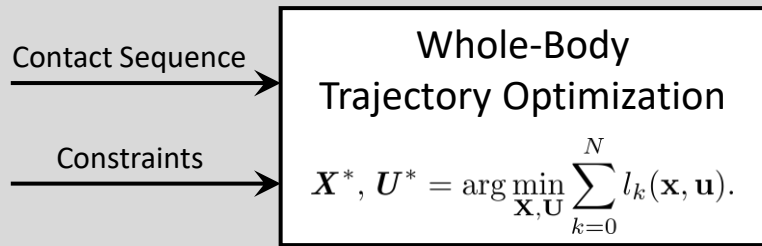


1. Offline Motion Planning



2. Online Stabilization

