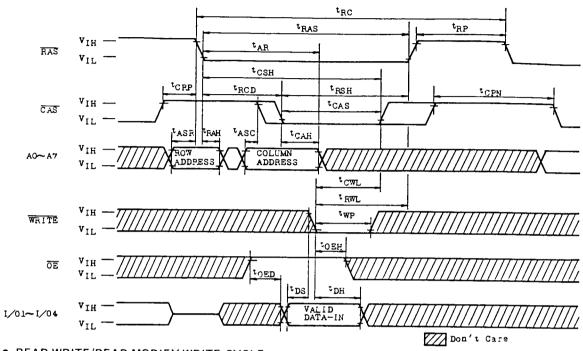
• READ CYCLE



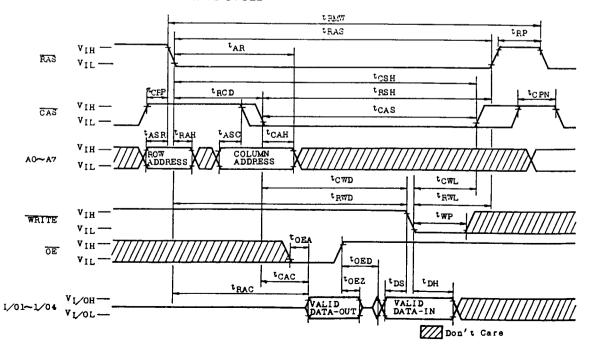
WRITE CYCLE (EARLY WRITE)



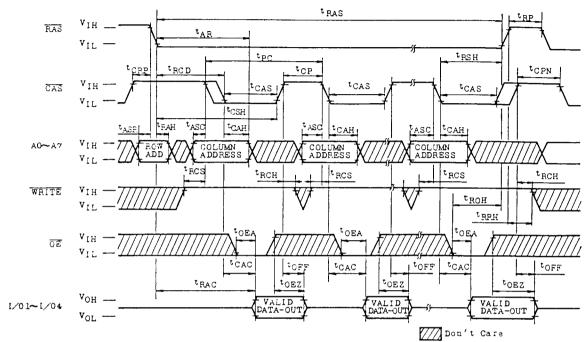
• WRITE CYCLE (OE CONTROLLED WRITE)



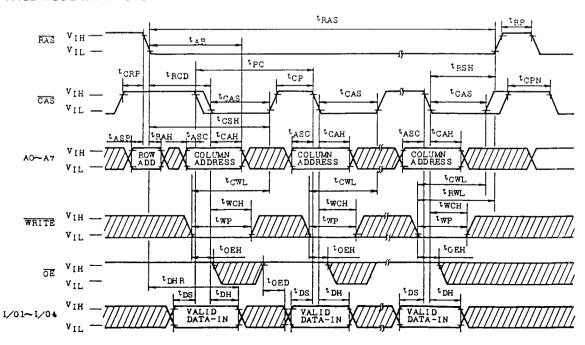
READ-WRITE/READ-MODIFY-WRITE CYCLE



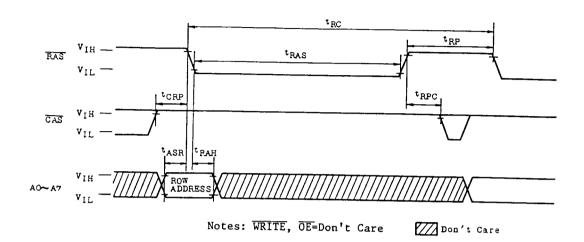
PAGE MODE READ CYCLE



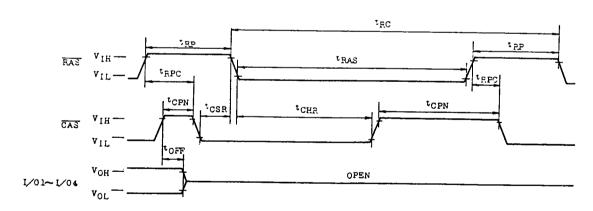
PAGE MODE WRITE CYCLE



• RAS ONLY REFRESH CYCLE

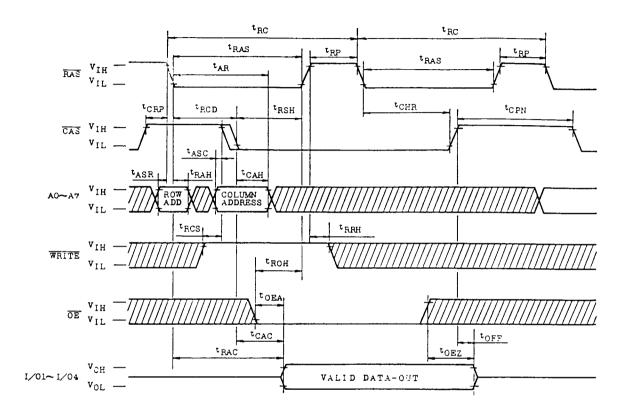


• CAS BEFORE RAS REFRESH CYCLE



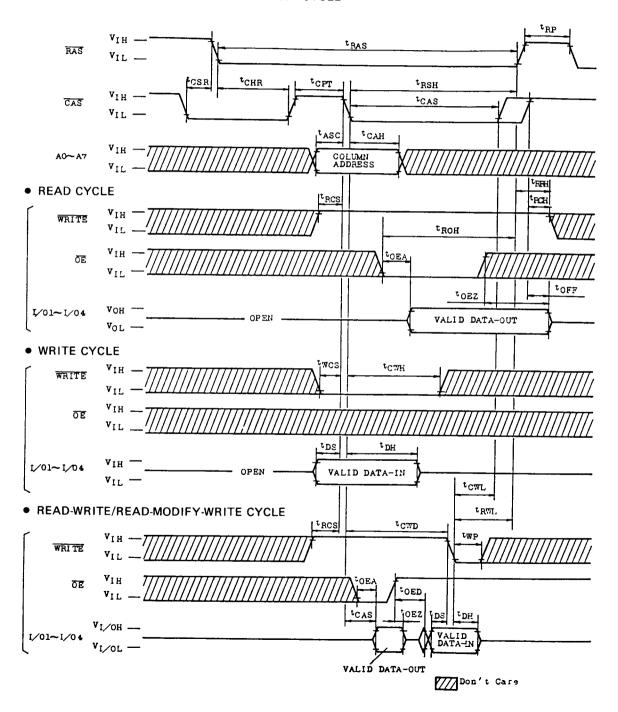
Note: $\overline{\text{WRITE}}$, $\overline{\text{OE}}$, A0 \sim A7=Don't Care

• HIDDEN REFRESH CYCLE





• CAS BEFORE RAS REFRESH COUNTER TEST CYCLE



APPLICATION INFORMATION

ADDRESSING

The 16 address bits required to decode 1 of the 65,536 cell locations within the TMM41464AP/AT/AZ are multiplexed onto the 8 address inputs and latched into the on-chip address latches by externally applying two negative going TTL-level clocks.

The first clock, the Row Address Strobe (\overline{RAS}), latches the 8 row address bits into the chip. The second clock, the Column Address Strobe (\overline{CAS}), subsequently latches the 8 column address bits into the chip. Each of these signals, \overline{RAS} , and \overline{CAS} , triggers a sequence of events which are controlled by different delayed internal clocks.

The two clock chains are linked together logically in such a way that the address multiplexing operation is done outside of the critical path timing sequence for read data access. The later events in the $\overline{\text{CAS}}$ clock sequence are inhibited until the occurrence of a delayed signal derived from the $\overline{\text{RAS}}$ clock chain. This ''gated $\overline{\text{CAS}}$ '' feature allows the $\overline{\text{CAS}}$ clock to be externally activated as soon as the Row Address Hold Time specification (t_{RAH}) has been satisfied and the address inputs have been changed from Row address to Column address information.

Data Inputs

Data is written during a write or read-modify-write cycle.

The falling edge of CAS or WRITE strobes data into the on-chip data latches. In an early-write cycle, WRITE is brought low prior to CAS and the data is strobed in by CAS with setup and hold times referenced to this signal. In delayed write or read-modify-write cycle, CAS will already be low, thus the data will be strobed in by WRITE with setup and hold times referenced to this signal.

In delayed or read-modify-write, \overline{OE} must be high to bring the output buffer to high impedance prior to impressing data on the I/O lines.

Data Outputs

The three-state output buffers provide direct TTL compatibility with a fan-out of two standard TTL loads. Data-out is the same polarity as data-in. The outputs are in the high-impedance state until CAS is brought low. In a read cycle the outputs go active after the access time interval trace and toea are

satisfied.

The outputs become valid after the access time has elapsed and remains valid which \overline{CAS} and \overline{OE} are low. \overline{CAS} or \overline{OE} going high returns it to a high impedance state. In an early-write cycle, the outputs are always in the high-impedance state. In a delayed-write or read-modify-write cycle, the outputs will follow the sequence for the read cycle.

The OE controls the impedance of the output buffers. In the logic high position the buffers will remain in a high impedance state.

When the \overline{OE} input is brought to a logic low level, the output buffer are enabled. Both \overline{CAS} and OE can control the output. Thus in a read operation, either \overline{OE} or \overline{CAS} returning high forces the outputs into the high impedance state.

RAS ONLY REFRESH

Refresh of the dynamic cell matrix is accomplished by performing a memory cycle at each of the 256 row address ($A_o \sim A_\tau$) within each 4 millisecond time interval. Although any normal memory cycle will perform the refresh operation, this function is most easily accomplished with "RAS-only" cycles, RAS only refresh results in a substantial reduction in operating power. This reduction in power is reflected in the I_{CG3} specification.

CAS BEFORE RAS REFRESH

 $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refreshing available on the TMM41464AP/AT/AZ offers an alternate refresh method. If $\overline{\text{CAS}}$ is held on low for the specified period (t_{CSR}) before $\overline{\text{RAS}}$ goes to low, on chip refresh control clock generators and the refresh address counter are enabled, and an internal refresh operation takes place. After the refresh operation is performed, the refresh address counter is automatically incremented in preparation for the next $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refresh operation.

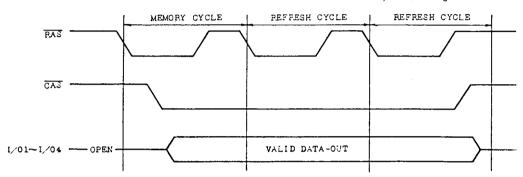
PAGE MODE

The "Page-Mode" feature of the TMM41464AP/AT/AZ allows for successive memory operations at multiple column locations of the same row address with increased speed without an increase in power. This is done by strobing the row address into the

chip and maintaining the RAS signal at a logic 0 throughout all successive memory cycles in which the row address is common. This "Page Mode" of operation will not dissipate the power associated with the negative going edge of RAS. Also, the time required for strobing in a new address is eliminated, thereby decreasing the access and cycle times.

HIDDEN REFRESH

An optional feature of the TMM41464AP/AT/AZ is that refresh cycles may be performed while maintaining valid data at the output pin. This is referred to as Hidden Refresh. Hidden Refresh is performed by holding $\overline{\text{CAS}}$ at V_{IL} and taking $\overline{\text{RAS}}$ high and after a specified precharge period (t_{RP}), executing a $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refresh cycle. (see Figure below)



This feature allows a refresh cycle to be "hidden" among data cycles without affecting the data availability.

CAS BEFORE RAS REFRESH COUNTER TEST

The internal refresh operation of TMM41464AP/AT/AZ can be tested by CAS BEFORE RAS REFRESH COUNTER TEST. This cycle performs READ/WRITE operation taking the internal counter address as row address and the input address as column address.

The test is performed after a minimum of 8 $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ cycles as initialization cycles. The test procedure is as follows.

1) Write "0" into all the memory cells at normal

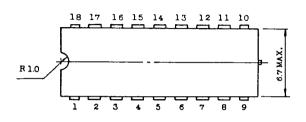
write mode.

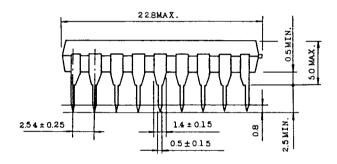
- ② Select one certain column address and read "0" out and write "1" in each cell by performing CAS BEFORE RAS REFRESH COUNTER TEST (READ-WRITE CYCLE). Repeat this operation 256 times.
- (3) Check "1" out of 256 bits at normal read mode, which was written at (2).
- (4) Using the same column as (2), read "1" out and write "0" in each cell performing CAS BEFORE RAS REFRESH COUNTER TEST. Repeat this operation 256 times.
- (5) Check "0" out of 256 bits at normal read mode, which was written at (4).
- 6 Perform the above 1 to 5 to the complement data.

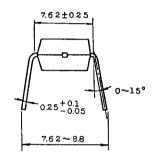
OUTLINE DRAWINGS

Plastic DIP

Unit in mm





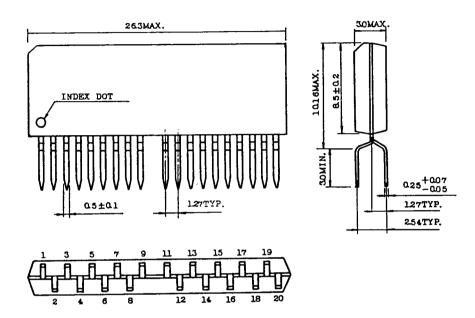


Note: Each lead pitch is 2.54mm. All leads are located within 0.25mm of their true longitudinal position with respect to No. 1 and No. 18 leads. All dimensions are in millimeters.

Note: Toshiba does not assume any responsibility for use of any circuitry described; no circuit patent licenses are implied, and Toshiba reserves the right, at any time without notice, to change said circuitry.

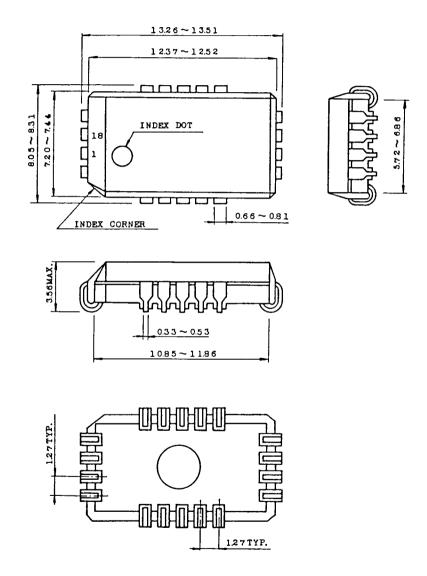
• Plastic ZIP

Unit in mm



• Plastic LCC

Unit in mm



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