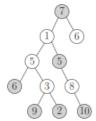
### Question 1 (20%): Maximum sum in binary trees

Given a binary tree where each node has a positive number, describe a dynamic programming algorithm to select the subset of nodes with the maximum sum provided that adjacent nodes cannot be picked. In the following example, the shaded nodes form the optimal solution. For full credits, your algorithm should run in O(n) time, where n is the number of nodes. The algorithm just needs to output the sum, not the actual nodes picked.



#### Solution

Let v(u) be the number of node u. Define s(u) to be the maximum sum achievable for picking nodes from the subtree below (and including) u. Then

$$s(u) = \max \begin{cases} s(u.left) + s(u.right) \\ v(u) + s(u.left.left) + s(u.left.right) + s(u.right.left) + s(u.right.right) \end{cases}$$

# Reasoning:

Case 1 means that we do not take u in the sum so that we take its children

Case 2 means that we take *u* in the sum so that we take its grandchildren

I use an array S[u], to store s(u), so that I do not compute the same value multiple times. The following pseudocode is based on *memorization*.

```
Initialize S[u]=0 for every node u MaxS (root)
```

MaxS(u)

If u is empty Return 0; // node does not exist

If S[u] > 0 Return S[u] // return stored value computed before

Swithout=0; // sum for case 1

Swith=0; // sum for case 2

Swithout= MaxS(u.left) + MaxS(u.right)

Swith = v(u) + MaxS(u.left.left) + MaxS(u.left.right) + MaxS(u.right.left) + MaxS(u.right.right)

If Swithout > Swith S[u]= Swithout

Else [u]=Swith

Return S[u]

## Alternative bottom up solution

I use post-order tree traversal, so that when I need the maximum sum for a node, the maximum sum for each node in its subtree has been computed. Thus, there is no need for recursive calls.

MaxSumTree(root)

For each node u in post-order traversal // the last node will be root

If *u* is a leaf node

S[u]=v(u)

S[u.left]=0; S[u.right]=0 //needed to avoid references to empty cells of S

Else // u is an intermediate node

```
Swithout= S[u.left] + S[u.right]
```

Swith=v(u) + S[u.left.left] + S[u.left.right] + S[u.right.left] + S[u.right.right]

If Swithout > Swith, S[u]= Swithout

else S[u]= Swith

Return S[u]

## Question 2 (20%): Longest increasing path in 2D Matrix

Consider a  $n \times n$  matrix M of distinct integers. We wish to find the longest path in M such that: cell M[i,j] can be reached by moving right from M[i,j-1], or down from M[i-1,j], provided that M[i,j-1] < M[i,j] or  $M[i-1,j] \le M[i,j]$ . The path can start and end in any cell of M. Describe a dynamic programming algorithm that outputs the longest path, and discuss its time/space complexity.

Example: In the following matrix the longest paths are 1,3,5,6 and 2,4,7,8, both with length 4.

M	<i>j</i> =1	<i>j</i> =2	<i>j</i> =3
<i>i</i> =1	2	1	3
i=2	4	7	5
i=3	9	8	6

#### **Solution**

I use L[i,j] to denote the length of the longest path ending at M[i,j], and Keep[i,j] to remember the previous cell that I visited, before reaching M[i,j]

```
Set: M[i,0] = M[0,j] = inf and initialize L[i,j] = 1
If M[i,j] > M[i,j-1] then L[i,j] = \max\{L[i,j], L[i,j-1]+1\}
If M[i,j] > M[i-1,j] then L[i,j] = \max\{L[i,j], L[i-1,j]+1\}
LIP(M, n, W)
Initialize: M[i, 0] = inf for 0 \le i \le n, M[i, 0] = inf for 0 \le j \le n, L[i, j] = 1 for 1 \le i \le n, 1 \le n
j \le n, Keep[i,j] = 0 for 1 \le i \le n, 1 \le j \le n
maxL=1 // longest path found so far
Li=1; Lj=1 // indices i,j for the last cell in the longest path found so far
for i = 1 to n do
      for j = 1 to n do
            If M[i,j] > M[i,j-1]
                  L[i,j] = L[i,j-1]+1 //first time I visit M[i,j]; L[i,j]=1
                  Keep[i,j] = "\leftarrow"
                  If L[i,j] > \max L
                            \max L = L[i,j]; Li = i; Lj = j
            If M[i,j] > M[i-1,j]
                  If (L[i-1,j]+1) > L[i,j] //second time I visit M[i,j]; need to check L[i,j]
                            L[i,j] = L[i-1,j]+1
                            Keep[i,j] = "\uparrow"
                            If L[i,j] > \max L
                                     \max L = L[i,j]; \text{Li}=i; \text{Lj}=j
```

```
Pseudocode for Printing
PrintLIP(i,j)
If Keep[i,j] == 0 RETURN
If Keep[i,j] == "\leftarrow "
PrintLIP(i,j-1)
else // Keep[i,j] == "\uparrow "
PrintLIP(i-1,j)
```

PrintLIP(Li,Lj)

Output(M[i,j]) // print M[i,j]) after the recursive calls so that the path is printed from beginning to end

The running time and space complexity is  $O(n^2)$  since I visit all cells of the matrix and each cell requires constant cost.

### Question 3 (30%): Set partitioning

Let *S* be a set of *n* positive integers.

1] Describe a dynamic programming algorithm that decides whether it is possible to partition S into two subsets SI and S2 that have equal sum. Assume that the sum of all elements in S is even. Describe the time and space complexity, considering that we only need the True/False answer, but not the sets SI, S2.

Example: if  $S = \{3,5,9,1\}$ , then the answer is True ( $SI = \{3,5,1\}$ )  $S2 = \{9\}$ ). If  $S = \{3,5,11,1\}$ , the answer is False.

2] Describe a dynamic programming algorithm that partitions S into two sets S1 and S2 so that the absolute difference between their sums is minimum. Your algorithm should output S1 and S2. Describe the time and space complexity.

```
Example: if S = \{3,5,11,1\}, the answer is SI = \{3,5,1\}, S2 = \{11\}, or SI = \{11\}, S2 = \{3,5,1\}
```

#### **Solution**

1] Let SUM be the sum of all elements in the set. Let W = SUM/2. I will use a Boolean Matrix  $B[0,...,n \times 0,...W]$ . B[i,j] is TRUE if I can have a sum equal to j, using the first i numbers. Boundary conditions: B[0,j]=False, B[0,0] and B[i,0]=True

```
The recurrence is: B[i,j]=B[i-1,j] OR B[i-1,j-n_i] B[i-1,j] means I already have sum equal to j without using n_i. B[i-1,j-n_i] means that I use n_i, so that I must have the sum j-n_i using the first i-1 numbers.
```

The solution is at the cell B[n, W]. The time complexity is nxW and the space complexity n+W because I only need the previous row.

Below is a modified version, based on the subset sum problem, Lecture 17, slides 3-11. In addition, a matrix Keep remembers the items that I take in the sum. Keep[i,j] means that I need element  $s_i$  for sum j. Although not required for part 1, we need Keep for part 2 of the question. In the following pseudocode  $s_i$  represents the i-th element of the set S.

```
SubsetSum(S, n, W)
Initialize: A[i, 0] = True for 0 \le i \le n, A[i, j] = False for 0 \le i \le n, 1 \le j \le W, Keep[i, j] = False for 1 \le i \le n, 1 \le j \le W
for i = 1 to n do

for j = 1 to W do

if s_i > j then // s_i exceeds sum and cannot be taken

A[i, j] = A[i - 1, j]
else // s_i \le j
if A[i - 1, j] = TRUE
A[i, j] = TRUE
Else // A[i - 1, j] = FALSE
If A[i - 1, j - s_i] = True
A[i, j] = True
Keep[i, j] = True // I \text{ need } s_i \text{ for sum } j
```

The running time and space complexity is O(nW) since I need to fill the cells of matrices A and Keep, and each cell requires constant cost.

2] If the pseudocode of part 1 returns True, I can partition into 2 sets with identical sums. If not, I find the last TRUE value in the last row A[n, W'] = True, where W' < W, and this corresponds to the minimum difference. The space requirement including *Keep*, is nxW. The following pseudocode creates the subsets SI and S2 with the minimum difference using the *Keep* matrix of part 1.

```
SI=empty; S2=S;

GenSubset(n, W')

GenSubset(i, j)

If i = 0 \text{ OR } j = 0 \text{ RETURN}

If Keep[i,j] == True

SI = SI \cup \{s_i\}; S2 = S2 - \{s_i\}

GenSubset(i - 1, j - s_i)

Else

GenSubset(i - 1, j)
```

# Question 4 (30%): Continuous subarray partitioning

Given an array A of n positive integers and an integer m (m is much smaller than n), we wish to split A into m **non-empty continuous** subarrays, so that the largest sum among these m subarrays is minimized. Provide the recurrence for the optimal solution, and describe a dynamic programming algorithm and its time/space complexity.

Example: Assume that the input array is A=[7,2,5,10,8] and m=2. There are four ways to split A into two subarrays: (1) [7], [2,5,10,8], (2) [7,2], [5,10,8], (3) [7,2,5], [10,8], (4) [7,2,5,10], [8] The best way is to split it into [7,2,5] and [10,8] because the largest sum between the two subarrays is only 18.

#### **Solution**

```
Let s[j] = \sum_{k=1}^{j} A[k]
```

With this pre-sum array s,  $\sum_{k=i}^{j} A[k] = s[j] - s[i-1]$  can be computed in O(1) time For  $1 \le j \le n$ ,  $j \le i \le m$ , d[i,j] is the optimal value of the subproblem that we split A[1..j] into i non-empty continuous subarrays so that the largest sum among these i subarrays is minimized.

```
Base case: d[1,j] = s[j] (no partition)
Recursive case: d[i,j] = min_{i-1 \le k < j}(max(d[i-1,k],s[j]-s[k]))
```

The last split can be at position i-1 to j-1. When the last split is at position k, this means we have split the array into i-1 subarrays for the first k elements, and d[i-1,k] stores the largest sum among these i-1 subarrays. The sum of the i-th subarray is s[j]-s[k]. So, max(d[i-1,k],s[j]-s[k]) is the largest sum among the i subarrays subject to the last split of A[1..j] is at position k. We simply try all possible k and pick the minimum.

```
CSP(A, n, m)
s[1] = A[1]
For j = 2 to n s[j] = s[j-1] + A[j] // compute pre-sum array s
d[1,1] = A[1]
For j = 1 to n d[1,j] = s[j] // base case for m = 1 (no partitioning)
For i = 2 to m // general case – number of partitions > = 2
For j = i to n // we cannot split if there are fewer elements than partitions (when j < i)
minS = inf
For k = i - 1 to n - 1 // last subbaray is A[k + 1, ..., j]. A[1, ..., k] has i - 1 partitions
kSum = max(d[i - 1, k], s[j] - s[k])
If kSum < minS
minS = kSum; Keep[i,j] = k
OutputSubArrays(A, n, m)
```

-----

OutputSubArrays(A,j,i)While i>0 and j>0OutputSubArrays(A,j-Keep[i,j],i-1)Print elements A[Keep[i,j]]+1 to A[j]

\_\_\_\_\_

The running time is  $O(n^2m)$  because there are O(nm) subproblems (i.e., cells in the 2D array), and each subproblem can be computed in O(n) time.