

# MATH 4370/7370 – Linear Algebra and Matrix Analysis

An example from metapopulations

Julien Arino

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**University  
of Manitoba**

# Outline

Position of the problem

A metapopulation of sources and sinks with explicit movement

The movement matrix

Local analysis of the model

Global behaviour

An interesting special case

## Why do this?

This is mostly about dynamics

Looping back to our first few lectures: *matrices are everywhere!*

This is a (rather abstract) problem in theoretical ecology (or mathematical ecology?)

We will be using a surprising number of results we have already seen

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# Rael & Taylor (2018)

*A flow network model for animal movement on a landscape with application to invasion*, Theoretical Ecology

$$P'_i = P_i B(P_i) + \sum_{j=1}^N a_{ji} P_j m(P_j, P_i) - P_i \sum_{j=1}^N a_{ij} m(P_i, P_j)$$

where

$$m(P_i, P_j) = \frac{\max\{0, \pi(P_i) - \pi(P_j)\}}{d_{ij}} \quad \pi(P_i) = \frac{P_i}{K_i}$$

$d_{ij}$  distance from  $i$  to  $j$ ,  $K_i$  carrying capacity

$$B(P_i) = \begin{cases} r_i \left(1 - \frac{P_i}{K_i}\right) & \text{sources} \\ -r_i & \text{sinks} \end{cases}$$



# Number of Source Patches Required for Population Persistence in a Source–Sink Metapopulation with Explicit Movement

Julien Arino<sup>1</sup>  · Nicolas Bajeux<sup>1,2</sup> · Steve Kirkland<sup>1</sup>

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## Position of the problem

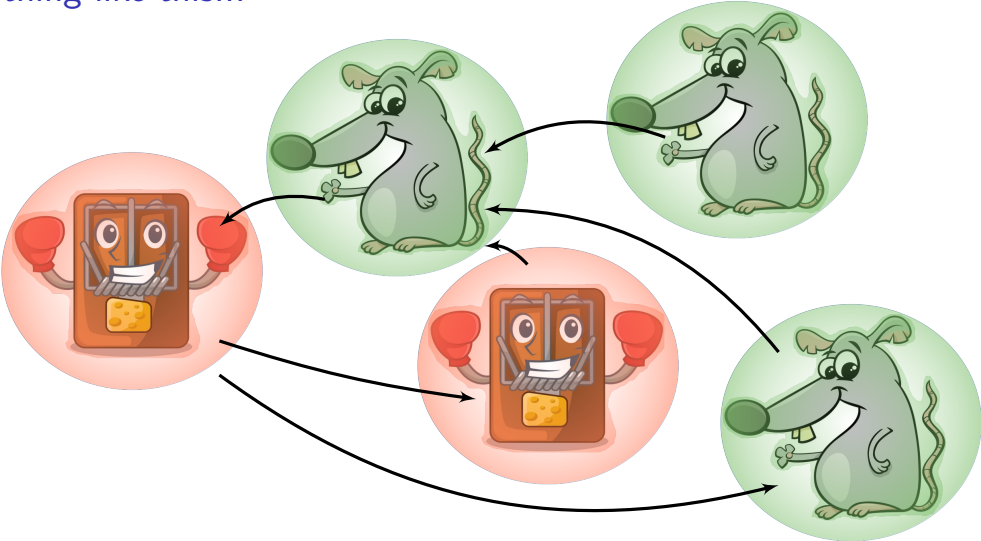
Assume a metapopulation of patches connected through transport of individuals between them

Some patches are sources, others are sinks:

- ▶ Population tends to persist in sources
- ▶ Population tends to vanish in sinks

*Ceteris paribus*, does there exist a ratio of the number of source to sink patches s.t. the population of the coupled system persists?

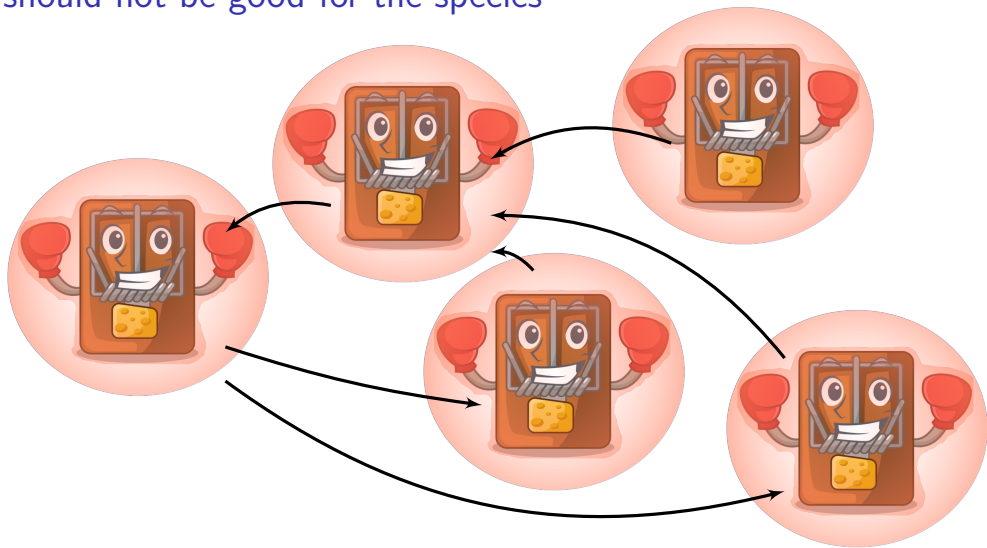
Something like this...



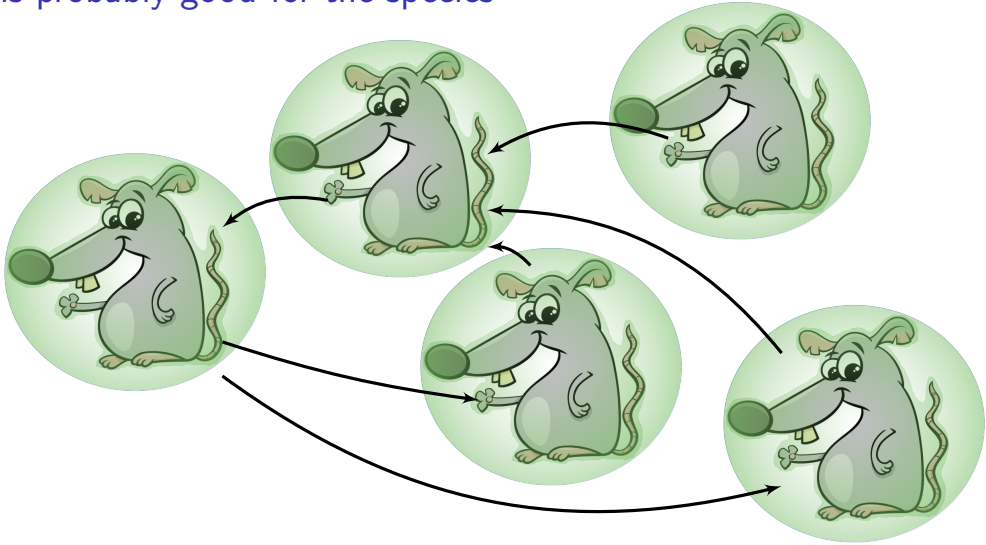


## Obvious special cases

This should not be good for the species



This is probably good for the species



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## Model for $N$ patches

W.l.o.g.:  $S \geq 0$  first patches are sources,  $N - S$  remaining are sinks [w.l.o.g. but not that trivial nonetheless]

**Sources:**

$$P'_i = r_i P_i \left(1 - \frac{P_i}{K_i}\right) + \sum_{j=1}^N m_{ij} P_j, \quad i = 1, \dots, S \quad (1a)$$

**Sinks:**

$$P'_i = -r_i P_i + \sum_{j=1}^N m_{ij} P_j, \quad i = S + 1, \dots, N \quad (1b)$$

$$m_{ii} = - \sum_{\substack{j=1 \\ j \neq i}}^N m_{ji}$$

## Vector form (v1)

$$\mathbf{P} = (P_1, \dots, P_N)^T$$

$$\mathbf{P}' = \mathbf{G}(\mathbf{P})\mathbf{P} + \mathcal{M}\mathbf{P}$$

where

$$\mathbf{G}(\mathbf{P}) = \text{diag} \left( r_1 \left( 1 - \frac{P_1}{K_1} \right), \dots, r_S \left( 1 - \frac{P_S}{K_S} \right), -r_{S+1}, \dots, -r_N \right)$$

$$\mathcal{M} = \begin{pmatrix} -\sum_{\substack{j=1 \\ j \neq 1}}^N m_{j1} & m_{12} & \cdots & m_{1N} \\ m_{21} & -\sum_{\substack{j=1 \\ j \neq 2}}^N m_{j2} & \cdots & m_{2N} \\ & & \ddots & \\ m_{N1} & m_{N2} & \cdots & -\sum_{\substack{j=1 \\ j \neq N}}^N m_{jN} \end{pmatrix}$$

## Vector form (v2)

$$\mathbf{P}_s = (P_1, \dots, P_S)^T \text{ (sources), } \quad \mathbf{P}_t = (P_{S+1}, \dots, P_N) \text{ (sinks)}$$

$$\mathbf{P}'_s = \mathbf{G}_s(\mathbf{P}_s)\mathbf{P}_s + \mathcal{M}_s\mathbf{P}_s + \mathcal{M}_{st}\mathbf{P}_t$$

$$\mathbf{P}'_t = -\mathcal{D}_t\mathbf{P}_t + \mathcal{M}_{ts}\mathbf{P}_s + \mathcal{M}_t\mathbf{P}_t$$

where

$$\mathbf{G}_s(\mathbf{P}_s) = \text{diag} \left( r_1 \left( 1 - \frac{P_1}{K_1} \right), \dots, r_S \left( 1 - \frac{P_S}{K_S} \right) \right)$$

$$\mathcal{D}_t = \text{diag} (r_{S+1}, \dots, r_N)$$

$$\begin{pmatrix} \mathcal{M}_s & \mathcal{M}_{st} \\ \mathcal{M}_{ts} & \mathcal{M}_t \end{pmatrix} = \mathcal{M} \tag{2}$$

## Main result we want to get to

### Theorem 8.1

*$\exists$  a unique critical interval  $S_{int} \subset (0, N) \subset \mathbb{R}$  s.t. if the number of source patches  $S < \min(S_{int})$ , the population-free equilibrium (PFE)  $(P_1, \dots, P_N) = (0, \dots, 0)$  of (1) is locally asymptotically stable and if  $S > \max(S_{int})$ , the PFE is unstable*

*If, additionally, the digraph of patches is strongly connected, then  $S_{int}$  reduces to a single point  $S^c$  and the PFE is globally asymptotically stable in the case that  $S < S^c$ ; in the case that  $S > S^c$ , there is a unique component-wise positive equilibrium  $\mathbf{P}^*$  that is GAS with respect to  $\mathbb{R}_+^N \setminus \{0\}$*



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# Properties of the movement matrix $\mathcal{M}$

## Lemma 8.2

1.  $0 \in \sigma(\mathcal{M})$  corresponding to left e.v.  $\mathbb{1}^T$   $[\sigma \text{ spectrum}]$
2.  $-\mathcal{M}$  is a singular M-matrix
3.  $0 = s(\mathcal{M}) \in \sigma(\mathcal{M})$   $[s \text{ spectral abscissa}]$
4. If  $\mathcal{M}$  irreducible, then  $s(\mathcal{M})$  has multiplicity 1

## Proof of Lemma 8.2

1. The result is obvious: all column sums of  $\mathcal{M}$  equal zero, i.e.,  $\mathbb{1}^T \mathcal{M} = 0 \mathbb{1}^T$
3. Using the Gershgorin Disk Theorem A.3 on  $\mathcal{M}$  indicates that all Gershgorin disks are tangent to the imaginary axis at  $(0,0)$ . As 0 is an eigenvalue of  $\mathcal{M}$ , it follows that  $s(\mathcal{M}) = 0$
4. This is a direct consequence of using the Perron-Frobenius Theorem A.5 on the essentially nonnegative matrix  $\mathcal{M}$

## Proof of Lemma 8.2 (cont'd)

2. From the Gershgorin Disk Theorem A.3, all eigenvalues of  $-\mathcal{M}$  belong to disks that lie to the right of the imaginary axis and, from the zero column sums, are tangent to that axis at  $(0, 0)$

Now consider  $-\mathcal{M} + \varepsilon \mathbb{I}$ , for  $\varepsilon > 0$ . This shifts the centers of all Gershgorin disks to the right by  $\varepsilon$  Theorem A.1 but does not change their radii, so all disks now lie strictly to the right of the imaginary axis

Thus all eigenvalues of  $-\mathcal{M} + \varepsilon \mathbb{I}$  have positive real parts

Furthermore,  $-\mathcal{M}$  and  $-\mathcal{M} + \varepsilon \mathbb{I}$  are of class  $Z_n$  (Definition A.6). Theorem A.7(18)  $\implies -\mathcal{M} + \varepsilon \mathbb{I}$  is of class  $K$ , i.e., an M-matrix. Since this is true for all  $\varepsilon > 0$ , Theorem A.8(1) implies that  $-\mathcal{M}$  is of class  $K_0$ . So  $-\mathcal{M}$  is an M-matrix and it is singular

## Properties of the movement matrix $\mathcal{M}$ (cont'd)

### Proposition 8.3 ( $D$ a diagonal matrix)

1.  $s(\mathcal{M} + d\mathbb{I}) = d, \forall d \in \mathbb{R}$
2.  $s(\mathcal{M} + D) \in \sigma(\mathcal{M} + D)$  associated to  $\mathbf{v} > \mathbf{0}$ . If  $\mathcal{M}$  irreducible,  $s(\mathcal{M} + D)$  has multiplicity 1 and is associated to  $\mathbf{v} \gg \mathbf{0}$
3.  $\text{diag}(D) \gg \mathbf{0} \implies D - \mathcal{M}$  invertible  $M$ -matrix and  $(D - \mathcal{M})^{-1} > \mathbf{0}$
4.  $\mathcal{M}$  irreducible and  $\text{diag}(D) > \mathbf{0} \implies D - \mathcal{M}$  nonsingular irreducible  $M$ -matrix and  $(D - \mathcal{M})^{-1} \gg \mathbf{0}$

## Proof of Proposition 8.3

1. From Lemma 8.2(3),  $s(\mathcal{M}) = 0$ . Therefore, using a “spectrum shift” Theorem A.1,  $s(\mathcal{M} + d\mathbb{I}) = d$
2. These are direct consequences of applying the Perron-Frobenius Theorem A.5 to the essentially nonnegative matrix  $\mathcal{M} + D$

## Proof of Proposition 8.3 (cont'd)

3. Define  $\underline{d} = \min_{i=1,\dots,N} d_{ii}$ . Then

$$\text{diag}(D) \gg \mathbf{0} \implies \underline{d} > 0 \implies -\mathcal{M} \leq \underline{d}\mathbb{I} - \mathcal{M} \leq D - \mathcal{M}$$

From Theorem A.8(5),  $\underline{d}\mathbb{I} - \mathcal{M}$  is an M-matrix. Since  $s(\mathcal{M}) = 0$ , using a “spectrum shift”, all eigenvalues of  $\underline{d}\mathbb{I} - \mathcal{M}$  have real parts larger than  $\underline{d}$ , so  $\underline{d}\mathbb{I} - \mathcal{M}$  is a nonsingular M-matrix. In turn, Theorem A.7(4)  $\implies D - \mathcal{M}$  nonsingular M-matrix and Theorem A.7(11) leads to the conclusion

4. Suppose  $\mathcal{M}$  irreducible. Let  $\bar{d} = \max_{i=1,\dots,N} d_{ii} > 0$ . Then  $D - \mathcal{M}$  is irreducible and diagonally dominant with all columns  $k = 1, \dots, N$  such that  $d_{kk} = \bar{d}$  satisfying the strict diagonal dominance requirement. (Other columns with nonzero entries in  $D$  also satisfy the requirement.) As a consequence, [Varga, 2010, Theorem 1.11] implies that  $D - \mathcal{M}$  nonsingular and inverse positivity follows from Theorem A.9

–  $\mathcal{M}$  is also the Laplacian matrix of a digraph

Note that  $-\mathcal{M}$  is also the Laplacian matrix of a directed graph

As such, finer estimates of the location of eigenvalues are available; see, e.g., [Agaev and Chebotarev, 2005]

However, the main concern here is with the spectral abscissa, so this is not needed



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## The *population-free equilibrium* (PFE)

We find the PFE  $\mathbf{P}_s = \mathbf{P}_t = \mathbf{0}$

At the PFE,

$$J_{\text{PFE}}^S = \mathcal{M} + (\mathcal{D}_s \oplus -\mathcal{D}_t) \quad (3)$$

where  $\mathcal{D}_s = \mathbf{G}_s(\mathbf{0}) = \text{diag}(r_1, \dots, r_S)$

The matrix

$$\mathcal{D}_s \oplus -\mathcal{D}_t = \text{diag}(r_1, \dots, r_S, -r_{S+1}, \dots, -r_N)$$

has  $S$  diagonal entries  $> 0$  and  $N - S$  diagonal entries  $< 0$

## Mechanism of the existence proof

Start with  $S = 0$  (only sinks)

$$\implies \mathcal{D}_s \text{ vacuous and } \mathcal{D}_s \oplus -\mathcal{D}_t = \text{diag}(-r_1, \dots, -r_N)$$

$$\implies s(J_{PFE}^S) < 0$$

Finish with  $S = N$  (only sources)

$$\implies \mathcal{D}_t \text{ vacuous and } \mathcal{D}_s \oplus -\mathcal{D}_t = \text{diag}(r_1, \dots, r_N)$$

$$\implies s(J_{PFE}^S) > 0$$

Eigenvalues of  $J_{PFE}^S$  depend continuously of entries of  $J_{PFE}^S$ , so  $s(J_{PFE}^S)$  changes signs, we are done.. if we are happy with a lot of uncertainty about behaviour of  $s(J_{PFE}^S)$

## Continuous perturbation of the spectrum

For  $S \in \{0, \dots, N-1\}$

$$J_{\text{PFE}}^{S,\varepsilon} = \mathcal{M} + \text{diag}(r_1, \dots, r_S, \varepsilon, -r_{S+2}, \dots, -r_N)$$

where  $\varepsilon \in [-r_{S+1}, r_{S+1}]$  is in  $(S+1)^{\text{th}}$  position

For  $S \in [0, N]$

$$J_{\text{PFE}}^S = J_{\text{PFE}}^{\xi,\varepsilon}, \quad \text{with} \quad \xi = \lfloor S \rfloor, \quad \varepsilon = 2(S - \lfloor S \rfloor)r_i - r_i \quad (4)$$

where  $i = \lfloor S \rfloor + 1$  if  $S < N$  and  $i = N$  when  $S = N$

Generally we vary  $\zeta$  continuously in each  $[-r_{S+1}, r_{S+1}]$

$$J_{\text{PFE}}^{S,-r_{S+1}} = J_{\text{PFE}}^S \quad \text{and} \quad J_{\text{PFE}}^{S,r_{S+1}} = J_{\text{PFE}}^{S+1}$$

## The spectral abscissa $s(J_{PFE}^S)$ switches signs

### Lemma 8.4

Let  $\underline{r} = \min_{i=1,\dots,N} \{r_i\}$

Then  $s(J_{PFE}^0) \leq -\underline{r} < 0$  and  $s(J_{PFE}^N) \geq \underline{r} > 0$

## Proof of Lemma 8.4

If  $S = 0$ , then

$$\mathcal{J}_{\text{PFE}}^0 = \mathcal{M} + \text{diag}(-r_1, \dots, -r_N)$$

From Proposition 8.2(3),  $s(\mathcal{M}) = 0$ . Note that this follows from using the Gershgorin Disk Theorem A.3, where for  $\mathcal{M}$ , all Gershgorin disks are left of the imaginary axis and tangent to origin of the complex plane

Then the centres of the Gershgorin disks of  $\mathcal{M} + \text{diag}(-r_1, \dots, -r_N)$  are shifted left by  $r_1, \dots, r_N$  while the radii remain the same

As a consequence, the closest disk(s) to the origin of the complex plane have centre(s)  $-\underline{r}$  and thus  $s(\mathcal{M} + \text{diag}(-r_1, \dots, -r_N)) \leq -\underline{r} < 0$

## Proof of Lemma 8.4 (cont'd)

If  $S = N$ , then

$$J_{\text{PFE}}^N = \mathcal{M} + \text{diag}(r_1, \dots, r_N)$$

For  $i = 1, \dots, N$ , define  $e_i = r_i - \underline{r} \geq 0$ , then

$$J_{\text{PFE}}^N = \mathcal{M} + \underline{r}\mathbb{I} + \text{diag}(e_1, \dots, e_N)$$

where, by Proposition 8.3(1),  $s(\mathcal{M} + \underline{r}\mathbb{I}) = \underline{r} > 0$

## Proof of Lemma 8.4 (cont'd)

First, assume  $\mathcal{M}$  irreducible

Then  $J_{\text{PFE}}^N$  is an irreducible essentially nonnegative matrix

Since  $J_{\text{PFE}}^N \geq \mathcal{M} + \underline{r}\mathbb{I}$ , Theorem A.10(3)  $\implies$

$$s(J_{\text{PFE}}^N) \geq s(\mathcal{M} + \underline{r}\mathbb{I}) = \underline{r}$$

with the inequalities being strict if there exists at least one  $e_i > 0$



## Proof of Lemma 8.4 (cont'd)

Now assume that  $\mathcal{M}$  reducible

Then  $\exists$  permutation matrix  $P$  such that  $P^T \mathcal{M} P$  is block upper triangular with irreducible blocks on the diagonal

Call  $C$  the number of such blocks, i.e., the number of strong components in the digraph of patches

For  $i = 1, \dots, C$ , denote  $n(i)$  the number of patches in strong component  $i$  and  $k(1), \dots, k(n(i))$  their indices

By abuse of notation, denote  $\mathcal{M}_{ii}$  the corresponding diagonal block in the reduced form of  $\mathcal{M}$

## Proof of Lemma 8.4 (cont'd)

Applying the permutation matrix  $P$  to  $J_{\text{PFE}}^N$  gives a block upper triangular matrix

$$P^T J_{\text{PFE}}^N P$$

with, for  $i = 1, \dots, C$ , the  $n(i) \times n(i)$  diagonal blocks  $\mathcal{M}_{ii} + E_i$  being irreducible and with

$$E_i = \underline{r}\mathbb{I} + \text{diag}(e_{k(1)}, \dots, e_{k(n(i))})$$

## Proof of Lemma 8.4 (cont'd)

Fix  $i = 1, \dots, C$  and let  $\mathbf{v}$  be a positive right eigenvector of  $\mathcal{M}_{ii} + E_i$  corresponding to the spectral abscissa  $s_1$  and  $\mathbf{w}$  be a positive left eigenvector of  $\mathcal{M}_{ii} + \underline{r}\mathbb{I}$  corresponding to the spectral abscissa  $s_2$ . Then

$$\begin{aligned} s_1 \mathbf{w}^T \mathbf{v} &= \mathbf{w}^T (\mathcal{M}_{ii} + \underline{r}\mathbb{I} + \text{diag}(e_{k(1)}, \dots, e_{k(n(i))})) \mathbf{v} \\ &= \mathbf{w}^T (\mathcal{M}_{ii} + \underline{r}\mathbb{I}) \mathbf{v} + \mathbf{w}^T \text{diag}(e_{k(1)}, \dots, e_{k(n(i))}) \mathbf{v} \\ &= s_2 \mathbf{w}^T \mathbf{v} + \mathbf{w}^T \text{diag}(e_{k(1)}, \dots, e_{k(n(i))}) \mathbf{v} \\ &\geq s_2 \mathbf{w}^T \mathbf{v} \end{aligned}$$

the inequality being strict if at least one of the  $e_{k(j)}$ ,  $j = 1, \dots, n(i)$ , is positive. Hence  $s_1 \geq s_2$ , i.e.,  $s(\mathcal{M}_{ii} + E_i) \geq s(\mathcal{M}_{ii} + \underline{r}\mathbb{I})$ . This is true for all diagonal blocks. Now, since  $P^T J_{\text{PFE}}^N P$  is block upper triangular,

$$s(J_{\text{PFE}}^N) = s(P^T J_{\text{PFE}}^N P) = \max\{s(\mathcal{M}_{11} + E_1), \dots, s(\mathcal{M}_{CC} + E_C)\}$$

## Proof of Lemma 8.4 (cont'd)

As  $P^T(\mathcal{M} + \underline{r}\mathbb{I})P$  is also block upper triangular,

$$\underline{r} = s(\mathcal{M} + \underline{r}\mathbb{I}) = \max\{s(\mathcal{M}_{11} + \underline{r}\mathbb{I}), \dots, s(\mathcal{M}_{11} + \underline{r}\mathbb{I})\}$$

As a consequence,  $s(J_{\text{PFE}}^N) \geq \underline{r} > 0$

Thus,  $S^c$  necessarily lies in the open interval  $(0, N)$ . The following lemma is of interest and the method of proof of the second assertion is used again later

### Lemma 8.5

1. For all  $S \in (0, N) \subset \mathbb{R}$ ,

$$J_{PFE}^0 < J_{PFE}^S < J_{PFE}^N \quad (5)$$

2.  $J_{PFE}^S$  is an increasing function of  $S$ , in the sense that

$$\forall S_1, S_2 \in [0, N] \subset \mathbb{R} \text{ such that } S_1 < S_2, \quad J_{PFE}^{S_1} < J_{PFE}^{S_2} \quad (6)$$

## Proof of Lemma 8.5

1. Let  $S \in (0, N)$  be fixed. Using (4), this gives a pair  $(\xi, \varepsilon) \in \{0, \dots, N\} \times [-r_i, r_i]$ , for  $i = 1 \dots N$ , such that  $J_{\text{PFE}}^S = J_{\text{PFE}}^{\xi, \varepsilon}$ . We have

$$\begin{aligned} J_{\text{PFE}}^{\xi, \varepsilon} - J_{\text{PFE}}^0 &= \mathcal{M} + \text{diag}(r_1, \dots, r_\xi, \varepsilon, -r_{\xi+2}, \dots, -r_N) \\ &\quad - \mathcal{M} - \text{diag}(-r_1, \dots, -r_N) \\ &= \text{diag}(2r_1, \dots, 2r_\xi, \varepsilon + r_{\xi+1}, 0, \dots, 0) \\ &> \mathbf{0} \end{aligned}$$

since  $\varepsilon \in [-r_{\xi+1}, r_{\xi+1}]$

Computing  $J_{\text{PFE}}^N - J_{\text{PFE}}^{\xi, \varepsilon}$  at the other endpoint works similarly, giving (5)

## Proof of Lemma 8.5 (cont'd)

2. Use (4) again to obtain two pairs  $(\xi_1, \varepsilon_1)$  and  $(\xi_2, \varepsilon_2)$ , where, by the assumption  $S_1 < S_2$ ,  $\xi_1 \leq \xi_2$ . First, assume that  $\xi_1 < \xi_2$ . Then

$$\begin{aligned} J_{\text{PFE}}^{\xi_2, \varepsilon_2} - J_{\text{PFE}}^{\xi_1, \varepsilon_1} &= \text{diag}(r_1, \dots, r_{\xi_2}, \varepsilon_2, -r_{\xi_2+2}, \dots, -r_N) \\ &\quad - \text{diag}(r_1, \dots, r_{\xi_1}, \varepsilon_1, -r_{\xi_1+2}, \dots, -r_N) \\ &= \text{diag}(0, \dots, 0, r_{\xi_1+1} - \varepsilon_1, 2r_{\xi_1+2}, \dots, 2r_{\xi_2}, \varepsilon_2 + r_{\xi_2+1}, 0, \dots, 0) \\ &> \mathbf{0} \end{aligned}$$

since  $\varepsilon_1 \in [-r_{\xi_1+1}, r_{\xi_1+1}]$ , and  $\varepsilon_2 \in [-r_{\xi_2+1}, r_{\xi_2+1}]$ . Now assume  $\xi_1 = \xi_2$ . Then, since  $S_1 < S_2$ , we find that  $\varepsilon_1 < \varepsilon_2$  and the diagonal matrix in the subtraction  $J_{\text{PFE}}^{\xi_2, \varepsilon_2} - J_{\text{PFE}}^{\xi_2, \varepsilon_1}$  takes the form  $\text{diag}(0, \dots, 0, \varepsilon_2 - \varepsilon_1, 0, \dots, 0) > \mathbf{0}$ . So (6) holds

## Proposition 8.6

$\mathcal{M}$  reducible  $\implies s(J_{PFE}^S)$  nondecreasing for  $S \in [0, N]$

$\mathcal{M}$  irreducible  $\implies s(J_{PFE}^S)$  increasing for  $S \in [0, N]$

$\implies \exists \mathcal{S}_{int} \subset (0, N)$  (resp.  $S^c \in (0, N)$ ) s.t. PFE LAS if  $S < \min(\mathcal{S}_{int})$  (resp.  $S < S^c$ )  
and PFE unstable if  $S > \max(\mathcal{S}_{int})$  (resp.  $S > S^c$ )



## Proof of Proposition 8.6

First, assume  $\mathcal{M}$  is irreducible. Then, by Lemma 8.5 and the fact that  $\mathcal{M}$  is irreducible (and thus so is  $J_{\text{PFE}}^S$ ), Theorem A.10(3) gives the result

## Proof of Proposition 8.6 (cont'd)

Now, assume that  $\mathcal{M}$  is reducible.  $\implies \exists$  permutation matrix  $P$  such that  $P^T \mathcal{M} P$  block upper triangular. Consider  $S \in [0, N] \subset \mathbb{R}$  and use (4) to obtain a corresponding pair  $(\xi, \varepsilon) \in \{0, \dots, N\} \times [-r_\xi, r_\xi]$ . Apply the same permutation to  $J_{\text{PFE}}^{\xi, \varepsilon}$ , giving

$$P^T J_{\text{PFE}}^{\xi, \varepsilon} P = \begin{pmatrix} \mathcal{M}_{11} + E_1 & \mathcal{M}_{12} & \cdots & \mathcal{M}_{1N} \\ 0 & \mathcal{M}_{22} + E_2 & & \\ & & \ddots & \\ 0 & \cdots & 0 & \mathcal{M}_{CC} + E_C \end{pmatrix}$$

where  $C$  is the number of strong components in the digraph of patches and

$$E_1 \oplus \cdots \oplus E_C = P^T \text{diag}(r_1, \dots, r_\xi, \varepsilon, -r_{\xi+2}, \dots, -r_N) P$$

with matrix on right hand side having  $\varepsilon$  as  $(\xi + 1)^{\text{th}}$  diagonal entry. As in the proof of Lemma 8.4, we have denoted  $\mathcal{M}_{ii}$  the diagonal blocks in the reduced form of  $\mathcal{M}$

## Proof of Proposition 8.6 (cont'd)

For  $j = 1, \dots, C$ , each of the matrices  $\mathcal{M}_{jj}$  is irreducible;  $C - 1$  of the matrices  $E_j$  are diagonal with entries  $-r_i$  and  $r_i$  on the diagonal (with some having only  $-r_i$ , some having only  $r_i$  and some having both types of entries)

The remaining  $E_j$  matrix is diagonal, with potentially  $-r_i$  and  $r_i$  as the others, but also  $\varepsilon$ . Call  $\eta \in \{1, \dots, C\}$  the index of the strong component containing the matrix with  $\varepsilon$

As a consequence, for all  $j = 1, \dots, C$ ,  $\mathcal{M}_{jj} + E_j$  are irreducible essentially nonnegative matrices, with only matrix  $\mathcal{M}_{\eta\eta} + E_\eta$  having an  $\varepsilon$  added to one of its diagonal entries

## Proof of Proposition 8.6 (cont'd)

As  $P^T J_{\text{PFE}}^{\xi, \varepsilon} P$  is block upper triangular, we have

$$s(P^T J_{\text{PFE}}^{\xi, \varepsilon} P) = \max \{s(\mathcal{M}_{11} + E_1), \dots, s(\mathcal{M}_{CC} + E_C)\}$$

Except for  $\mathcal{M}_{\eta\eta} + E_\eta$ , all matrices  $\mathcal{M}_{ii} + E_i$  have fixed spectral abscissa. Concerning matrix  $\mathcal{M}_{\eta\eta} + E_\eta$ , it is clear that the reasoning in the proof of Lemma 8.5(2) carries through and thus,

$$\forall \varepsilon_1, \varepsilon_2 \in [-r_{\xi+1}, r_{\xi+1}], \varepsilon_1 < \varepsilon_2 \implies J_{\text{PFE}}^{\xi, \varepsilon_1} < J_{\text{PFE}}^{\xi, \varepsilon_2}$$

Hence  $s(J_{\text{PFE}}^{\xi, \varepsilon})$  is the maximum of a set of  $C$  functions,  $C - 1$  of which are constant in  $\varepsilon$  and one of which is increasing in  $\varepsilon$ . It now follows that  $s(J_{\text{PFE}}^S)$  is a nondecreasing function of  $S$ , as desired

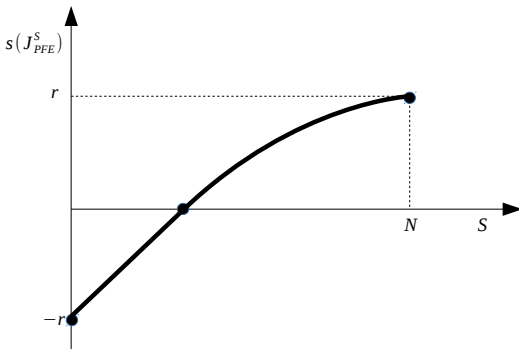
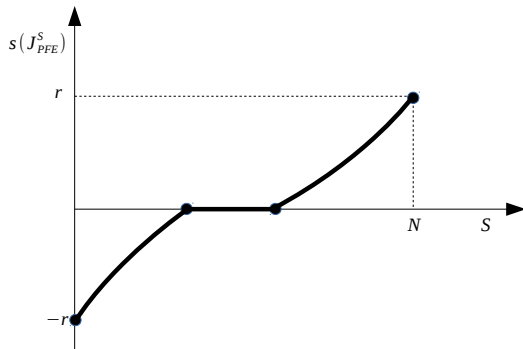
## We now can do Part 1 of Theorem 8.9

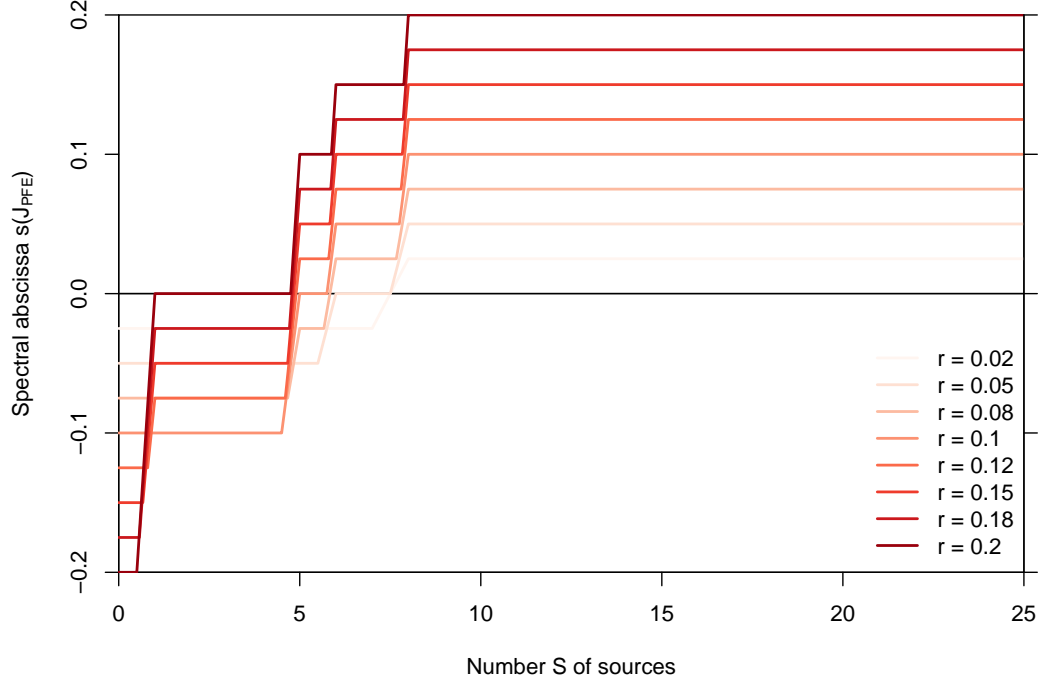
As  $J_{\text{PFE}}^S$  is essentially nonnegative, its spectral abscissa  $s(J_{\text{PFE}}^S)$  is an eigenvalue. Eigenvalues of  $J_{\text{PFE}}^S$  depend continuously on  $S$  (Theorem A.2). By Lemma 8.4,  $s(J_{\text{PFE}}^0) < 0$  and  $s(J_{\text{PFE}}^N) > 0$ , so by the Intermediate Value Theorem, there exists at least one point  $S^c \in (0, N)$  such that  $s(J_{\text{PFE}}^{S^c}) = 0$

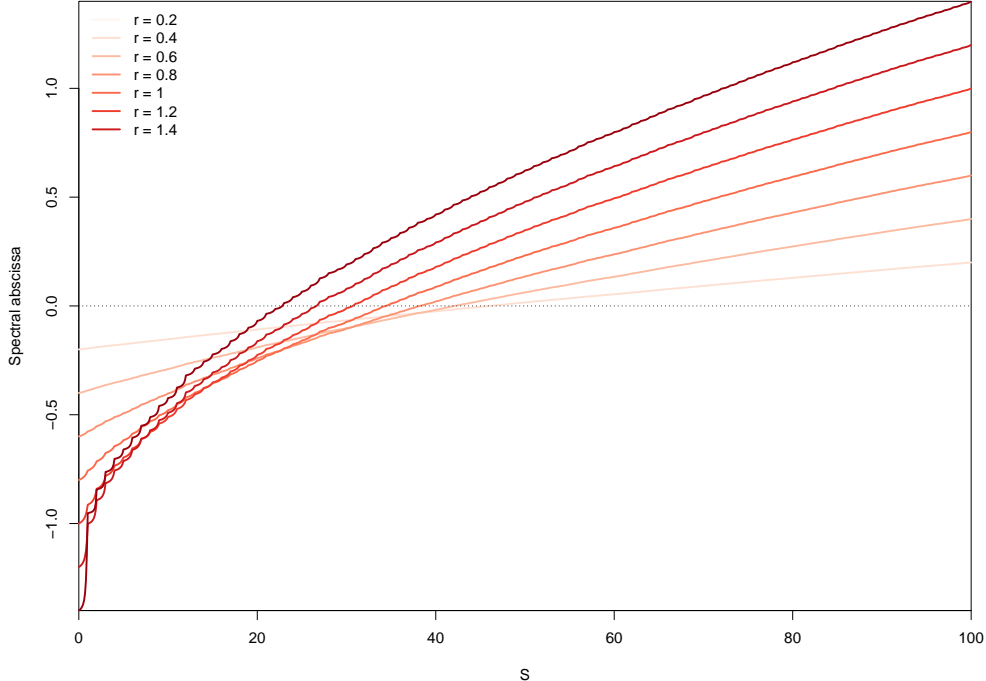
In the case where  $\mathcal{M}$  is irreducible,  $s(J_{\text{PFE}}^S)$  is increasing by Proposition 8.6 and as a consequence,  $S^c$  is unique. In the case where  $\mathcal{M}$  is reducible,  $s(J_{\text{PFE}}^S)$  is nondecreasing, therefore there exists an interval  $\mathcal{S}_{int}$ , possibly reduced to a single point, such that  $s(J_{\text{PFE}}^S) = 0$  for all  $S \in \mathcal{S}_{int}$

The usual criteria for local asymptotic stability and instability of equilibria then imply the first part of Theorem 8.9 for  $S < S^c$  and  $S > S^c$  (irreducible case) or  $S < \min(\mathcal{S}_{int})$  and  $S > \max(\mathcal{S}_{int})$  (reducible case)

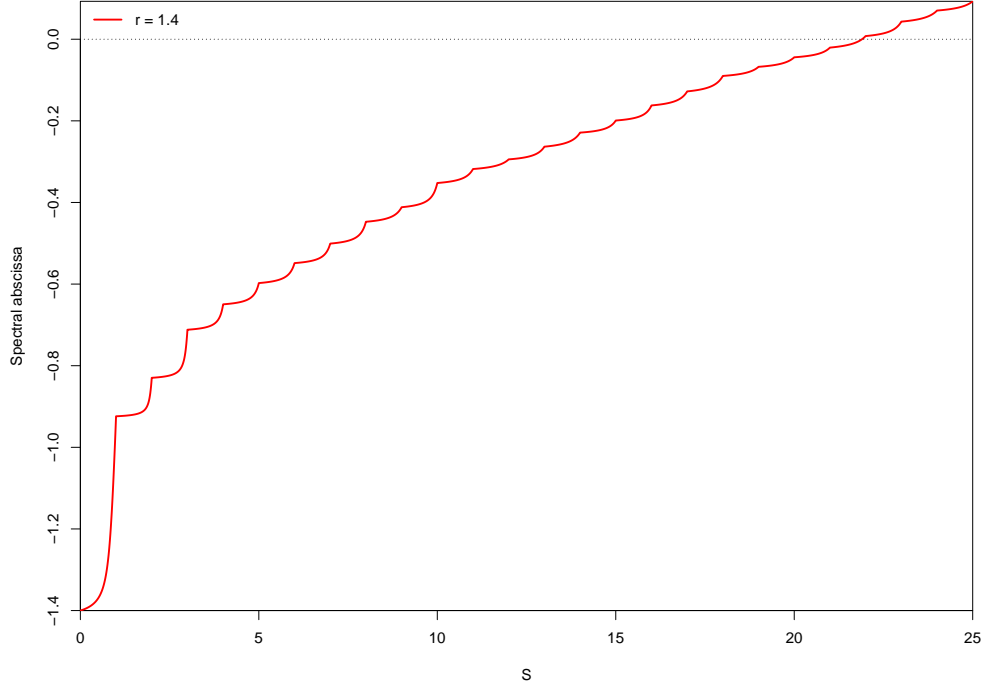
- ▶  $\mathcal{M}$  reducible:  $\exists \mathcal{S}_{int} \subset (0, N)$  s.t. PFE LAS if  $S < \min(\mathcal{S}_{int})$  and PFE unstable if  $S > \max(\mathcal{S}_{int})$
- ▶  $\mathcal{M}$  irreducible:  $\exists S^c \in (0, N)$  s.t. PFE LAS if  $S < S^c$  and PFE unstable if  $S > S^c$











As indicated by [Deutsch and Neumann, 1985], perturbation of the diagonal leads to convex changes in the spectral abscissa on each sub-interval

## We have a reproduction number when $\mathcal{M}$ irreducible

### Proposition 8.7

*Suppose  $\mathcal{M}$  irreducible. Define the basic reproduction number*

$$\mathcal{R}_0 = \rho \left( (\mathcal{M}_s + \mathcal{M}_{st}(\mathcal{D}_t - \mathcal{M}_t)^{-1} \mathcal{M}_{ts})^{-1} \mathcal{D}_s \right) \quad (7)$$

*where  $\mathcal{M}_s, \mathcal{M}_t, \mathcal{M}_{st}, \mathcal{M}_{ts}$  are defined as in (2),  $\mathcal{D}_s = \text{diag}(r_1, \dots, r_S)$  and  $\mathcal{D}_t = \text{diag}(r_{S+1}, \dots, r_N)$ . Then*

$$s(J_{PFE}^S) < 0 \iff \mathcal{R}_0 < 1 \text{ and } s(J_{PFE}^S) > 0 \iff \mathcal{R}_0 > 1 \quad (8)$$

## Proof of Proposition 8.7

Write (3) as

$$J_{\text{PFE}}^S = \mathcal{M} + \tilde{\mathcal{D}}_s - \tilde{\mathcal{D}}_t$$

where  $\tilde{\mathcal{D}}_s = \mathcal{D}_s \oplus \mathbf{0}_{N-S \times N-S}$  and  $\tilde{\mathcal{D}}_t = \mathbf{0}_{S \times S} \oplus \mathcal{D}_t$ . Let  $-\alpha$  be the spectral abscissa of  $\mathcal{M} + \tilde{\mathcal{D}}_s - \tilde{\mathcal{D}}_t$ . From Proposition 8.3(2), there is a vector  $\mathbf{v} \gg \mathbf{0}$  such that

$$(\mathcal{M} + \tilde{\mathcal{D}}_s - \tilde{\mathcal{D}}_t)\mathbf{v} = -\alpha\mathbf{v}$$

In other words,

$$\alpha\mathbf{v} = (\tilde{\mathcal{D}}_t - \mathcal{M})\mathbf{v} - \tilde{\mathcal{D}}_s\mathbf{v}$$

## Proof of Proposition 8.7 (cont'd)

By the assumption of irreducibility of  $\mathcal{M}$ , it follows from Proposition 8.3(4) that  $\tilde{\mathcal{D}}_t - \mathcal{M}$  is an irreducible nonsingular M-matrix and  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \gg \mathbf{0}$

Then

$$\alpha (\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \mathbf{v} = \mathbf{v} - (\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \tilde{\mathcal{D}}_s \mathbf{v}$$

with the matrix  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \tilde{\mathcal{D}}_s > \mathbf{0}$

As a consequence, from the Perron-Frobenius Theorem A.5, the spectral radius of  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \tilde{\mathcal{D}}_s$  is an eigenvalue and is associated to a nonnegative eigenvector

## Proof of Proposition 8.7 (cont'd)

Let  $\mathbf{u}$  be such an eigenvector, normalised so that  $\mathbf{u}^T \mathbf{v} = 1$ . Then

$$\alpha \mathbf{u}^T (\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \mathbf{v} = \mathbf{u}^T \mathbf{v} \left( 1 - \rho \left\{ (\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \tilde{\mathcal{D}}_s \right\} \right)$$

Thus

$$\alpha > 0 \iff \rho \left\{ (\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \tilde{\mathcal{D}}_s \right\} < 1$$

and

$$\alpha < 0 \iff \rho \left\{ (\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \tilde{\mathcal{D}}_s \right\} > 1$$

## Proof of Proposition 8.7 (cont'd)

From the structure of  $\tilde{\mathcal{D}}_s$ , the spectral radius of  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1}\tilde{\mathcal{D}}_s$  is the spectral radius of

$$(\tilde{\mathcal{D}}_t - \mathcal{M})_{[11]}^{-1} \mathcal{D}_s$$

where  $(\tilde{\mathcal{D}}_t - \mathcal{M})_{[11]}^{-1}$  is the (1,1) block in  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1}$

Writing  $\mathcal{M}$  as (2), we have by the formula for the inverse of a  $2 \times 2$  block matrix that

$$(\tilde{\mathcal{D}}_t - \mathcal{M})_{[11]}^{-1} = (-\mathcal{M}_s - \mathcal{M}_{st}(\mathcal{D}_t - \mathcal{M}_t)^{-1}\mathcal{M}_{ts})^{-1}$$

## Proof of Proposition 8.7 (cont'd)

Clearly,

$$\begin{aligned}\rho\left((- \mathcal{M}_s - \mathcal{M}_{st}(\mathcal{D}_t - \mathcal{M}_t)^{-1}\mathcal{M}_{ts})^{-1}\mathcal{D}_s\right) \\ = \rho\left((\mathcal{M}_s + \mathcal{M}_{st}(\mathcal{D}_t - \mathcal{M}_t)^{-1}\mathcal{M}_{ts})^{-1}\mathcal{D}_s\right)\end{aligned}$$

giving the result



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So..

we are done!

.. Are we? The result is only local, can we go further?

## System (1) is cooperative

Jacobian of (1):

$$J(\mathbf{P}_s, \mathbf{P}_t) = \begin{pmatrix} \mathbf{G}'_s(\mathbf{P}_s)\mathbf{P}_s + \mathbf{G}_s(\mathbf{P}_s) + \mathcal{M}_s & \mathcal{M}_{st} \\ \mathcal{M}_{ts} & -\mathcal{D}_t + \mathcal{M}_t \end{pmatrix} \quad (9)$$

where

$$\mathbf{G}'_s(\mathbf{P}_s) = \text{diag} \left( -\frac{r_1}{K_1}, \dots, -\frac{r_S}{K_S} \right)$$

Thus

$$J(\mathbf{P}_s, \mathbf{P}_t) = \mathcal{M} + ((\mathbf{G}'_s(\mathbf{P}_s)\mathbf{P}_s + \mathbf{G}_s(\mathbf{P}_s)) \oplus -\mathcal{D}_t)$$

with  $\mathbf{G}'_s(\mathbf{P}_s)\mathbf{P}_s + \mathbf{G}_s(\mathbf{P}_s)$  and  $-\mathcal{D}_t$  diagonal

$\implies$  system (1) is cooperative

## A theorem of Hirsch

So, to move forward, we would like to apply the following result

### Theorem 8.8 (Th. 6.1 in Hirsch (1984) – BAMS 11(1))

*Let  $\mathbf{F}$  be a  $C^1$  vector field in  $\mathbb{R}^n$  with flow  $\phi$  preserving  $\mathbb{R}_+^n$  for  $t > 0$  and strongly monotone in  $\mathbb{R}_+^n$ . Suppose that the origin is an equilibrium and all trajectories in  $\mathbb{R}_+^n$  are bounded. Suppose the matrix-valued map  $D\mathbf{F} : \mathbb{R}_+^n \rightarrow \mathbb{R}^{n \times n}$  is strictly antimonotone, i.e.,*

$$\mathbf{x} > \mathbf{y} \implies D\mathbf{F}(\mathbf{x}) < D\mathbf{F}(\mathbf{y})$$

*Then either all trajectories in  $\mathbb{R}_+^n$  go to the origin, or there exists a unique equilibrium  $\mathbf{P}^* \in \text{Int}\mathbb{R}_+^n$  and all trajectories in  $\mathbb{R}_+^n \setminus \{\mathbf{0}\}$  limit to  $\mathbf{P}^*$*

OK, nice, but..

Take

$$\mathbf{P}_1 = (0, \dots, 0, \star, \dots, \star) \text{ and } \mathbf{P}_2 = (0, \dots, 0, \star, \dots, \star)$$

have their first  $S$  entries zero, i.e.,  $\mathbf{P}_1 = (\mathbf{0}_s, \mathbf{P}_t^1)$  and  $\mathbf{P}_2 = (\mathbf{0}_s, \mathbf{P}_t^2)$ ; assume  $\mathbf{P}_1 > \mathbf{P}_2$ ,  
i.e.,  $\mathbf{P}_t^1 > \mathbf{P}_t^2$

Then

$$\begin{aligned} J(\mathbf{0}_s, \mathbf{P}_t^1) &= \mathcal{M} + ((\mathbf{G}'_s(\mathbf{0}_s)\mathbf{0}_s + \mathbf{G}_s(\mathbf{0}_s)) \oplus -\mathcal{D}_t) \\ &= \mathcal{M} + (\mathcal{D}_s \oplus -\mathcal{D}_t) \\ &= J(\mathbf{0}_s, \mathbf{P}_t^2) \end{aligned}$$

i.e.,

$$J_{\mathbf{P}_1}^S = J_{\mathbf{P}_2}^S$$

$\implies$  (1) is not strictly antimonotone

## (non) lasciate ogni speranza, voi ch'intrate

Except for strict antimonotonicity of  $\mathbf{F}$ , all hypotheses of [Hirsch (1984) – Th. 6.1] are satisfied:

- ▶ in the case  $\mathcal{M}$  irreducible, (1) is strongly monotone (by [Hirsch (1984) – Th. 1.7])
- ▶ the origin is an equilibrium
- ▶ all solutions of (1) are bounded in  $\mathbb{R}_+^N$  (not shown here, but not hard)

$\implies$  by other results (e.g., Hirsch *ibid*), there exists  $\mathbf{P}^* \gg \mathbf{0}$

What is the use of strict antimonotonicity in the proof of [Hirsch (1984) – Th. 6.1]? ..  
To show uniqueness of  $\mathbf{P}^*$

More precisely: let  $\mathbf{z} \in (\mathbf{0}, \mathbf{P}^*)$ , where  $\mathbf{P}^* \gg \mathbf{0}$  is a nontrivial equilibrium

Strict antimonotonicity  $\implies \mathbf{F}(\mathbf{z}) > \mathbf{0}$ , and we can then proceed with the remainder of the proof of [Hirsch (1984) – Th. 6.1]

Let us show that we indeed have  $\mathbf{F}(\mathbf{z}) > \mathbf{0}$  for (1), despite the lack of strict antimonotonicity

As in [Hirsch (1984) – Th. 6.1]: for  $i = 1, \dots, N$ , let

$$\begin{aligned} g_i : [0, 1] &\rightarrow \mathbb{R} \\ s &\mapsto F_i(s\mathbf{P}^*) \end{aligned}$$

Then  $g_i(0) = g_i(1) = 0$  for  $i = 1, \dots, N$  and, for  $i = S + 1, \dots, N$  (sinks),

$$g_i(s) = -r_i s P_i^* + \sum_{j=1}^N m_{ij} s P_j^* = \left( r_i P_i^* + \sum_{j=1}^N m_{ij} P_j^* \right) s = 0$$

However, for  $i = 1, \dots, S$  (sources),

$$g_i(s) = r_i \left( 1 - \frac{s P_i^*}{K_i} \right) s P_i^* + \sum_{j=1}^N m_{ij} s P_j^*$$

Ha!

$$g_i''(s) = -\frac{2r_i P_i^{*2}}{K} < 0, \quad i = 1, \dots, S$$

$\implies$  for  $i = 1, \dots, S$ ,  $g_i(s) > 0$  when  $s \in (0, 1)$

$\implies$  when  $S > 0$ ,  $\mathbf{F}(\mathbf{z}) > \mathbf{0}$ ,  $\forall \mathbf{z} \in (\mathbf{0}, \mathbf{P}^*)$



And we can then carry on with the remainder of the proof of [Hirsch (1984) – Th. 6.1]

To finish, the case  $S = 0$  is easy:

$$\left( \sum_{i=1}^N P_i \right)' = - \sum_{i=1}^N r_i P_i < 0$$

since at least one of the  $P_i(0) > 0$

$$\Rightarrow \left( \sum_{i=1}^N P_i \right) \rightarrow 0 \Rightarrow \lim_{t \rightarrow \infty} P_i(t) = 0 \text{ for } i = 1, \dots, N$$

Et hop!  $\square$

## To conclude (mathematically)

### Theorem 8.9

*There exists a critical interval  $S_{int} \subset (0, N) \subset \mathbb{R}$  s.t.*

- ▶  $S < \min(S_{int}) \implies$  PFE LAS
- ▶  $S > \max(S_{int}) \implies$  PFE instable

*Additionally, if the patch digraph is strongly connected, then*

- ▶  $S_{int}$  is reduced to a point  $S^c$
- ▶  $S < S^c \implies$  PFE GAS
- ▶  $S > S^c \implies \exists! \mathbf{P}^* \gg \mathbf{0}$  GAS for  $\mathbb{R}_+^N \setminus \{\mathbf{0}\}$

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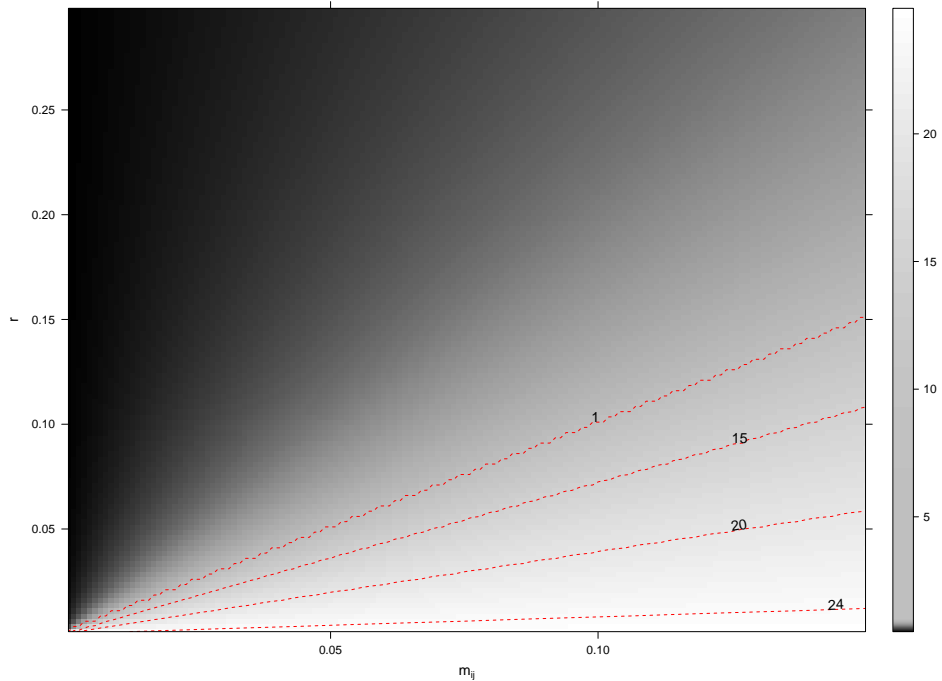
An interesting special case

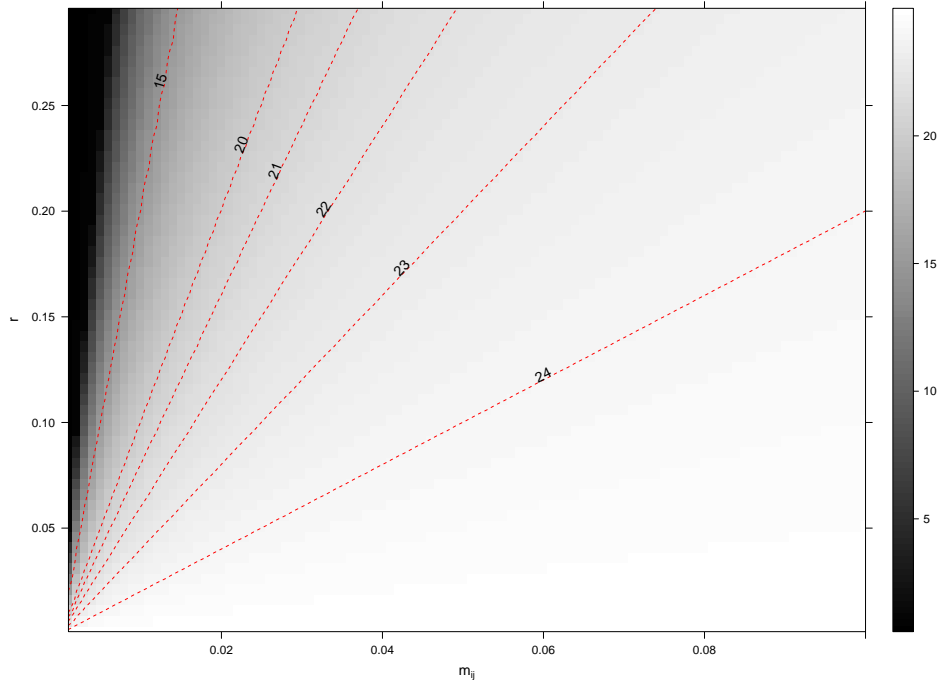
In the 2 figures that follow:

- ▶  $N = 50$
- ▶  $r = r_i, \forall i = 1, \dots, N$
- ▶  $m_{ij} = m, \forall i, j = 1, \dots, N$  s.t.  $m_{ij} > 0$
- ▶ plot is value of  $S^c$  as a function of  $m$  and  $r$

Figure 1: ring of patches

Figure 2: complete digraph





## Case of complete homogeneous movement

### Proposition 8.10

*Suppose that the movement digraph is complete and that  $m_{ij} = m$  for  $i, j = 1, \dots, N$ ,  $i \neq j$*

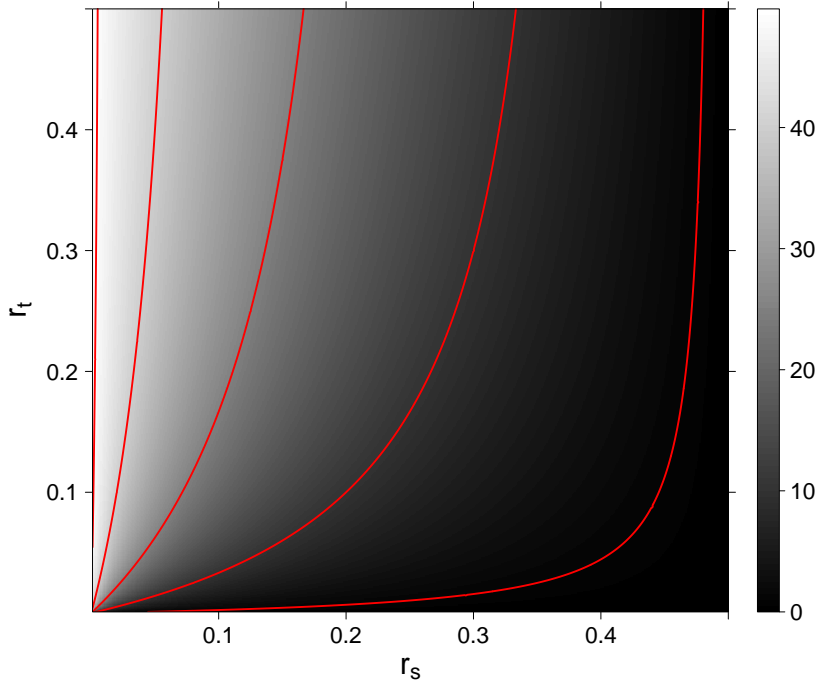
*Suppose that  $S \in \{1, \dots, N-1\}$ , that for  $i = 1, \dots, S$ ,  $r_i = r_s$  and that for  $i = S+1, \dots, N$ ,  $r_i = r_t$*

*Then*

$$S^c = \frac{mNr_t - r_sr_t}{m(r_s + r_t)} \quad (10)$$

If  $r_s = r_t = r$ , then

$$S^c = \frac{N}{2} - \frac{r}{2m} \quad (11)$$





## Proof of Prop 8.10 uses equitable partitions

Section 9.3 in *Algebraic Graph Theory*, Godsil & Royle (2013)

An **equitable partition**  $\pi$  splits a graph  $X$  into **cells**  $\mathcal{C}_i$ ,  $i = 1, \dots, r$ , s.t. for a vertex  $u$  in cell  $\mathcal{C}_i$ , the number of neighbours in cell  $\mathcal{C}_j$  is a constant  $b_{ij}$  that does not depend on  $u$

$\iff$  the subgraph of  $X$  induced by each cell is regular [vertices have same degree]  
and edges joining two distinct cells form a semiregular bipartite graph [vertices have same degree in each bipartite component]

The digraph with the  $r$  cells of  $\pi$  as vertices and the  $b_{ij}$  arcs from the  $i^{\text{th}}$  to the  $j^{\text{th}}$  cell of  $\pi$  is the **quotient**  $X/\pi$  of  $X$  on  $\pi$ . The adjacency matrix of  $X/\pi$  is  $A(X/\pi) = [b_{ij}]$

# Characterising an equitable partition

## Lemma 8.11 (A friendly characterisation)

*$X$  graph,  $A(X)$  its adjacency matrix,  $\pi$  a partition of  $V(X)$  with characteristic matrix  $P$ . Then*

$$\pi \text{ equitable} \iff \text{column space of } P \text{ is } A\text{-invariant}$$

Write

$$J_{\text{PFE}}^S = \begin{pmatrix} m\mathbb{J} - Nm\mathbb{I} + r_s\mathbb{I} & m\mathbb{J} \\ m\mathbb{J} & m\mathbb{J} - Nm\mathbb{I} - r_t\mathbb{I} \end{pmatrix} \quad (12)$$

with  $\mathbb{J}$  matrix of all 1's

Consider (12) as the adjacency matrix of a digraph  $\mathcal{G}$

Suppose partition  $\pi$  splits  $\mathcal{G}$  in two cells,  $\{S_i\}_{i=1,\dots,S}$  (sources) and  $\{T_i\}_{i=S+1,\dots,N}$  (sinks)

The characteristic matrix of  $\pi$  is the  $N \times 2$ -matrix

$$C = \begin{pmatrix} \mathbb{1}_S & \mathbf{0}_S \\ \mathbf{0}_{N-S} & \mathbb{1}_{N-S} \end{pmatrix}$$

We have

$$J_{\text{PFE}}^S \mathbb{1} = J_{\text{PFE}}^S \begin{pmatrix} \mathbb{1}_S \\ \mathbb{1}_{N-S} \end{pmatrix} = \begin{pmatrix} r_s \mathbb{1}_S \\ -r_t \mathbb{1}_{N-S} \end{pmatrix}$$

Thus the column space of  $C$  is  $J_{\text{PFE}}^S$ -invariant  $\implies \pi$  is equitable

# Properties of equitable partitions

## Lemma 8.12

*$\pi$  equitable partition of graph  $X$  with characteristic matrix  $P$ , and  $B = A(X/\pi)$ . Then  $AP = PB$  and  $B = (P^T P)^{-1} P^T AP$*

## Theorem 8.13

*$\pi$  equitable partition of graph  $X \implies$  characteristic polynomial of  $A(X/\pi)$  divides characteristic polynomial of  $A(X)$*

$\Rightarrow$  the quotient matrix  $B_{\text{PFE}}^S$  satisfies

$$B_{\text{PFE}}^S = (C^T C)^{-1} C^T J_{\text{PFE}}^S C$$

$$\Rightarrow B_{\text{PFE}}^S = \begin{pmatrix} mS - mN + r_s & m(N - S) \\ mS & -(mS + r_s) \end{pmatrix}$$

And  $\sigma(B_{\text{PFE}}^S) \subset \sigma(J_{\text{PFE}}^S)$

$B_{\text{PFE}}^S$  essentially nonnegative (and clearly irreducible)

$$\implies \exists! \mathbf{v}_p \gg \mathbf{0} \text{ s.t. } B_{\text{PFE}}^S \mathbf{v}_p = \lambda_p \mathbf{v}_p = s(B_{\text{PFE}}^S) \mathbf{v}_p$$

Then  $J_{\text{PFE}}^S C = C B_{\text{PFE}}^S$

So

$$J_{\text{PFE}}^S C \mathbf{v}_p = C B_{\text{PFE}}^S \mathbf{v}_p = \lambda_p C \mathbf{v}_p$$

and  $C \mathbf{v}_p$  is an eigenvector of  $J_{\text{PFE}}^S$  that is also  $\gg \mathbf{0}$

As the only eigenvector  $\gg \mathbf{0}$  of  $J_{\text{PFE}}^S$  corresponds to  $s(J_{\text{PFE}}^S)$ , we have  
 $s(J_{\text{PFE}}^S) = s(B_{\text{PFE}}^S)$

To compute  $S^c$ , recall  $S^c$  is value of  $S$  where PFE loses stability

Consider  $B_{\text{PFE}}^S$ . We have  $\text{tr}(B_{\text{PFE}}^S) = -mN + r_s - r_t$  and

$$\det(B_{\text{PFE}}^S) = -mS(r_s + r_t) - r_s r_t + mNr_t$$

One shows easily that  $\det(\cdot)$  governs stability

$$\implies S^c = \frac{mNr_t - r_s r_t}{m(r_s + r_t)}$$





## Appendix – Used results

Theorem A.1 ([Horn and Johnson, 2013, Problem 1.2.P8])

*Let  $A \in \mathcal{M}_n$  and  $\lambda \in \mathbb{C}$  be given. Suppose that the eigenvalues of  $A$  are  $\lambda_1, \dots, \lambda_n$ . Explain why  $p_{A+\lambda\mathbb{I}}(t) = p_A(t - \lambda)$  and deduce from this identity that the eigenvalues of  $A + \lambda\mathbb{I}$  are  $\lambda_1 + \lambda, \dots, \lambda_n + \lambda$*

## Theorem A.2 ([Horn and Johnson, 2013, Theorem 2.4.9.2])

*Let an infinite sequence  $A_1, A_2, \dots \in \mathcal{M}_n$  be given and suppose that  $\lim_{k \rightarrow \infty} A_k = A$  (entrywise convergence)*

*Let  $\lambda(A) = [\lambda_1(A) \cdots \lambda_n(A)]^T$  and  $\lambda(A_k) = [\lambda_1(A_k) \cdots \lambda_n(A_k)]^T$  be given presentations of the eigenvalues of  $A$  and  $A_k$ , respectively, for  $k = 1, 2, \dots$ . Let  $S_n = \{\pi : \pi \text{ is a permutation of } \{1, 2, \dots, n\}\}$ . Then for each given  $\varepsilon > 0$  there exists a positive integer  $N = N(\varepsilon)$  such that*

$$\min_{\pi \in S_n} \max_{i=1, \dots, n} \{|\lambda_{\pi(i)}(A_k) - \lambda_i(A)|\} \leq \varepsilon \text{ for all } k \geq N$$

[Varga, 2010]

Let  $A \in \mathcal{M}_n(\mathbb{C})$ . Denote  $N = \{1, \dots, n\}$ . For  $i \in N$ , define

$$r_i(A) = \sum_{j \in N \setminus \{i\}} |a_{ij}|$$

to be the  $i$ th deleted row sums of  $A$ . Assume that  $r_i(A) = 0$  if  $n = 1$ . Let

$$\Gamma_i(A) = \{z \in \mathbb{C} \mid |z - a_{ii}| \leq r_i(A)\} \quad i \in N$$

be the  $i$ th **Gershgorin disk** of  $A$  and

$$\Gamma(A) = \bigcup_{i \in N} \Gamma_i(A)$$

be the **Gershgorin set** of  $A$ .  $\Gamma_i$  and  $\Gamma$  are closed and bounded in  $\mathbb{C}$ .  $\Gamma_i(A)$  is a disk centred at  $a_{ii}$  and with radius  $r_i(A)$ ,  $i \in N$ .

### Theorem A.3 (Gershgorin, 1931)

*For all  $A \in \mathcal{M}_n(\mathbb{C})$  and for all  $\lambda \in \sigma(A)$ , there exists  $k \in \mathbb{N}$  such that*

$$|\lambda - a_{kk}| \leq r_k(A)$$

*i.e.,  $\lambda \in \Gamma_k(A)$  and thus  $\lambda \in \Gamma(A)$ . Since this is true for all  $\lambda$ , we have*

$$\sigma(A) \subseteq \Gamma(A)$$

### Remark A.4

*This also works with deleted column sums; indeed, just consider  $A^T$  in this case. However, this typically gives different disks*

Theorem A.5 (Perron-Frobenius [Fiedler, 2008, Theorem 4.2.1])

*$A \geq 0$  be irreducible. Then  $\rho(A)$  is a simple positive eigenvalue of  $A$  and there exists a positive eigenvector  $\mathbf{x}$  associated to  $\rho(A)$ . No other nonnegative vector is associated with any other eigenvalue of  $A$*

### Definition A.6

A matrix is of class  $Z_n$  if it is in  $\mathcal{M}_n(\mathbb{R})$  and such that  $a_{i,j} \leq 0$ ,  $i \neq j$ ,  $i, j = 1, \dots, n$

$$Z_n = \{A \in \mathcal{M}_n : a_{i,j} \leq 0, i \neq j\}$$

We also say that  $A \in Z_n$  has the **Z-sign pattern**

### Theorem A.7 ([Fiedler, 2008, Theorem 5.1.1])

Let  $A \in Z_n$ . TFAE and define matrices of class  $K$  (or nonsingular  $M$ -matrix)

1. There is a nonnegative vector  $x$  such that  $Ax > 0$
2. There is a positive vector  $x$  such that  $Ax > 0$
3. There is a diagonal matrix  $\text{diag}(D) > 0$  such that the entries in  $AD = [w_{ik}]$  are such that

$$w_{ii} > \sum_{k \neq i} |w_{ik}| \forall i$$

4. For any  $B \in Z_n$  such that  $A \geq B$ , then  $B$  is nonsingular
5. Every real eigenvalue of any principal submatrix of  $A$  is positive.
6. All principal minors of  $A$  are positive



## Theorem A.7 ([Fiedler, 2008, Theorem 5.1.1] (continued))

7. *For all  $k = 1, \dots, n$ , the sum of all principal minors is positive*
8. *Every real eigenvalue of  $A$  is positive*
9. *There exists a matrix  $C \geq 0$  and a number  $k > \rho(A)$  such that  $A = k\mathbb{I} - C$*
10. *There exists a splitting  $A = P - Q$  of the matrix  $A$  such that  $P^{-1} \geq 0$ ,  $Q \geq 0$ , and  $\rho(P^{-1}Q) < 1$*
11.  *$A$  is nonsingular and  $A^{-1} \geq 0$*
- 12.
- 13.
- 14.
- 15.
- 16.
- 17.
18. *The real part of any eigenvalue of  $A$  is positive*

### Theorem A.8 ([Fiedler, 2008, Theorem 5.2.1])

Let  $A \in Z_n$ . TFAE and define matrices of class  $K_0$

1.  $A + \varepsilon \mathbb{I} \in K$  for all  $\varepsilon > 0$
2. Every real eigenvalue of a principal submatrix of  $A$  is nonnegative
3. All principal minors of  $A$  are nonnegative
4. The sum of all principal minors of order  $k = 1, \dots, n$  is nonnegative
5. Every real eigenvalue of  $A$  is nonnegative
6. There exists  $C \geq 0$  and  $k \geq \rho(C)$  such that  $A = k\mathbb{I} - C$
7. Every eigenvalue of  $A$  has nonnegative real part

## Theorem A.9 ([Fiedler, 2008, Theorem 5.2.10])

Let  $A \in Z$  be irreducible. TFAE

1.  $\exists \mathbf{x} > \mathbf{0}$  s.t.  $A\mathbf{x} > \mathbf{0}$
2.  $\exists \mathbf{x} > \mathbf{0}$  s.t.  $A\mathbf{x} \geq \mathbf{0}$  and  $A\mathbf{x} \neq \mathbf{0}$
3.  $A \in K$
4.  $A^{-1} > \mathbf{0}$

Theorem A.10 ([Smith, 1995, Corollary 4.3.2])

*Let  $A$  be quasi-positive. Then  $s(A) \in \sigma(A)$  and  $\exists \mathbf{v} > \mathbf{0}$  such that  $A\mathbf{v} = s(A)\mathbf{v}$ . Moreover,  $\operatorname{Re} \lambda < s(A)$  for all  $\lambda \in \sigma(A) \setminus \{s(A)\}$ . If, in addition,  $A$  is irreducible, then*

- 1.  $s(A)$  has algebraic multiplicity 1*
- 2.  $\mathbf{v} \gg \mathbf{0}$  and any eigenvector  $\mathbf{w} > \mathbf{0}$  of  $A$  is a positive multiple of  $\mathbf{v}$*
- 3. If  $B$  is a matrix satisfying  $B > A$ , then  $S(B) > s(A)$*
- 4. If  $s(A) < 0$  then  $-A^{-1} \gg \mathbf{0}$*



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