

80-BUS NEWS

NOVEMBER—DECEMBER 1982

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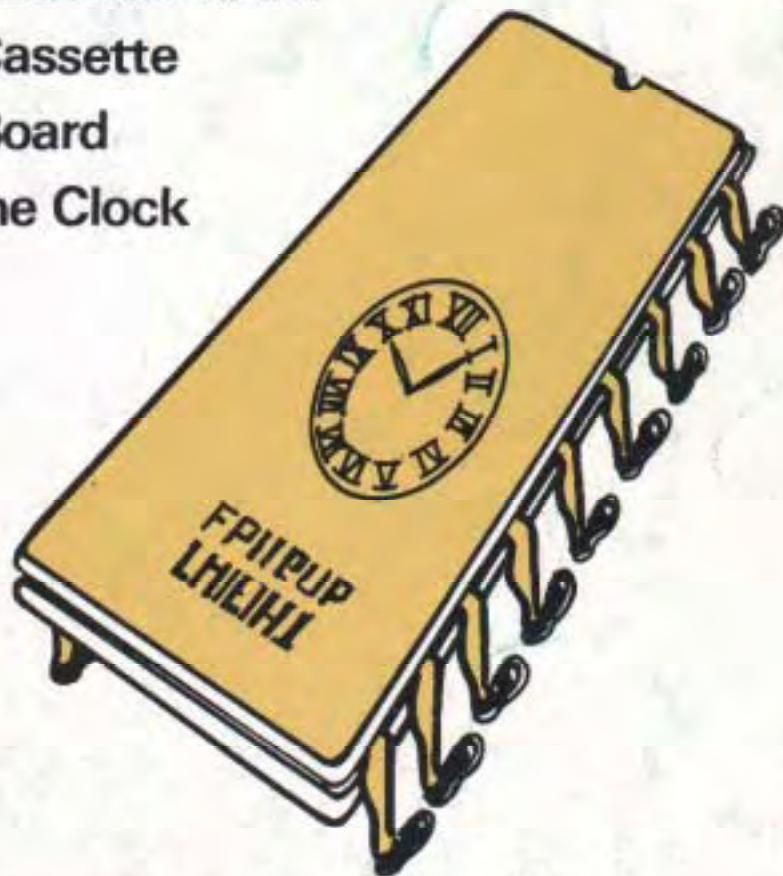
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- WHAT IS CP/M ?
- REVIEWS

Battery Backed RAM

Digital Cassette

Sound Board

Real Time Clock



The Magazine for
NASCOM & GEMINI USERS

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2. 80-BUS NEWS

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EDITORIAL

Life seems to be a constant round of exhibitions at the moment! Having only just got PCW out of the way, a couple of weeks ago it was Compec's turn. But Compec must be THE show of the year. It goes under the title of 'Trade Only', but a quick walk around reveals that this is not really the case. It is the show, however, that every manufacturer HAS to go to, and one at which many products are often seen for the first time.

When I made my first visit to Compec (in 1978) it was mainly a show for minis and mainframes, with hardly a micro to be seen. Over the last few years the balance of the show has shifted, and this year it reached the stage of being probably about 85-90% micros - a real reflection of the way in which the market has moved. With the advent of cheaper memory, cheaper mass storage, and more intelligent peripherals, the range of 64K systems with, say, 10 Megabytes of hard disk storage for less than £3000 is growing rapidly. And below the £200 mark things are moving even more rapidly.

In 1978 the Nascom 1 was not only one of the very few micros available in the UK, but at less than £200 was an absolute bargain. Now everybody and his brother is producing, or announcing, a sub-£200 and even sub-£100 micro. And yet these are totally different. Expansion is limited, and consequently the life of the product is too. Many Nascom owners have had their systems for 4 years now, and yet they have available to them, if they wish, all of the facilities of today's £200 or £3000 systems. Yes, it has cost them more to get there, but that is the cost of buying ANY electronic goods sooner rather than later.

It is the bus that makes Nascom and Gemini products so flexible. Purchase a single board computer, watch technology change, and watch your computer become out-moded by its inherent inflexibility. Buy a multiboard (or MultiBoard!) micro, and add colour, speech, floppy-disks, hard-disks, A to D or IEEE488 capability etc. as need, technology, or even finance permits. And that, in a round about sort of way, brings me back to Compec.

Nascom and Gemini were both at Compec. Nascom were showing various Nascom 3s sporting floppy-disks, AVCs and running Nas-Net. There was also a Kenilworth Computer on show, more of which in a moment. Gemini were sharing their stand with Quantum. There were two Galaxy 2s on show, one standard and one with Winchester, and three Quantums, one standard, one with Pluto, and one with Winchester. Plus another Kenilworth Computer (see on!). But a fair proportion of the stand was dedicated to showing Gemini's MultiBoard range. Gemini are now finding that, because of the flexibility of the bus, and because of the growing range of bus compatible product from themselves, and a number of other British manufacturers, that OEM sales (i.e. sales of boards to other manufacturers to use in their own 'brand named' equipment) are growing rapidly. And that is good news for everybody, as many OEMs want guarantees that the equipment will still be available in two or three years time, and that obviously means that 80-BUS must continue to grow.

And so, what is the Kenilworth Computer? Well, it is rather difficult to describe, but in the absence of a photo I will have a go. It is available in two versions, one Nascom based and one Gemini based. It is portable, weighing about 28 lbs. It contains two slimline 400K drives and a 9" screen. Starting at the bottom, the cards are mounted vertically on the left, and the drives, side by side, on the right. Above this is the screen, and above that the PSU. Total dimensions approx. (guessed) 9" wide, 13" deep and 17" high. The Nascom based version contains N2, AVC, RAM, FDC with N2 keyboard. The cheaper Gemini based version contains the GM813 CPU-RAM, GM812 IVC and GM809 FDC, with the GM827 extended keyboard. A novel looking unit and I will be watching with great interest to see how it goes. Osborne watch out!

Well, that's my bit over once again. A Merry Christmas to you all, and may Santa stumble down your chimney with a Winchester unit!

A report on the Microcode Control battery backed RAM board.B. M. Farrelly

Whilst looking for an EPROM board which I could afford, an ad. offering a 32K battery backed RAM board which would also accomodate single rail EPROMs caught my eye. It was too good a chance to miss, especially as the manufacturer was willing to supply a bare board at a reasonable cost. I wasn't sure what the battery backed RAM would be used for, but no doubt I would think of something.

A cheque was despatched, and before long the board arrived, complete with manual. Parts were ordered from a certain mail order firm, which had better remain anonymous, and after several weeks, and not a few phone calls, TWO parcels arrived. The bad news was that two deductions had also been made to my Access account, perhaps I should have bought a made up version.

For my money I got an 80-BUS compatible double sided board. It is silk screened and solder masked, and is made to a high standard. The only reservation I would have is that the supply rail tracks are a bit light, but to be fair it does not seem to be causing any problems. There were a couple of minor errors in the silk screening, but nothing serious.

The documentation was a different story though. It seems I have heard that cry before!! One useful feature is a "How it works" section, which other producers would do well to follow. Not so good were the examples of wiring the link options. They were WRONG!!!

Construction was simple enough, anyone who has built a Nascom will have no trouble here. One nice feature was that even though DIL resistor arrays were specified, extra rows of holes had been left on the board so that ordinary resistors would fit. A small saving but worth having. I also liked the idea of having all the 80-BUS lines available - even those that are not used go to holes, making mods. easier.

The board will hold 16 memory chips, which may be 6116, 2516 or a mixture of both, depending on whether RAM or EPROM is required. Battery backup is provided by an on-board PCB battery, and each memory IC may be battery backed or not using the link options, but for obvious reasons EPROMS should not use this facility. The board may be configured as one 32K, or two 16K pages, in 4K blocks. The blocks need not be consecutive, and if two pages are selected the addresses may overlap, but if so be sure not to enable them both together. Options are set by wire links. The "off the peg" board uses special, no solder, push-in connectors for this. Since I did not have any, wire wrap pins were used instead. Working out what to link to where is not too difficult so long as no notice is taken of the examples given.

Paging is different from the normal Nascom/Gemini method in that the board may be enabled on reset regardless of which page it has been set to. If this is done however the page control bit works in reverse i.e. to turn the board off the appropriate bit must be set.

One important point to note is that, although the board responds to RAMDIS it does not generate it, a shortcoming in a board which claims to support EPROMs, but I can see the problem on a board with interchangeable RAM and EPROM, of deciding whether to originate RAMDIS or respond to it. Since my system has 64K of RAM, well it doesn't yet but it will have, a RAMDIS output was essential, so a slight mod was needed. The only other problem was that the board would not run at 4MHz without waits. The makers claim 6MHz but maybe I have a slow chip somewhere. No matter, a little thought and some more surgery, and I now have an EPROM board which will also support battery backed RAM.

In conclusion if you want a low cost EPROM board you could do worse, and if you need battery backed RAM this is the board for you.

I know what that RAM will be used for. A permanent record of which programs are on what tapes, preferably automatically updated every time a program is saved. All it needs is someone to write the software!

SOUND BOARD REVIEW

by E. Cameron

Product : WT910 Sound Board
 Manufacturer : Winchester Technology
 Supplier : Amersham Computer Centre
 Documentation : Yes, one manual

The WT910 sound board is 80-BUS/Nasbus compatible (Ed.- see note below), marketed in 'bare bones' style, 'bare bones' meaning that there are enough chips to enable the programmer to produce sounds. There is an on-board amplifier and speaker as well.

Setting up

The most difficult part of getting the board to work was unscrewing the top of Sidney's case. (Yes, my computer has a name - so does every appliance in the house!) So while the top was off, I took the time to straighten the GGIDW panel (Good Grief It Doesn't Work) anyhow.

Operational/Programming

The board was constructed as a 'write only' board and occupies addresses 0000 to 000F. You have to insert a wait state in order to produce sounds - this is explained but it caused me ten minutes of (Ab) use to the GGIDW panel. Programming can be done in either BASIC, by use of Poke and Doke, or by assembler. Producing a sound involves the following sequence:

Step	Functional Block	Operation
1	Tone generator	Program tune frequencies for each channel
2	Noise generator	Program noise frequency
3	Mixers	Enable tone and/or noise on selected channel
4	Amplitude control	Program 'fixed' or envelope control on selected channels
5	Envelope generator	Program period and select envelope shape

Five easy steps, and there are three channels to play with. This is the second product from Winchester Technology that I have seen, and if the first is anything like the sound board, then they are on the right track - good manuals and excellent hardware. Also included in the basic board are spaces for the addition of the AY-3-1350 chip, along with its support circuitry. This chip extends the capabilities of the sound board and is a pre-programmed micro that plays the first 25 notes of 25 different tunes.

One last item - you can also add the Astec 1286 video/sound modulator. This will allow you to combine the computer video and WT910 sound output into one signal path. However, this is not recommended if also using their colour board, due to harmonics in the 6MHz region.

Impressions

I have never bought a 'bad' Gemini or Nascom board - yet. This board is built to the same quality as the other boards that I have. Being a confirmed DIY type, it is a pleasure to solder components onto boards that have firmly anchored PCB runs. This board does, and space to spare. Aimed at anyone needing sound effects for programming, or desiring to be a Beethoven, this is the board for you.

(Ed.'s Note - In a Nascom/Nas-Sys environment this board lives 'overlaid' on the Nas-Sys ROM, which is OK, but it is not strictly 80-BUS compatible as a complete Gemini system is purely RAM based, and therefore the fact that this board is memory mapped could lead to all sorts of complications. I also understand (regrettably) that WT are no longer trading, although your local friendly dealer may still have some boards in stock.)

Doctor Dark's Diary – Episode 13. Pascal Episode.

Well, the new batch of home brew is just about drinkable, so I had better get on with this, before the rot sets in...

Let's kick off with the "Rory is right" section. He said that P.J.Brown's new book, "Pascal from BASIC" should be Computer Book of the year, and I agree wholeheartedly. If you have been putting off learning Pascal because you didn't like the look of the text books that were available, you now have no excuse. I have found a mistake as well, however, on page 100. The equation for the addition of two complex numbers should read:-

$$(a,b) + (c,d) = (a+c, b+d)$$

but this is a minor quibble, and anyway the Pascal procedure to do the job is correct, so perhaps we were being tested to see if we were paying attention...

Free procedure number 1.

Yet another version of my favourite way of clearing the screen, which I have now implemented in four different languages, or was it five? Anyway, here is that old chestnut, the spiral screen wipe, yet again...

```
PROCEDURE spiral(col : colour);
VAR
  lox, hix, loy, hiy, i, j : integer;
BEGIN
  {Set the size of the first box to be drawn.}
  lox := 0; hix := 95; loy := 0; hiy := 44;
  REPEAT
    {Draw a box one pixel wide round the screen.}
    BEGIN
      {Line along the top of the screen.}
      FOR i := lox TO hix DO
        BEGIN
          GRAPH(col,i,loy);
          {This line gives a short delay each time it appears.
          There is no reason why it should not itself be a procedure.}
          FOR j := 1 TO 10 DO BEGIN END
        END;
      {Line down the right hand side of the screen.}
      FOR i := loy+1 TO hiy DO
        BEGIN
          GRAPH(col,hix,i);
          FOR j := 1 TO 10 DO BEGIN END
        END;
      {Line backwards across the bottom of the screen.}
      FOR i := hix-1 DOWNTO lox DO
        BEGIN
          GRAPH(col,i,hiy);
          FOR j := 1 TO 10 DO BEGIN END
        END;
      {Upwards line on the left of the screen.}
      FOR i := hiy-1 DOWNTO loy+1 DO
        BEGIN
          GRAPH(col,lox,i);
          FOR j := 1 TO 10 DO BEGIN END
        END;
```

```

{Reduce the size of the box being drawn.}
lox := lox+1;  loy := loy+1;
hix := hix-1;  hiy := hiy-1
END
UNTIL loy = hiy;
{Which means we have reached the middle, almost!
The next bit fills in the remaining blank line.}
FOR i := lox TO hix DO
BEGIN
  GRAPH(col,i,loy);
  FOR j := 1 TO 10 DO BEGIN END
END
END;
PROCEDURE spiralwipe;
BEGIN
  spiral(on);
  spiral(off)
END;

```

The procedure is called by including the word "spiralwipe" in your program, this spirals round twice. The first time round, all the pixels making up the spiral are switched on, and on the second spiral, they are switched off. Alternatively, you can use the call

```
spiral(invert);
```

which will spiral round the screen just once, inverting all the graphics characters as it goes. Once again, impress your friends...

Medium sized review of a large book.

I don't think Rory has done this one yet, although it's a mystery how he gets through so many! This is about "Microcomputer Architecture and Programming" by John F. Wakerly, which is published by Wiley. It is the last book I bought from the Computer Book Club, before I told them I had had enough of their methods. (See last vitriolic episode for the boring details...)

Anyway, as I said, this is a large book, with 692 pages. The author describes the book as being suitable for an introductory course on (micro) computer organisation and assembly language programming. Since it is so large, I have read only a few chapters so far. I do like the style, which is somewhat like a transatlantic version of P.J.Brown. Reviews are allowed to contain reasonably sized chunks from the book in question, so here is an example, from chapter 3, which is headed "Data Structures in Pascal Programs."

"Niklaus Wirth, the designer of Pascal, has written a programming textbook called "Algorithms + Data Structures = Programs". From the previous chapter, you should already have a good idea of what programs and algorithms are. To find out what data structures are, just subtract, and you don't have to read this chapter..."

The two chapters before that give a review of "fundamental concepts" and Pascal respectively. They are good, although the experienced reader will be able to skip through them pretty fast. The greater part of the book, as yet unread in detail, I have to describe by glancing at it, or reading the description at the start of the book. There are four chapters in the first, "introductory and remedial", part of the book. Part 2 describes basic principles that apply to all computers, using as examples two hypothetical processors, which just happen to have instruction sets and features that are subsets of those of the Motorola 6809 and the Zilog Z8000. I wanted to learn more about the Z8000, so I have looked ahead to the section concerned, and it seems very comprehensive, not to mention comprehensible.

Part 3 describes in detail the workings of several processors, including the 68000, the Texas 9900, the PDP-11(!), Z8000, and the Intel 8086. The last is of particular interest, as it is very similar to the 8088 used in the Pluto graphic board. (Any reader who doesn't wish he or she had a Pluto has already sold his/her soul and bought one!) This is not a cheap book, and although I like it so far, I can see that it would not suit every user's needs. If you don't want to know about Pascal, which is used throughout for examples, and think that 16 bit processors are never going to be cheap enough for you, or are happy running other people's programs, the book is definitely not for you. (And why are you reading this?) If what I have said made it sound interesting, then "Look before you buy", is my advice. I think you'll probably buy...

Tuesday's fabulous excitement.

This consisted, once again, of taking Marvin to the Taunton Computer Club, much to the astonishment of the rest of the serious members. (I am beginning to see that that club is much like this one, in that it has a great proportion of members who prefer to do nothing at all. As an example of this, at our annual general meeting, I promised to arrange a coach to the Personal Computer World Show, if enough members wanted to go. Just about everyone who was there put their hand up as a person who would go to the show. But when it came to sending in the application form on our club newsletter, it turned out that the entire membership had lost their pens! This saved me the bother of arranging a coach trip, and by the time you read this, I and the rest of the "Serious Members" will have probably been and seen the show anyway.) In the meantime, I had a great time, showing the younger members of the club that I was still one step ahead of even the most brilliant BASIC programmers amongst them. If you rush through a Pascal program or two, even the most remarkable youthful genius types can be impressed, so long as they only know BASIC. The trouble is, they will probably all go out and buy "Pascal from BASIC", and then I will have to learn something else in a hurry. In emergencies, I use little snippets of number theory from Hofstadter's book to subdue these youthful upstarts. It is for their own good, of course. If they realised how clever they actually are, they would become so unbearable that they would have to be beaten up...

Mispnirt of the Year (so far).

I nominate Personal Computer World's September issue, page 274. The I.B.S. Ltd advertisement offers readers the opportunity to purchase "6/12 Slut Mother Boards". Entries on a pound note, please, and note that any entry involving "Band rates" will be disqualified instantly, as will anyone who mentions any of my errors.

How to Win £5000.

See the same issue of Personal Computer World for details of a competition with a prize of the size mentioned above. The first part of the competition requires you to find a mystery number, subject to the following conditions. The number required is the lowest palindromic number (in other words, it reads the same forwards and backwards) which, if you square it and subtract a million, gives a result which contains at least one of each of the digits 0 to 9. Well, that is at least a ten digit result, you are saying, and that means it is not easy to write a program to solve it. The simple fact is that few machines can handle numbers of that sort of size easily. Scores of you may write and tell me if I'm wrong, but I don't think Nascom ROM BASIC can operate on numbers of that order, unless one or more of the recently available extension BASICs can do the job.

So, how have I solved part one of the puzzle? (I have, honestly!) I wrote a program in Hisoft Pascal 4, which generated each palindromic number in ascending order, and then tested them to see if they met the conditions. The program used the following declarations to set up a data structure capable of holding the big numbers.

```

TYPE
  DIGIT = 0..9;
  NUMBER = ARRAY [1..6] OF DIGIT;
  BIGNUMBER = ARRAY [1..12] OF DIGIT;
VAR
  STARTAT, VALUE : NUMBER;
  RESULT : BIGNUMBER;

```

The rest of the program consists mainly of routines which manipulate the arrays of digits, which could be of any length, if you wanted enormous accuracy. One procedure puts the square of VALUE into RESULT, another knocks a million off, and so on. Of course, there is no room to print the whole program here. When run, it took seven minutes to come up with the answer, which I am not going to tell you, as that would not help you to improve your programming skills. A more recent revision of the same program, which generates its palindromic numbers a faster way, gives the six suitable numbers less than a million in just under ten minutes, and could be made to go even faster, if I could be bothered to do it, simply by changing the routine that squares the number to take advantage of the symmetry of the number. The most important thing, I think, to come out of this, unless I get the £5000 at the end of it all, is the realisation that the people who used to annoy me by going on about "Problem Solving" with Pascal were right. All except one...

Great Stupid Remarks of the Twentieth Century.

In a recent edition (16/8/82) of Datalink, Margaret Park writes:- "Edsger Djikstra the programming guru credited with the invention of structured programming, damned the language completely by saying that programmers who had started on Basic (sic) were unteachable. "As potential programmers," he said, "they are mentally mutilated beyond hope of regeneration."

It is important to realise that these people who are "credited" with inventing this, that, or indeed the other, have hardly ever done so. If you think Arthur C. Clarke really invented the communication satellite, you need your head looked at. And if Marshall McLuhan was right, I can send in a blank tape, instead of going to all the bother of writing this article at all, on the grounds that "the medium is the message". All these "gurus" can do is make a nice after dinner speech. They each select a theme, and choose a set of suitably far-out, trendy things to say, and make a fortune for themselves on what Douglas Adams has rightly identified as the "Chat Show Circuit". Structured programming is a method of programming that is independant of the programming language in use. You can write structured programs in zarking machine code. You can write them in BASIC, and it may even be possible to write them in Pilot. You may have had a Nascom 1 when there was no BASIC available for it, and have written structured programs for that, too. And along comes this guy Djockstrap, and tells you that your brain is too curdled for you to learn any new language, ever, no matter how you try. Well, I wonder what language Djikstra actually learned to program in, 'cos he looks very old in the photograph in Datalink. It was almost certainly Fortran. Nascom guru Doctor Dark, inventor of the Hyperspace Beer-Drive writes, "Wow, he was lucky he didn't learn Cobol first. That makes your w***y drop off..."

What is wrong with Pascal? (Shock Horror!)

Honestly, there really is one thing missing from Pascal, and it just happens that this is the one thing BASIC is better at than almost anything else (that takes care of the ones I don't know! PIC X(12), indeed!) String handling is easy in Pascal, as long as all the strings are the same length! You can not use things like

```
A$ = LEFT$(B$,4) + MID$(A$,3,3) + " Wowee!"
```

even if you want to. But of course, you can define a set of procedures and functions that would make this sort of thing possible. I have started work on just such a set of procedures, and have made a little progress, some of it in the right direction...

It is necessary to learn how to use the "dynamic variables" of Pascal, as the other way of approaching the problem, using a huge array of characters, while probably faster, takes up memory all the time. That defeats one of the objects, so the dynamic approach it is. The things BASIC can do to its string variables include setting them to "empty", concatenation, and the ever useful LEFT\$, MID\$ and RIGHT\$. Also useful are the ability to type into a string from the keyboard, and to print strings out. Some sort of clue as to how difficult such things are to program in Pascal can be gained from P. J. Brown's remarks on the matter, when his exponent of structured programming, Professor Primple remarks, "My program to analyse English sentences works well, but there is a small restriction that all sentences must contain ten words and each word must be of five letters."

The stuff I have written so far starts out with these declarations:-

```
CONST
  longeststring = 256; {Can be more, or less.}
  longestname = 8; {Length of stringnames.}

TYPE
  stringname = PACKED ARRAY [1..longestname] OF CHAR;
  stringlength = 0..longeststring;
  stringcontents = PACKED ARRAY [1..longeststring] OF CHAR;
  stringitem =
    RECORD
      name      : stringname;
      length    : stringlength;
      contents  : stringcontents;
      next      : ^stringitem
    END;
  stringpointer = ^stringitem
```

In most versions of Pascal, "stringpointer" would have been declared before "stringitem", and "next" would be of type stringpointer. The Hisoft version won't let you use the slight forward declaration involved, but this is not a handicap, as it is easily avoided, as shown. Anyway, the declarations above show the sort of data structure I am trying to use in my string handling routines. Whenever a new string is needed, the program includes a NEW(soandso), where the "soandso" is the name of a pointer. Space is then allocated by the run time routines for another record of the type shown above. It may prove to be unnecessary to write the system after all, since an Apple owner I know has suggested that the UCSD string handling routines might work. I'll let you know if they do... And now a rest, while I try to beat my score of 232 at Adventure. How DO you get past the Plover Room, without falling down a pit?

Interfacing the EPSON MX80.

by Big H

The following article(s) if this prose is worthy of print, will attempt to describe the ins and outs (ups and downs) of getting that very expensive printer PRINTING. Although specific references apply to the MX80 type III, much is applicable to the whole MX-range. Since the interface is a standard 'Centronics type', the general principle applies to any number of printers. I refuse to class that race of tanks dressed up as printers (you know... 5 bit code etc.) as printers. By the way, does any one want a slightly footmarked Creed 444? Advertising over - Included will be notes on how to patch into NAS-PEN, NAS-DIS and ZEAP (if it isn't already obvious) and a listing of a fairly comprehensive relocatable routine to set up and drive the printer through the on board PIO. Later on for those with the MX80 types II or III (and a larger overdraft than everyone else), use of the HI-RES graphic facilities is described. These can be used to define your own characters and with suitable software.... produce a dot for dot dump of the Nascom screen. Do I hear cries of 'Cor - What a cop out'? Well you can take it all back because a listing of such a program will be given. With luck, it will not only provide a simple screen dump but also true/inverted and half/normal/double width images of any defined screen window. (This guy is just unbelievable! - Ed.)

Epson Interface.

But first the basic printer interface and its driving software. The rightmost columns of Table 1 show the pin connections of the Epson interface. All signals are (naturally) TTL compatible. Synchronisation is achieved by the STROBE signal and handshaking provided by either ACKNLG or BUSY. I have chosen to use the BUSY line, but for no particular reason. Data transfer is achieved by waiting for the printer to be 'NOT BUSY', applying the data, waiting for it to stabilise and then asserting STROBE for a minimum of 0.5 microsec. Apart from ACKNLG, the only other signals (on the printer I/F) not used are SLCT IN and SLCT. The function of these (to select the printer/tell you it is selected respectively) was disabled using the Epson's internal DIL switches. This is OK as I don't see me operating a bank of MX's from my Nascom - not this year at least!

DIL Switches.

The internal DIL switches definitely deserve a mention as they allow you to set up many of the programmable functions immediately on power up. Things like character size, form length, line spacing and even whether or not your zero has a slash across it can all be set.

The Electric String.

The assignment of the PIO ports is shown by diagram 1 and the actual connections made by the cable is shown by the middle columns of table 1. The Epson manual tells you to use twisted pair cable and the return earth signals. Twisted cable is not easy to get hold of and shouldn't be necessary so long as the

cable doesn't trail up stairs to the back room. Admittedly, my cable is only a couple of feet long but it was all I could find when the printer arrived.

EPRINT Listing.

The commented listing of EPRINT should be relatively simple to follow but I shall explain some areas such as setting up the PIO and printer. EPRINT by the way stands for Epson Printout Ready In No Time or alternatively Extra Playing Round In Nascom Trauma.

NAS-PEN, ZEAP etc.

When executed, the first questions asked involve what software you want to run the printer with. Dependent on the replies, the vectors held in RAM for the ZEAP and NAS-PEN output routines may be set to DUTCHA, the character output routine. Unfortunately NAS-DIS has no RAM vector and so can only use the printer (as with BASIC) by setting DUTCHA as the user output routine. Needless to say, NAS-PEN or ZEAP must be initialised before executing EPRINT or they will just overwrite the vectors when 'cold started'. If ZEAP is selected, then the printer AUTO FEED EXT line will have to be disabled. This is because while the ZEAP sends a CR and LF, the printer will automatically do a LF on reception of the CR. Hence two LF's and double line spacing, very nice but paper is expensive. NAS-PEN, and software using the user output routine will only send a CR and so AUTO FEED EXT is left low unless ZEAP is selected. A value stored in D is used to set this line later on.

Setting Printer Status.

Several questions are asked relating to the way you require the printer to be configured. Many more variations could be catered for (column width, print size etc.) but it becomes tedious setting too many whenever you switch on or start using some different software. You will usually configure the printer the same way and anyway codes can be embedded in the text to set anything else.

As mentioned above AUTO FEED EXT is controlled by the level of that line, all the other features are set by sending control codes to the printer. Before any codes are sent to the printer, it is reset by holding INIT low for longer than 60 microseconds. There is no need to compensate for CPU clock speeds (2/4 MHz. etc.) as all timing is done assuming a 4MHz. clock and all delays may be exceeded without effect.

The length of page is set by ESC C nn (nn is a hex. value 0<nn<127.).

The paper end detector is set on by ESC 9 or off by ESC 8. This stops the buzzer going off while using single sheets which is annoying because it is LOUD and buzzes for ages.

The printer is told to skip over the perforation at the end of each page by ESC E 6. The 6 tells it to skip 6 lines which with normal spacing is one inch. Note that the DIL switches have been left to cause the printer to initialise in the NO SKIP condition.

Having set all these conditions, the printer status is tested and suitable messages output to the screen.

SETUP has been written as a subroutine so that it may be used by other programs such as the screen dump to be described later. There is one other section of code that probably warrants explanation, setting up the PIO which is described below.

Configuring the PIO.

In keeping with explaining setting up the printer before explaining setting the PIO, I have configured PORT B first and will explain it last. Confused?

PORT A:

This is set up in bit (control) mode with all the bits as outputs. In order, the bytes sent to PACONT to do this are: fFF;0;7;3. fFF selects mode 3 (control mode) and the following 0 makes all the bits outputs. The 7 is the interrupt control word which is set to prevent any interrupts. The final 3 disables all interrupts on PORT A just to be sure.

PORT B:

This is identical to the configuring of PORT A except for the second byte. This is fF8 (1111 1000) because we require bits 0,1 and 2 to be outputs and bits 3,4 and 5 to be inputs. We don't care about 6 and 7 and so could have sent f38 etc.

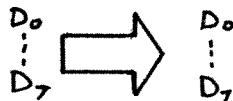
The next installment.

The screen dump program will have to wait until next time, while I think of some suitable abbreviated names for it. I hope all this is of interest to someone and maybe even useful. In this extremely unlikely event I would be glad to supply a cassette of the ZEAP source to those too busy (lazy) to type it all in. A cheque for £1-50 (to cover costs) to COMPWARE at 57 Repton Dr. Haslington Crewe Cheshire CW1 1SA will secure this.

DIAGRAM 1 : SCHEMATIC SUMMARY OF CONNECTIONS.

NASCOM PIO

PORT A



PORT B

NOT USED:

+5v, ASTB, ARDY,
BSTB, BRDY

D₀ → STROBE

D₁ → INIT

D₂ → AUTO FEED EXT

D₃ ← BUSY

D₄ ← PE

D₅ ← ERROR

D₆

D₇

NOT USED:

10 ACKNLS

13 SLCT

36 SLCT IN

35 +5v PULL UP

0v (16,18) ————— 0v (19-30,16,33)

Table 1: Nascom 2 PIO / Epson MX80 connections.	
PIO	CABLE
	EPSON
1 B5	32 STROBE
2 B4	12 PE
3 B6	-
4 B3	4 BUSY
5 B7	-
6 B2	6 AUTO FEED EXT
7 ARDY	-
8 B1	8 INIT
9 BSTB	-
10 BO	10 STROBE
11 BSTB	-
12 BRDY	-
13 AO	A0 13
14 NC	-
15 A1	A1 15
16 Ov	Ov 16
17 A2	A2 17
18 Ov	Ov 18
19 A3	A3 19
20 +5v	-
21 A4	A4 21
22 +5v	-
23 A5	A5 23
24 A7	A7 24
25 Ab	Ab 25
26 NC	-
	1 (Twisted earth returns)
	30 /earth returns)
	31 INIT
	32 ERROR
	33 OV
	34 NC
	35 +5v Pull up
	36 STCT IN
	18 CHASSIS-GND
	19 NC
	20 -
	21 -
	22 -
	23 -
	24 -
	25 -
	26 -

206F7645
72207065
72666572
6174596F

74656374
6F72206F

6E3F20 0590 DEFBO
RCAL YESNO
POP HL
POP DE
ADD A,"Y
LD E,A
PUSH DE
PUSH HL
JR PENULQ
0680 ; GET Y/N ANSWER
0690 ;
0700 ;
0710 YESNO SCAL BLINK
0720 NC,YESNO
0730 "Y
0740 JR Z,ANSOK
0750 CP "N
0760 JR Z,ANSOK
0770 JR YESNO
0780 ; ANSOK RST ROUT
0800 PUSH AF
0810 LD A,CR
0820 RST ROUT
0830 POP AF
0840 SUB "Y
0850 RET
0860 ;
0870 ; DUMCAL JR YESNO
0890 ;
0900 ;
0910 ;
0920 PENULQ RST PRS
DEFM /What page length (HEX.)? /
0930
20706167
65206C65
6E677468
202B4B45
582E293F
20
0940 DEFBO CR,O
SCAL INLIN
SCAL NUM
JR C,PENULQ
LD HL,(NUMV)
LD C,L
LD B,"B
POP HL
POP DE
PUSH BC
PUSH DE
PUSH HL
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74R25 ;
74S25 ;
74T25 ;
74U25 ;
74V25 ;<

```

811C 3E07 1640 LD A,7 OUT (PACONT),A 2150 ; 60 mic. sec. DELAY
811E D305 1650 LD A,3 OUT (PACONT),A 2160
8120 3E03 1660 OUT 2170
8122 D306 1670 ; 2180 DEL60 LD B,17
1680 ; 2190 LOOP DJNZ LOOP
1690 ; 2200 RET

8124 3E1B 1700 LD A,ESC ; Set form length using
                           ; value stored in C
                           ; \Save character
8126 D777 1710 RCAL OUTCHA 2210 ; PRINTER DRIVER ROUTINE
8128 3E43 1720 LD A,C
                           ; \Wait 'till printer
812A D773 1730 RCAL OUTCHA 2220 ; BUSY line is low
812C C1 1740 POP BC
                           ; \Restore character
812D 79 1750 LD A,C
                           ; \Apply to data lines
812E D76F 1760 RCAL OUTCHA 2230 ; Pause to stabilise
8130 3E1B 1770 LD A,ESC ; \Set paper end detector
                           ; on/off according to the
                           ; value stored in B
8132 D76B 1780 RCAL OUTCHA 2240 ; \Keep port B status
8134 7B 1800 LD A,B
                           ; \Reset STROBE (BO)
8135 D768 1810 RCAL OUTCHA 2250 OUT (PBDATA),A
8137 7B 1820 ; NOP
8138 FE4E 1830 LD A,E ; \Set skip/no skip
                           ; according to the value
                           ; stored in E
813B 280C 1840 CP "N" 2260 OUT (PBDATA),A
813C 3E1B 1850 JR Z,NOSKIP 2270 IN A,(PBDATA)
813E D75F 1860 LD A,ESC
8140 3E4E 1870 RCAL OUTCHA 2280 RET
8142 D75B 1880 LD A,"N"
8144 3E06 1890 RCAL OUTCHA 2290
8146 D757 1900 LD A,6
                           ; \Skip 6 lines
8148 DB05 1920 ; 2300 -----
                           ; \Labels ETC. :
814A CB67 1930 NOSKIP IN A,(PBDATA) 2420
                           ; \Get printer status
814C 2B13 1940 BIT 4,A 2440
                           ; \Paper OK if B4 low
814E EF 1950 JR Z,PAOK 2450 PRS EQU £2B ; NAS-SYS Print string, RST
814F 5072696E 1960 RST PRS 2460 PRT EQU £30 ; O/P A to screen,
814F 74557220 1970 DEFN /Printer out of paper./ 2470 BLINK EQU £7B ; blink for I/P, SCAL
816A EF 2010 RST PRS 2480 INLIN EQU £63 ; input a line,
816B 5072696E 2020 DEFN /Printer in error status./ 2490 NUM EQU £64 ; get line value,
8170 655772 2050 ; 2500 MRET EQU £5B ; monitor return,
8172 2E 1980 DEF8 CR,0 2510 ;
                           ; Store for val from NUM
8164 0D00 1990 PAOK BIT 5,A 2520 NUMV EQU £C21
                           ; \No error if B5 low
8166 CB6F 2000 JR NZ,NOERR 2530 USROUT EQU £C78 ; vectored jump to USROUT
8168 201E 2000 ; 2540 ZEPAD EQU £F05 ; ZEPAD vector to printer
816A EF 2010 RST PRS 2550 PENADD EQU £101E ; NAS-PEN vector to printer
816B 5072696E 2020 DEFN /Printer in error status./ 2560
8172 6557720 2050 ; 2570 ; PIO PORT ADDRESSES:
8174 695E2045 2070 DDEL60 JR DEL60 2580
8176 72726F72 2080 ; 2590 ; ASCII CODES:
8178 207461 2090 ; 2600 PACONT EQU 6 ; Port A control
817A 7475732E 2030 DEF8 CR,0 2610 PADATA EQU 4 ; " A data
8180 0D00 2040 RET 2620 PBCONT EQU 7 ; " B control
8182 C9 2050 ; 2630 PBDATA EQU 5 ; " B data
8184 0D00 2110 NOERR RST PRS 2640
8186 1812 2070 DDEL60 JR DEL60 2650
8188 EF 2090 ; 2660 ; ASCII CODES:
8189 5072696E 2110 DEF8 CR,0 2670
                           ; Dummy call point
                           ; for delay routine
8190 74557220 2100 NOERR RST PRS 2680 CR EQU £D ; Carriage return
8192 72656164 2120 DEF8 CR,0 2690 ESC EQU £1B ; Escape
8194 C9 2130
8196 2140 ;

```

This question is often asked when the purchase of new computer systems is considered. What advantages has CP/M got to offer, is it very complicated, even what does CP/M stand for? In many ways all these questions may be answered glibly by saying that these things are not seen by the user, and therefore the user need not concern himself with them. However, this answer is not entirely true, as the choice of computer operating system is of great importance when it comes to system support and choice of available software.

CP/M stands for Control Program for Microcomputers, and the original version was designed in the late 1970's by Digital Research Inc., to allow a standard form of interchange between one computer system and another. CP/M as such has been a story of growing success, and has been progressively improved with time. What it is, is a standard control program which takes over the computer disk system and the way in which the computer talks to the outside world, through the keyboard, display monitor, printer, etc. This offers one great advantage, in that a program written obeying the CP/M rules on one type of machine will be entirely compatible when run on another type of machine. This of course opens up the availability of software to a far wider market leading to greater choice and lower prices.

In use CP/M is a fairly simple concept, and only has five straight forward commands. These are at the system level and are rarely used by computer operators concerned with business systems, who are primarily concerned with the operation of a program, stock control, financial, etc. The program is working under CP/M, where CP/M is the controlling executive handling the transfer of data and programs to and from the disks, and handling the communication of the program through the keyboard, printer and display monitor. In this respect, CP/M is transparent to the user, and it is the program in use which appears to be in control. At the system development level, where the user is concerned with the design and development of programs, CP/M offers a number of useful utilities giving access to the computer at the machine program level. Most of the CP/M utilities are useful to the machine programmer, except the context editor utility (ED.COM) which is awkward and inconvenient to use. This utility is easily replaced with others of considerably greater usefulness.

CP/M has had much adverse comment unfairly levelled at it. Unfair because the criticism has been concerned with the CP/M input and output facilities, which are not the concern of CP/M, but of the manufacturer of the machine fitted with CP/M. This has come about because, whilst CP/M itself is standardized, the machines to which it is fitted vary widely. To allow CP/M to be adapted to any machine, the machine manufacturer has to write an interface program between CP/M and the machine, this is known as the Basic Input/Output System, or BIOS. It is in this area where criticism is called for, many machine BIOSes are simplistic indeed, and lead to what can only be described as unfriendly operation, giving only simple error messages and the minimum of help. It is rare to find a CP/M machine with useful and friendly performance through the BIOS, although such machines exist, the Gemini range being a shining example.

So what has CP/M got to offer, this may be summed up in one word, compatibility! As mentioned above a program written using the CP/M rules can be run on almost any CP/M based machine. The word 'almost' was used advisedly as the Tandy range of computers have adapted CP/M for their own purposes and in the process made their implementation of CP/M incompatible with all other CP/M machines, a self defeating sales gimmick to ensure that software for their machines can only be purchased through themselves, thereby limiting choice and competition. Having said that CP/M programs are compatible, which is true, there are of course some incompatibilities, usually mechanical. The most obvious is the

mechanical incompatibility between 8" and 5.25" disks. Further, unfortunately, there is lack of standardization between the various 5.25" disk systems themselves. Usually these varying standards have been chosen with care for very valid technical reasons concerned with available disk space. However, it does mean that whilst the programs are compatible, the disks on which programs and data are stored may not be directly transferable from one machine to another.

On the brighter side, these various disk standards do not present much of a problem to software suppliers who are capable of supplying software in almost any disk standard. However, an obscure standard, in an unpopular format is less likely to be attractive to a software supplier, meaning investment in copying software is likely to show a lesser return for the effort involved compared with the popular formats, suggesting that the prices for software in unpopular formats are likely to be a little higher than those in the more popular formats. But usually software houses offset the higher cost of unpopular formats against the more popular formats, and charge a standard price for a given piece of software.

Likewise differing formats do not usually present a problem to end users except where several different CP/M based machines are in use in one situation. In this instance, the machine supplier is often in a position to supply the necessary interchange software and hardware to allow the various machines to be interconnected. In this way only one set of software need be purchased for several machines, assuming the software licences allow multiple copies to be made.

To sum up then, CP/M itself remains transparent to the user, being solely concerned with the efficient handling of the transfer of data and programs to and from the disks. The BIOS handles all the communications with the outside world, which it does to a greater or lesser degree of effectiveness depending upon the ability of the manufacturer of the machine in question. (The effectiveness of the BIOS is a good guide to the quality of support that may be expected from a manufacturer.) The main benefit is the vast choice of standard software available at reasonable prices, brought about by the compatibility that CP/M has introduced throughout the small business system and system development markets.

CLASSIFIED ADS.

Nascom 1 cased, PSU, Cottis Blandford cassette, Stuart colour board, Smart 1 buffer/32K RAM (with memory plague - no instruments/knowledge to fix). £170 ONO. Phone 0382-67896

Nascom 2 cased with 48K, Nas-Sys 3 and graphics. Imp printer, Hobbit digital cassette system. Zeap, Nas-Dis, Debug, Sargon chess. Many games, spare cassettes, books, magazines, manuals. Family circumstances force sale at £590.
Tel. Keith Brown, Colchester (0206) 841295

Teletype KSR 33. RS232 i/f fitted. Can be seen working on Nascom 2. Excellent condition. £50. Keyboard with 80 good quality keys and case. £6.
Tel. Crowthorne 6894.

REVIEW OF HS1NA. J. Perkins

INTRODUCTION

A number of storage systems have appeared recently based around the Philips Mini Digital Cassette Recorder (DCR). Priced at less than half the cost of a floppy disk system, they are intended as a cheap(er) alternative to floppies if you want high-speed mass storage.

At the time of writing, there are three such systems available for the Nascom: the 'Hobbit' system at £99+VAT, the Grange Electronics 'CFS' at £170+, and the MicroSpares 'HS1N' system, at £199+ for a single drive system, and £279+ for a double drive system. This is a review of the HS1N double-drive system.

WHAT YOU GET

I ordered this system last summer (1981) after reading an article on it by the designers in PCW (it was also advertised in PCW), and I sat back and waited for it to come. I waited, and waited, and waited... finally, FOUR MONTHS later, it arrived (now where have I heard that before??) courtesy of the GPO. When I unpacked it, this is what I found:

- Two mini DCR's
- One 'NASBUS Compatible' controller card
- Two leads to connect the drives to the controller card.
- Firmware in two 2708's
- Two 4118's for workspace
- One mini-cassette
- One manual

One of the connecting leads was twice the length of the other, and was wired up wrong! Luckily no damage resulted from this. The lack of a 77 way edge connector is to be deplored, as some would consider this essential to connecting the controller card to the bus. Rather than wait weeks for them to send me one (or for them to tell me where to go) I got one from my local Nascom dealer.

HARDWARE

The controller card is an 8"x8" double-sided through-plated fibreglass board, which is just roller-tinned. It would have made a more professional finish if it had been solder masked and silk-screened as well. The board is supposedly 'NASBUS Compatible' and seems to conform to the spec. in all but one aspect: the DMA daisy-chain link had been omitted. At first I thought that this was a design/assembly oversight, but I have since realised that this is to enable enterpid users to fit the DMA chip on the prototyping area of the board, enabling files to be loaded under DMA control... with suitable software, of course. This, of course, wasn't mentioned in the manual (more of which later). The lack of a link won't worry those 99.9% of users who'll never use DMA, and anyway it is the simplest of tasks to add a link should you need it.

All chips on the board are socketed, but none (yes, NONE!!!) are marked on the board. This must give headaches to the poor guy who has to assemble the thing, not to mention anyone who encounters problems, as the circuit diagram supplied is appalling! The controller circuitry occupies about two-thirds of the board, the rest being a prototyping area.

The board I received was very much an 'Issue 1' board, with quite a few wire links and broken tracks on it. Some of these links had fallen off when I unpacked the board (due, no doubt, to the solder joints being cut too close to the board) and a bit of detective work was needed to put things right. Just to

confuse the unwary, the documentation gives the clear impression that the /NASIO circuitry must be added by the user, and the manual goes on to suggest a method of implementing this (using extra chips, of course). To really confuse matters, the actual circuitry used (it IS supplied) lives on the prototyping area and uses a completely different circuit to that suggested!! The DBDR circuitry (for Nascom-1 owners) also lives on the prototyping area.

The circuit itself uses the Z80-SIO to provide the necessary parallel to serial conversion. TTL and CMOS logic provide the phase-encoding and the interface to the drives. The system uses phase-encoding to store bits of information on the tape. Briefly, this entails a change of flux on the tape representing a 1 or a 0, depending on whether this happens on a positive or negative-going clock edge. This ensures that the tape magnetisation changes at least once every clock cycle. Having seen the source listing of the CFS system (which uses the PIO) I must say I think that using the SIO was the best approach, since it avoids the machinations required to generate the serial data stream, generate checksums, sync. characters, etc., and this is reflected in the command set available, which is certainly much more extensive than that on CFS (more about the software later). It also allows an easy upgrade to DMA.

The data rate used is 6000 bits per second, which, because no start/stop bits are used, is the equivalent of 7500 bps (e.g. using CUTS, if you could get it to work that fast!). Data is recorded in blocks of 2K bytes, and the catalogue, which is at the start of the tape, also uses a 2K block. This gives a capacity of 56K bytes per side, excluding the directory. Any data less than 2K in length uses a 'padded out' block. Each data block consists of sync. characters (which serve not only to indicate the start of a block but also to synchronise the read electronics), the load address, a length word, the data stream itself, followed by the CRC characters. Thus, say, a 10 byte 'file' can be loaded without the other 2038 bytes 'above' it in RAM being corrupted.

The hardware falls down in one very important point: whereas the drive buffers use ports £F8-£FB, the SIO uses ports £FC-£FF. This is bad news indeed to those using page mode on their RAM/ROM cards, since the page mode circuitry also uses port £FF (and port £FE on the MAP 256K RAM and Gemini GM813 CPU-I/O-64K RAM boards). Use TOS, and you'll inevitably 'load' a file into ROM. Switch a RAM card back into the system & you'll be reprogramming the SIO!!! The solution is to reconfigure the SIO at a different I/O address (and change the software to suit). The port decoding is hard-wired, but luckily there are a couple of unused inverters on the board, so it is just a matter of breaking a track or two and inverting an address line to reconfigure the port decoding. This is something I have yet to do (spot the RAM-A user!). Neither are the address/data lines buffered on the card: some of the lines have several LS-TTL loads attached to them. Buffering would then make it easier (neater) to mount the 2708s/4118s on the card if your Nascom (& RAM-A) card are already chock full of ZEAP, NASDIS, DEBUG, NASPEN, etc., or has been reconfigured for 2716/6116's.

The drives themselves (of which no information is supplied) are very compact, being about 4" cubed in size. They require a 12 volt power supply, which in this case is drawn from the NASBUS. The manual says that if more than 800mA is already being drawn from the 12V line, then an extra power supply may be needed. The cassettes are very small, being the same type as those used in 'Dictaphone' machines, only the ones used are certified free from drop-outs, which they do indeed seem to be (unlike 'computer quality' C10 audio cassettes). This means that Read/Write errors are definitely a thing of the past! Uncertified cassettes may also be used, but on your own head be it!

SOFTWARE

The operating software (called 'TOS' - Tape Operating System) occupies 2K bytes and is supplied in two 2708 EPROMS. It resides at location £D000, and uses 2K bytes of workspace, which 'sits' on top of TOS at £D800. Two 4118s are

supplied for this. This prevents BASIC from overwriting TOS's workspace when cold-started. TOS overlays ROM ZEAP, but it is a simple matter to install a switch in the 4K decode line (on the N2) to switch between the two. I of course encountered difficulty in this task owing to Blocks A & B on the N2 card being in different places to that documented (i.e. for block A read block B, and vice versa).

The TOS command structure is fairly extensive, with commands being entered in the true NASSYS fashion, i.e. a single command letter followed by a number of arguments. In TOS these arguments are obligatory and are summarised below.

```
B d     Save BASIC file on drive d
C d     Display catalogue of drive d
D d nn Delete file number nn from drive d
I      Initialise a blank tape in drive A
J      BASIC cold start
N      NASSYS cold start
P d     Save NASPEN file on drive d
Q      NASPEN warm start
R      Rewind both tapes, read in catalogues
R d nn Read file nn from drive d
T d nn Transfer file nn from drive d to the other drive
W d ssss eeee Write file from fssss to feeee-1 to drive d
X      Rewind both tapes prior to removal
Z      BASIC warm start
```

I understand that the latest version of TOS has a multiple-delete command, which presumably is of the form D d nn xx yy .. which would delete file numbers nn, xx, yy, etc. from the tape in drive d. I have made alterations to TOS to include the following (extra) commands:

```
E xxxx - Execute program at address xxxx. Additional arguments
        may be supplied, as with the NASSYS 'E' command.
R d     - Rewind the tape & read the catalogue of the specified
        drive (TOS only does this for both drives at once).
X d     - Rewind the specified tape to the start prior to removal.
Y      - BASIC warm start.
Z d     - Save ZEAP file on the specified drive.
```

When saving a file, TOS prompts for a filename, which may be upto 17 characters long. This gives ample room for, say, the version number and, in the case of machine code files, the execution address. With the Write command TOS also prompts for a single-character filetype (BASIC & NASPEN default to B and P respectively). No check is made to see if there is already a file of the name you have specified. Each file is assigned a file number, and this number is used to access the file. This reduces the chance of typing errors, which is quite possible if one had to type in 17-character filenames each time. It does mean, however, that when loading a file under program control (i.e. from another program, e.g. loading a data file into RAM) that the file number be specified. While (short) routines are given in the manual for saving a (named) file & loading a (numbered) file under program control, no routine is given for loading a named file. When you consider that the Delete command can cause the assigned filenumbers to change, this is a serious drawback. No source listing is supplied, but having disassembled the software, writing such a routine shouldn't be too difficult.

There were a couple of bugs in TOS, which interfere with the operation of the 'I' command, in which the blank catalogue written to the tape isn't really blank. If any other reader has found this problem, there are a couple of bytes to

change. Since this bug may also be present in other versions (with different addresses) the code which should be changed is just after the prompt for the tape number and the three SCALs to process the answer and get it into HL. The code should read:

E5	PUSH HL
CDFADO	CALL £DOFA ; REWIND TAPE
21ADD7	LD HL,£D7AD
012700	LD BC,£0027 ; ** WAS £23 **
1152DB	LD DE,£DB52
EDBO	LDIR ; WRITE NULL CATALOGUE
2158DB	LD HL,£DB58
2231DB	LD (£DB31),HL ; SAVE CAT. START
212100	LD HL,£21 ; LENGTH ** WAS £1D **
2233DB	LD (£DB33),HL ; SAVE LENGTH

Another undesirable feature (alright then, a bug) in TOS occurs if any errors occur when using TOS under program control. Since errors can occur at several 'depths' in TOS (e.g. an error in the number of arguments, no tape present, a read/write error, etc.) there could be problems in knowing how many return addresses should be 'thrown away' so that TOS can do a quick exit. TOS gets round this the easy way by warm-starting itself whenever errors occur. No problem when using TOS normally (i.e. from the keyboard) but when using TOS under program control, it means that control remains in TOS. No way to get back to your program. You can't just type "W" or "R" (Write or Read) because the arguments are obligatory. You can't return to NASSYS to see what they are because 'N' cold-starts NASSYS, and this resets the workspace. Unless you have designed your program carefully, you have lost all the data your program just spent a long time building. It would be far better to return, say, to the outer level of the Read/Write routines or whatever, and then return to the caller if an error is detected. The latest versions of TOS have a 'Vectored Error handling function' which I presume means that control is passed through a location in RAM to a (user) error routine.

The Write command (and B & P) automatically verifies each block after it has been written by rewinding to the start of the block and then 'reading' the block (but not loading it into RAM) and checking the CRC character at the end. If an error occurs, the block is rewritten, and if the error persists, the command is aborted & an error message is displayed. A drawback is that the catalogue will still contain an 'entry' for the erroneous file, which will have to be deleted.

The I command is used to initialise a tape, and all it does is write a blank directory to the start of the tape. TOS automatically checks to see whether the tape has already been initialised, and displays an error message if it has. No command has been provided to delete the catalogue (e.g. so that it may be reinitialised with another tape number). This is deliberate, as it avoids the accidental 'erasure' of a whole side. It can be done, however, by outputting the relevant commands to the ports, and this method is given in the manual. TOS also remembers where it is on a tape, so when reading more than one file off a tape, there is no need to read in the catalogue both times (or even the once). TOS cannot, however detect if a tape has been removed & replaced with another one. Thus the 'R' command (no arguments) is best used immediately after inserting a cassette.

TOS is written for Nascom systems using NASSYS monitors (sorry, all those NASBUG fans) and automatically detects whether NASSYS 1 or 3 is in use. Much use is made of NASSYS routines but not every call is made in the Approved Manner. The offenders are the call to Parse and to Errm. I don't see why Errm is called (when an invalid command is entered) instead of the address of TOS's own error routine (which calls ERRM anyway in the Approved Manner). These routines are called by reflections in RAM, so should your NASSYS be different (e.g. NASSYS 4 if & when,

or a 'custom' version, maybe) the solution is to single-step through TOS until the addresses have been copied to RAM, then modify these addresses to suit, then proceed.

TOS cannot be used with NASSYS running in RAM. This is because the catalogue load address depends on the drive in use (i.e. Drive A catalogue must be loaded into the Drive A catalogue space in RAM) and not on the drive used to create the catalogue. TOS gets round this by 'throwing away' the header bytes into 'ROM' at location 0. It should be a simple matter (I haven't tried it) to change the address to, say, £800 which is in the video RAM margin. TOS also uses absolute addresses to copy over the NASSYS subroutine table. Again, this is avoidable. TOS calls STMON, which initialises NASSYS, so just a simple look into \$STAB should suffice (unless I've missed something). In fact (I know 'cos I've done it) rewriting TOS to have its own PARSE routine and to look in \$STAB as above releases a bit more space, enough for FOUR whole new commands! It also allows it to run on any version of NASSYS. The bit that initialises the SIO can also be rewritten to take up a fraction of its original length. The lack of a Save ZEAP command in the original version of TOS is to be deplored, especially, as I've said, there is enough room to slot one in.

It may also be of interest to note that a software package is available from HS Design in Scotland (from the same guys who designed the HS1N) for HS1N systems, which greatly extends the commands under Crystal BASIC to include many disk-like commands. The command set looks very comprehensive, and would certainly be worth looking into if you use Crystal BASIC a lot. It will only run on the latest version of TOS (not earlier ones, though they will supply the latest version free with the BASIC Extension if you return the original ROMs), but I doubt very much whether it will run on my 'custom' version. I wouldn't buy it, but only because a) I don't have Crystal BASIC, b) I'd probably lose the extra facilities of 'my' TOS, and c) I don't use BASIC all that much anyway.

DOCUMENTATION

The documentation supplied comes in the form of a small manual which is A5 size. I've mentioned the misleading bit about the /NASIO circuitry, and also the appalling circuit diagram (which is so bad it looks more like a wiring diagram). No source listing of the software is supplied either, so what does the manual contain? Well, basically it explains the operation of the various commands fairly well (enough to enable you to save files without getting it wrong) but I found the format a little cramped. An A4 size manual with more help on using TOS under program control (I keep on about this, but since it is advertised as 'looking like' a floppy disk system & all floppy disk users use operating system commands to load/save data from their programs, I don't see why TOS users shouldn't either) would also be useful (or perhaps a commented sources listing - I've done it myself but probably didn't get it all right, and there's still one or two bits I still don't understand). Some information on the drives themselves would also be useful.

COMPATABILITY WITH OTHER SYSTEMS

I know very little about the 'Hobbit' system except that it uses the PIO, so all comments here relate to comparisons with the 'CFS' system. CFS also writes in blocks of 2K, also at 6000 bps. CFS commands are 'menu-driven' but are less extensive than those of TOS (they do include a 'save ZEAP' command, though). CFS data format is a sync. byte, followed by a load address word, followed by a length word, followed by the checksum, followed by the data bytes. This is therefore incompatible with the HS1N format, and CFS systems will be unable to read HS1N tapes, and vice-versa. One day I might 'con' a CFS user to help with some routines to overcome this. If and when they are finished I might write it up into an article for the mag. (By the way, can 80-Bus News accept NASPEN files dumped onto these min-cassettes? No, I thought not).

CONCLUSION

This system has been in use for several months now, and I must say that I am very pleased with it. I use my Nascom a damn sight more often than I did when I was relying on audio cassettes. I now use my Nascom for actual serious work (i.e. with huge ZEAP/NASPEN, etc. files)... when was the last time you dumped several 28K files to (audio) tape in an evening, eh?? And how often does it refuse to verify, meaning you have to do the whole thing again? With the HS1N, no such problems occur, as verification is automatic (as I've mentioned). If a block fails to verify (which usually means you are using uncertified tapes) it will try again... in the meantime you can go away & make a cuppa or whatever. Above all, this system is so fast compared with the old CUTS system that you will soon wonder how you ever managed without it!

The few points I criticised don't detract from the system's usefulness & versatility, they just make the system look a trifle untidy. They really need attention though, for a more 'professional' finish... an 'issue 2' release, perhaps? I could make a long list of extra commands it would be 'nice' to have, in addition to the ones I have already added, e.g. Loading a named file, Append ZEAP/NASPEN/BASIC file, auto-relocation of ZEAP file when loading (useful if you need to relocate the ZEAP buffer)... but then TOS wouldn't occupy 2K (it would be more like 4K). There is no reason why the intrepid user shouldn't add his own commands, if he/she wishes...

Since I bought the system from Microspares in Edinburgh it has achieved 'Nascom Approved' status, so perhaps some of the points I have mentioned have received attention. I should also think that the HS1N will now be available through your friendly local Nascom dealer.

One final thought...this article was prepared using NASPEN. The file will take about 30 seconds to save & verify. The Editor likes NASPEN (CUTS) tapes [Ed. - or disks!]. It will probably take about half an hour to dump it & verify it. Now where did I put that old cassette recorder...

POLYDOS TAPE BACKUP

M. J. R. GIBBS

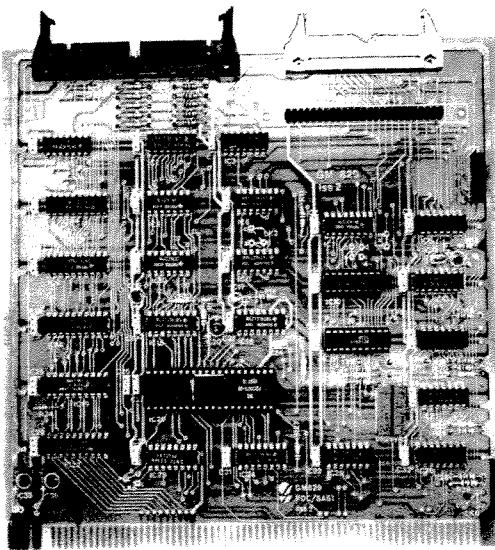
Recently (much to the disgust of my Bank Manager) I have purchased a disk system, the Gemini G809/G815 running with Polydos, which is an excellent product and I have been able to interface all my existing software so that the I/O can be either Disk or Tape.

However, one of the problems that I had was producing backup copies, and after having one disaster (entirely my own fault) doing a backup with a single disk system, I decided to write a Tape Backup Utility. This utility reads in all the files on the disk and writes them to tape, some common files can be omitted by placing the file names in a list. The user only has to load the disk, set the tape on to record and run the program, then the Backup is taken automatically. The files are written onto tape in a similar way to the Generate command. To recover the files you simply set the tape unit to play, and each file is read into memory. Stop the tape after the file required has been read and then use the Polydos 'SAVE' command to restore the data. All files are located at £1000 upwards (and must be less than £B000 long), each file is identified and the load and execute addresses are displayed. All files are copied including ones that have been 'Deleted'. I have enclosed two listings the first a full Assembly listing and the second a dump using a slightly modified version of the DUMP utility published in vol 1 issue 2 (The addresses on the left hand side are the RAM addresses), the program loads and executes at f0C80. Using this program it is possible to backup a disk in a few minutes with the cassette running at 4800 Baud, depending on how full the disk is (I run my cassette at 6000 baud without any trouble).

Additional Information on Gemini Multiboard Products

NOVEMBER 1982.

Since the Autumn Catalogue of Gemini MultiBoard products was published, a number of interesting additional items have been added to the product range. This supplementary section includes information on these new products, plus further information on other aspects of MultiBoard and 80-BUS.



GM829 — FDC/SASI BOARD

- * Single/Double Density Operation
- * Single/Double Sided Drive Support
- * Up to 4 mixed 3.5", 5.25" and 8" Drives
- * Industry Standard SASI Hard Disk Interface

The Gemini GM829 combined FDC (floppy disc controller) and SASI (Shugart Associates Systems Interface) board has been designed to allow both floppy disc drives and Winchester hard disk drives to be easily added to a MultiBoard system.

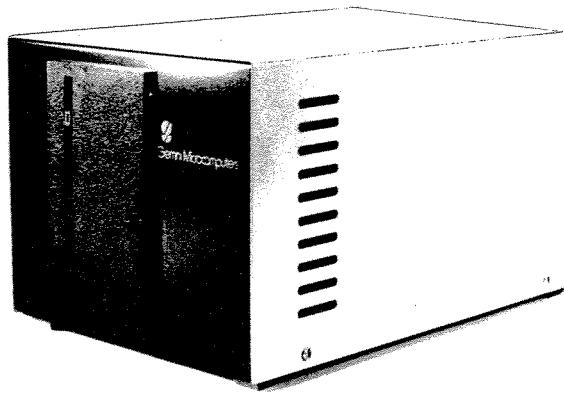
Up to four floppy disk drives may be controlled. These may be single or double sided, 48 or 96 TPI drives, in single or double density formats. The drives may also be 3.5", 5.25" or 8" types, or a combination of these. Switching between single and double density, and 3.5"/5.25" and 8" drives, are under software control.

High performance and reliability are provided by variable write precompensation and phase locked loop data recovery circuitry. The board uses the Western Digital 1397 chip set and occupies 8 Z80 I/O ports. These ports may be set to one of two positions, allowing two GM829 boards to be used in a single system.

The industry standard 50 way 'SASI' interface allows Winchester hard disk sub-systems, such as the Gemini GM835, to be simply plugged straight in.

This board is a development of the extremely popular GM809 FDC board and maintains the same elegant and reliable engineering design which has been proven on the GM809. Full 5.25" software compatibility is maintained, with the added advantage of also being able to control 3.5/5.25" 8" and hard disk drives simultaneously from the one 80-BUS board.

GM829 — FDC/SASI — £145



GM835 — WINCHESTER DRIVE SUB-SYSTEM

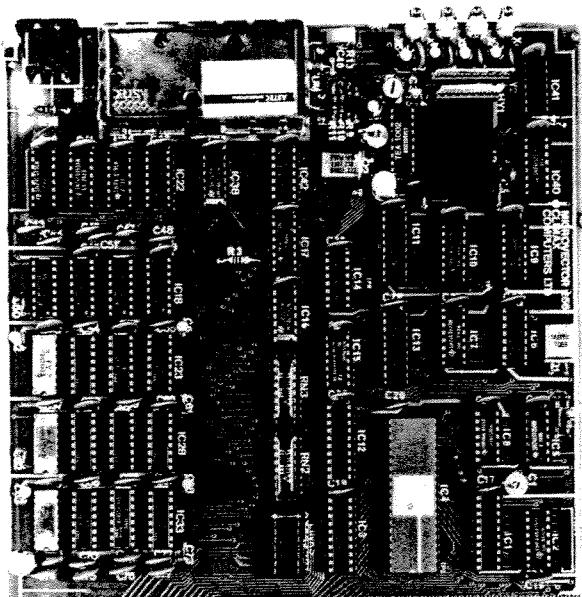
- * 5.4 Megabyte Formatted Capacity
- * Industry Standard SASI Interface
- * Integral Controller and Power Supply

The Gemini GM835 has been designed to plug directly into the new GM829 FDC/SASI board to provide the MultiBoard user with the hard-disk advantages of high performance, high speed, high reliability and high storage.

The housing, styled to match the Gemini Galaxy and GM825 floppy disk housings, contains the Winchester drive, a Z80 based Winchester controller board, and a switch mode power supply. The drive used is the British made Rodime R0201, providing 6.67 Megabytes of unformatted capacity, 5.4 Megabytes formatted. Average seek time is 90ms and the data transfer rate is 5 MBits per second. The intelligent controller provides a 512 byte sector buffer and automatic error detection and correction.

Higher capacity drives will be made available in the future.

GM835-6 — 5.4 MBYTE WINCHESTER SUB-SYSTEM — £1450



CC837 – COLOUR GRAPHICS DISPLAY INTERFACE

- * 256 x 256 16 Colour Pixel Display
- * Ultra-fast Vector and Character Generation
- * 96 ASCII Character Set
- * Audio and Light Pen Inputs
- * Available January 1983

The Climax Computers CC837 is a high performance graphics display interface board. Various graphics primitives such as vector and character generation are provided by a Thomson EF9365 Graphic Display Processor. The plotting rate is typically 1 million pixels per second, giving animation capability. Various vector and character types can be selected and characters may be scaled to give 256 different sizes.

The CC837A has a high quality PAL UHF output with an intercarrier sound facility as well as a composite 75 ohm B/W output. The CC837B has additional 75 ohm RGB outputs for connection to a video monitor.

The CC837 provides a resolution of 256 x 256 pixels in 16 colours using 32K bytes of on-board memory. The board occupies 17 Z80 I/O ports, commands being single byte control codes. A socket is provided, compatible with the AM820 light pen, to be used for interactive graphic procedures.

A comprehensive set of assembly language subroutines given in the operating manual enables the user to develop his own graphics programs quickly and efficiently.

CC837A – COLOUR GRAPHICS (PAL) – £199

CC837B – COLOUR GRAPHICS (PAL + RGB) – £220

Multinet Local Area Network

IN DESIGN

Available January 1983

GM836 – Network Interface Board

- * Low Cost
- * Up to 32 Stations
- * Simple Interface to MultiBoard Systems
- * Available January 1983

There are many occasions when it would be useful to be able to connect several MultiBoard based computer systems together, in order to communicate with each other or to share expensive resources such as disks and printers.

Gemini have developed MultiNet for this purpose, and as with all Gemini products, MultiNet is low cost, easily expandable and highly flexible.

The Gemini GM836 is a small add-on board which plugs into the 26-way connector of the PIO of a GM811 or GM813 CPU board by means of a ribbon cable. The board contains all of the necessary interfacing circuitry to allow the connection of a machine to the network. Data is transmitted serially using a differential transmission method at about 300 Kbaud along a single coaxial cable. Connection between any machine and the network is by BNC T-Junction, this allows any station to be disconnected from the network without disturbing the operation of other stations. Using this system up to 32 machines can be connected to the network and the length of cable can be up to 600m (2000 feet) end to end.

The associated software uses a CSMA/CD (Carrier Sense Multiple Access with Collision Detection) technique where station access to the network is on a contention basis, the software deferring transmission until the network is silent, transmitting, detecting a collision (or simultaneous transmission by another station) and then delaying for a random time before attempting to retransmit. Data is transmitted through the network in variable sized packets, each packet having a CRC to detect errors during transmission, retries being automatically performed if a packet is delivered incorrectly.

A MultiNet System

MultiNet allows several stations access to shared disks and printers when in a CP/M environment. Gemini are currently in the process of developing both hardware and software to allow this to be achieved extremely cost effectively.

The hardware consists of a number of MultiBoard based systems without disks but with the network interface integral to the machine, and the appropriate software to allow all disk and printer operations to be performed by another MultiBoard system acting as a combined file and printer server, which has a printer and Winchester hard disk drive and is dedicated to managing all the shared resources. Software will also be available to allow machines running under CP/M with their own disk drives (such as the Gemini Galaxy) to connect to the network and access the shared resources.

IN DESIGN

Available January 1983

Multiboard Based SYSTEMS



GM839 — PROTOTYPING BOARD

- * Fibreglass PCB
- * 80-BUS Signal Identification
- * High Density IC Capability
- * Available January 1983

The Gemini GM839 high quality 80-BUS prototyping board provides the MultiBoard user with a convenient means of adding specialised 'one-off' boards to his system. This single sided fibreglass PCB provides extensive power supply tracking and the layout has been optimised to allow a high IC packing density. Additionally one edge of the PCB has been designed to accommodate multi-way insulation displacement type connectors.

The component side of the GM839 is silk-screened to show the positioning of the power rails and component pads, and all 80-BUS signals are identified. On the track side of the board the 80-BUS lines are identified by number. An 80-BUS specification booklet is included.

GM839 — PROTOTYPING BOARD — £TBA

MP840 — TERMINATED BACKPLANE

- * 14 Slot Backplane
- * Signal Termination
- * Extensive Ground Shielding

The Microcode MP840 is a 14 slot 80-BUS backplane which has been specially designed to overcome problems often associated with running long microcomputer backplanes. All active bus signals are terminated into a potential balanced RC filter and are interleaved with ground shield tracks, plus one side of the backplane provides a complete ground plane.

The backplane features interrupt and bus request daisy chaining and can be used in different lengths by a simple 'score and break' operation.

MP840 — 14 SLOT BACKPLANE — £47

GEMINI GALAXY

The Gemini Galaxy 1, launched in January 1982, has met with considerable success in a variety of fields. Being based around the MultiBoard range it has proved particularly useful as both a hardware and software development system. In addition it has found many applications in business and education.

With the more recent availability of the GM813 board, capable of replacing both the GM811 and GM802 boards in a Galaxy type system, and with the addition of the new GM827 extended keyboard to the product range, Gemini has now launched the Galaxy 2 range of computers. The Galaxy, briefly described in the Autumn Catalogue, is available in its Mark 2 form in three alternative disk drive configurations.

GM903

The standard Galaxy 2 is the GM903, and like all of the Galaxy 2 range it is based on a three board MultiBoard set, the GM813 CPU-I/O-64KRAM, GM812 IVC and GM809 FDC, along with the GM827 extended keyboard. This configuration provides the user with two spare 80-BUS slots for future expansion.

In the GM903, twin Micropolis 1015F5 drives are fitted, providing 800K of formatted disk storage.

As in all Galaxy configurations, the CP/M 2.2 operating system is included in the package, along with a 12" video monitor.

GM904

For users who require a Galaxy 2 but either do not need twin disk drives, or wish to start with a lower cost system, the GM904 offers all of the features of the GM903 but is supplied with only one 1015F5 drive, providing 400K of formatted disk storage. All connectors and cables are included to allow the second drive to be added at a later date if required.

GM905

The third option in the Galaxy 2 range is the GM905. This system is aimed at users with particularly high storage requirements and is supplied with twin Micropolis 1015F6 drives, offering a massive 1.6 Megabytes of formatted disk storage.

GM903 — GALAXY 2 WITH TWIN 400 KBYTE DRIVES — £1495

GM904 — GALAXY 2 WITH ONE 400 KBYTE DRIVE — £1275

GM905 — GALAXY 2 WITH TWIN 800 KBYTE DRIVES — £1695

Further storage expansion capability of the Galaxy system is provided by the GM825 disk drive unit and GM835 Winchester drive sub-system, both of which have been specifically designed to complement the Galaxy range.

Purchasing Your Multiboard System

Gemini Microcomputers does not normally sell its products direct to the end user, unless that user is an OEM requiring large quantities of product. Sales are usually made via a number of dealers throughout the UK and Europe. Details of your nearest dealer can be obtained from the computer press, or by telephoning Gemini on 02403 - 28321.

NON GEMINI 80-BUS PRODUCTS

It is Gemini Microcomputer's policy to include 80-BUS compatible products in its catalogues which are manufactured and marketed by other companies. The purpose of this is to ensure that the potential customer is aware of the wide range of 80-BUS products available.

'All Gemini products have product numbers which have 'GM' prefixes. Products with other prefixes are manufactured by the following companies, and are generally available from Gemini dealers.

CC - Climax Computers Ltd.,
17a Broad Street,
South Molton,
Devon. EX36 4JE

EV - EV Computing Ltd.,
700 Burnage Lane,
Burnage,
Manchester.

IO - IO Research Ltd.,
6 Laleham Avenue,
Mill Hill,
London. NW7 3HL

MP - Microcode (Control) Ltd.,
41a Moor Lane,
Clitheroe,
Lancs.

AM - Arfon Microelectronics Ltd.,
*These products are currently
being re-sourced. Contact
your dealer for further details.*

COMPATIBILITY WITH OTHER MICROCOMPUTERS

Gemini Microcomputers commenced production of Nascom compatible products in 1980. This range of products continued to grow during the following year, and in mid 1981 we published the 80-BUS specification. The purpose of this was to remove some of the ambiguities present in the Nasbus specification and to encourage other manufacturers to produce 80-BUS compatible products by giving the BUS structure a name unassociated with one specific company.

80-BUS, therefore, is essentially identical to Nasbus, and Gemini MultiBoard products are thus compatible with the Nascom range of computers and have been used by many people to expand their Nascoms.

80-BUS NEWS

'80-BUS NEWS' is a magazine produced six times a year for owners of 80-BUS based microcomputers. The aim of '80-BUS NEWS' is to provide owners of Gemini and Nascom systems with a comprehensive guide to the equipment that they own, and to provide information on the extremely wide range of further hardware and software products which are available for their machines.

A major objective of '80-BUS NEWS' is to act as a central discussion point for Gemini and Nascom users. Each issue of '80-BUS NEWS' contains a blend of hardware and software reviews, articles on hardware construction and on programming, a number of tips and hints, letters received from readers, and some occasional light relief - all with the aim of assisting both Gemini and Nascom owners to obtain the maximum use and/or pleasure from their chosen equipment.

ERRATUM

Please note that the price of the GM807 3A Power Supply, as shown in the Autumn Catalogue, should be £40 and NOT £140.

Gemini Microcomputers reserves the right to amend prices and specifications without notice.

DUMP V1.0 Disk - Tape Backup V1.0

As was mentioned in the last issue of 80BUS News, the series 'Kiddies Guide to Assembler Programming' had found its inevitable end as the topics to be covered were becoming too long and complex to be dealt with in a single issue. However, as the urge to write in a, hopefully, understandable manner is no less diminished, the search for other topics has continued. In this article the intention is to cover the Gemini GM822 real time clock kit from both the construction and the software point of view.

Of late a number of real time clocks have appeared for the Nascom and Gemini, five at the last count, ranging in price from about £25.00 to £50.00, with one at £125.00. The later is the Gemini GM816 I/O card which also contains a CTC, three PIOs and fairly comprehensive expansion capability as well, which explains the otherwise highish price. Of the cheaper clocks, these are small cards measuring up to three inches square and are intended to be piggy backed onto the host board with double sided sticky tape, or to be mounted separately as convenient. Four of the five clocks feature the National Semiconductor MM58174A chip, the fifth I have not seen, but from the price, it would be reasonable to assume the same chip. All incorporate battery backup. The clocks are provided in either built or kit form with the necessary software and documentation to build, connect and run them.

The Gemini GM822 is the only version I have had experience with, and this part of the article will be confined to a review of that item. The Gemini GM822 is supplied in kit form at £29.50 + VAT, a middle of the road price when compared with its competitors.

The kit comprises the documentation and the component parts. The documentation is extensive, covering the constructional details, a detailed description of the circuit employed, some three pages on the workings of the MM58174 itself which is considerably more understandable than the National Semiconductor data sheet for the chip (not supplied), and a simple software listing in both assembler and HEX dump for either the Nascom or Gemini machines. The routines are simple and well explained. Because they are short, however, the routines are unforgiving of input errors, but form a sound basis for more elaborate routines which may be written.

The components were all there as per the parts list, although a connecting lead to the PIO plug was not provided. The printed circuit board is a little disappointing, and not up to the usual Gemini standard. The PCB is glass fibre and is quite small, about 4cm by 6cm, the tracking is single sided only. Unfortunately the board is not coated in the usual Gemini green solder resist and it is only too easy to bridge pins of the IC sockets or the 26 way IDS connecting plug during assembly. Extra care during assembly and inspection needs to be taken. The only other problem encountered during assembly was with the tantalum bead capacitor. The documentation blithely warns about ensuring that the component is connected with the correct polarity, but as the type supplied was of the colour coded variety with no polarity markings, this could present a problem for those who do not know the correct connection. For those who do not know the correct connection, the positive lead is on the right when holding the capacitor leads down with the coloured spot facing you. No other problems were encountered during assembly.

Two clocks were ultimately constructed, the first one at home and the second at work a few days later. So, to the first clock, constructed and tested at home. The software was typed in from the HEX listings provided, and checked. The port base address, 04H for Nascom, or 0B4H for Gemini was changed throughout to 1CH to suit a spare port on my Nascom I/O card, and to remain consistent with some already existing software which had been acquired from others who already had the clock working. The clock was connected with a 6" ribbon cable folded 'Z' shaped and flattened to shorten it to about 2" and the clock stuck down on top of

an adjacent PIO chip with double sided, foamed, particularly tenacious sticky tape, making for tidy mechanical assembly. On test the clock functioned perfectly.

The clock is provided with a trimmer for setting the onboard crystal to exactly 32.768KHz, however, no advice on setting this is offered. The best method is adjustment over a long period, days or weeks, carefully taking up any errors in time noted. Connecting any external device such as a frequency counter will load the onboard clock and render inaccurate readings, also the accuracy of most cheaper frequency counters is likely to be less than the accuracy required for setting the clock to +/- 5 seconds a day, so the only choice is long term adjustment. There is also a second problem associated with clock accuracy, and that is that unless the chip is addressed completely within a specified minimum time frame, the clock will gain about 1/100th of a second each time it is addressed. More on this later. All this is coupled in my case, with the fact that my computer is now mounted in an inaccessible totally enclosed aluminium box for RF shielding, making long term adjustment an impractical proposition. The trimmer was set to mid position, and over the last two weeks the clock has gained some seven seconds. As I am only interested in hours and minutes, this is of little importance.

The second clock constructed a few days later at work, however, behaved in a most erratic fashion. This clock was connected to the onboard port of a Gemini GM811 CPU card, and the software, which had worked correctly on the home built clock, was reassembled to port OB4H. Due note was taken of the warning in the clock documentation concerning the Gemini CP/M initialisation routines setting the port for Centronics printer operation causing rubbish to be written into the clock registers, and these were duly bypassed. Regardless of how the clock was initialised, it would not return from the read routine unless a finger was placed across the crystal and then it would always return completely repeatable rubbish. After much checking of the PIO, the software and almost complete component substitution, the conclusion was reached that the crystal oscillator was either running at low level or not at all, and that the only item that could be at fault was the pcb board itself. This being patently ridiculous, we must have missed something. None the less, the pcb was rigorously cleaned to remove any last vestige of flux that could be causing the clock to run at low level as it had been noted that attaching a 'scope to the crystal would produce a visible increase in clock level, although this was probably a byproduct of the capacitance of the 'scope probe.

Then, by accident, light started to dawn. In desperation, we had by now adopted the very bad practice of not powering down the computer before making component substitution. Tim removed the clock chip with all power on and replaced it with another, and it all appeared to work. This caused some investigation of the clock power down circuitry and battery backup. However, this was not found to be at fault, and another lucky accident revealed the true cause. Having persuaded the clock to work by plugging in the chip with the power on, the failed condition could be caused by either powering up or by resetting the computer. It was apparent that it was the reset state which caused the problem, and that under this condition the clock chip was being fed with a register combination which not only jammed the clock chip, but made the chip incapable of accepting new data during any subsequent initialisation process, powering down the computer made no difference to the jammed clock as the battery backup on the clock board took over automatically. Once jammed the clock chip remained jammed. In fact the only way to unjam a jammed clock chip was to remove it from the board and then plug it back in (having initialised the port to address the chip).

On the Nascom 2 (not Nascom 1) and the Gemini, the PIO device is reset when the computer is reset and also on power up, causing the PIO to go to an input condition and to float the input/output pins which are left in a high impedance state. Normally the input/output pins float high. By attaching our in line port analyser, which sounds complicated but consists of no more than a CMOS non inverting buffer sensing each port line and lighting a LED when a 'high' appears on the port line, we noted that the port line which addressed the clock

board chip select, CS, did not float high as expected but remained resolutely at about the two volt level. This, despite the inclusion of a 100K pullup resistor on the clock board to ensure the CS line remained high. Taking in to account the loading effect of the high impedance meter used to measure this voltage, the approximate voltage on this line was guessed as being about the 2.5 volt level. Changing the PIO or the buffer made no difference, it remains a mystery where the leakage causing the line to be lower than expected is occurring.

However, accepting that this leakage does occur, and as this voltage is about the threshold of the board chip select buffer, which is a CMOS device with a threshold of about 2.5 volts, we thought that any spurious noise on this line, and there has to be some, was causing the CMOS buffer on the clock board to select the clock chip. This was confirmed with a 'scope looking at the select pin of the clock chip, after the input and power down buffers. A definite short glitch was noted on the select pin during a computer reset sequence. The cause, like the voltage leakage remains unknown. As the output lines of the PIO are directly connected to the clock chip which again is a MOS device, these are also susceptible to noise due their high impedance inputs. This appears to cause the clock chip write input to open during a computer reset sequence and so to write the rubbish on the data lines to the clock chip registers which were being addressed by the rubbish on the clock chip address lines, also directly connected to the PIO. We were relieved to cure the problem by the simple expedient of changing the 100K pullup resistor for a 22K pullup.

Unfortunately, this did not remove all the problems, the clock would now work correctly whilst the computer was left running, however, on power down and subsequent power up the clock was occasionally being corrupted. Having previously eliminated the power down and battery backup, this left the power up condition. This was confirmed as being the cause by powering down the computer with the clock connected, then unplugging the clock and powering the computer up again. Reconnecting the clock with the power on and then reading the clock, the clock worked correctly. The clock circuitry has a 100K pullup resistor in series with a 100nF capacitor to stop the CS line becoming active during power up. 100K and 100nF gives a time constant of 10mS which is the time allowed for the power supply rails to settle. This may be adequate for a switch mode power supply, as the clock at home had shown no trouble in this respect. However, the works computer was fitted with a large conventional power supply. Investigation of the power supply start up revealed that the rails did not become stable for at least 100ms, and during that time the state of the PIO was extremely indeterminate. It was obvious then that the 10mS allowed for stabilisation was inadequate for the power supply in use, and the 100nF capacitor was changed for a 2uF tantalum, giving a 200mS time constant. This cleared the remaining problem.

Both the problems noted above could do with further investigation, why were these problems not noted on the prototypes, and are the conclusions drawn above and the solutions adopted, the correct ones. Our aim at work was to make the clock work, not to conduct an investigation into the behaviour of PIOs and power supplies at reset and power up. Perhaps Gemini may like to make some comment in a future issue.

To sum up then, the Gemini GM822 represents a useful addon which is simple to construct and easily added to the system. A one evening project with a useful end result. Having cured the problems mentioned above, both clocks have behaved well. Taking the cost of the competing clock boards into account, the Gemini GM822 seems to be about par for the course in terms of value for money and facilities provided.

I didn't like the software supplied with the clock so I set to and wrote some new routines. These used large chunks of the originals and in this case I can not credit them as I do not know who wrote them in the first place, however, thank you, whoever you are. The routines are listed elsewhere and are written for use under CP/M only, but are otherwise Nascom/Gemini compatible although I have maintained port 1CH as the clock port. This could easily be changed on reassembly. The most important improvement is that they contain error checking of the input, making it impossible to program wrong data into the clock. However,

there is still room for improvement, as since writing these I have discovered that it is possible for a clock register to become programmed with OFH as a legitimate character, caused by spurious pulses on the PIO lines. Under these circumstances the program goes into a permanent loop, thinking that the clock has just changed time. Some sort of time-out is required, where say, after having had 256 goes at reading the clock and failed, the routine returns the register contents regardless.

Having fitted a real time clock (RTC) some use has to be found to justify the clock. In the circles I move in, a couple of people have already found uses for the clock. Richard has modified his M80 assembler to include the time and date on printed listings, which can be very useful. David has written an elegant little utility called INDEX which gives a CP/M directory listing and allows a one line comment after each program entry. The date being added to the index created at the time of updating. I hope INDEX will see its way round a larger circle soon, although, as it requires the GM822 RTC to be hung on a Z80 PIO at port 1CH, it does make it a dedicated program, and therefore not universally usable. Note that in each instance port 1CH has been used, and it has been mutually agreed amongst ourselves that port 1CH will be the clock port. My own interest has been to hook the clock into a compiled Basic program.

As was mentioned earlier, the MM58174A clock exhibits a peculiar characteristic, in that it gains time if access is made to it over too long a time frame. I do not have the National data sheet to hand, but if I remember correctly, the clock must be accessed within a period of roughly 15ms from reading the first register to reading the last. This means that the access software has to be very fast. On the other hand, in instances where it is not the intention to display the clock on the screen, reading it back at its fastest increment of tenths of seconds, this is of little consequence. The software provided by Gemini certainly fails in this respect in that it wastes a lot of time within the read loop determining whether the clock has changed time, and if not, to convert the incoming nibble to ASCII and to save it in the temporary workspace. The obvious method to correct for this would be to copy the registers 'as is' to the temporary workspace using the tightest possible loop, perhaps using an INI instruction or even an INIR instruction if it could be contrived, then, having copied the registers to the temporary workspace, to sort them out later. I have not given this approach much thought, but it should be possible. The later National MM58174AN chip does not suffer from this problem, but is more expensive.

Making use of the clock to display the time continually on the screen, whilst a nice idea, is not as easy as it sounds. That is, assuming the computer is to be used for other things apart from displaying the time. It is not difficult to write a program which will continually read the clock and place the result on the screen, Gemini have already provided the clock read routines, and a simple change to the software could be made to cause the routine restart itself instead of making the clock return to the routine which called it. This is a massive waste of time as the processor is 100% wrapped up in reading the clock. There is no time left for other things. As the clock is capable of creating interrupts, one method would be to use the interrupt output connected to the strobe input of the PIO to create an interrupt every time the clock changed state. The fastest interrupt rate on the MM58174 is one every half a second, this could be used to update the clock display every second, whilst causing minimum disruption to processing of other things. As it happens, the interrupt output of the GM822 was deliberately not returned to the strobe line of the PIO, as this could be the cause of some very strange software faults by the creation of undesired interrupts when used with disk systems (which must not be interrupted), or other interrupt driven auxiliaries elsewhere in the system, where the use of the EI and DI instructions could cause other problems. The interrupt output is connected to one of the output bits which means it can only be used when mode 3, the bit masked interrupt mode of the PIO is selected. This mode, whilst more flexible is also more difficult to implement.

EV Computing in Manchester have come up with a novel solution using the Gemini GM812 IVC card, where the video card Z80 is run under a new piece of software, and interrupts are created on the video card. This overcomes all the objections to running the RTC in an interrupt mode on the main Z80, and because their modification includes its own battery backed up RAM as well, allows preset messages to be generated as required. An ingenious solution, and one which may be retrofitted to the IVC card with little difficulty.

One method of display I have yet to investigate is to incorporate the clock routines within the keyboard routine. This is a compromise solution, as the clock would only be displayed whilst the keyboard was being scanned but not actually processing an incoming character. However, as the computer spends the vast majority of its time doing just that, the system should be quite effective. Naturally the clock display would freeze when other processing was taking place, for instance, whilst fetching and putting to disk, where the keyboard is no longer scanned, but I consider these as minor inconveniences, there are not many times in an evening where the processor does not look at the keyboard at least once within a ten second period. The only time I can think of is when assembling a large program, where the processor may be occupied for three or four minutes. I intend to display the time at the top right of the screen, but not to trap the top line so that the time can always be scrolled when, say, listing a program. Again, I do not think this will matter, as the display will be restored within one second of the screen display becoming stable.

My use for the clock has been in a computer logging system written in compiled Basic. Much as I like, and need the practice at machine assembler, I am sufficiently aware of my limitations not to take on a program which requires eight overlay programs, none of which is less than 14K of Basic source. The problem remained, however, of reading the clock from Basic. The clock updates its registers every tenth of a second, and indicates the update by changing the output of the registers from a four bit BCD number to the code OFH. Trying to access the twelve registers via one port by outputting (using the Basic OUT instruction) to create the address, and cause and output strobe and then inputting the data from each register within one tenth of a second is impossible in straight Basic. I also doubt that compiled Basic would complete the task within the time allotted, as the compiler is not renowned for producing efficient code. So the obvious approach was a USR type routine.

In Microsoft MBASIC the distinction between the USR and CALL user subroutines is finely drawn, although the CALL function is more appropriate when used compiled. The problem was to decide how to extract the data returned by the clock, when the Microsoft manual glosses over this rather vital point. It is also rather obscure about how to pass information to a machine code subroutine as well, although after careful reading and repeating the words slowly to myself, the technique was finally revealed. The final program was simple and straightforward, although how it works is another matter.

```

1000 TM$="*****"
1010 ADDR% = PEEK(VARPTR(TM$)+1)+256*PEEK(VARPTR(TM$)+2)
1020 CALL TIME(ADDR%) : ' Get the time using the machine code subroutine
1030 MONTH=PEEK(ADDR%) : DYWK=PEEK(ADDR%+1) : DAY=PEEK(ADDR%+2)
1040 HOUR=PEEK(ADDR%+3) : MIN=PEEK(ADDR%+4) : SEC=PEEK(ADDR%+5)

```

It all relies on making use of the way the strings are handled within the Basic. Anyone who has tried to investigate how the Microsoft Basic stores strings will have noted that the string space is allocated dynamically, that is, the string is put into a workspace and a three byte pointer is set up to point to the string and to supply the string length. This allows the strings to be shuffled about without having to reserve the maximum space for string manipulations. To save space further, any strings declared in the program, prior to use, are not copied into the string workspace, but are left exactly where they are within the Basic source, and a pointer is set to point inside the Basic source.

In the above case, TM\$ will be the variable space for the machine code clock read routine. All that is required is to pass the address of TM\$ to the machine code routine. When the Microsoft Basic CALL is used, upto three variables may be passed to the machine code routine in HL, DE and BC. If there are more variables, BC is set to the address of a table of variables and that is passed for the machine code routine to pick up. In this instance only the address of TM\$ is required. The VARPTR function returns the address of the string pointer, which holds:

- 1) The string length
- 2) The actual string address, low byte first

Line 1010 returns the actual address of TM\$, ADDR%. Note that this must be an integer variable, as only a 16 bit number can be sent to the machine code routine in HL. Line 1020 CALLs the the machine code routine and ADDR% is passed in HL. The machine code routine places the month, day of week, day, hour, minute and seconds in the first six bytes of TM\$ and lines 1030 and 1040 read these back. I would have thought that as the CALL function within Basic can pass variables to a machine code routine, it ought to be able to pass them back, however I can not find out how to do this, so if anyone knows, drop me a line.

The machine code read subroutine is very simple (refer to the program listing READ ROUTINE FOR GEMINI GM822), and is a stripped down version of my rewrite of the routines that came with the clock. It need only be a read routine as there is no facility for setting the clock within the logging program. Note, however, as I wish to return the variables as complete integers, I use a times 10 routine to convert the separate nibbles into integers. The routine has been assembled at address 0000H, and is intended to be linked into the compiled Basic program. Any line of code within the listing suffixed by an accent (such as CD 0009') means that that absolute address would need to be changed if the program were moved elsewhere. As it stands, the TIME routine can not be used with Basic without the compiler. However, as has already been discussed, strings declared within a Basic program are not moved about by Basic until required, so it could be POKEed into a string declared as the first line of the program within the Basic source. In this way, provided that no Basic lines were inserted prior to the declared string, the addresses would be absolute and the absolute code adjusted to suit. Note that this idea will only work with a specific version of the Microsoft Mbasic, as Microsoft have a tendency to move the source buffer addresses about between different versions; also that this technique makes the first line of the program unlistable, as it will contain some 128 bytes of reserved words, junk, and other nasty things.

So, having got the time from the clock routine, what to do with it? Well, one nice exercise is to display it within a Basic program, in the form say, 14.34 GMT, 21 Sep 1982. Not a difficult job, but shows some of the more useful attributes of string manipulation in Basic. Those who have read through the machine code clock setting routines will have noticed similar routines.

```

2000 MN$="JanFebMarAprMayJunJlyAugSepOctNovDec"
2010 DY$="SunMonTueWedThuFriSat"
2020 IF DAY>9 THEN D$=RIGHT$(STR$(DAY),2)+" " ELSE D$="0"+RIGHT$(STR$(DAY),1)+" "
2030 IF HOUR>9 THEN H$=RIGHT$(STR$(HOUR),2)+"." ELSE H$="0"+RIGHT$(STR$(HOUR),1)+"."
2040 IF MIN>9 THEN MIN$=RIGHT$(STR$(MIN),2) ELSE MIN$="0"+RIGHT$(STR$(MIN),1)
2050 DY$=MID$(DY$,3*DYWK-2,3)+" "
2060 MN$=MID$(MN$,3*MONT-2,3)+" "
2070 YR$="1982"
2080 DATE$=H$+MIN$+" GMT, "+DY$+MN$+YR$

```

The points to note are the way in which the day and month are picked from the string by calculating the relevant point in the string and then using the MID\$ function. Note also the way the STR\$ function is used within a RIGHT\$ function to truncate the numeric variable and return it as a string. In line 2080 it simply becomes process of adding up the strings.

An off shoot of presenting the date is the ability to use the date in numerical sorts. The obvious method is split a date into its component parts, using the tens and units of the year, the month and the day; so that 21/09/82 would end up as 820921. This would work as each day is a unique number and days increase in ascending order. However, the number sequence is not contiguous which could cause a number of problems, not the least of which is the complicated validation to determine if a date is missing within a sequence of dates, or possibly an extra day having been entered in error. Whilst initially attractive, the method of using the date backwards has a number of disadvantages. Better then that the number sequence be contiguous. This can be achieved by starting at a base date and counting upwards. The only problem then is to decide the base date and how to cope with leap years, etc.

A numeric sequence often used for this is the Julian date. Based on the year nought. It is accurate but is confused by the normal slippage of leap years every four hundred years, also by the abnormal leap year skip which occurs every 4000 years. The next modulo 4000 leap year correction takes place in the year 2000, and the one after that in the year 6000. The one in the year 2000 might be of interest, but the one in the year 6000 will probably only be important to someone with an interest in cryogenics. However, for general purposes, the Julian number has a lot going for it.

To convert an input date to a Julian number the following simple routine may be used, it does assume that the date will be this century.

```
3000 INPUT "Date (DD/MM/YY) ";DT$  
3010 DAY=VAL(LEFT$(DT$,2)) : MONTH=VAL(MID$(DT$,4,2)) : YEAR=1900+VAL(RIGHT$(DT$,2))  
3020 DT=INT(30.57*MONTH)+INT(365.25*YEAR-395.25+.5)+DAY  
3030 IF MONTH >2 THEN IF INT(YEAR/4)=YEAR/4 THEN DT=DT-1 ELSE DT=DT-2  
3040 ' DT now equals the Julian number.
```

This is all very good, the conversion back again is also simple, with the addition in this case to convert the number to a string in the same form as the input.

```
4000 Y=INT(DT/365.26)+1  
4010 D=DT+INT(395.25-365.25*Y+.5)  
4020 IF INT(Y/4)*4=Y THEN D1=1 ELSE D1=2  
4030 IF D>91-D1 THEN D=D+D1  
4040 MONTH=INT(D/30.57)  
4050 DAY=D-INT(30.57*MONTH)  
4060 IF M>12 THEN M=1 : Y=Y+1  
4070 YEAR=Y-1900  
4080 D$=RIGHT$(STR$(DAY),LEN(STR$(DAY))-1) : IF DAY<=9 THEN D$="0"+D$  
4090 J$=SPACE$(2) : LSET J$=D$ : DT$=J$+ "/"  
4100 M$=RIGHT$(STR$(MONTH),LEN(STR$(MONTH))-1) : IF MONTH<=9 THEN M$="0"+M$  
4110 J$=SPACE$(2) : LSET J$=M$ : DT$=DT$+M$+ "/"  
4120 Y$=RIGHT$(STR$(YEAR),LEN(STR$(YEAR))-1)  
4130 J$=SPACE$(2) : LSET J$=Y$ : DT$=DT$+J$  
4140 ' DT$ now equals the date string
```

So having started with clock hardware, I have finished with Julian dates. Time is an interesting subject, you can do so much with it. I only wish there were a program to provide me with about forty hours in a day, then perhaps I would have time to do everything I wish to do and still find time to sleep.

THE CEMENT COUNCIL REPORT

Comment: Adapted from the original routines by
D. R. Hunt 00/00/00.

• Z80

GLOBAL RTC
RASTER EOT 1 CU

```

; CP/M equates
CONIN    EQU 1          ; Console input routine
CONOUT   EQU 2          ; Console output routine
LILININ  EQU 10         ; Line input
CR       EQU OAH         ; Carriage return
LF      EQU 005H         ; Line feed
BDOS    EQU 0005H        ; BDOS jump vector

```

```

; CP/M work spaces          ; Input arguments
A082H      EQU     0082H      ; Input hours
A083H      EQU     A082H+0    ; Input minutes
A084H      EQU     A082H+3    ; Input day
A085H      EQU     A082H+6    ; Input month
A086H      EQU     A082H+9    ; Input year
A087H      EQU     A082H+12   ; Input + sign
A088H      EQU     A082H+15   ; Input + sign
A089H      EQU     A082H+18   ; Input + sign
A08AH      EQU     A082H+21   ; Input + sign
A08BH      EQU     A082H+24   ; Input + sign
A08CH      EQU     A082H+27   ; Input + sign
A08DH      EQU     A082H+30   ; Input + sign
A08EH      EQU     A082H+33   ; Input + sign
A08FH      EQU     A082H+36   ; Input + sign
A090H      EQU     A082H+39   ; Input + sign
A091H      EQU     A082H+42   ; Input + sign
A092H      EQU     A082H+45   ; Input + sign
A093H      EQU     A082H+48   ; Input + sign
A094H      EQU     A082H+51   ; Input + sign
A095H      EQU     A082H+54   ; Input + sign
A096H      EQU     A082H+57   ; Input + sign
A097H      EQU     A082H+60   ; Input + sign
A098H      EQU     A082H+63   ; Input + sign
A099H      EQU     A082H+66   ; Input + sign
A09AH      EQU     A082H+69   ; Input + sign
A09BH      EQU     A082H+72   ; Input + sign
A09CH      EQU     A082H+75   ; Input + sign
A09DH      EQU     A082H+78   ; Input + sign
A09EH      EQU     A082H+81   ; Input + sign
A09FH      EQU     A082H+84   ; Input + sign
A09AH      EQU     A082H+87   ; Input + sign
A09BH      EQU     A082H+90   ; Input + sign
A09CH      EQU     A082H+93   ; Input + sign
A09DH      EQU     A082H+96   ; Input + sign
A09EH      EQU     A082H+99   ; Input + sign
A09FH      EQU     A082H+102  ; Input + sign

```

```

; Port assignments
PDATA EQU BASE      ; Data port for commands
PADDR EQU BASE+1    ; Data port for commands
PCDATA EQU BASE+2   ; Control port for data
PCADDR EQU BASE+3   ; Control port for data

```

```

; POCHEX1000 instructions
CRDODE EQU OFPH ; Control mode
ALLIN EQU OFPH ; All inputs
ALLOUT EQU O ; All outputs
INTINOUT EQU 10H ; All out except INT input

```

; Addresses for RTC	
TEST	EQU 0
TMONTH	EQU 12
START	EQU 14
INSTAT	EQU 15
MONSTRB	EQU 0EH
DRDSTRB	EQU 80H
WRSTRB	EQU 40H

DRIVE ROUTINES FOR THE GEMINI GM822 RTC MODULE

卷之三

MINT MARKS, TRADES AND TITLES

ERIC RICE TIME SETI

DEFB CR,LF,**CR,LF** 'Set time in the form:- HH:MM DD:MM.
DEFB

DETB or T for time.'

DEFB CR,LF
DEFB 'Enter time ? ',0

```

    ERNES:  DEFB      'Error'
    CRLF:  DEFB      CR,LF,O
    ; Output string
    HOURS: DEFB      '00:00:00.0

```

DAY: DEF B
MONTH: DEF B

36

36

```

; **** Subroutines to read/write to the RTC ****
; **** Called with:- C=PCADDR - data port for command ****
; **** D=RTC register address E=RTC reg. + strobe (R or W) ****
; **** B=RTC reg. + strobe (R or W) ****

; **** Subroutine to read a RTC register ****
; **** READ: OUT (C),D ; Set up address
; **** OUT (C),E ; Read strobe on
; **** IN A,(PDATA) ; Read a nibble
; **** OUT (C),D ; Strobe off
; **** RET

; **** Write <A> to a RTC register ****
; **** WRITE: OUT (PDATA),A ; Put data in PIO register
; **** OUT (C),D ; Set to output
; **** OUT (C),E ; Address the RTC
; **** OUT (C),F ; WR strobe on
; **** OUT (C),G ; WR strobe off
; **** IN DATA ; Set back to input
; **** JR RET

; **** Routine to read the RTC registers ****
; **** to work space in RAM at (HL) ****
; **** OUTADDR: CALL QUADDRL ; Set command port to o/p
; **** INDATA: CALL INDATAH ; Set data port to i/p
; **** LD HL,WSPACE ; Read into here
; **** LD B,12 ; 12 registers to read
; **** LD D,TMONTHH-NOSTRTB ; 10's of months + no strobe
; **** LD E,TMONTHH-RDSTRB ; 10's of months + read strobe
; **** C,PCADDR ; C = control port address
; **** LD RDRTCL: CALL READ ; Get the data
; **** AND OFH ; Isolate the lower nibble
; **** CP OFH ; Valid?
; **** JR Z,RDRTC ; No, so start again
; **** ADD A,50H ; Yes, so make it ASCII
; **** LD (HL),A ; Store in workspace
; **** INC HL ; Next RTC register
; **** DEC D ; Loop if more
; **** DJNZ RDRTCL, RET ; Done

; **** Set command port to control mode, all lines output ****
; **** OUTADDR: LD A,0FFH ; Ensure all data lines ...
; **** OUT (PCADDR),A ; ... will be 1's
; **** LD A,CMODE ; Set mode
; **** OUT (PDATA),A ; Set direction
; **** LD A,ALLOUT ; Set mode
; **** OUT (PCDATA),A ; Set direction
; **** RET

; **** Set command port to control mode, all lines output (0BAH) ****
; **** OUTADDR: LD A,0FFH ; Ensure all data lines ...
; **** OUT (PCADDR),A ; ... will be 1's
; **** LD A,CMODE ; Set mode
; **** OUT (PCADDR),A ; Set direction
; **** LD A,INTOUT ; Set mode
; **** OUT (PCADDR),A ; Set direction
; **** RET

; **** Set command port to control mode, all lines output ****
; **** OUTADDR: CALL QUADDRL ; Set command port to o/p
; **** OUT (C),D ; Set data port to i/p

```

DRIVE ROUTINES FOR THE GEMINI GM822 RTC MODULE M-80 14 Sep 1982 14:48 PAGE 1-4

```

0157' 21 00B8' LD HL,WRKSPC ; Write from here
015A' 06 0C B,12 ; 12 registers to write
015C' 16 EF D,INSTAT+NOSTRB ; Interrupt status + no strobe
015E' 13 4F E,INSTAT+WRSTRB ; Interrupt status + write strobe
0160' OB 1D C,PADDR ; C = control port address
0162' 7E WRRTSL: LD A,(HL) ; Get the data
0163' CD 0121' INC HL ; Put in the RTC
0166' 23 DEC D ; Next RTC register
0167' 15 DEC E
0168' 1D DJNZ WRTCL ; Loop if more
0169' 10 F7 RET ; Done
016B' C9

; **** Display the current date and time in the ****
; **** form:- 19:00:56.6 Mon 21 Sep 1982 ****
;

016C' CD 00F0' TIME: CALL INDATA ; Set PIOs to RESET state
016F' CD 00F9' . CALL INADDR ; Get data into workspace
0172' CD 012E' ; Get the month LD HL,WSPACE ; Point to output string
0175' 21 02BB' CALL PLSTRG ; Calculate offset
0178' CD 01D1' D,O
017B' 16 00 LD E,A
017D' 5F LD HJ,MNSTRG ; Add it to <HL>
017E' 21 00CC' ADD HL,DE
0181' 19 00A5' LD DE,MONTH
0182' 11 00A5' LD BC,3
0185' 01 0003 LD LDDR ; Copy across
0188' ED B0 ; Get the day of the week LD A,(WSPACE+2) ; Get day number
018A' 3A 02BD' SUB JOH ; Place in string
018D' D6 30 CALL TIME3 ; Calculate offset
018F' CD 01E9' SUB J
0192' D6 03 LD D,O
0194' 16 00 LD E,A
0196' 5F LD HL,DYSTRG ; Add it to <HL>
0197' 21 00B7' ADD HL,DE
019A' 19 00C0' LD DE,DAYMN
019B' 01 0003 LD BC,5
01A1' ED B0 LDIR ; Get the date and time
01A3' 21 02BE' LD HL,WSPACE+3 ; Copy across
01A6' 11 00A0' LD DE,DAY ; Now the day
01AB' ED A0 LDI LDI DE,HOURS ; Now the hours/mins/secs
01AD' 11 0090' LD A,3
01B0' 3E 03 HMS: LDI INC DE
01B2' ED A0
01B4' 01B5' 13 DEC A ; More?

```

DRIVE ROUTINES FOR THE GEMINI GM822 RTC MODULE M-80 14 Sep 1982 14:48 PAGE 1-5

```

01B8' 20 F8 ; Yes, so loop
01BA' ED A0 ; Copy across the tenths
01BC' 21 0090' ; Now display it
01BF' CD 01C3' ; Done
01C2' C9

; Print the string
PRINT: LD A,(HL)
        OR A
        RET Z
        INC HL
        LD E,A
        PUSH HL
        LD C,CONOUT
        CALL BDOS
        POP HL
        JR PRINT

; **** Get place in string ****
PLSTRG: LD A,(HL)
        INC HL
        SUB JOH
        CALL TIME10
        LD B,A
        LD A,(HL)
        SUB JOH
        ADD A,B
        CALL TIMES3
        SUB Z
        RET

; **** Multiplication routines ****
TIME10: RICA LD B,A
        RICA ADD A,B
        RET

; **** Multiply by 2 ****
TIME11: RICA LD B,A
        RICA ADD A,B
        RET

; **** Multiply by 2 again ****
TIME12: RICA LD B,A
        RICA ADD A,B
        RET

; **** and again ****
TIME13: RICA LD B,A
        RICA ADD A,B
        RET

; **** Save the partial product ****
TIME14: RICA LD B,A
        ADD A,B
        RET

; **** Multiply by 2 ****
TIME15: RICA LD B,A
        ADD A,B
        RET

; **** Add the partial product ****
TIME16: RICA LD B,A
        ADD A,B
        RET

```

DRIVE ROUTINES FOR THE GEMINI GM822 RTC MODULE N-80 14 Sep 1982 14:48 PAGE 1-6

DRIVE ROUTINES FOR THE GEMINI GM822 RTC MODULE M-80 14 Sep 1982 14:48 PAGE 1-7

```

***** Set RTC from ASCII values at ARG0 *****  

***** Arguments are in the form HH:MM DD/MM.D *****  

*****  

; **** D0ED' CD 00F0' SET: CALL INDATA ; Get PIOs out of reset state  

; **** D1F0' CD 00F9' CALL INADR  

; **** A0' D1F5' XOR A ; Set non test mode  

; **** D1F4' 16 ED LD D, TEST+NOSTRB  

; **** D1F4' 1E 40 LD E, TEST+WRSRTRB  

; **** D1F8' OF 1D LD C, PADDR  

; **** D1F9' CD 0121' CALL WRITE  

; **** D1FA' 21 00BB LD HL, MONTH ; Get the month across ...  

; **** D1FD' LD 02B0' LD DE, WSPACE ; ... to the register workspace  

; **** D0200' 11 02BB' LD LDI  

; **** D0203' ED A0 LD LDI  

; **** D0205' ED A0 LD LDI  

; **** D0207' 3A 008E LD A,(IDWK) ; Get day of the week  

; **** D020A' 12 LD (DE),A  

; **** D020B' 13 INC DE  

; **** D020C' 21 0088 LD HL, TDAY ; Now the day  

; **** D020F' ED A0 LD LDI  

; **** D0211' ED A0 LD LDI  

; **** D0213' 21 0082 LD LDI  

; **** D0216' ED A0 LD LDI  

; **** D0218' ED A0 LD LDI  

; **** D021A' 23 TNC HL ; ... end the mins  

; **** D021B' ED A0 LD LDI  

; **** D021D' ED A0 LD LDI  

; **** D021F' CD 0151' CALL WRTC  

; **** D0222' 21 006C' LD HL,STMES  

; **** D0225' CD 01C3' CALL PRINT  

; **** D0228' OF 01 C, CONIN  

; **** D022A' CD 0005 CALL BIOS  

; **** D022D' 21 008D' LD HI,CRLF  

; **** D022F' CD 01C3' CALL PRINT ; ... to start  

; **** D0230' 21 006C' LD A,1 ; Start the RTC  

; **** D0233' 3E 01 LD D, START+NOSTRB  

; **** D0235' 16 EE LD E, START+WRSRTRB  

; **** D0237' 1E 4B LD C, PADDR  

; **** D0239' 03 1D CALL WRITE  

; **** D023B' CD 0121' BPP

```

```

0254: CD 0C3' CALL PRINT
0255: 18 F3 JR RTC1 ; Else, read clock
0256: CD 0C4' CALL TIME
0257: ED 7B 0C7' LD SP,(STK) ; Get the stack back
0258: C9 RETN ; Back to CP/M

; *****
; ***** Get and validate input *****
; *****

0261: 21 0000' VALID: LD HL,TIMES ; Put up the caption
0262: CD 01C3' CALL PRINT
0263: 21 0080 LD HL,ARGS-2 ; Put the max string length at
0264: 36 19 LD (HL),25
0265: EB DE,HL ; Point to the input buffer
0266: 0E 0A LD C,LININ
0267: CD 0005 CALL BDOS ; Get the input
0268: 21 00BD LD HL,CRLF
0269: CD 01C3' CALL PRINT
0270: 21 0082 LD HL,ARGS
0271: CD 0075 CALL A,(HL) ; Test for time
0272: 7E LD CP 'T'
0273: FE 54 JR NZ,VALID1 ; No, so validate input
0274: 20 02 XOR A ; Yes, so clear any <C> flag
0275: AF RETN ; Done

; Validate the input string, and convert to nibbles
; Do hours and mins, then days and months, then day of w
; Point to ARGS in <DE>
; Point to validation table
; Do it 4 times
; Get the input
; Test if less than 0 ...
; ... or greater than (HL)
; Point to next (HL) for next
; Ok so convert to BCD nibble
; Put it back in workspace
; Point to next input ...
; ... and do it all again

0282: EB VALID1: EX DE,HL ; HL,INVAL
0283: 21 00AE' LD HL,INVAL
0284: 06 04 LD B,4
0285: 0A,DE' LD A,(DE)
0286: 00,DE' LD O,(DE)
0287: 1A,DE' LD A,(DE)
0288: FE 30 INC C,ERR
0289: 38 25 CP (HL)
0290: BE INC HL
0291: 23 INC NC,ERR
0292: 30 21 SUB 30H
0293: 12 LD (DE),A ; Put it back in workspace
0294: 13 INC DE ; Point to next input ...
0295: 1A,DE' LD A,(DE)
0296: FE 30 CP O,(DE)
0297: D6 30 JR C,ERR
0298: 38 18 LD (HL)
0299: BE INC HL
0300: 23 INC NC,ERR
0301: 30 14 SUB 30H
0302: D6 30 LD (DE),A
0303: 12 INC DE ; Skip the interdigit gap
0304: 13 INC DE ; More ?
0305: 15 INC DE
0306: 10 E3 DJNZ VALID2 ; Do the day of the week, same as before
0307: LD A,(DE)
0308: 00,DE' LD C,ERR

```

```

DRIVE ROUTINES FOR THE GEMINI GM822 RTC MODULE      M-80   14 Sep 1982  14:48  PAGE 1-8
PAGE 1          READ ROUTINE FOR THE GM822 RTC M-80   11 Oct 1982  10:49  PAGE 1

0248'    38 08          JR      C,EER      *Z80
02AA'    BE             CP      (HL)
02AB'    30 05          JR      NC,ERR
02AD'    D6 30          SUB    30H
02AF'    12             LD      (DE),A
02B0'    18 02          JR      VALID3
; Error trap
02B2'    37             ERB:  SCF      ; Set the <C> flag to say error
02B3'    C9             RET
; All valid, so set clock
02B4'    CD 01ED'       VALID3: CALL SET
02B7'    C9             RET      ; All done
; *****
; ***** Work spaces
; *****
02B8'    00             WRKSPC: DEF B 0           ; Interrupt / status
02B9'    00             DEF B 0           ; Stop / start
02BA'    02             DEF B 2           ; Leap year status
02BB'    WSPACE: DEF S 12            ; Copy of RTC registers
02C7'    STK:  DEF S 2           ; Stack save space
02C9'    02             DEF S 10          ; Stack space
02D9'    STACK:          RET
END      RTC

DRIVE ROUTINES FOR THE GEMINI GM822 RTC MODULE      M-80   14 Sep 1982  14:48  PAGE S
PAGE 1          Macros:
Symbols:
0OFF      ALLIN
001C      BASE
0001      CONIN
008D      CRLF
00B7      DYSTRG
01B2      HMS
008E      IDWYK
008B      IMONTH
000F      INSTAT
000A      LF
0000      ALLOUT
0005      BDOS
0002      CONOUT
0040      DAY
0088      ERMES
0090      HOURS
0082      IHOURS
0099      INADDR
0010      INTOUT
000A      LININ
00E0      NOSTRB
001D      PADDR
0010      PCDATA
012E      PRINT
0080      RDRTBL
0245      RTC1
02D9      SPACK
006C      STMES
01E3      TIME10
0000      TFLMES
0288      VALID2
0288      VALID3
0151      WRSPC
02B8      WSTRBL
0040      WSPACE

Macros:
        *GLOBAL. TIME
        *BASE      EQU     1CH      ; Base address of control PCI
        *PORT ASSIGNMENTS
        ; Port assignments
        PCMDR  EQU     BASE+0  ; Data port for commands
        PADDR   EQU     BASE+1  ; Data port for commands
        PCDATA  EQU     BASE+2  ; Control port for data
        PCADDR  EQU     BASE+3  ; Control port for data
        ; Control instructions
        CMODE   EQU     ORPH   ; Control mode
        ALLIN   EQU     OFPH   ; All inputs
        INTOUT  EQU     10H    ; All out except INT input
        ; Addresses for MM58174
        TMONTH  EQU     12     ; Addresses for MM58174
        NOSTRB  EQU     OEOH   ; No strobe or select
        RDSTRB  EQU     80H    ; Read strobe on
        ; *****
        ; PIO control subroutines *****
        ; Set data port to control mode, all lines input
        INDATA: LD      A,CMDR  ; Control mode
                 OUT    (PCADDR),A ; Set mode word
                 LD      A,ALLIN  ; Set direction
                 OUT    (PCDATA),A ; Set direction
                 RET
        ; Set command port to control mode, all lines input
        INADDR: LD      A,CMDR  ; Control mode
                 OUT    (PCADDR),A ; Set mode word
                 LD      A,ALLIN  ; Set direction
                 OUT    (PCDATA),A ; Set direction
                 RET
        ; Ensure all data 1's
        OUTADDR: LD      A,OFFH  ; Ensure all data 1's
                  OUT    (PADDR),A ; ... will be 1's
                  LD      A,CMDR  ; Set mode
                  OUT    (PCADDR),A ; Set direction
                  LD      A,INOUT  ; Set direction
                  OUT    (PCDATA),A ; Set direction
                  RET
        ; Set command port to control mode, all lines output
        EXCPT:  LD      A,OFFH  ; EXCPT the INT line (0B4H)
                 OUT    (PADDR),A ; Set mode word
                 LD      A,CMDR  ; Set mode
                 OUT    (PCADDR),A ; Set direction
                 LD      A,INOUT  ; Set direction
                 OUT    (PCDATA),A ; Set direction
                 RET
        ; Set command port to control mode, all lines output
        OUT:    LD      A,OFFH  ; Ensure all data 1's
                 OUT    (PADDR),A ; ... will be 1's
                 LD      A,CMDR  ; Set mode
                 OUT    (PCADDR),A ; Set direction
                 LD      A,INOUT  ; Set direction
                 OUT    (PCDATA),A ; Set direction
                 RET

```

No Fatal error(s)

```

READ ROUTINE FOR THE GM322 RUC M-80 11 Oct 1982 10:49 PAGE 1-1

*****
; **** Subroutine to read to the MM28174
; **** Called with:-
;   C=PADR - data port for command
;   D=RUC register address
;   E=RUC reg. + strobe (R or W)
; **** Read a MM28174 register
; **** Set up address
; **** Read strobe on
; **** Read a nibble
; **** Strobe off

***** READ: OUT (C),D ; Set up address
          OUT (C),E ; Read strobe on
          IN A,(PDATA) ; Read a nibble
          OUT (C),D ; Strobe off

001F' ED 51
0021' ED 59
0023' DB 1C
0025' ED 51
0027' C9

```

READ ROUTINE FOR THE GM822 RTC M-80 11 Oct 1982 10:49 PAGE 1-2

```

***** Subroutine to read to the MM58174
***** Called with:-
    O=PADDR = data port for command
    D=RTC reg. address
    E=RTC reg. + strobe (R or W)
    H=Mn Sc form:- Mth.Dy.Hr Mn.Sc

***** Read a MM58174 register
    JAD: OUT    (C),D      ; Set up address
          OUT    (C),E      ; Read strobe on
          IN     A,(PDATA)   ; Read a nibble
          OUT    (C),D      ; Strobe off
    RET

***** Routine to read the RTC registers
***** to work space in RAM at (HL)
    ORTC: CALL   QUADDR    ; Set command port to o/p
          CALL   INDATA    ; Set data port to i/p
          LD    HL,(PTR)
    LD    B,12       ; 12 registers to read
    LD    D,TMONTH+NOSTRB ; 10's of months + no strobe
    LD    E,TMONTH+RDSTRB ; 10's of months + read strobe
    LD    C,PADDR    ; C = control port address
    READ: CALL   RDRTCL   ; Get the data
    AND   OFH        ; Isolate the lower nibble
    CP    OFH        ; Valid?
    JR    Z,RDRTC    ; No, so start again
    LD    (HL),A      ; Store in workspace
    INC   HL
    DEC   D          ; Next RTC register
    DEC   E          ; Loop if more
    DJNZ  RDRTCL    ; Done
    RET

***** Convert nibbles into single byte
***** READ ROUTINE FOR THE GM622 RTC M-80
    TIME0: RLCA    ; Multiply by 2
          LD    B,A      ; Save the partial product
          RLCA    ; Multiply by 2 again
          RLCA    ; Multiply by 2 again
          ADD   A,B      ; Add the partial product
    RET

    TIME: LD    E,(HL)    ; Get the address of TM$0
          INC   HL
          LD    D,(HL)
          DE,HL
          (PBR),HL
          LD    (PBR),HL
          CALL  NDATA    ; Set PIOs to RESET state
          EX
          LD    EB
          005B
          005C
          005D
          005E
          22 007B
          CD 0000
          CD 0009
          CD 0028
          006A
          2A 007E
          006D
          54
          006E
          5D 0049
          ED A0
          0072
          0074
          0076
          0077
          0078
          0079
          007B
          007D
          007E
          PTR: DEFS 2
    END

***** READ ROUTINE FOR THE GM622 RTC M-80
    11 Oct 1982 10:49 PAGE S
    BASE 0049' BCD2BN
    INADR 0000' INDATA
    NOSTRB 0012' QUADDR
    PCADDR 001E' PCDATA
    PTR 0028' RDRTC
    RDSTRB 0080' READ
    TIME1 0056' TIME1
    TIME2 0050' TIME2
    TIME3 0051' TIME3
    TIME4 0052' TIME4

***** Macros:
    Symbols:
    00FF ALLN
    0009' CMODE
    0010 INTOUT
    0011 PADDR
    0012 PDATA
    0039' RDRCL
    001C BASE
    0009' INADR
    00E0 NOSTRB
    001D PCADDR
    001F PTR
    0080 RDSTRB
    0049' BCD2BN
    0012' QUADDR
    001E' PCDATA
    0028' RDRTC
    0056' READ
    0050' TIME1
    0051' TIME2
    0052' TIME3
    0053' TIME4

```

00049:	7E
0004A:	23
0004B:	CD
0004C:	0054,
0004D:	46
0004F:	23
00050:	80
00051:	12
00052:	13
00053:	59

```
*****; **** Convert nibbles into single byte *****;
```

PAGE S

READ ROUTINE FOR THE GM622 RTC M-80 11 Oct 1982 10:49

Macros:

Symbols:	001C	BASE	C049'	BCD2BN
C0FF	ALLIN	0009'	0000'	INDATA
C0FF	CMODE	00E0	0012'	QUADDR
C010	INTOUT	001F	001E'	PCDATA
C01D	PADDR	007E'	0028'	RDRTC
C01C	PDATA	0080	001F'	READ
C039'	RDTCL	0076'	0054'	TIME10
C00A'	RDSTRB	0000	0000	TIME1
C00C'	RDSTRT	0000	0000	TIME0

Macros:	Symbols:
	00FF
	0OFF
	0010
	001D
	001C
	0039'
	005AI'
	000C

No Fatal error(s)

NASCOM PROGRAM LIBRARY

When 80-BUS News absorbed INMC80 we also acquired a quantity of programs from the program library. We now need the valuable space that they are occupying and so here are some offers that you can't refuse!! All of the programs are ones which were sent in by INMC members and are source code listings on A4 paper. In order to dispose of them quickly we are offering them at 'giveaway' prices, but must insist on a minimum program order of £1. As we run out of certain lines we will make up the value of the order with alternative programs. Postage is 30p per UK order and 60p overseas.

These offers hold until January 31, 1983 and after that date the program library will be permanently closed.

NasSys Programs

S2	Reaction Test	OC80-OFAD	0.20
	When the random digit appears, press the same digit on the keyboard.		
	Better than 0.6 seconds is good - how good are you?		
S3	Bouncing Beastie	OC80-OFCF	0.05
	A character bounces around the screen leaving a trail behind it.		
S4	Reverse	OC80-OF99	0.25
	Arrange the randomly generated list of numbers in order in the fewest moves by reversing any number of them at a time.		
S5	Double Mastermind	OC80-OFB9	0.35
	Try and crack the Nascom's four digit code while it tries to crack yours. (It won't let you cheat!)		
S7	JJ	OC80-OEOF	0.20
	Enter the machine code of this before looking to see how it works.		
	Written to demonstrate machine code string handling.		
S8	Unizap	OC80-OED9	0.25
	Recreate the life of the Universe. Take it from the 'big bang' to its 'ultimate destiny' by shooting stars.		
S9	Random Buzz-word Linker	OC80-OF3E	0.20
	Short of jargon? Then use the 'Functional flexibility' of this program to give you 'limited transitional communication' in your 'balanced digital engineering' !!		
S10	Quiz Program (+Italian file)	OC80-ODCB (+ODDO-OFD5)	0.25
	What is Italian for 'please' or English for 'Fratello'? Find out with this quiz. Also additional files (see below).		
S11	Cockney Rhyming Slang (for S10)	ODDO-OFD6	0.10
S12	Currency Types (for S10)	ODDO-OFC0	0.10
S13	Capital Cities (for S10)	ODDO-OFE1	0.10
S14	Ship Game	OC80-OFA4	0.30
	Blow up ships using your torpedoes. Ships come at random speed, distance & direction.		
S15	Hangman	OC80-OFA4	0.25
	Can you guess the word before you are hung? Can add own words.		
S16	Memory Test 1	OFOO-OF6F	0.10
	Tests for addressing faults		
S17	Memory Test 2	OFOO-OF61	0.10
	Tests for bit faults/pattern sensitivity.		
S24	Octal-Hexadecimal Conversion	OC80-OCE8	0.10
S28	Decimal-Hexadecimal Conversion	OC80-OD2B	0.15
S34	Random I-Ching Characters	OC80-OD25	0.10
	Great mystical significance (for those who understand these things).		
S36	Sub-Search	OC80-ODA3	0.20
	Ship traverses screen dropping random depth charges on randomly moving submarines.		

Nasbug Programs

T1	Crash	OC50-0FC9	0.35
	Land the spacecraft. Real time. Can you make NASA proud of you.		
T2	Reaction Test (as S2)	OC50-0FCC	0.25
T3	Bouncing Beastie (as S3)	OD00-0DAB	0.10
T4	Reverse (as S4)	OC60-0F88	0.25
T5	Double Mastermind (as S5)	OC50-0FD5	0.30
T6	Possum	OD00-0D84	0.10
	The hex digits are displayed and then flash one at a time. By pressing any key the character corresponding to the code will be displayed.		
T7	JJ (as S7)	OC50-0DE5	0.20
T9	Random Buzz-words (as S9)	OC50-0F35	0.20
T10	Quiz Program + Italian (as S10)	OC50-0DAA	0.25
T21	TV Test Pattern	OD00-0D19	0.05
	Displays test pattern to set up TV.		
T22	NIM	OD00-0FC4	0.45
	The classic game of NIM.		
T23	Attack	OD00-0E7F	0.20
	Shoot the descending aliens before they get you!		
T24	Octal-Hexadecimal (as S24)	OD00-0DBC	0.15
T26	24 Hour Digital Clock	OD00-0D7B	0.15
T28	Decimal-Hexadecimal (as S28)	OC90-0D07	0.10
T29	Life	OC50-0FA0	0.20
	The ubiquitous simulation of Life, using special characters to give an expanded universe. Very fast.		
T31	Compact Editor	OF70-0FDF	0.05
T32	Carre Chinois	OC50-0F3F	0.40
	We have no idea of what this game is or what it does. But it is totally written and extensively commented in French!		
T33	Lollypop Lady Trainer	OC60-0F95	0.50
	A classic! See if you can get the chickens across the road without them getting run over.		
T34	Random I-Ching (as S34)	OC50-0CF3	0.15
T35	Walled Chase.	OC50-0E27	0.50
	One player chases another, but there are invisible walls in the way which appear when you hit them. Compulsive.		
T36	Sub-Search (as S36)	OEOB-0F31	0.25
T37	Random Display	OC60-0C84	0.05
	Random patterns of asterisks.		
T38	Submarines	OC60-0E50	0.40
	Hit the randomly displayed submarines with your steerable depth charges.		
T39	Burst The Balloon	OC50-0E02	0.50
	Shoot the balloons as they make their way up the screen at the mercy of random breezes. Frustrating.		

Nascom 8K BASIC Programs

B1	Hello	0.15
	Is your problem health, sex (yes please), money or your job? Let this fun program make some suggestions.	
B2	Russian Roulette	0.15
	Will you or your Nascom survive as you take it turns to fire a revolver at yourselves?	
B4	Cubist Art	0.05
	Impress the neighbours with the artistic capability of your Nascom. Sort of animated wallpaper. (Graphics ROM required.)	
B6	Calender	0.05
	Enter the year required (between 1601 and 2399) and let the Nascom calculate and display the calender for that year.	

B8	Eliza	0.35
	With this program loaded, your Nascom is especially trained in psychoanalysis. What are your particular hangups?	
B9	Camel	0.25
	You have stolen the priceless idol belonging to a tribe of knock-kneed pygmies. They want it back and are in hot pursuit. Can you reach safety before the pygmies (or wild Neringi Berbers) catch you?	
B10	Comrade X	0.50
	You are the premier of the communist island of Niatrib. You must decide your country's budget, harvest and economic strategy. You have 8 years in office, can you survive before the peasants revolt or you are exiled (or worse)!	

Please indicate clearly what programs you want, e.g. S3, T3 or B3 along with some possible alternatives. Add up the program costs, plus the postage charge, and send cheques, money orders, postal orders, payable to '80-BUS News' to:

Program Offers, Interface Data Ltd., Oakfield Corner, Sycamore Rd.,
Amersham, Bucks. HP6 5EQ.

Modifying Nascom RAM A board for 2732 EPROMs

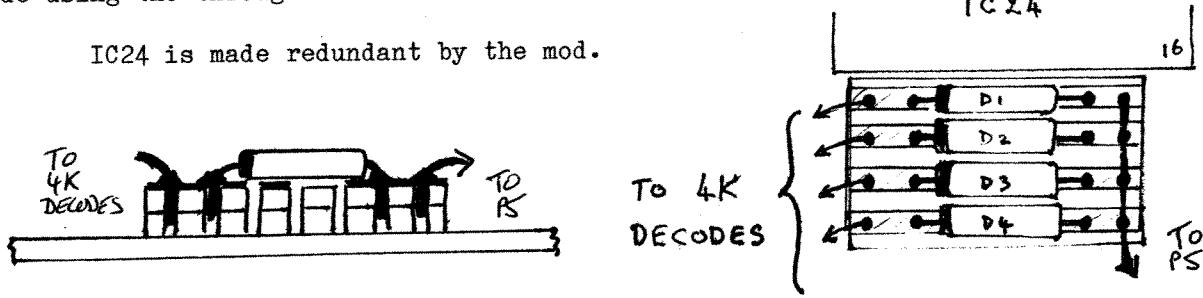
John Harrison

I decided to modify my system to take 4K EPROMs, and having read the two articles in INMC80-5 I chose the RAM board as an easier mod. than the main board. In practice, it turned out to be rather more complicated by the time I had it working.

The published scheme covered 2K and 4K chips, but the 4K version will not work. The problem with taking the 4K decodes direct to the chip selects (p20) instead of using them to enable IC24, is that P5 also drives the data highway buffer, IC26. There are two ways around this: P5 can be driven with 4 wire ORed 4K decodes and IC24 fed with A13 and A12 and used to drive the chip select lines, i.e. the 2K scheme but bigger. Alternatively the decodes can be taken direct to the chip select lines, and diode ORed to P5. The advantage of this approach is that it gives freedom to choose any set of addresses, whereas the other method constrains the 4 blocks used to have different values of A12/A13, e.g. to be 4 contiguous blocks. With 32K of RAM and a toolkit in 2 x 1K EPROMs at B000 I could not accept this constraint.

The problem then was where to lose 4 diodes, neatly. After some thought, I mounted them on a minimally sized piece of 0.1" Verostrip which just fitted between IC24 and the decode pads. I araldited this copper side up onto the board which could just be done without covering any tracks. To allow room for the tails of the diode leads, I used an extra thickness of Veroboard as a spacer. The rest of the modification is as the original one except that I cut the tracks to IC27 pins 19 and 21 on the non component side. This allowed the links to be added also on that side using the through hole thus made available.

IC24 is made redundant by the mod.



The occasion may arise when you want to use a Gemini Galaxy (or Nascom + IVC) as a terminal on another computer system. Some communications programs exist for this, but they often include a host of non-essential features, and do not always do exactly what you require. One program I have used and can recommend is Ward Christensen's MODEM7. I have used this successfully in conjunction with a 300 Baud modem for exchanging files over the PSTN (Public Switched Telephone Network). Another great point in it's favour is that it is Public Domain software and is available on a CP/M user group disk (vol. 47) in source form and at low cost.

However if the computer to which you wish to communicate is close at hand, then the two machines are likely to be connected together directly via the RS232 serial interfaces. In this environment (with no intervening modems) high baud rates can be used, (eg 9600 baud), but problems will immediately be encountered as a result. This is due to the fact that while the IVC is scrolling the screen in response to a line-feed character, (a process which takes a few milliseconds), it can't respond to any commands, although it will accept and store any characters sent to it. As a result a conventional "echo" program would miss incoming characters while waiting for the IVC to respond to a "keyboard poll" request. (At 9600 baud the characters can come at a rate of approximately one per millisecond).

A hardware "handshake" on every character received over the RS232 interface would be a way around this problem, ensuring that no characters are sent unless the Galaxy is ready to accept them, but if you're connected into anything other than a similar CP/M micro it may be impossible to implement. But luckily on the Galaxy it is a relatively simple task to program round the problem, and this is illustrated in the listing of REMOTE below. REMOTE is a "bare bones" program that will turn your intelligent Galaxy into a dumb terminal. I have used it to turn a Galaxy into a 9600 baud terminal on a larger minicomputer system.

The program uses a first-in first-out buffer (FIFO) to get round the problem mentioned above. It polls the incoming UART register at every available opportunity, and if a character is found there, it is transferred to the FIFO. The main program loop checks the keyboard for a character, and if one is found it is sent out via the UART. It then checks to see if there is any data in the FIFO, and if there is it transfers the next character from there to the IVC. The loop then repeats.

This program can be used as the basis for a more comprehensive package. For example I have a version that performs the following:

If Control/I is typed on the keyboard then the FIFO pointers are not zeroed once the characters have been displayed. (i.e. the incoming characters are stored in the buffer and not discarded.)

If Control/D is typed the FIFO pointers are zeroed and the Control/I ("Insert") mode is switched off.

If Control/W is typed then the current contents of the FIFO buffer are appended to a previously specified disk file and the FIFO pointers are then zeroed.

If Control/E is typed then the output file is closed and the program returns to the CP/M command level.

Once again these extensions are fairly straightforward to add, and enable the user to keep a selective record of the session on the terminal. The "bare bones" are here, flesh them out to suit your requirements!

```

*250
title Remote terminal emulation
;
; Remote terminal Emulation for GEC 4065.
;

escape equ 1bh ; 8250 data port
uartd equ 0B8h ; 8250 status port
uart5 equ 0B1h ; IVC data port
ivrd equ 0B2h ; IVC status port
ivcs equ 0B3h ; IVC data port
ivc5 equ 0B4h ; IVC status port

***** Uart Drivers. *****
;

; POLLU - Polls the Uart and moves any waiting
; character to (DE)
pollu: in a,(uartd) ; Check status
        and 0fh
        ret z ; Return if no character
        in a,(uartd) ; Get it
        and 7fh ; Strip msb
        ld (de),a ; Store in the buffer
        de inc ; Bump pointer
        ld a,d ; Check for limit
        cp 2
        ret nz ; Return if not there
        limit equ $-1 ; Else don't advance pointer
        dec de
        ret

; SEROUT - Outputs the character in <A> to the
; serial port
serout: push af
        in a,(uartd) ; Check ready to accept
        and 20h
        jr z,sero0 ; wait if not
        pop af
        or a
        jp pe,sero1 ; Get character back
        or 80h
        out (uartd),a ; Check parity
        ret

***** IVC drivers *****
;

; GETVID - gets a character from the IVC.
; PUTVID - sends character in <A> to the IVC.
; Both poll the Serial Port while waiting.

getvid: call pollu ; Check for incoming character
        in a,(ivcs) ; See if IVC ready
        rica
        jr c, getvid ; Loop if busy
        in a,(ivcd)
        ret

putvid: push af
        in a,(ivcs) ; Service the serial port
        ; See if IVC ready
        rrca
        jr c,pvo
        pop af
        out (ivcd),a ; Recover character
        ret

; Get a character from the keyboard
; Returns NZ if a character is read
;

const: ld a,escape ; Send ESC "k"
        call putvid
        ld a,'k'
        call putvid
        call getvid ; Read reply
        or a
        ret z ; return if none
        a,escape ; Send ESC "K" to get it
        call putvid
        ld a,'K'
        call putvid
        call getvid ; Read the character
        call op
        op 'C' and 1fh ; ^C?
        ret nz ; No, return with NZ set
        jp 0 ; Yes, abort & reboot
;

***** MAIN LOOP *****
;

; Uses a FIFO buffer to handle the data
; DE = Input pointer HL = Output pointer
;

start: ld sp,stack
        ld a,(7) ; Get buffer limit
        dec a ; (limit),a ; (Make sure we don't clobber BDOS)
        loop0: ld (limit),a ; set the buffer limit
                de,buffer
                hl,buffer
                loop1: ld const
                        call nz,serout ; Check keyboard...
                        push hl ; ...and echo any character
                        or a ; See if anything in the buffer
                        sbc hl,de
                        pop hl ; No, zero pointers
                        jr z,loop0 ; Yes, get character...
                        ld a,(hl)
                        inc hl
                        call putvid
                        jr loop1 ; ...and echo it
;

; Workspace
;

stack: defs 32
        stack: buffer equ $
        end\
```

RANDOM RUMOURS (& TRUTHS)**S. Monger**

I understand that a copy of the latest 'Gemini MultiBoard' leaflet went out with each of the last issues of 80-BUS, and that this has resulted in several comments along the lines of 'What has it to do with me, I'm a NASCOM owner'.....stunned silence.....well, I now wonder if we (at 80-BUS News) should pack up and go home, or if we really have omitted stating the 'obvious' (to us) in this rag. Just in case, here comes an attempt at an explanation :

Once upon a time there was a company called Nascom, producing a micro imaginatively entitled the 'Nascom 1' (N1). Now this micro took the UK market by storm, and lots and lots of them were sold. Then Nascom (NM) decided to expand the N1, and defined the Nasbus system. A memory and an I/O board were produced to fit this bus, and then the more powerful Nascom 2.

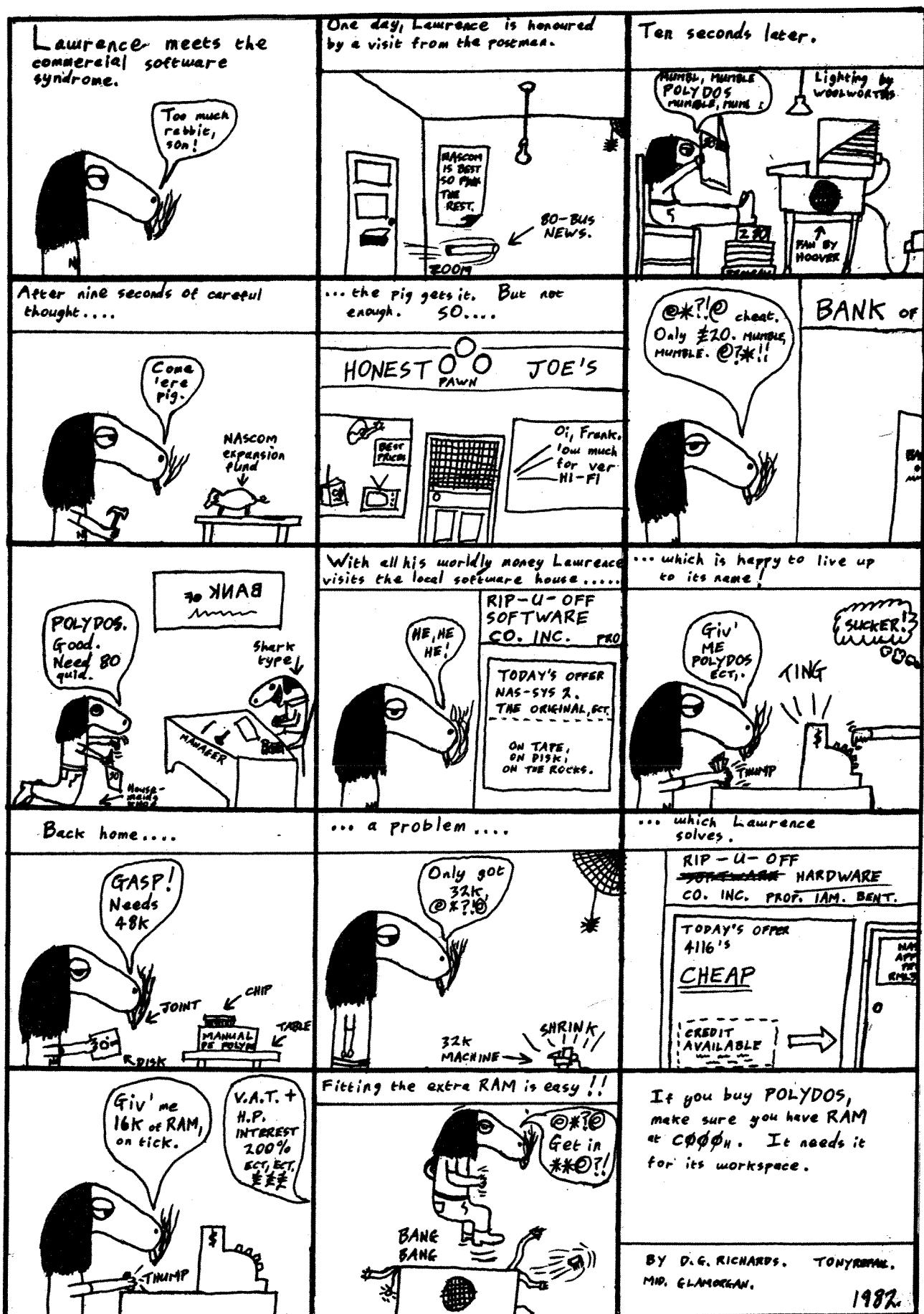
Unfortunately, for a number of reasons, NM went into receivership. Under receivership there was little advertising or production done, as a buyer was sought. Consequently the market waned considerably, and a number of dealers (including one owned by John Marshall (JM), the ex-MD of NM) got together to continue advertising NM products and to promote various 'Nasbus' add-ons of their own. Out of the success of this JM formed Gemini. Unfortunately, as this was occurring, the receiver took a dim view of the dealers using the word 'Nasbus' and started flinging writs around. So Gemini sat down, looked at the somewhat ambiguous definition of Nasbus, redefined and cleared up certain points, and renamed it as 80-BUS, a name chosen not only because of 'Z80' and the '80-way' bus, but also because it is a more generalised name, appropriate for other manufacturers to use as opposed to something like 'Gem-bus'. The 80-BUS spec. was subsequently published in INMC80, issue 4, the predecessor to this rag.

After a year in the receivers hands, NM was bought by Lucas Logic (Spring '81). Then, in my opinion, they proceeded to do 'not a lot' and have never (to date) acknowledged the existance of Gemini. Meanwhile Gemini had produced quite a number of 80-BUS (i.e. Nasbus compatible) products, which sold in large numbers to NM owners, and had also by now produced their own CPU and video cards. This made the Gemini range complete within itself, as well as all expansion cards remaining compatible with NM. With few products coming from NM, the INMC80 magazine found its subscription declining and little to write about and so it moved towards supporting 'the bus' (80-BUS and Nasbus) as a whole, instead of dedicating itself to the one manufacturer's products. In January '82, 80-BUS News was created, absorbing INMC80.

So, having wandered slightly off track, I hope that it is now obvious to all that Gemini 80-BUS expansion products shown in their catalogue, along with those from EV Computing, Arfon, IO Research and Microcode also shown in the catalogue, are in fact usable in expanding Nascom 1, 2 and 3 systems.

Well, having waffled on about that for so long I now have little room left for my usual tripe. I was going to tell you that Mike York has now implemented the UCSD system on the Nascom, and is currently doing it for the Gemini. Not that I know anything about UCSD, other than the fact that it has the usual flavour of nutty but avid followers, and that it is an alternative to the CP/M operating system. I was also going to tell you that Mike Ayres (ex. Sales Manager of Tandy) now holds the same title with Lucas Logic (Nascom) - ex. sales manager. Furthermore, I was going to mention that Gemini Winchester units (mentioned last iss.) are now a reality (only for MultiBoard/ Micropolis & Galaxy systems at the moment, although they will be producing alternative software - write to them saying what system YOU want to add one to). I was also considering mentioning the availability of a 256K RAM board from MAP Systems (and don't expect it to remain the only large RAM board), as well as the fact that Gemini are about to release a new CP/M BIOS containing virtual disk support, screen dump capability, and stand-alone terminal mode.

I might even have mentioned CP/M 3 - but there just isn't room!!



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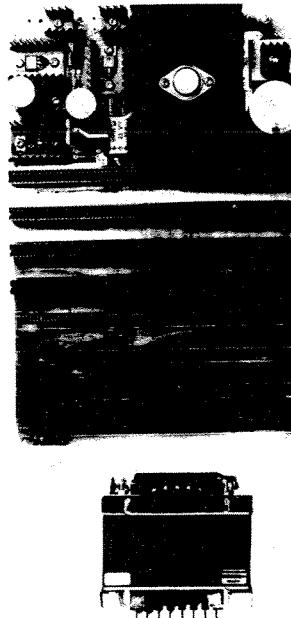
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