1. Maximum sum in binary tree as the constraint would be adjacent nodes cannot be picked so each time iterating the binary tree, the optimal solution would be take that node or not take it if we take that node, we must take the grandchildrens in order to maximize the sum if we don't take that node, we must take the both childrens since they are not adjacent and the condition of taking the node or not would be Let A be the binary tree with A[0] is the root node $\max((A[0] + A[3] + A[4] + A[5] + A[6]), A[1] + A[2])$ and this would be the simplest form to solve this kind of problem extend to solving the general problem Let dp[n] to be the array storing the maximum of n node can get initialize all 0 function $\max Sum(node)$

base case if no node then return

if dp[index of node] not equal to zero means this node has been get the optimal solution so return

max sum from left left child = maxSum(node.left.left)

max sum from left right child = maxSum(node.left.right)

max sum from right left child = maxSum(node.right.left)

max sum from right right child = maxSum(node.right.right)

max sum from grandchildren = (maxSum(node.left.left)+
maxSum(node.left.right)+maxSum(node.right.left)+maxSum(node.right.right))

```
max sum from left child = maxSum(node.left)
max sum from right child = maxSum(node.right)
```

since we either choose grandchildren or both children so the return would be maximum between them adding the optimal solution in $dp[index\ of\ node]$

 $return \max((node + max sum from grandchildren), (max sum from left child + max sum from right child))$ The initial call would be maxSum(A[0])

since this algorithm will iterate each node once so the time complexity would easily be taken as O(n)

```
2. Longest increasing path in 2D Matrix
since every time the path can only go downward or rightward
for the optimal solution if M[i,j] < M[i+1,j] or M[i,j] < M[i,j+1]
then M[i, j] must include in the solution and the largest path accumulated from right or down plus 1
so the algorithm just need to recursively doing this condition checking
Let dp[n][n] initialized as same size with M and all element to be 1
global \ variable \ Longest = 0
define a function LIP(inputting i, j)
       boundary and base case check
       if i > n or j > n then return
       if dp[i][j]! = 1 then this cell has been checked so return
       recursively call function
       LIP(i + 1, j)
       LIP(i, j + 1)
       if i + 1 < n \text{ and } M[i][j] < M[i + 1][j]
              save the optimal solution in dp[i][j]
              dp[i][j] = max(dp[i][j], dp[i + 1][j]) + 1
       if j + 1 < n \text{ and } M[i][j] < M[i][j + 1]
              dp[i][j] = max(dp[i][j], dp[i][j+1]) + 1
       compare the longest to dp[i][j] to check whether dp[i][j] have a better length then longest
       longest = max(longest, dp[i][j])
the initial call would be LIP(0,0)
after running the whole LIP function call
global variable longest would be the longest path
For the time complexity
this LIP function recursively run over each element from M once
as if dp[i][j]! = 1 would stop the LIP function from calling the checking element again
```

For the space complexity

this algorithm require a array ap same size as M n by n and one more global variable longest so the space complexity would be $n^2 + 1 = O(n^2)$

and each time of recursion would do constant time of comparison

such that the LIP function would run in $O(n^2)$ since there are n^2 elements

```
3. Set partitioning
1. this question can be understand as if there is a subset of S have half of sum of S
let dp[i][j] be a array storing if there is a subset of S[1 \text{ to } n] have sum to i
at each time determining if there is a subset equal to i
we can divide it into two situations
1. there is a subset of S[1, j - 1] excluding S[j] have sum to i
2. the sum i can be obtained from a subset of S[1, j-1] + S[j] = i
if both case is false means the set S[1 \text{ to } j-1] cannot have a sum equals to i
Let sum = sum(S)/2
initialize all the part of dp[0][0 \text{ to } n] = true \text{ as } 0 \text{ can be get from empty set}
initialize all the part of dp[1 \text{ to } n][0] = f also as empty set cannot have sum > 0
for i = 1 to sum
        for j = 1 to n
                inherit the previous subset of not including element S[j]
                dp[i][j] = dp[i][j-1]
                if i >= S[j]
                means the sum i can be achieved by subset of S[1, j-1] and S[j] otherwise it is impossible
                because any subset adding S[j] would larger than i
                then either dp[i - S[j]][j - 1] is true or it follow the dp[i][j - 1]
after all the iteration of set S, the dp[sum][n] indicate whether there is a subset of S have half of sum of S
and this will be the answer of this question
For the time complexity
there are sum * n times iterations which is equals to O(sum * n)
for the space complexity
the dp array is created to store every subset S[0 \text{ to } n] to [0 \text{ to } sum] solutions, so it is O(sum * n)
2.
to solve this problem, the algorithm would reuse the algorithm from 1. to build the dp array same as 1.
then create a new iteration as now dp[sum][n] may not be true
so the iteration would keep checking on the largest dp[i] to be true as this would make the difference to be smallest
```

for time complexity since it is the same as iterating all the element and matching with 1 to sum so it is the same as 1.0(sum $\,^*$ n)

if dp[i][n] is true then return and we know i would be the smallest number to sum

Let sum = Sum(S)//2for i = sum to 0

then after returning dp[i][n] would be answer

for space complexity it also uses the dp array to store all the conditions, it is also the same as the 1. to be O(sum * n)

```
4. Continuous subarray partitioning
```

the recurrence for the optimal solution would be each time take a subarray, then search the remaining array each time m=m-1 doing the slicing and returning the max(Sum(subarray), Sum(remaining array)) then try all the subarray and find the minimum of all the max(Sum(subarray), Sum(remaining array))

this is a brutal force to check all the subarray that A divided m times

for introducing the dp solution algorithm need a 2d array dp[n][m] recording for n size subset with slicing m times condition and we can use it to deduce next element's situation first of all need a array S implemented as follow

$$S[1] = A[1]$$

$$For i = 2 to len(A)$$

$$S[i] = A[i] + S[i - 1]$$

and we can easily get the sum of subarray and remain array then use this to do the comparison so each time on a element the algorithm should find the all possible outcomes from all the slicing and find the min

Let i denoted as i^{th} element and j denoted as j^{th} slice

dp[i][j] = min(dp[i][j], max(dp[k][j - 1], S[i] - S[k]));

dp[k][j-1] is indicating the subarray's sum

S[i] - S[k] means the remaining array's sum

the k is looping over from 1 to i to get the minimum of all the possible slicing for subarray of A[1 to i]

so the whole implementation would be

```
for i = 1 to n dp[i][1] = S[i] as doing no slicing the maximum sum would the the accumulating sum S[i] For i = 1 to n For j = 2 to m For k = 1 to i dp[i][j] = min(dp[i][j], max(dp[k][j - 1], S[i] - S[k]));
```

then the value storing in dp[n][m] would be the answer

for time complexity

this algorithm mainly run through n elements and m times partitioning and run in k times recording each time condition since the worst case for k is n times so the whole algorithm run in $O(n^2 * m)$ time

for space complexity

this algorithm created a extra dp array of size $n \times m$ so it takes O(n * m) space