



---

The Inverses of Some Matrices Deviating Slightly from a Symmetric, Tridiagonal, Toeplitz Form

Author(s): D. Meek

Source: *SIAM Journal on Numerical Analysis*, Vol. 17, No. 1 (Feb., 1980), pp. 39-43

Published by: [Society for Industrial and Applied Mathematics](#)

Stable URL: <http://www.jstor.org/stable/2156547>

Accessed: 22/03/2011 11:05

---

Your use of the JSTOR archive indicates your acceptance of JSTOR's Terms and Conditions of Use, available at <http://www.jstor.org/page/info/about/policies/terms.jsp>. JSTOR's Terms and Conditions of Use provides, in part, that unless you have obtained prior permission, you may not download an entire issue of a journal or multiple copies of articles, and you may use content in the JSTOR archive only for your personal, non-commercial use.

Please contact the publisher regarding any further use of this work. Publisher contact information may be obtained at <http://www.jstor.org/action/showPublisher?publisherCode=siam>.

Each copy of any part of a JSTOR transmission must contain the same copyright notice that appears on the screen or printed page of such transmission.

JSTOR is a not-for-profit service that helps scholars, researchers, and students discover, use, and build upon a wide range of content in a trusted digital archive. We use information technology and tools to increase productivity and facilitate new forms of scholarship. For more information about JSTOR, please contact [support@jstor.org](mailto:support@jstor.org).



*Society for Industrial and Applied Mathematics* is collaborating with JSTOR to digitize, preserve and extend access to *SIAM Journal on Numerical Analysis*.

<http://www.jstor.org>

## THE INVERSES OF SOME MATRICES DEVIATING SLIGHTLY FROM A SYMMETRIC, TRIDIAGONAL, TOEPLITZ FORM\*

D. MEEK†

**Abstract.** In some problems in numerical analysis one is faced with solving a linear system of equations in which the matrix of the linear system is symmetric, tridiagonal and Toeplitz, except for elements at or near the corners. The anomalous elements usually arise from boundary conditions in the original problem. This paper is concerned with expressing the inverse of this type of matrix in such a way that some of its theoretical properties may be obtained.

**1. Introduction.** Symmetric, tridiagonal, Toeplitz matrices arise as the matrix of a linear system of equations in several problems in numerical analysis. The equations for interpolating cubic splines with equi-spaced knots and certain boundary conditions [1, p. 11 and p. 13] have this special form. Symmetric, tridiagonal, Toeplitz matrices are used as comparison matrices in the error analysis of second order boundary value problems with certain boundary conditions [4, p. 362]. The explicit inverse of the symmetric, tridiagonal, Toeplitz matrix has been found by several authors [8], [3] and [9].

This paper is concerned with matrices which differ slightly from the symmetric, tridiagonal, Toeplitz pattern in that elements at or near the corners of the matrix do not fit that pattern. Such matrices arise in interpolation with cubic splines if the boundary conditions are natural conditions [2, p. 133] or periodic boundary conditions [1, p. 12], or a variety of other conditions [6]. The error analysis of the finite difference solution of second order boundary value problems with certain boundary conditions requires a comparison matrix of this type [7].

Kershaw [5] has found the inverses of two matrices which are slight variations of symmetric, tridiagonal, Toeplitz matrices. In this paper more extensive variations of the symmetric, tridiagonal, Toeplitz form are considered. The theory of difference equations is used to develop formulae for the inverses of the matrices considered.

**2. Matrices with four anomalous corner elements.** The first matrix to examine,  $B$ , is a symmetric, tridiagonal, Toeplitz matrix which has had the four corner elements changed. Let  $B$  be the  $N \times N$  matrix

$$B = \begin{pmatrix} a & -1 & & & c \\ -1 & x & -1 & 0 & \\ & -1 & x & & \\ & 0 & & x & -1 \\ b & & & -1 & d \end{pmatrix}_{N \times N}$$

and supposing that  $B$  is nonsingular, let  $S = (s_{ij})_{N \times N}$  be the inverse of  $B$ . The identity  $BS = I$  is expressed by the equations

$$(1) \quad as_{1,j} - s_{2,j} + cs_{N,j} = \delta_{1,j},$$

$$(2) \quad -s_{i-1,j} + xs_{i,j} - s_{i+1,j} = \delta_{i,j}, \quad i = 2, 3, \dots, N-1,$$

and

$$(3) \quad bs_{1,j} - s_{N-1,j} + ds_{N,j} = \delta_{N,j}$$

for each  $j = 1, 2, \dots, N$ , where  $\delta_{i,j}$  is the Kronecker delta.

\* Received by the editors August 16, 1978.

† Department of Computer Science, University of Manitoba, Winnipeg, Manitoba, Canada R3T 2N2.

The elements  $s_{i,j}$  can be written as a linear sum of the solutions to two difference equations which have been solved explicitly. The two difference equations are:

$$(4) \quad -e_{i-1} + xe_i - e_{i+1} = 0, \quad i = 2, 3, \dots, N-1, \quad e_1 = 0 \quad \text{and} \quad e_N = 1,$$

and

$$(5) \quad -t_{i-1,j} + xt_{i,j} - t_{i+1,j} = \delta_{i,j}, \quad i = 2, 3, \dots, N-1, \quad t_{1,j} = 0 \quad \text{and} \quad t_{N,j} = 0,$$

for  $j = 2, 3, \dots, N-1$ , while  $t_{i,1} = t_{i,N} = 0$ .

The solutions to (4) and (5) are (see [3])

$$(6) \quad e_i = \begin{cases} \sinh(i-1)\theta / \sinh(N-1)\theta, & \text{if } x > 2 \text{ and } 2 \cosh \theta = x, \\ (i-1)/(N-1) & \text{if } x = 2, \\ \sin(i-1)\theta / \sin(N-1)\theta, & \text{if } x < 2 \text{ and } 2 \cos \theta = x, \end{cases}$$

and

$$(7) \quad t_{i,j} = \begin{cases} e_j e_{N-i+1} / e_2 & \text{if } i \geq j, \\ e_i e_{N-j+1} / e_2 & \text{if } i < j. \end{cases}$$

Suppose  $s_{i,j}$  is expressed as

$$(8) \quad s_{i,j} = t_{i,j} + A_j e_{N-i+1} + B_j e_i,$$

where  $A_j$  and  $B_j$  have yet to be determined. It can be seen that the above expression for  $s_{i,j}$  will always satisfy the equations (2), and that in general  $A_j$  and  $B_j$  can be determined so that it satisfies equations (1) and (3). If the expression (8) is substituted into equation (1), then

$$(9) \quad (a - e_{N-1})A_j + (c - e_2)B_j = t_{2,j} + \delta_{1,j}$$

and if the expression (8) is substituted into equation (3), then

$$(10) \quad (b - e_2)A_j + (d - e_{N-1})B_j = t_{N-1,j} + \delta_{N,j}.$$

The quantity  $t_{2,j} + \delta_{1,j}$  is equal to  $e_{N-j+1}$ , and the quantity  $t_{N-1,j} + \delta_{N,j}$  is equal to  $e_j$  (see equation (7)), thus the equations for  $A_j$  and  $B_j$  become

$$(11) \quad \begin{pmatrix} a - e_{N-1} & c - e_2 \\ b - e_2 & d - e_{N-1} \end{pmatrix} \begin{pmatrix} A_j \\ B_j \end{pmatrix} = \begin{pmatrix} e_{N-j+1} \\ e_j \end{pmatrix}.$$

If equation (11) has a unique solution, then the inverse of matrix  $B$  is  $S = (s_{i,j})_{N \times N}$  where  $s_{i,j}$  is expressed in the form (8),  $e_i$  and  $t_{i,j}$  are given by (4) and (5), and  $A_j$  and  $B_j$  are given by (11).

As an example of the use of the above formulae, sufficient conditions on  $a, b, c, d$  and  $x$  so that  $B^{-1} \geq 0$  will now be stated. Firstly, take  $x \geq 2$  so that  $e_i \geq 0$  for  $i = 1, 2, \dots, N$ , and  $t_{i,j} \geq 0$  for all pairs  $(i, j)$ ,  $i = 1, 2, \dots, N$ ,  $j = 1, 2, \dots, N$ . From expression (8), it is clear that  $A_j$  and  $B_j$  should be nonnegative, thus

$$(12) \quad \begin{pmatrix} a - e_{N-1} & c - e_2 \\ b - e_2 & d - e_{N-1} \end{pmatrix}^{-1} \geq 0$$

is required. This can be simplified somewhat, but weakened, by the requirement

$$(13) \quad \begin{pmatrix} a - r & c \\ b & d - r \end{pmatrix}^{-1} > 0,$$

where  $r = x/2 - \sqrt{(x/2)^2 - 1}$ . If  $N$  is sufficiently large, then condition (13) implies condition (12). Thus  $x \geq 2$  and condition (13) ensure that  $B^{-1} \geq 0$  for all  $N$  above some

value. For example,

$$\begin{pmatrix} a & -1 & & 0 & c \\ -1 & 5.2 & -1 & & \\ & -1 & & 5.2 & -1 \\ b & 0 & & -1 & d \end{pmatrix}_{N \times N}^{-1} \cong 0$$

for  $N$  sufficiently large if  $a \geq 0.2$ ,  $d \geq 0.2$ ,  $c \leq 0$ ,  $b \leq 0$  and  $(a - 0.2)(d - 0.2) > bc$ .

It should be noted that if matrix  $B$  does have a positive inverse, then the row sums of  $B^{-1}$  can be obtained fairly easily since formulae for  $\sum_{j=1}^N t_{ij}$  and  $\sum_{i=1}^N e_i$  are known [3].

**3. Matrices with sixteen anomalous corner elements.** The second matrix to examine is a symmetric, tridiagonal Toeplitz matrix in which sixteen corner elements have been changed. Let  $B$  be the  $N \times N$  matrix

$$B = \begin{pmatrix} a_{11} & a_{12} & & c_{11} & c_{12} \\ a_{21} & a_{22} & -1 & & c_{21} & c_{22} \\ & -1 & x & -1 & 0 & \\ & & -1 & & x & -1 \\ & & 0 & & -1 & d_{11} & d_{12} \\ b_{11} & b_{12} & & & & d_{21} & d_{22} \\ b_{21} & b_{22} & & & & & \end{pmatrix}_{N \times N}$$

and supposing  $B$  is nonsingular, let  $S = (s_{i,j})_{N \times N}$  be the inverse of  $B$ . The development of formulae for  $s_{i,j}$  is similar to that used in the previous section and will be sketched here. The identity  $BS = I$  can be written:

$$\begin{aligned} a_{11}s_{1,j} + a_{12}s_{2,j} + c_{11}s_{N-1,j} + c_{12}s_{N,j} &= \delta_{1,j}, \\ a_{21}s_{1,j} + a_{22}s_{2,j} - s_{3,j} + c_{21}s_{N-1,j} + c_{22}s_{N,j} &= \delta_{2,j}, \\ -s_{i-1,j} + xs_{i,j} - s_{i+1,j} &= \delta_{i,j}, \quad i = 3, 4, \dots, N-2, \\ b_{11}s_{1,j} + b_{12}s_{2,j} - s_{N-2,j} + d_{11}s_{N-1,j} + d_{12}s_{N,j} &= \delta_{N-1,j}, \\ b_{21}s_{1,j} + b_{22}s_{2,j} + d_{21}s_{N-1,j} + d_{22}s_{N,j} &= \delta_{N,j}. \end{aligned}$$

If  $e_i$  and  $t_{i,j}$  are the solutions to the following difference equations

$$-e_{i-1} + xe_i - e_{i+1} = 0, \quad i = 3, 4, \dots, N-2, \quad e_2 = 0 \quad \text{and} \quad e_{N-1} = 1$$

and

$$-t_{i-1,j} + xt_{i,j} - t_{i+1,j} = \delta_{i,j}, \quad i = 3, 4, \dots, N-2, \quad t_{2,j} = 0 \quad \text{and} \quad t_{N-1,j} = 0,$$

for  $j = 3, 4, \dots, N-2$ , while  $t_{i,2} = t_{i,N-1} = 0$ ; then  $s_{i,j}$  can in general be expressed as

$$s_{i,j} = t_{i,j} + A_j e_{N-i+1} + B_j e_i, \quad i = 2, 3, \dots, N-1.$$

The quantities  $s_{1,j}$ ,  $s_{N,j}$ ,  $A_j$  and  $B_j$  must satisfy the equation

$$\begin{pmatrix} a_{11} & a_{12} & c_{11} & c_{12} \\ a_{21} & a_{22} - e_{N-2} & c_{21} - e_3 & c_{22} \\ b_{11} & b_{12} - e_3 & d_{11} - e_{N-2} & d_{12} \\ b_{21} & b_{22} & d_{21} & d_{22} \end{pmatrix} \begin{pmatrix} s_{1,j} \\ A_j \\ B_j \\ s_{N,j} \end{pmatrix} = \begin{pmatrix} \delta_{1,j} \\ e_{N-j+1} \\ e_j \\ \delta_{N,j} \end{pmatrix}.$$

and it will be assumed that this equation has a unique solution.

As an example of the usefulness of the above formulae, consider sufficient conditions that  $B^{-1}$  be nonnegative. The choice  $x \geq 2$  and the choice of corner elements so that

$$\begin{pmatrix} a_{11} & a_{12} & c_{11} & c_{21} \\ a_{21} & a_{22} - e_{N-2} & c_{21} - e_3 & c_{22} \\ b_{11} & b_{12} - e_3 & d_{11} - e_{N-2} & d_{12} \\ b_{21} & b_{22} & d_{21} & d_{22} \end{pmatrix}^{-1} \geq 0$$

ensures that  $B^{-1} \geq 0$ . As before, the above condition may be replaced by

$$\begin{pmatrix} a_{11} & a_{12} & c_{11} & c_{21} \\ a_{21} & a_{22} - r & c_{21} & c_{22} \\ b_{11} & b_{12} & d_{11} - r & d_{12} \\ b_{12} & b_{22} & d_{21} & d_{22} \end{pmatrix}^{-1} > 0,$$

where  $r = x/2 - \sqrt{(x/2)^2 - 1}$  and then one can say that  $B^{-1} \geq 0$  for sufficiently large  $N$ . Since

$$\begin{pmatrix} 8 & -4 & 2 & -1 \\ -4 & 7 & -4 & 2 \\ 2 & -4 & 7 & -4 \\ -1 & 2 & -4 & 8 \end{pmatrix}^{-1} > 0,$$

$$\begin{pmatrix} 8 & -4 & & & & 2 & -1 \\ -4 & 8 & -1 & & & -4 & 2 \\ & -1 & 2 & -1 & 0 & & \\ & & -1 & & & 2 & -1 \\ & & & -1 & & -1 & 8 & -4 \\ 2 & -4 & 0 & & & -4 & 8 \\ -1 & 2 & & & & & & 8 \end{pmatrix}_{N \times N}^{-1} \geq 0$$

for all  $N$  above some value

**Acknowledgment.** The author acknowledges the financial support of the National Research Council of Canada.

#### REFERENCES

- [1] J. H. AHLBERG, E. N. NILSON AND J. L. WALSH, *The Theory of Splines and Their Applications*, Academic Press, New York, 1967.
- [2] G. DAHLQUIST AND A. BJÖRCK, *Numerical Methods*, translated by Ned Anderson, Prentice-Hall, Englewood Cliffs, NJ, 1974.
- [3] C. F. FISCHER AND R. A. USMANI, *Properties of some tridiagonal matrices and their application to boundary value problems*, this Journal, 6 (1969), pp. 127-142.
- [4] P. HENRICI, *Discrete Variable Methods in Ordinary Differential Equations*, John Wiley, New York, 1962.
- [5] D. KERSHAW, *The explicit inverses of two commonly occurring matrices*, Math. Comp., 23 (1969), pp. 189-191.
- [6] ———, *The orders of approximation of the first derivative of cubic splines at the knots*, Ibid., 26 (1972), pp. 191-198.
- [7] D. S. MEEK AND R. A. USMANI, *The linear second order boundary value problem with certain mixed, non-separated boundary conditions*, J. Comput. Appl. Math., submitted.

- [8] D. E. RUTHERFORD, *Some continuant determinants arising in physics and chemistry II*, Proc. Royal Soc. Edinburgh Sect. A, 63 (1952), pp. 232–241.
- [9] V. R. UPPULARI AND J. A. CARPENTER, *An inversion method for band matrices*, J. Math. Anal. Appl., 31 (70), pp. 554–558.
- Reference added in proof to complement reference [6].*
- T. R. LUCAS, *Error bounds for interpolating cubic splines under various end conditions*, this Journal, 11 (1974), pp. 569–584.