

Exercises on clustering

INSA Toulouse
Olivier Roustant & Joris Guerin

Exercise 1: Hierarchical clustering and Ward dissimilarity

Let $\mathcal{C} = \{x_1, \dots, x_n\}$ be a dataset of \mathbb{R}^d . Assume that these data are split in 2 classes $\mathcal{C}_1, \mathcal{C}_2$ of sizes n_1, n_2 . Denote by g the global centroid and by g_1, g_2 the class centroids:

$$g = \frac{1}{n} \sum_{i=1}^n x_i, \quad g_j = \frac{1}{n_j} \sum_{i \in \mathcal{C}_j} x_i \quad (j = 1, 2).$$

Denote by $\|\cdot\|$ the usual Euclidean norm in \mathbb{R}^d . Define the inertia of a set of points as the unnormalized variance:

$$I(\mathcal{C}) = \sum_{i=1}^n \|x_i - g\|^2, \quad I(\mathcal{C}_j) = \sum_{i \in \mathcal{C}_j} \|x_i - g_j\|^2 \quad (j = 1, 2).$$

1. In this question, you prove the formula of *inertia decomposition*.

- By writing $x_i - g = (x_i - g_j) + (g_j - g)$, show that (one form of Huygens formula)

$$\sum_{i \in \mathcal{C}_j} \|x_i - g\|^2 = I(\mathcal{C}_j) + n_j \|g_j - g\|^2.$$

- Deduce that

$$I(\mathcal{C}) = \sum_{j=1}^2 I(\mathcal{C}_j) + \sum_{j=1}^2 n_j \|g_j - g\|^2.$$

Explain why the first term is called *within-class inertia*, and the second one *between-class inertia*. Is this formula true for K classes?

2. In this question, you obtain a simple expression of the between-class inertia, involving the distance between centroids.

- What property directly gives the formula: $g = \frac{n_1}{n} g_1 + \frac{n_2}{n} g_2$?
- Deduce that $\|g_1 - g\| = \frac{n_2}{n} \|g_1 - g_2\|$ and $\|g_2 - g\| = \frac{n_1}{n} \|g_1 - g_2\|$.
- Finally, prove the formula for the between-class inertia:

$$\sum_{j=1}^2 n_j \|g_j - g\|^2 = \frac{n_1 n_2}{n_1 + n_2} \|g_1 - g_2\|^2.$$

3. Explain why the between-class inertia is a dissimilarity, called *Ward dissimilarity*.

4. Illustrate through an example the difference between average and ward linkage.

Exercise 2: Convergence of k -means algorithm.

Let $\{x_1, \dots, x_n\}$ be a dataset of \mathbb{R}^d . At step t of k -means algorithm, we have:

- a partition $\mathcal{A}^{(t)}$ in K classes, i.e. a function $\mathcal{A}^{(t)} : \{1, \dots, n\} \rightarrow \{1, \dots, K\}$ which allocates a class to each individual. The corresponding classes are $\mathcal{C}_j^{(t)} = \{i \in \{1, \dots, n\} \text{ such that } \mathcal{A}^{(t)}(i) = j\}$ (for $j = 1, \dots, K$).
- centers $c_1^{(t)}, \dots, c_K^{(t)}$, equal to the class centroids $\mathcal{C}^{(t)}_1, \dots, \mathcal{C}^{(t)}_K$ defined by $\mathcal{A}^{(t)}$.

Recall that k -means is a 2 stage procedure:

1. **(Allocation update)**. Choose the new allocation as the closest centroid obtained at previous step (choose one at random in case of equality):

$$\text{For } i = 1, \dots, n : \quad \mathcal{A}^{(t+1)}(i) = \operatorname{argmin}_{j=1, \dots, K} \|x_i - c_j^{(t)}\|.$$

2. **(Centroid update)**. Compute the centroid of the new class, defined by the new allocation obtained at stage 1:

$$\text{For } j = 1, \dots, K : \quad c_j^{(t+1)} = \operatorname{argmin}_{c \in \mathbb{R}^n} \sum_{i \in \mathcal{C}_j^{(t+1)}} \|x_i - c\|^2.$$

You are going to prove that **k -means stops after a finite number of iterations**: there exists $t_0 \in \mathbb{N}$ such that for all $t \geq t_0$,

$$\text{For all } i = 1, \dots, n, \text{ and } j = 1, \dots, K : \quad \mathcal{A}^{(t+1)}(i) = \mathcal{A}^{(t)}(i), \quad c_j^{(t+1)} = c_j^{(t)}.$$

For that, we consider the within-class inertia associated to $\mathcal{A}^{(t)}$:

$$J(\mathcal{A}^{(t)}) = \sum_{j=1}^K \sum_{i \in \mathcal{C}_j^{(t)}} \|x_i - c_j^{(t)}\|^2 = \sum_{i=1}^n \|x_i - c_{\mathcal{A}^{(t)}(i)}^{(t)}\|^2.$$

1. Explain why $c_j^{(t+1)}$ defined in the 'centroid update' step is indeed the centroid of the updated class.
2. In this question you prove that the *within-class inertia decreases*.

$$\bullet \text{ Explain why } J(\mathcal{A}^{(t)}) \geq \sum_{i=1}^n \|x_i - c_{\mathcal{A}^{(t+1)}(i)}^{(t)}\|^2 = \sum_{j=1}^K \sum_{i \in \mathcal{C}_j^{(t+1)}} \|x_i - c_j^{(t)}\|^2.$$

$$\bullet \text{ Deduce that } J(\mathcal{A}^{(t)}) \geq \sum_{j=1}^K \sum_{i \in \mathcal{C}_j^{(t+1)}} \|x_i - c_j^{(t+1)}\|^2 = J(\mathcal{A}^{(t+1)}).$$

3. Prove that the sequence $J(\mathcal{A}^{(t)})$ is converging, and that the limit is reached. *Hint: What can say about all possible partitions $\mathcal{A}^{(t)}$?*
4. Deduce from the 'centroid update' step that, after some t^* , for all $j = 1, \dots, K$: $c_j^{(t+1)} = c_j^{(t)}$. Finally, explain why, after $t^* + 1$ we have for all $i = 1, \dots, K$: $\mathcal{A}^{(t+1)}(i) = \mathcal{A}^{(t)}(i)$.
5. Is the limit equal to the global minimum of the within-class inertia?