

Analysis of Jeffcott rotor considering contact mechanism

MECH 501

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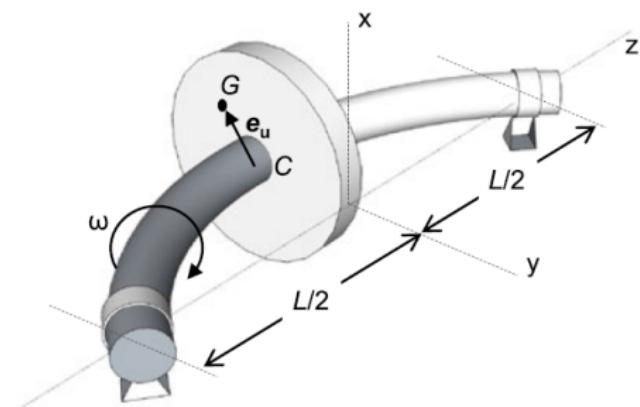
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Problem statement

Jeffcott Rotor

- simplified lumped parameter model
- mathematical idealization

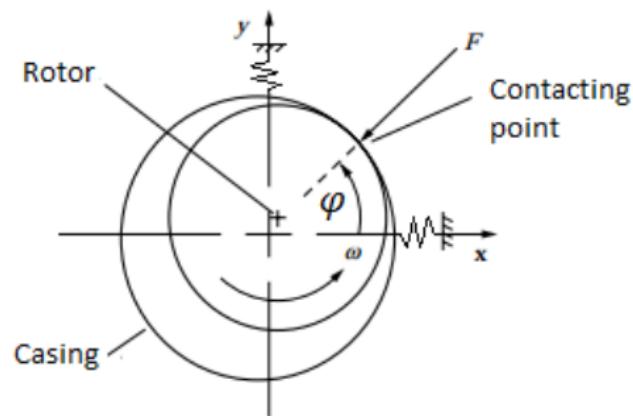




Problem statement

Jeffcott Rotor

- Contact Consideration
- Methods to find solution
 - ▶ Time Integration method
 - ▶ Harmonic Balance method
- Applications



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Governing Equation

-

$$m_r \ddot{r}_r(t) + c_r \dot{r}_r(t) + k_r r_r(t) = \lambda(t) + f_{textext}(t)$$

$$m_s \ddot{r}_s(t) + c_s \dot{r}_s(t) + k_s r_s(t) = -\lambda(t)$$

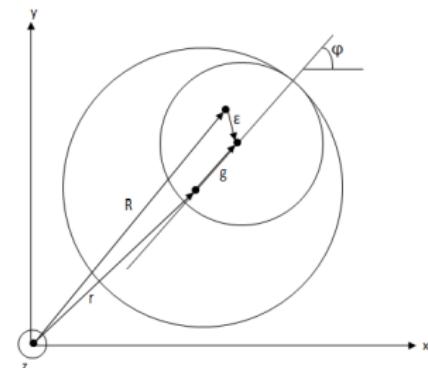
$$\lambda(t) = -k_c [(|r_r(t) - r_s(t)| - g)^+ \angle(r_r - r_s)]$$

where subscript r means rotor, s means stator.

$$r(t) = x(t) + iy(t)$$

$$f_{textext}(t) = m_r e_m w^2 e^{i\omega t}$$

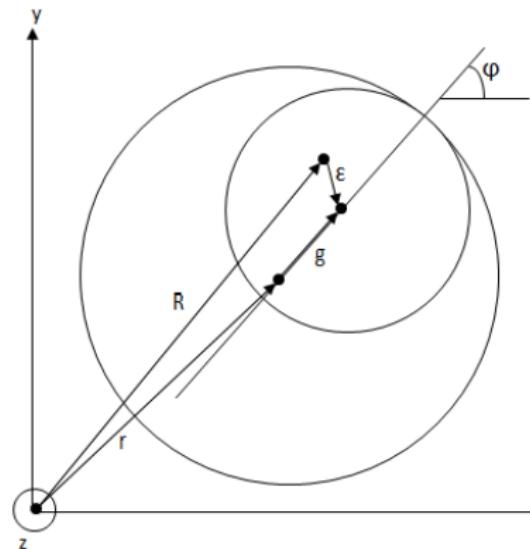
$$k_c = 100k_r(1 + i0.1)$$





Solution

- Numerical Solution
- Runge-kutta Method
- ode45
 - ▶ State-space form
 - ▶ Initial conditions





Results

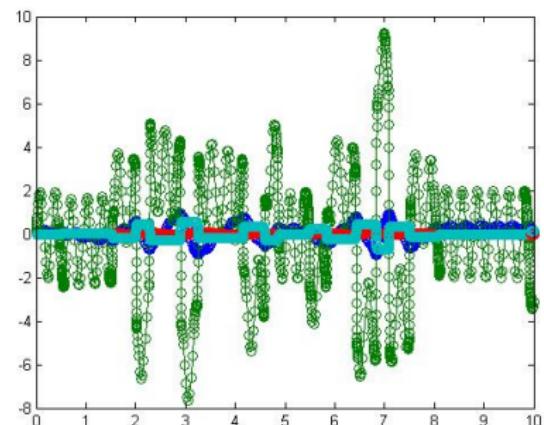
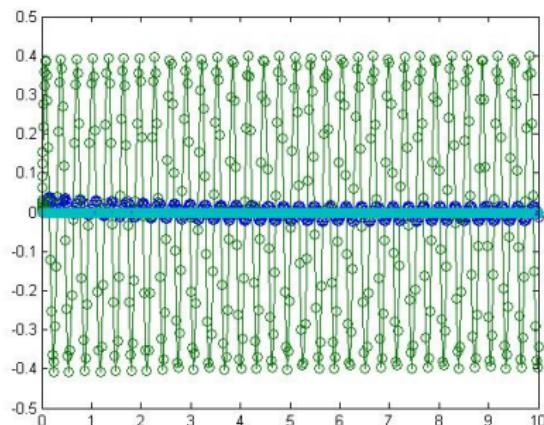
periodic solution

Non-periodic solution



Variation in solution

Left: $e = 0.02$, right: $e = 0.1$





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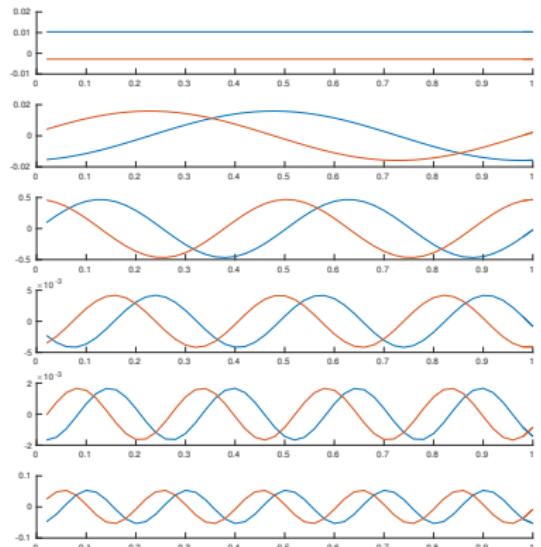
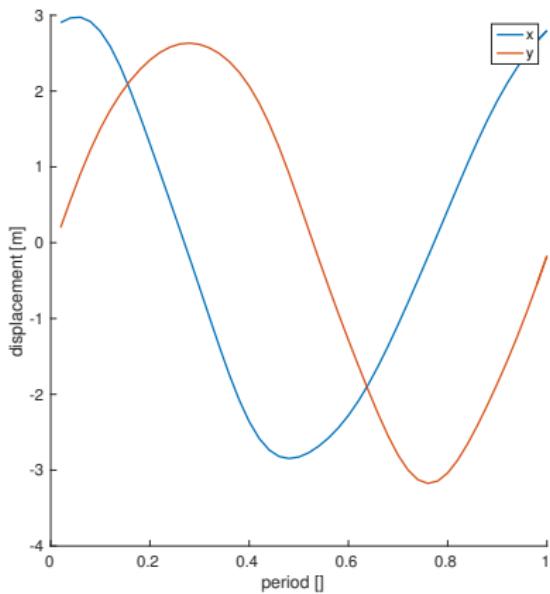
Governing Equation
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3 Harmonic Balance Method

Harmonic Balance Method basics
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Harmonic Balance Method basics





Harmonic Balance Method basics

- for problem

$$\ddot{x}(t) = f(x(t), \dot{x}(t)) \quad (2)$$

- assume an approximate solution $x^h(t) \in C^h$

$$x(t) \approx x^h(t) = \sum_{m=-M}^{M} c_m e^{imwt} = \Phi(t)\mathbf{c} \quad (3)$$

where $0 < M < \infty$, C^h is the finite space spanning from the finite base functions e^{imwt} .

- (2) yields

$$\ddot{x}^h(t) = (imw)^2 \sum_{m=-M}^{M} c_m e^{imwt} = -m^2 w^2 \Phi(t)\mathbf{v} \quad (4)$$



Harmonic Balance Method basics

weak form

- define the test function $v^h(t) \in C^h$ in the same finite space

$$v^h(t) = \sum_{m=-M}^{M} v_m e^{im\omega t} = \Phi(t)v \quad (5)$$

- Then, the nonlinear ODE (2) is equivalent to the weak form

$$\int_0^{2\pi/\omega} v^h(t) [\ddot{x}^h - f(x^h(t), \dot{x}^h(t))] dt = 0, \quad \forall v^h(t) \in C^h \quad (6)$$



Harmonic Balance Method basics

- For $2M + 1$ unknown coefficients c_m , $m = -M, \dots, -1, 0, 1, \dots, M$, we have $2M + 1$ equations which make solution unique



$$\int_0^{2\pi/w} e^{-i(-M)wt} [\ddot{x}^h - f(x^h(t), \dot{x}^h(t))] dt = 0$$

...

$$\int_0^{2\pi/w} e^{-i(-1)wt} [\ddot{x}^h - f(x^h(t), \dot{x}^h(t))] dt = 0$$

$$\int_0^{2\pi/w} e^{-i(0)wt} [\ddot{x}^h - f(x^h(t), \dot{x}^h(t))] dt = 0$$

$$\int_0^{2\pi/w} e^{-i1wt} [\ddot{x}^h - f(x^h(t), \dot{x}^h(t))] dt = 0$$

...

$$\int_0^{2\pi/w} e^{-iMwt} [\ddot{x}^h - f(x^h(t), \dot{x}^h(t))] dt = 0$$

- In summary, we are going to solve a residual function $\mathbf{f} : \mathbb{R}^{2M+1} \rightarrow \mathbb{R}^{2M+1}$

$$\mathbf{f}(\mathbf{c}_r, \mathbf{c}_s) = \mathbf{0}$$

(8)



Harmonic Balance Method basics

Iteration algorithm

- For a certain w , given the initial guess $\mathbf{c}^{(0)}$, We use " time-> frequency -> time -> frequency -> ..." iteration. The one time period $[0, 2\pi/w]$ is divided into N small segments $[t_{n-1}, t_n]$, $n = 1, 2, \dots, N$.

- at iteration step k : frequency -> time:

$$r_r(t)^{(k)} = \Phi(t)\mathbf{c}_r^{(k)}, \quad r_s(t)^{(k)} = \Phi(t)\mathbf{c}_s^{(k)}$$

- time domain:

$$\lambda^{(k)}(t_n) = -k_c[(|r_r^{(k)}(t_n) - r_s^{(k)}(t_n)| - g)^+ \angle(r_r^{(k)}(t_n) - r_s^{(k)}(t_n))]$$

- time -> frequency

$$\mathbf{f}(\mathbf{r}_r(t_n, \mathbf{c}_r^{(k)}), \mathbf{r}_s(t_n, \mathbf{c}_s^{(k)}), \lambda(t_n, \mathbf{c}^{(k+1)})) = \mathbf{0}$$

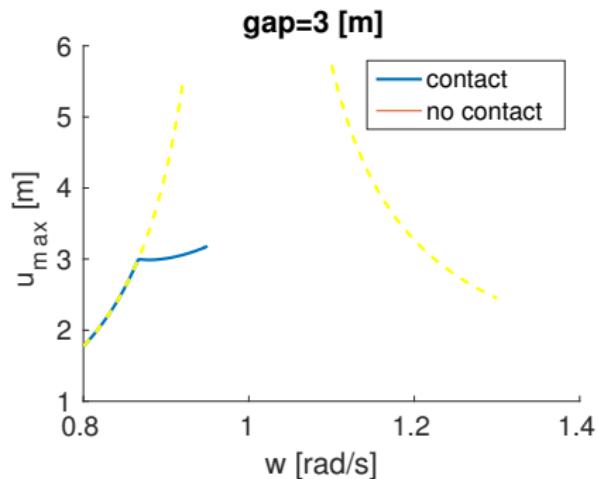
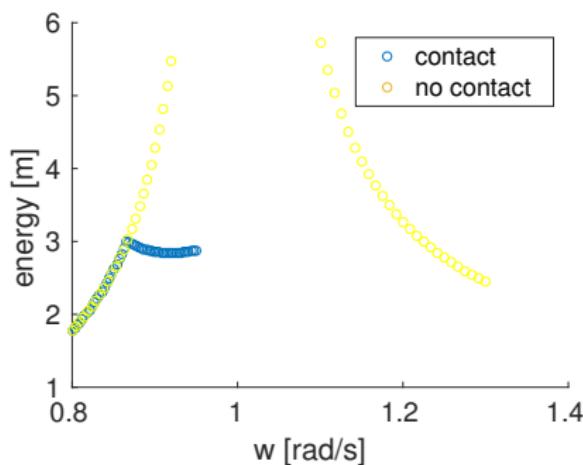
- if not terminate, go to step 1.



Results

Energy - forcing frequency

$$\text{energy} = \sqrt{c_{-M}^2 + \dots + c_{-1}^2 + c_0^2 + c_1^2 + \dots + c_M^2}$$





Results – periodic solution

No contact

With contact

$$r_r(t) = (2.1569 + 0.1128i)e^{i\omega t}$$

$$r_r(t) = \dots + (-0.0079 + 0.0011i)e^{i\omega t} + (0.005$$

$$r_s(t) = \dots + (0.0007 - 0.0002i)e^{i\omega t} + (-0.002$$