# Introduction to Bayesian learning

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### Learning

 We are given a set of observed data assumed to be generated from some distribution.

$$X := (x_1, \dots, x_n) \overset{\text{i.i.d.}}{\sim} p_{\text{true}}(x). \tag{1}$$

- Since we don't have an access to  $p_{\text{true}}(x)$ , we setup a model  $p(x;\theta)$  defined with a parameter  $\theta$ .
- Now we select  $\theta$  that best describes the observed data X through  $p(x;\theta)$ .

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#### Learning

- Best describes?  $p(x;\theta)$  should be close to  $p_{\text{true}}(x)$  .
- · A popular example maximum likelihood.

$$\mathbb{D}_{\mathrm{KL}}[p_{\mathrm{true}}(x) \| p(x;\theta)] = \int p_{\mathrm{true}}(x) \log \frac{p_{\mathrm{true}}(x)}{p(x;\theta)} \mathrm{d}x$$

$$= -\mathbb{E}_{p_{\mathrm{true}}(x)}[\log p(x;\theta)] - \mathbb{H}[p_{\mathrm{true}}(x)]$$

$$\approx -\frac{1}{n} \sum_{i=1}^{n} \log p(x_i;\theta) + \mathrm{const.}$$
 (2)

#### Model

- A simplified representation of (random) phenomenon with mathematical language.
- "All models are wrong, but some are useful." George E. P. Box.
- · How do we know whether a model is good enough?
- · How can we compare different models?

# Bayesian learning

• It all began from a simple formula.

$$p(B|A) = \frac{p(A|B)p(B)}{p(A)}. (3)$$

• Bayesian learning: treat  $\theta$  as a random variable with prior  $p(\theta)$ , and compute its posterior  $p(\theta|X)$  after observing data.

$$p(\theta|X) = \frac{p(X|\theta)p(\theta)}{p(X)} = \frac{p(\theta)\prod_{i=1}^{n}p(x_i|\theta)}{p(X)}.$$
 (4)

#### Frequentism vs Bayesianism

#### Frequentists

- Probability is a limiting frequency of an event happening over repeated experiments.
- Parameter  $\theta$  is a fixed value, and it is meaningless to define the frequency of  $\theta$  (and thus  $p(\theta)$ ).
- We are interested in doing repeated experiments for X (even if it is hypothetical).

#### Bayesian

- Probability is quantification of uncertainty for some event.
- It is natural to define an uncertainty of a parameter  $\theta$  as  $p(\theta)$ .
- We are interested in the uncertainty of  $\theta$  after observing data X the posterior  $p(\theta|X)$ .
- We are not particularly interested in the uncertainty of X because we have observed it.

#### Coin toss example

· Say we have observed a set of outcomes from a coin toss.

$$X = (x_1, \dots, x_n), \quad x_i \in \{H, T\} \text{ for } i = 1, \dots, n.$$
 (5)

· We assume a very simple Bernoulli model.

$$p(x = \mathsf{H}; \theta) = \theta, \quad \theta \in [0, 1]. \tag{6}$$

• We want to estimate the parameter  $\theta$ .

- Believing that our simple model is correct, there should be only one parameter  $\theta$  that could have generated X.
- · Define an estimator  $\hat{\theta}_X$  by maximizing the log-likelihood.

$$\hat{\theta}_X := \arg\max_{\theta} \sum_{i=1}^n \log p(x_i; \theta) = \frac{\sum_{i=1}^n \mathbb{1}_{\{x_i = H\}}}{n}.$$
 (7)

•  $\hat{\theta}_X$  would approach  $\theta$  as we observe more and more data (do more coin tosses).

- It is perfectly natural to define a probability of  $\hat{\theta}_X$ , because we can do repeated experiments to compute them.
- In other words,  $\hat{\theta}_X$  itself is a random variable, with mean and variance computed as

$$\mathbb{E}_{p_{\text{true}}(X)}[\hat{\theta}_X] = \theta, \quad \text{Var}_{p_{\text{true}}(X)}[\hat{\theta}_X] = \frac{\theta(1-\theta)}{n}.$$
 (8)

· By the central limit theorem,

$$\frac{\hat{\theta}_X - \theta}{\sqrt{\frac{\theta(1-\theta)}{n}}} \stackrel{d}{\to} \mathcal{N}(0,1). \tag{9}$$

By the law of large numbers,

$$\hat{\sigma}_X^2 := \frac{\hat{\theta}_X (1 - \hat{\theta}_X)}{n} \xrightarrow{p} \frac{\theta (1 - \theta)}{n}. \tag{10}$$

· By the Slutsky's theorem,

$$\frac{\hat{\theta}_X - \theta}{\hat{\sigma}_X} \stackrel{d}{\to} \mathcal{N}(0, 1), \tag{11}$$

and thus the Confidence Interval (CI) at level  $\alpha$  (100(1 -  $\alpha$ )% CI) is computed as

$$\Pr\left(\hat{\theta}_X - Z_{1-\frac{\alpha}{2}}\hat{\sigma}_X < \theta < \hat{\theta}_X + Z_{1-\frac{\alpha}{2}}\hat{\sigma}_X\right) \to 1 - \alpha, \tag{12}$$

where  $Z_a$  is the inverse CDF of  $\mathcal{N}(0,1)$ .

- Does this mean that the probability of  $\theta$  being included in the crist  $1-\alpha$ ?
  - No!  $\theta$  is a fixed value. What's varying is the data X (and thus the cromputed from X).
  - So, the correct interpretation is, if we compute cis for many datasets X generated from  $p_{\text{true}}(x)$  over and over again, the fraction among those containing  $\theta$  would approach  $1 \alpha$ .
  - · Does that sound intuitive?

# Coin toss example - a Bayesian approach

• Believing that our model is true, we represent our uncertainty about  $\theta$  as a prior distribution.

$$p(\theta) = \text{Beta}(\theta; a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \theta^{a-1} (1-\theta)^{b-1}.$$
 (13)

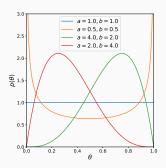


Figure 1: PDF of beta distribution with various parameters.

# Coin toss example - a Bayesian approach

 Luckily, the posterior after observing X is still a Beta distribution, with parameters

$$p(\theta|X) = \text{Beta}\left(\theta; a + \sum_{i=1}^{n} \mathbb{1}_{\{x_i = H\}}, b + \sum_{i=1}^{n} \mathbb{1}_{\{x_i = T\}}\right).$$
 (14)

 $\cdot$  The Credible Region (CR)  $[L_X,U_X]$  at level lpha is defined as

$$\int_{L_X}^{U_X} p(\theta|X) d\theta = 1 - \alpha.$$
 (15)

• This requires a numerical approximation, but can directly be interpreted as, the probability of  $\theta$  (after observing X) contained in  $[L_X, U_X]$  is  $1 - \alpha$ !

# Model selection for regression

- Assume we have a dataset  $\mathcal{D} := (X, Y) = \{(x_i, y_i)\}_{i=1}^n$ .
- We assume that  $\mathcal{D}$  was generated from some function  $y=f_{\theta}(x)$  plus some additive noise.

$$p(y|x;\theta) = \mathcal{N}(y|f_{\theta}(x), \sigma_y^2). \tag{16}$$

• What would be a proper form of  $f_{\theta}(x)$ ?

$$f_{\theta}(x; \mathbf{m}_1) = \theta_0 + \theta_1 x. \tag{17}$$

$$f_{\theta}(x; \mathbf{m}_2) = \theta_0 + \theta_1 x + \theta_2 x^2. \tag{18}$$

#### Model selection for regression

· Is it right to compare the maximum likelihoods of models?

$$\max_{\theta} p(Y|X;\theta,\mathfrak{m}_1) < \max_{\theta} p(Y|X;\theta,\mathfrak{m}_2)? \tag{19}$$

· No, as you all might know, the infamous overfitting issue.

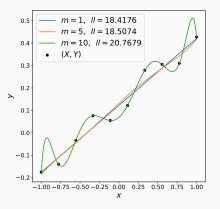


Figure 2: Maximum likelihood fits with various degrees.

### Model selection for regression - frequentist approaches

- This happens because we don't take the model complexity into account.
- Akaike Information Criterion (AIC): penalize complex models (k : number of parameters).

$$AIC(\mathfrak{m}) = 2k - \max_{\theta} \log p(Y|X; \theta, \mathfrak{m}). \tag{20}$$

- · Alternative approaches: create more samples.
  - · Cross-validation.
  - · Bootstrapping.
- Also devise model-specific statistics whose distribution is well understood and easy to compute.

### Model selection for regression - a Bayesian approach

 In Bayesian model, we can naturally define the marginal likelihood or evidence of data by averaging over all possible parameters.

$$p(Y|X;\mathfrak{m}) = \int p(Y|X,\theta;\mathfrak{m})p(\theta)d\theta.$$
 (21)

• We can even treat the model  $\mathfrak m$  as a random variable, and compute the posterior probability of the model.

$$p(\mathfrak{m}|X,Y) = \frac{p(Y|X,\mathfrak{m})p(\mathfrak{m})}{p(Y|X)}.$$
 (22)

# Model selection for regression - a Bayesian approach

• To compare two models, we compute the Bayes factor.

$$\frac{p(Y|X,\mathfrak{m}_1)}{p(Y|X,\mathfrak{m}_2)}. (23)$$

 Likewise, this requires a numerical approximation (sometimes given analytically though), but we can intuitively compare two different models without additional metrics, datasets (cross-validation), and model-specific statistics.

### Frequentism vs Bayesianism - summary

#### Frequentism

- · Probabilties are limiting frequencies.
- Everything makes sense under the context of repeated experiments.
- · Model parameters are fixed.
- In some sense, current data X is not that important!
- Rather awkward definition of confidence interval, and requires some care for model comparison.

#### Bayesianism

- · Probabilities are uncertainties.
- Naturally defines uncertainties of parameters and even models via probabilities.
- Intuitive definitions of confidence (credible region) and model comparison (Bayes factor).
- · Computations may be non-trivial.

#### Why I'm a Bayesian?

- In my opinion, it is more close to human way of learning concepts.
  - We have an initial knowledge, and it gets updated once we observe data.
  - · Sequential update rule.

$$p(\theta|X_1, X_2) = \frac{p(X_2|\theta)p(\theta|X_1)}{p(X_2|X_1)} = \frac{p(X_2|\theta)p(X_1|\theta)p(\theta)}{p(X_2|X_1)P(X_1)}.$$
 (24)

- Freedom to think of probabilities or uncertainties of non-trivial concepts (e.g., Bayesian nonparametric models)
- General principle for model assessment and comparison (I don't think the computation is the issue).
- · It's cool.

#### Why uncertainty matters?

- · Importance of knowing what you don't know.
  - · Uber incident.
  - Racist algorithm by Google.
  - · Medical diagnosis and decision making with financial data.
- Uncertainty guided sequential decision making
  - · Bayesian optimization.
  - · Reinforcement learning.
  - · Active learning.

# Elements of Bayesian learning

- We have a data X. We setup a model  $\mathfrak{m}$  with a parameter  $\theta$ .
- Inference: compute  $p(\theta|X)$ .

$$p(\theta|X) = \frac{p(X|\theta)p(\theta)}{p(X)}.$$
 (25)

• Prediction: for a new data  $x_*$  and a function of interest f,

$$p(f(x_*)|X) = \int p(f(x_*)|\theta)p(\theta|X)d\theta.$$
 (26)

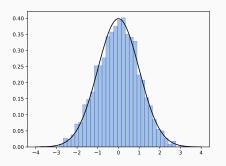
• Model comparision and criticism (posterior predictive checks, Bayes factors, ...).

### The most useful identity

Monte-Carlo estimator of expectation.

$$\frac{1}{n} \sum_{i=1}^{n} f(x_i) \stackrel{P}{\to} \mathbb{E}_{p(x)}[f(x)] = \int f(x)p(x) dx, \tag{27}$$

where  $x_1, \ldots, x_n \overset{\text{i.i.d.}}{\sim} p(x)$ .



**Figure 3:** Monte-Carlo approximation for  $\mathcal{N}(0,1)$ .

#### **Recommended Readings**

- http://jakevdp.github.io/blog/2014/03/11/ frequentism-and-bayesianism-a-practical-intro/
- http://www.stat.cmu.edu/~larry/=sml/Bayes.pdf