Group 67 - Research Paper

Deep Learning for Object Recognition on a Mobile Robot Julian Weisbord, Miles McCall, Michael Rodriguez Oregon State University CS 463 Spring 2018

Abstract—The research paper is the write up of our research findings. It includes the methods and technologies we tested in our project and the results from those experiments. This document acts as the conclusion to the research aspect of our project.

Index Terms—Deep Learning, Online Learning, Object Recognition, Mobile Robot

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I. INTRODUCTION

Network Model

Accuracy Training

1

2

Our project is research oriented, meaning we spent time experimenting and investigating different technologies and techniques. Our software pipeline has several major programs that interact with each other to collect and process of our data. For each of these steps we looked into alternative solutions to the problem, and analyzed details such cost benefit analyses and the potential to scale technologies as the classification model grows.

II. AREAS OF RESEARCH

While the main goal of our project was to create a fully functional software pipeline, we incorporated research into every component of the pipeline. The problem of sequential online learning is not solved by one perfect algorithm or software library

- A. Data Gathering
- B. Image Cropping
- C. Neural Network Model
- D. Online Learning Techniques

III. RESULTS



Fig. 1: Accuracy Training

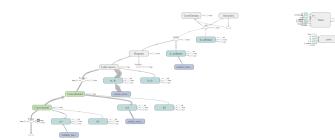


Fig. 2: Network Model

IV. CONCLUSION
APPENDIX