# MATH 4370/7370 - Linear Algebra and Matrix Analysis

An example from metapopulations

Julien Arino

Fall 2023



#### Outline

Position of the problem

A metapopulation of sources and sinks with explicit movement

The movement matrix

Local analysis of the model

Global behaviour

An interesting special case

### Why do this?

This is mostly about dynamics

Looping back to our first few lectures: matrices are everywhere!

This is a (rather abstract) problem in theoretical ecology (or mathematical ecology?)

We will be using a surprising number of results we have already seen

#### Position of the problem

A metapopulation of sources and sinks with explicit movement

The movement matrix

Local analysis of the mode

Global behaviour

An interesting special case

### Rael & Taylor (2018)

A flow network model for animal movement on a landscape with application to invasion, Theoretical Ecology

$$P'_{i} = P_{i}B(P_{i}) + \sum_{j=1}^{N} a_{ji}P_{j}m(P_{j}, P_{i}) - P_{i}\sum_{j=1}^{N} a_{ij}m(P_{i}, P_{j})$$

where

$$m(P_i, P_j) = \frac{\max\{0, \pi(P_i) - \pi(P_j)\}}{d_{ij}} \qquad \pi(P_i) = \frac{P_i}{K_i}$$

 $d_{ij}$  distance from i to j,  $K_i$  carrying capacity

$$B(P_i) = egin{cases} r_i \left(1 - rac{P_i}{K_i}
ight) & ext{sources} \ -r_i & ext{sinks} \end{cases}$$





#### Number of Source Patches Required for Population Persistence in a Source–Sink Metapopulation with Explicit Movement

Julien Arino<sup>1</sup> • Nicolas Bajeux<sup>1,2</sup> • Steve Kirkland<sup>1</sup>

Received: 26 October 2018 / Accepted: 26 February 2019 / Published online: 7 March 2019 © Society for Mathematical Biology 2019



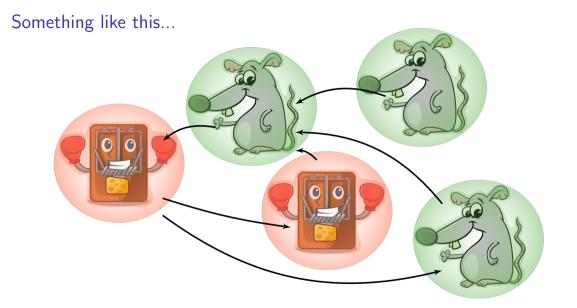
#### Position of the problem

Assume a metapopulation of patches connected through transport of individuals between them

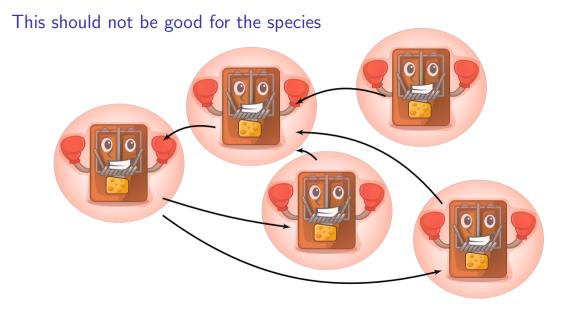
Some patches are sources, others are sinks:

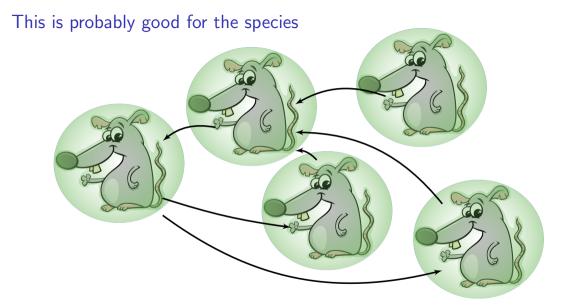
- Population tends to persist in sources
- Population tends to vanish in sinks

*Ceteris paribus*, does there exist a ratio of the number of source to sink patches s.t. the population of the coupled system persists?



#### Obvious special cases





#### Position of the problem

A metapopulation of sources and sinks with explicit movement

The movement matrix

Local analysis of the mode

Global behaviour

An interesting special case

#### Model for N patches

W.l.o.g.:  $S \ge 0$  first patches are sources, N-S remaining are sinks [w.l.o.g. but not that trivial nonetheless]

#### Sources:

$$P'_{i} = r_{i}P_{i}\left(1 - \frac{P_{i}}{K_{i}}\right) + \sum_{i=1}^{N} m_{ij}P_{j}, \quad i = 1, \dots, S$$
 (1a)

Sinks:

$$P'_{i} = -r_{i}P_{i} + \sum_{j=1}^{N} m_{ij}P_{j}, \quad i = S + 1, \dots, N$$
 (1b)

$$m_{ii} = -\sum_{\substack{j=1\i 
eq i}}^{N} m_{ji}$$

#### Vector form (v1) $\mathbf{P} = (P_1, \dots, P_N)^T$

$$P' = G(P)P + MP$$

 $\mathbf{G}(\mathbf{P}) = \operatorname{diag}\left(r_1\left(1 - \frac{P_1}{\kappa_1}\right), \dots, r_S\left(1 - \frac{P_S}{\kappa_S}\right), -r_{S+1}, \dots, -r_N\right)$ 

A metapopulation of sources and sinks with explicit movement

### Vector form (v2)

$$\mathbf{P}_s = (P_1, \dots, P_S)^T$$
 (sources),  $\mathbf{P}_t = (P_{S+1}, \dots, P_N)$  (sinks)

$$egin{aligned} \mathbf{P}_s' &= \mathbf{G}_s(\mathbf{P}_s)\mathbf{P}_s + \mathcal{M}_s\mathbf{P}_s + \mathcal{M}_{st}\mathbf{P}_t \ \mathbf{P}_t' &= -\mathcal{D}_t\mathbf{P}_t + \mathcal{M}_{ts}\mathbf{P}_s + \mathcal{M}_t\mathbf{P}_t \end{aligned}$$

where

$$egin{aligned} \mathbf{G}_s(\mathbf{P}_s) &= \operatorname{diag}\left(r_1\left(1-rac{P_1}{\mathcal{K}_1}
ight), \ldots, r_S\left(1-rac{P_S}{\mathcal{K}_S}
ight)
ight) \ \mathcal{D}_t &= \operatorname{diag}\left(r_{S+1}, \ldots, r_N
ight) \ \left(egin{aligned} \mathcal{M}_s & \mathcal{M}_{st} \ \mathcal{M}_{ts} & \mathcal{M}_t \end{aligned}
ight) &= \mathcal{M} \end{aligned}$$

p. 11 - A metapopulation of sources and sinks with explicit movement

#### Main result we want to get to

#### Theorem 7.1

 $\exists$  a unique critical interval  $S_{int} \subset (0, N) \subset \mathbb{R}$  s.t. if the number of source patches  $S < \min(S_{int})$ , the population-free equilibrium (PFE)  $(P_1, \ldots, P_N) = (0, \ldots, 0)$  of (1) is locally asymptotically stable and if  $S > \max(S_{int})$ , the PFE is unstable

If, additionally, the digraph of patches is strongly connected, then  $S_{int}$  reduces to a single point  $S^c$  and the PFE is globally asymptotically stable in the case that  $S < S^c$ ; in the case that  $S > S^c$ , there is a unique component-wise positive equilibrium  $\mathbf{P}^*$  that is GAS with respect to  $\mathbb{R}^N_+ \setminus \{0\}$ 

A metapopulation of sources and sinks with explicit movement

#### Position of the problem

A metapopulation of sources and sinks with explicit movement

#### The movement matrix

Local analysis of the mode

Global behaviour

An interesting special case

#### Properties of the movement matrix ${\cal M}$

#### Lemma 7.2

- 1.  $0 \in \sigma(\mathcal{M})$  corresponding to left e.v.  $\mathbb{1}^T$
- 2. -M is a singular M-matrix
- 3.  $0 = s(\mathcal{M}) \in \sigma(\mathcal{M})$
- 4. If  $\mathcal M$  irreducible, then  $s(\mathcal M)$  has multiplicity 1

[ $\sigma$  spectrum]

[s spectral abscissa]

#### Proof of Lemma 7.2

1. The result is obvious: all column sums of  $\mathcal{M}$  equal zero, i.e.,  $\mathbb{1}^T \mathcal{M} = 0 \mathbb{1}^T$ 

3. Using the Gershgorin Disk Theorem [Varga, 2010] on  $\mathcal M$  indicates that all Gershgorin disks are tangent to the imaginary axis at (0,0). As 0 is an eigenvalue of  $\mathcal M$ , it follows that  $s(\mathcal M)=0$ 

4. This is a direct consequence of using the Perron-Frobenius Theorem on the essentially nonnegative matrix  ${\cal M}$ 

2. From the Gershgorin Disk Theorem [Varga, 2010], all eigenvalues of  $-\mathcal{M}$  belong to disks that lie to the right of the imaginary axis and, from the zero column sums, are tangent to that axis at (0,0)

Now consider  $-\mathcal{M}+\varepsilon\mathbb{I}$ , for  $\varepsilon>0$ . This shifts the centers of all Gershgorin disks to the right by  $\varepsilon$  [Horn and Johnson, 2013, Problem 1.2.P8] but does not change their radii, so all disks now lie strictly to the right of the imaginary axis

Thus all eigenvalues of  $-\mathcal{M} + \varepsilon \mathbb{I}$  have positive real parts

Furthermore,  $-\mathcal{M}$  and  $-\mathcal{M}+\varepsilon\mathbb{I}$  are of class  $Z_n$ : they have nonpositive offdiagonal entries. [Fiedler, 2008, Theorem 5.1.1(18)]  $\Longrightarrow -\mathcal{M}+\varepsilon\mathbb{I}$  is of class K, i.e., an M-matrix. Since this is true for all  $\varepsilon>0$ , [Fiedler, 2008, Theorem 5.2.1(1)] implies that  $-\mathcal{M}$  is of class  $K_0$ . So  $-\mathcal{M}$  is an M-matrix and it is singular

p. 15 - The movement matrix

### Properties of the movement matrix $\mathcal{M}$ (cont'd)

#### Proposition 7.3 (D a diagonal matrix)

- 1.  $s(\mathcal{M} + d\mathbb{I}) = d, \forall d \in \mathbb{R}$
- 2.  $s(\mathcal{M} + D) \in \sigma(\mathcal{M} + D)$  associated to  $\mathbf{v} > \mathbf{0}$ . If  $\mathcal{M}$  irreducible,  $s(\mathcal{M} + D)$  has multiplicity 1 and is associated to  $\mathbf{v} \gg \mathbf{0}$
- 3. diag $(D)\gg \mathbf{0} \implies D-\mathcal{M}$  invertible M-matrix and  $(D-\mathcal{M})^{-1}>\mathbf{0}$
- 4.  $\mathcal{M}$  irreducible and  $\operatorname{diag}(D) > \mathbf{0} \Longrightarrow D \mathcal{M}$  nonsingular irreducible M-matrix and  $(D \mathcal{M})^{-1} \gg \mathbf{0}$

#### Proof of Proposition 7.3

1. From Lemma 7.2(3),  $s(\mathcal{M}) = 0$ . Therefore, using a "spectrum shift" [Horn and Johnson, 2013, Problem 1.2.P8],  $s(\mathcal{M} + d\mathbb{I}) = d$ 

2. These are direct consequences of applying the Perron-Frobenius Theorem to the essentially nonnegative matrix  $\mathcal{M} + D$ 

### Proof of Proposition 7.3 (cont'd)

3. Define  $\underline{d} = \min_{i=1,...,N} d_{ii}$ . Then

$$diag(D) \gg \mathbf{0} \implies \underline{d} > 0 \implies -\mathcal{M} \le d\mathbb{I} - \mathcal{M} \le D - \mathcal{M}$$

From [Fiedler, 2008, Theorem 5.2.5],  $d\mathbb{I}-\mathcal{M}$  is an M-matrix. Since  $s(\mathcal{M})=0$ , using a "spectrum shift", all eigenvalues of  $d\mathbb{I}-\mathcal{M}$  have real parts larger than  $\underline{d}$ , so  $\underline{d}\mathbb{I}-\mathcal{M}$  is a nonsingular M-matrix. In turn, [Fiedler, 2008, Theorem 5.1.1(4)]  $\Longrightarrow D-\mathcal{M}$  nonsingular M-matrix and [Fiedler, 2008, Theorem 5.1.1(11)] leads to the conclusion

4. Suppose  $\mathcal{M}$  irreducible. Let  $\overline{d} = \max_{i=1,\dots,N} d_{ii} > 0$ . Then  $D - \mathcal{M}$  is irreducible and diagonally dominant with all columns  $k = 1,\dots,N$  such that  $d_{kk} = \overline{d}$  satisfying the strict diagonal dominance requirement. (Other columns with nonzero entries in D also satisfy the requirement.) As a consequence, [Varga, 2010, Theorem 1.11] implies that  $D - \mathcal{M}$  nonsingular and inverse positivity follows from [Fiedler, 2008, Theorem 5.2.10]

p. 18 - The movement matrix

### $-\mathcal{M}$ is also the Laplacian matrix of a digraph

Note that  $-\mathcal{M}$  is also the Laplacian matrix of a directed graph

As such, finer estimates of the location of eigenvalues are available; see, e.g., [Agaev and Chebotarev, 2005]

However, the main concern here is with the spectral abscissa, so this is not needed

Position of the problem

A metapopulation of sources and sinks with explicit movement

The movement matrix

Local analysis of the model

Global behaviour

An interesting special case

### The population-free equilibrium (PFE)

We find the PFE  $P_s = P_t = 0$ 

At the PFE,

$$J_{\text{PFE}}^{S} = \mathcal{M} + (\mathcal{D}_{s} \oplus -\mathcal{D}_{t})$$
(3)

where  $\mathcal{D}_s = \mathbf{G}_s(\mathbf{0}) = \operatorname{diag}(r_1, \dots, r_S)$ 

The matrix

$$\mathcal{D}_s \oplus -\mathcal{D}_t = \operatorname{diag}(r_1, \ldots, r_S, -r_{S+1}, \ldots, -r_N)$$

has S diagonal entries > 0 and N - S diagonal entries < 0

#### Mechanism of the existence proof

Start with 
$$S=0$$
 (only sinks)  $\implies \mathcal{D}_s$  vacuous and  $\mathcal{D}_s \oplus -\mathcal{D}_t = \operatorname{diag}(-r_1, \dots, -r_N)$   $\implies s(J_{PFE}^S) < 0$ 

Finish with 
$$S = N$$
 (only sources)  
 $\implies \mathcal{D}_t$  vacuous and  $\mathcal{D}_s \oplus -\mathcal{D}_t = \operatorname{diag}(r_1, \dots, r_N)$   
 $\implies s(J_{PFF}^S) > 0$ 

Eigenvalues of  $J_{\text{PFE}}^{S}$  depend continuously of entries of  $J_{\text{PFE}}^{S}$ , so  $s(J_{\text{PFE}}^{S})$  changes signs, we are done.. if we are happy with a lot of uncertainty about behaviour of  $s(J_{\text{PFE}}^{S})$ 

### Continuous perturbation of the spectrum

For 
$$S \in \{0, ..., N-1\}$$

$$J_{ ext{PFE}}^{S,arepsilon} = \mathcal{M} + ext{diag}(r_1, \dots, r_S, arepsilon, -r_{S+2}, \dots, -r_N)$$

where  $\varepsilon \in [-r_{S+1}, r_{S+1}]$  is in  $(S+1)^{\text{th}}$  position

For  $S \in [0, N]$ 

$$J_{\mathrm{PFE}}^{S} = J_{\mathrm{PFE}}^{\xi,\varepsilon}, \quad \text{with} \quad \xi = \lfloor S \rfloor, \quad \varepsilon = 2(S - \lfloor S \rfloor)r_i - r_i$$
 (4)

where i = |S| + 1 if S < N and i = N when S = N

Generally we vary  $\zeta$  continuously in each  $[-r_{S+1}, r_{S+1}]$ 

$$J_{\mathrm{PFE}}^{S,-r_{S+1}} = J_{\mathrm{PFE}}^{S} \quad \text{and} \quad J_{\mathrm{PFE}}^{S,r_{S+1}} = J_{\mathrm{PFE}}^{S+1}$$

## The spectral abscissa $s(J_{\mathrm{PFE}}^{S})$ switches signs

#### Lemma 7.4

Let 
$$\underline{r} = \min_{i=1,...,N} \{r_i\}$$

Then 
$$s(J_{PFE}^0) \le -\underline{r} < 0$$
 and  $s(J_{PFE}^N) \ge \underline{r} > 0$ 

#### Proof of Lemma 7.4

If S = 0, then

$$J_{ ext{PFE}}^0 = \mathcal{M} + ext{diag}(-r_1, \dots, -r_N)$$

From Proposition 7.2(3),  $s(\mathcal{M}) = 0$ . Note that this follows from using the Gershgorin Theorem, where for  $\mathcal{M}$ , all Gershgorin disks are left of the imaginary axis and tangent to origin of the complex plane

Then the centres of the Gershorin disks of  $\mathcal{M} + \text{diag}(-r_1, \dots, -r_N)$  are shifted left by  $r_1, \dots, r_N$  while the radii remain the same

As a consequence, the closest disk(s) to the origin of the complex plane have centre(s)  $-\underline{r}$  and thus  $s(\mathcal{M} + \text{diag}(-r_1, \dots, -r_N)) \leq -\underline{r} < 0$ 

If S = N, then

$$\textit{J}_{\text{PFE}}^{\textit{N}} = \mathcal{M} + \mathsf{diag}(\textit{r}_1, \ldots, \textit{r}_{\textit{N}})$$

For i = 1, ..., N, define  $e_i = r_i - \underline{r} \ge 0$ , then

$$\mathit{J}_{\mathrm{PFE}}^{\textit{N}} = \mathcal{M} + \underline{\textit{r}}\mathbb{I} + \mathsf{diag}(\emph{e}_1,\ldots,\emph{e}_{\textit{N}})$$

where, by Proposition 7.3(1),  $s(\mathcal{M} + \underline{r}\mathbb{I}) = \underline{r} > 0$ 

First, assume  $\mathcal{M}$  irreducible

Then  $J_{\text{PFE}}^{N}$  is an irreducible essentially nonnegative matrix

Since 
$$J_{\mathrm{PFE}}^{\mathcal{N}} \geq \mathcal{M} + \underline{r}\mathbb{I}$$
, [Smith, 1995, Corollary 4.3.2(3)]  $\Longrightarrow$ 

$$s(J_{\mathrm{PFE}}^{N}) \geq s(\mathcal{M} + \underline{r}\mathbb{I}) = \underline{r}$$

with the inequalities being strict if there exists at least one  $e_i > 0$ 

Now assume that  $\mathcal{M}$  reducible

Then  $\exists$  permutation matrix P such that  $P^T \mathcal{M} P$  is block upper triangular with irreducible blocks on the diagonal

Call C the number of such blocks, i.e., the number of strong components in the digraph of patches

For i = 1, ..., C, denote n(i) the number of patches in strong component i and k(1), ..., k(n(i)) their indices

By abuse of notation, denote  $\mathcal{M}_{ii}$  the corresponding diagonal block in the reduced form of  $\mathcal{M}$ 

Applying the permutation matrix P to  $J_{\mathrm{PFE}}^{N}$  gives a block upper triangular matrix

$$P^T J_{\mathrm{PFE}}^N P$$

with, for i = 1, ..., C, the  $n(i) \times n(i)$  diagonal blocks  $\mathcal{M}_{ii} + E_i$  being irreducible and with

$$E_i = \underline{r}\mathbb{I} + \mathsf{diag}\left(e_{k(1)}, \dots, e_{k(n(i))}\right)$$

Fix  $i=1,\ldots,C$  and let  ${\bf v}$  be a positive right eigenvector of  $\mathcal{M}_{ii}+E_i$  corresponding to the spectral abscissa  $s_1$  and  ${\bf w}$  be a positive left eigenvector of  $\mathcal{M}_{ii}+\underline{r}\mathbb{I}$  corresponding to the spectral abscissa  $s_2$ . Then

$$s_{1}\mathbf{w}^{T}\mathbf{v} = \mathbf{w}^{T} \left( \mathcal{M}_{ii} + \underline{r}\mathbb{I} + \operatorname{diag}(e_{k(1)}, \dots, e_{k(n(i))}) \right) \mathbf{v}$$

$$= \mathbf{w}^{T} \left( \mathcal{M}_{ii} + \underline{r}\mathbb{I} \right) \mathbf{v} + \mathbf{w}^{T} \operatorname{diag}(e_{k(1)}, \dots, e_{k(n(i))}) \mathbf{v}$$

$$= s_{2}\mathbf{w}^{T}\mathbf{v} + \mathbf{w}^{T} \operatorname{diag}(e_{k(1)}, \dots, e_{k(n(i))}) \mathbf{v}$$

$$\geq s_{2}\mathbf{w}^{T}\mathbf{v}$$

the inequality being strict if at least one of the  $e_{k(j)}$ ,  $j=1,\ldots,n(i)$ , is positive. Hence  $s_1 \geq s_2$ , i.e.,  $s(\mathcal{M}_{ii}+E_i) \geq s(\mathcal{M}_{ii}+\underline{r}\mathbb{I})$ . This is true for all diagonal blocks. Now, since  $P^TJ_{\mathrm{PFE}}^NP$  is block upper triangular,

$$s(J_{\mathrm{PFE}}^{N}) = s(P^{T}J_{\mathrm{PFE}}^{N}P) = \max\{s(\mathcal{M}_{11} + E_{1}), \dots, s(\mathcal{M}_{CC} + E_{C})\}$$

As  $P^T(\mathcal{M} + \underline{r}\mathbb{I})P$  is also block upper triangular,

$$\underline{r} = s(\mathcal{M} + \underline{r}\mathbb{I}) = \max\{s(\mathcal{M}_{11} + \underline{r}\mathbb{I}), \dots, s(\mathcal{M}_{11} + \underline{r}\mathbb{I})\}$$

As a consequence,  $s(J_{\text{PFE}}^N) \geq \underline{r} > 0$ 

Thus,  $S^c$  necessarily lies in the open interval (0, N). The following lemma is of interest and the method of proof of the second assertion is used again later

#### Lemma 7.5

1. For all  $S \in (0, N) \subset \mathbb{R}$ ,

$$J_{PFE}^0 < J_{PFE}^S < J_{PFE}^N \tag{5}$$

2.  $J_{PFE}^{S}$  is an increasing function of S, in the sense that

$$\forall S_1, S_2 \in [0, N] \subset \mathbb{R} \text{ such that } S_1 < S_2, \quad J_{PFE}^{S_1} < J_{PFE}^{S_2}$$
 (6)

### Proof of Lemma 7.5

1. Let  $S \in (0, N)$  be fixed. Using (4), this gives a pair  $(\xi, \varepsilon) \in \{0, \dots, N\} \times [-r_i, r_i]$ , for  $i = 1 \dots N$ , such that  $J_{\text{PFE}}^S = J_{\text{PFE}}^{\xi, \varepsilon}$ . We have

$$J_{\mathrm{PFE}}^{\xi,\varepsilon} - J_{\mathrm{PFE}}^{0} = \mathcal{M} + \mathrm{diag}(r_{1},\ldots,r_{\xi},arepsilon,-r_{\xi+2},\ldots,-r_{N}) \ - \mathcal{M} - \mathrm{diag}(-r_{1},\ldots,-r_{N}) \ = \mathrm{diag}(2r_{1},\ldots,2r_{\xi},arepsilon+r_{\xi+1},0,\ldots,0) \ > \mathbf{0}$$

since  $\varepsilon \in [-r_{\xi+1}, r_{\xi+1}]$ 

Computing  $J_{\mathrm{PFE}}^{N}-J_{\mathrm{PFE}}^{\xi,\varepsilon}$  at the other endpoint works similarly, giving (5)

p. 32 - Local analysis of the model

### Proof of Lemma 7.5 (cont'd)

2. Use (4) again to obtain two pairs  $(\xi_1, \varepsilon_1)$  and  $(\xi_2, \varepsilon_2)$ , where, by the assumption  $S_1 < S_2$ ,  $\xi_1 \le \xi_2$ . First, assume that  $\xi_1 < \xi_2$ . Then

$$\begin{split} J_{\mathrm{PFE}}^{\xi_{2},\varepsilon_{2}} - J_{\mathrm{PFE}}^{\xi_{1},\varepsilon_{1}} &= \mathsf{diag}(r_{1},\ldots,r_{\xi_{2}},\varepsilon_{2},-r_{\xi_{2}+2},\ldots,-r_{N}) \\ &- \mathsf{diag}(r_{1},\ldots,r_{\xi_{1}},\varepsilon_{1},-r_{\xi_{1}+2},\ldots,-r_{N}) \\ &= \mathsf{diag}(0,\ldots,0,r_{\xi_{1}+1}-\varepsilon_{1},2r_{\xi_{1}+2},\ldots,2r_{\xi_{2}},\varepsilon_{2}+r_{\xi_{2}+1},0,\ldots,0) \\ &> \mathbf{0} \end{split}$$

since  $\varepsilon_1 \in [-r_{\xi_1+1}, r_{\xi_1+1}]$ , and  $\varepsilon_2 \in [-r_{\xi_2+1}, r_{\xi_2+1}]$ . Now assume  $\xi_1 = \xi_2$ . Then, since  $S_1 < S_2$ , we find that  $\varepsilon_1 < \varepsilon_2$  and the diagonal matrix in the subtraction  $J_{\mathrm{PFE}}^{\xi_2, \varepsilon_2} - J_{\mathrm{PFE}}^{\xi_2, \varepsilon_1}$  takes the form  $\mathrm{diag}(0, \dots, 0, \varepsilon_2 - \varepsilon_1, 0, \dots, 0) > \mathbf{0}$ . So (6) holds

p. 33 - Local analysis of the model

### Proposition 7.6

 $\mathcal{M}$  reducible  $\implies s(J_{PFE}^S)$  nondecreasing for  $S \in [0, N]$ 

 $\mathcal{M}$  irreducible  $\implies s(J_{PFE}^{S})$  increasing for  $S \in [0, N]$ 

 $\implies \exists S_{int} \subset (0, N) \text{ (resp. } S^c \in (0, N)) \text{ s.t. PFE LAS if } S < \min(S_{int}) \text{ (resp. } S < S^c)$  and PFE unstable if  $S > \max(S_{int})$  (resp.  $S > S^c$ )

. 34 - Local analysis of the model

### Proof of Proposition 7.6

First, assume  $\mathcal{M}$  is irreducible. Then, by Lemma 7.5 and the fact that  $\mathcal{M}$  is irreducible (and thus so is  $J_{\mathrm{PFE}}^{\mathcal{S}}$ ), [Smith, 1995, Corollary 4.3.2(3)] gives the result

Now, assume that  $\mathcal{M}$  is reducible.  $\Longrightarrow \exists$  permutation matrix P such that  $P^T \mathcal{M} P$  block upper triangular. Consider  $S \in [0, N] \subset \mathbb{R}$  and use (4) to obtain a corresponding pair  $(\xi, \varepsilon) \in \{0, \dots, N\} \times [-r_{\xi}, r_{\xi}]$ . Apply the same permutation to  $J_{\mathrm{PFE}}^{\xi, \varepsilon}$ , giving

$$P^T J_{\mathrm{PFE}}^{\xi,\varepsilon} P = egin{pmatrix} \mathcal{M}_{11} + \mathcal{E}_1 & \mathcal{M}_{12} & \cdots & \mathcal{M}_{1N} \\ 0 & \mathcal{M}_{22} + \mathcal{E}_2 & & & \\ & & \ddots & & \\ 0 & \cdots & 0 & \mathcal{M}_{CC} + \mathcal{E}_C \end{pmatrix}$$

where C is the number of strong components in the digraph of patches and

$$E_1 \oplus \cdots \oplus E_C = P^T \operatorname{diag}(r_1, \ldots, r_{\varepsilon}, \varepsilon, -r_{\varepsilon+2}, \ldots, -r_N)P$$

with matrix on right hand side having  $\varepsilon$  as  $(\xi + 1)^{\text{th}}$  diagonal entry. As in the proof of Lemma 7.4, we have denoted  $\mathcal{M}_{ii}$  the diagonal blocks in the reduced form of  $\mathcal{M}$ 

. 36 - Local analysis of the model

For  $j=1,\ldots,C$ , each of the matrices  $\mathcal{M}_{jj}$  is irreducible; C-1 of the matrices  $E_j$  are diagonal with entries  $-r_i$  and  $r_i$  on the diagonal (with some having only  $-r_i$ , some having only  $r_i$  and some having both types of entries)

The remaining  $E_j$  matrix is diagonal, with potentially  $-r_i$  and  $r_i$  as the others, but also  $\varepsilon$ . Call  $\eta \in \{1, \ldots, C\}$  the index of the strong component containing the matrix with  $\varepsilon$ 

As a consequence, for all  $j=1,\ldots,C$ ,  $\mathcal{M}_{jj}+E_j$  are irreducible essentially nonnegative matrices, with only matrix  $\mathcal{M}_{\eta\eta}+E_\eta$  having an  $\varepsilon$  added to one of its diagonal entries

As  $P^T J_{\mathrm{PFE}}^{\xi,\varepsilon} P$  is block upper triangular, we have

$$s(P^T J_{\mathrm{PFE}}^{\xi,\varepsilon} P) = \max \{ s(\mathcal{M}_{11} + E_1), \dots, s(\mathcal{M}_{CC} + E_C) \}$$

Except for  $\mathcal{M}_{\eta\eta}+E_{\eta}$ , all matrices  $\mathcal{M}_{ii}+E_{i}$  have fixed spectral abscissa. Concerning matrix  $\mathcal{M}_{\eta\eta}+E_{\eta}$ , it is clear that the reasoning in the proof of Lemma 7.5(2) carries through and thus,

$$\forall \varepsilon_1, \varepsilon_2 \in [-r_{\xi+1}, r_{\xi+1}], \ \varepsilon_1 < \varepsilon_2 \implies J_{\mathrm{PFE}}^{\xi, \varepsilon_1} < J_{\mathrm{PFE}}^{\xi, \varepsilon_2}$$

Hence  $s(J_{\mathrm{PFE}}^{\xi,\varepsilon})$  is the maximum of a set of C functions, C-1 of which are constant in  $\varepsilon$  and one of which is increasing in  $\varepsilon$ . It now follows that  $s(J_{\mathrm{PFE}}^{\mathcal{S}})$  is a nondecreasing function of S, as desired

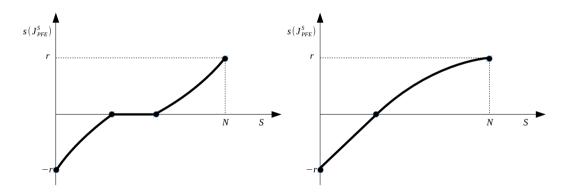
### We now can do Part 1 of Theorem 7.9

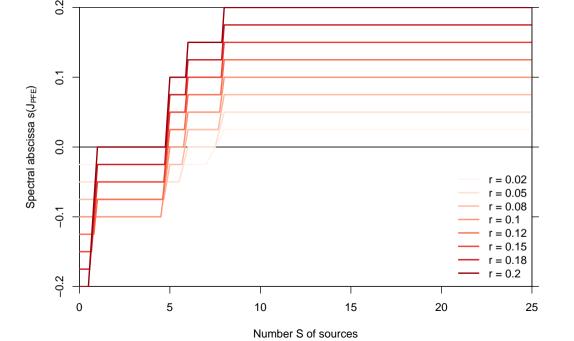
As  $J_{\mathrm{PFE}}^{\mathcal{S}}$  is essentially nonnegative, its spectral abscissa  $s(J_{\mathrm{PFE}}^{\mathcal{S}})$  is an eigenvalue. Eigenvalues of  $J_{\mathrm{PFE}}^{\mathcal{S}}$  depend continuously on S [Horn and Johnson, 2013, Theorem 2.4.9.2]. By Lemma 7.4,  $s(J_{\mathrm{PFE}}^{0}) < 0$  and  $s(J_{\mathrm{PFE}}^{\mathcal{N}}) > 0$ , so by the Intermediate Value Theorem, there exists at least one point  $S^c \in (0, N)$  such that  $s(J_{\mathrm{PFE}}^{S^c}) = 0$ 

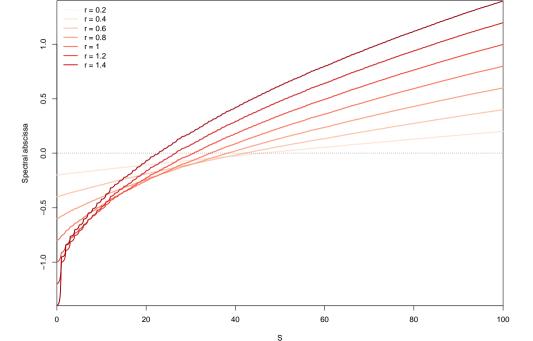
In the case where  $\mathcal{M}$  is irreducible,  $s(J_{\mathrm{PFE}}^S)$  is increasing by Proposition 7.6 and as a consequence,  $S^c$  is unique. In the case where  $\mathcal{M}$  is reducible,  $s(J_{\mathrm{PFE}}^S)$  is nondecreasing, therefore there exists an interval  $\mathcal{S}_{int}$ , possibly reduced to a single point, such that  $s(J_{\mathrm{PFE}}^S) = 0$  for all  $S \in \mathcal{S}_{int}$ 

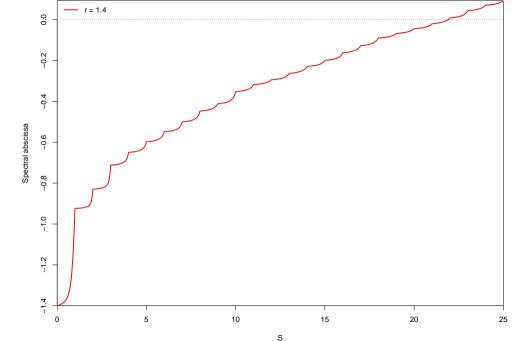
The usual criteria for local asymptotic stability and instability of equilibria then imply the first part of Theorem 7.9 for  $S < S^c$  and  $S > S^c$  (irreducible case) or  $S < \min(S_{int})$  and  $S > \max(S_{int})$  (reducible case)

- ▶  $\mathcal{M}$  reducible:  $\exists \mathcal{S}_{int} \subset (0, N)$  s.t. PFE LAS if  $S < \min(\mathcal{S}_{int})$  and PFE unstable if  $S > \max(\mathcal{S}_{int})$
- lacktriangledown irreducible:  $\exists S^c \in (0, N)$  s.t. PFE LAS if  $S < S^c$  and PFE unstable if  $S > S^c$









As indicated by [Deutsch and Neumann, 1985], perturbation of the diagonal leads to convex changes in the spectral abscissa on each sub-interval

### We have a reproduction number when ${\mathcal M}$ irreducible

### Proposition 7.7

Suppose  ${\mathcal M}$  irreducible. Define the basic reproduction number

$$\mathcal{R}_0 = \rho \left( \left( \mathcal{M}_s + \mathcal{M}_{st} (\mathcal{D}_t - \mathcal{M}_t)^{-1} \mathcal{M}_{ts} \right)^{-1} \mathcal{D}_s \right) \tag{7}$$

where  $\mathcal{M}_s$ ,  $\mathcal{M}_t$ ,  $\mathcal{M}_{st}$ ,  $\mathcal{M}_{ts}$  are defined as in (2),  $\mathcal{D}_s = \text{diag}(r_1, \dots, r_S)$  and  $\mathcal{D}_t = \text{diag}(r_{S+1}, \dots, r_N)$ . Then

$$s(J_{PFE}^{S}) < 0 \iff \mathcal{R}_0 < 1 \text{ and } s(J_{PFE}^{S}) > 0 \iff \mathcal{R}_0 > 1$$
 (8)

45 – Local analysis of the model

### Proof of Proposition 7.7

Write (3) as

$$J_{ ext{PFE}}^{\mathcal{S}} = \mathcal{M} + ilde{\mathcal{D}}_s - ilde{\mathcal{D}}_t$$

where  $\tilde{\mathcal{D}}_s = \mathcal{D}_s \oplus \mathbf{0}_{N-S \times N-S}$  and  $\tilde{\mathcal{D}}_t = \mathbf{0}_{S \times S} \oplus \mathcal{D}_t$ . Let  $-\alpha$  be the spectral abscissa of  $\mathcal{M} + \tilde{\mathcal{D}}_s - \tilde{\mathcal{D}}_t$ . From Proposition 7.3(2), there is a vector  $\mathbf{v} \gg \mathbf{0}$  such that

$$(\mathcal{M} + \tilde{\mathcal{D}}_s - \tilde{\mathcal{D}}_t)\mathbf{v} = -\alpha\mathbf{v}$$

In other words,

$$lpha \mathbf{v} = ( ilde{\mathcal{D}}_t - \mathcal{M})\mathbf{v} - ilde{\mathcal{D}}_s \mathbf{v}$$

p. 46 – Local analysis of the model

By the assumption of irreducibility of  $\mathcal{M}$ , it follows from Proposition 7.3(4) that  $\tilde{\mathcal{D}}_t - \mathcal{M}$  is an irreducible nonsingular M-matrix and  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \gg \mathbf{0}$ 

Then

$$lpha \left( \tilde{\mathcal{D}}_t - \mathcal{M} \right)^{-1} \mathbf{v} = \mathbf{v} - \left( \tilde{\mathcal{D}}_t - \mathcal{M} \right)^{-1} \tilde{\mathcal{D}}_s \mathbf{v}$$

with the matrix  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1} \tilde{\mathcal{D}}_s > \mathbf{0}$ 

As a consequence, from the Perron-Frobenius Theorem, the spectral radius of  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1}\tilde{\mathcal{D}}_s$  is an eigenvalue and is associated to a nonnegative eigenvector

Let **u** be such an eigenvector, normalised so that  $\mathbf{u}^T \mathbf{v} = 1$ . Then

$$lpha \mathbf{u}^{\mathsf{T}} \left( \tilde{\mathcal{D}}_t - \mathcal{M} \right)^{-1} \mathbf{v} = \mathbf{u}^{\mathsf{T}} \mathbf{v} \left( 1 - \rho \left\{ \left( \tilde{\mathcal{D}}_t - \mathcal{M} \right)^{-1} \tilde{\mathcal{D}}_s \right\} \right)$$

Thus

$$\alpha > 0 \iff \rho \left\{ \left( \tilde{\mathcal{D}}_t - \mathcal{M} \right)^{-1} \tilde{\mathcal{D}}_s \right\} < 1$$

and

$$lpha < 0 \iff 
ho \left\{ \left( ilde{\mathcal{D}}_t - \mathcal{M} \right)^{-1} ilde{\mathcal{D}}_s 
ight\} > 1$$

From the structure of  $\tilde{\mathcal{D}}_s$ , the spectral radius of  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1}\tilde{\mathcal{D}}_s$  is the spectral radius of

$$ig( ilde{\mathcal{D}}_t - \mathcal{M}ig)_{ extstyle extstyle 11 extstyle e$$

where  $(\tilde{\mathcal{D}}_t - \mathcal{M})_{\text{fill}}^{-1}$  is the (1,1) block in  $(\tilde{\mathcal{D}}_t - \mathcal{M})^{-1}$ 

Writing  $\mathcal{M}$  as (2), we have by the formula for the inverse of a 2  $\times$  2 block matrix that

$$\left( ilde{\mathcal{D}}_t - \mathcal{M} 
ight)_{ ext{f11}}^{-1} = \left( -\mathcal{M}_s - \mathcal{M}_{st} (\mathcal{D}_t - \mathcal{M}_t)^{-1} \mathcal{M}_{ts} 
ight)^{-1}$$

Clearly,

$$\rho\left(\left(-\mathcal{M}_{s}-\mathcal{M}_{st}(\mathcal{D}_{t}-\mathcal{M}_{t})^{-1}\mathcal{M}_{ts}\right)^{-1}\mathcal{D}_{s}\right)$$

$$=\rho\left(\left(\mathcal{M}_{s}+\mathcal{M}_{st}(\mathcal{D}_{t}-\mathcal{M}_{t})^{-1}\mathcal{M}_{ts}\right)^{-1}\mathcal{D}_{s}\right)$$

giving the result

Position of the problem

A metapopulation of sources and sinks with explicit movement

The movement matrix

Local analysis of the mode

Global behaviour

An interesting special case

So..

we are done!

.. Are we? The result is only local, can we go further?

p. 51 - Global behaviour

# System (1) is cooperative

Jacobian of (1):

$$J(\mathbf{P}_{s}, \mathbf{P}_{t}) = \begin{pmatrix} \mathbf{G}_{s}'(\mathbf{P}_{s})\mathbf{P}_{s} + \mathbf{G}_{s}(\mathbf{P}_{s}) + \mathcal{M}_{s} & \mathcal{M}_{st} \\ \mathcal{M}_{ts} & -\mathcal{D}_{t} + \mathcal{M}_{t} \end{pmatrix}$$
(9)

where

$$\mathbf{G}_s'(\mathbf{P}_s) = \operatorname{diag}\left(-rac{r_1}{\mathcal{K}_1}, \ldots, -rac{r_S}{\mathcal{K}_s}
ight)$$

Thus

$$J(\mathsf{P}_s,\mathsf{P}_t) = \mathcal{M} + ig( (\mathsf{G}_s'(\mathsf{P}_s)\mathsf{P}_s + \mathsf{G}_s(\mathsf{P}_s)) \oplus -\mathcal{D}_t ig)$$

with  $\mathbf{G}_s'(\mathbf{P}_s)\mathbf{P}_s + \mathbf{G}_s(\mathbf{P}_s)$  and  $-\mathcal{D}_t$  diagonal

 $\implies$  system (1) is cooperative

### A theorem of Hirsch

So, to move forward, we would like to apply the following result

### Theorem 7.8 (Th. 6.1 in Hirsch (1984) - BAMS 11(1))

Let  $\mathbf{F}$  be a  $C^1$  vector field in  $\mathbb{R}^n$  with flow  $\phi$  preserving  $\mathbb{R}^n_+$  for t>0 and strongly monotone in  $\mathbb{R}^n_+$ . Suppose that the origin is an equilibrium and all trajectories in  $\mathbb{R}^n_+$  are bounded. Suppose the matrix-valued map  $D\mathbf{F}: \mathbb{R}^n_+ \to \mathbb{R}^{n \times n}$  is strictly antimonotone, i.e.,

$$x > y \implies DF(x) < DF(y)$$

Then either all trajectories in  $\mathbb{R}^n_+$  go to the origin, or there exists a unique equilibrium  $\mathbf{P}^* \in \operatorname{Int}\mathbb{R}^n_+$  and all trajectories in  $\mathbb{R}^n_+ \setminus \{\mathbf{0}\}$  limit to  $\mathbf{P}^*$ 

### OK, nice, but...

Take

$$P_1 = (0, ..., 0, \star, ..., \star) \text{ and } P_2 = (0, ..., 0, \star, ..., \star)$$

have their first S entries zero, i.e.,  $\mathbf{P}_1 = (\mathbf{0}_s, \mathbf{P}_t^1)$  and  $\mathbf{P}_2 = (\mathbf{0}_s, \mathbf{P}_t^2)$ ; assume  $\mathbf{P}_1 > \mathbf{P}_2$ , i.e.,  $\mathbf{P}_t^1 > \mathbf{P}_t^2$ 

Then

$$egin{aligned} J(\mathbf{0}_s, \mathbf{P}_t^1) &= \mathcal{M} + ig( (\mathbf{G}_s'(\mathbf{0}_s) \mathbf{0}_s + \mathbf{G}_s(\mathbf{0}_s)) \oplus -\mathcal{D}_t ig) \ &= \mathcal{M} + ig( \mathcal{D}_s \oplus -\mathcal{D}_t ig) \ &= J(\mathbf{0}_s, \mathbf{P}_t^2) \end{aligned}$$

i.e.,

$$J_{\mathbf{P}_1}^S = J_{\mathbf{P}_2}^S$$

 $\implies$  (1) is not strictly antimonotone

### (non) lasciate ogne sperenza, voi ch'intrate

Except for strict antimonotonicity of  $\mathbf{F}$ , all hypotheses of [Hirsch (1984) – Th. 6.1] are satisfied:

- ▶ in the case  $\mathcal{M}$  irreducible, (1) is strongly monotone (by [Hirsch (1984) Th. 1.7])
- the origin is an equilibrium
- $\triangleright$  all solutions of (1) are bounded in  $\mathbb{R}^N_+$  (not shown here, but not hard)

 $\implies$  by other results (e.g., Hirsch *ibid*), there exists  $\mathbf{P}^* \gg \mathbf{0}$ 

What is the use of strict antimonotonicity in the proof of [Hirsch (1984) – Th. 6.1]? .. To show uniqueness of  $\mathbf{P}^*$ 

More precisely: let  $z \in (0, P^*)$ , where  $P^* \gg 0$  is a nontrivial equilibrium

Strict antimonotonicity  $\implies$   $\mathbf{F}(\mathbf{z}) > \mathbf{0}$ , and we can then proceed with the remainder of the proof of [Hirsch (1984) – Th. 6.1]

Let us show that we indeed have  $\mathbf{F}(\mathbf{z})>\mathbf{0}$  for (1), despite the lack of strict antimonotonicity

As in [Hirsch (1984) – Th. 6.1]: for i = 1, ..., N, let

$$g_i:[0,1]\to\mathbb{R}$$
  $s\mapsto F_i(s\mathbf{P}^*)$ 

Then  $g_i(0) = g_i(1) = 0$  for i = 1, ..., N and, for i = S + 1, ..., N (sinks),

$$g_i(s) = -r_i s P_i^* + \sum_{i=1}^N m_{ij} s P_j^* = \left(r_i P_i^* + \sum_{i=1}^N m_{ij} P_j^*\right) s = 0$$

However, for i = 1, ..., S (sources).

$$g_i(s) = r_i \left(1 - rac{sP_i^*}{K_i}
ight) sP_i^* + \sum^N m_{ij} sP_j^*$$

Ha!

 $g_i''(s) = -\frac{2r_iP_i^{*2}}{K} < 0, \quad i = 1, \dots, S$ 

$$\implies$$
 for  $i = 1, ..., S$ ,  $g_i(s) > 0$  when  $s \in (0, 1)$   
 $\implies$  when  $S > 0$ ,  $\mathbf{F}(\mathbf{z}) > \mathbf{0}$ ,  $\forall \mathbf{z} \in (\mathbf{0}, \mathbf{P}^*)$ 

And we can then carry on with the remainder of the proof of [Hirsch (1984) - Th. 6.1]

To finish, the case S = 0 is easy:

$$\left(\sum_{i=1}^N P_i\right)' = -\sum_{i=1}^N r_i P_i < 0$$

since at least one of the  $P_i(0) > 0$ 

$$\implies \left(\sum_{i=1}^N P_i\right) \to 0 \implies \lim_{t \to \infty} P_i(t) = 0 \text{ for } i = 1, \dots, N$$

Et hop! □

## To conclude (mathematically)

#### Theorem 7.9

There exists a critical interval  $S_{int} \subset (0, N) \subset \mathbb{R}$  s.t.

- $ightharpoonup S < \min(S_{int}) \implies PFE \ LAS$
- $ightharpoonup S > \max(S_{int}) \implies PFE instable$

Additionally, if the patch digraph is strongly connected, then

- $\triangleright$   $S_{int}$  is reduced to a point  $S^c$
- $ightharpoonup S < S^c \implies PFE GAS$
- ►  $S > S^c \implies \exists ! \mathbf{P}^* \gg \mathbf{0} \text{ GAS for } \mathbb{R}_+^N \setminus \{\mathbf{0}\}$

Position of the problem

A metapopulation of sources and sinks with explicit movement

The movement matrix

Local analysis of the mode

Global behaviour

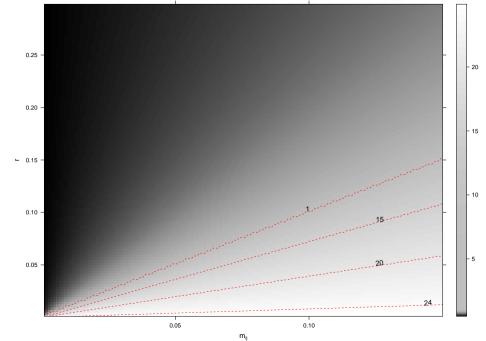
An interesting special case

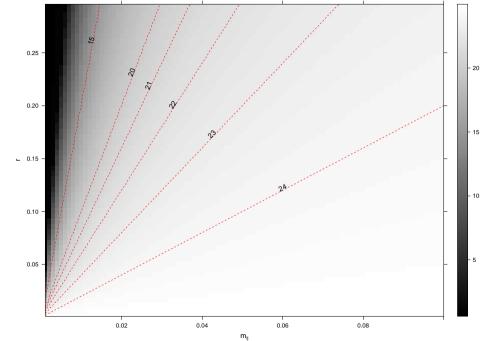
In the 2 figures that follow:

- N = 50
- $ightharpoonup r = r_i, \forall i = 1, \dots, N$
- ▶  $m_{ij} = m, \forall i, j = 1, ..., N \text{ s.t. } m_{ij} > 0$
- ightharpoonup plot is value of  $S^c$  as a function of m and r

Figure 1: ring of patches

Figure 2: complete digraph





## Case of complete homogeneous movement

#### Proposition 7.10

Suppose that the movement digraph is complete and that  $m_{ij} = m$  for i, j = 1, ..., N,  $i \neq j$ 

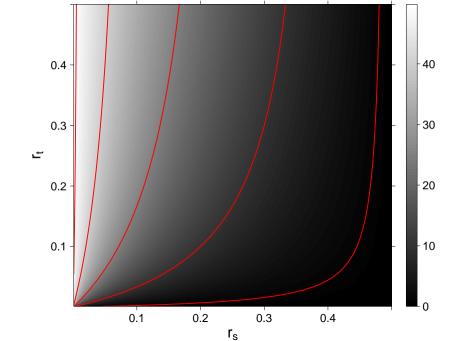
Suppose that 
$$S \in \{1, ..., N-1\}$$
, that for  $i = 1, ..., S$ ,  $r_i = r_s$  and that for  $i = S + 1, ..., N$ ,  $r_i = r_t$ 

Then

$$S^c = \frac{mNr_t - r_s r_t}{m(r_s + r_t)} \tag{10}$$

If 
$$r_s = r_t = r$$
, then

$$S^c = \frac{N}{2} - \frac{r}{2m} \tag{11}$$



### Proof of Prop 7.10 uses equitable partitions

Section 9.3 in Algebraic Graph Theory, Godsil & Royle (2013)

An **equitable partition**  $\pi$  splits a graph X into **cells**  $C_i$ ,  $i=1,\ldots,r$ , s.t. for a vertex u in cell  $C_i$ , the number of neighbours in cell  $C_j$  is a constant  $b_{ij}$  that does not depend on u

 $\iff$  the subgraph of X induced by each cell is regular [vertices have same degree] and edges joining two distinct cells form a semiregular bipartite graph [vertices have same degree in each bipartite component]

The digraph with the r cells of  $\pi$  as vertices and the  $b_{ij}$  arcs from the  $i^{\rm th}$  to the  $j^{\rm th}$  cell of  $\pi$  is the **quotient**  $X/\pi$  of X on  $\pi$ . The adjacency matrix of  $X/\pi$  is  $A(X/\pi) = [b_{ij}]$ 

### Characterising an equitable partition

### Lemma 7.11 (A friendly characterisation)

X graph, A(X) its adjacency matrix,  $\pi$  a partition of V(X) with characteristic matrix P. Then

 $\pi$  equitable  $\iff$  column space of P is A-invariant

Write

$$J_{\text{PFE}}^{S} = \begin{pmatrix} m \mathbb{J} - Nm \mathbb{I} + r_{s} \mathbb{I} & m \mathbb{J} \\ m \mathbb{J} & m \mathbb{J} - Nm \mathbb{I} - r_{r} \mathbb{I} \end{pmatrix}$$
(12)

with J matrix of all 1's

Consider (12) as the adjacency matrix of a digraph  ${\cal G}$ 

Suppose partition  $\pi$  splits  $\mathcal{G}$  in two cells,  $\{S_i\}_{i=1,...,S}$  (sources) and  $\{T_i\}_{i=S+1,...,N}$  (sinks)

The characteristic matrix of  $\pi$  is the  $N \times 2$ -matrix

$$C = \begin{pmatrix} \mathbb{1}_S & \mathbf{0}_S \\ \mathbf{0}_{N-S} & \mathbb{1}_{N-S} \end{pmatrix}$$

p. 67 - An interesting special case

We have

$$J_{\mathrm{PFE}}^{\mathcal{S}}\mathbb{1} = J_{\mathrm{PFE}}^{\mathcal{S}} \begin{pmatrix} \mathbb{1}_{\mathcal{S}} \\ \mathbb{1}_{\mathcal{N}-\mathcal{S}} \end{pmatrix} = \begin{pmatrix} r_{s}\mathbb{1}_{\mathcal{S}} \\ -r_{t}\mathbb{1}_{\mathcal{N}-\mathcal{S}} \end{pmatrix}$$

Thus the column space of C is  $J_{\text{PFE}}^{S}$ -invariant  $\implies \pi$  is equitable

### Properties of equitable partitions

#### Lemma 7.12

 $\pi$  equitable partition of graph X with characteristic matrix P, and  $B = A(X/\pi)$ . Then AP = PB and  $B = (P^TP)^{-1}P^TAP$ 

#### Theorem 7.13

 $\pi$  equitable partition of graph  $X \Longrightarrow$  characteristic polynomial of  $A(X/\pi)$  divides characteristic polynomial of A(X)

 $\implies$  the quotient matrix  $B_{\text{PFE}}^{S}$  satisfies

$$B_{\mathrm{PFE}}^{S} = (C^{T}C)^{-1}C^{T}J_{\mathrm{PFE}}^{S}C$$

$$\implies B_{\text{PFE}}^{S} = \begin{pmatrix} mS - mN + r_s & m(N - S) \\ mS & -(mS + r_s) \end{pmatrix}$$

And  $\sigma(B_{\text{DEE}}^S) \subset \sigma(J_{\text{DEE}}^S)$ 

 $B_{PFE}^{S}$  essentially nonnegative (and clearly irreducible)

$$\implies \exists ! \mathbf{v}_p \gg \mathbf{0} \text{ s.t. } B_{\mathrm{PFE}}^{S} \mathbf{v}_p = \lambda_p \mathbf{v}_p = s(B_{\mathrm{PFE}}^{S}) \mathbf{v}_p$$

Then  $J_{PFE}^{S}C = CB_{PFE}^{S}$ 

So

$$J_{\mathrm{PFE}}^{\mathcal{S}} C \mathbf{v}_{p} = C B_{\mathrm{PFE}}^{\mathcal{S}} \mathbf{v}_{p} = \lambda_{p} C \mathbf{v}_{p}$$

and  $C\mathbf{v}_p$  is an eigenvector of  $J_{\text{PFE}}^S$  that is also  $\gg \mathbf{0}$ 

As the only eigenvector  $\gg$  **0** of  $J_{\text{PFE}}^{\mathcal{S}}$  corresponds to  $s(J_{\text{PFE}}^{\mathcal{S}})$ , we have  $s(J_{\text{PFE}}^{\mathcal{S}}) = s(B_{\text{PFE}}^{\mathcal{S}})$ 

To compute  $S^c$ , recall  $S^c$  is value of S where PFE loses stability

Consider 
$$B_{\rm PFE}^S$$
. We have  ${\rm tr}(B_{\rm PFE}^S)=-mN+r_s-r_t$  and  ${\rm det}(B_{\rm PFE}^S)=-mS(r_s+r_t)-r_sr_t+mNr_t$ 

One shows easily that det(·) gouverns stability

$$\implies S^c = \frac{mNr_t - r_s r_t}{m(r_s + r_t)}$$

- Agaev, R. and Chebotarev, P. (2005).
  - On the spectra of nonsymmetric Laplacian matrices.
  - Linear Algebra and its Applications, 399:157–168.
  - Deutsch, E. and Neumann, M. (1985). On the first and second order derivatives of the Perron vector. Linear Algebra and its Applications, 71:57–76.
- Fiedler, M. (2008). Special Matrices and their Applications in Numerical Mathematics.
  - Dover, second edition. Horn, R. and Johnson, C. (2013).
    - Matrix Analysis. Cambridge University Press, 2nd edition.
- Smith, H. (1995). Monotone dynamical systems, volume 41 of Mathematical Surveys and Monographs.
- American Mathematical Society, Providence, RI. p. 73 - An interesting special case



Varga, R. (2010). Geršgorin and his Circles. Springer.