## Lagrange multipler method

Example: cost minimitation

Firms produce output by combining K, L

- cost function:
  - · labor : per unit cost w = #4
  - · capital:
  - => TC(K,L) = w.L+r.K = 4L+2K
- production function:

  Q (K, L) = 5 K 1/3 L 2/3
- Objectue:

produce Q = 100 at minimal cost!

 $\Rightarrow$  min TC(K,L) st: R(K,L) = 100

four steps

(2) 
$$F_{L} = 4 + \lambda \cdot \frac{2}{3} 5 \kappa'''^{3} L^{2/3}$$
  
 $F_{K} = 2 + \lambda \frac{1}{3} 5 \kappa^{2/3} L^{2/3}$   
 $F_{L} = 5 \kappa''^{3} L^{2/3} - 100$ 

(3) 
$$\lambda \cdot \frac{2}{3} \sum_{k} |x|^{1/3} |x|^{-1/3} = -4$$
 (1)

$$\lambda \cdot \frac{1}{3} = -2$$
 (2)

plug K=L into  $F_{\lambda}$  and set equal to zero:  $5K^{1/3}K^{2/3} - 100 = 0$ 

$$ax_1 + bx_2 = h$$

$$c x_1 + d x_2 = k$$

can be written compactly:

$$AX = B$$

$$\rightarrow X = \frac{B}{A}$$

where:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$B = \begin{bmatrix} h \\ k \end{bmatrix}$$

constant matrix

Solving linear equation systems using augmented matrices

solve: 
$$3x_1 + 4x_2 = 1$$
  
 $x_1 - 2x_2 = 7$ 

Define: augmented (coefficient) matix

Elementary row operations

An argumented coefficient matrix can be transformed into a row-equivalent matrix by performing any of the following 3 sperations:

(iii) add a constant multiple of one row to another row 
$$(cR_j + R_i \hookrightarrow R_i)$$

Objective:

$$\begin{bmatrix} 1 & 0 & 1 & m \\ 0 & 1 & 1 & m \end{bmatrix}$$

$$\begin{bmatrix} 1 \cdot x_1 + 0 \cdot x_2 = m \\ 0 \cdot x_1 + 1 \cdot x_2 = n \end{bmatrix} \Rightarrow \begin{cases} x_1 = m \\ x_2 = n \end{cases}$$

back to example

$$R_1 \hookrightarrow R_2 \Longrightarrow \begin{bmatrix} 1 & -2 & | & 7 \\ 3 & 4 & | & 1 \end{bmatrix}$$

$$-3R_1 + R_2 \iff R_2 \implies \begin{bmatrix} 1 & -2 & 1 & 7 \\ 0 & 10 & 1 & -20 \end{bmatrix}$$

$$\frac{1}{10} R_2 \leftrightarrow R_2 \Rightarrow \begin{bmatrix} 1 & -2 & 1 & 7 \\ 0 & 1 & 1 & -2 \end{bmatrix}$$

$$2R_2 + R_1 \leftrightarrow R_1 \Rightarrow \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \end{bmatrix}$$

$$= \begin{cases} x_1 = 3 \\ x_2 = -2 \end{cases}$$

## Example

$$6x_2 + 2x_1 = -3$$
  
 $x_1 + 3x_2 = 2$ 

$$A = \begin{bmatrix} 2 & 6 \\ 1 & 3 \end{bmatrix}$$

$$B = \begin{bmatrix} -3 \\ 2 \end{bmatrix} \qquad X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$-2R_1 + R_2 \longrightarrow R_2 \Rightarrow \begin{bmatrix} 1 & 3 & \vdots & 2 \\ 0 & 0 & \vdots & -7 \end{bmatrix}$$

$$|ast row:$$

$$0 \cdot x_1 + 0 \cdot x_2 = -7$$

$$\Rightarrow contradiction$$

=> inconsistent, no solution

$$2x_1 - x_2 = 4$$
  
 $-6x_1 + 3x_2 = -12$ 

$$\frac{1}{2}R_1 \leftrightarrow R_1 \Rightarrow \begin{bmatrix} 1 & -\frac{1}{2} & \frac{1}{2} \\ -6 & 3 & \frac{1}{2} - 12 \end{bmatrix}$$

$$6R_1 + R_2 \Leftrightarrow R_2 \Rightarrow \begin{bmatrix} 1 & -\frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} ast & row : \\ & & & \\ & & \\ & & & \\ & & \\ & & & \\ &$$

-> not a conhadiction

$$\frac{\text{from first row:}}{1 \cdot x_1 - \frac{1}{2} x_2 = 2}$$

for example: if  $x_2 = 4$  then  $x_1 = 4$ more general: if  $x_2 = t$  then  $x_1 = 2 + \frac{1}{2}t$  $\Rightarrow$  set of solutions:

> infinitely many solutions

in last 3 examples

-> what about more general/bigger equation systems?

## Gauss-Jordan Elimination

Example: 
$$x_3 + 2x_1 - 2x_2 = 3$$
  
 $3 x_1 - x_3 + x_2 = 7$   
 $-3x_2 + x_1 + 2x_3 = 0$ 

urik as: 
$$AX = B$$
 where  $X = \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix}$ 

$$\Rightarrow A = \begin{bmatrix} 2 & -2 & 1 \\ 3 & 1 & -1 \\ 1 & -3 & 2 \end{bmatrix} \quad \begin{bmatrix} 3 = \begin{bmatrix} 7 \\ 7 \\ 0 \end{bmatrix}$$

$$R_1 \leftrightarrow R_3 \Rightarrow \begin{bmatrix} 1 & -3 & 2 & | & 0 & 7 \\ 3 & 1 & -1 & | & 7 \\ 2 & -2 & 1 & | & 3 \end{bmatrix}$$

$$-3R_1 + R_2 \Leftrightarrow R_2 \Rightarrow \begin{bmatrix} 1 & -3 & 2 & | & 0 \\ -2R_1 + R_3 \Leftrightarrow R_3 \Rightarrow \begin{bmatrix} 0 & 10 & -7 & | & 7 \\ 0 & 4 & -3 & | & 3 \end{bmatrix}$$

$$\frac{1}{10}R_{2} \iff R_{2} \implies \begin{bmatrix} 1 & -3 & 2 & 1 & 0 & 7 \\ 0 & 1 & -7/10 & 7/10 \\ 0 & 4 & -3 & 3 \end{bmatrix}$$

$$3R_{2}+R_{1} \iff R_{1} \implies \begin{bmatrix} 1 & 0 & -1/10 & | & 21/10 \\ 0 & 1 & -7/10 & | & 7/10 \\ -4R_{2}+R_{3} \iff R_{1} & \begin{bmatrix} 0 & 0 & -2/10 & | & 21/10 \\ 0 & 0 & -2/10 & | & 21/10 \end{bmatrix}$$

$$-5R_3 \leftrightarrow R_3 \implies \begin{bmatrix} 1 & 0 & -\frac{1}{10} & \frac{21}{10} \\ 0 & 1 & -\frac{7}{10} & \frac{7}{10} \\ 0 & 0 & 1 & 1 -1 \end{bmatrix}$$

$$\frac{1}{10}R_3 + R_1 \iff R_1 \implies \begin{bmatrix} 1 & 0 & 0 & 1 & 2 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & -1 \end{bmatrix}$$
 reduced form makix
$$x_1 = 2$$

$$x_2 = 0$$

$$x_3 = -1$$

## Definition:

- A makir is said to be in reduced form if
  - (i) each row consisting entirely of zeros is below any row having at less tone nonzero element.
  - (ii) the leftmost nonzero dement in each row is 1
  - (iii) all other elements in the column containing the leftmost 1 of a siven row one zero.
  - (:v) the leftmost ( in any row is to the right of the leftmost ) in the row above.

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}$$

ang. coeff. mahix:

$$-2R_1+R_2 \leftrightarrow R_2 \Rightarrow 0 0$$

$$-1R_1+R_3 \leftrightarrow R_3 \Rightarrow 0$$

$$-2R_{1}+R_{2} \leftrightarrow R_{2} \Rightarrow \begin{bmatrix} 1 & 2 & 4 & 1 & -1 & 1 & 1 \\ 0 & 0 & 0 & 1 & -2 & 1 & 0 \\ -1R_{1}+R_{3} \leftrightarrow R_{3} & \leftrightarrow R_{3} & \begin{bmatrix} 0 & 1 & 3 & -1 & 4 & 1-3 \end{bmatrix}$$

$$R_2 \hookrightarrow R_3 \implies \begin{bmatrix} 1 & 2 & 4 & 1 & -1 & 1 & 1 \\ 0 & 1 & 3 & -1 & 4 & 1 & -3 \\ 0 & 0 & 0 & 1 & -2 & 1 & 0 \end{bmatrix}$$

$$\Rightarrow 1_{X_1} + 0_{X_2} - 2_{X_3} + 0_{X_4} - 3_{X_5} = 7$$

$$0_{X_1} + X_2 + 3_{X_3} + 0_{X_4} + 2_{X_5} = -3$$

$$0_{X_1} + 0_{X_2} + 0_{X_3} + x_4 - 2_{X_5} = 0$$

$$(=) \quad x_1 = 7 + 2x_3 + 3x_5$$

$$x_2 = -3 = 3x_3 - 2x_5$$

$$x_4 = 2x_5$$

If we let  $x_3 = s$  and  $x_5 = t$ then for any set  $\in \mathbb{R}$ 

$$x_1 = 7 + 2s + 3t$$
 $x_2 = -3 - 3s - 2t$ 
 $x_4 = 2t$ 
 $x_3 = s$ 
 $x_5 = t$