PROBABILÍSTICAS PARA REPRESENTAÇÃO DE GRAFOS GIGANTES

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Motivation

Why are **sketching data structures** relevant to **graph** problems?



Some real-life graphs are massive

Observing global structures is hard Facebook 2.2 Number of active users, 2018. https://www.statista.com/statistics/264810/number-of-monthl y-active-facebook-users-worldwide/ billion **Twitter** Routers 128 66 Estimated number of Typical amount of RAM in a typical router. directed edges, 2018. MB billion http://files.shareholder.com/downloads/AMD A-2F526X/5887909887x0x961126/1C3B57 60-08BC-4637-ABA1-A9423C80F1F4/Q31 7_Selected_Company_Metrics_and_Financia ls.pdf 23 100's

of billions

billion

Internet

Number of connected devices, 2018.

https://www.statista.com/statistics/471264/iotnumber-of-connected-devices-worldwide/

Metagenomic assemblies

Number of basepairs in a typical metagenomic sample.

https://arxiv.org/abs/1112.4193



Memory is limited

Graphs are getting bigger



Too many vertices

Even sparse graphs with hundreds of billions of vertices may have a hard time fitting in main memory.



Too many edges

The amount of memory needed to represent dense graphs grow quadratically with the number of vertices.



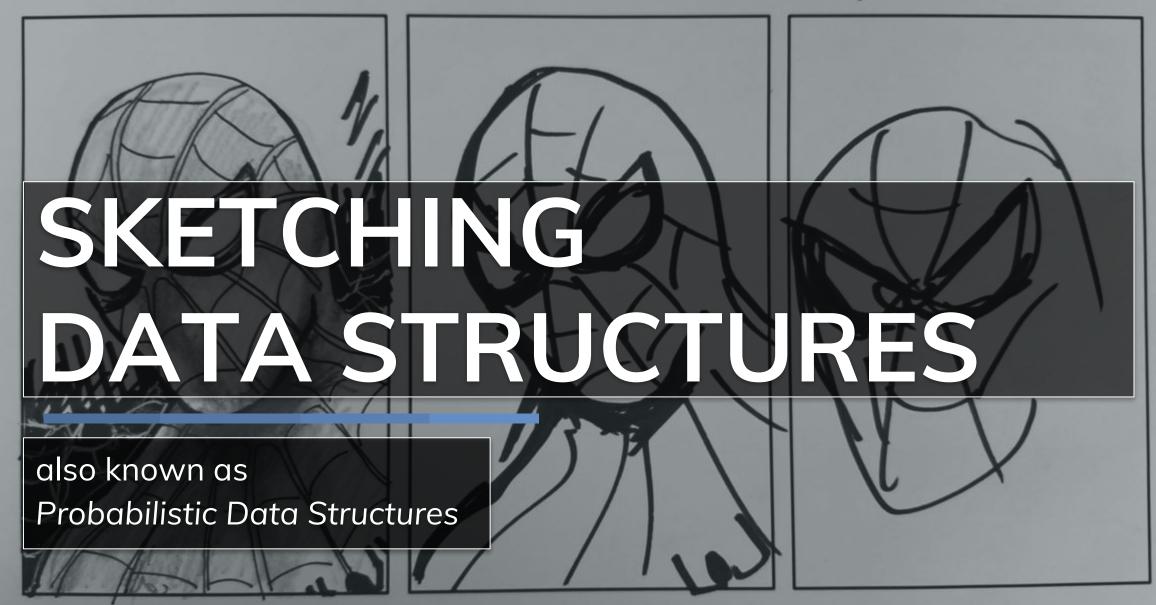
Limited hardware

Modern IoT setups sometimes rely on hardware with limited amount of resources to spare in a graph processing application.

10 Minutes

1 minute

10 seconds



Metagenomic assembly

De novo assembly of genomes from short-reads in metagenomic samples.

- A read is a variable-length fragment of larger genomes.
- Each read is broken down into **fixed-length** strings: a **k-mer**.
- Those k-mers define a de Bruijn graph.

1. Sample ...GTCATACTACGATACATAACTAGACTAGACTAAGACATACGATA... 2. Short-reads **ATACTACGATA GTCATACTA** CTAGACTAGACTAAGAC **ATACATAACTA AAGACATACGATA** 3. K-mers **ATACTACGATA GTCATACTA** ATACTAC TACTACG ACTACGA CATACTA **CTACGAT TACGATA** 4. de Bruijn graph **ATACTAC**

Pell, Jason, et al. (2012). **Scaling metagenome sequence assembly with probabilistic de Bruijn graphs**. Proceedings of the National Academy of Sciences.

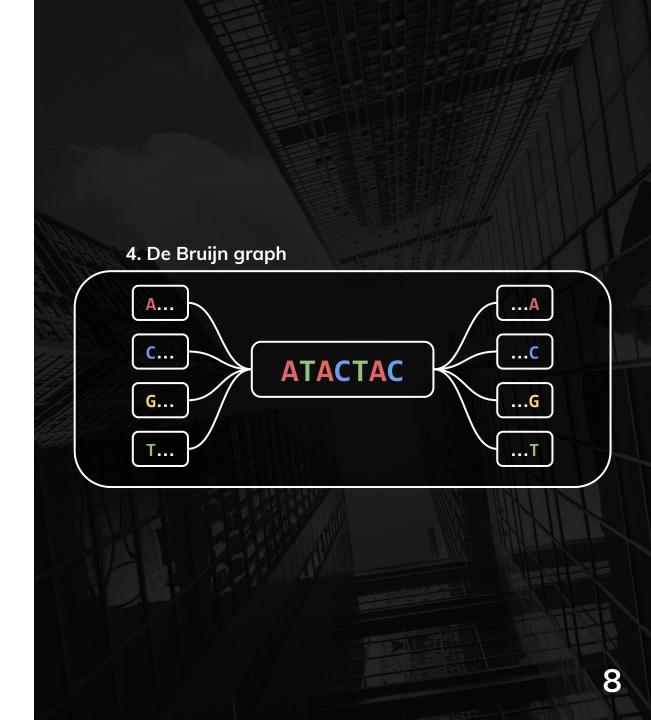
Metagenomic assembly

De novo assembly of genomes from short-reads in metagenomic samples.

- The good: you do not really need to store edges.
- The bad: O(4^k) vertices. Human genome alone: 512GB.

Problem: to find components in the graph created from a metagenomic sample.

Pell, Jason, et al. (2012). **Scaling metagenome sequence assembly with probabilistic de Bruijn graphs**. Proceedings of the National Academy of Sciences.

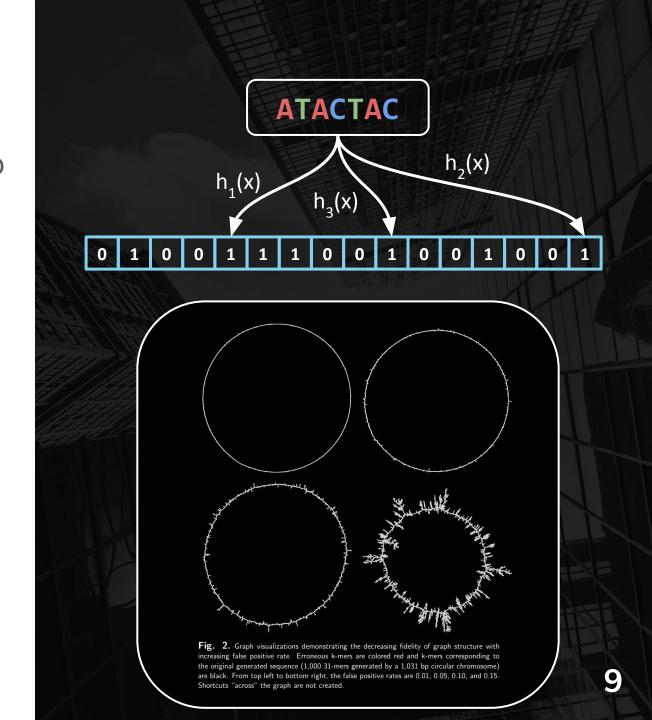


Bloom filter

Represents sets, allowing membership tests with a probability of **false positives**.

- There are no false negatives;
- 10 bits per element are enough to ensure for a probability of false positives of less than 1%.
- Some applications can handle as high as 15% f.p., requiring less than 4 bits per element.

Bloom, B. H. (1970). **Space/time trade-offs in hash coding with allowable errors**. Communications of the ACM.







Data Intensive Biology Lab, UC Davis **School of Veterinary Medicine** dib-lab / khmer % Fork 283 Watch ▼ ★ Unstar 539 17 Pull requests 44 Projects 1 <> Code (!) Issues 287 Wiki Wiki ili Insights In-memory nucleotide sequence k-mer counting, filtering, graph traversal and more http://khmer.readthedocs.io/ graph-traversal @ 6,661 commits 2 127 branches ♦ 56 releases \$2 67 contributors যাঁ View license The khmer software for advanced biological sequencing data analysis What is khmer? The khmer software is a set of command-line tools for working with DNA shotgun sequencing data from genomes, transcriptomes, metagenomes, and single cells. khmer can make de novo assemblies faster, and sometimes better, khmer can also identify (and fix) problems with shotgun data. You can read more about khmer in our software paper. khmer is free and open source software.



Probabilistic Implicit Representations

Use less **memory** by allowing **errors**



Space Optimal Representations

- A representation is said to be **space optimal** if it requires O(f(n)) bits to represent a class containing $2^{\Theta(f(n))}$ graphs on n vertices;
- Optimality depends on the represented class.

	General Graphs	Trees	Complete Graphs
Adjacency Matrix: O(n²)		X	X
Adjacency List: O(m log n)	X		





2^{⊖(n log n)} members:

- Trees;
- Interval graphs;
- Planar;
- Complete graphs;
- ...

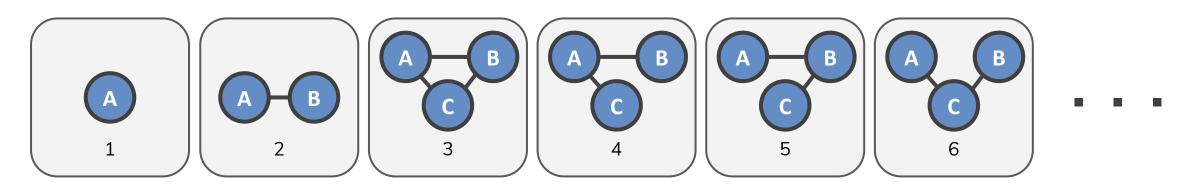
2^{Θ(n²)} members:

- General graphs;
- Bipartites/co-bipartite;
- Split;
- Chordal;
- Comparability;
- ...





- A representation is said to be **space optimal** if it requires O(f(n)) bits to represent a class containing $2^{\Theta(f(n))}$ graphs on n vertices;
- We could just enumerate all labelled graphs and use that as optimal representation.







A representation is said to be **implicit** if it has the following properties:



Space optimal

O(f(n)) bits to represent a class containing $2^{\Theta(f(n))}$ graphs on n vertices;



Distributes information

Each vertex stores O(f(n)/n) bits;



Local adjacency test

Only local vertex information is required to test adjacency;



Probabilistic Implicit Representations

For **probabilistic implicit representations**, we introduce a **fourth property**:



Space optimal

O(f(n)) bits to represent a class containing $2^{\Theta(f(n))}$ graphs on n vertices;



Distributes information

Each vertex stores O(f(n)/n) bits;



Local adjacency test

Only local vertex information is required to test adjacency;



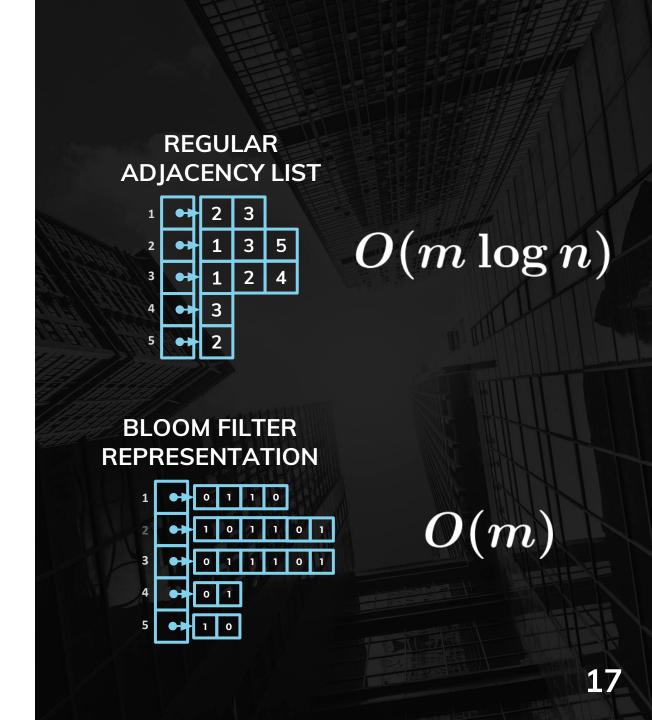
Probabilistic adjacency test

Constant relative probability of false positives or false negatives.

Bloom filter

Idea: to **replace** each vertex set in an adjacency list with a **Bloom filter**.

- Each edge would require only
 O(1) bits, instead of O(log n);
- By using Bloom filters, there would be no false negatives, only false positives.
- Similarly, a single Bloom filter could be used to store the entire edge set, but technically this would not be an implicit representation.



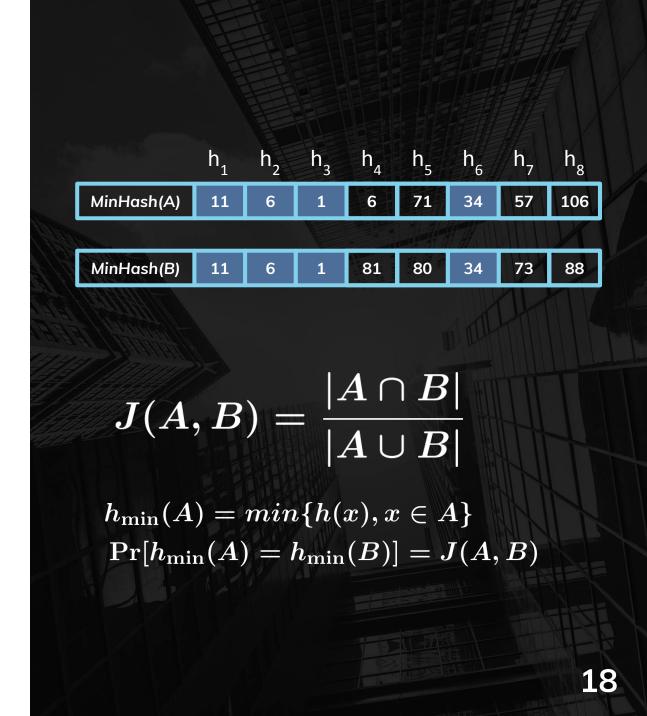
MinHash

Represents sets through a constant-sized signature and allow computing the Jaccard coefficient between two or more sets.

- This is known as a Locality-Sensitive Hashing (LSH).
- Similar techniques encode other metrics, e.g. Charikar Signatures (SimHash) encode cosine distance.

Broder, A. Z. (1997). On the resemblance and containment of documents. In Compression and complexity of sequences.

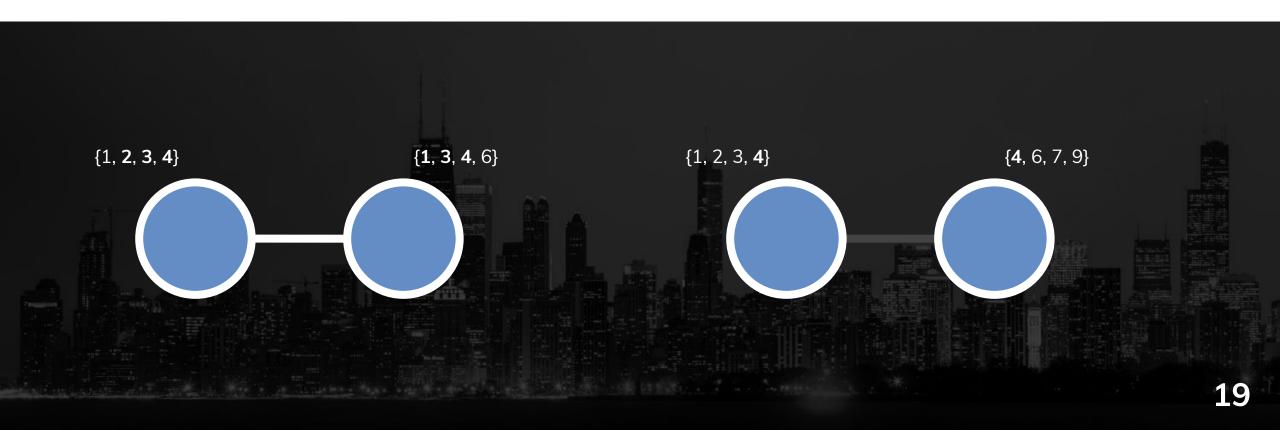
Charikar, Moses S. (2002). Similarity estimation techniques from rounding algorithms. Proceedings of STOC'02.



MinHash



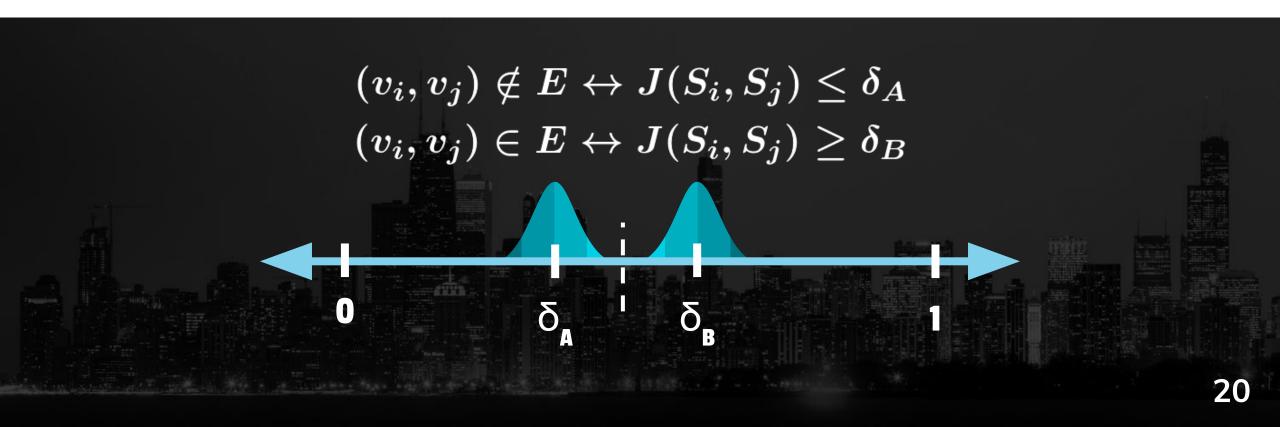
Idea: construct a set for each vertex, such that the Jaccard index between any pair of vertices encodes their adjacency.



MinHash



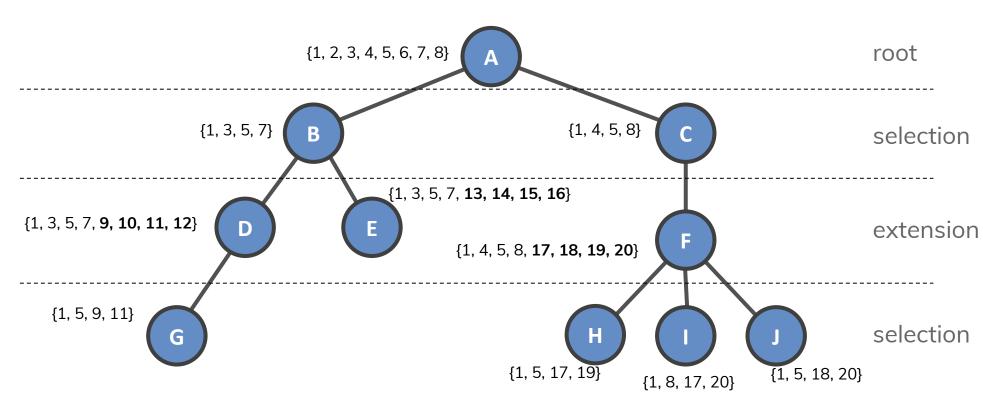
Idea: construct a set for each vertex, such that the Jaccard index between any pair of vertices encodes their adjacency.







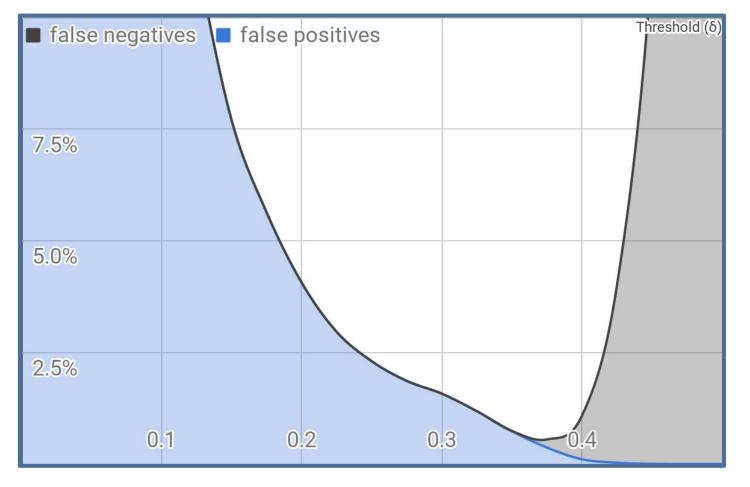
Example of sets construction for $\delta_A = \frac{1}{3}$ and $\delta_B = \frac{1}{2}$.







For MinHash-based representation

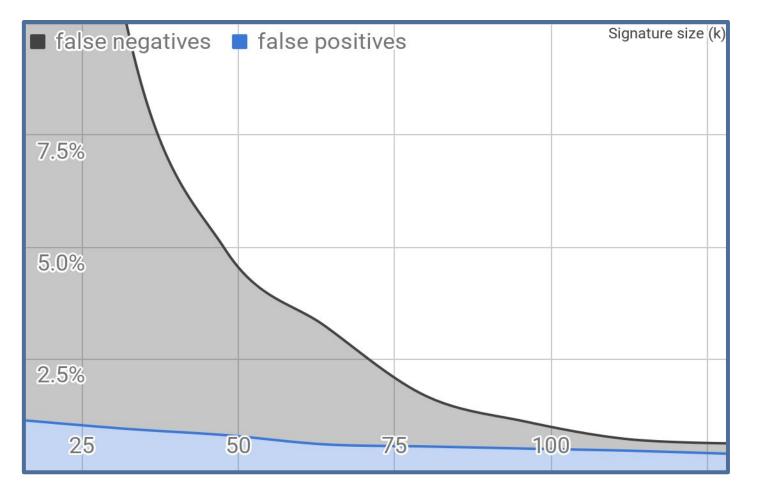


Observations

- The experiment was run with k=128 hash functions and a graph with n=200 vertices.
- Increasing the threshold seems to increase the rate of false negatives and decrease false positives.
- The perfect threshold depends on the application tolerance for false positives and false negatives.



For MinHash-based representation

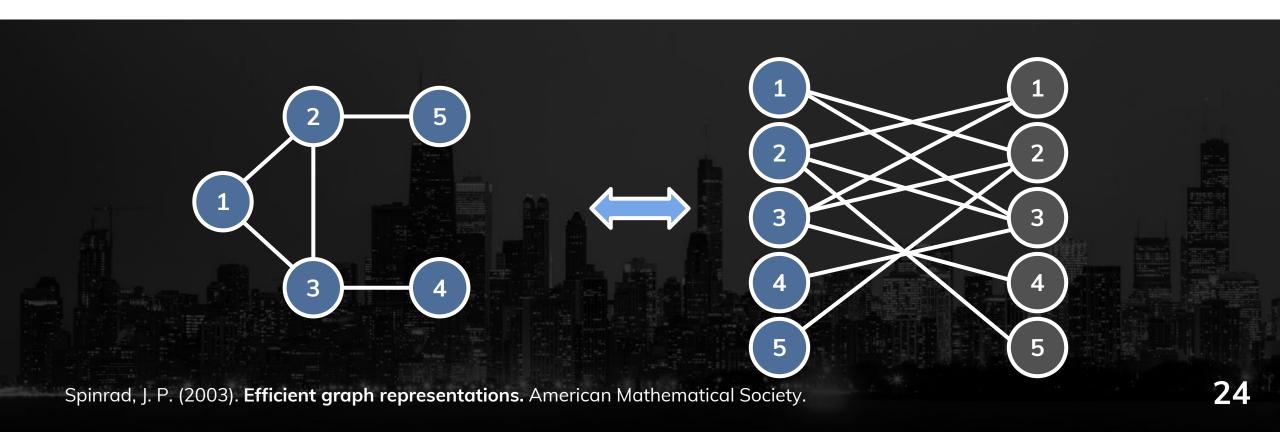


Observations

- The experiment was run with $\delta = 0.375$ and a graph with n=200 vertices.
- Increasing the signature size seems to have more effect on the rate of false negatives than positives.
- This effect appears the same for whatever choice of threshold.



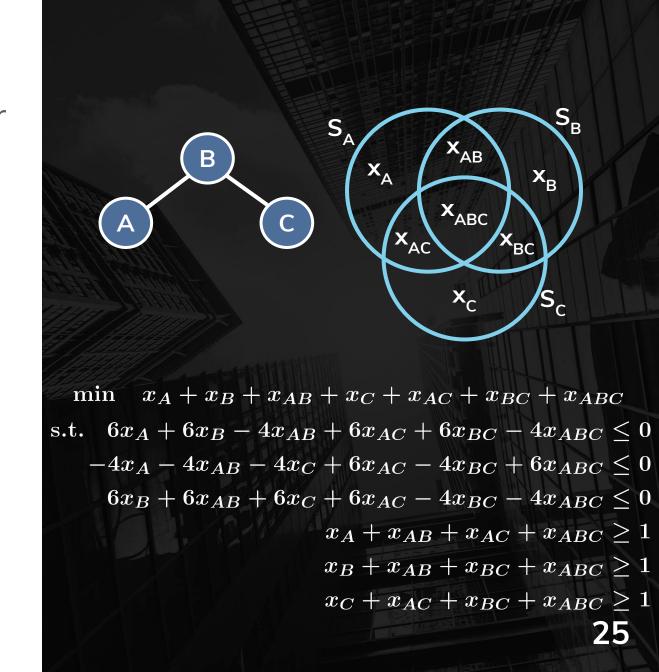
Any efficient representation for bipartite, co-bipartite or split graphs can be used to represent general graphs efficiently.



Other results

Modeling this problem through integer programming allows proving the infeasibility of specific configurations.

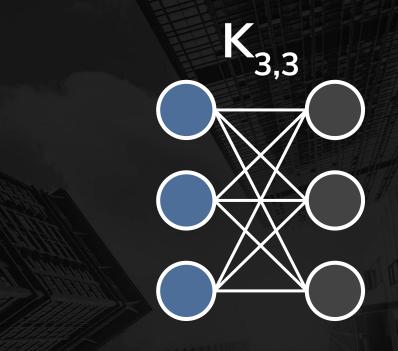
- Each possible subset of vertices is modelled as a variable.
- Each variable describes the size of the set intersection between those vertices.



Other results

Modeling this problem through integer programming allows proving the infeasibility of specific configurations.

- Each possible subset of vertices is modelled as a variable.
- Each variable describes the size of the set intersection between those vertices.
- Do all threshold values have an infeasible bipartite graph? Still an open problem.



- Impossible for $\delta_A = 0.4 \text{ e } \delta_B = 0.6$.
- Possible for $\delta_A = \frac{1}{3} e \delta_B = \frac{1}{2}$.





Some open questions



Other graph classes?

It seems plausible that other classes with $2^{\Theta(n \log n)}$ graphs should probably admit efficient probabilistic representations.



Any class with $2^{\Theta(n^2)}$ graphs?

Finding such class could prove this technique useful even for relatively small graphs.



Bipartite, co-bipartite, or split?

Proving that would imply the existence of an efficient probabilistic representation in O(n) bits for all graphs.

This work was awarded as one of the **top 9 master's thesis of 2017** in a contest held by the Brazilian Computer Society (SBC).

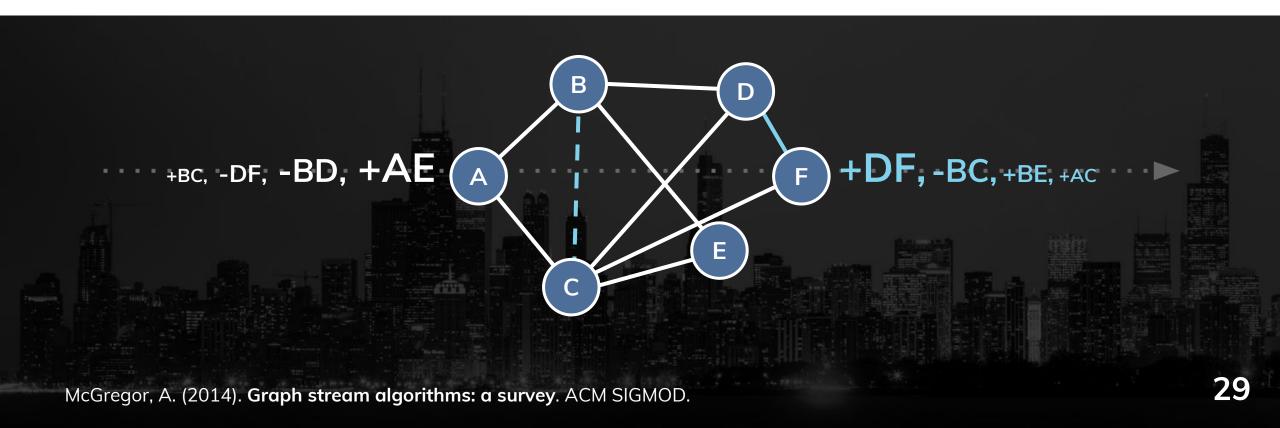
How to represent **dynamic graphs** in sublinear space?



Graph Streams are graphs represented in the data stream model, i.e.

single-pass through a stream of edge insertions and deletions.

Problem: compute parameters with restricted space.





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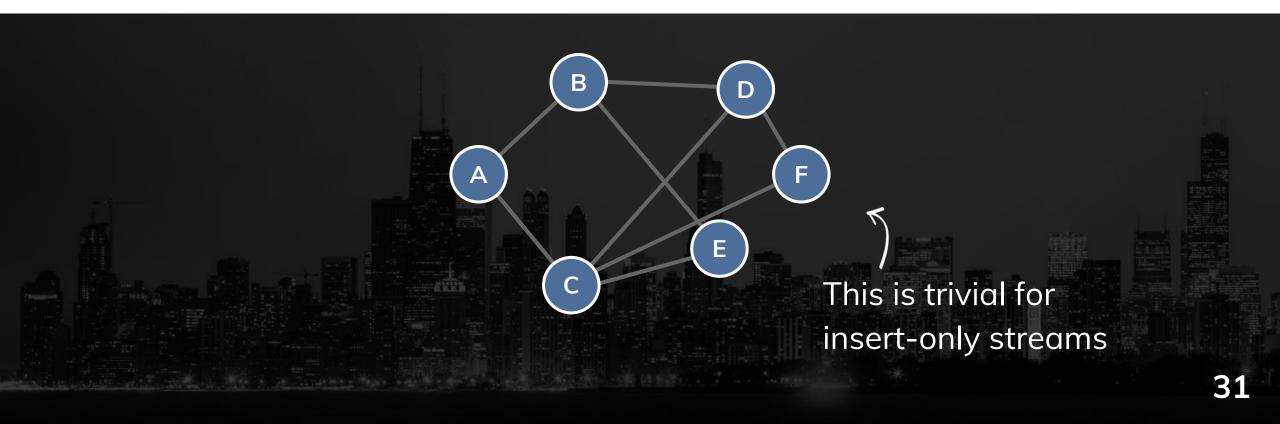
Problem: compute parameters with restricted space.

	Insert-Only	Insert-Delete	Sliding Window (width w)
Connectivity	Deterministic [27]	Randomized [5]	Deterministic [22]
Bipartiteness	Deterministic [27]	Randomized [5]	Deterministic [22]
Cut Sparsifier	Deterministic [2,8]	Randomized [6, 31]	Randomized [22]
Spectral Sparsifier	Deterministic [8,46]	Randomized $\tilde{O}(n^{5/3})$ space [7]	Randomized $\tilde{O}(n^{5/3})$ space [22]
(2t-1)-Spanners	$O(n^{1+1/t})$ space [11,23]	Only multiple pass results known [6]	$O(\sqrt{wn^{(1+1/t)}})$ space [22]
Min. Spanning Tree	Exact [27]	$(1 + \epsilon)$ -approx. [5] Exact in $O(\log n)$ passes [5]	$(1+\epsilon)$ -approx. [22]
Unweighted Matching	2-approx. [27] 1.58 lower bound [42]	Only multiple pass results known [3, 4]	$(3+\epsilon)$ -approx. [22]
Weighted Matching	4.911-approx. [25]	Only multiple pass results known [3, 4]	9.027-approx. [22]

Table 1: Single-Pass, Semi-Streaming Results: Algorithms use $O(n \operatorname{polylog} n)$ space unless noted otherwise. Results for approximating the frequency of subgraphs discussed in Section 2.3.

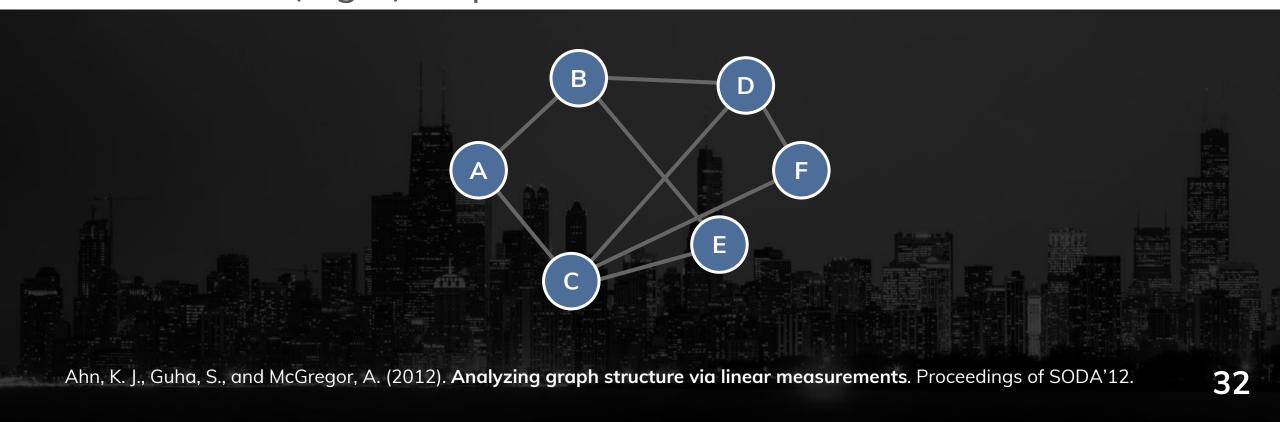


Is it possible to check if the graph is **connected** in a streaming model? Can we sample a full **spanning forest** using **O(n log^c n) bits**?

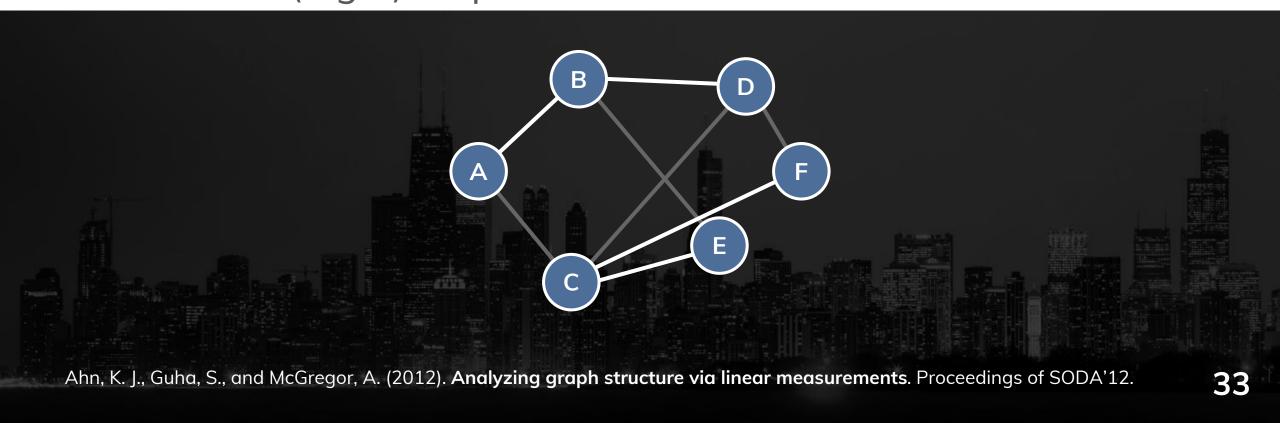




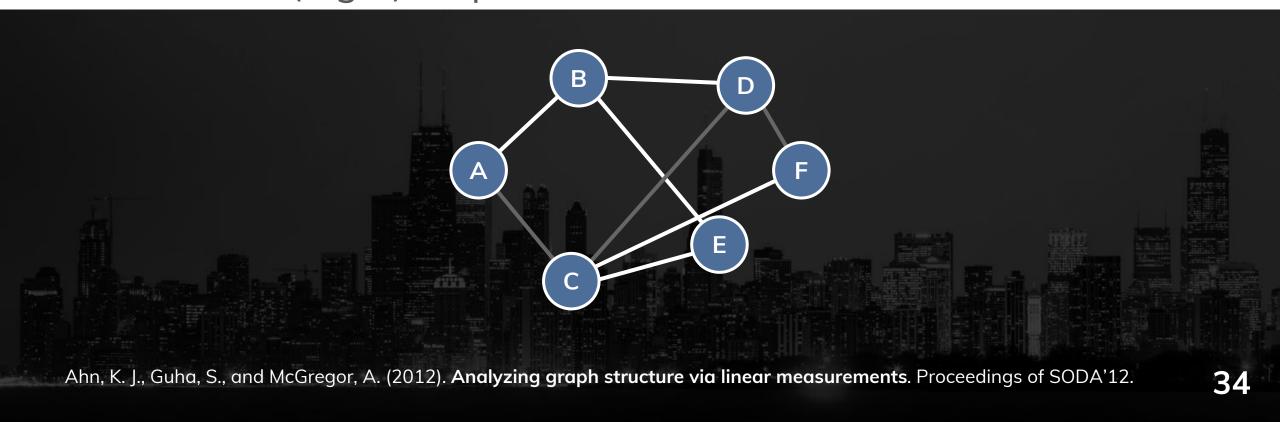
Idea: we can sample an edge from each vertex and merge its endpoints in a single "super-vertex". Repeat. This procedures finishes in O(log n) steps.



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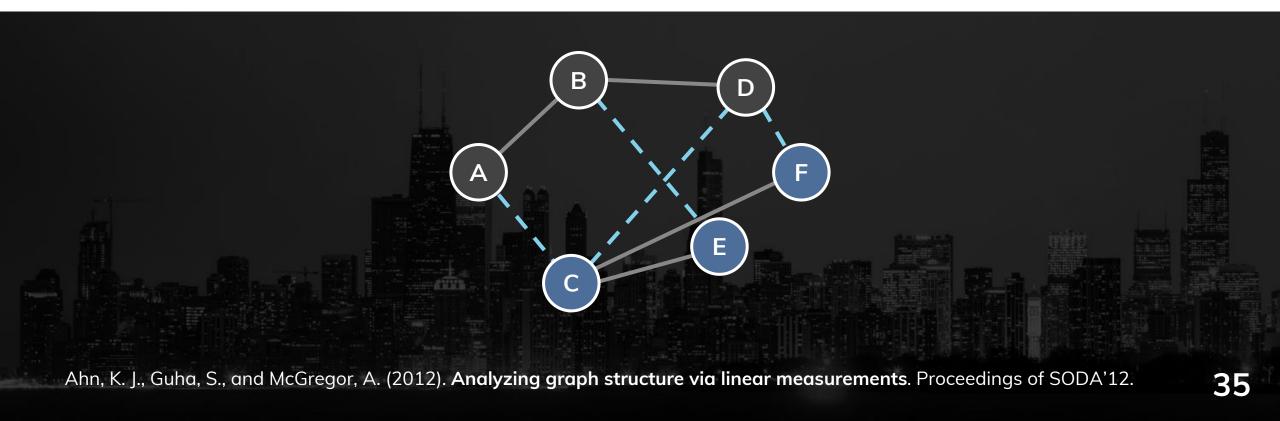


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A simpler problem:

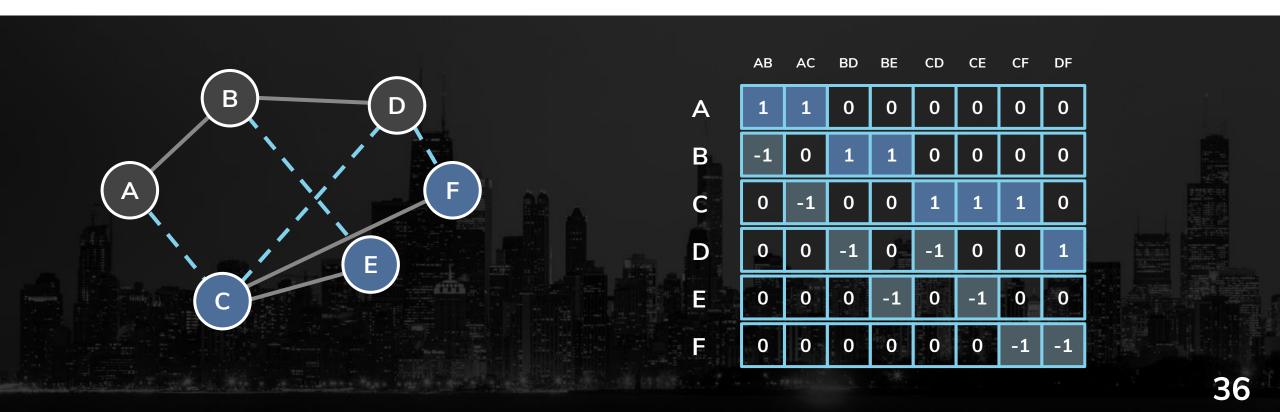
Is it possible to sample a random edge from any cut-set $[S, V\S]$ in a graph stream storing $O(n \log^c n)$ bits?





Sampling edges from cut-set

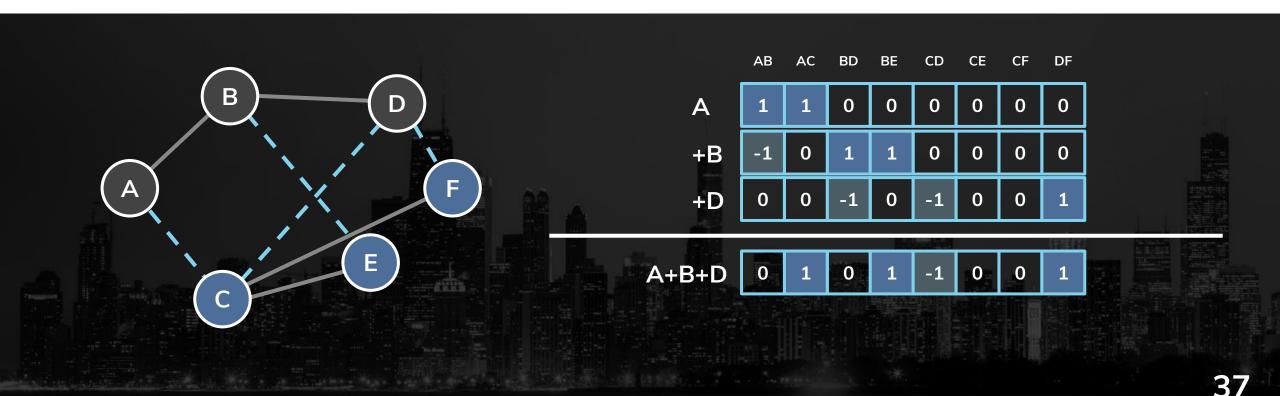
Idea: to represent graph through a modified **incidence matrix**, where each edge has value 1 or -1, depending on which vertex is the endpoint.





Sampling edges from cut-set

The main benefit from this representation is the ability to **sum incidence vectors** to find the corresponding vector of a cut-set. Being able to **sample nonzero coordinates** from this vector implies sampling edges from such cut-set.



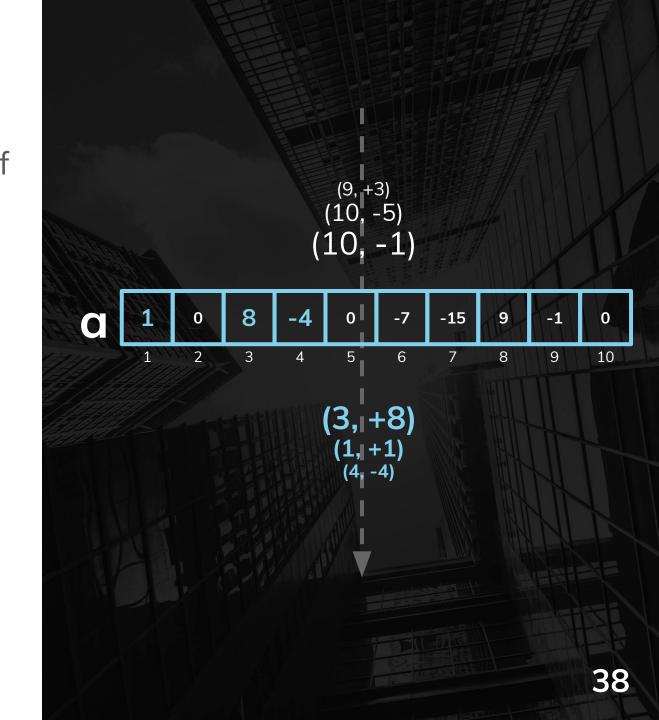
What is ℓ_0 -sampling?

Sampling, with uniform probability, of a nonzero coordinate from a vector **a**, represented incrementally by a stream of updates.

- Some updates may cancel others;
- Must be done in sublinear space;
- Known lower-bound: $\Omega(\log^2 n)$.

Cormode, G., Muthukrishnan, S., and Rozenbaum, I. (2005). **Summarizing and mining inverse distributions on data streams via dynamic inverse sampling**. In Proceedings of VLDB'05.

Jowhari, H., Saglam, M., and Tardos, G. (2011). **Tight bounds for lp-samplers, finding duplicates in streams, and related problems**. In Proceedings of PODS'11.



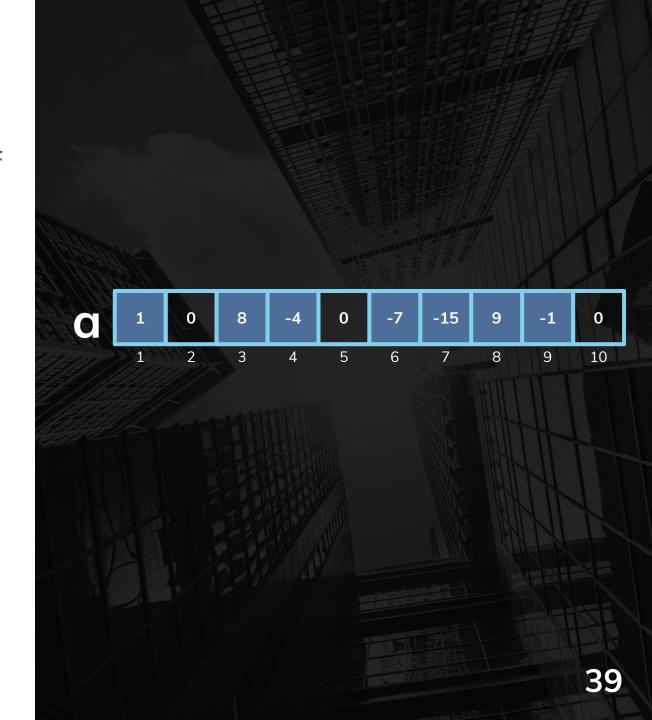
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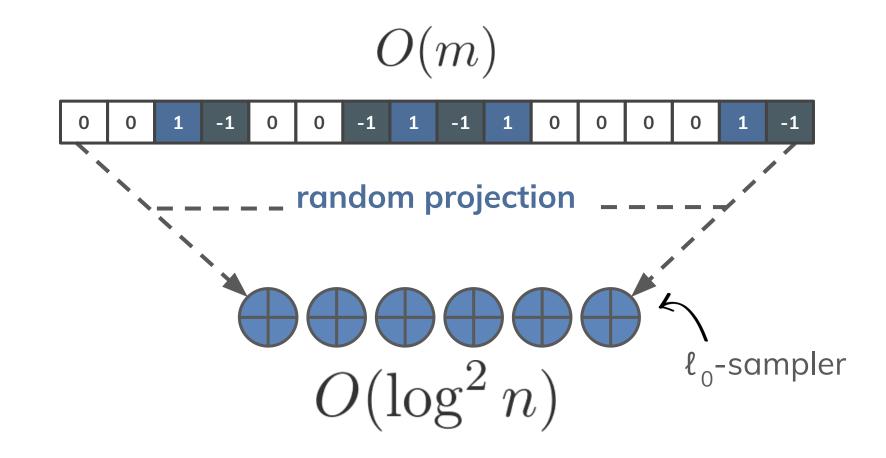
Jowhari, H., Saglam, M., and Tardos, G. (2011). **Tight bounds for lp-samplers, finding duplicates in streams, and related problems**. In Proceedings of PODS'11.





Sampling edges from cut-set

Is it possible to encode each incidence vector in a compact representation?





ℓ_0 -sampling algorithm

The sampling algorithm is based on the following idea:



Assign each coordinate a random bucket

Use hash functions. Each bucket must have **exponentially decreasing** probabilities of representing each coordinate.



Find 1-sparse vector

There is a **high probability** that at least one bucket will represent a 1-sparse vector, that is, a vector with a single nonzero coordinate.

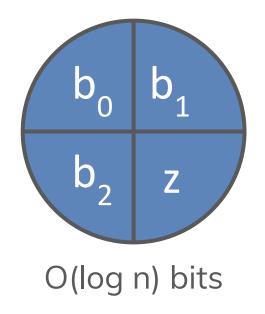


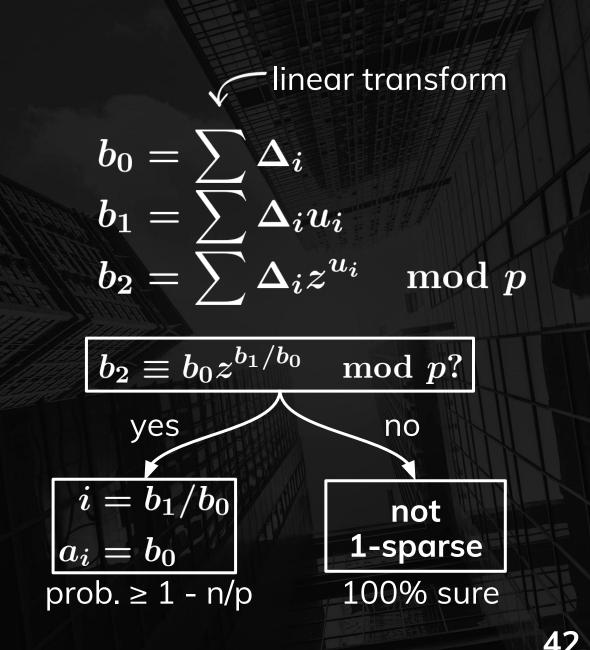
Recover its only nonzero coordinate

Through a randomized procedure called **1-sparse recovery**, it is possible to recover the nonzero coordinates from 1-sparse vectors, using O(log n) bits.

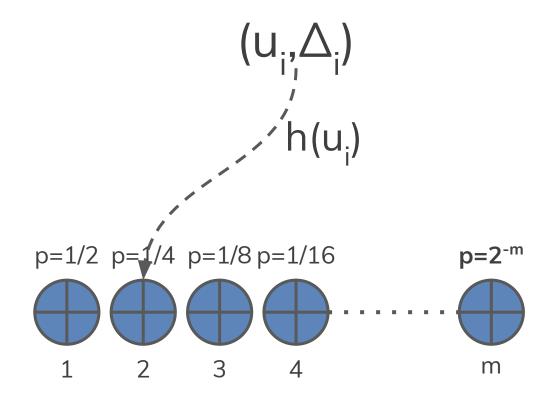
1-sparse recovery

Tests if a vector is 1-sparse. If yes, it recovers the single nonzero coordinate.



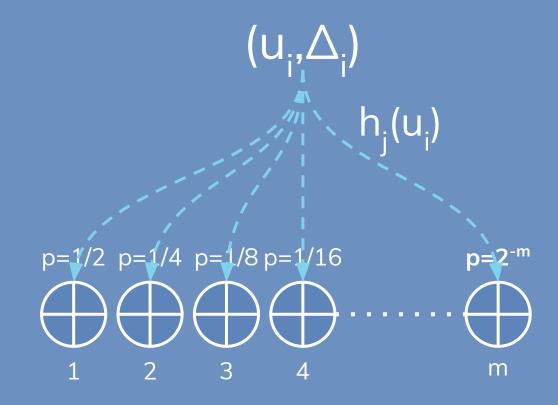


Variant (a)



- Single hash function (more efficient);
- Non-independent buckets.

Variant (b)

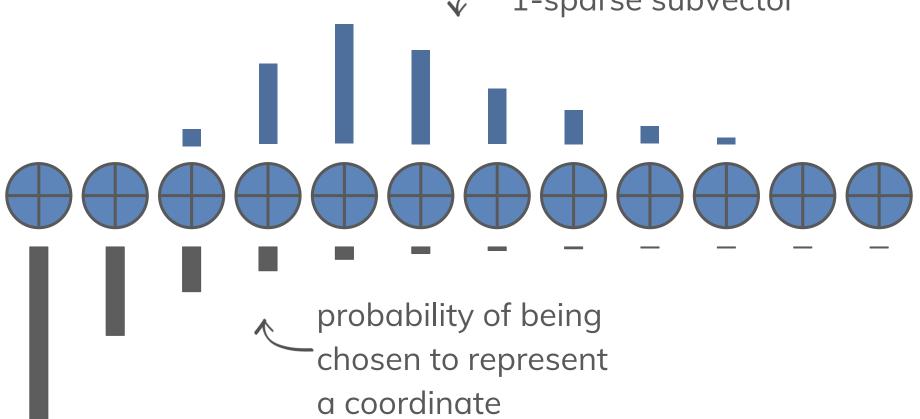


- Multiple hash function;
- Independent buckets (easier).

ℓ_0 -sampling algorithm

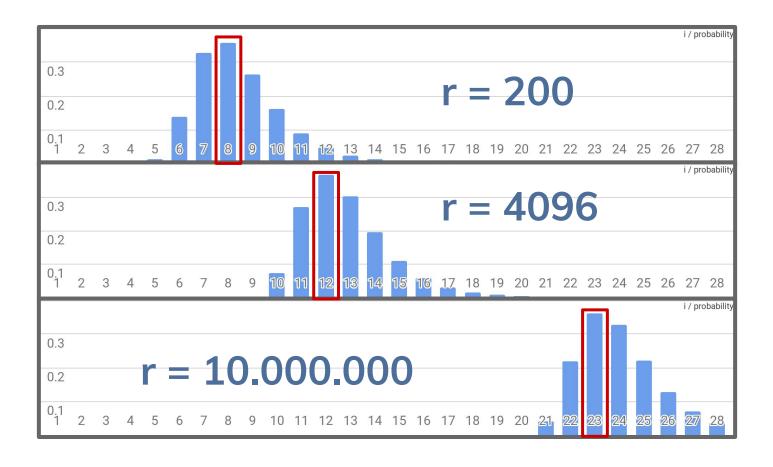
Two distinct probabilities

probability of representing a 1-sparse subvector



ℓ_0 -sampling algorithm $p_i = r2^{-i} \exp(-r2^{-i})$

$$p_i = r2^{-i} \exp(-r2^{-i})$$



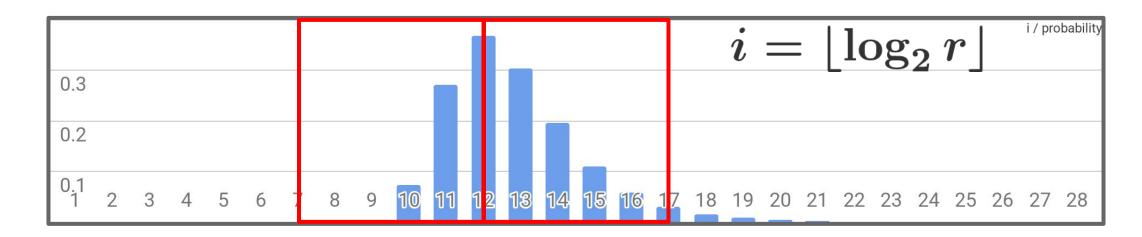
Observations

- We define r, the number of nonzero coordinates in a vector. p_i is the probability of the ith bucket being 1-sparse.
- It is easy to see that for every value of r, there will always be a bucket with high probability of recovery (~0.35).
- There will also be other adjacent buckets with high probability of recovery.



ℓ_0 -sampling algorithm

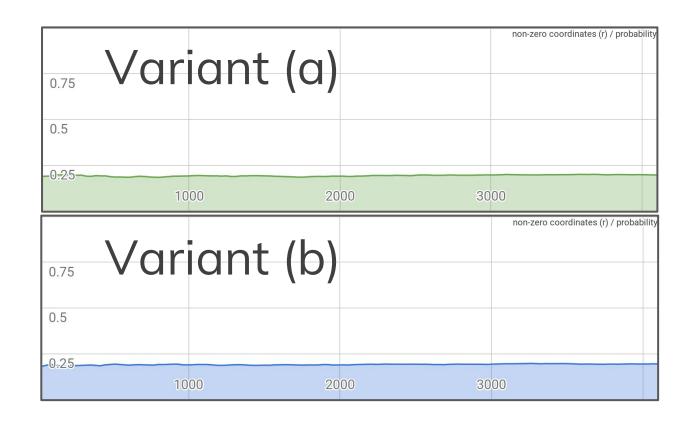
 $m = \lceil \log_2 n + 5 \rceil$ is enough to ensure a probability of failure of less than 0.31.



$$\Pr[ext{Failure}] \leq \prod_{k=i-5}^{i+5} 1 - r2^{-k} \exp(-r2^{-k}) \leq 0.31$$
 analyzing factors' maxima



Correcly sized setup.



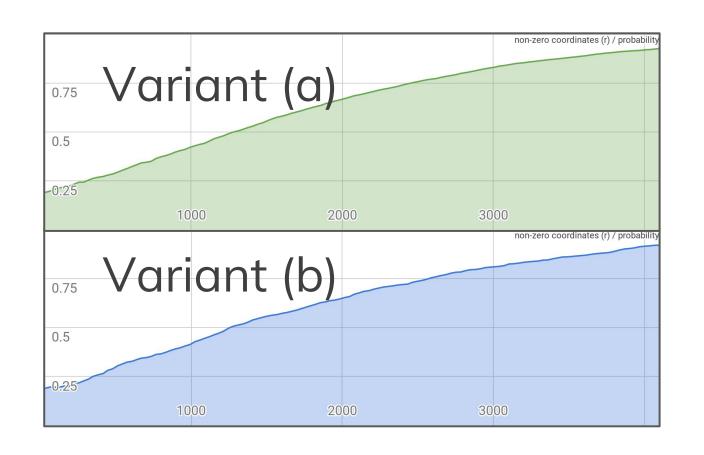


Observations

- We tested both variants in a correctly sized setup, i.e. $r \le 4096$, m = 17.
- Variants behave similarly, with error apparently constant under 20% in both tests.
- The distribution of sampled coordinates (not shown) was also similar in both tests.



Undersized setup.



Observations

We tested both variants in an undersized setup, i.e. $r \le 4096$, m = 10.

Variants behave similarly, with error growing from under 20% to almost 100% in both tests.

The distribution of sampled coordinates (not shown) was also similar in both tests.

Outlook

What should we expect from **sketching data structures** in a near future?



In this talk...

... I presented the application of three **sketching data structures** for massive graph problems.



Bloom Filter

Adjacency test on general graphs in O(m) bits. Specially useful for sparse massive graphs. Has constant probability of false positives. No false negatives.



MinHash

Adjacency test on trees in O(n) bits. Better space complexity than the optimal deterministic representation. Useful for giant trees (over a billion nodes).



ℓ₀-Sampler

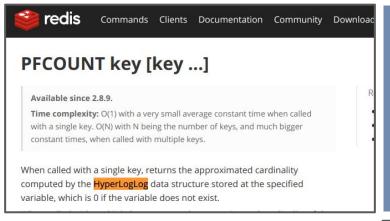
Dynamic spanning forest in O(n log³ n) bits. Useful for very dense graphs.



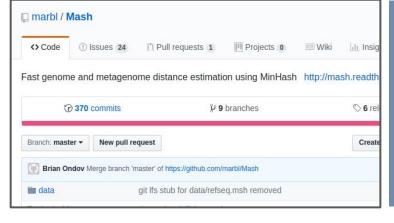
Sketching data structures are growing

Not only a theory. Not only for graphs.

Mash: Fast genome and metagenome distance estimation using **MinHash**.



MMDS book chapter 4: several sketch-based stream algorithms.



Redis **PFCOUNT**: set distinct count using **HyperLogLog**.





Our next steps

We are searching for new algorithms that use ℓ_0 -sampling as a primitive



 ℓ_0 -Sampler

The ability to sample edges from cut-sets is very useful and can help to produce many new graph algorithms.

