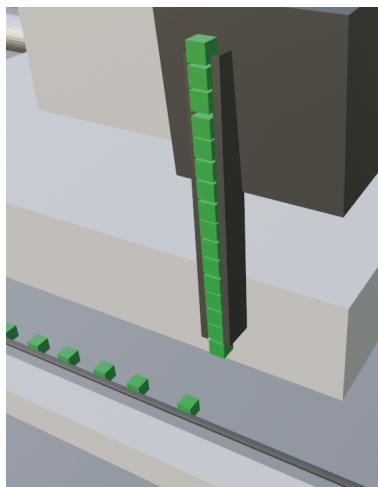


Figure 1 - Ariadne precision sowing robot



Seed cubes are stacked in a tool. The tool traverses the thread, precision glueing the seeds in place.

It is envisaged that the system could autonomously pick seeds from different hoppers, place them in the stack, and then attach them to the thread.

Figure 2 - Seed cube detail view

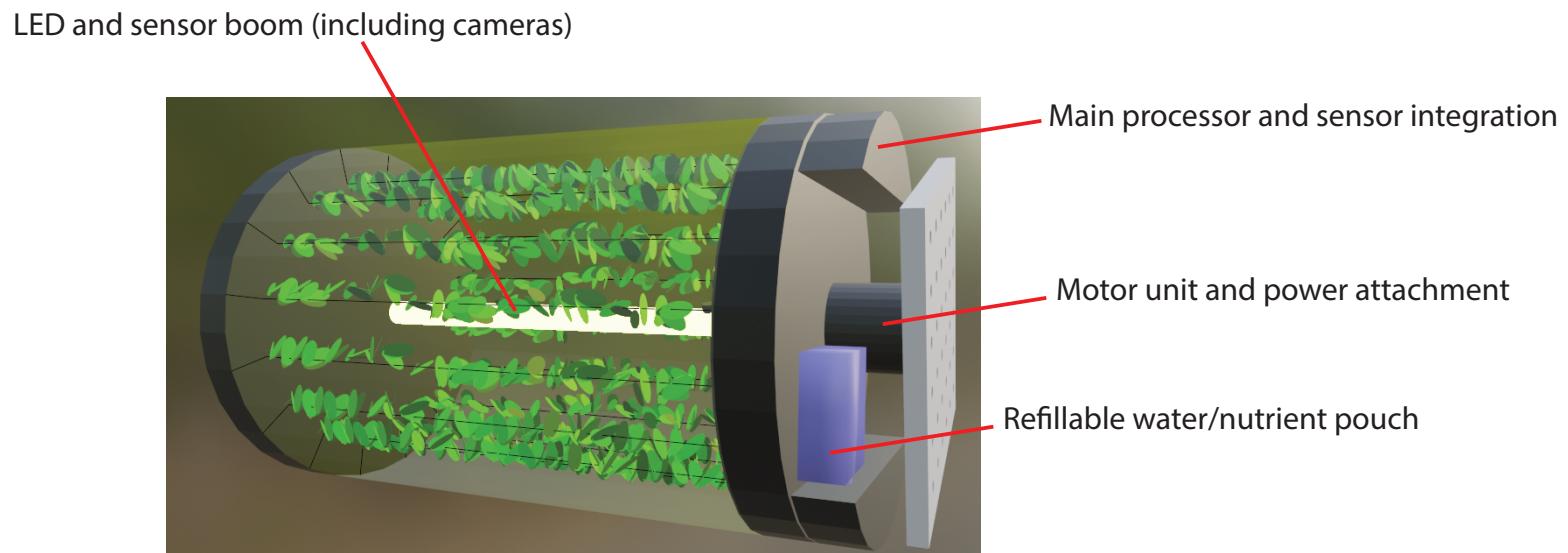
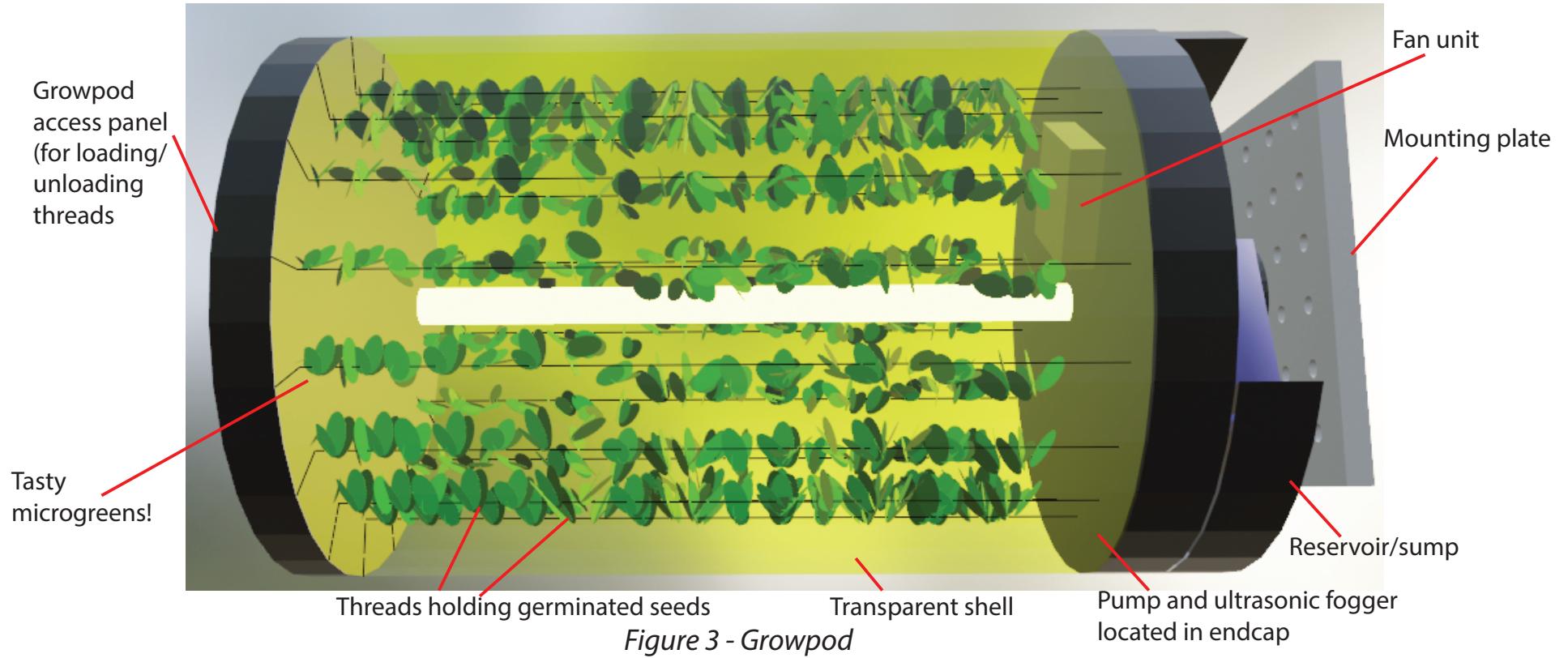


Figure 4 - Growpod end view