

Lab 1

Implementing a solver for systems of linear equations

Due to October 25th 23:45h

Julen Cayero, Cecilio Angulo



Bachelor's Degree in Video Game Design and Development

- 1 Introduction
- 2 Theory review
- 3 Problems

- 4 Lab rules
- 5 Class assignment
- 6 Lab Homework

Outline

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It wouldn't be too difficult to implement a naive solver using the Gauss method.

We will need 2 functions:

- Triangulate a given matrix
- 2 Backtracking of a triangular matrix

However, in practice there are some problems associated with this way of proceeding related with:

- Avoid handling large numbers
- Identify critical cases (Indeterminate or incompatible system)
- 3 Proceed efficiently (we are not going in deep here)



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Naïve Gaussian Elimination Theory review

Gaussian elimination can be easily implemented to solve a system of equations in a simple two step procedure:

I Forward Elimination: Given the matrix \mathbf{A} and the independent term \mathbf{b} as inputs produce a upper triangular matrix \mathbf{A}_t and a independent term \mathbf{b}_t such that

$$\mathbf{A}_t \mathbf{x} = \mathbf{b}_t$$
 and $\mathbf{A} \mathbf{x} = \mathbf{b}$

are equivalent, i.e., share the same solution \boldsymbol{x}

2 Back Substitution (a.k.a Backtracking): Given an upper triangular and regular matrix \mathbf{A}_t and a vector \mathbf{b}_t find the solution \mathbf{x} such that

$$\mathbf{A}_t \mathbf{x} = \mathbf{b}_t$$



Forward Elimination

Convert

$$\begin{array}{c} a_{11}x_1+a_{12}x_2+a_{13}x_3+\cdots+a_{1n}x_n=b_1\\ a_{21}x_1+a_{22}x_2+a_{23}x_3+\cdots+a_{2n}x_n=b_2\\ a_{31}x_1+a_{32}x_2+a_{33}x_3+\cdots+a_{3n}x_n=b_3\\ &\vdots\\ a_{n1}x_1+a_{n2}x_2+a_{n3}x_3+\cdots+a_{nn}x_n=b_n \end{array} \quad \text{into} \quad \begin{array}{c} a_{11}x_1+a_{12}x_2+\cdots a_{1n}x_n=b_1\\ a'_{22}x_2+a'_{23}x_3\cdots a'_{2n}x_n=b_2\\ a'_{33}x_3+\cdots a'_{3n}x_n=b_3\\ &\vdots\\ a'_{nn}x_n=b_n \end{array}$$

Naïve Gaussian Elimination Theory review

Forward Elimination: First Step

The target is to make 0' under a_{11}

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} & b_2 \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} & b_3 \\ \vdots & & \ddots & & & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} & b_n \end{pmatrix}$$

Applying
$$\mathbf{r}_2 = a_{11}\mathbf{r}_2 - a_{21}\mathbf{r}_1$$

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} & b_1 \\ 0 & a'_{22} & a'_{23} & \cdots & a'_{2n} & b'_2 \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} & b_3 \\ \vdots & & \ddots & & & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} & b_n \end{pmatrix}$$

generally applying $oldsymbol{r}_i = a_{11}oldsymbol{r}_i - a_{i1}oldsymbol{r}_1 \quad orall j > 1$

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} & b_1 \\ 0 & a'_{22} & a'_{23} & \cdots & a'_{2n} & b'_2 \\ 0 & a'_{32} & a'_{33} & \cdots & a'_{3n} & b'_3 \\ \vdots & \ddots & & & \vdots \\ 0 & a'_{n2} & a'_{n3} & \cdots & a'_{nn} & b'_n \end{pmatrix}$$



Naïve Gaussian Elimination Theory review

Forward Elimination: next n-1 steps

The second row can be used to make 0's under a'_{22} , followed by the third row to make 0's under a''_{33} and so on.

To make 0's under the pivot a_{pp} located a row p you must modify the row j as:

$$\mathbf{r}_j = a_{pp}\mathbf{r}_j - a_{jp}\mathbf{r}_p \quad \forall j > p$$

Finally achieving

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} & b_1 \\ 0 & a'_{22} & a'_{23} & \cdots & a'_{2n} & b'_2 \\ 0 & 0 & a''_{33} & \cdots & a''_{3n} & b''_3 \\ \vdots & & \ddots & & & \vdots \\ 0 & 0 & 0 & \cdots & a_{nn}^{n-1\prime} & b_n^{n-1\prime} \end{pmatrix}$$

Back Substitution: First step

Solve the last equation

$$x_n = \frac{b_n}{a_{nn}}$$

Back Substitution: Next steps

Proceed visiting each row in decreasing order solving one equation at a time to find the associated unknown

$$x_i = \frac{b_i - \sum_{j=i+1}^{N} a_{ij} x_j}{a_{ii}}$$

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ 0 & a_{22} & a_{23} & \cdots & a_{2n} \\ 0 & 0 & a_{33} & \cdots & a_{3n} \\ \vdots & & \ddots & & & \\ \vdots & & & & \ddots \\ 0 & 0 & 0 & \cdots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{pmatrix}$$

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Handling large numbers Problems

Computer does not like large numbers ¹. Try:

```
1 a = 1E99
2 b = 1E99 + 1
3 c = a-b
```

- Which value do you expect for c?
- What is the value of c that Python throws?

When triangulating, the operation

$$r_j = r_j Aa(p, p) - r_p Aa(j, p)$$

Do not control if the values of A are bounded.

In case you're interested, there are special ways of dealing with those numbers, however it will be complex and computational expensive

Handling large numbers II Problems

Things we can do:

1 Since we can multiply and divide every row by a non-zero number

$$r_j = r_j - r_p Aa(j, p)/Aa(p, p)$$

However we must ensure that A(p,p) is far enough from 0.

2 Since we can choose any row to triangulate, before making the 0's, we will swap the actual row for the row with the largest (absolute value) pivot and proceed as normal.

This is called partial pivoting

Division by 0 Problems

What is the result of applying the previous forward elimination method to solve the system:

$$x + 2y + 3z = 14$$
$$x + 2y - 2z = -1$$
$$y + 2z = 8$$

The solution is again to use the partial pivoting

Identify critical cases Problems

Indeterminate or Incompatible systems of equations?

By maintaining the strategy of selecting the row with the largest pivot, we can check when the pivot \approx 0 which leads to critical cases.

Set a **threshold** value (something small $\approx 1E-8$) and compare the pivot value against it. Consider to warn the user if you identify a very small value for the pivot.



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- Always respect the delivery dates.
- Use the templates when provided and DO NOT MODIFY THE FILE NAMES OR THE FUNCTION NAMES
- Verify that your code works before submit.
- Always upload the files in a .zip with the name structure: Surname1_Name1_Surname2_Name2....zip

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At the end of the class you must deliver

- A working function that performs the bactracking.
- 2 An script making two calls to your function to solve two different (Compatible and Determinate) systems solved in class. One of them must contain at least 4 equations (thus 4 unknowns).

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Before October 25th at 23:45 you must deliver:

- The notebook with the answers to the exercises
- The lab1_functions.py file with your implementations