

Aula 11

• Teste 1 até ao Cap. 2.1. slide 12

(FP2) (20) (e)  $\begin{bmatrix} 1, 1, 5 \end{bmatrix}_S = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$  tal que  $(1, 1, 5) = a_1(1, 1, 2) + a_2(0, 1, 1) \Leftrightarrow \begin{cases} a_1 = 1 \\ a_2 = 3 \end{cases}$

$$\begin{bmatrix} 1, 1, 5 \end{bmatrix}_S = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

(5) (d)  $\langle (1, 1, 1), (1, 0, 0), (2, 2, 2) \rangle = \{(x, y, z) = \alpha_1(1, 1, 1) + \alpha_2(1, 0, 0) + \alpha_3(2, 2, 2), \alpha_1, \alpha_2, \alpha_3 \in \mathbb{R}\}$

$$= \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 2 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix}, \alpha_1, \alpha_2, \alpha_3 \in \mathbb{R} \right\}$$

Quando é que o sistema  $AX=B$  é possível?  $\text{car}(A)=\text{car}([A|B])$ ?

$$[A|B] = \left[ \begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 1 & 0 & 2 & 0 \\ 1 & 0 & 2 & 2 \end{array} \right] \sim \left[ \begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & -1 & 0 & 0 \\ 0 & 1 & 0 & 2-x \end{array} \right] \sim \left[ \begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 2-y \end{array} \right]$$

$$L_2 \leftarrow L_2 - L_1, \quad L_3 \leftarrow L_3 - L_1$$

$$L_3 \leftarrow L_3 - L_2$$

Temos que  $\text{car}(A)=2$  para  $AX=B$  ser possível termos de ter  $\text{car}(A)=\text{car}([A|B])=2$  o que implica que  $z-y=0$ . Assim,  $\langle (1, 1, 1), (1, 0, 0), (2, 2, 2) \rangle = \{(x, y, z) \in \mathbb{R}^3 : z-y=0\}$

(15)  $K = \{(1, 0, 1, 0), (0, 1, 1, -1, 0)\}$

$K$  é l.i.?  $(0, 0, 0, 0) = \alpha_1(1, 0, 1, 0) + \alpha_2(0, 1, 1, -1, 0) \Leftrightarrow \begin{cases} \alpha_1 = 0 \\ \alpha_2 = 0 \end{cases}$  Poss. Det.

$K$  é l.i. mas não gera  $\mathbb{R}^4$  porque só temos 2 vetores.

$\langle K \rangle = \{(x, y, z, t) = \alpha_1(1, 0, 1, 0) + \alpha_2(0, 1, 1, -1, 0), \alpha_1, \alpha_2 \in \mathbb{R}\}$ .

$$\begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} \Leftrightarrow AX=B$$
 quando é possível /  $\text{car}(A)=\text{car}([A|B])$ ?

$$[A|B] = \left[ \begin{array}{cc|c} 1 & 0 & x \\ 0 & 1 & y \\ 1 & -1 & z \\ 0 & 0 & t \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 0 & x \\ 0 & 1 & y \\ 0 & -1 & z-x \\ 0 & 0 & t \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 0 & x \\ 0 & 1 & y \\ 0 & 0 & z-x+y \\ 0 & 0 & t \end{array} \right]$$

$$L_3 \leftarrow L_3 - L_1, \quad L_3 \leftarrow L_3 + L_2$$

$$\text{car}(A)=2$$

para que  $\text{car}([A|B])=2$  temos de ter  $t=0$  e  $z-x+y=0$

Assim,

$$\langle K \rangle = \{(x, y, z, t) \in \mathbb{R}^4 : z-x+y=0 \text{ e } t=0\} \neq \mathbb{R}^4$$

$\Leftrightarrow x=y+z$

Por exemplo,  $(0, 0, 0, 1)$  e  $(0, 0, 1, 0)$   $\notin \langle K \rangle$  e  $\{(0, 0, 0, 1) \text{ e } (0, 0, 1, 0)\}$  é l.i. porque  $(0, 0, 0, 0) = \alpha_1(0, 0, 0, 1) + \alpha_2(0, 0, 1, 0) \Rightarrow \alpha_1 = \alpha_2 = 0$ .

Pelo Teorema do slide 8, o conjunto  $K \cup \{(0, 0, 0, 1), (0, 0, 1, 0)\}$  ainda é l.i. E pelo Corolário do slide 12, como  $\dim \mathbb{R}^4 = 4$  qualquer conjunto com 4 vetores de  $\mathbb{R}^4$  l.i. é automaticamente uma base de  $\mathbb{R}^4$ .

Portanto,  $((1, 0, 1, 0), (0, 1, 1, -1, 0), (0, 0, 0, 1), (0, 0, 1, 0))$  é uma base de  $\mathbb{R}^4$ .

1º teste 24/25

②  $\alpha \in \mathbb{R}$

(a)  $A$  tem inversa  $\Leftrightarrow \text{car}(A) = 3$  (nº de colunas)

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 1 & 1 \\ \alpha & 0 & 3 \end{bmatrix} \xrightarrow{L_3=L_3-\alpha L_1} \begin{bmatrix} 1 & -1 & 2 \\ 0 & 1 & 1 \\ 0 & \alpha & 3-3\alpha \end{bmatrix} \xrightarrow{L_3=L_3-\alpha L_2} \begin{bmatrix} 1 & -1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 3-3\alpha \end{bmatrix} \text{ escalonada}$$

$\text{car}(A) = 3 \Rightarrow$  e só se  $3-3\alpha \neq 0 \Leftrightarrow 3\alpha \neq 3 \Leftrightarrow \alpha \neq 1$ .

(b)  $\alpha=2$

$$(i) [A | I_3] = \left[ \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 2 & 0 & 3 & 0 & 0 & 1 \end{array} \right] \xrightarrow{L_3=L_3-2L_1} \left[ \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 2 & -1 & -2 & 0 & 1 \end{array} \right] \xrightarrow{L_3=L_3-2L_1}$$

$$\sim \left[ \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & -3 & -2 & 2 & 1 \end{array} \right] \xrightarrow{L_1=L_1+L_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 3 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & -3 & -2 & 2 & 1 \end{array} \right] \xrightarrow{L_1=L_1+L_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & -1 & 1 \\ 0 & 1 & 0 & -2/3 & 1/3 & 1/3 \\ 0 & 0 & -3 & -2 & -2 & 1 \end{array} \right] \sim$$

$$\xrightarrow{L_3=L_3/3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & -1 & 1 \\ 0 & 1 & 0 & -2/3 & 1/3 & 1/3 \\ 0 & 0 & 1 & 2/3 & 2/3 & -1/3 \end{array} \right] = [I_3 | A^{-1}]$$

(ii)  $X_{3 \times 3} = ?$

$$A^T X + 5B = DC \Leftrightarrow \boxed{A^T X} = \boxed{DC - 5B} \Leftrightarrow \underbrace{(A^T)^{-1} A^T X}_{I_3} = (A^T)^{-1} (DC - 5B)$$

$$\Leftrightarrow X = \underbrace{(A^{-1})^T}_{2(b)(i)} (DC - 5B)$$

$$= \begin{bmatrix} -1 & -2/3 & 2/3 \\ -1 & 1/3 & 2/3 \\ 1 & 1/3 & -1/3 \end{bmatrix} \left( \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} 5 & -5 & 0 \end{bmatrix} - 5 \begin{bmatrix} 1 & -1 & 2 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right)$$

$$= \begin{bmatrix} -1 & -2/3 & 2/3 \\ -1 & 1/3 & 2/3 \\ 1 & 1/3 & -1/3 \end{bmatrix} \left( \begin{bmatrix} 10 & -10 & 0 \\ 5 & -5 & 0 \\ 0 & 0 & 0 \end{bmatrix} - \begin{bmatrix} 5 & -5 & 10 \\ 5 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix} \right)$$

$$= \begin{bmatrix} -1 & -2/3 & 2/3 \\ -1 & 1/3 & 2/3 \\ 1 & 1/3 & -1/3 \end{bmatrix} \begin{bmatrix} 5 & -5 & 10 \\ 0 & -10 & 0 \\ 0 & 0 & -5 \end{bmatrix} = \begin{bmatrix} -5 & 35/3 & 20/3 \\ -5 & 5/3 & 20/3 \\ 5 & -25/3 & -25/3 \end{bmatrix}$$

(FP1) (18)  $[A | B] = \left[ \begin{array}{ccc|cc} 1 & \alpha-1 & \alpha & \alpha-2 \\ 0 & \alpha-1 & 0 & 1 \\ 0 & 0 & \alpha & \alpha-3 \end{array} \right] \xrightarrow{L_2=\frac{L_2}{\alpha-1}, \alpha \neq 1} \left[ \begin{array}{ccc|cc} 1 & \alpha-1 & \alpha & \alpha-2 \\ 0 & 1 & 0 & 1/(\alpha-1) \\ 0 & 0 & 1 & (\alpha-3)/\alpha \end{array} \right]$

$$L_3 = \frac{L_3}{\alpha}, \alpha \neq 0$$

$AX=B$  é possível determinado  $\Leftrightarrow \text{car}(A) = \text{car}([A|B]) = 3 = \text{nº de colunas de } A$ , isto é,  $\alpha \in \mathbb{R} \setminus \{0, 1\}$ .

| Se  $\alpha = 0$  ?

$$[A|B] = \left[ \begin{array}{ccc|c} 1 & -1 & 0 & -2 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & -3 \end{array} \right] \text{ como } \text{car}(A) = 2 < \text{car}([A|B]) = 3, AX=B \text{ é impossível.}$$

| Se  $\alpha = 1$  ?

$$[A|B] = \left[ \begin{array}{ccc|c} 1 & 0 & -1 & -1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{array} \right] \xrightarrow{L_2 \leftrightarrow L_3} \left[ \begin{array}{ccc|c} 1 & 0 & -1 & -1 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 1 \end{array} \right] \text{ como } \text{car}(A) = 2 < \text{car}([A|B]) = 3, AX=B \text{ é impossível.}$$


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$A_{m \times n}$  com linhas  $L_1, \dots, L_m$  entre o espaço das linhas de  $A$  e

$$\mathcal{L}(A) = \langle L_1, \dots, L_m \rangle$$

Lema (Cap. 2.2 slide 3) exemplos

$$(i) \langle (1, 0, 1), (0, 1, -1) \rangle = \langle (0, 1, -1), (1, 0, 1) \rangle$$

$$(ii) \langle (1, 1) \rangle = \langle 2(1, 1) \rangle = \langle (2, 2) \rangle$$

$$(iii) \langle (1, 0, 1), (0, 1, -1) \rangle = \langle (1, 0, 1), (0, 1, -1) + 3(1, 0, 1) \rangle = \langle (1, 0, 1), (3, 1, 2) \rangle$$

Teorema Se  $A \in \mathbb{R}^{n \times m}$  então  $\dim \mathcal{L}(A) = \text{d}(A)$ .

$$\underline{\text{Exp}} \quad A = \left[ \begin{array}{cccc} 1 & -2 & -4 & 3 \\ 2 & -4 & -7 & 5 \\ 1 & -2 & -3 & 2 \end{array} \right] \rightsquigarrow \underbrace{\left[ \begin{array}{cccc} 1 & -2 & -4 & 3 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right]}_{= Ae \text{ escalonada}} \rightsquigarrow \left[ \begin{array}{cccc} 1 & -2 & 0 & -1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right] = A_r \text{ reduzida}$$

$((1, -2, -4, 3), (0, 0, 1, -1))$  e  $((1, -2, 0, -1), (0, 0, 1, -1))$  são bases de  $\mathcal{L}(A)$ . Temos que  $\dim \mathcal{L}(A) = 2 = \text{car}(A)$ .