SEARCH ALGORITHMS APPLIED TO CITIZEN SAFETY AND HARASSMENT PREVENTION

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ABSTRACT

Street sexual harassment is just one of the many manifestations of the unsafe situations that people go through in Medellín. These actions have negative repercussions such as anger and discomfort for women, them being the most affected by the lack of security in the streets. According to what has been exposed we consider that providing mobility options that consider the possibilities of harassment can contribute to the improvement of the situation previously stated. This project proposes the creation of an algorithm that takes harassment into account as a variable, to provide safer mobility alternatives to people.

Finally, for our Project, we chose the Dijkstra algorithm, a version implemented by ourselves, in which we make use of the PriorityQueue to improve search times. The results obtained are specially satisfactory, obtaining an estimated time of 5 seconds for the generation of the 3 routes, the one with the shortest distance, the one with the lowest risk of harassment and a third one that takes both variables into account when generating the routes. As observations, we can note that in general the path of the shortest route and the one with the least harassment are not usually too different from each other. And to finish we denote the great improvement that we had when implementing the algorithm, going from initial times of approximately 2 minutes to 5 -7 seconds.

Keywords

The shortest route, street sexual harassment, identification of safe routes, crime prevention

1. INTRODUCTION

Street sexual harassment is one of the main reasons people feel unsafe when it comes to transit the streets. According to "Medellín, ciudad segura para mujeres y niñas" 61,5 per cent of women, residents of communes Manrique, Villa Hermosa, La Candelaria and the corregimiento of Altavista, manifested feeling discomfort going out past 7 p.m. [7] The phenomenon is aggravated in places like the downtown, according to surveys conducted with women from commune 10, La Candelaria, shows that 57.6 per cent perceive a lot of fear in public spaces [6]. Adding to this we have robbery, for example, the stealing of vehicles in 2022 increased by 10 per cent compared to the previous year [13]. The violence among other factors threatens the citizen security of the city.

The previously stated helps us measure the levels of the problem and although it is a situation too difficult to address, we consider the importance of providing citizens with tools that allow them to have a certain degree of security while they transit through the city. Under this order of ideas, choosing between different suggested routes considering the variables of estimated time and safety of the journey is one of the tools that can help reduce harassment and perception of insecurity.

1.1 The problem

Considering what has been stated in the introduction when can put in perspective that sexual harassment is a reality and a problematic situation present in Medellín. We can define street sexual harassment as a particular type of violence, both physical and verbal, some of its expressions are, sexually explicit comments, follow-up, public masturbation, touching, and exhibitionism among others. Among some of the feelings generated by sexual harassment are feeling invaded, vulnerable, and insecure in places where people have been previously harassed, but they are not limited to it being the feelings of shame, helplessness, and anger, other of its many repercussions [11].

Under this order of ideas, we contemplate a tool that provides the user with mobility alternatives, which consider both safety and travel time, an option that helps prevent situations of harassment. In our specific case, three route options will be calculated considering the two variables mentioned above, so the user can choose the route based on their needs.

1.2 Solution

As a solution to the problem planted in section 1.1. We proposed the implementation of a variant of Dijkstra's algorithm, explained deeper in section 4.2.1, which roughly works by creating a list of unvisited nodes with all nodes, saving the origin node, and after that, visiting the neighbour's nodes of this, with the final purpose to find the node that his connection weight is less of all nodes, and starts a new comparison with the new node as the origin. In our case, we decide to implement 3 different algorithm types, one with the least longitude between the origin node and destination node, the second, to show the route with the less rate of harassment, and the third one, to do an average of the longitude and the harassment and show the way with the lest of both combined.

1.3 Structure of the article

Next, in Section 2, we present work related to the problem. Then, in Section 3, we present the datasets and methods used

in this research. In Section 4, we present the algorithm design. Then, in Section 5, we present the results. Finally, in Section 6, we discuss the results and propose some directions for future work.

2. RELATED WORK

Below, we explain four works related to finding ways to prevent street sexual harassment and crime in general.

2.1 Safe & the city

It´s a free personal security navigation app that allows you to plan and share routes while making sure to keep you safe. The user would receive a notification while walking on streets previously marked by the police as dangerous and high theft possibility. The app counts with a quick access call to 999, so the user can communicate with emergency services. It also has a section to report in case the user feels unsafe, and their reviews can help others who are going to use the same route. Safe & the city is currently available in all UK cities, also in Berlin and Germany [16].

2.2 Safest Route Detection Application

This is a project developed as a web application with react.js and the app uses an algorithm to compute the safest route, it uses the user data to do the calculations of throwing the safest path. The implemented algorithm is developed to generate a decision tree, and this is how was implemented. The documentation doesn't specify the algorithm that the application uses [14].

2.3 The Safest Path via Safe Zones

This project uses safe zones as reference points, for example, if the defined path is outside the reference zones the path is considered dangerous, studying the Euclidean and spatial network variants.
This is a graph that represents the paths and the safes zones

The project doesn't use a specific algorithm, they first transform the data into a graph of safe zones, origin, and destination, then any shortest path algorithm may be applied to find the safest path, but in the project, they proposed a novel edge pruning algorithm that utilizes hyperbolas [1].

2.4 Bypass: An app that provides you with the city zones that you must avoid

While using Google Maps you will always have the shortest path, the ones that avoid traffic jams. However, when you use the app in the city it doesn't specify the zones that you must avoid according to their bad reputation, with this premise Bypass was presented, an app that through a map would show you which parts of the city you should avoid, based on its bad reputation, the application would do the calculation of the danger of the place with information that was obtained in the network and the valuation of the users. The system identifies using red squares, with more or less intensity, the streets that are better to avoid, and if you were to be on one of those dangerous routes, the application highlights the fastest route to get out of it. It also had the option to mark points of interest like hospitals, and shops, among others [8]. Currently, this project is no longer available.

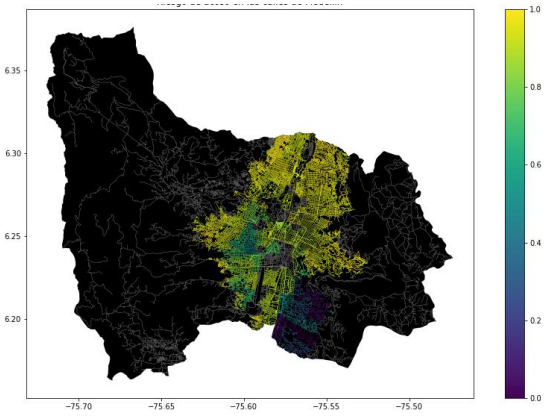
3. MATERIALS AND METHODS

In this section, we explain how the data were collected and processed, and then different alternative path algorithms that reduce both the distance and the risk of sexual street harassment.

3.1 Data collection and processing

The map of Medellín was obtained from *Open Street Maps* (OSM)[1] and downloaded using the Python API[2] OSMnx. The map includes (1) the length of each segment, in meters; (2) the indication of whether the segment is one-way or not, and (3) the known binary representations of the geometries obtained from the metadata provided by OSM.

For this project, a linear combination (LC) was calculated that captures the maximum variance between (i) the fraction of households that feel insecure and (ii) the fraction of households with incomes below one minimum wage. These data were obtained from the 2017 Medellín quality of life survey. The CL was normalized, using the maximum and minimum, to obtain values between 0 and 1. The CL was obtained using principal components analysis. The risk of harassment is defined as one minus the normalized CL.



[1] https://www.openstreetmap.org/

[2] https://osmnx.readthedocs.io/

Figure 1 presents the calculated risk of bullying. The map is available on GitHub[3] .

Figure 1. The risk of sexual harassment was calculated as a linear combination of the fraction of households that feel unsafe and the fraction of households with income below one minimum wage, obtained from the 2017 Medellín Quality of Life Survey.

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3.2 Algorithmic alternatives that reduce the risk of sexual street harassment and distance

In the following, we present different algorithms used for a path that reduces both street sexual harassment and distance.

3.2.1 Dijkstra's Algorithm

The published algorithm in 1956, was named after his Dutch creator Edsger Dijkstra [19]. Is an algorithm that is used to find the shortest path in a node graph. Given a start node and a finish node the Dijkstra algorithm starts exhausting the connections of the start node, to say that this node is already solved, it will put temporary tags over all connected nodes, and said tag is conformed by the name, and the distance of the start node of the connection, the tags will be temporary until the container node be solved, in this case, the tag that contains the minimum distance will be saved. This process will repeat until the target node is reached, from this final node it will return from the path that contains the labels with the lowest distance upon reaching the start node, giving us the shortest path. The worst-case complexity of this algorithm is O(N ^ 2), where n is the number of nodes in the graph [4].

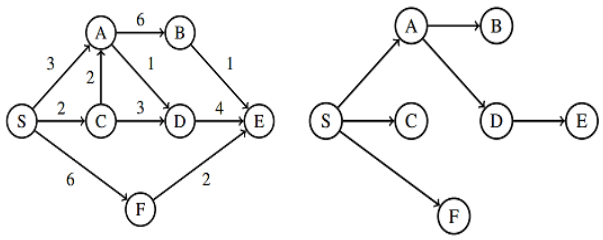


Figure 2: Dijkstra's Algorithm. Brilliant.org, 2022 https://brilliant.org/wiki/dijkstras-short-path-finder/

3.2.2 A star Algorithm

Also known as A*, was presented for the first time in 1968 by Peter E. Hart, Nils J. Nilsson, and Bertram Raphael. It is classified within the search algorithms in graphs of heuristic or informed type, widely used to find a possible and efficient route between two points, with the lowest possible cost [17]. It works by labelling the different nodes according to the cost of reaching the target. This tag has the function of showing the current distance from the source node to the tagged node and indicating the distance from the node to be tagged to the destination node. It creates a path tree, like Dijkstra's algorithm [2]. The main difference between A star is that each node uses a function that gives an estimate of the total cost of the route. Due to its nature, the limitations of this algorithm depend on the quality of the heuristic, being unfeasible if the latter is not optimal. The quality of the heuristics, as we have already said, plays a fundamental role in terms of the algorithmic complexity of A star, being able to reach O(E) complexity with a very good, or worse. [9].

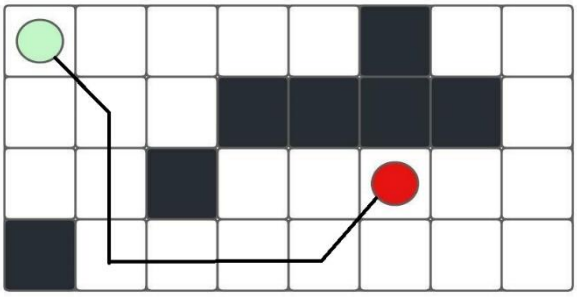


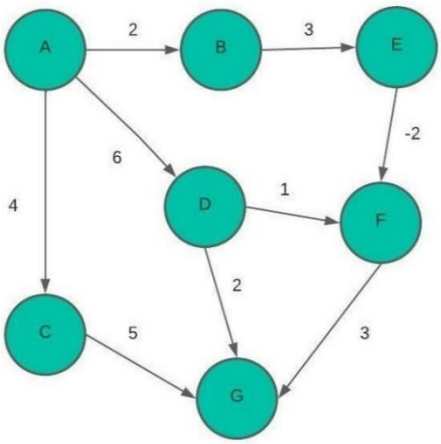
Figure 3: Example of A algorithm.*

3.2.3 Bellman Ford Algorithm

It is an algorithm for searching a graph or tree data structure. It starts at the root of a tree and goes as far from it as possible by that route then returns until it finds an unexplored route and travels through it [10]. Each node calculates the distance between it and all others within a path and stores that information on a path. Each node then sends its table to adjacent nodes. when a node receives a distance table from adjacent nodes it calculates the shortest path to the other nodes and updates its table. A special feature of this algorithm is that it supports negative figures and allows to detection of the existence of an absorbent circuit. The complexity of this algorithm can range from O(E) at best to O(N ^ 3) at worst [18].

[3]https://github.com/mauriciotoro/ST0245Eafit/tree/master/proyecto/Datasets

[4]https://github.com/julianvb03/ST0245-5001.git



Node	Shortest cost from A
A	0
B	2
C	4
D	6

Figure 4: Table of Bellman Fort algorithm.

3.2.4 Depth- First Search (DFS)

Depth-first search is an algorithm for searching a graph or tree data structure. The algorithm starts at the root node of a tree and descends as far as it can in a given branch, then backwards until it finds an unexplored path, the explore. The algorithm does this until the entire graph has been explored. Many problems in computer science can be thought of in terms of graphs. For example, network analysis, route mapping, planning, and spanning tree finding are graph problems. To analyse these problems, search algorithms such as depth-first search are useful. This algorithm has a complexity of O(N + V) where n is the number of vertices and v are the number of edges. [3].

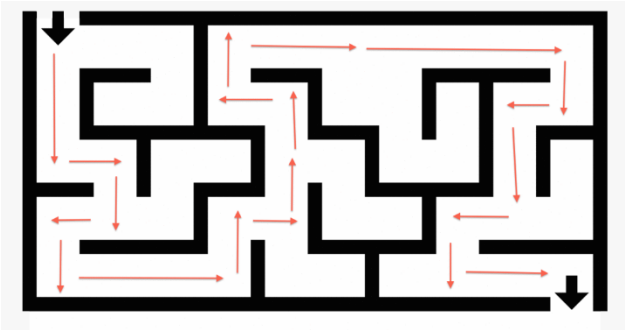


Figure 5: Example of DFS algorithm. Brilliant.org 2022, from https://brilliant.org/wiki/depth-first-search-dfs/

4. ALGORITHM DESIGN AND IMPLEMENTATION

In the following, we explain the data structures and algorithms used in this work. The implementations of the data structures and algorithms are available on Github4 ..

4.1 Data Structures

The data structure that we used to represent the streets of the city was a graph, whose structure in Python is represented as a dictionary, this is a unique origin from which we can start to our destination; the key is another dictionary, which his key is all adjacent nodes to the origin, and the content is a tuple with the distance and the harassment.

The data structure is presented in Figure 2.

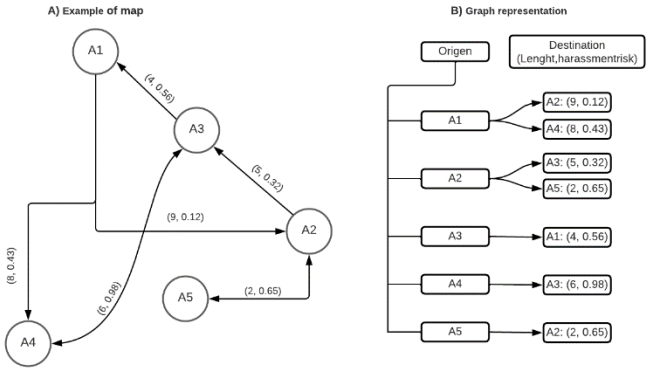


Figure 2. An example street map is presented in (a) and its representation as an adjacency list in (b).

4.2 Algorithms

In this paper, we propose an algorithm for a path that minimizes both the distance and the risk of street sexual harassment.

4.2.1 Algorithm for a pedestrian path that reduces both distance and risk of sexual street harassment

The algorithm that we select finally was Dijkstra's algorithm, whose functionality we are going to explain.

To the initial node, we assign the weight as cero, because from this we start the comparations, with the rest nodes of the graph, at the rest we assign a big arbitrary value and then assign 'None' as the predecessor. Subsequently, we create a group of non-visited nodes. While the list of nodes is not empty. For the current node A, considering his adjacent nodes non-visited N with a weight, and depending on the version of the algorithm is going to be harassment risk or an average of both. If the current weight plus the weight of A is less than the sum of the current plus the weight of N, update the weight of A, and save N as a predecessor. When finally visit all the near nodes of A, delete the group of non-visited nodes, then select the node with less weight and mark it as a new node, afterwards repeat the process.

The algorithm is exemplified in Figure 3.

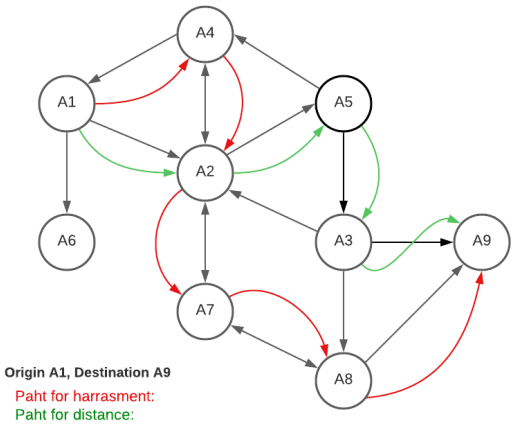


Figure 3: Calculation of a path that reduces both distance and risk of harassment (please feel free to change this figure if you use a different algorithm).

4.2.2 Calculation of two other paths to reduce both the distance and the risk of sexual street harassment

Finally, our program will return 3 possible paths, taking the following variables into consideration, first the distance that according to the need could be a need. As a second path, we decided to make one that would take the risk of harassment as an absolute priority, which is the one that we wanted to place the most emphasis on with the project, and the third and final one is one that is calculated by raising the distance to the power of risk, with in order to provide an alternate route different enough to represent another route option.

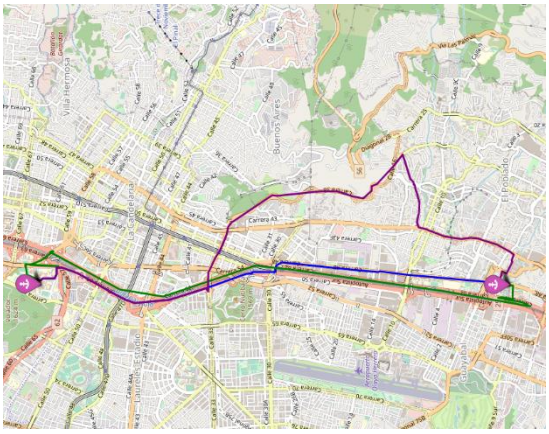


Figure 4: Map of the city of Medellín showing three pedestrian paths that reduce both the risk of sexual harassment and the distance in meters between the EAFIT University and the National University.

4.3 Algorithm complexity análisis

While the most robust version of Djikstra has a complexity of O(N ^ 2) , the version with PriorityQueue, in this way we start a PriorityQueue that starts with the origin, having a tuple that stores the first variable with which the comparison, in this way the top of the queue will always be compared, which in the long run with the stop case will save enough comparisons to optimize the algorithm. This added to the fact that our graph is represented as an adjacency list allows us to have an optimal data structure in memory, more specifically the complexity of the algorithm is O((V + E) * logV). Where V is the number of vertices and E the number of edges, this represented in our graph would be interpreted as. V are the coordinates marked as unique origins and E would be the connections that the streets have with each other. Finally, the complexity of the PriorityQueue operations would be O(logN) for the insert and delete operations and O(1) to obtain the smallest element.

In terms of memory, the data structure that we use to represent the graph is the adjacency list structure, which finally has a memory complexity of O(V + E) where V is the number of nodes and E is the number of edges of the graph.
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Algorithm	Time complexity
Djikstra	O((V + E) * logV).

Table 1: Time complexity of the Dijkstra algorithm V is the number of vertices and E is the number of edges.

Data Structure	Complexity of memory
Adjacency List	O(V + E) = O(V)

Table 2: Memory complexity of the adjacency list where V is the number of nodes and E the number of edges.

4.4 Algorithm design criteria

Finally, the version of Djikstra, an algorithm that we explain in more depth in Dijkstra's Algorithm section. The version that we implemented in our code was one that used Priority Queues to optimize the complexity of the algorithm. In the early stages of development, the execution time of the algorithm was one of our main problems, so we looked for the most optimal way to improve it. The operation that this fulfils is to allow us to always compare the shortest route that we have at the moment, in order to increase the probabilities of arriving in the shortest possible time of travel to our destination, in which case the algorithm will take it as a stop case.

5. RESULTS

In this section, we present some quantitative results on the three pathways that reduce both the distance and the risk of sexual street harassment.

5.1 Results of the paths that reduce both distance and risk of sexual street harassment

Next, we present the results obtained from *three paths that reduce both distance and harassment*, in Table 3.

Origin	Destination	Distance	Risk
Eafit	Unal	7,510 m	0.744
Eafit	Unal	10,430 m	0.473
Eafit	Unal	10,050 m	0.595

Distance in meters and risk of sexual street harassment (between 0 and 1) to walk from EAFIT University to the National University.

5.2 Algorithm execution times

In Table 4, we explain the ratio of the average execution times of the queries presented in Table 3.

Calculate the execution time for the queries presented in Table 3.

Calculation of v	Average run times (s)
v = time	7.514 s
v = harassment	7.514 s
v = average of both	7.514 s

Table 4: *Algorithm* name execution times *Dijkstra*

6. CONCLUSIONS

After testing the algorithm multiple times, we can conclude that it is highly optimal and functional, as opposed to our first versions which were slow and inefficient, this project has also taught us how through software we can start projects that positively impact the community in this case through the prevention of sexual harassment, and especially how much is learned by putting knowledge into practice.

6.1 Future work

In the future we would like to direct the course of this project to our personal interests, in this case we would like to create a web page in which we can make use of what has been developed here to complement it with our knowledge in that area, it would also be interesting to consider being able to bring a version to mobile systems, which represents a good challenge in the future to believe in terms of knowledge.

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