April 15, 2005

FINAL EXAMINATION

TITLE PAGE

DEPARTMENT & COURSE NO: 136.480

TIME: 2.5 HOURS

EXAMINATION: Dynamical Systems: Theory & Applications

EXAMINERS: A. Gumel

LAST NAME: (Print in ink) ______

FIRST NAME (Print in ink) _____

STUDENT NUMBER: _____

SIGNATURE (in ink): (I understand that cheating is a serious offense)

INSTRUCTIONS TO STUDENTS:

The duration of the exam is 2.5 hours.

Attempt ALL questions.

No texts, cell phones, notes or calculators are permitted

Justify your answers. Show all your work and provide explanations where necessary.

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	/50

DEPARTMENT & COURSE NO: 136.480 TIME: 2.5 HOURS EXAMINATION: Dynamical Systems: Theory & Applications EXAMINERS: A. Gumel

[6] 1. Find the fixed points of the following discrete maps:

(a)
$$U_{n+1} = 3U_n - U_n^3$$
;

(b)
$$U_{n+1} = \mu U_n (1 - U_n);$$

(c)
$$X_{n+1} = \frac{3}{4} - X_n^2 - Y_n^2$$
, $Y_{n+1} = X_n Y_n$.

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PAGE 2 of 7 TIME: 2.5 HOURS

DEPARTMENT & COURSE NO: 136.480 TIME: 2. EXAMINATION: Dynamical Systems: Theory & Applications EXAMINERS: A. Gumel

Consider the map $U_{n+1} = U_n + \alpha U_n (1 - U_n)$, where α is a parameter. Determine whether or not the map has a 2-cycle. If applicable, give the range of α for which a 2-cycle exists. [4] 2.

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PAGE 3 of 7 TIME: 2.5 HOURS

DEPARTMENT & COURSE NO: 136.480 TIME: 2. EXAMINATION: Dynamical Systems: Theory & Applications EXAMINERS: A. Gumel

Classify the type of bifurcation the following single parameter differential equation undergoes. Determine the value(s) of x and μ where such [5] bifurcation occur(s).

$$\dot{\bar{x}} = \mu + \frac{1}{2}x - \frac{x}{1+x}.$$

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FINAL EXAMINATION PAGE 4 of 7 TIME: 2.5 HOURS

DEPARTMENT & COURSE NO: 136.480 TIME: 2. EXAMINATION: Dynamical Systems: Theory & Applications EXAMINERS: A. Gumel

[10] 4. By considering the flow in the rectangle with corners $(\pm 1, \pm 2)$, prove that the following system has at least one limit cycle. Sketch a phase diagram for the flow across the rectangle.

$$\dot{x} = y - 8x^3,$$

$$\mathring{y} = 2y - 4x - 2y^3.$$

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FINAL EXAMINATION PAGE 5 of 7 TIME: 2.5 HOURS

DEPARTMENT & COURSE NO: 136.480 TIME: 2. EXAMINATION: Dynamical Systems: Theory & Applications EXAMINERS: A. Gumel

For the system below, use an appropriate Lyapunov function to prove that the origin is globally asymptotically stable [7] 5.

$$\dot{x} = -x - y^2 + x z - x^3$$
,

$$\dot{y} = -y + z^2 + x \ y - y^3,$$

$$\dot{z} = -z + x^2 + y z - z^3$$
.

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FINAL EXAMINATION PAGE 6 of 7 TIME: 2.5 HOURS

DEPARTMENT & COURSE NO: 136.480 TIME: 2. EXAMINATION: Dynamical Systems: Theory & Applications EXAMINERS: A. Gumel

[8] 6. Show that the system

$$\dot{x} = \mu x - y + x y^2$$

$$\dot{y} = x + \mu y + y^3$$

undergoes a Hopf bifurcation at the origin for some values of $\,\mu.\,$ Is the bifurcation degenerate, subcritical or supercritical? Hint: You many use deductive reasoning and elimination.

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DEPARTMENT & COURSE NO: 136.480

TIME: 2.5 HOURS

EXAMINATION: Dynamical Systems: Theory & Applications

EXAMINERS: A. Gumel

[10] 7. Consider the epidemic model

$$\frac{dS}{dt} = \Pi - \beta SI - \mu S,$$

$$\frac{dE}{dt} = \beta SI - \mu E - \sigma E,$$

$$\frac{dI}{dt} = \sigma E - \mu I,$$

where S = S(t), E = E(t) and I = I(t) are the populations of susceptible, exposed (asymptomatically-infected) and infectious individuals. The parameter $\Pi > 1$ and $0 < \beta, \mu, \sigma \le 1$. Find the condition(s) for the local and global

asymptotic stability of the disease-free equilibrium $(S^*, E^*, I^*) = (\frac{\Pi}{\mu}, 0, 0)$.

FINAL EXAMINATION

		TITLE PAGE		
DEPARTMENT &	& COURSE #: <u>136.480</u>	TIME: 3 HOURS		
EXAMINATION	Dynamical Systems : Theory and Applications	EXAMINERS: A. Gumel		
NAME: (PRINT)				
STUDENT NUMBER:				
SIGNATURE:	(I understand that cheating is a	sarious offense)		
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INSTRUCTIONS TO CANDIDATES:

This exam is 3 hours long.

Attempt ALL questions.

DATE: April 2004

No texts, notes or calculators are permitted

Justify your answers. Show all your work and provide explanations where necessary.

Answer questions in the space provided beneath the questions. If space is insufficient, you may continue your answer on the reverse side of the page. If you do continue your answer, please indicate that it is continued.

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TOTAL		
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FINAL EXAMINATION DATE: April 2004

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DEPARTMENT & COURSE #: 136.480 TIME: 3_HOURS

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u> EXAMINER: A. Gumel

Values

- (1) Consider the map $x_{n+1} = x_n + \mu \ell x_n (1 x_n)$, where μ is a parameter and $\ell > 0$ is the step size.
 - (i) Determine the stability of each of the fixed points of the map;

(ii) Determine whether or not the map has a 2-cycle (and, if applicable, give the range of $\mu\ell$ for which this happens);

(iii) If a 2-cycle exists, determine its stability range in parameter space.

DATE: April 2004 FINAL EXAMINATION

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DEPARTMENT & COURSE #: 136.480 TIME: 3 HOURS

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u> EXAMINER: A. Gumel

Values

(2A) Find the Lyapunov exponent of the tent map given by

$$x_{n+1} = \begin{cases} rx_n & \text{for } 0 \le x_n \le 0.5, \\ r - rx_n & \text{for } 0.5 \le x_n \le 1, \end{cases}$$

with $0 \le r \le 2$ and $0 \le x_n \le 1$.

(2B) Show that the "Newton Map" $x_{n+1} = f(x_n)$ when $f(x_n) = x_n - \frac{g(x_n)}{g'(x_n)}$ for finding the roots of $g(x) = x^2 - 16 = 0$ has super-stable fixed points at $x^* = \pm 4$ at $x^* = \pm 4$.

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DEPARTMENT & COURSE #: 136.480 TIME: 3 HOURS

•EXAMINATION: <u>Dynamical Systems</u>: EXAMINER: <u>A. Gumel</u>
<u>Theory and Applications</u>

Values

(3) Classify the type of bifurcation the following differential equations undergo and draw their bifurcation diagrams:

$$(i) \ \dot{x} = x(\mu + e^x)$$

(ii)
$$\dot{x} = x - \frac{\mu x}{1 + x^2}$$
.

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TIME: 3 HOURS DEPARTMENT & COURSE #: 136.480

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u> EXAMINER: A. Gumel

Values

(4) Use the Dulac criterion in (i) and a suitable Lyapunov function in (ii) to show that the following planar systems have no closed orbits in the positive quadrant (note that "dot" represents differentiation with respect to t).

(i)
$$\dot{x} = x(2-x-y)$$

 $\dot{y} = y(4x-x^2-3)$

(ii)
$$\dot{x} = -8x - xy^2 - 3y^3$$

 $\dot{y} = 2x^2y + 2xy^2$

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DEPARTMENT & COURSE #: 136.480 TIME: 3_HOURS

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u> EXAMINER: A. Gumel

Values

(5) Show that the system

$$\dot{x} = \mu x - y + xy^2$$

$$\dot{y} = x + \mu y + y^3$$

undergoes a Hopf bifurcation at the origin as μ varies. Is the bifurcation subcritical, supercritical or degenerate?

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DEPARTMENT & COURSE #: 136.480

TIME: 3 HOURS

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u>

EXAMINER: A. Gumel

Values

(6) Consider the Lorenz system given by

$$\dot{x} = \sigma(y-x)$$

$$\dot{y} = \beta x - y - xz$$

$$\dot{z} = xy - bz.$$

(i) Show that the origin is globally-asymptotically stable for $0 < \beta < 1$.

(ii) What type of bifurcation occurs at $\beta=1$? Briefly justify your answer.

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DEPARTMENT & COURSE #: 136.480 TIME: 3 HOURS

EXAMINATION: <u>Dynamical Systems</u>: EXAMINER: <u>A. Gumel</u>
Theory and Applications

Values

(7) Consider the epidemic model

$$\begin{array}{ll} \frac{dS}{dt} &=& \Pi - \beta SI - \mu S \\ \frac{dE}{dt} &=& \beta SI - \mu E - \sigma E \\ \frac{dI}{dt} &=& \sigma E - \mu I \end{array}$$

where $S=S(t),\,E=E(t)$ and I=I(t) are the populations of susceptible, exposed (asymptomatically-infected) and infectious individuals and $\Pi>>1,\,\beta,\,\mu$, and σ are positive parameters.

(i) Find condition(s) for the local asymptotic stability of the disease-free equilibrium $(S^*, E^*, I^*) = \left(\frac{\Pi}{\mu}, 0, 0\right)$.

(ii) Use the Perron-Frobenius theorem to establish the global asymptotic stability of this equilibrium solution.

DATE: April 23, 2003 FINAL EXAMINATION

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DEPARTMENT & COURSE NO: 136.480 TIME: 3 hours

EXAMINATION: Dynamical Systems: Theory EXAMINER: A. Gumel

& Applications

Attempt ALL questions

- (1A) Show that the logistic map, given by $x_{n+1} = \mu x_n (1 x_n)$, has a stable 2-cycle for $3 < \mu < 1 + \sqrt{6}$.
- (1B) Suppose that f has a super-stable p-cycle containing the point x_0 . Show that the Liapunov exponent $\lambda = -\infty$.
- (1C) Consider the map $x_{n+1} = \sin x_n$. Show that the stability of its unique fixed point is not determined by linearization. Use graphical (cobweb) approach to show that this fixed point is stable.
 - (2) Consider the differential equation $\dot{x} = x + \frac{rx}{1+x^2}$. Classify the type of bifurcation it undergoes, and find the bifurcation point (r_c) . Sketch the bifurcation diagram in the (x,r) plane.
 - (3) Obtain, and classify, the critical points of the following system

$$\dot{x} = x \left(1 - \frac{x}{2} - y \right),$$

$$\dot{y} = y\left(x - 1 - \frac{y}{2}\right).$$

Use this information to draw the phase portrait for the system.

DATE: April 23, 2003 FINAL EXAMINATION

PAGE 2 of 2

DEPARTMENT & COURSE NO: 136.480 TIME: 3 hours

EXAMINATION: Dynamical Systems: Theory EXAMINER: A. Gumel

& Applications

(4) Show that the system

$$\dot{x}=y-x^3.$$

$$\dot{y} = -x - y^3$$

has no closed orbits, by constructing a Liapunov function of the form $V = c_1 x^2 + c_2 y^2$ (where c_1 and c_2 are to be suitably chosen).

- (5) Let $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$ be a continuously differentiable vector field defined on a simply connected subset R of the plane. Prove that there are closed orbits lying entirely in R if there exists a continuously differentiable, real-valued function $g(\mathbf{x})$ such that $\nabla \cdot (g\dot{\mathbf{x}})$ has one sign throughout R.
- (6) Consider the Lorenz system

$$\dot{x} = \sigma(y - x)$$

$$\dot{y} = rx - y - xz$$

$$\dot{z} = xy - \beta z.$$

- (a) Use the Liapunov function $V = \frac{1}{2}(x^2 + \sigma y^2 + \sigma z^2)$ to find conditions on σ , r, β which are sufficient for asymptotic stability of the origin.
- (b) Investigate the existence and stability of other possible equilibria of the system (determine, in particular, whether the system undergoes a certain type of Hopf bifurcation). What would you expect if you simulate the model with $\sigma=10$, $\beta=\frac{8}{3}$ and r=28?

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DEPARTMENT & COURSE #: 136.480	TIME: 2.5 HOURS			
EXAMINATION: <u>Dynamical Systems</u> : <u>Theory and Applications</u>	EXAMINERS: A. Gumel			
NAME: (PRINT)				
STUDENT NUMBER:				
SIGNATURE: (I understand that cheating is a serious offense)				

INSTRUCTIONS TO CANDIDATES:

Attempt ALL four questions. Each question carries 10 marks.

This exam is 2.5 hours long.

No texts, notes or calculators are permitted

Justify your answers. Show all your work and provide explanations where necessary.

Answer questions in the space provided beneath the questions. If space is insufficient, you may continue your answer on the reverse side of the page. If you do continue your answer, please indicate that it is continued.

QUESTION	MARK
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Dec. 14, 2001

FINAL EXAMINATION

PAGE 1 of 4

DEPARTMENT & COURSE #: 136.480

TIME: 2.5 HOURS

EXAMINATION: Dynamical Systems:

Theory and Applications

EXAMINERS: A. Gumel

Values

Q1A Consider the "Newton map"

5

2

$$x_{n+1} = f(x_n)$$
 with $f(x_n) = x_n - \frac{g(x_n)}{g'(x_n)}$.

Show that the Newton map for finding the roots of $g(x) = x^2 - 4$ has superstable fixed points at $x^* = \pm 2$.

Q1B Calculate the Liapunov exponent of the map $x_{n+1} = rx_n$.

Does the map exhibit chaotic dynamics?

Q1C Consider the map $x_{n+1} = \sin x_n$. Show that the stability of its unique fixed point is not determined by linearization. Use graphical (cobweb) approach to show that this fixed point is stable.

Dec. 14, 2001

FINAL EXAMINATION

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DEPARTMENT & COURSE #: 136.480

TIME: 2.5 HOURS

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u>

EXAMINERS: A. Gumel

Values

Q2 Consider differential equation $\dot{x} = x + \frac{rx}{1 + x^2}$. Classify the type of 10 bifurcation it undergoes, and find the critical bifurcation value (r_c) . Sketch the bifurcation diagram in the (x, r) plane.

Dec. 14, 2001 FINAL EXAMINATION

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DEPARTMENT & COURSE #: 136.480

TIME: 2.5 HOURS

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u>

EXAMINERS: A. Gumel

Values

Q3A Classify the fixed points of the system

$$\dot{x} = xy - 1$$

$$\dot{y} = x - y^3.$$
(1)

Q3B Use the phase portrait of

6
$$\frac{dx}{dt} = -10^{-6}xy + 0.0003x$$

$$\frac{dy}{dt} = 10^{-6}xy - 0.1y$$
(2)

to determine the fate of a trajectory (x, y) = (20, 000, 100)

Dec. 14, 2001 FINAL EXAMINATION

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DEPARTMENT & COURSE #: 136.480 TIME: 2.5 HOURS

EXAMINATION: <u>Dynamical Systems</u>: <u>Theory and Applications</u> EXAMINERS: A. Gumel

Values

Q4 Given the system

10

$$\dot{x} = -y - \mu(x^3 + xy^2)
\dot{y} = x - \mu(y^3 + x^2y)$$
(3)

where μ is a parameter. Show that the linearized system incorrectly predicts the origin to be a centre for all values of μ .