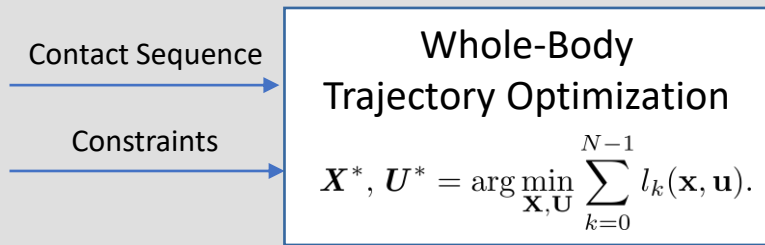


## 1. Offline Motion Planning



## 2. Online Stabilization

