

SYST0002 - LECTURE #1 ESPACE D'ÉTAT EN ID.

↳ DYNAMIQUE \Leftrightarrow ODE's.

$$\begin{aligned}\dot{x} &\equiv \frac{dx}{dt} = f(x, \mu) && \text{PARAMÈTRES.} \\ &= a \cdot x + b \cdot \mu && \begin{array}{l} \rightarrow \text{ENTRÉE(S)} \\ \rightarrow \text{VARIABLE(S)} \end{array}\end{aligned}$$

$$\dot{x} = f(x)$$

SYSTÈME FERMÉ

$$\dot{x} = f(x, \mu)$$

SYSTÈME OUVERT.

$$\left(\begin{array}{l} \dot{x} = \sin(x) \\ \dot{x} = x^2 + \mu \\ \dot{x} = \sqrt{x} \end{array} \right. \quad f(x) \text{ NON-LINÉAIRES!}$$

$$\left(\begin{array}{l} \dot{x} = a \cdot x, \text{ } a \text{ PARAMÈTRE. LINÉAIRES} \\ \dot{x} = a \cdot x + b \mu, \text{ } a, b \text{ PARAMÈTRES} \end{array} \right.$$

$$\dot{x} = f(x)$$

~~RÉSOLVER ? $\rightarrow x(t)$~~

\hookrightarrow MÉTHODES QUANTITATIVES.

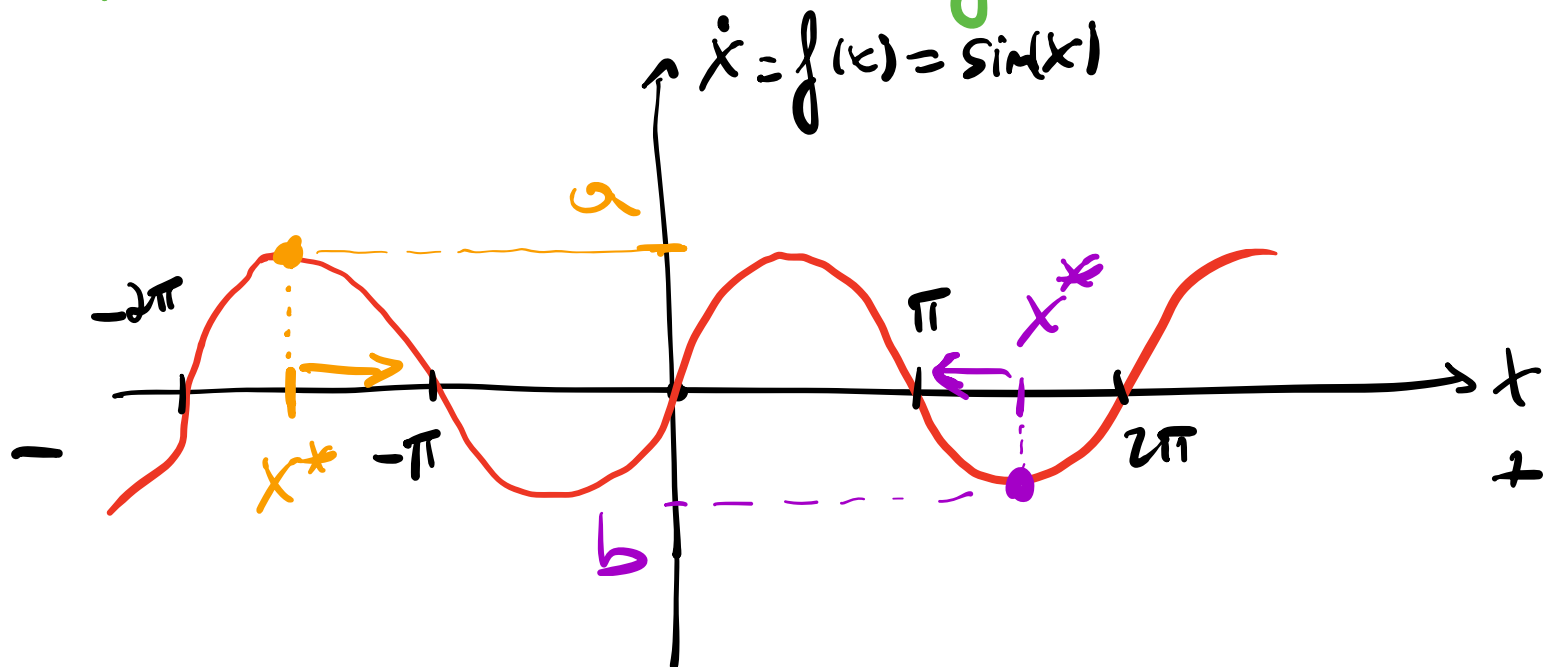
Ex: $\dot{x} = \sin(x)$ [NON LINÉAIRE].

\hookrightarrow ① Si $x_0 = \frac{\pi}{4}$, \swarrow VERS OÙ x VA CONVERGER?

\hookrightarrow ② POUR TOUTE C.I.? $x \rightarrow t \rightarrow +\infty$?

\hookrightarrow PORTRAIT DE PHASE!

ID: TRACER \dot{x} VS $x \Leftrightarrow f(x)$ VS x



$\hookrightarrow f(x) = \sin(x)$ DÉTERMINE L'ÉVOLUTION TEMPORELLE DE x EN TOUT POINT.

• En x^* , $f(x^*) = a > 0$

$\hookrightarrow \dot{x} > 0$, $\frac{dx}{dt} > 0$, $x \nearrow$

• En x^* , $f(x^*) = b < 0$

$\hookrightarrow \dot{x} < 0$, $\frac{dx}{dt} < 0$, $x \searrow$

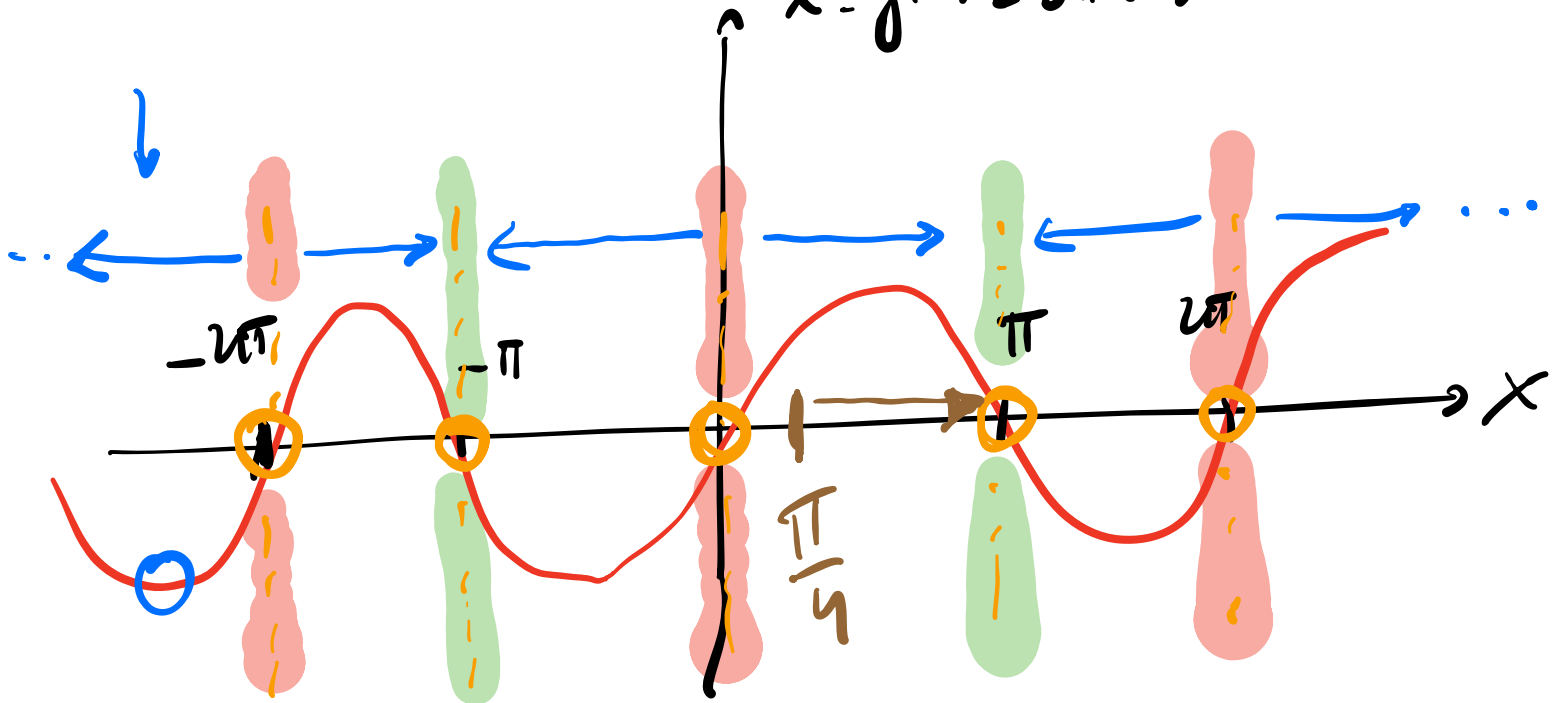
• En \bar{x} , $f(\bar{x}) = 0$

$\hookrightarrow \dot{x} = 0$, $\frac{dx}{dt} = 0$, $x \longrightarrow$

EQUILIBRE / POINT FIXE.

ANALYSE DU PORTRAIT DE PHASE

$$\dot{x} = f(x) = \sin(x)$$



① POINTS FIXES? $\dot{x} = f(x) = 0$.

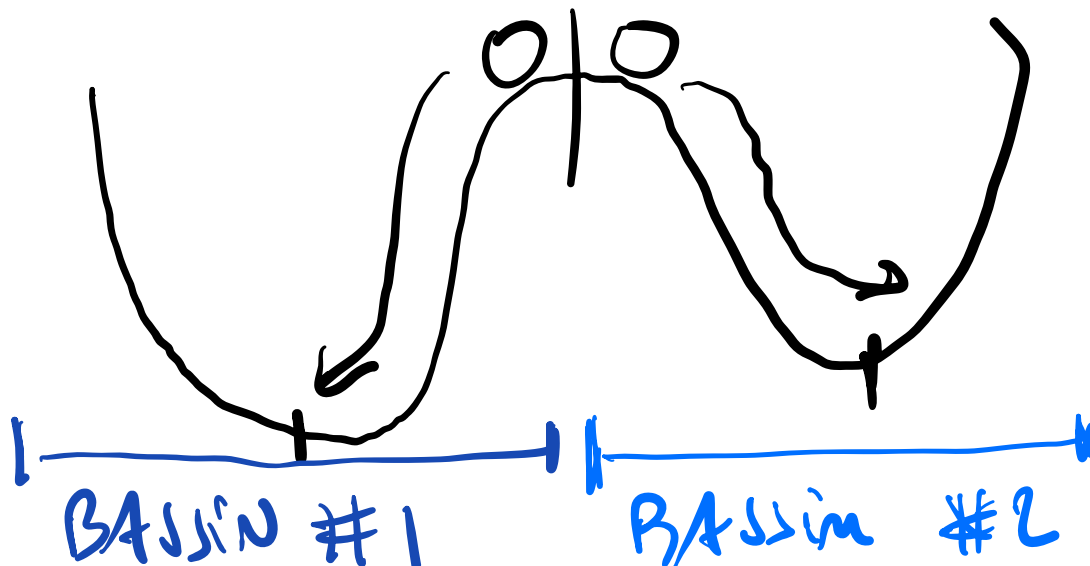
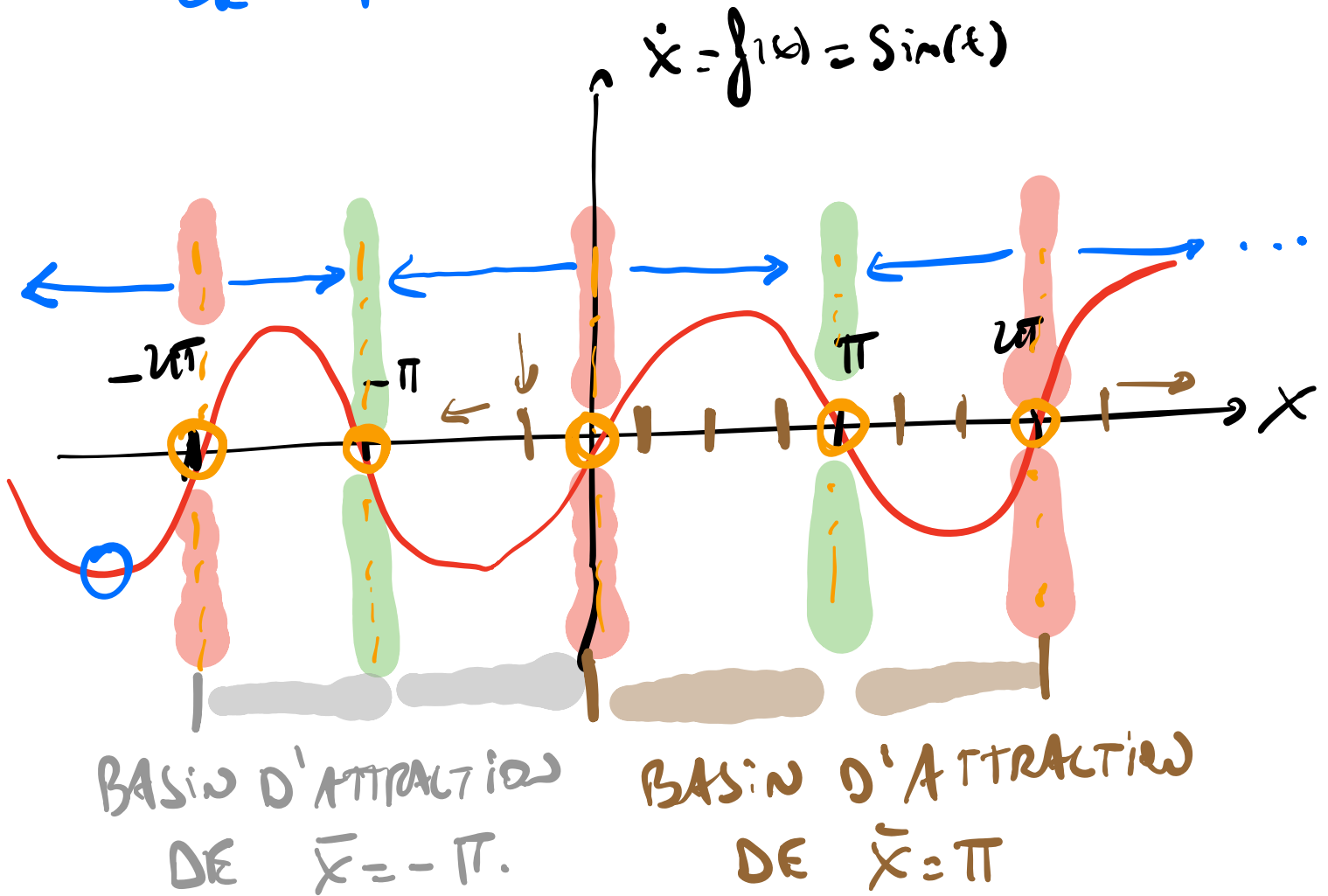
② \hookrightarrow POINTS REPULSIFS / INSTABLES.

\hookrightarrow POINTS ATTRAYANTS / STABLES

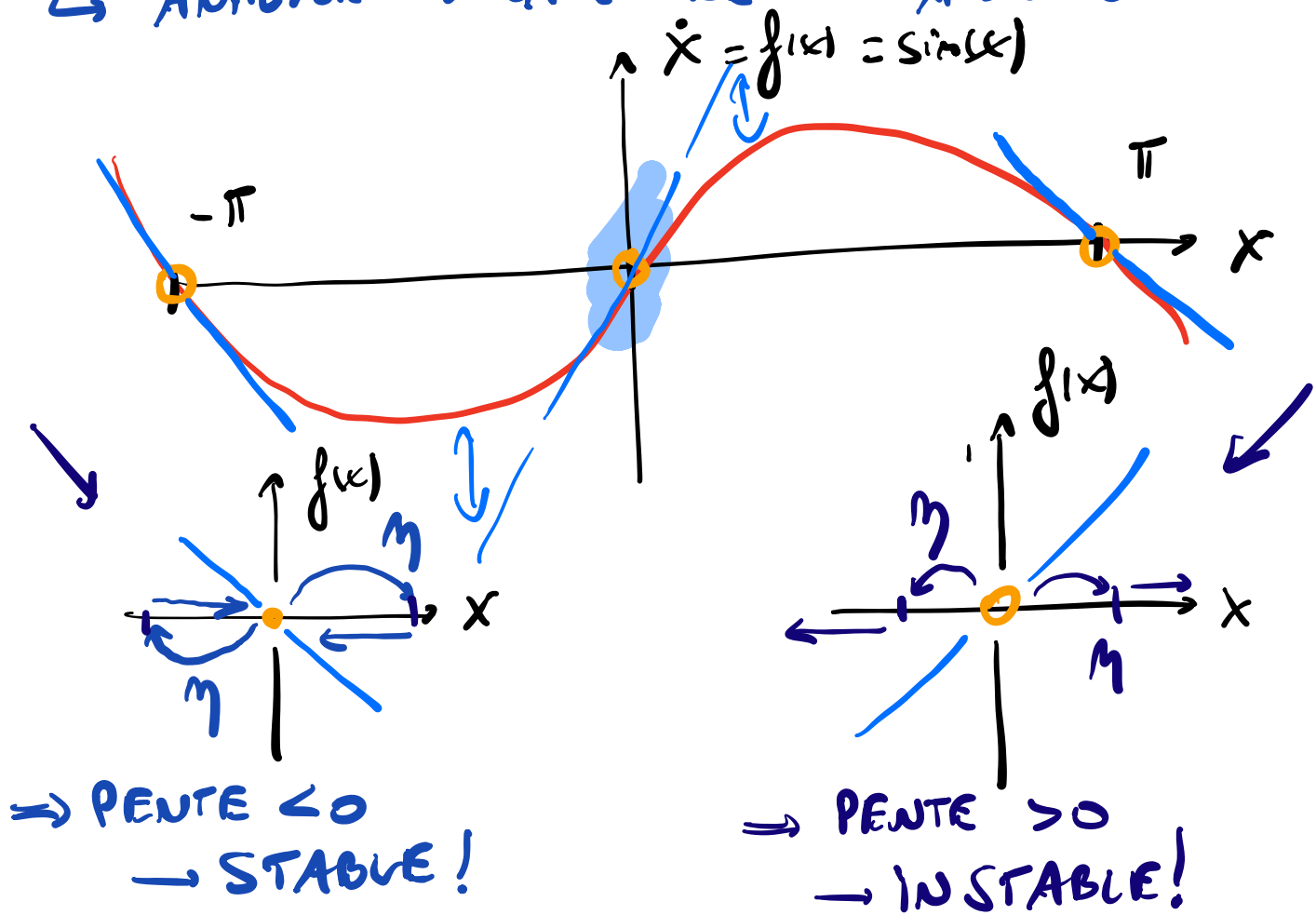
\hookrightarrow STABILITÉ DES POINTS FIXES.

↳ POUR TOUTE C.I.? **BASSIN D'ATTRACTION**
[D'UN POINT FIXE STABLE]

≡ LES C.I. QUI VONT CONVERGER VERS
 CE POINT.



↳ ANALYSE LOCALE DE STABILITÉ.



PENTE $f'(x) \big|_{\bar{x}}$

↳ LINEARISATION!

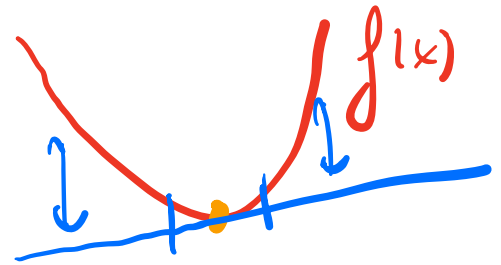
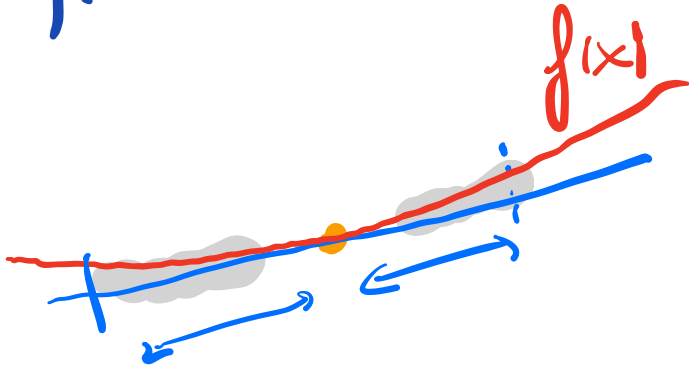
LOCAL!

AUTOUR D'UN POINT!

LINÉARISATION AUTOUR DE \bar{x} :

↳ Si \bar{x} : POINT FIXE ET $\eta(t) = \underline{x(t) - \bar{x}}$

$\eta(t)$: PETITE PERTURBATION AUTOUR DE \bar{x} .



$$\textcircled{A} \rightarrow \dot{\eta} = \frac{d}{dt}(x - \bar{x}) = \frac{dx}{dt} = f(x) = f(\bar{x} + \eta)$$

⇒ EXPANSION DE TAYLOR

$$\textcircled{B} \quad \underbrace{f(\bar{x} + \eta)}_{=0} \approx \underbrace{f(\bar{x})}_{=0} + \eta \cdot \underbrace{\frac{\partial f(\bar{x})}{\partial x}}_{\text{TERME DOMINANT}} + \underbrace{O(\eta^2)}_{\text{petite perturbation}}$$

Si η PETIT

$$\rightarrow \dot{\eta} = f(\bar{x} + \eta) \approx \eta \cdot \boxed{\frac{\partial f(\bar{x})}{\partial x}}$$

PENTE DE
 $f(x)$
ÉVALUÉ EN
 $\bar{x} = a$

$$\approx \eta \cdot a.$$

$$\rightarrow \dot{\eta} = a \cdot \eta \quad ; \quad a = \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}}$$

PARAMÈTRE.

$$\hookrightarrow \dot{\eta} = f(\eta) \text{ où } f(\eta) = a \cdot \eta$$

\rightarrow LINÉAIRE.

$$\left\{ \begin{array}{l} \dot{\eta} = a \cdot \eta \\ \eta(0) = \eta_0 \end{array} \right. \quad ; \quad a = \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}}$$

$$\hookrightarrow \eta(t) = \eta_0 e^{at}$$

$a > 0 \rightarrow \text{Exp}$
 $a < 0 \rightarrow \text{Exp}$

$$! a = 0 ? \rightarrow \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}} = 0$$

$$\hookrightarrow f(\bar{x} + \eta) \approx \underbrace{f(\bar{x})}_{=0} + \underbrace{\eta \cdot \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}}}_{=0} + O(\eta^2)$$

DOMINANT
Si $a=0$!

