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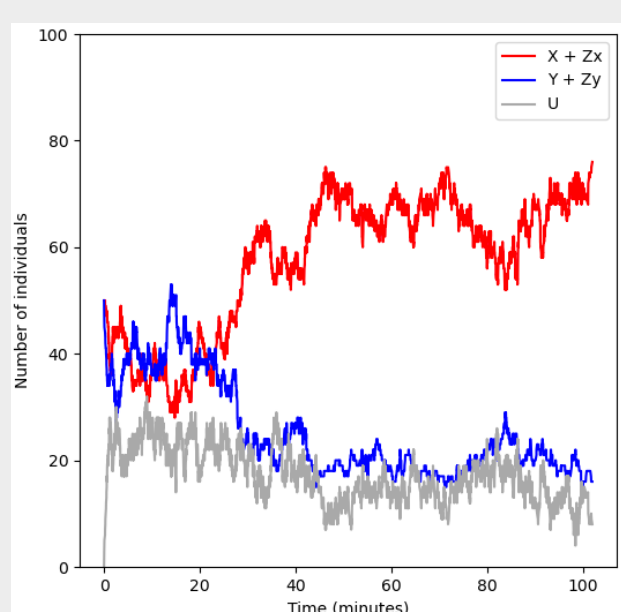
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Abstract

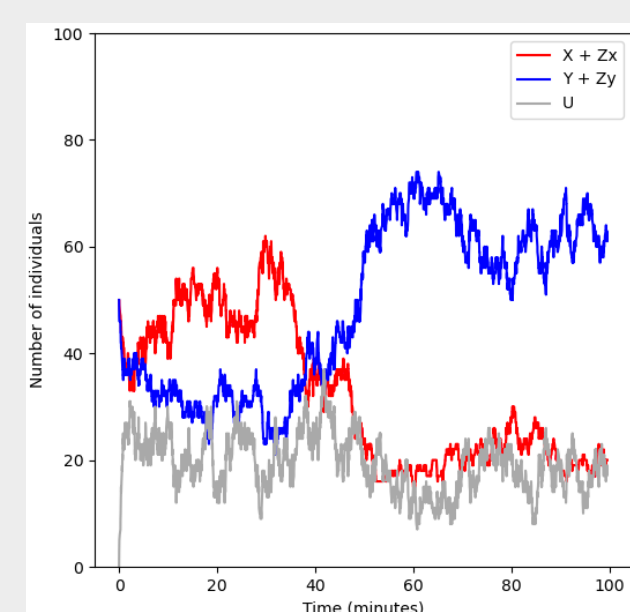
- Consensus in collective systems essential for coordinated behaviour
- Strongly opinionated minorities can disrupt opinion dynamics
- Approach:** investigate robustness of consensus-reaching among stubborn individuals (**zealots**) and **contrarians**
 - Statistical model checking to formally quantify **robustness** under perturbations of the amount of disruptive individuals
 - Investigate robustness landscape for combinations of different disruptive agents
- Goal: guide design and control of swarm robotics systems with focus on resilience to disruptive agents

Background

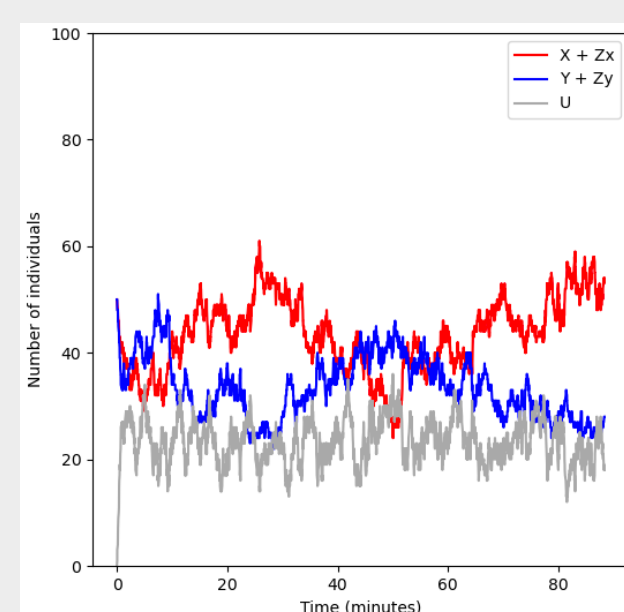
- Underlying model of decision-making: **cross-inhibition model** with 'undecided' state between switching opinion (2a), including
 - zealots:** never change their own opinion (2b)
 - contrarians:** counter opinion of individual they interact with (2c)
 - both zealots and contrarians (2d)
- Scenario:**
 - 2 equivalent options X and Y
 - Group of N=100 individuals
 - Initial state: equally split between X and Y, varying amount of disruptive individuals
- Observation of 3 different group dynamics:



(1a) stable consensus

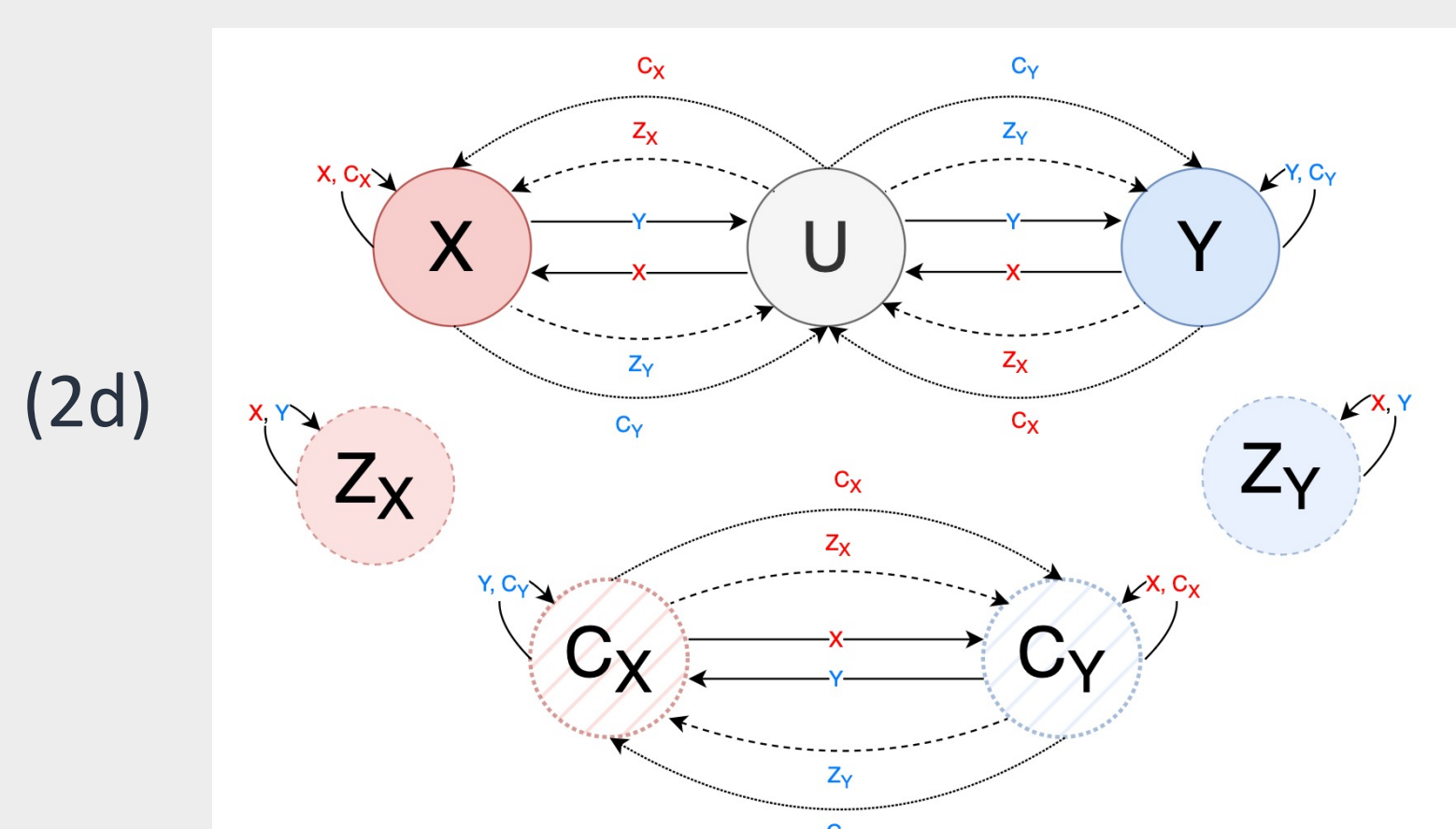
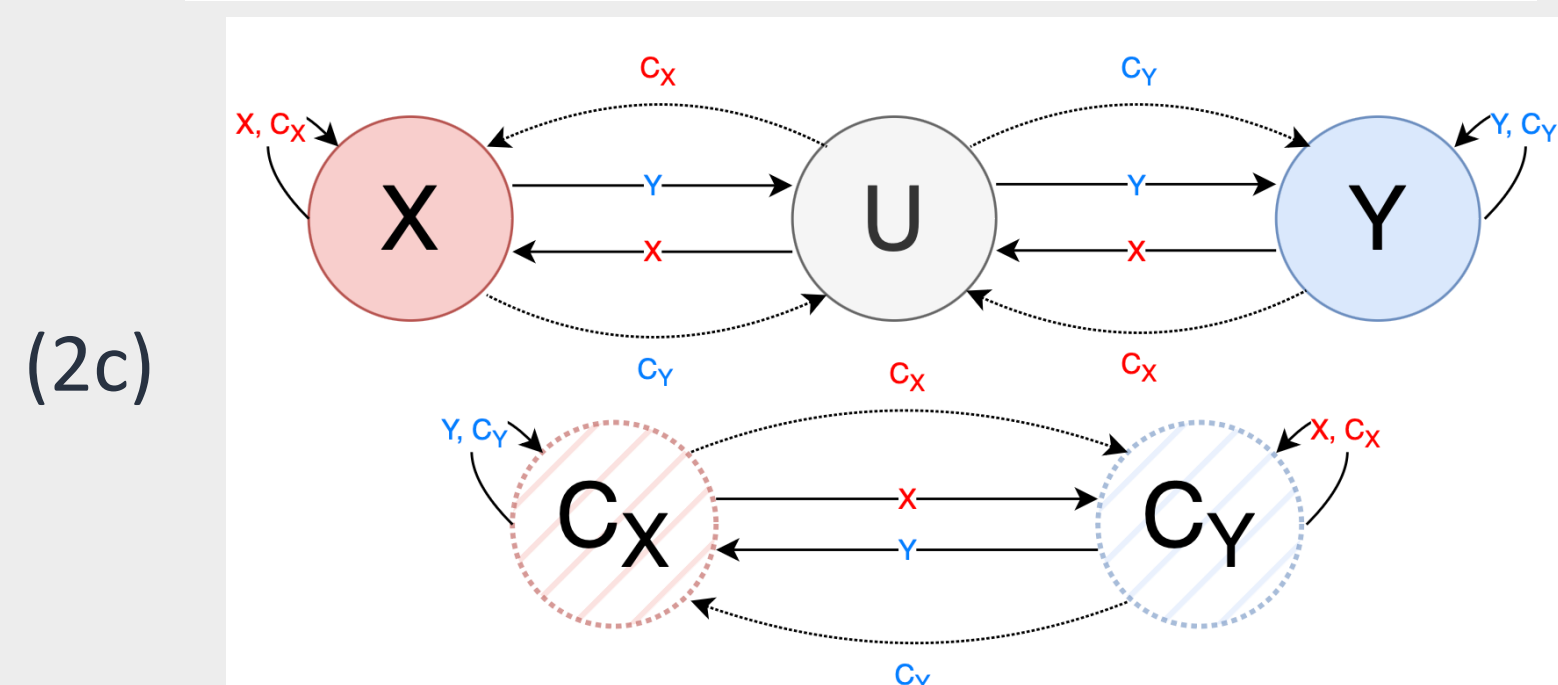
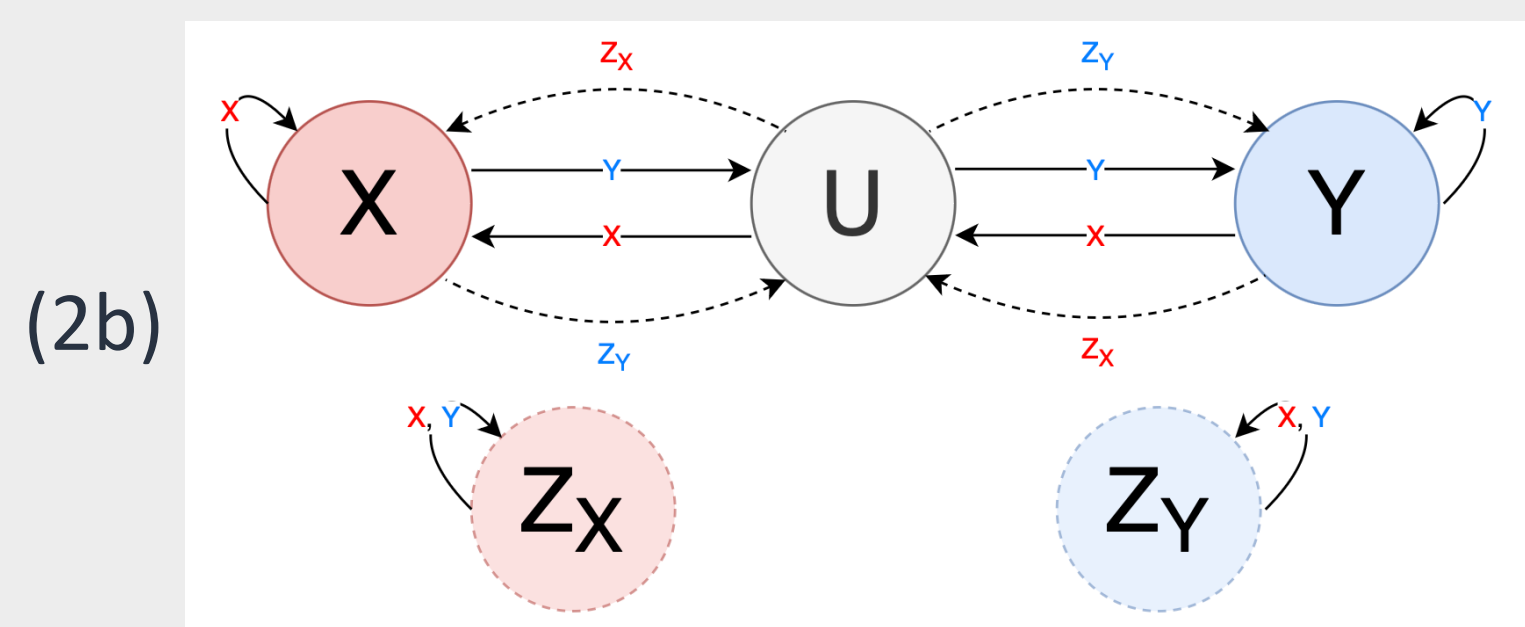
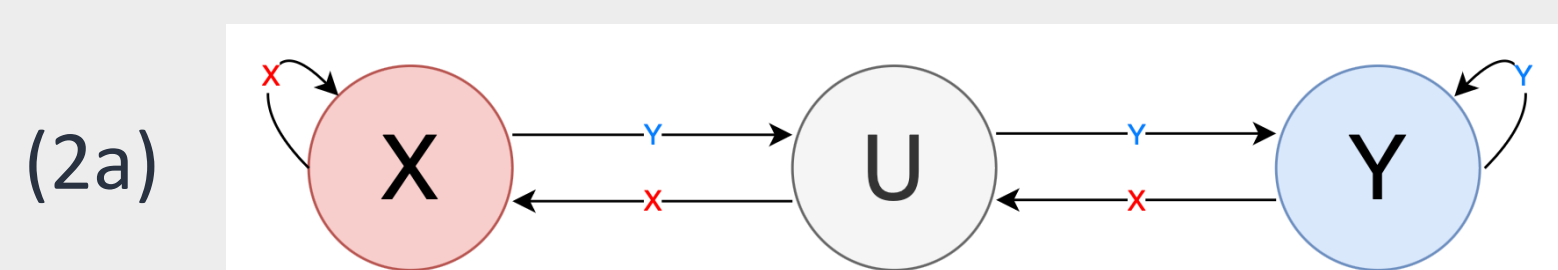


(1b) switching consensus

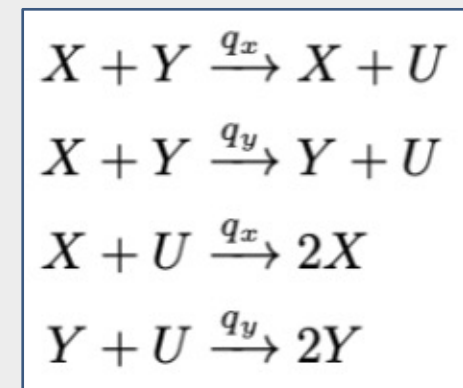


(1c) no consensus

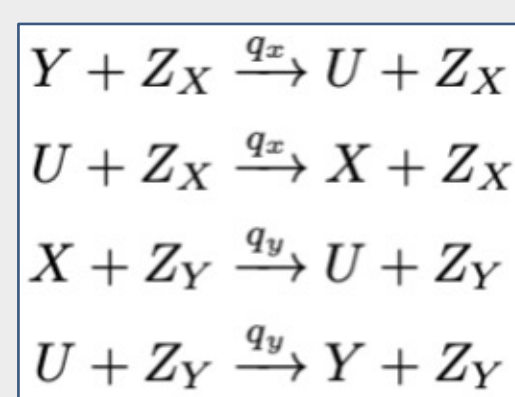
Models



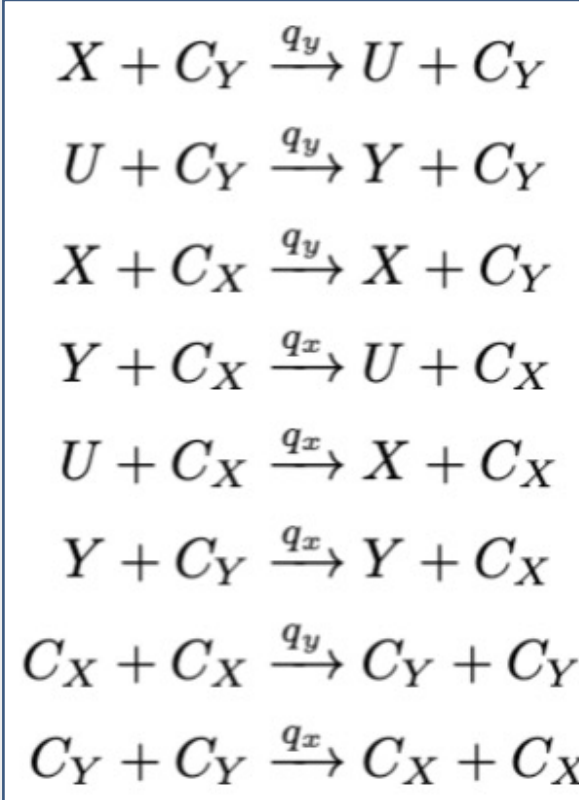
Cross-Inhibition model



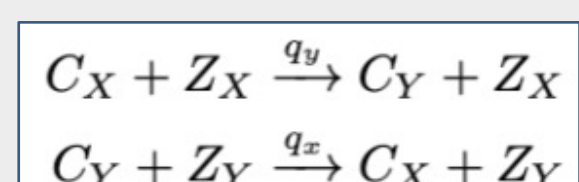
Zealots



Contrarians



Both Zealots & Contrarians



Analysis

- Formally describe observed scenarios in **Bounded Linear Temporal Logic**
 - Definition of consensus with five parameters: at least *majority* $m\%$ of population commits to same decision, *difference* of at least d between both groups, consensus is reached within *reaching time* t , consensus is maintained for at least *holding time* h , switch to other opinion happens within *switching time* s
 - Baseline:** $m=50, d=10, t=35, h=40, s=10$
 - Stable consensus (1a) in BLTL:**

$$F_{\leq t}(G_{\leq h}(((x + Z_x + C_x \geq \min_m) \wedge ((x + Z_x + C_x) - (y + Z_y + C_y) \geq d)) \vee ((y + Z_y + C_y \geq \min_m) \wedge ((y + Z_y + C_y) - (x + Z_x + C_x) \geq d))))))$$

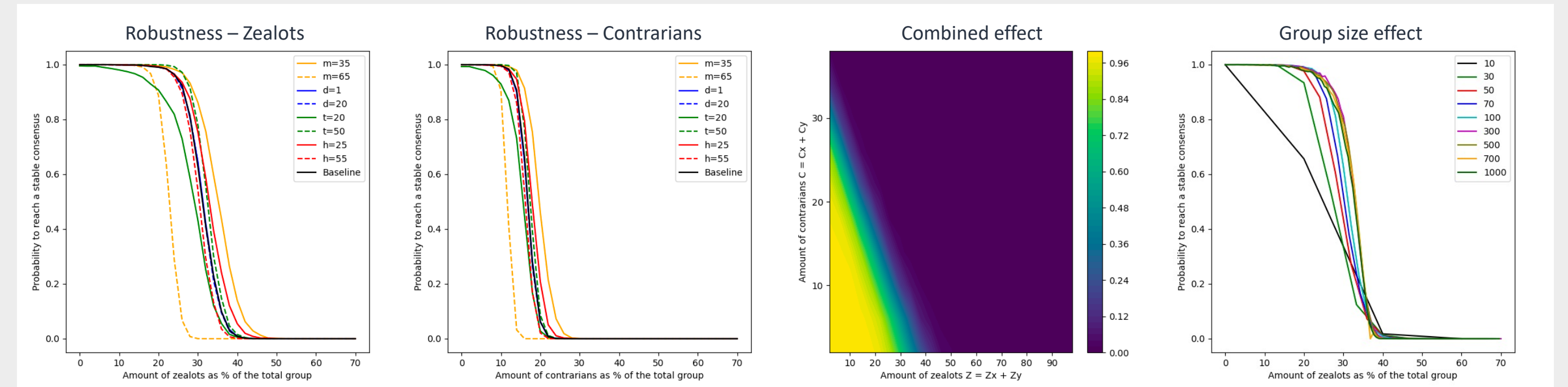
- Switching consensus (1b) in BLTL:**

$$F_{\leq t}(((x + Z_x + C_x) - (y + Z_y + C_y) \geq d) \wedge (\text{true } U_{\leq s}((y + Z_y + C_y) - (x + Z_x + C_x) \geq d))) \vee (((y + Z_y + C_y) - (x + Z_x + C_x) \geq d) \wedge (\text{true } U_{\leq s}((x + Z_x + C_x) - (y + Z_y + C_y) \geq d))))$$

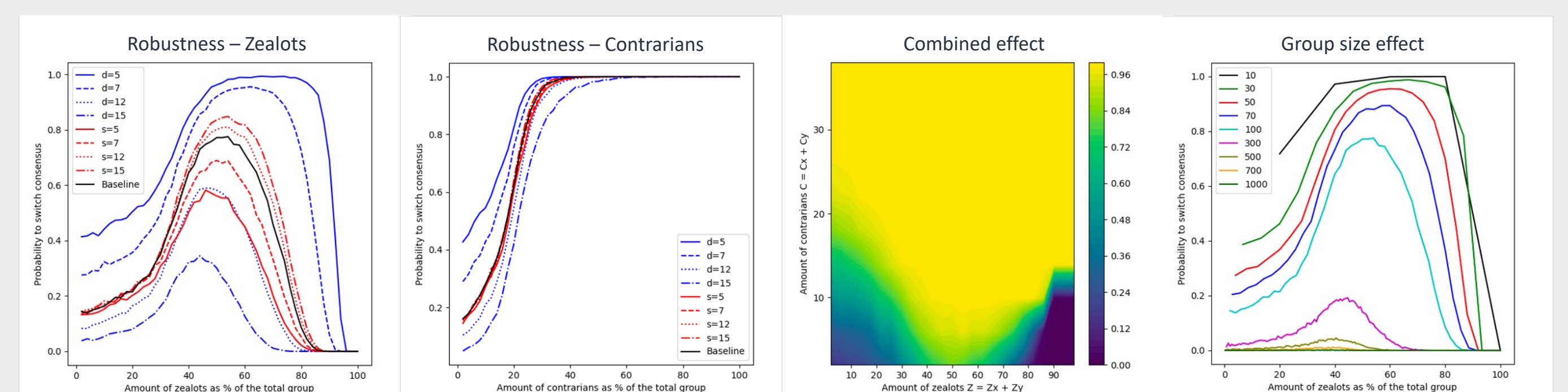
- Statistical model checking** to estimate satisfaction probability and explore robustness of scenarios

Results

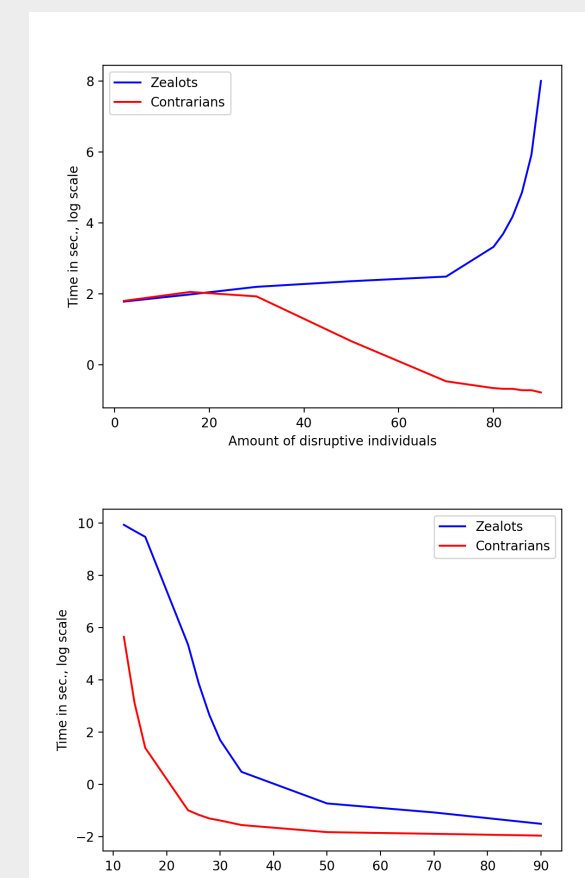
- Robustness of reaching a stable consensus (1a)



- Robustness of switching consensus (1b)



- Expected times



...to reach consensus

#	2	16	30	50	70	80	82	84	86	88	90
Zealots	5.95	7.28	9.02	10.57	12.04	27.82	39.94	64.95	128.85	374.04	2975.68
Contrarians	6.07	7.81	6.89	1.95	0.63	0.52	0.51	0.51	0.49	0.49	0.46

...to hold consensus

#	12	14	16	24	26	28	30	34	50	70	90
Zealots	20686.51	16368.28	13047.85	210.98	47.71	14.13	5.46	1.61	0.48	0.34	0.22
Contrarians	283.57	22.53	4.03	0.37	0.31	0.27	0.25	0.21	0.16	0.15	0.14

Conclusion

- Disruptive individuals can change opinion dynamics
- Our method is more informative
- Stable consensus:** robust up to certain #zealots/#contrarians, then rapid phase transition; zealots are less harmful for reaching consensus
- Switching consensus:** only range of zealots for which switching occurs with high probability; contrarians promote switching dynamics
- Future work:** explore variations of current scenario, asymmetric model (vote for better option), control theory

References

[1] Reina, A., Zakir, R., De Masi, G., Ferrante, E.: Cross-inhibition leads to group consensus despite the presence of strongly opinionated minorities and asocial behaviour. Communications Physics 6(1), 236 (2023)

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