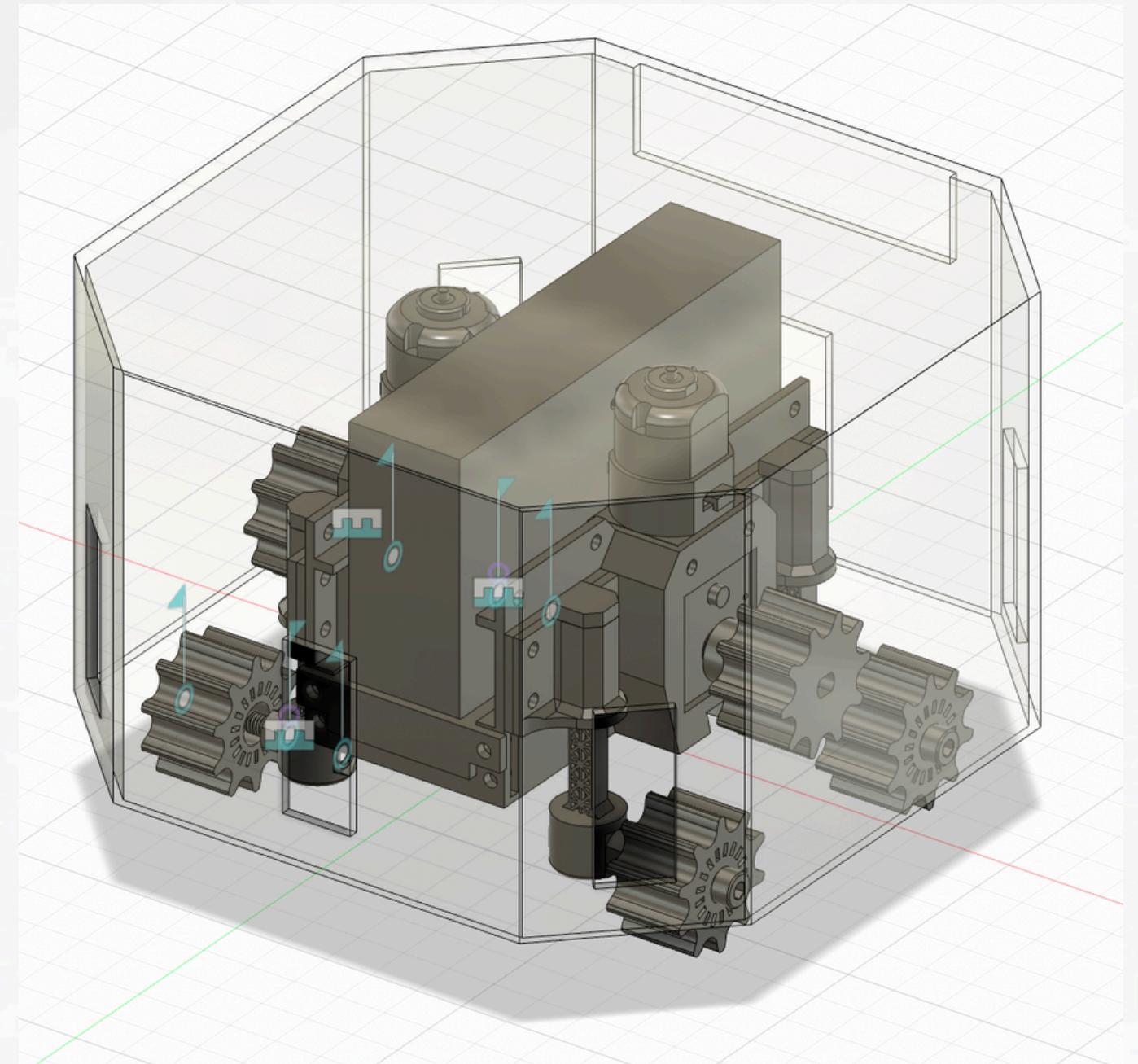
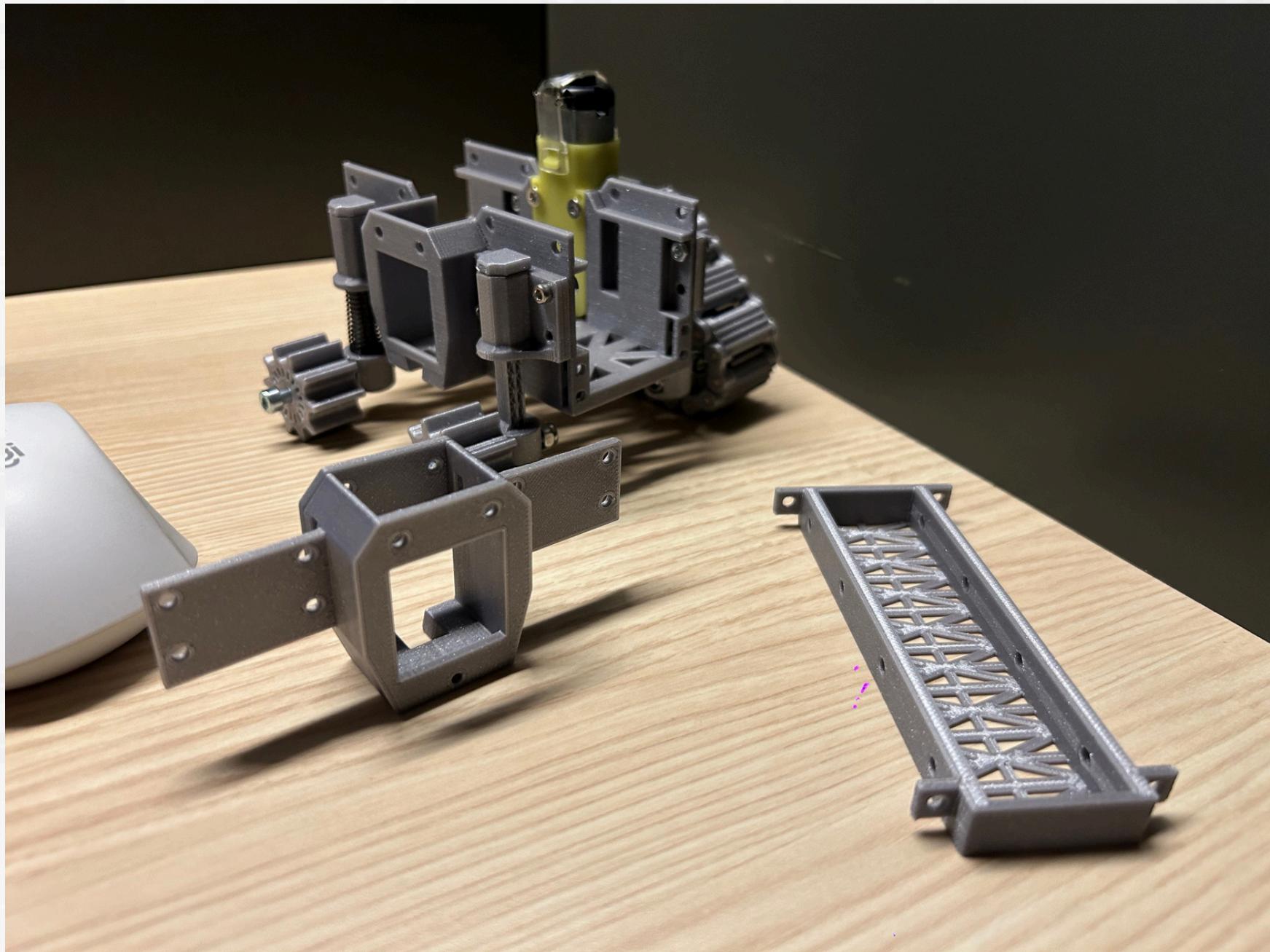


ROBOTICS PROJECT

SPRINT ASSESSMENT 3

Julian Leclerc

RECAP



Robotic Project

SPRINT OVERVIEW

CARDS STARTED WITH: **15**

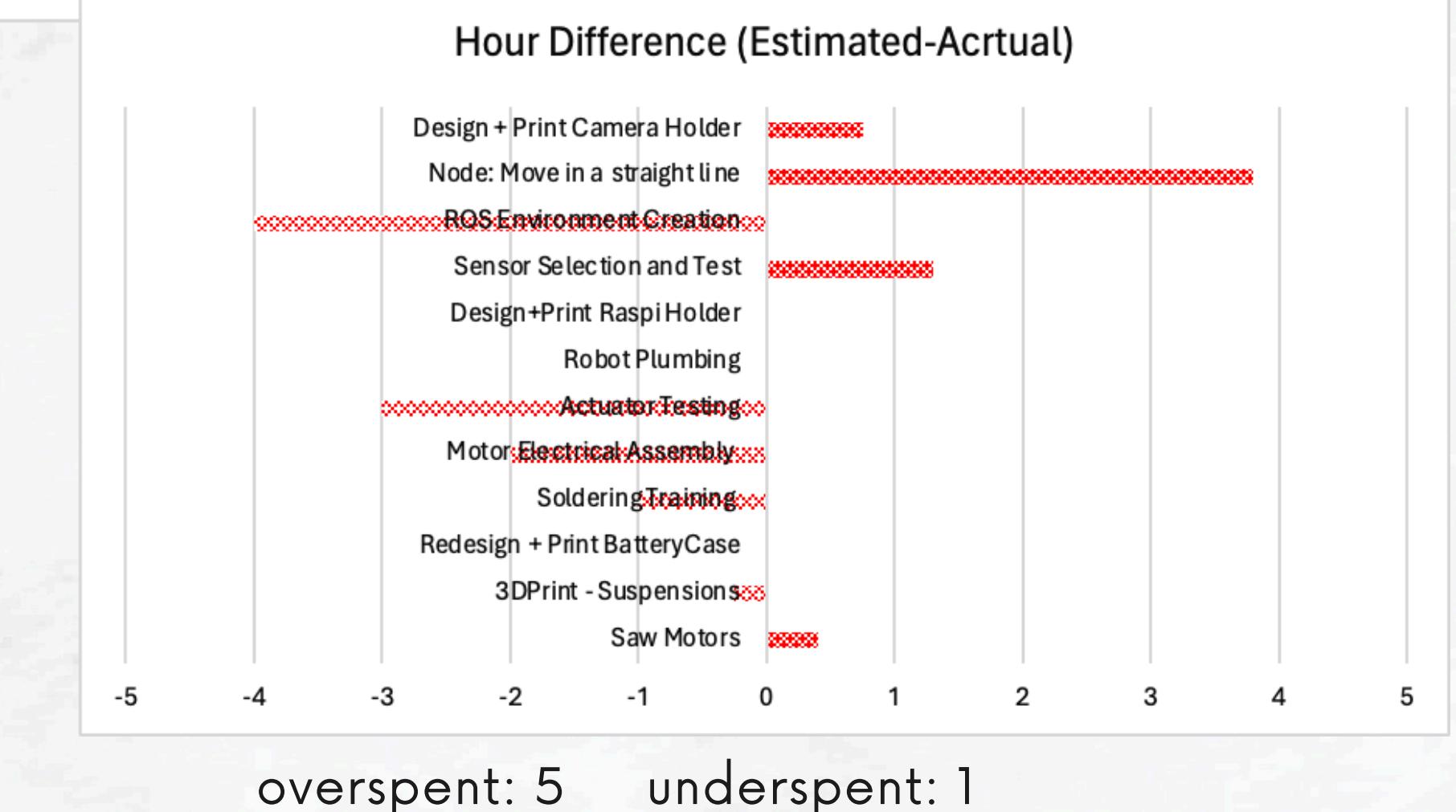
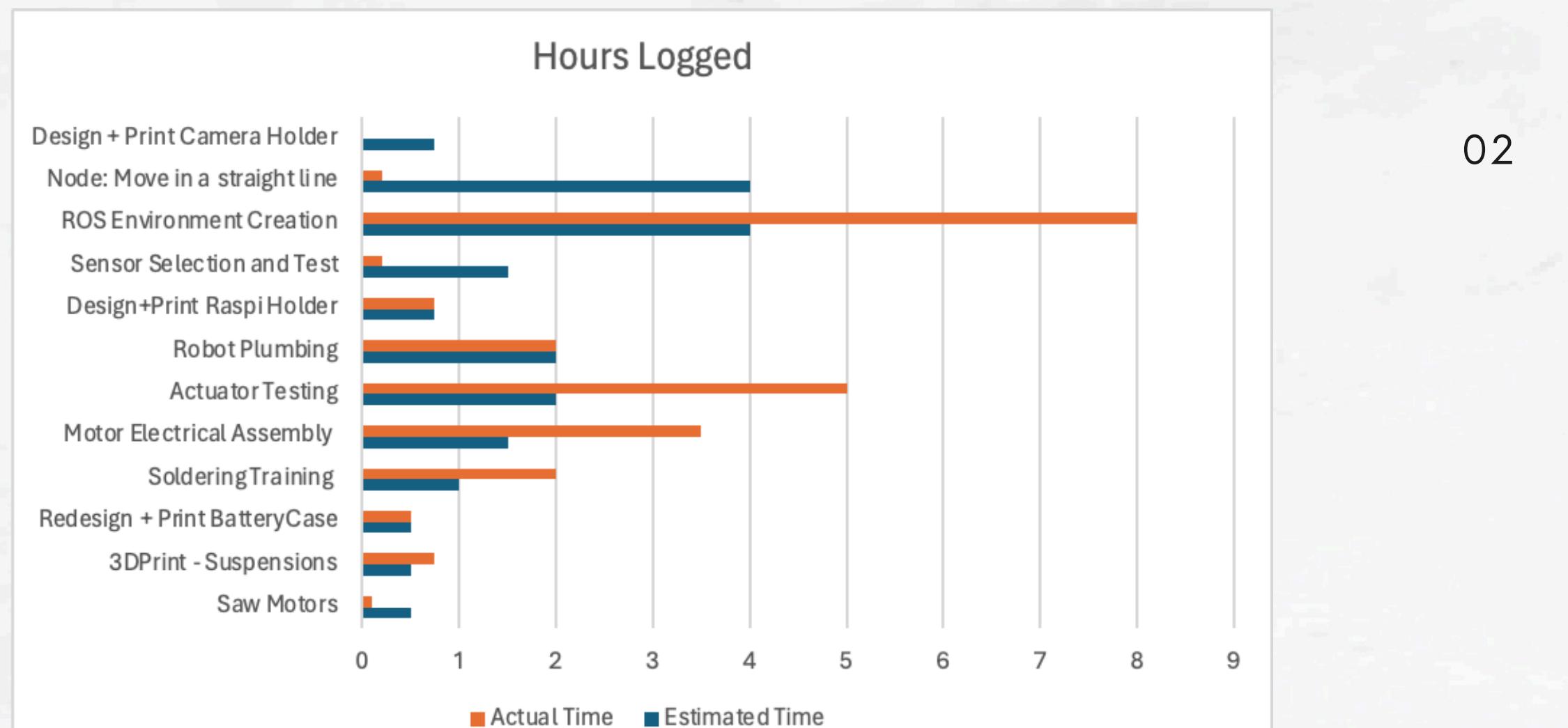
HOURS PLANNED: **26.5**

HOURS DONE: **30.5**

CORRECT TIME
ESTIMATION:
3

NOT INCLUDING MID SPRINT

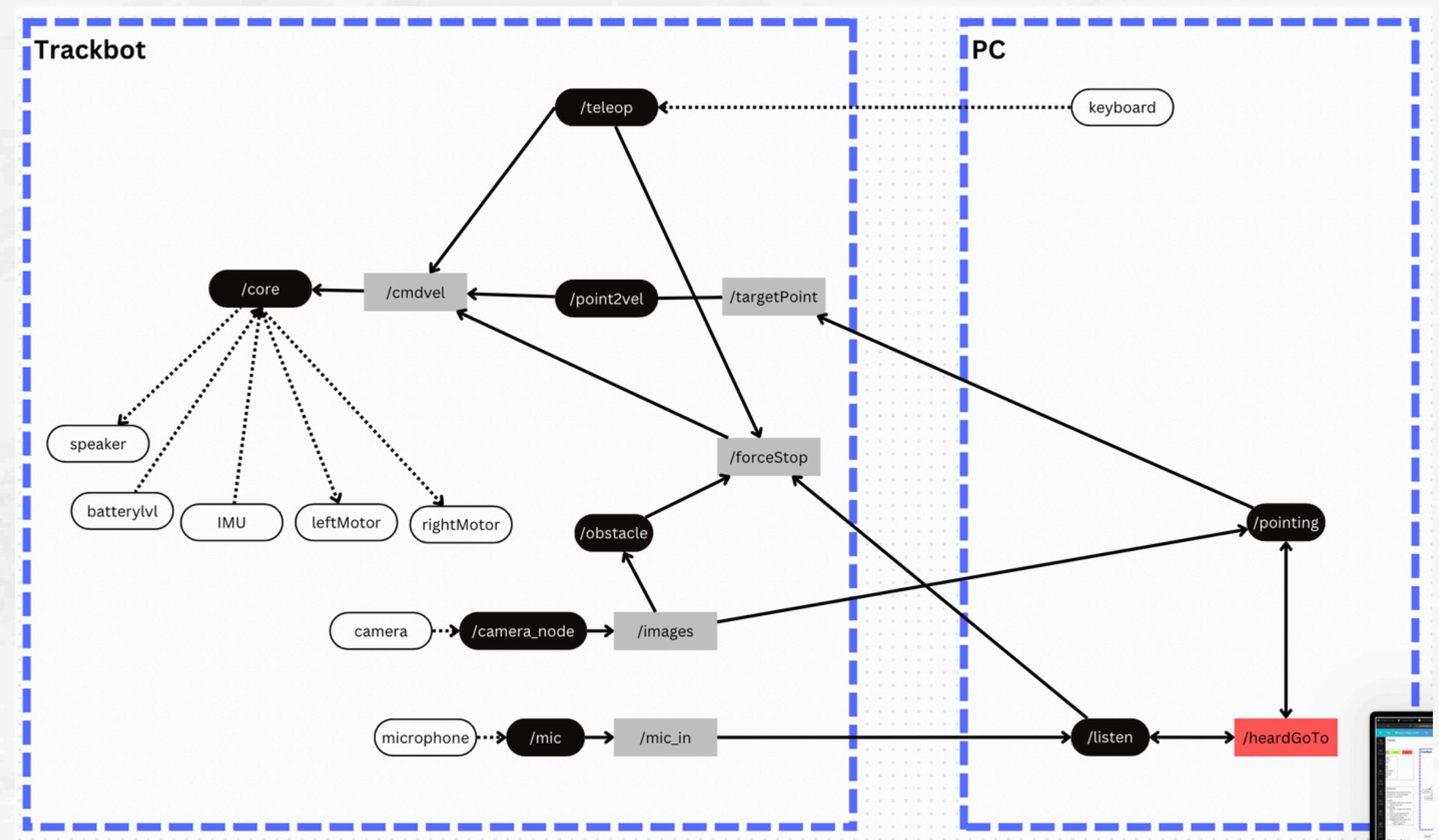
- 2 cards in Backlog (Sensor select and Print)
- 2 cards in Doing (ROS and Node creation)
- 0 card in Feedback
- 1 card in Testing (Raspi holder)
- 13 cards in Done



ROS PLUMBING

PLANNED 2, SPENT: 2

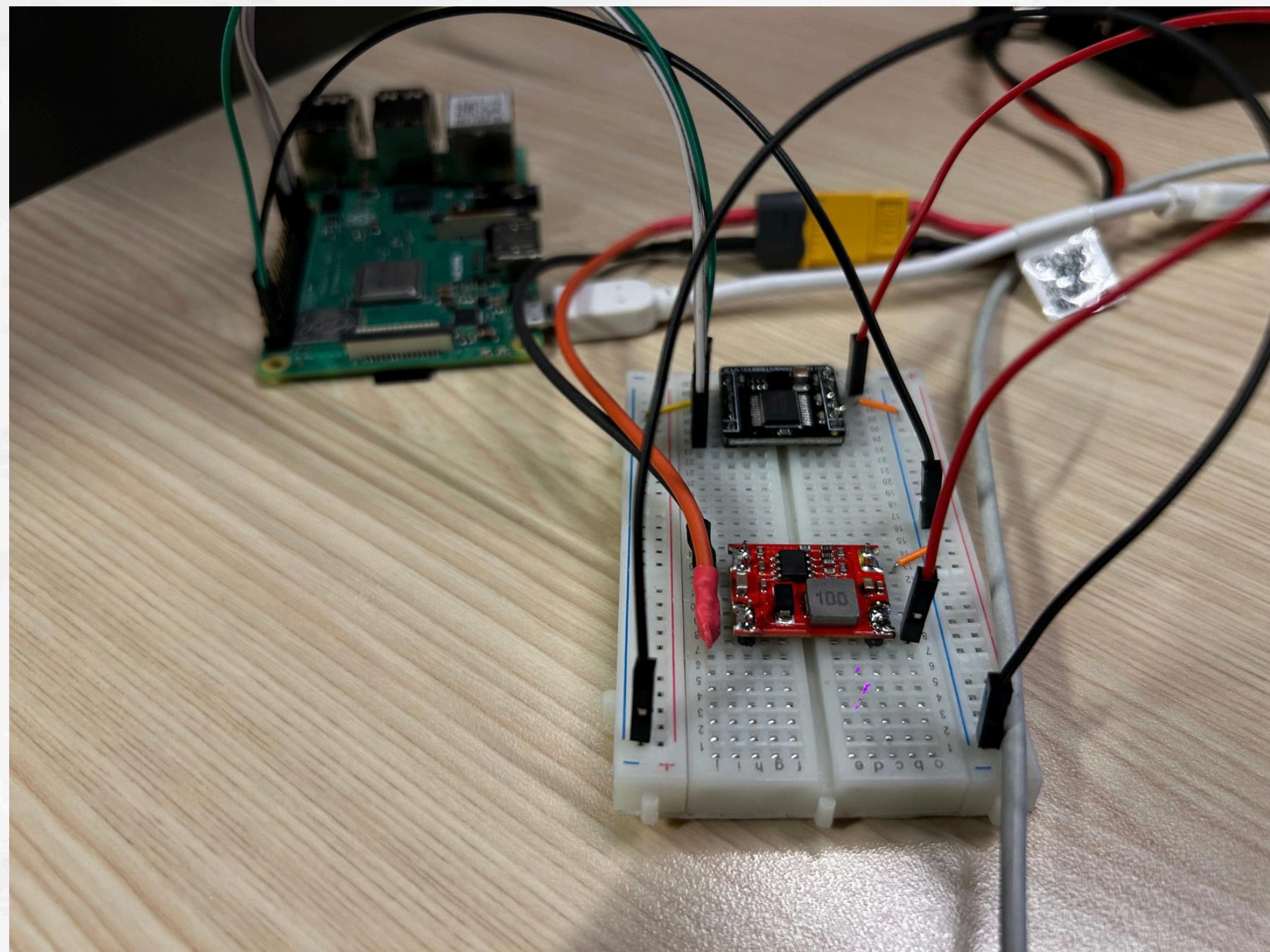
**BEST
CARDS**



MOTOR ELECTRICAL ASSEMBLY

PLANNED 1.5 , SPENT: 3.5

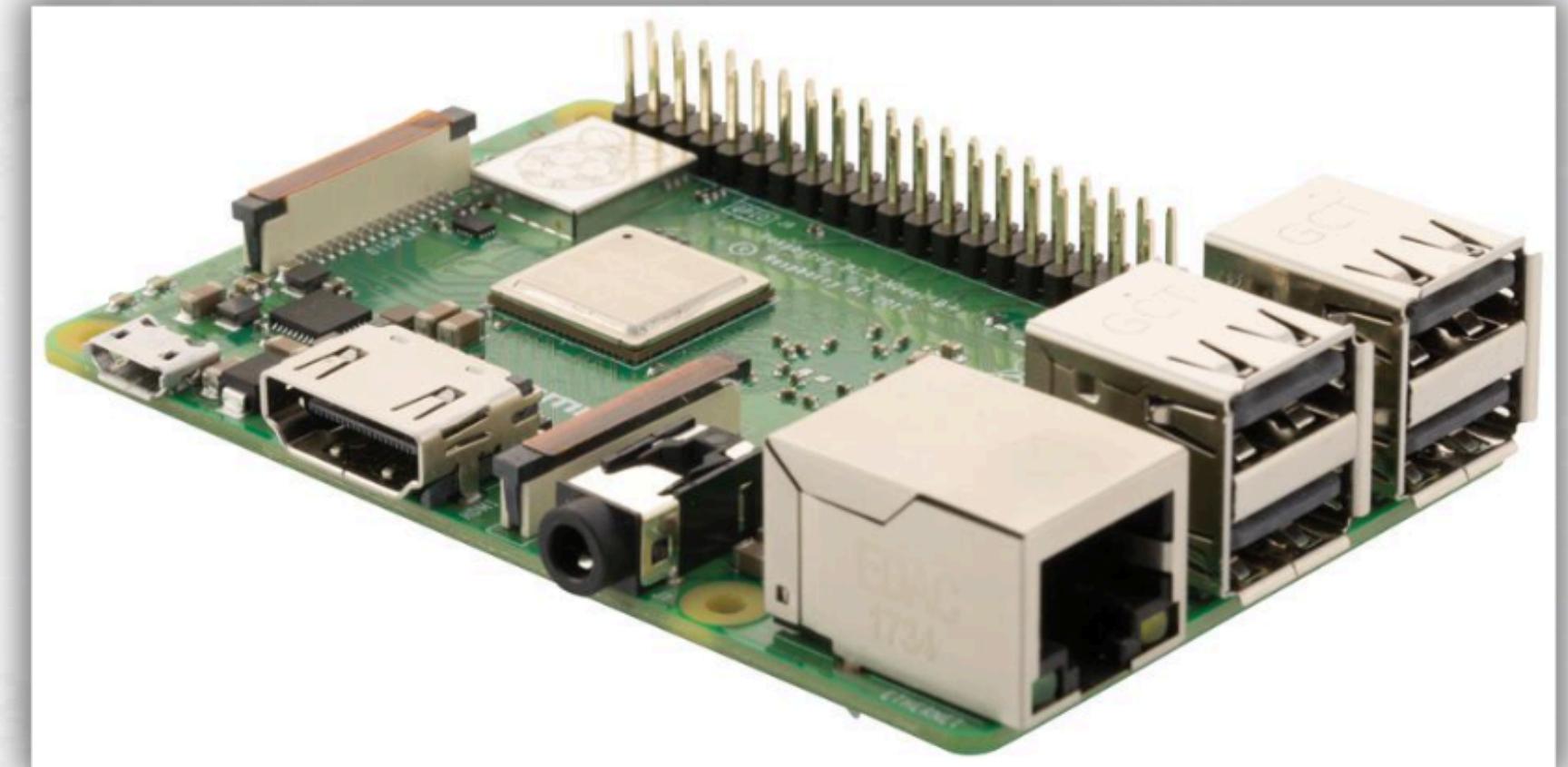
**WORST
CARDS**



ACTUATOR TESTING

PLANNED 2, SPENT: 5

**WORST
CARDS**



ROS ENVIRONMENT CREATION

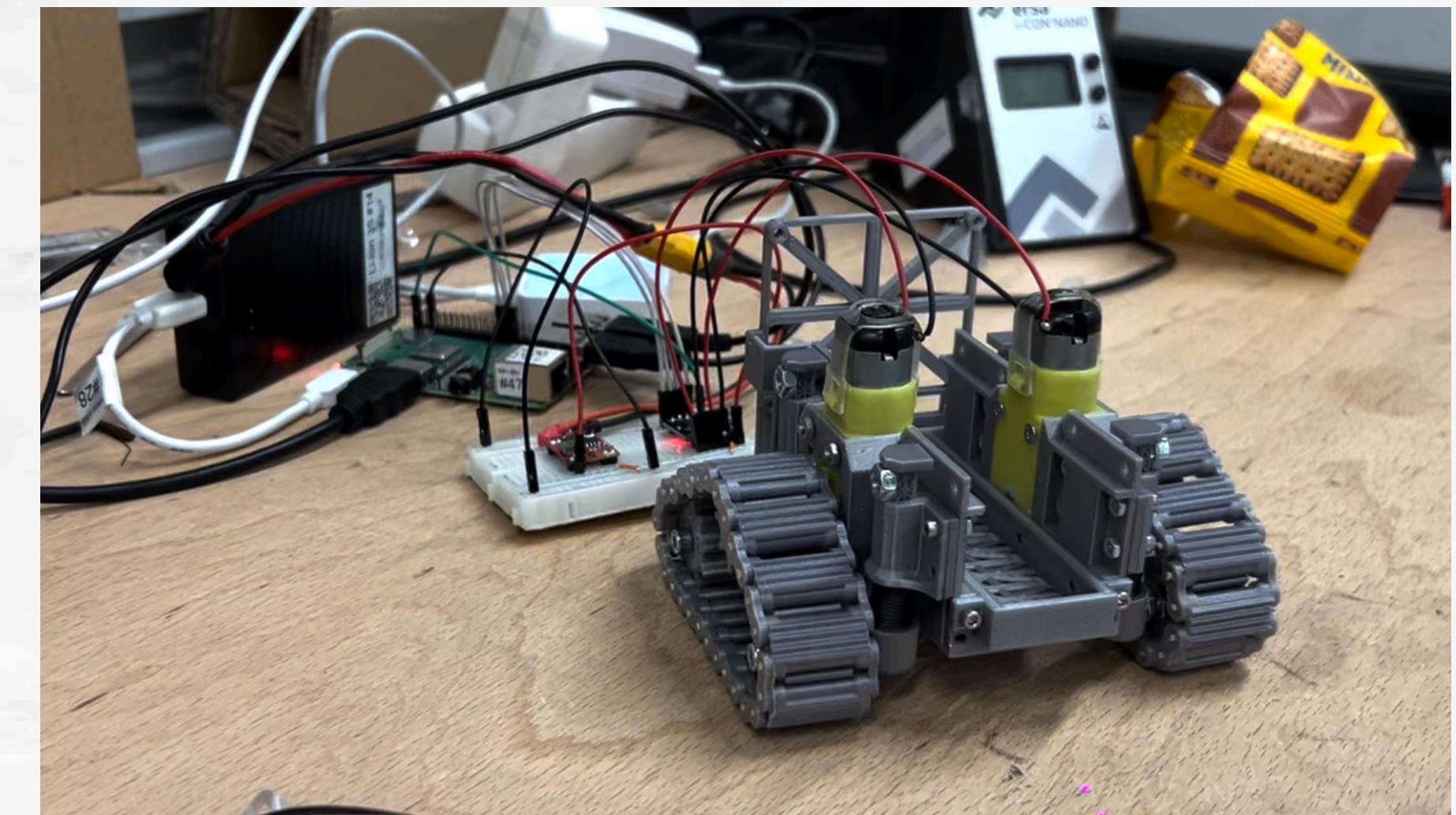
PLANNED 4, SPENT: 8

**WORST
CARDS**

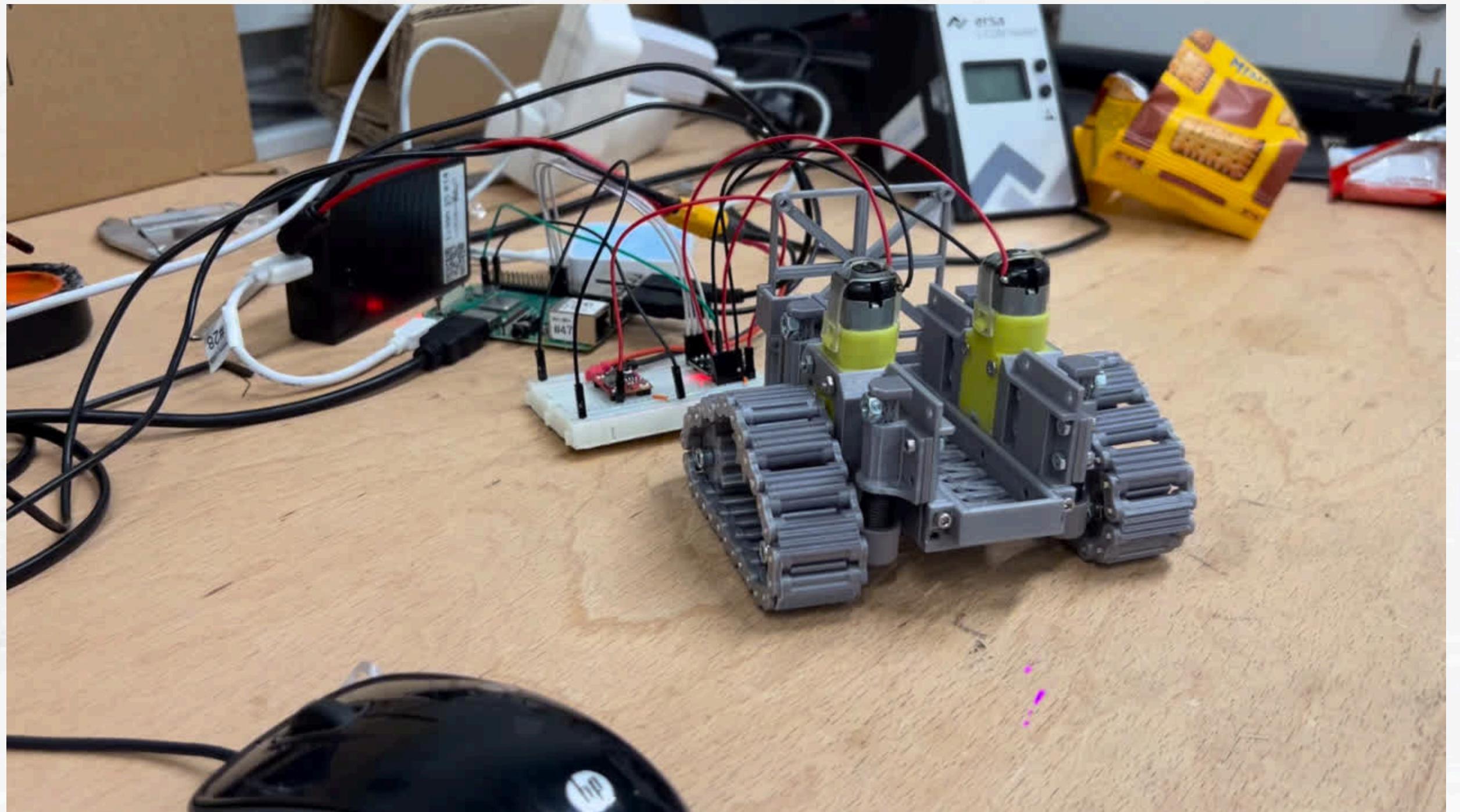
```
Julian — rosCPP [40 of 55] — ssh://ubuntu@192.168.0.102 — 80x24
Scanning dependencies of target rosCPP_generate_messages_nodejs
[ 26%] Generating Javascript code from rosCPP/Empty.srv
[ 26%] Generating Javascript code from rosCPP/Logger.msg
[ 26%] Built target rosCPP_generate_messages_cpp
[ 27%] Generating Javascript code from rosCPP/GetLoggers.srv
[ 29%] Generating Javascript code from rosCPP/SetLoggerLevel.srv
[ 31%] Generating Python srv __init__.py for rosCPP
[ 31%] Generating Python msg __init__.py for rosCPP
[ 31%] Built target rosCPP_generate_messages_nodejs
[ 31%] Built target rosCPP_generate_messages_py
Scanning dependencies of target rosCPP_generate_messages
Scanning dependencies of target rosCPP
[ 31%] Built target rosCPP_generate_messages
[ 33%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/network.cpp.o
[ 37%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/master.cpp.o
[ 37%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/subscriber.cpp.o
[ 37%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/common.cpp.o
[ 38%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/publisher_link.cpp.o
[ 40%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/service_publication.cpp.o
[ 41%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/connection.cpp.o
[ 43%] Building CXX object CMakeFiles/rosCPP.dir/src/libros/single_subscriber_publisher.cpp.o

```

Most Spectacular Success



RESULT



University of Tartu

THANK YOU

Julian Leclerc