

# ISLAMIC UNIVERSITY OF TECHNOLOGY



ARTIFICIAL INTELLIGENCE LAB

CSE 4712

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## Lab 4

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# 1 Tasks

## 1.1 Task 1

Introduce a recursive definition named `sumto` that takes a limit to find the sum of all odd numbers upto the given limit.

**Sample Input:**

```
1 sumto(5, N).
```

**Sample Output:**

```
1 N=9
```

## 1.2 Task 2

In Artificial Intelligence, data often arrives in complex, nested structures (lists within lists), but algorithms often require a simple linear sequence. Your task is to write a Prolog predicate `flatten_list(NestedList, FlatList)`. This predicate should take a list of lists and return a single combined list.

**Sample Input:**

```
1 flatten_list([[a, b], [c], [b, d, e]], X).
```

**Sample Output:**

```
1 X=[a, b, c, b, d, e]
```

## 1.3 Task 3

Prolog naturally attempts to find every possible solution by backtracking. However, in mathematical functions like Factorial, once we reach the base case ( $N = 1$ ), there is no need to search further. The standard definition of factorial below:

```
1 % Base case
2 factorial(1, 1).
3
4 factorial(N, Result) :-
5   N > 1,
6   N1 is N - 1,
7   factorial(N1, R),
8   Result is R * N.
```

Rewrite this predicate to include the Cut (!) operator in the base case. This should tell Prolog to stop searching for alternatives once it successfully reaches  $N = 1$ .

**Sample Input:**

```
1 factorial(5, X).
```

**Sample Output:**

```
1 X=120
```

## 1.4 Task 4

Pathfinding is a core AI concept. If given a simple directed graph such as:

```
1 edge(a, b).  
2 edge(b, c).  
3 edge(c, d).  
4 edge(d, e).  
5 edge(c, e).
```

Write a predicate `find_path` that finds the path from a start node to the goal node. It should return `false` if no path exists.

**Sample Input:**

```
1 find_path(a, c, X).  
2 find_path(e, a, X)
```

**Sample Output:**

```
1 X=[a, b, c]  
2 X=false
```

## 1.5 Task 5

Simple recursive definitions of pathfinding often fail when a **undirected graph** contains “cycles” (e.g., A connects to B, and B connects back to A), causing the program to enter an infinite loop. Write a predicate `path(Start, End, Path)` that avoids cycles by keeping track of visited nodes if given a simple directed graph such as:

```
1 edge(a, b).  
2 edge(b, c).  
3 edge(c, d).  
4 edge(d, b).  
5 edge(c, e).
```

It should return `false` if no path exists.

**Sample Input:**

```
1 path(a, e, X).
```

**Sample Output:**

```
1 X=[a, b, c, e]
```