Least squares Sample Subtitle

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Showing why least squares

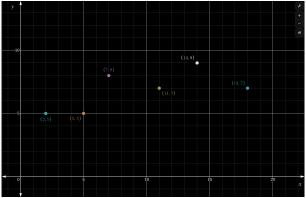
We have a variable y. We know that it's dependent of another variable x in some way. But we don't know how, exactly. So we go to the field and measure certain points. Those that we can reach. Six of them.

$$(2,5), (5,5), (7,8), (11,7), (14,9), (18,7)$$

That is: at x = 2 we measure y = 5, at x = 5 we measure y = 5 again, but at x = 7 we got y = 8, and so on.

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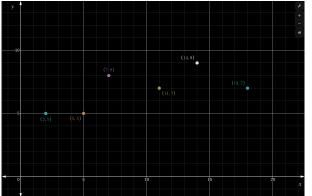
Back to desk we plot these points.



There is a model lurking in these points? A line perhaps?

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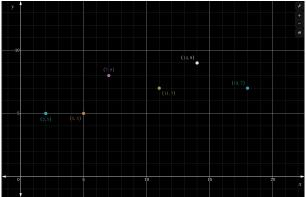
Let's start by tracing a line wich "best fit" that data



Why a line? To warm the modeling machine in our minds we are considering a line, a one degree polynomial.

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What line to plot? How to choose that line?



Enter the math...

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A very common way to express a line in the plane is isolating y as a polynomial function of x:

$$y = mx + b$$

From this equation we can see that m is the *slope* of the line and b is the y-intercept (the value of y when x = 0).

Will be handy for us to write this equation using vector notation:

$$y = \begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix}$$

And switching terms:

$$\begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = y$$

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Ok. Fine. This form

$$\begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = y$$

will be a useful one because we know x and y in six points. For example take the first point (2,5)

$$\begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = 5$$

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And yes, your guess is true. We can incorporate the second point (5,5) and get

$$\begin{bmatrix} 2 & 1 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \end{bmatrix}$$

Doing the product you can workout m and b from this equation. m=0 and b=5. Because the matrix is square. And invertible by the way.

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Going further, incorporate the third point.

$$\begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ 8 \end{bmatrix}$$

This invalidate the previous result. m cannot be 0 more. Neither b with 5.

Actually, henceforth the equation is over-determined and have no solution.

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Fourth point.

$$\begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ 8 \\ 7 \end{bmatrix}$$

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Fifth point.

$$\begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \\ 14 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ 8 \\ 7 \\ 9 \end{bmatrix}$$

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Sixth and last point.

$$\begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \\ 14 & 1 \\ 18 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \\ 7 \\ 9 \\ 7 \end{bmatrix}$$

This is the equation derived from our measurement.

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Time to name things.

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Call A to the matrix

$$A = \begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \\ 14 & 1 \\ 18 & 1 \end{bmatrix}$$

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Call x to the column vector

$$x = \begin{bmatrix} m \\ b \end{bmatrix}$$

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Call b to the column vector

$$b = \begin{bmatrix} 5 \\ 5 \\ 8 \\ 7 \\ 9 \\ 7 \end{bmatrix}$$

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Thus, the equation

$$\begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \\ 14 & 1 \\ 18 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ 8 \\ 7 \\ 9 \\ 7 \end{bmatrix}$$

becomes

$$Ax = b$$

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In other words: if you want to know the values m and b in the equation y = mx + b of the line we are searching find the x such Ax = b.

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$$||Ax - b|| \neq 0$$

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$$||Ax - b|| \neq 0$$

We need the least squares approximate solution

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In the least squares approximate solution of Ax = b we, provided that $||Ax - b|| \neq 0$, select x that the *norm* of the *residual* r = Ax - b is minimal.

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Let's see it.

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All start with our equation Ax = b.

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Take the original matrix A:

$$A = \begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \\ 14 & 1 \\ 18 & 1 \end{bmatrix}$$

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Take the original matrix A:

$$A = \begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \\ 14 & 1 \\ 18 & 1 \end{bmatrix}$$

Transpose it, and get A^{T} :

$$A^{\mathsf{T}} = \begin{bmatrix} 2 & 5 & 7 & 11 & 14 & 18 \\ 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

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Multiply A^{T} by A

$$A^{\mathsf{T}}A = \begin{bmatrix} 2 & 5 & 7 & 11 & 14 & 18 \\ 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \\ 11 & 1 \\ 14 & 1 \\ 18 & 1 \end{bmatrix} = \begin{bmatrix} 719 & 57 \\ 57 & 6 \end{bmatrix}$$

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Invert the product

$$(A^{\mathsf{T}}A)^{-1} = \begin{bmatrix} 719 & 57 \\ 57 & 6 \end{bmatrix}^{-1} = \begin{bmatrix} \frac{2}{355} & -\frac{19}{355} \\ -\frac{19}{355} & \frac{719}{1065} \end{bmatrix}$$

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Multiply inverse and transpose

$$(A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}} = \begin{bmatrix} \frac{2}{355} & -\frac{19}{355} \\ -\frac{19}{355} & \frac{719}{1065} \end{bmatrix} \begin{bmatrix} 2 & 5 & 7 & 11 & 14 & 18 \\ 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{3}{71} & -\frac{9}{355} & -\frac{1}{71} & \frac{3}{355} & \frac{9}{355} & \frac{17}{355} \\ \frac{121}{213} & \frac{434}{1065} & \frac{64}{213} & \frac{92}{1065} & -\frac{79}{1065} & -\frac{307}{1065} \end{bmatrix}$$

Let's call this product $(A^{T}A)^{-1}A^{T}$ the *pseudo-inverse*

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Finally multiply the pseudo-inverse by b

$$x = (A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}b \tag{1}$$

$$= \begin{bmatrix} -\frac{3}{71} & -\frac{9}{355} & -\frac{1}{71} & \frac{3}{355} & \frac{9}{355} & \frac{17}{355} \\ \frac{121}{213} & \frac{434}{1065} & \frac{64}{213} & \frac{92}{1065} & -\frac{79}{1065} & -\frac{307}{1065} \end{bmatrix} \begin{bmatrix} 5\\8\\7\\9\\7 \end{bmatrix}$$
(2)

$$= \begin{bmatrix} \frac{61}{355} \\ \frac{5539}{1065} \end{bmatrix} \tag{3}$$

$$= \begin{bmatrix} 0.171831 \\ 5.20094 \end{bmatrix} \tag{4}$$

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That's it

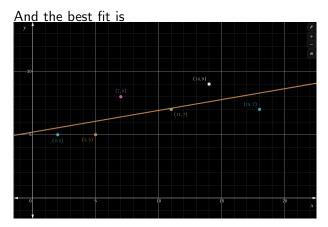
$$x = \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} \frac{61}{355} \\ \frac{5539}{1065} \end{bmatrix} \text{ or } \begin{bmatrix} 0.171831 \\ 5.20094 \end{bmatrix}$$

and m = 0.171831and b = 5.20094and the line is

$$y = 0.171831x + 5.20094$$

and that is the line which best fit our data points.

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Least squares

Recapitulation

You have a bunch of data points and suspect that a polynomial function y = Ax + B from this points is a good model.

You build a matrix A and a vector b from the polynomial and the points.

The polynomial coefficients are a vector x so Ax = bThen $x = (A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}b$

Least squares

Don't worry, its XXI century

So the key is calculate $x = (A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}b$. But you don't need to do this by hand like Gauss did. See the code, in this case Javascript code, using the mathjs package.

```
const { multiply, transpose, inv, matrix, format } =
   require( "mathjs")
const solve = (A. b) \Rightarrow \{
  const transposed = transpose(A)
  const product = multiply(transposed, A)
  const inverse = inv(product)
  const pseudoInverse = multiply(inverse, transposed)
                     = multiply(pseudoInverse, b)
  const x
  return x
const A = matrix([[2,1],[5,1],[7,1],[11,1],[14,1],[18,1]))
const b = matrix([5,5,8,7,9,7])
console.log(format(solve(A, b),5))
```

The polynomial function

Get a terminal and do the magic

The polynomial function

Get a terminal and do the magic

```
$ node ls.js
[0.17183, 5.2009]
```

Going further

Mind blowing is coming

To avert catastrophic damage in our brains it's time to rename things

In the example we found a line y = mx + b, now:

m becomes a₁

b becomes a₀

x becomes x_1

y remains the same

The found line, then, becomes

$$y = a_1 x_1 + a_0 = 0.17183 x_1 + 5.2009$$

Nothing has changed, only the names.

The polynomial function

In the example we picked a line for regression.

A line in a plane can be expressed as a polynomial function $P(x_1)$ where y (the dependent variable, a real number) is a function of x_1 (the independent variable, a real number)

$$y \colon \mathbb{R} \to \mathbb{R} = P(x_1) = a_1x_1 + a_0$$

But there are others $P(x_1)$ s, for example:

$$y \colon \mathbb{R} \to \mathbb{R} = P(x_1) = a_2 x_1^2 + a_1 x_1 + a_0$$

What about using that quadratic function as the model for the measured points?

Let's see...

A curve as a model

That is the curve: $y = a_2x_1^2 + a_1x_1 + a_0$ And those are the points: (2,5), (5,5), (7,8), (11,7), (14,9), (18,7)Replacing x_1 and y in each point, and rearranging:

$$4a_2 + 2a_1$$
 $+a_0 = 5$ (5)
 $25a_2 + 5a_1$ $+a_0 = 5$ (6)
 $49a_2 + 7a_1$ $+a_0 = 8$ (7)
 $121a_2 + 11a_1$ $+a_0 = 7$ (8)
 $196a_2 + 14a_1$ $+a_0 = 9$ (9)
 $324a_2 + 18a_1$ $+a_0 = 7$ (10)

A curve as a model

The curve: $y = a_2 x_1^2 + a_1 x_1 + a_0$ In matrix form:

$$\begin{bmatrix} 4 & 2 & 1 \\ 25 & 5 & 1 \\ 49 & 7 & 1 \\ 121 & 11 & 1 \\ 196 & 14 & 1 \\ 324 & 18 & 1 \end{bmatrix} \begin{bmatrix} a_2 \\ a_1 \\ a_0 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ 8 \\ 7 \\ 9 \\ 7 \end{bmatrix}$$

In this case

$$x = \begin{bmatrix} -0.028205\\ 0.73633\\ 3.2181 \end{bmatrix}$$

and the curve is $y = -0.028205x_1^2 + 0.73633x_1 + 3.2181$

Adding one dimension

Until now we were working with polynomials whis one independent variable (x_1) and one dependent variable (y)

$$y: \mathbb{R} \to \mathbb{R} = P(x_1)$$

What about a polynomial with two independent variables? Nothing, the least squares method stays the same. Note that is all about finding coefficients. So for example take

$$y\colon \mathbb{R}^2 \to \mathbb{R} = P(x_1, x_2)$$

where

$$y = a_5 x_1^2 + a_4 x_2^2 + a_3 x_1 x_2 + a_2 x_1 + a_1 x_2 + a_0$$

Adding one dimension

That function $(y = a_5x_1^2 + a_4x_2^2 + a_3x_1x_2 + a_2x_1 + a_1x_2 + a_0)$ is useful when you need a model to represent height at a certain point given with two coordinates (x_1, x_2) .

In this case we are looking for six coefficients

$$x = \begin{bmatrix} a_5 \\ a_4 \\ a_3 \\ a_2 \\ a_1 \\ a_0 \end{bmatrix}$$

so we need at least six points (x_1, x_2, y) to uniquely determinate those coefficients.

Adding one dimension

If you have more points than six you form the matrix A, form the vector b as usual, and resolve \times using the least squares approximate solution:

$$x = (A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}b$$

Multidimensional input

Of course you can extend the application of least squares to problems where the input have more than two dimension

$$y: \mathbb{R}^n \to \mathbb{R} = P(x_1, x_2, \dots, x_n)$$

Take for example a set of measured temperatures in certain points (ten or more) (x_1, x_2, x_3, t) in the interior of a body. If we want a quadratic model then the polynomial will be:

$$y = f(x_1, x_2, x_3) : \mathbb{R}^3 \to \mathbb{R}$$

$$\tag{11}$$

$$y = a_9 x_1^2 + a_8 x_2^2 + a_7 x_3^2 + a_6 x_1 x_2 + a_5 x_1 x_3 +$$
 (12)

$$a_4x_2x_3 + a_3x_1 + a_2x_2 + a_1x_3 + a_0 (13)$$

Multidimensional input

Take the measurements, build the matrix A evaluating x_1, x_2, x_3 , their products and their squares, build the column vector b evaluating y. Be aware that x (in Ax = b) will be

$$\begin{array}{c}
 a_9 \\
 a_8 \\
 a_7 \\
 a_6 \\
 a_5 \\
 a_4 \\
 a_3 \\
 a_2 \\
 a_1 \\
 a_0
 \end{array}$$

evaluate $x = (A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}b$ and you are done.

Multidimensional output

What about $\mathbb{R}^n \to \mathbb{R}^m$?

Almost the same, with certain precautions.

Take the case of $y: \mathbb{R}^3 \to \mathbb{R}^3$ where

$$y_1: \mathbb{R}^3 \to \mathbb{R} = P_1(x_1, x_2, x_3)$$
 (14)

$$y_2: \mathbb{R}^3 \to \mathbb{R} = P_2(x_1, x_2, x_3)$$
 (15)

$$y_3: \mathbb{R}^3 \to \mathbb{R} = P_3(x_1, x_2, x_3)$$
 (16)

Multidimensional output

We can isolate and resolve each function e.g., taking the first coordinate of $y(y_1)$:

from the measurements and the selected polynomial model form the matrix A_1 so:

$$A_1 x = b_1$$

 $x = (A_1^{\mathsf{T}} A_1)^{-1} A_1^{\mathsf{T}} b_1$

x here denotes $\begin{bmatrix} a_{11} & a_{21} & \dots & a_{n1} \end{bmatrix}^T$ (the second subscript indicates that those are the coefficients of P_1 , the polynomial of y_1)

Doing the same for y_2 and y_3 the model for the transformation $y: \mathbb{R}^3 \to \mathbb{R}^3$ is complete.

But these results came from isolated functions. What if I want a least squares solution for the transformation as a whole? Let's see it.

Multidimensional output

What if I want a least squares solution for the transformation as a whole?

Instead of calculate

$$(A_1^{\mathsf{T}}A_1)^{-1}A_1^{\mathsf{T}}b_1$$
 for P_1
 $(A_2^{\mathsf{T}}A_2)^{-1}A_2^{\mathsf{T}}b_2$ for P_2
 $(A_3^{\mathsf{T}}A_3)^{-1}A_3^{\mathsf{T}}b_3$ for P_3

We cant integrate the evaluation of the column vector x (the coefficients) using the following calculation:

$$x = (A_1^T A_1 + A_2^T A_2 + A_3^T A_3)^{-1} (A_1^T b_1 + A_2^T b_2 + A_3^T b_3)$$

And that is the way to map, for example, from one color set to another given a set of example points.