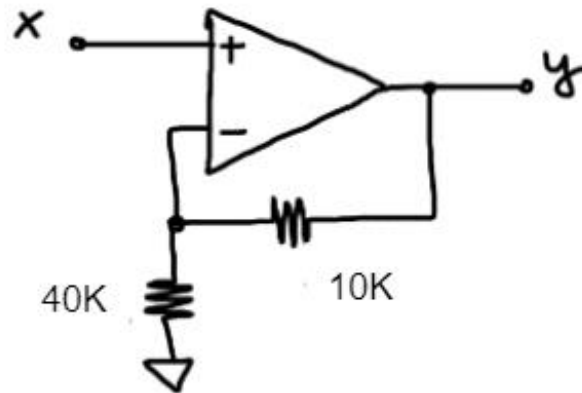
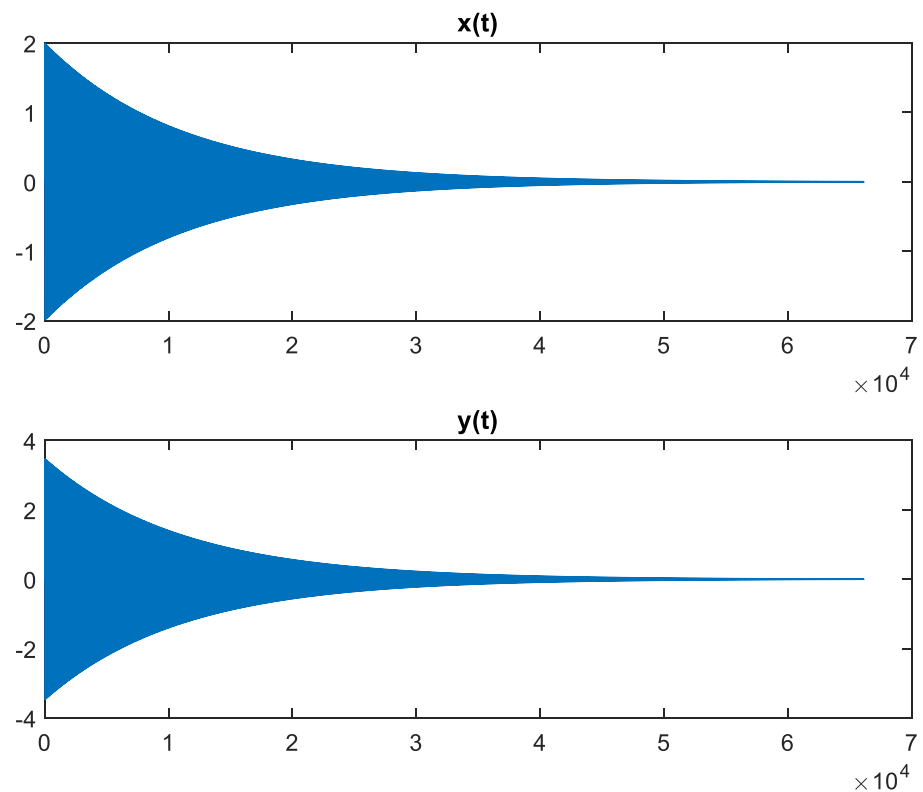


## HOMEWORK 2

$$1. \quad y(t) = \left(1 + \frac{R_2}{R_1}\right) x(t) = \left(1 + \frac{10}{40}\right) x(t) = 1.25x(t) \rightarrow y(t) = 1.25x(t)$$



2. Since we have that  $F_s = 110025\text{Hz}$  that means we will have a sample of the wave every  $1/F_s = 90.7\mu\text{s}$ . If we sample the wave for 6 seconds, we will have a total of 66151 samples for both signals. In the figure  $x(t)$  is the original signal and  $y(t)$  is the amplified signal. Code is at the end. As a fact when we use `sound(y(t))` in MATLAB we hear the same signal but louder.



3. We first get the impulse response  $h(t)$ .

$$V_C(t) = \frac{1}{C} \int_0^t i(\tau) d\tau$$

If we let  $h(t) = V_C(t)$  and  $i(\tau) = \delta(\tau)$  we get that

$$h(t) = \frac{1}{C} \int_0^t \delta(\tau) d\tau = \frac{1}{C}$$

By knowing the relationship between the impulse response and the unit step response we get that  $s(t) = \frac{1}{C} t$ .

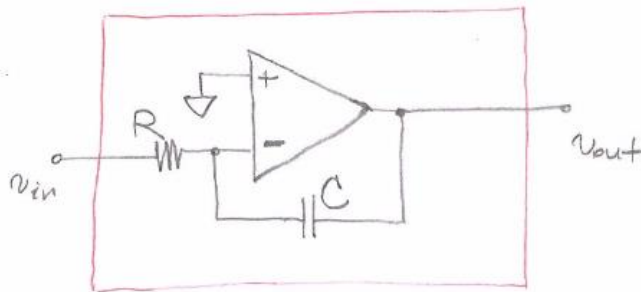
As we can see, the larger  $C$  gets, the smaller the slope will be. For  $C = 1$  we have a ramp function.

4. We can get the transfer function by using the complex impedance of the resistor and the capacitor.

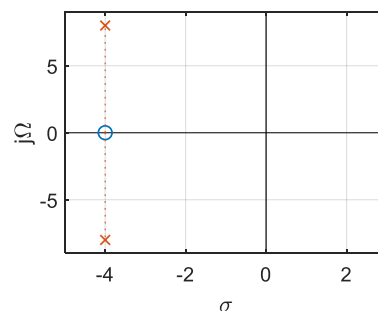
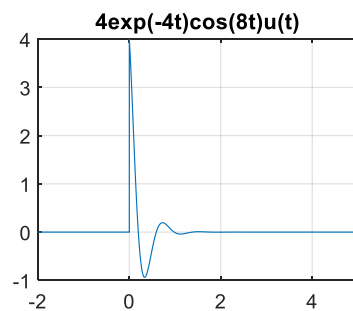
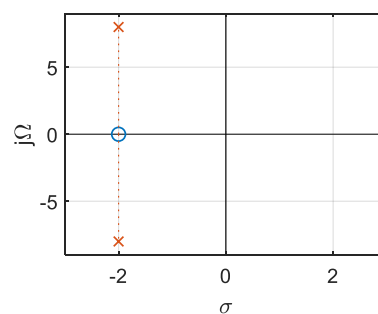
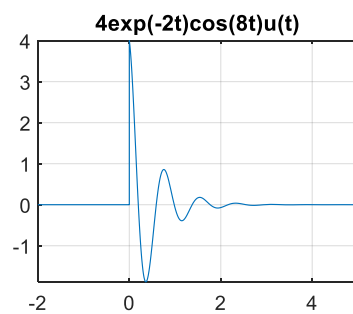
$$Z_C = \frac{1}{Cs} ; Z_R = R ; H(s) = \frac{V_{out}(t)}{V_{in}(t)} = -\frac{Z_C}{Z_R} = -\frac{1}{RCs}$$

For  $V_{in} = u(t)$   $R = 10\text{K}\Omega$  and  $C = 10\mu\text{F}$  we get that

$$V_{out} = -\frac{1}{RC} \int_0^{0.4} u(t) dt = -4V$$



5. Figure shows the output. Code can be seen at the end.



The second sinusoid ( $\exp(-4t)$ ) is more damped, so that is why the poles in the sigma axis are in  $-4$ , which corresponds, as we can see in the time domain, to a more decaying function. However, the location in the complex axis does not change because the frequency of both functions is the same.

6. The one-sided Laplace transform has the following properties:

Functions and constants are causal. Also the one-sided Laplace transform has linearity, time and frequency shifting, expansion and contraction.

Other properties include:

Multiplication by  $t \rightarrow tF(t) = -dF(s)/ds$

Derivative  $\rightarrow sF(s) - f(0^-)$

Second derivative  $\rightarrow s^2F(s) - sf(0) - f'(0)$

Integral  $\rightarrow F(s)/s$

7. See derivation of the formula:

$$X(s) = 0.5\mathcal{L}[e^{j(\Omega_0 t + \theta)}u(t)] + 0.5\mathcal{L}[e^{-j(\Omega_0 t + \theta)}u(t)]$$

$$X(s) = 0.5 \frac{e^{j\theta}}{s-j\Omega} \frac{s+j\Omega}{s+j\Omega} + 0.5 \frac{e^{-j\theta}}{s+j\Omega} \frac{s-j\Omega}{s-j\Omega} = \frac{0.5e^{j\theta}s + 0.5e^{j\theta}j\Omega + 0.5e^{-j\theta}s - 0.5e^{-j\theta}j\Omega}{s^2 + \Omega^2} =$$

$$\frac{s0.5(e^{j\theta} + e^{-j\theta}) - 0.5\frac{1}{j}\Omega(e^{j\theta} - e^{-j\theta})}{s^2 + \Omega^2} = \frac{s\cos(\theta) - \Omega\sin(\theta)}{s^2 + \Omega^2}$$

Special cases:

$$\theta = 0 \rightarrow X(s) = \frac{s}{s^2 + \Omega^2}; \theta = -\frac{\pi}{2} \rightarrow X(s) = \frac{\Omega}{s^2 + \Omega^2}; \theta = \frac{\pi}{4} \rightarrow X(s) = \frac{s - \Omega}{s^2 + \Omega^2}$$

Code for 2:

```
%general data
amp = 2;
freq = 200;
sampling_freq = 11025;
%signal
t=0:1/sampling_freq:6;
y = amp.*exp(-t).*sin(2*pi*freq.*t);
y2 = 0.4*amp.*exp(-(t-0.1)).*sin(2*pi*freq.*(t-0.1));
y3 = 0.2*amp.*exp(-(t-0.4)).*sin(2*pi*freq.*(t-0.4));

ysound = y + y2 + y3;

%sound(y)
%sound(ysound)

subplot(2,1,1)
plot(y)
title('x(t)')
subplot(2,1,2)
plot(ysound)
title('y(t)')
```

Code 5:

```
%general data
amp = 4;
freq = 200;
%signal
t = sym('t');
y = amp*exp(-2*t)*cos(8*t)*heaviside(t);
y2 = amp*exp(-4*t)*cos(8*t)*heaviside(t);
L = laplace(y)
L2 = laplace(y2)
numL=[4 8];denL=[1 4 68];
numL2=[4 16];denL2=[1 8 80];
subplot(2,2,1)
fplot(y,[-2,5]); grid
title('4exp(-2t)cos(8t)u(t)')
subplot(2,2,2)
splane(numL, denL)
subplot(2,2,3)
fplot(y2,[-2,5]); grid
title('4exp(-4t)cos(8t)u(t)')
subplot(2,2,4)
splane(numL2, denL2)
```