



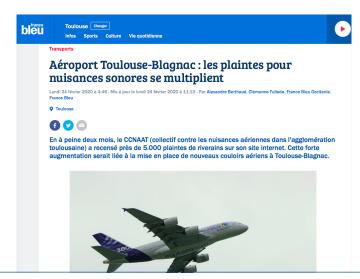
Parametric optimization of an acoustic liner

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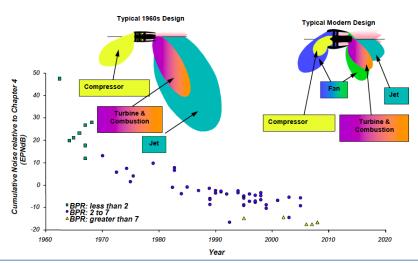


La moitié des Français considère le bruit des transports comme la principale source de nuisances sonores. Des recherches se poursuivent donc activement pour permettre de réduire le bruit des réacteurs des avions au sol et en vol.

6,5 millions d'euros : c'est le montant total des amendes infligées par l'ACNUSA (Autorité de contrôle



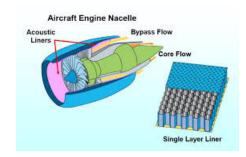








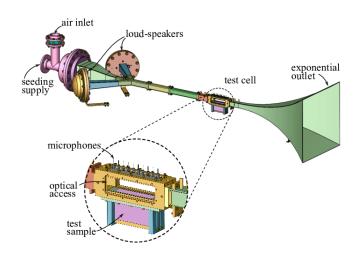




Use of liners in nacelle aircraft engine to reduce fan, turbine and combustion noises ACARE, Clean Sky 2, ACNUSA ...



Acoustic liners in ducts

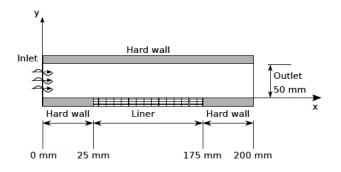


ONERA's aero-thermo-acoustic test bench





Acoustic liners in ducts



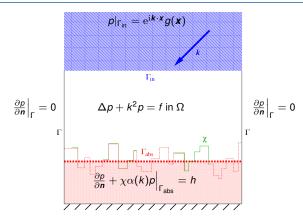
ONERA's aero-thermo-acoustic test bench

J. Primus, F. Simon, E. Piot, AIAA Paper #2011-2869 (2011)
 O. Léon, E. Piot, D. Sebbane, F. Simon, Exp. Fluids 58, 72 (2017)





Model problem



Model problem for acoustical liners with $\partial\Omega=\Gamma_{in}\cup\Gamma_{abs}\cup\Gamma$

- Γ_{in} inflow condition (e.g. incident plane wave with vanishing Mach number $M_0 = 0$);
- Γ hard-wall $(Z \to \infty)$;
- Γ_{abs} acoustic liner with absorption coefficient $\alpha \in \mathbb{C}$.





Optimization problem: Setting

ullet The characteristic function χ gives the distribution of absorbing layer on the boundary Γ_{abs} :

$$\chi(\mathbf{x}) = \begin{cases} 1 & \text{if there is porous material at } \mathbf{x} \\ 0 & \text{if there is no porous material at } \mathbf{x} \end{cases}$$

with the condition that $0 < \beta = \int_{\Gamma_{abs}} \chi dS < \int_{\Gamma_{abs}} dS$.

• The goal is to find χ such that the acoustic disturbance $J(\chi) := \int_{\Omega} |p_{\chi}|^2 d\mathbf{x}$ is minimal, when p_{χ} is the solution of:

$$\begin{cases} \Delta p + k^2 p = 0 & \text{in } \Omega \,, \\ p = g & \text{on } \Gamma_{\text{in}} \,, \\ \partial_{\textbf{n}} p = 0 & \text{on } \Gamma \,, \\ \partial_{\textbf{n}} p + \alpha \chi p = 0 & \text{on } \Gamma_{\text{abs}} \,. \end{cases} \tag{P_χ}$$

Eligible admissible set:

$$U_{ad}(\beta) = \left\{ \chi \in L^{\infty}(\Gamma_{abs}); \, \forall \boldsymbol{x} \in \Gamma_{abs}, \, \chi(\boldsymbol{x}) \in \{0,1\}, \, \int_{\Gamma_{abs}} \chi dS = \beta \right\}.$$

 \bullet Relaxation method: we rather seek χ in $\textit{U}_{\rm ad}^*(\beta)\supset\textit{U}_{\rm ad}(\beta)$ with

$$U_{\text{ad}}^*(\beta) = \left\{\chi \in L^{\infty}(\Gamma_{\text{abs}}); \, \forall \textbf{\textit{x}} \in \Gamma_{\text{abs}}, \, \chi(\textbf{\textit{x}}) \in [0,1], \, \int_{\Gamma_{\text{abs}}} \chi dS = \beta \right\},$$

and it can be shown that $\min_{\chi \in U^*_{ad}(\beta)} J(\chi)$ has at least one solution (Th. 7.4.4 page 106).





Optimization problem: $J'(\chi)$

• Fréchet derivative of the cost function $J(\chi)$: the linear form $J'(\chi):L^{\infty}(\Gamma_{abs})\to L^1(\Gamma_{abs})$ such that

$$J(\chi + \chi_0) = J(\chi) + \langle J'(\chi), \chi_0 \rangle + o(\chi_0), \quad \lim_{\|\chi_0\|_{\infty} \to 0} \frac{|o(\chi_0)|}{\|\chi_0\|_{\infty}} = 0.$$

• Theorem: the cost function $J(\chi) = \int_{\Omega} |p_{\chi}|^2 dx$ is derivable in the sense of Fréchet and

$$\boxed{J'(\chi) = -\text{Re}\{\alpha p_{\chi} q_{\chi}\}},$$

where q_{χ} is the solution of the adjoint problem (P'_{χ}) considering $J(\chi)$ as the objective function

$$\begin{cases} \Delta q + k^2 q = -2\overline{p}_{\chi} & \text{in } \Omega\,,\\ q = 0 & \text{on } \Gamma_{\text{in}}\,,\\ \partial_{\textbf{n}} q = 0 & \text{on } \Gamma\,,\\ \partial_{\textbf{n}} q + \alpha \chi q = 0 & \text{on } \Gamma_{\text{abs}}\,. \end{cases} \tag{P_{χ}^{\prime}}.$$

• Outlook: ambient flow $\varrho_0(\mathbf{x}), p_0(\mathbf{x}), \mathbf{v}_0(\mathbf{x})$, uncertainty quantification...





Optimization problem: Gradient descent

Gradient descent algorithm:

$$\chi^{(k+1)} = \mathcal{P}_{\ell_k} \left[\chi^{(k)} - \mu_k J'(\chi^{(k)}) \right],$$

where $\mu_k > 0$ is the learning rate, which is iteratively updated:

- If $J(\chi^{(k+1)}) < J(\chi^{(k)})$, then $\mu_{k+1} = \mu_k + \epsilon$ for the next iteration;
- If $J(\chi^{(k+1)}) \geq J(\chi^{(k)})$, then $\chi^{(k+1)}$ is re-evaluated by dividing μ_k by 2.
- To ensure that $\chi^{(k+1)} \in [0, 1]$, we use the projector:

$$\mathcal{P}_{\ell}[\chi] = \max(0, \min(\chi + \ell, 1)),$$

where ℓ plays the role of a Lagrange multiplier to ensure that the constraint $\int_{\Gamma_{abs}} \chi dS = \beta$ is fulfilled; it is updated iteratively by dichotomy.

• The algorithm is ended after K iterations, or whenever $\|\chi^{(k+1)} - \chi^{(k)}\|_2$ for instance is arbitrarily small.

G. Allaire, Conception Optimale des Structures. Springer-Verlag, Berlin (2007)





Optimization problem: Algorithm

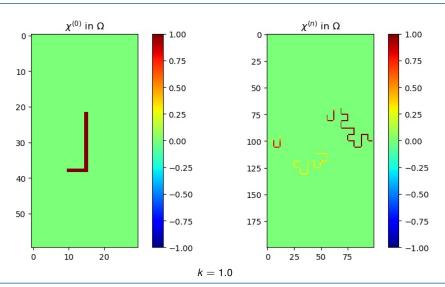
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\chi^{(0)} \in U_{ad}(\beta); \mu = \mu^{(0)};
for k = 0: K do
     compute p^{(k)}; q^{(k)}; J(\chi^{(k)}); J'(\chi^{(k)});
     E = J(\chi^{(k)}):
     while E \geq J(\chi^{(k)}) \& \mu > \epsilon_0 do
          \ell = 0:
          \chi^{(k+1)} = \mathcal{P}_{\ell} \left[ \chi^{(k)} - \mu J'(\chi^{(k)}) \right];
          while |\int_{\Gamma_{abs}} \chi^{(k+1)} dS - \beta| \ge \epsilon_1 do
               if \int_{\Gamma_{abs}} \chi^{(k+1)} dS \ge \beta then
                    \ell \leftarrow \ell - \epsilon_2;
                else
                     \ell \leftarrow \ell + \epsilon_2:
                \chi^{(k+1)} = \mathcal{P}_{\ell} \left[ \chi^{(k)} - \mu J'(\chi^{(k)}) \right];
          end while
          compute p^{(k+1)}; J(\chi^{(k+1)});
          E = J(\chi^{(k+1)}):
          if E < J(\chi^{(k)}) then
                \mu \leftarrow \mu + \epsilon_3;
          else
                \mu \leftarrow \mu/2;
          end if
     end while
```



end for

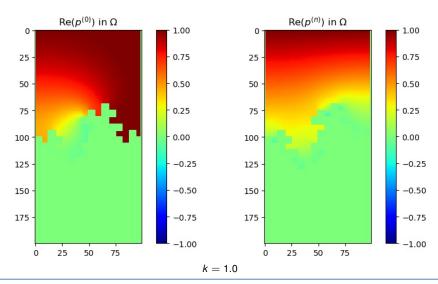


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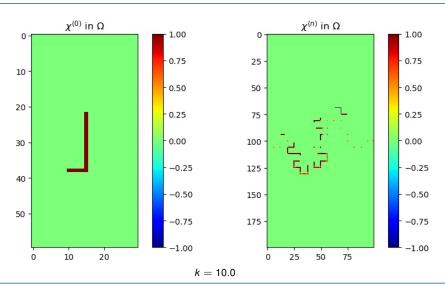






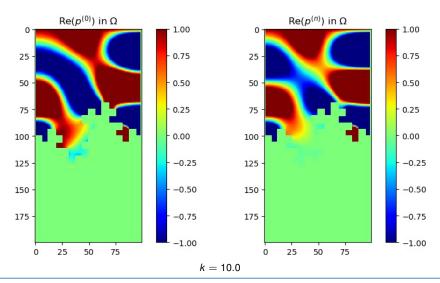














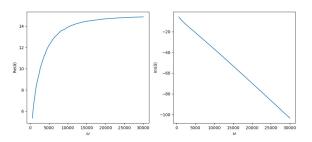


Absorption

- The complex-valued, regular function $\omega \mapsto \alpha(\omega)$ has a strictly positive real part $\operatorname{Re}\{\alpha\} > 0$ and strictly negative imaginary part $\operatorname{Im}\{\alpha\} < 0$;
- The condition $\frac{\partial p}{\partial n} + (\text{Re}\{\alpha\} i|\text{Im}\{\alpha\}|)p = 0$ is satisfied by the wave:

$$e^{-\alpha \mathbf{n} \cdot \mathbf{x}} = e^{-\operatorname{Re}\{\alpha\} \mathbf{n} \cdot \mathbf{x}} e^{i|\operatorname{Im}\{\alpha\}|\mathbf{n} \cdot \mathbf{x}}.$$

which is a propagating plane wave \times an exponentially decreasing amplitude where dissipation grows with $\operatorname{Re}\{\alpha\}$.



Real and imaginary parts of α for melamine foam

F. Magoulès, T. P. K. Nguyen, P. Omnes, A. Rozanova-Pierrat, SIAM J. Control Optim. 59(1), 561 (2021)





• The pressure $\widehat{p}(\pmb{x},\omega)$ and particle velocity $\widehat{\pmb{v}}(\pmb{x},\omega)$ of a fluid in a porous material with motionless, rigid skeleton satisfy (constitutive equation and linearized Darcy's law in the frequency domain with a $e^{-i\omega t}$ dependence):

$$\frac{\mathrm{i}\omega}{\mathcal{K}_{\mathrm{eq}}(\omega)}\widehat{\boldsymbol{\rho}} = \boldsymbol{\nabla}\cdot\widehat{\boldsymbol{\nu}}\,,\quad \mathrm{i}\omega\varrho_{\mathrm{eq}}(\omega)\widehat{\boldsymbol{\nu}} = \boldsymbol{\nabla}\widehat{\boldsymbol{\rho}}\,,$$

where $K_0 = \varrho_0 c_0^2$ and $\varrho_{eq}(\omega) = \varrho_0 \widehat{\alpha}(\omega)$, $K_{eq}(\omega) = K_0 / \widehat{\beta}(\omega)$.

Dynamic tortuosity accounting for viscous and inertial effects in the frequency domain:

$$\widehat{\alpha}(\omega) = \alpha_h + \frac{\eta \phi}{\varrho_0 k_0} \widehat{A}(\omega),$$

where $t\mapsto A(t)$ a time-dependent dimensionless viscosity coefficient accounting for viscous effects; η pore fluid dynamic viscosity; ϕ porosity; α_h tortuosity (the ratio of the microscopic mean-square velocity of fluid particles relative to the skeleton with respect to their macroscopic quadratic velocity); k_0 intrinsic permeability depending on the geometry of the pore network solely.



• The pressure $\widehat{p}(\pmb{x},\omega)$ and particle velocity $\widehat{\pmb{v}}(\pmb{x},\omega)$ of a fluid in a porous material with motionless, rigid skeleton satisfy (constitutive equation and linearized Darcy's law in the frequency domain with a $\mathrm{e}^{-\mathrm{i}\omega t}$ dependence):

$$\frac{\mathrm{i}\omega}{K_{\mathrm{eq}}(\omega)}\widehat{\boldsymbol{\rho}} = \boldsymbol{\nabla}\cdot\widehat{\boldsymbol{v}}\,,\quad \mathrm{i}\omega\varrho_{\mathrm{eq}}(\omega)\widehat{\boldsymbol{v}} = \boldsymbol{\nabla}\widehat{\boldsymbol{\rho}}\,,$$

where $K_0 = \varrho_0 c_0^2$ and $\varrho_{eq}(\omega) = \varrho_0 \widehat{\alpha}(\omega)$, $K_{eq}(\omega) = K_0 / \widehat{\beta}(\omega)$.

Dynamic compressibility, or bulk modulus, accounting for thermal effects:

$$\widehat{\beta}(\omega) = \gamma(1 + \widehat{B}(\omega)),$$

where $t \mapsto B(t)$ a time-dependent compressibility coefficient (in s⁻¹) accounting for thermal effects of the fluid phase; γ ratio of specific heats.



For a homogeneous equivalent fluid layer of porous material of thickness L, the transfer matrix T for plane acoustic waves travelling in the direction of the (inward) normal n to the layer, such that:

$$\begin{pmatrix} \widehat{p}(\mathbf{x},\omega) \\ \widehat{\mathbf{v}}(\mathbf{x},\omega) \cdot \mathbf{n} \end{pmatrix}_{\mathbf{x} \cdot \mathbf{n} = 0} = \mathbf{T}(\omega) \begin{pmatrix} \widehat{p}(\mathbf{x},\omega) \\ \widehat{\mathbf{v}}(\mathbf{x},\omega) \cdot \mathbf{n} \end{pmatrix}_{\mathbf{x} \cdot \mathbf{n} = L},$$

is:

$$extbf{\textit{T}}(\omega) = egin{bmatrix} \cos(k_{
m eq}(\omega)L) & -{
m i}Z_{
m eq}(\omega)\sin(k_{
m eq}(\omega)L) \ \frac{1}{{
m i}Z_{
m eq}(\omega)}\sin(k_{
m eq}(\omega)L) & \cos(k_{
m eq}(\omega)L) \end{bmatrix},$$

with the equivalent frequency-dependent speed of sound $c_{\rm eq}$, wave number $k_{\rm eq}$, and characteristic impedance $Z_{\rm eq}$:

$$c_{
m eq}(\omega) = \sqrt{rac{ extit{K}_{
m eq}(\omega)}{arrho_{
m eq}(\omega)}}\,, \quad extit{k}_{
m eq}(\omega) = rac{\omega}{c_{
m eq}(\omega)}\,, \quad extit{Z}_{
m eq}(\omega) = arrho_{
m eq}(\omega) c_{
m eq}(\omega)\,.$$



• Boundary impedance of the layer of thickness L such that $Z = \frac{\hat{p}}{\hat{v} \cdot n} |_{x \cdot n = L}$:

$$Z(\omega) = -\frac{T_{22}(\omega)}{\phi T_{21}(\omega)},$$

where ϕ porosity of the last layer in contact with the air–typically a perforated plate.

Hence one identifies:

$$\alpha(\omega) = -i\omega \frac{\varrho_{\rm eq}(\omega)}{Z(\omega)} = -\omega \varrho_{\rm eq}(\omega) \frac{X(\omega) + iR(\omega)}{|Z(\omega)|^2}.$$

