

JUAN SALAZAR

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Education	Massachusetts Institute of Technology (MIT), Cambridge, MA	
	M. Eng in Electrical Engineering and Computer Science GPA: 4.4	May 2022
	B.S. in Aerospace Eng. (Conc. in Autonomous Systems) & Electrical Eng. GPA: 4.4	June 2020
	Underactuated Robotics · Manipulation · Control · Space Systems Engineering	
Research & Work Experience	ARES Corporation (NASA Johnson Space Center), Houston, TX	January 2023 - Present
	<i>Systems Engineer/ISS Robotics Analyst</i> <ul style="list-style-type: none">• Design ISS robotic arm trajectories to assess kinematic feasibility of planned operations• Present results at engineering review and ISS program management boards• Develop applications to automate workflow and extend analysis software functionality in Python	
	Distributed Robotics Laboratory (CSAIL), Cambridge, MA	July 2018 - May 2022
	<i>Undergraduate/Graduate Research Assistant</i> <ul style="list-style-type: none">• Developed autonomous coordination for soft robotic fish that led to publication• Contributed to development of visual tracking algorithm using OpenCV and ROS• Developed tools for computational design and control of underwater vehicles using Python	
Leadership	NASA BIG Idea Challenge (Extreme Terrain Mobility)	November 2021 - June 2022
	<i>Software & Autonomy Lead</i> <ul style="list-style-type: none">• Led a team of 5 to develop simulation for finalist lunar robot in 2022 BIG Idea Challenge• Developed physics-based hexapod walking simulator using ROS, Python, and Gazebo to support real design trade studies• Formulated software architecture and walking capability system requirements	
	MIT Rocket Team	August 2018 - July 2019
	<i>Payload Team Lead, Outreach Chair</i> <ul style="list-style-type: none">• Led development of sensor payload for sounding rocket launched to ~10,000 ft• Developed microcontroller firmware for onboard sensor operations and data storage in C	
Publications	Juan Salazar , Levi Cai, Braden Cook, Daniela Rus. “Multi-Robot Visual Control of Autonomous Soft Robotic Fish.” Accepted, IEEE OES AUV Symposium, 2022.	
Skills & Awards	Software: Python, C/C++, Git, Gazebo, ROS, Linux, MATLAB Hardware: 3D Printers, Microcontrollers, Circuits & Electronics Languages: French (fluent), Spanish (fluent) Awards: 1st Place Team, 2018 Unified Engineering Flight Competition	