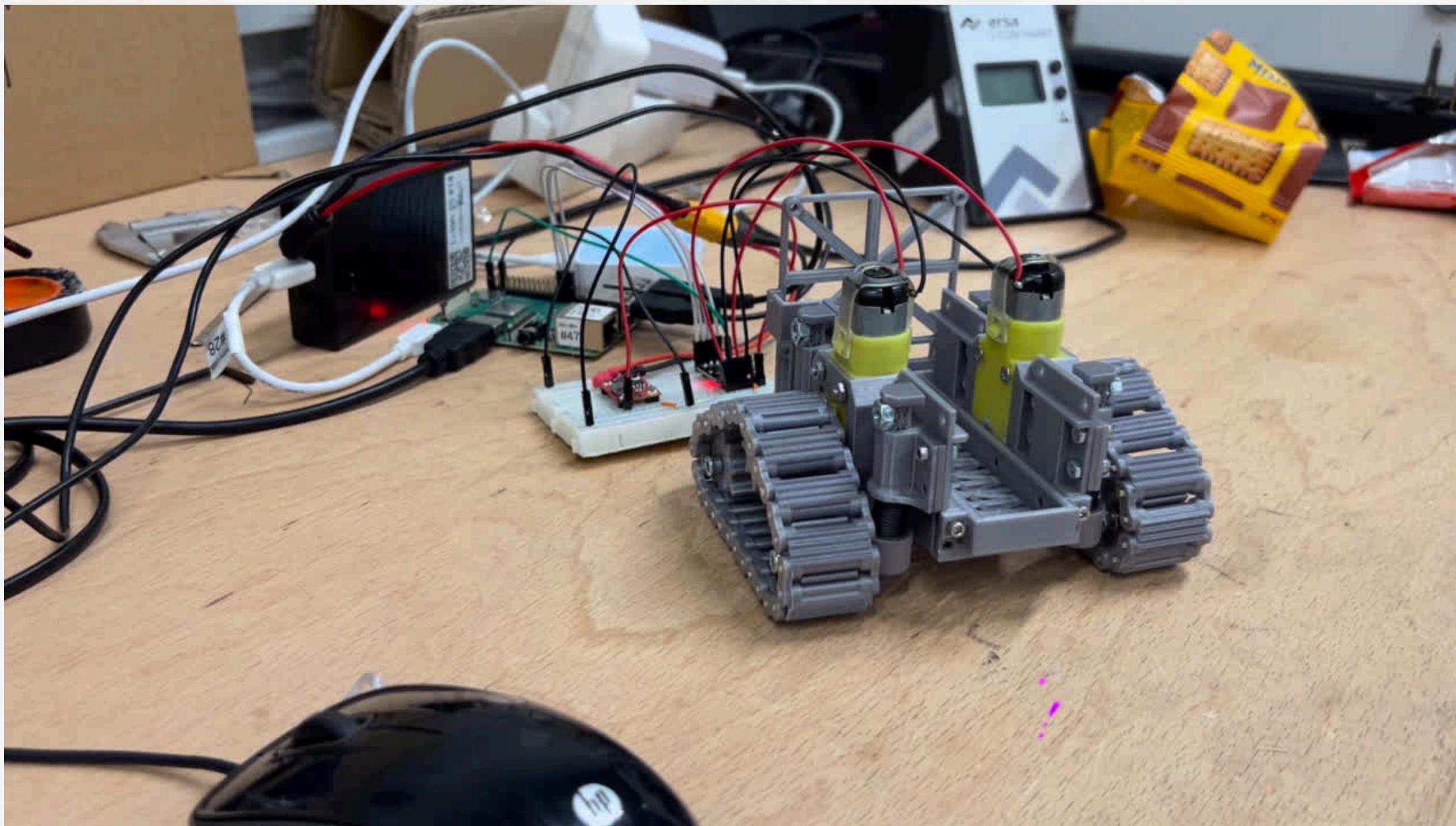


# ROBOTICS PROJECT

SPRINT ASSESSMENT 4

Julian Leclerc

# RECAP

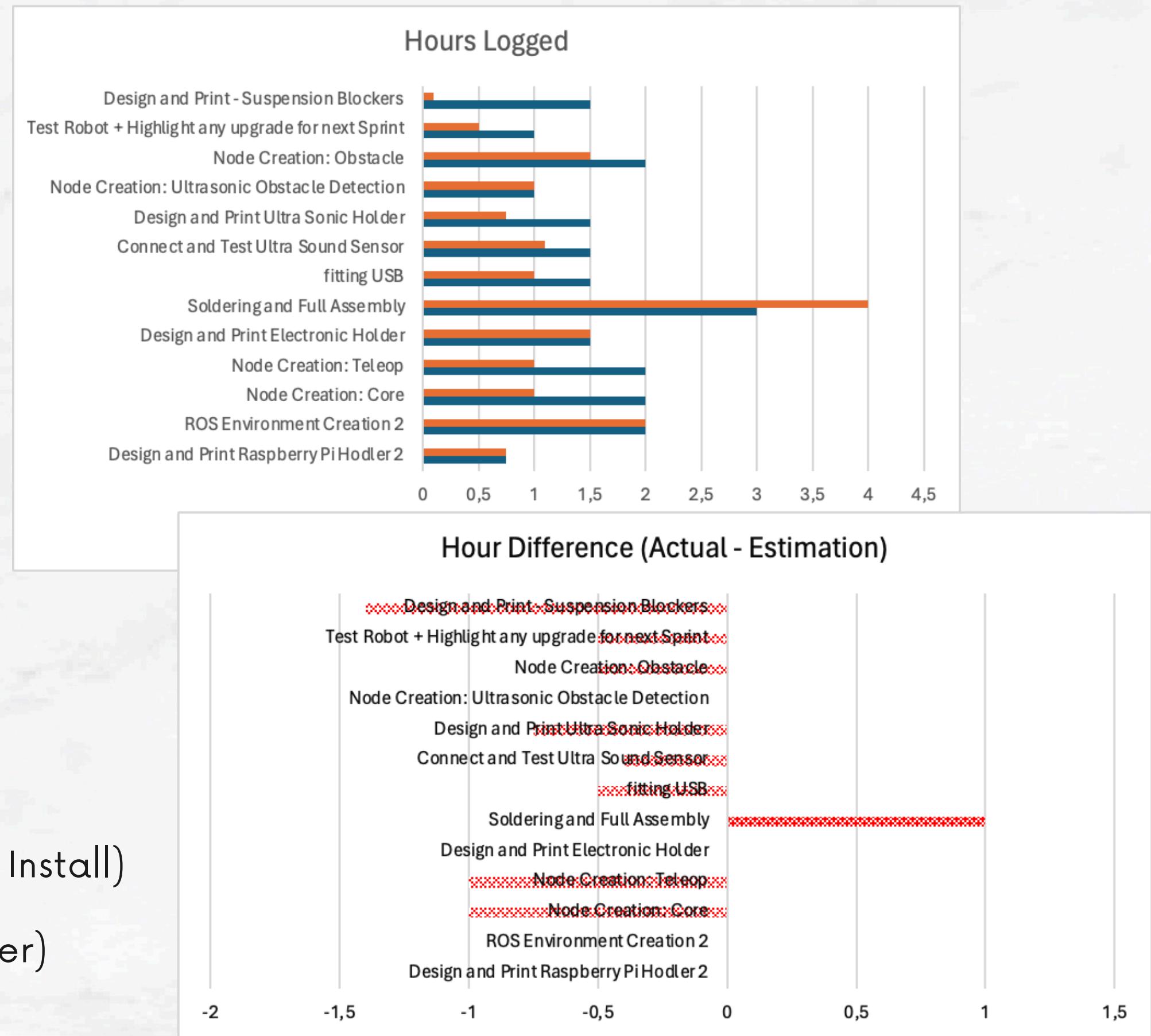


# SPRINT OVERVIEW

---

CARDS STARTED WITH: **18**  
 HOURS PLANNED: **30**  
 HOURS DONE: **23,7**  
 CORRECT TIME ESTIMATION:  
**4**  
 NOT INCLUDING MID SPRINT

- 2 cards in Backlog (Camera Test and Install)
- 0 cards in Doing
- 1 card in Feedback (Suspension Blocker)
- 0 card in Testing
- 15 cards in Done



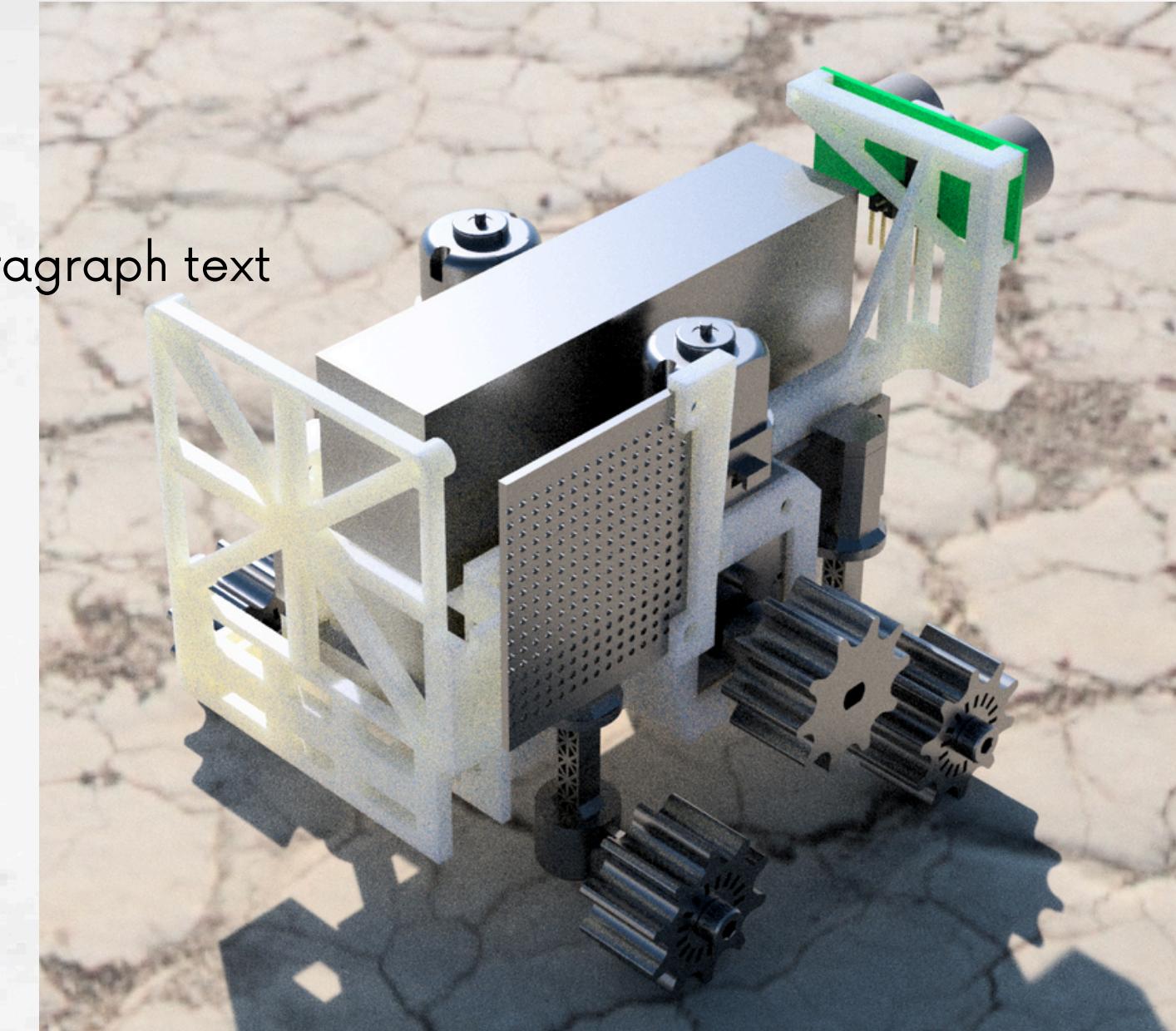
overspent: 1   underspent: 8

## DESIGN AND PRINT RASPBERRY PI HODLER 2

PLANNED 0.75 , SPENT: 0.75

**BEST  
CARDS**

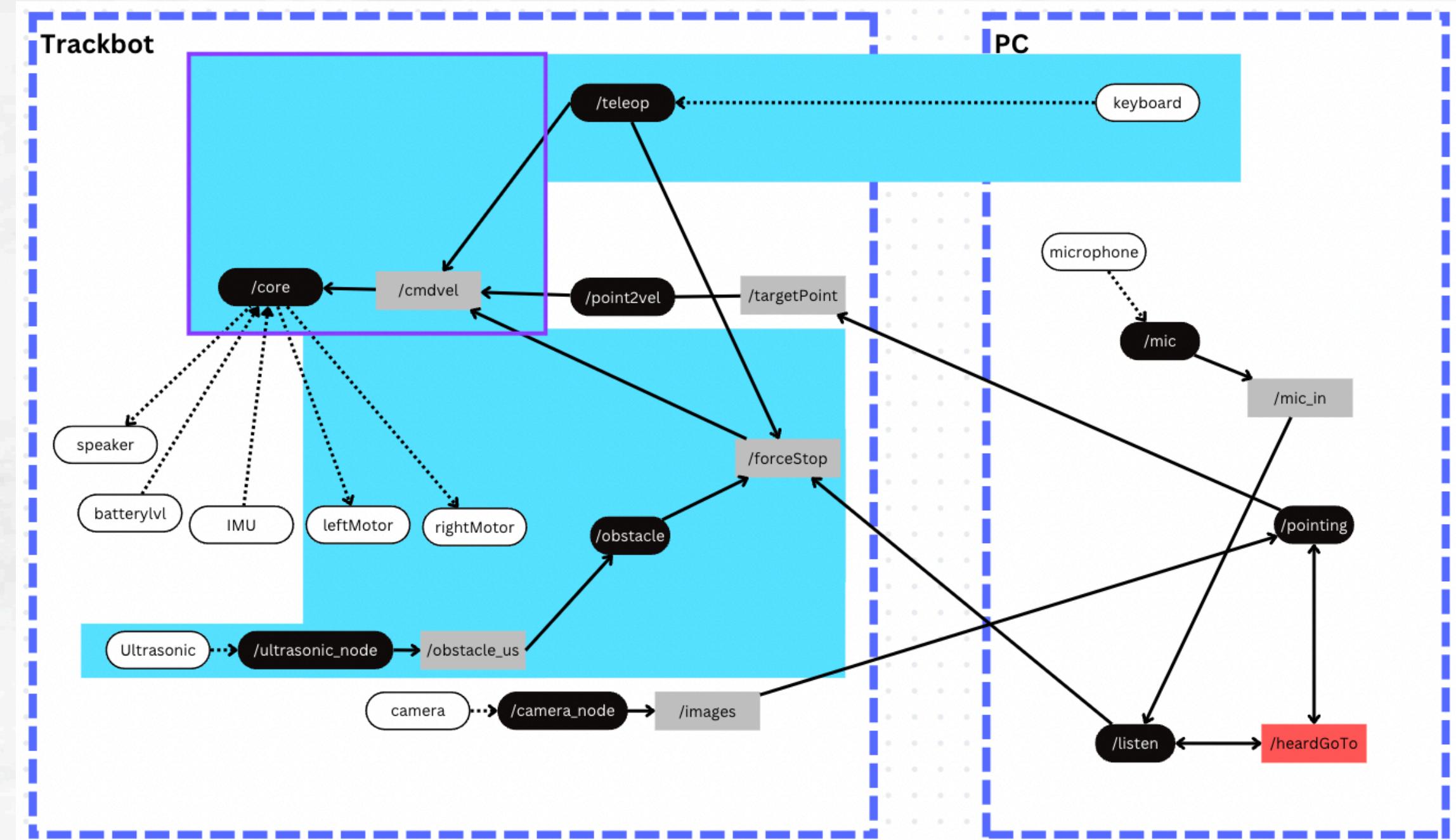
Your paragraph text



## NODE CREATION: OBSTACLE

PLANNED 2, SPENT: 1.5

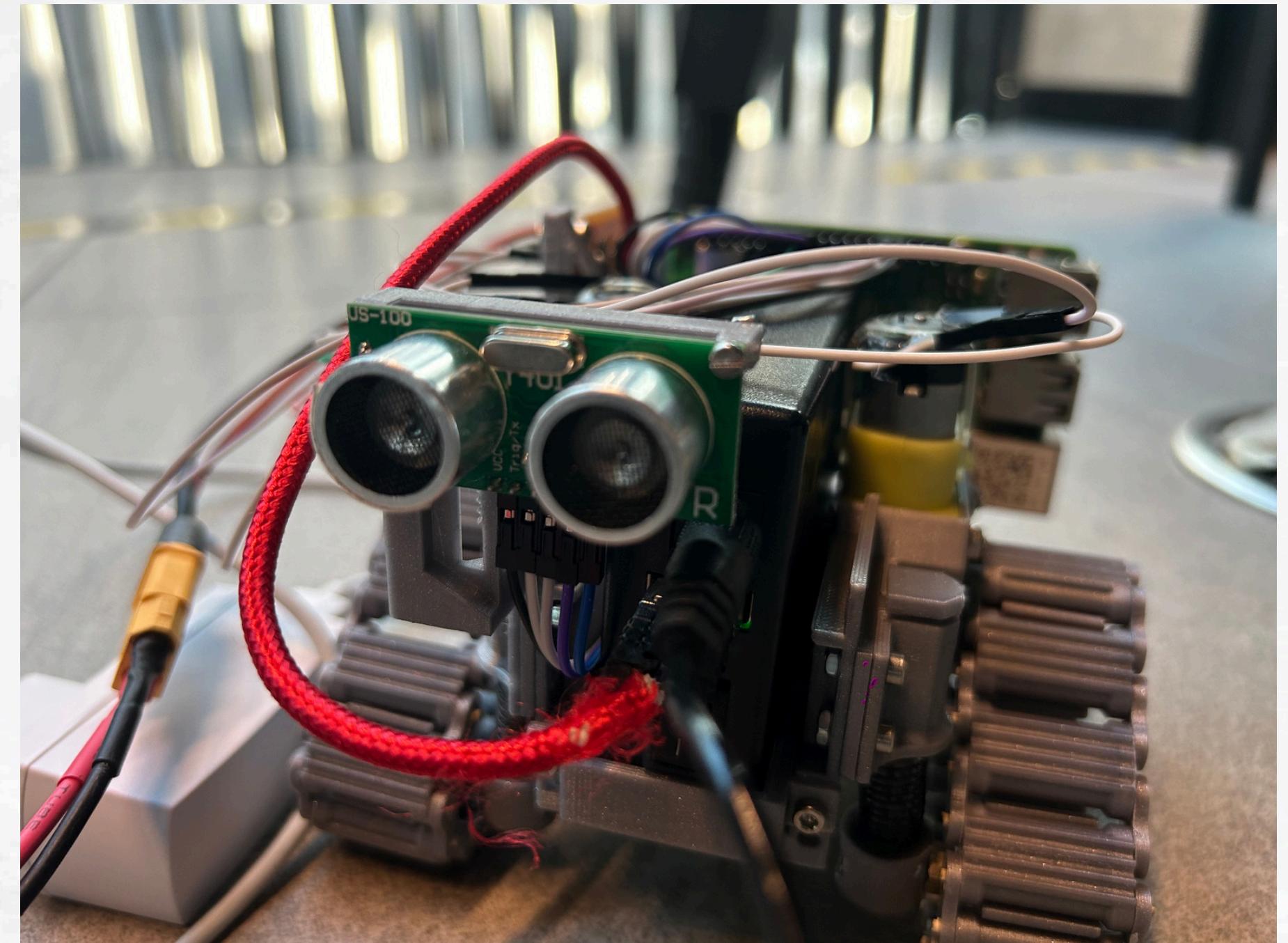
# BEST CARDS



## CONNECT AND TEST ULTRA SOUND SENSOR

PLANNED 1.5 , SPENT: 1.1

**WORST  
CARDS**



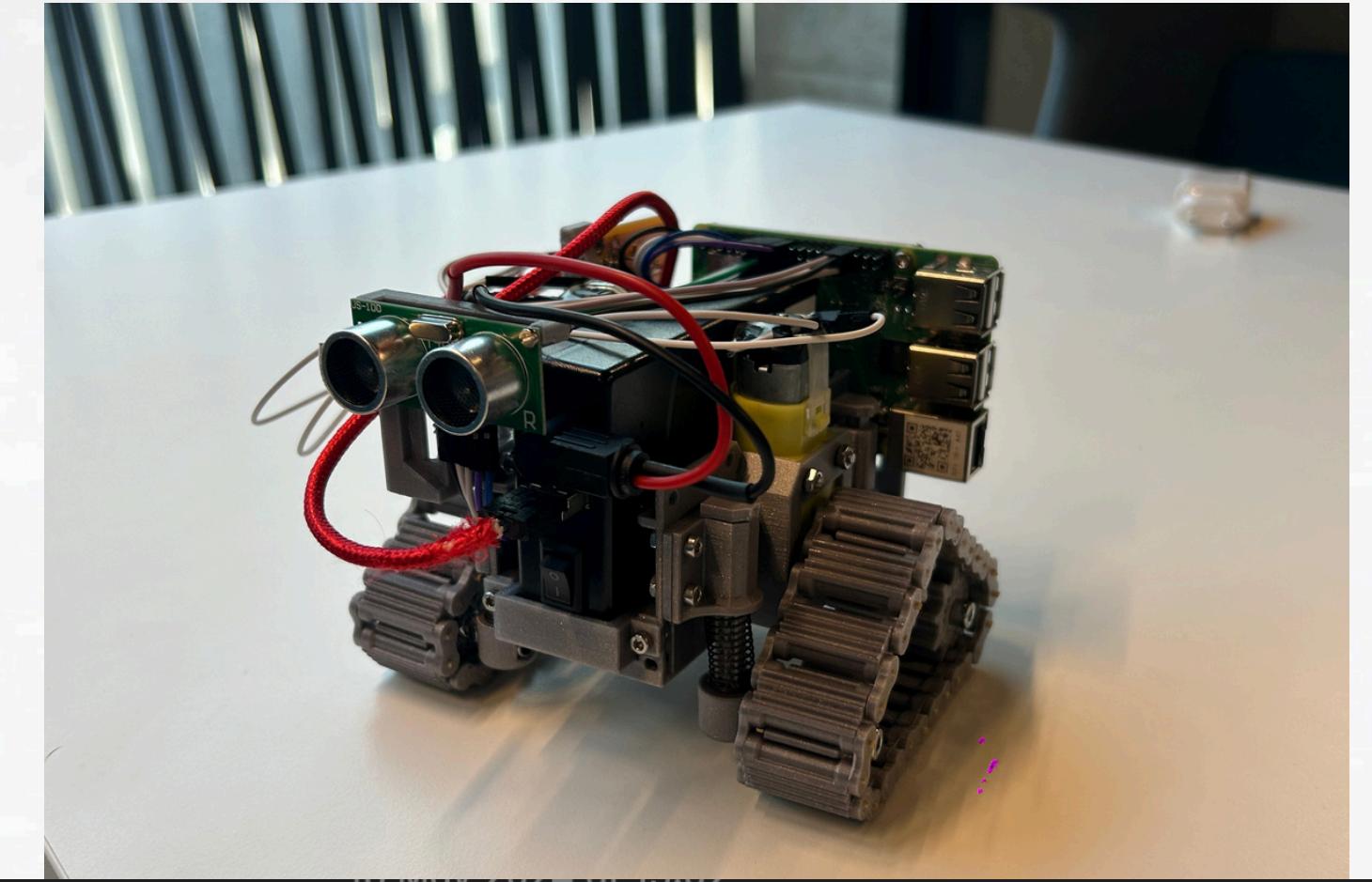
## TEST ROBOT + HIGHLIGHT ANY UPGRADE FOR NEXT SPRINT

PLANNED 1, SPENT: 0.5

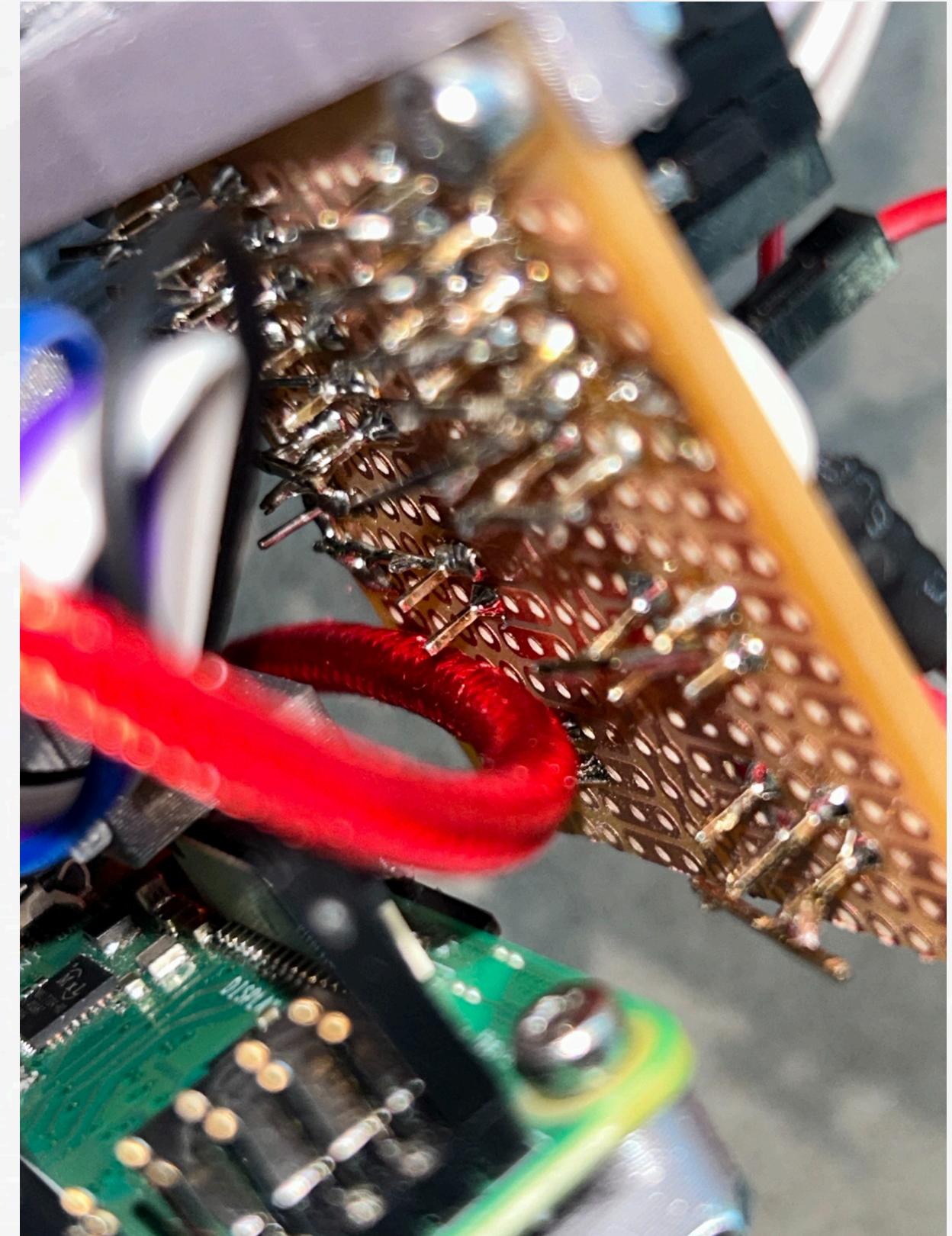
# WORST CARDS

### ROBO UPGRADES

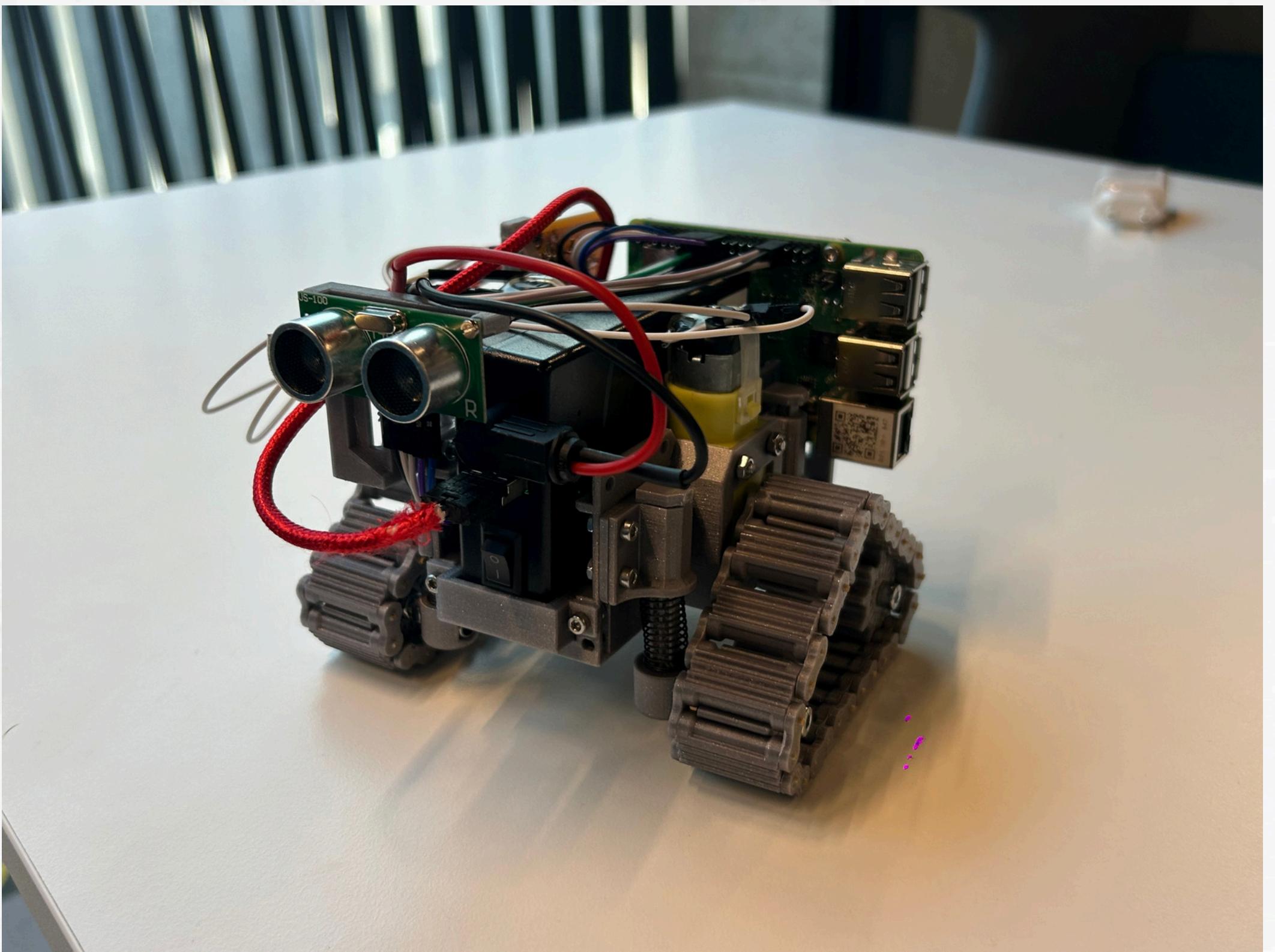
- Uneven track tension,
- Loud Wheel Sound
- Wire management (cut wires)
- Delayed response sometimes (either upgrade network or lower message amount on [ros](#))
- Left Side stops sometimes (causes maybe prev but also maybe motors)



# Most Spectacular ??



# RESULT



University of Tartu

# THANK YOU

Julian Leclerc