

Math 136.382 Final Exam Solutions
Summer 2006

$$\textcircled{1} \quad N = C(1 - be^{-kt}) \quad (k > 0)$$

Assume C is known

$$\frac{N}{C} = 1 - be^{-kt}$$

$$\left(1 - \frac{N}{C}\right) = be^{-kt} \quad \textcircled{1}$$

$$\ln\left(1 - \frac{N}{C}\right) = \ln b - kt. \quad \textcircled{1}$$

$$\text{let } Y = \ln\left(1 - \frac{N}{C}\right) \quad \textcircled{1}, \text{ so } Y = -kt + c$$
$$c = \ln b \quad \textcircled{1}$$

For least-squares

$$\left. \begin{aligned} (\sum t_i^2)(-k) + (\sum t_i)c &= \sum t_i Y_i \\ (\sum t_i)(-k) + nc &= \sum Y_i \end{aligned} \right\} \quad \textcircled{3}$$

$$\text{ie. } \left(\sum_{i=1}^n t_i^2 \right)(-k) + \left(\sum_{i=1}^n t_i \right) \ln b = \sum_{i=1}^n t_i \ln\left(1 - \frac{N_i}{C}\right)$$
$$\left(\sum_{i=1}^n t_i \right)(-k) + n \ln b = \sum_{i=1}^n \ln\left(1 - \frac{N_i}{C}\right) \quad \textcircled{3}$$

② (a) Note: $\Delta^2 y_i$ should be constant & has

average value $\frac{4+4+3+6+3+4+5+2}{8}$
 $= \frac{31}{8} \approx 4$

Thus, assume $\Delta^2 y_i = 4$ (since the polynomial has integer coefficients & hence must give integer values only)

Corrected table

x_i	y_i	Δy_i	$\Delta^2 y_i$
1	2	5	
2	7	9	4
3	16	13	4
4	29	17	4
5	46	21	4
6	67	25	4
7	92	29	4
8	121	33	4
9	154	37	4
10	191		

Corrections shown

6 corrections

(b) need only 3 data pts - use first three
 $y = ax^2 + bx + c$

→
$$\begin{aligned} 2 &= a + b + c \\ 7 &= 4a + 2b + c \\ 16 &= 9a + 3b + c \end{aligned}$$

$$\begin{aligned} 5 &= 3a + b \\ 9 &= 5a + b \\ 4 &= 2a \end{aligned}$$

$$\begin{aligned} a &= 2 \\ b &= -1 \\ c &= 1 \end{aligned}$$

$$y = 2x^2 - x + 1$$

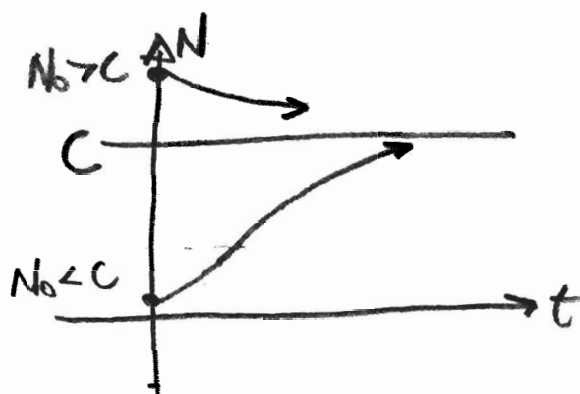
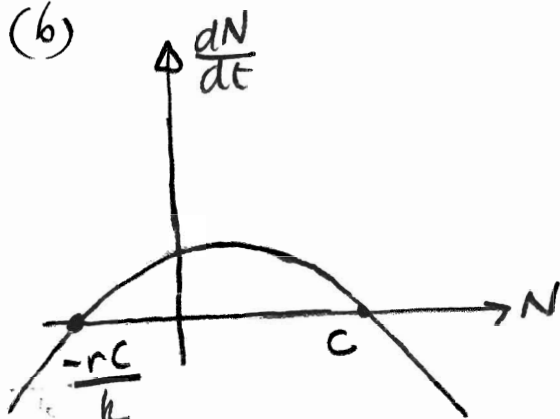
$$(3) (a) \frac{dN}{dt} = kN \left(1 - \frac{N}{C}\right) + i$$

$$i = r(C - N)$$

$r > 0$ so $i > 0$
when $N < C$.

$$\begin{aligned} \frac{dN}{dt} &= kN \left(1 - \frac{N}{C}\right) + rC \left(1 - \frac{N}{C}\right) \\ &= (kN + rC) \left(1 - \frac{N}{C}\right) \end{aligned}$$

(b)



note: $-\frac{rc}{k} < 0$

$$(c) \quad \eta = N + \frac{rc}{k} \Rightarrow \frac{d\eta}{dt} = \frac{dN}{dt}$$

$$\Downarrow$$

$$N = \eta - \frac{rc}{k}$$

$$= \left(k \left(\eta - \frac{rc}{k}\right) + rC\right) \left(1 - \frac{\eta - \frac{rc}{k}}{C}\right)$$

$$= k\eta \left(\frac{C - \eta + \frac{rc}{k}}{C}\right)$$

$$= k\eta \left[\frac{C(1 + \frac{r}{k}) - \eta}{C} \right]$$

$$= k\eta \left(1 + \frac{r}{k}\right) \left[\frac{1 - \frac{\eta}{C(1 + \frac{r}{k})}}{1 + \frac{r}{k}} \right]$$

$$= k^* \eta \left[1 - \frac{\eta}{C^*} \right]$$

with $k^* = k \left(1 + \frac{r}{k}\right) > k$
 $C^* = C \left(1 + \frac{r}{k}\right) > C$

(d) $\eta = \frac{C^*}{1 + Fe^{-k^*t}}$

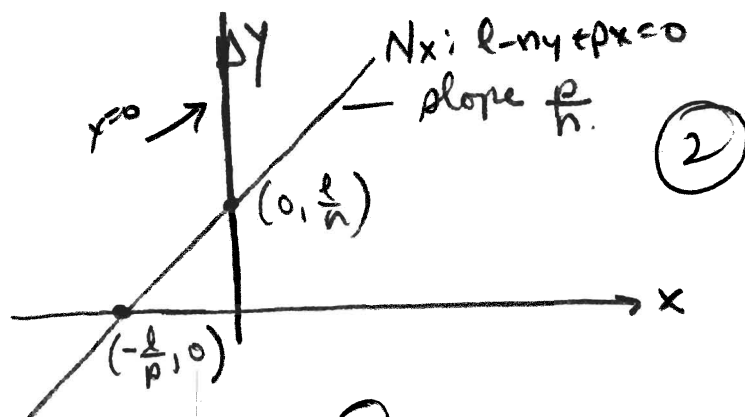
(e) But $\eta = N + \frac{rC}{k}$, $k^* = k \left(1 + \frac{r}{k}\right)$
 $C^* = C \left(1 + \frac{r}{k}\right)$

so $N + \frac{rC}{k} = \frac{C \left(1 + \frac{r}{k}\right)}{1 + Fe^{-k \left(1 + \frac{r}{k}\right)t}}$

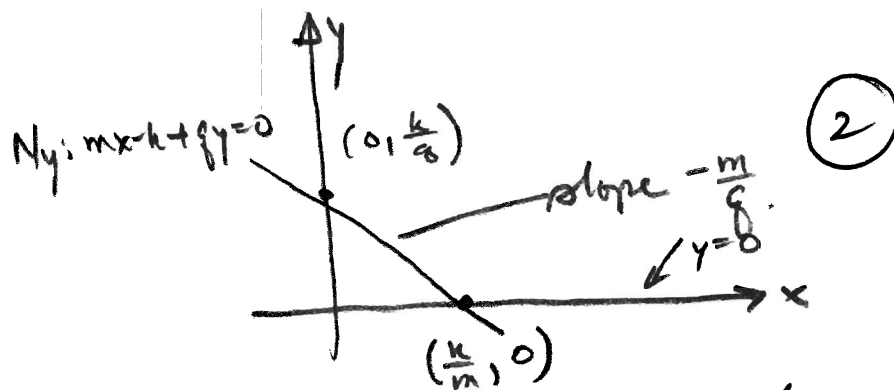
$\Rightarrow N = \frac{C \left(1 + \frac{r}{k}\right)}{1 + Fe^{-k \left(1 + \frac{r}{k}\right)t}} - \frac{rC}{k}$

$$\begin{aligned} \textcircled{4} \quad \frac{dx}{dt} &= x(l - ny) + px^2 \\ \frac{dy}{dt} &= y(mx - k) + gy^2 \end{aligned} \quad \left. \vphantom{\begin{aligned} \frac{dx}{dt} &= x(l - ny) + px^2 \\ \frac{dy}{dt} &= y(mx - k) + gy^2 \end{aligned}} \right\} \frac{k}{g} > \frac{l}{n}$$

(a) nullclines: for x : N_x : $x=0$ or $l - ny + px = 0$ ①
 $\rightarrow y = \frac{l}{n} + \frac{p}{n}x$ ②

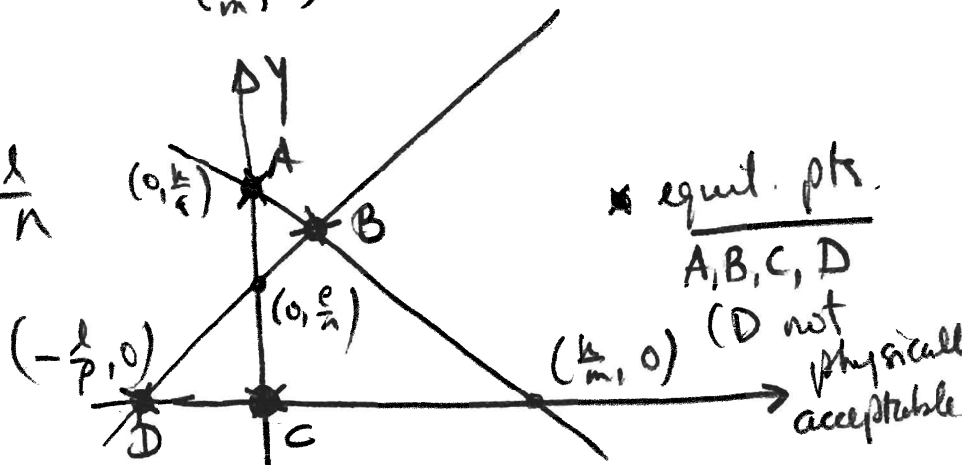


for y : N_y : $y=0$ or $mx - k + gy = 0$ ①
 $y = \frac{k}{g} - \frac{m}{g}x$ ②



~~8~~

(b) superimpose with $\frac{k}{g} > \frac{l}{n}$



~~3~~

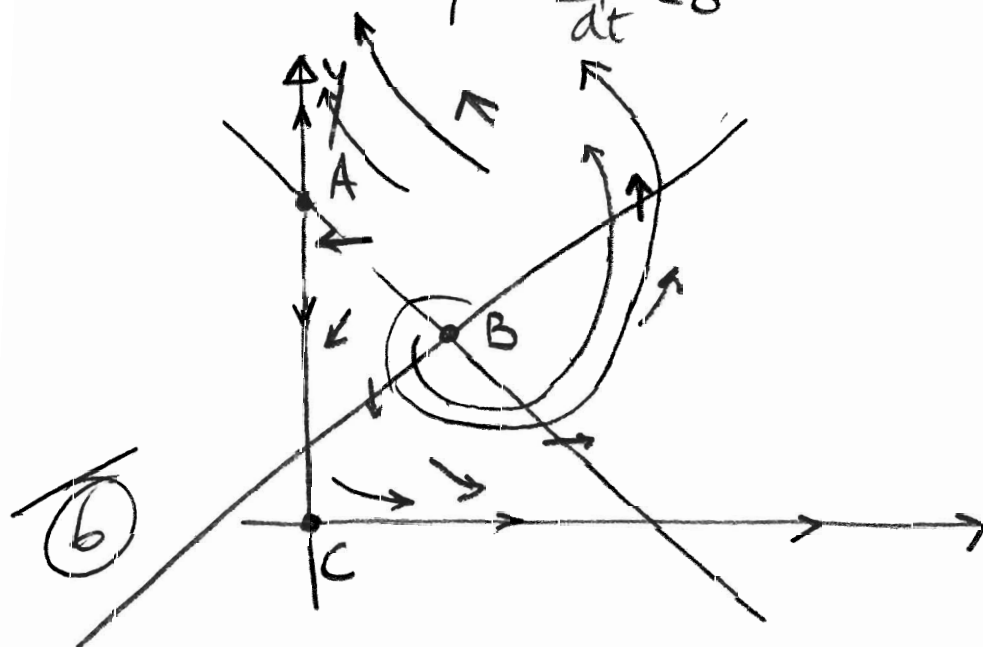
(c)(d) restrict consideration to $x \geq 0, y \geq 0$:

above N_x : $y > \frac{l}{n} + \frac{p}{n}x \Rightarrow 0 > l - ny + px \Rightarrow \frac{dx}{dt} < 0$ } 2

below N_x : $\frac{dx}{dt} > 0$

above N_y : $y < \frac{k}{g} - \frac{m}{g}x \Rightarrow mx - k + gy > 0 \Rightarrow \frac{dy}{dt} > 0$ } 1

below N_y : $\frac{dy}{dt} < 0$



direction fields 2

anticipated trajectories . 2

(c) It appears that all three of the physically meaningful equil. pts are unstable (although it might be possible to reach pt A).

3

⑤

$$\frac{dx}{dt} = lx - nxy$$

with $l = 0.2, n = 0.001$

$$\frac{dy}{dt} = ky - mxy$$

with $k = 0.4, m = 0.002$

(a) $x_c = \frac{k}{m} = \frac{0.4}{0.002} = 200$ ②

$y_c = \frac{l}{n} = \frac{0.2}{0.001} = 200$ ②

④

(b) $y e^{-ny} = K x^k e^{-mx}$ ②

$$y^{0.2} e^{-0.001y} = K x^{0.4} e^{-0.002x}$$

$(100, 150) \text{ on } \Rightarrow K = \frac{(150)^{0.2} e^{-0.001(150)}}{(100)^{0.4} e^{-0.002(100)}}$
 $= \frac{(150)^{0.2} e^{-0.15}}{(100)^{0.4} e^{-0.2}} \approx 0.453871566$ ②

\therefore trajectory is given by

⑤

$$y^{0.2} e^{-0.001y} = 0.453871566 x^{0.4} e^{-0.002x}$$
 ①

(c) for max value of x we must have $y = y_c = 200$

$\rightarrow x_{\max}$ must satisfy $(200)^{0.2} e^{-0.001(200)} = 0.453871566 x^{0.4} e^{-0.002x}$

$\Rightarrow x^{0.4} e^{-0.002x} = 5.204920814$ ②

③

①

(d) let $f(x) = x^{0.4} e^{-0.002x} - 5,204,920,814$

To solve $f(x) = 0$ let
 $x_0 =$ any number greater than
 x_c ($x_0 > 200$) ②

& consider the recursively defined sequence

③
$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} \quad n \geq 1. \quad \text{[Newton's method.]}$$

other methods OK if explained fully!

$$\begin{aligned}
 6(a) \quad (P_N)_{\text{MAX}} &= P_N((t_M)_N) = P_N\left(\frac{1}{b} \ln\left(\frac{N}{N_0}\right)\right) \\
 &= \binom{N-1}{N_0-1} e^{-N_0 \ln\left(\frac{N}{N_0}\right)} \left[1 - e^{-\ln\left(\frac{N}{N_0}\right)}\right]^{(N-N_0)} \\
 &= \binom{N-1}{N_0-1} \left(\frac{N}{N_0}\right)^{-N_0} \left[1 - \left(\frac{N}{N_0}\right)^{-1}\right]^{(N-N_0)} \\
 &= \binom{N-1}{N_0-1} \left(\frac{N_0}{N}\right)^{N_0} \left(\frac{N-N_0}{N}\right)^{(N-N_0)} \\
 &= \frac{(N-1)!}{(N_0-1)! (N-N_0)!} \frac{N_0^{N_0} (N-N_0)^{N-N_0}}{N^N}
 \end{aligned}$$

$$\begin{aligned}
 (b) \quad \frac{(P_{N+1})_{\text{MAX}}}{(P_N)_{\text{MAX}}} &= \frac{\frac{N!}{(N_0-1)! (N+1-N_0)!} \frac{N_0^{N_0} (N+1-N_0)^{N+1-N_0}}{(N+1)^{N+1}}}{\frac{(N-1)!}{(N_0-1)! (N-N_0)!} \frac{N_0^{N_0} (N-N_0)^{N-N_0}}{N^N}} \\
 &= \left(\frac{N}{N+1-N_0}\right) \frac{(N+1-N_0)^{N+1-N_0} N^N}{(N+1)^{N+1} (N-N_0)^{N-N_0}} \\
 &= \frac{(N+1-N_0)^{N-N_0}}{(N-N_0)^{N-N_0}} \frac{N^{N+1}}{(N+1)^{N+1}} \\
 &= \left(1 + \frac{1}{N-N_0}\right)^{N-N_0} \bigg/ \left(1 + \frac{1}{N}\right)^N
 \end{aligned}$$

But $\left\{ \left(1 + \frac{1}{n}\right)^n \right\}$ is increasing \uparrow

$$\begin{aligned}
 N-N_0 < N \quad \text{so} \quad \left(1 + \frac{1}{N-N_0}\right)^{N-N_0} < \left(1 + \frac{1}{N}\right)^N
 \end{aligned}$$

$$\Rightarrow \frac{(P_{N+1})_{\text{MAX}}}{(P_N)_{\text{MAX}}} < 1$$

(c) Since a population must reach size N
before reaching size $N+1$,
 $(P_N)_{\text{MAX}}$ must be greater than
 $(P_{N+1})_{\text{MAX}}$.

$$\textcircled{1} \quad \frac{ds}{dt} = -\beta SI, \quad \frac{dR}{dt} = rI, \quad S + I + R = N.$$

$$(a) \quad \frac{dI}{dt} = -\frac{ds}{dt} - \frac{dR}{dt} = \beta SI - rI = I(\beta S - r)$$

$$\frac{dI}{dt} = 0 \iff I = 0 \quad \text{or} \quad S = r/\beta.$$

↓
clearly this
provides a minimum
value for I .

$$(b) \quad \text{along a trajectory: } \frac{dI}{dS} = \frac{\beta SI - rI}{-\beta SI} = \frac{r}{\beta S} - 1$$

$$\text{separate: } dI = \left(\frac{r}{\beta S} - 1\right) dS$$

$$\Rightarrow I = \frac{r}{\beta} \ln S - S + C$$

$$\text{But } I = 10 \text{ when } S = 9990$$

$$\Rightarrow 10 = \frac{r}{\beta} \ln 9990 - 9990 + C$$

$$\Rightarrow C = 10000 - \frac{r}{\beta} \ln(9990)$$

$$\Rightarrow I = 10000 + \frac{r}{\beta} \ln\left(\frac{S}{9990}\right) - S.$$

along a trajectory.

$$(c) \quad \text{For } I_{\max} \text{ we must have } \frac{dI}{dt} = 0$$

$$\Rightarrow \text{for } I_{\max}, \quad S = \frac{r}{\beta}$$

$$\Rightarrow I_{\max} = 10000 + \frac{r}{\beta} \ln\left(\frac{r}{9990\beta}\right) - \frac{r}{\beta}$$

$$\text{But } \frac{r}{\beta} = \frac{0.9}{0.0002} = 4500$$

$$\begin{aligned} \therefore I_{\max} &= 10000 + 4500 \ln\left(\frac{4500}{9990}\right) - 4500 \\ &= 5500 + 4500 \ln\left(\frac{4500}{9990}\right) \\ &= 1911.21761852. \end{aligned}$$