Calibration results
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Camera-system parameters:
cam0 (/camera/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.04293889 -0.02654887 0.00155863 0.00038597] +- [0.00091404 0.0005967 0.00011994 0.00007765]
projection: [613.20895076 613.32044385 631.62425069 370.37760597] +- [0.87910367 0.8127326 0.48206756 0.55690526]
reprojection error: [0.000008, -0.000012] +- [1.098457, 0.853751]
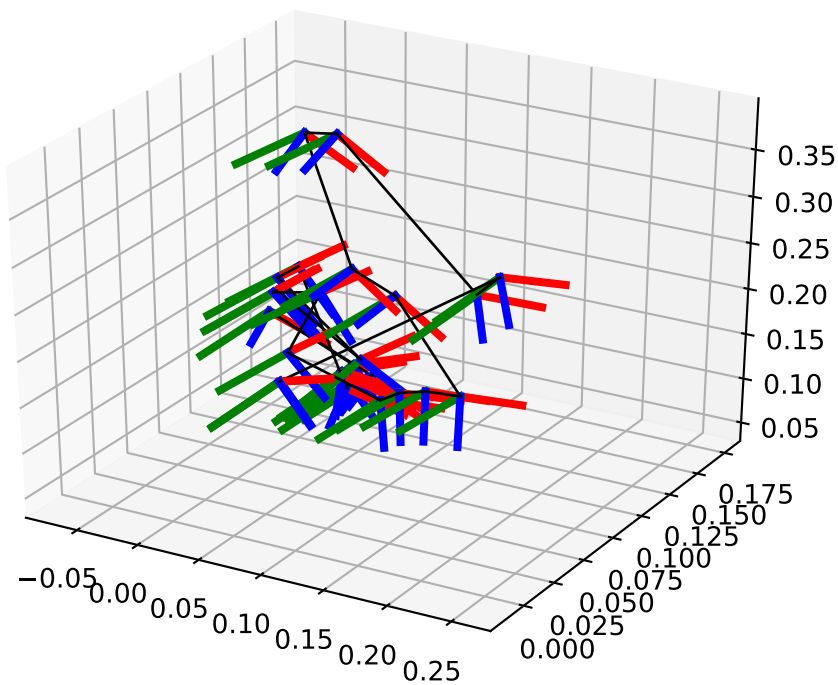

Target configuration
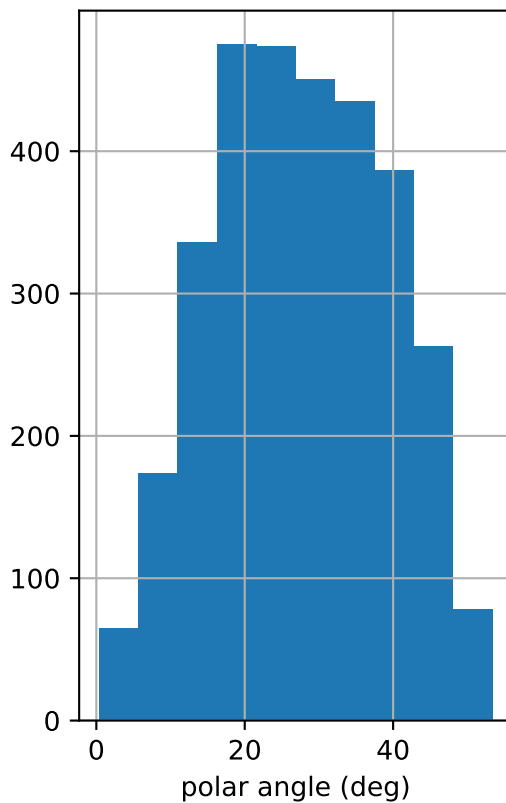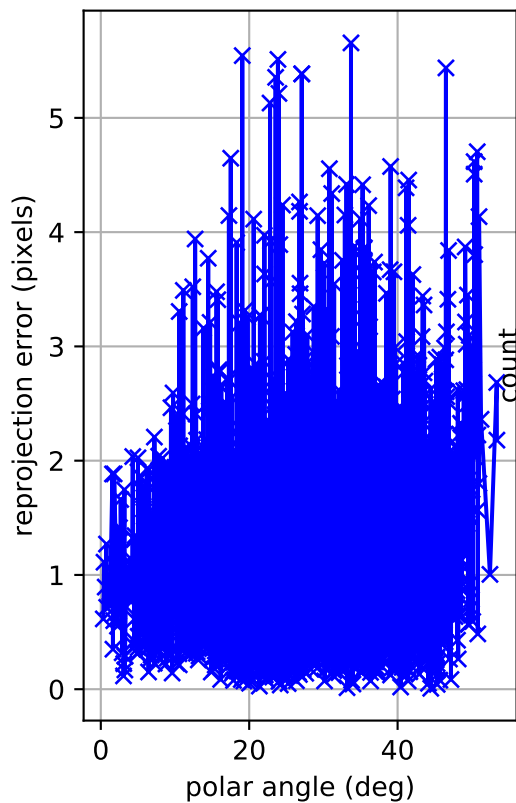====================

Type: aprilgrid
Tags:
Rows: 6
Cols: 6
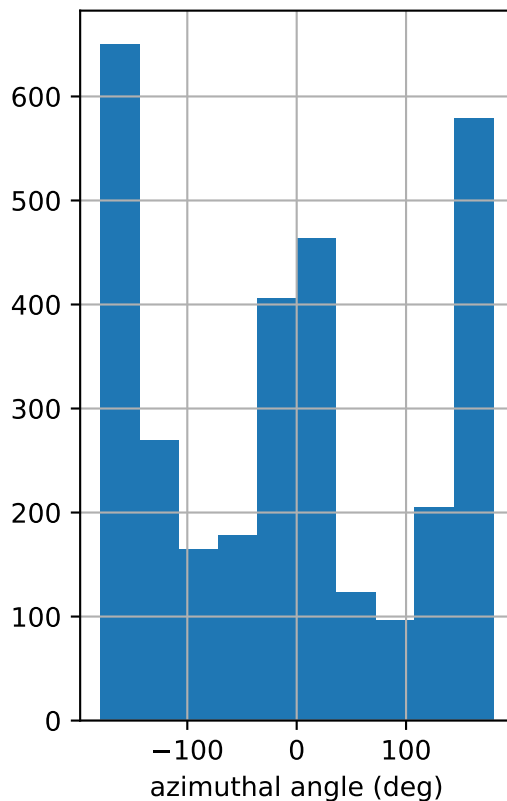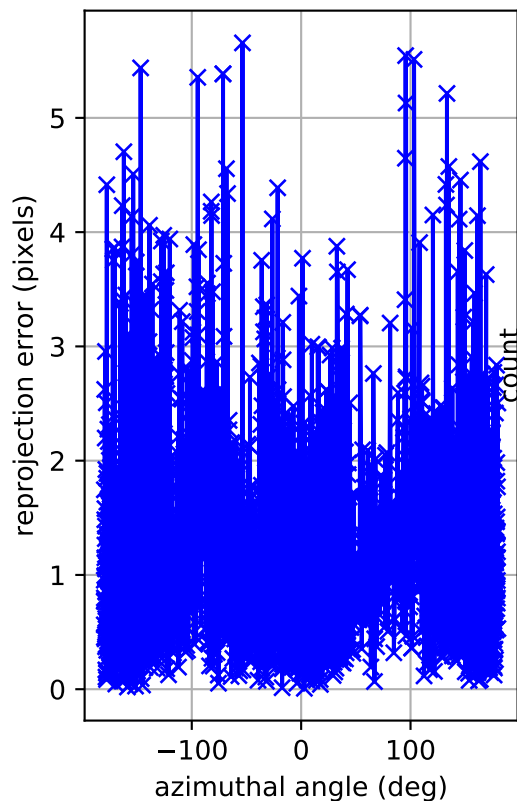Size: 0.02 [m]
Spacing 0.006 [m]
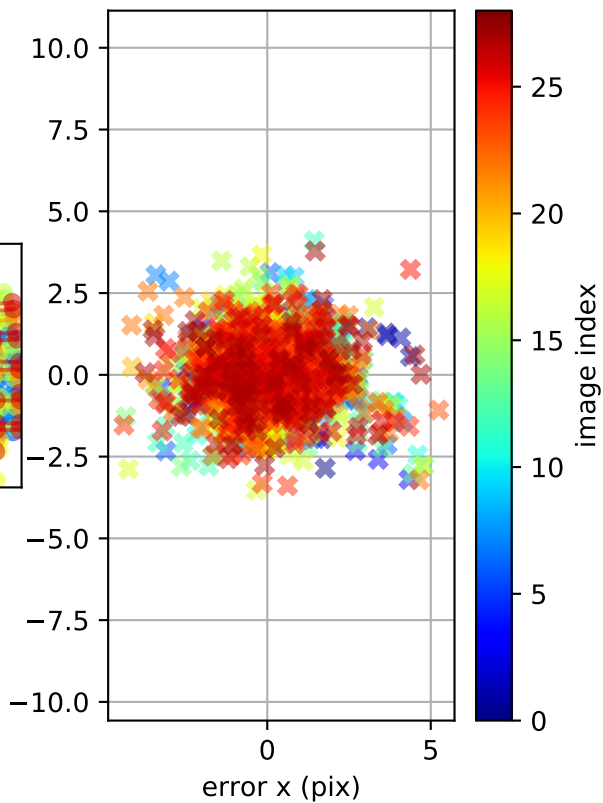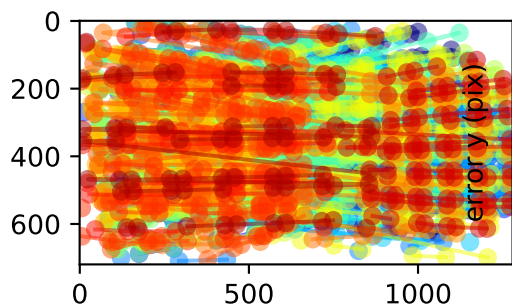
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners