VisionWorks™ **CUDA Accelerated Computer Vision Library** May 2016

VisionWorks™ at a Glance



CUDA accelerated library

(OpenVX primitives + NVIDIA extensions + Plus Algorithms)



Flexible framework for seamlessly adding user-defined primitives. Interoperability with OpenCV



Thread-safe API



Documentation, tutorials, sample software pipelines that teach use of primitives and framework

VisionWorks™ Supported Platforms

Automotive



JETSON TK1 Pro → Drive PX2

Embedded



JETSON TX1



JETSON TK1

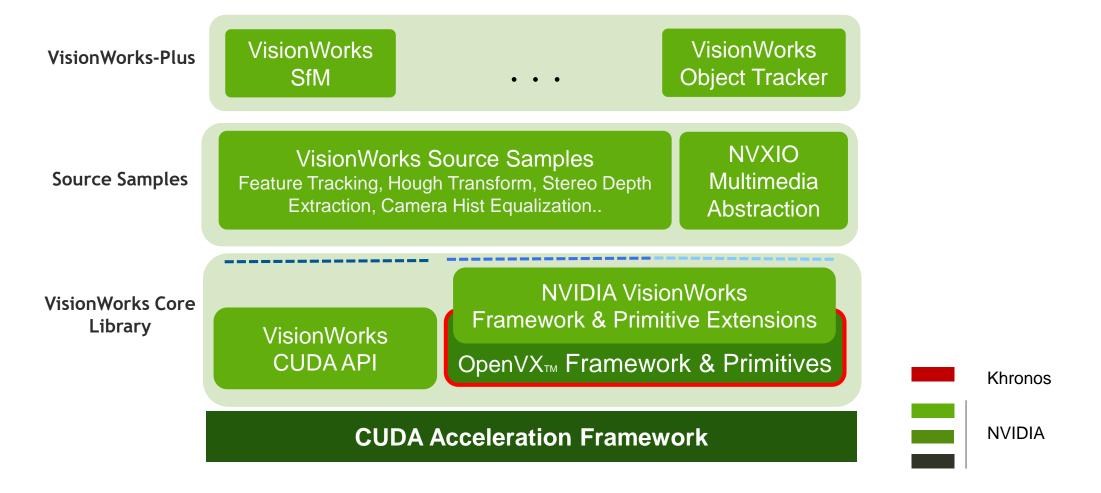
Desktop



Ubuntu Linux 14.04, Windows 8



VisionWorks™ Toolkit Software Stack



VisionWorks™ Primitives

All OpenVX **Primitives**



NVIDIA **Extensions**

IMAGE ARITHMETIC

Absolute Difference Accumulate Image Accumulate Squared Accumulate Weighted Add/ Subtract/ Multiply + **Channel Combine** Channel Extract Color Convert +

Copylmage

Convert Depth Magnitude MultiplyByScalar Not / Or / And / Xor Phase Table Lookup **Threshold**

FLOW & DEPTH

Median Flow Optical Flow (LK) + Semi-Global Matching Stereo Block Matching **IME Create Motion Field IME Refine Motion Field** IME Partition Motion Field

GEOMETRIC TRANSFORMS

Affine Warp + Warp Perspective + Flip Image Remap Scale Image +

FILTERS

BoxFilter Convolution Dilation Filter **Erosion Filter** Gaussian Filter Gaussian Pyramid Laplacian3x3

Median Filter Scharr3x3 Sobel 3x3

FEATURES

Canny Edge Detector FAST Corners + **FAST Track** Harris Corners + Harris Track **Hough Circles Hough Lines**

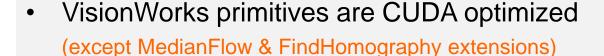
ANALYSIS

Histogram Histogram Equalization Integral Image Mean Std Deviation Min Max Locations

- + type/mode extension by NVIDIA
- NVIDIA extension primitives

VisionWorks™ Primitives

All OpenVX Primitives



85% of VisionWorks OpenVX API is also accelerated with NEON.
Table of NEON optimized primitives are listed in VisionWorks Toolkit Ref.

(Go to "VisionWorks API" -> "NVIDIA Extensions API" -> "Vision Primitives API")



- Primitive acceleration with VisionWorks
 - Up to 92x speedup compared to OpenCV CPU kernels on Drive PX (Ave 8x)
 - Up to 13x speedup compared to OpenCV CUDA kernels on Drive PX (Ave 2x)

(Measured on Drive PX, OS='V4L' Linux Kernel='3.18.21-tegra-g06aec38'

CPU Rate='1632 MHz' GPU Rate='844 MHz' EMC Rate='1600 MHz')

NUDIA. VISIONWORKS

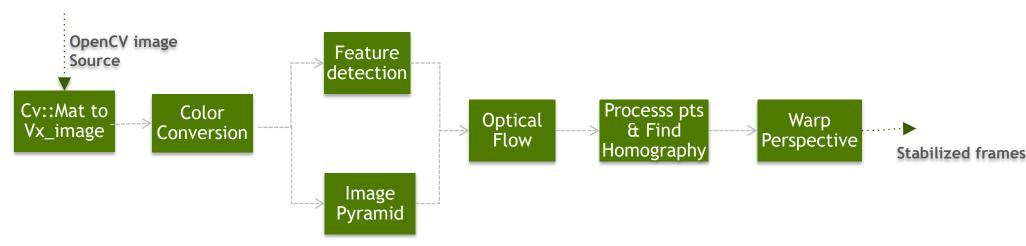
Programming with VisionWorks Library

VisionWorks OpenVX™ Immediate Mode

Video STABILIZATION SAMPLE

OpenVX Immediate mode API (prefixed as vxu) enables developers to easily port their applications.

Ported Video Stabilization algorithm in OpenCV-CUDA to VisionWorks Immediate Mode.

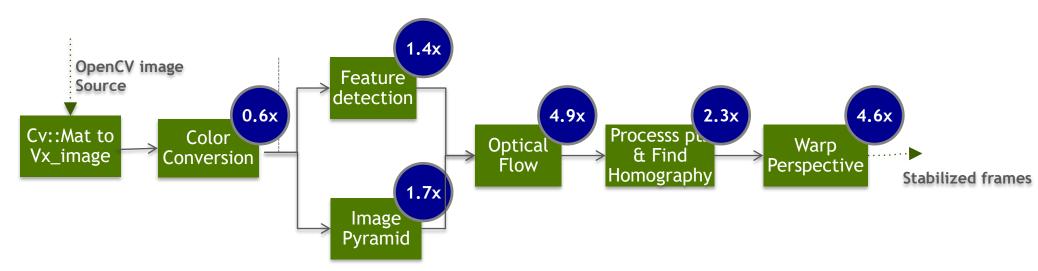


VisionWorks OpenVX™ Immediate Mode

Video STABILIZATION SAMPLE

Performance boost: Video stabilization application is accelerated by 2.6x

(including the overhead for Mat to vx_image conversions)

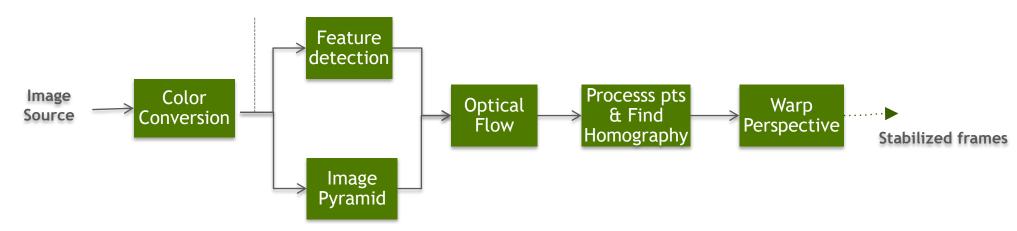


VisionWorks OpenVX™ Graph MODE

Video STABILIZATION SAMPLE

OpenVX Graph API (prefixed with vx) enables advanced optimizations

- Buffer reuse
- Efficient use of streaming and CUDA textures
- Automatic scheduling across processing units based on various factors (safety, perf,..)
- Tiling and pipelining vision functions at sub-frame level

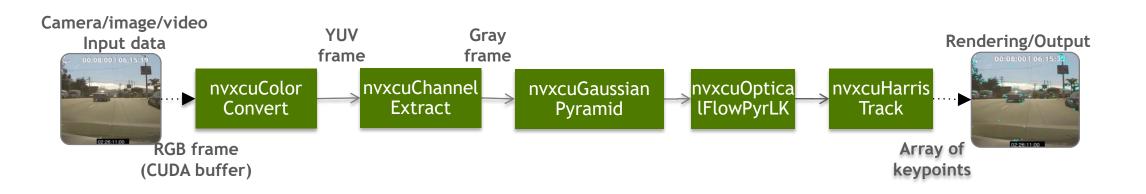


VisionWorks CUDA API

FEATURE TRACKING SAMPLE

VisionWorks CUDA API enables developer with low-level access. Developer manages

- Data allocations and transfer
- Scheduling and pipelining



VisionWorks™ API Selection



VisionWorks OpenVX™ Immediate Mode

Quick port from other libraries

One can reassign CPU and GPU tasks based on perf.

VisionWorks OpenVX™ Graph Mode

Let the graph manager to hide overheads, optimize and manage data

One can reassign CPU and GPU tasks based on perf.

VisionWorks CUDA API

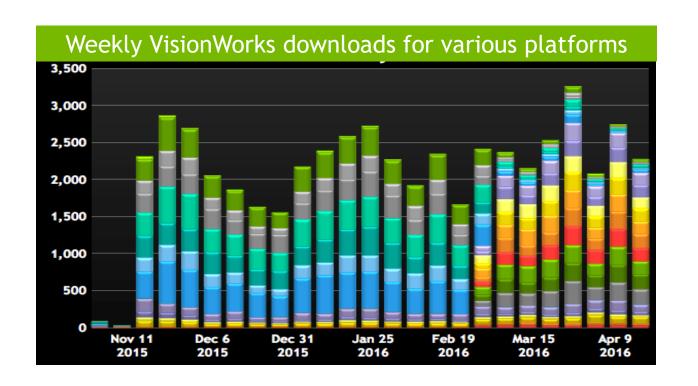
Low level CUDA API access for advanced CUDA developers



VisionWorks™ Conclusion

NVIDIA.

- First Khronos OpenVX™ 1.0 compliant library (Jan 2015)
- Optimization and visualization
- 45K downloads since release in Nov 2015.



Resources & Useful Links



http://www.embedded-vision.com/

https://www.khronos.org/openvx/

https://developer.nvidia.com/embedded/visionworks

VisionWorks Webinars - https://developer.nvidia.com/embedded/learn/tutorials