| OPCODE | u-ins            | STEPS                        |
|--------|------------------|------------------------------|
| NOP    | NOP              | no operation                 |
|        |                  |                              |
| FETCH  | FETCH_1          | AR <- PC , Read              |
|        | FETCH_2          | DR <- M , PC <- PC + 1       |
|        | FETCH_3          | IR <- DR ,AR <- PC ,Read     |
|        |                  |                              |
|        | 1010.4           |                              |
| LDAC   | LDAC_1           | DR <- M , PC <- PC + 1       |
|        | LDAC_2           | TR <- DR , AR <- PC , Read   |
|        | LDAC_3<br>LDAC_4 | DR <- M , PC <- PC + 1       |
|        | LDAC_4<br>LDAC_5 | AR <- DRTR , Read<br>DR <- M |
|        | LDAC_5           | AC <- DR                     |
|        | LDAC_0           | AC V- DIV                    |
| STAC   | STAC_1           | DR <- M , PC <- PC + 1       |
|        | STAC_2           | TR <- DR , AR <- PC , Read   |
|        | STAC_3           | DR <- M , PC <- PC + 1       |
|        | STAC_4           | AR <- DRTR , Read            |
|        | STAC_5           | DRTR <- AC , Write           |
|        | STAC_6           | AR <- AR +1                  |
|        | STAC_7           | DR <- TR , Write             |
| CLAC   | CLAC             | AC <- 0, Z <- 0              |
|        |                  |                              |
| JUMP   | JUMP_1           | DR <- M , PC <- PC + 1       |
|        | JUMP_2           | TR <- DR , AR <- PC , Read   |
|        | JUMP_3           | DR <- M , PC <- PC + 1       |

|        | JUMP_4   | PC <- DRTR , Read                   |
|--------|----------|-------------------------------------|
| JUMPZ  | JUMPZY_1 | DR <- M , PC <- PC + 1              |
|        | JUMPZY_2 | TR <- DR , AR <- PC , Read          |
|        | JUMPZY_3 | DR <- M , PC <- PC + 1              |
|        | JUMPZY_4 | PC <- DRTR , Read                   |
|        | JUMPZN_1 | PC <- PC + 1                        |
|        | JUMPZN_2 | PC <- PC + 1                        |
| MULTWO | MULTWO_1 | ALU_op <- 110                       |
|        | MULTWO_2 | AC <- AC * 2                        |
| INC    | INC_1    | DR <- M , PC <- PC + 1              |
|        | INC_2    | <pre>INC_sel &lt;- DR[3:0]</pre>    |
|        |          | R[R1] <- R[R1] + 1                  |
| ADD    | ADD_1    | DR <- M ; PC <- PC + 1              |
|        | ADD_2    | WTA_sel <- DR[4:0]                  |
|        | ADD_3    | AC <- AC + R[R1]                    |
| MUL    | MUL_1    | DR <- M ; PC <- PC + 1              |
|        | MUL_2    | WTA_sel <- DR[4:0]                  |
|        | MUL_3    | AC <- AC * R[R1]                    |
| XOR    | XOR_1    | DR <- M ; PC <- PC + 1              |
|        | XOR_2    | WTA_sel <- DR[4:0]                  |
|        | XOR_3    | AC <- AC (+) R[R1], if AC=0 set Z=1 |
| MOVEAC | MOVEAC_1 | DR <- M ; PC <- PC + 1              |
|        | MOVEAC_2 | WTR_sel <- DR[4:0] , A bus <- AC    |

| MOVETOAC | MOVETOAC_1 | DR <- M ; PC <- PC + 1            |
|----------|------------|-----------------------------------|
|          | MOVETOAC_2 | WTA_sel <- DR[4:0] , AC <- R[R1]  |
|          |            |                                   |
| RESET    | RESET_1    | DR <- M , PC <- PC + 1            |
|          | RESET_2    | RESET_sel <- DR[3:0]              |
|          |            | R[R1] <- 0                        |
|          |            |                                   |
| DIV      | DIV_1      | DR <- M ; PC <- PC + 1            |
|          | DIV_2      | WTA_sel <- DR[4:0]                |
|          | DIV_3      | AC <- AC / R[R1], if AC=0 set Z=1 |
| MOD      | MOD_1      | DR <- M ; PC <- PC + 1            |
| MOD      | MOD 2      | WTA_sel <- DR[4:0]                |
|          | MOD 3      | AC <- AC % R[R1]                  |
|          | כ_סטויון   | AC V- AC % N[NI]                  |