

Problem Set II

1. (30%) **Euler's method:** https://en.wikipedia.org/wiki/Euler_method

For $\frac{dy}{dt} + 2y = 2 - e^{-4t}$, $y(0) = 1$,

- Derive its closed-form solution.
 - Use Euler's Method to find the approximation to the solution at $t = \{1, 2, 3, 4, 5\}$, and compare to the exact solution in (a).
 - Use different step size $h = \{0.1, 0.05, 0.01, 0.005, 0.001\}$ and plot out the approximated function value.
2. (70%) **Geodesic shooting.** Implement geodesic shooting by the following two strategies and compare the differences between the final transformations ϕ_1 at time point $t = 1$.

(a)

$$\begin{aligned}\frac{dv_t}{dt} &= K[(Dv_t)^T \cdot v_t + \text{div}(v_t v_t^T)], \\ \frac{d\phi_t}{dt} &= v_t \circ \phi_t.\end{aligned}$$

(b)

$$\begin{aligned}\frac{dv_t}{dt} &= -K[(Dv_t)^T \cdot v_t + \text{div}(v_t v_t^T)], \\ \frac{d\phi_t}{dt} &= -D\phi_t \cdot v_t.\end{aligned}$$

Note: Use your code of frequency smoothing in PS1 to implement the smoothing operator K (set the truncated number of frequency as 16^2).

(c) Deform a given source image by using the transformations ϕ_1 obtained from (a) and (b).

* Use Euler integration to solve the above ordinary differential equations.

IMPORTANT NOTES:

* Interpolation function: MATLAB function `interp2` with the option 'spline'.

* Initial velocity field v_0 and source image are included in the data folder. The initial transformation ϕ_0 is an image coordinate, which can be easily generated from MATLAB.

* All results should be clearly reported and discussed in the report.