Fast Coalgebraic Bisimilarity Minimization

(POPL'23)

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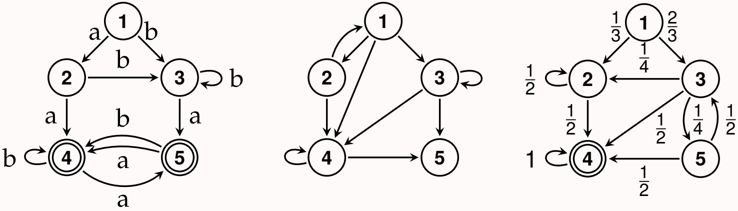
The Automaton Zoo

Deterministic finite automata, tree automata, (labeled) transition systems, weighted and probabilistic automata, Markov decision processes, ...



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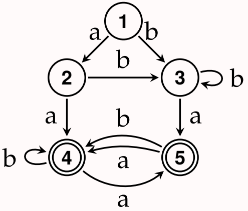

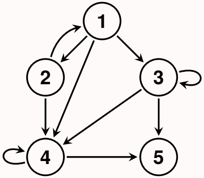

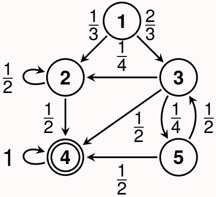

Automaton Minimization

Find and merge behaviorally equivalent states

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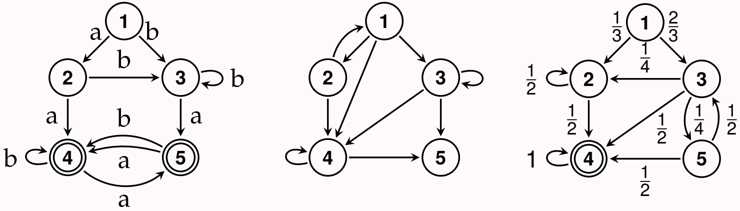

Automaton Minimization

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Coalgebraic Bisimilarity Minimization

Algorithms that work for a general class of F-automata

Our contribution

a **fast** and **general** algorithm for minimizing automata

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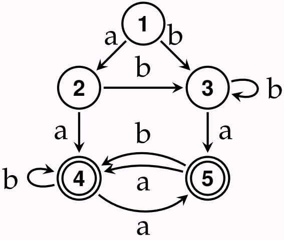
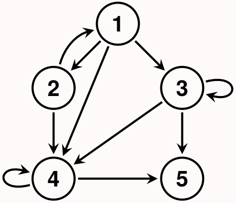
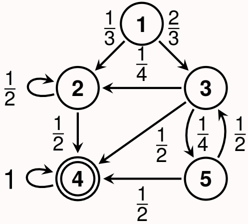
a **fast** and **general** algorithm for minimizing automata

- *General:* works for any computable coalgebra
- *Decent asymptotic complexity:* $O(\phi_F \cdot m \log n)$
- *Fast in practice:* no penalty for generality
- *Low memory usage:* important for large automata

Examples of Coalgebraic Automata

Automaton type	**Equivalence**	**Functor $F(X)$**
DFA	Language Equivalence	$2 \times A^X$
Transition Systems	Strong Bisimilarity	$\mathcal{P}(X)$
LTS	Strong Bisimilarity	$\mathcal{P}(A \times X)$
Weighted Systems	Weighted Bisimilarity	$M^{(X)}$
Markov Chain	Probabilistic Bisimilarity	$A \times \mathcal{D}(X)$
MDP	Probabilistic Bisimilarity	$\mathcal{P}(\mathcal{D}(X))$
Weighted Tree Automata	Backwards Bisimilarity	$M^{(\Sigma X)}$
Monotone Neigh. Frames	Monotone Bisimilarity	$\mathcal{N}(X)$
$\vdots$	$\vdots$	$\vdots$

Automaton types compose: $F \circ G, F + G, F \times G, \ldots$

DFA	Transition system	Markov chain
		
$F(X) = \{\mathsf{F}, \mathsf{T}\} \times X \times X$	$F(X) = \mathcal{P}_{\mathsf{f}}(X)$	$F(X) = \{\mathsf{F}, \mathsf{T}\} \times \mathcal{D}(X)$
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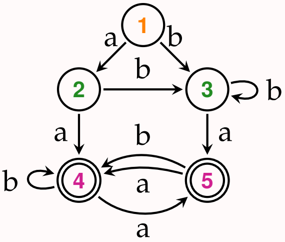
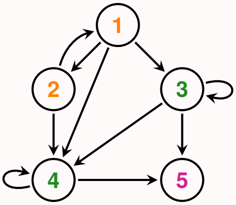
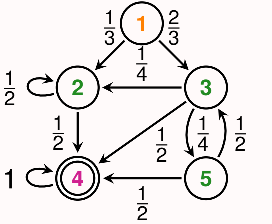
<table>
<tr><th>DFA</th><th>Transition system</th><th>Markov chain</th></tr>
<tr><td>
</td><td>
</td><td>
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What is coalgebraic bisimilarity minimization?

The input:

- a functor $F(X)$ – describes automaton type
- a coalgebra $t : C \to F(C)$ – the automaton

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- a functor $F(X)$ – describes automaton type
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The output:

- a partition $p : C \to C'$
  – the equivalence classes of bisimilar states
- s.t. $p(x) = p(y) \implies Fp(t(x)) = Fp(t(y))$
- $|C'|$ as small as possible

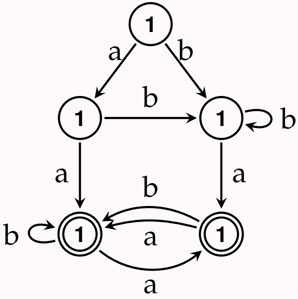
Sketch of our algorithm

1. Assume all states are equivalent
2. Split equivalence classes by *signature* (*normalised* outgoing transitions)
3. Iterate until convergence

Key points

- Only recompute signatures of *changed* states
- Do not loop over *unchanged* states

Our algorithm: Minimizing a DFA



Algorithm

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Iterate until all states have signatures:

1. Pick equivalence class & compute missing signatures.
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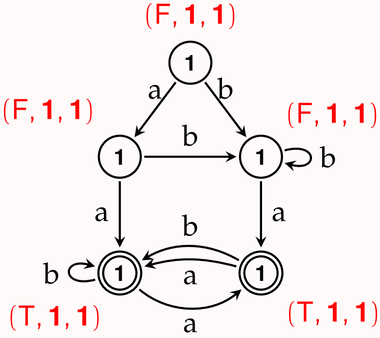

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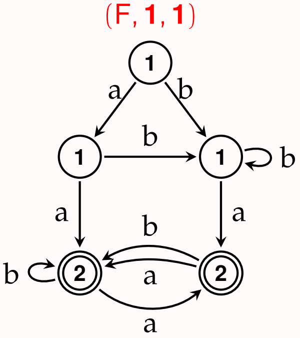

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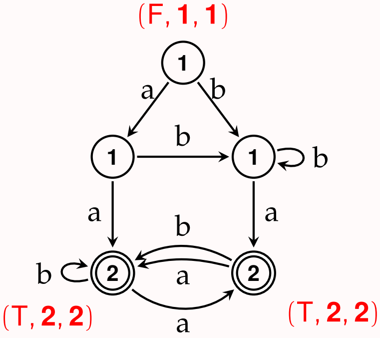

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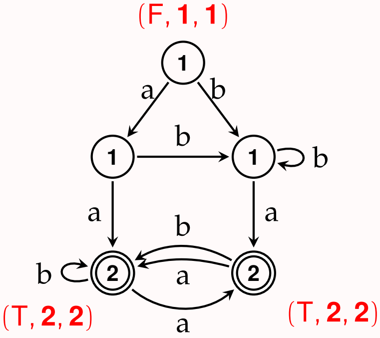

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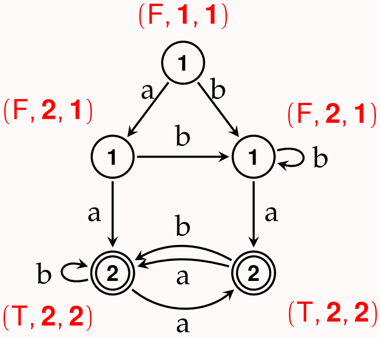

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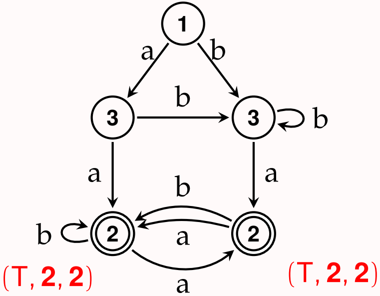

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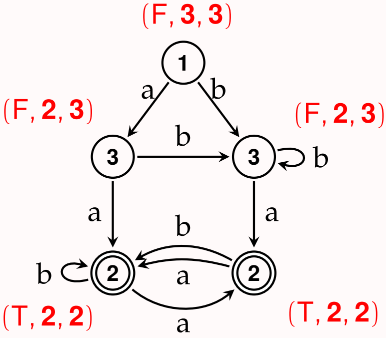

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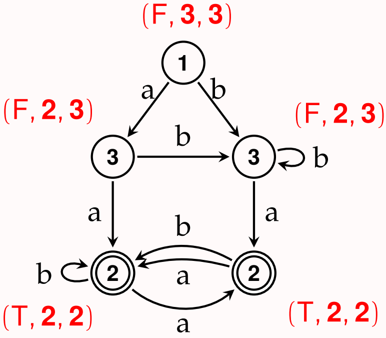

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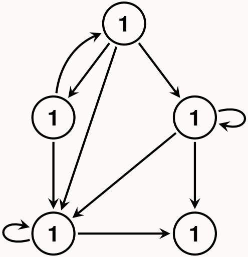

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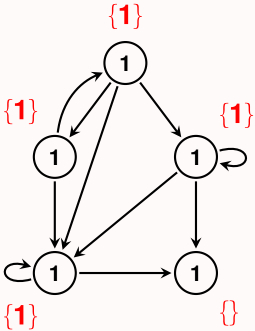

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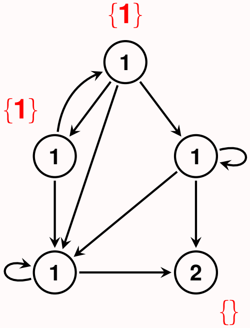

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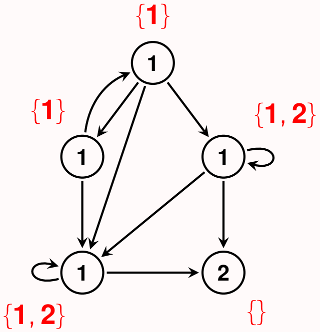

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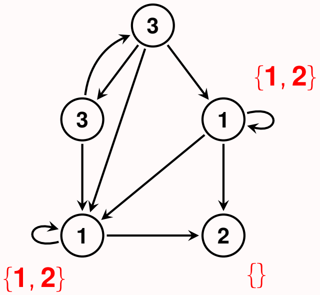

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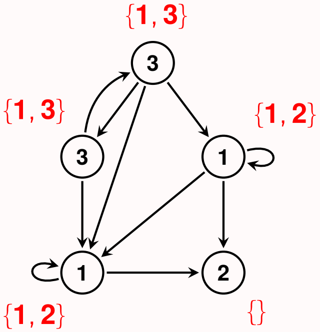

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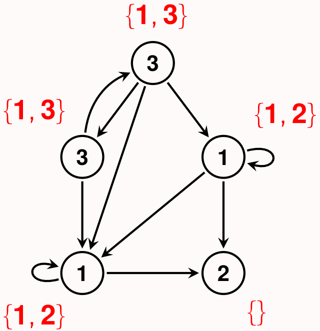

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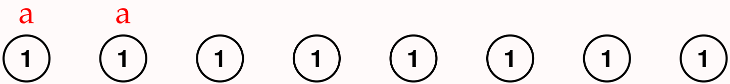
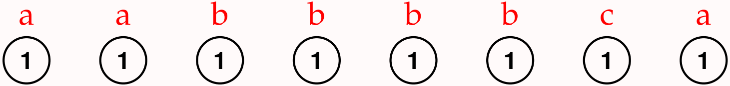
The general picture

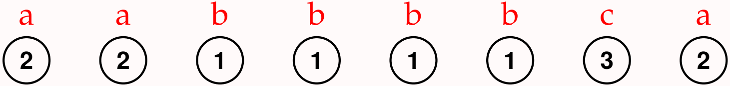
1. *Pick equivalence class with missing signatures:*



2. *Compute missing signatures:*



3. *Assign new state numbers:*



4. *Remove invalid signatures from predecessors*

What we need from the automaton

- Set of states C
- Predecessors of each state $\mathsf{pred} : C \to \mathcal{P}(C)$
- **Procedure to (re)compute signatures**
  $\mathsf{sig} : (C \to \mathbb{N}) \to (C \to F(\mathbb{N}))$

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Key: *re-use old state number for*
largest new equivalence class
Invalidates fewer signatures

Complexity: $O(m \log n)$ signature computations

Hopcroft's trick

State	**1**	**2**	**3**	**4**	**5**	**6**	**7**	**8**	**9**
Iteration 1	1	1	1	1	1	1	1	1	1

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Iteration 2	2	3	3	3	1	1	1	1	1

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Iteration 1	1	1	1	1	1	1	1	1	1
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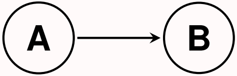
Each state's number changes $O(\log n)$ times!

Why $O(m \log n)$ signature recomputations?



An edge **A** $\rightarrow$ **B** may cause a signature recomputation of **A** when **B**'s state number changes.

Time complexity: $O(\Phi_F \cdot m \log n)$

Key ingredient: *never touch unchanged states*

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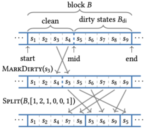
Key ingredient: *never touch unchanged states*

- n-way partition refinement data structure
- also tracks invalid signatures
- uses radix sort & bucket sort for n-way split

Algorithm 5 Refinable partition data structure with n-way split

```
procedure MarkDirty(s)
    ▹ Determine the block data ◃
    B := block_of[s]
    j := state2loc[s]
    (start, mid, end) := blocks[B]
    ▹ Do nothing if already dirty ◃
    if mid ≤ j then return
    ▹ Add to worklist if first dirty state ◃
    if mid = end then worklist.add(B)
    ▹ Swap s with the last clean state ◃
    s′ := loc2state[mid − 1]
    state2loc[s′] := j
    state2loc[s] := mid
    loc2state[j] := s′
    loc2state[mid] := s
    ▹ Move marker to make s dirty ◃
    blocks[B].mid −= 1
```




```
procedure Split(B, A: B_di → ℕ)
    ▹ Cumulative counts of sub-block sizes ◃
    (start, mid, end) := blocks[B]
    D[0.. max_i A[i] + 1] := 0
    D[0] := mid − start
    for j ∈ B_di do
        D[A[j]] += 1
    i_max = argmax_i D[i]
    for i ∈ 1..|D| do
        D[i] += D[i − 1]
    ▹ Re-order the states by A-value ◃
    dirty := copy(loc2state[mid..end])
    for i ∈ reverse(0..|A|) do
        D[A[i]] −= 1
        j := start + D[A[i]]
        loc2state[j] := dirty[i]
        state2loc[loc2state[i]] := j
    D[0] −= mid − start
    ▹ Create blocks and assign IDs ◃
    D.add(end − start)
    old_block_count := |blocks|
    for i ∈ 0..|D| − 1 do
        j_0 := start + D[i]
        j_1 := start + D[i + 1]
        if i = i_max then
            blocks[B] = (j_0, j_1, j_1)
        else
            blocks.add(j_0, j_1, j_1)
            idx := |blocks| − 1
            block_of[loc2state[j_0..j_1]] := idx
    return old_block_count..|blocks|
```

Algorithm 6 Optimized Partition Refinement for all Set functors

```
procedure PartRefSetFun(C, sig, pred)        ▹ i.e. for the implementation of c: C → FC
    Create a new refinable partition structure p: C → ℕ
    Init p to have one block of all states, and all states marked dirty.
    while there is a block B with a dirty state do
        Compute the arrays                                  } Compute signatures,
            (sigs_di: B_di → 2*) := (x ↦ sig(x, p))         } in total O(m log n) calls
            (sigs_cl: B_cl1 → 2*) := (x ↦ sig(x, p))        } to the coalgebra
        A: B_di → ℕ := Renumber′(sigs_di, sigs_cl)          } Split B according to
        B⃗_new := Split(B, A)                                } signatures in O(|B_di|)
        for every B′ ∈ B⃗_new and s ∈ B′ do                  } Mark dirty all states with
            for every s′ ∈ pred(s) do                       } a successor in a new block
                MarkDirty(s′)                               } in total time O(m log n)
    return the partition p
procedure Renumber’(p: B_di → 2*, q : B_cl1 → 2*)
    (A: B_di → ℕ) := Renumber(p)
    if there are d ∈ B_di, c ∈ B_cl1 with p(d) = q(c) then  } Ensure that A(d) = 0 for all dirty
        Swap the values 0 and A(d) in the array A.          } states d that have the same
    return A                                                } signature as the clean states.
```

$\Longrightarrow$ **signature recomputations dominate**

Comparison

	CoPaR	*DCPR*	*mCRL2*	*Boa*
Complexity	$O(m \log n)$	$O(\phi_F n^2)$	$O(m \log n)$	$O(\phi_F m \log n)$
Generality	Zippable	Coalg	LTS+	Coalg
Language	Haskell	Haskell	C++	Rust

benchmark		time (s)			memory (MB)	
type	**n**	***CoPaR***	***DCPR***	***Boa***	***DCPR***	***Boa***
fms	**1639440**	232	84	1.12	514×32	196
	4459455	–	406	4.47	1690×32	582
wlan	**607727**	105	855	0.28	147×32	42
	1632799	–	2960	0.79	379×32	93
wta(W)	**152107**	566	79	0.74	642×32	83
	944250	–	675	11.96	6786×32	1228
wta(Z)	**156913**	438	82	0.48	677×32	92
	1007990	–	645	16.75	5644×32	1325
wta(2)	**154863**	449	160	0.81	621×32	79
	1300000	–	1377	23.35	7092×32	1647

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What is the cost of generality?

benchmark		time (s)		memory (MB)	
type	**n**	***mCRL2***	***Boa***	***mCRL2***	***Boa***
cwi	**2416632**	13.9	1.4	1780	249
	7838608	214.2	15.8	5777	814
	33949609	282.2	31.5	16615	2776
vasy	**6020550**	33.8	3.1	2124	520
	11026932	51.6	6.1	2768	619
	12323703	56.9	7.0	3103	734

For ***mCRL2***, we pick its best algorithm and self-reported time.
For ***Boa***, we report wall-clock time.

We are $O(\phi_F \cdot m \log n)$ rather than $O(m \log n)$, so

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ϕ_F *is cheap!*

Don't incrementalize, just recompute:

- Saves memory
- Saves random reads
- Saves iterations*

Conclusion

Minimization can be **simple**, **generic**, and **fast**

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Future

- Other notions of equivalence (*e.g.*, branching)
- Specialization by monomorphisation
- Integration into Storm (with Sebastian Junges)
- Minimize *your* automata!