

SYSTÈME - LECTURE #1 ESPACE D'ÉTAT EN 1D.

↳ DYNAMIQUE \Leftrightarrow ODE's.

$$\dot{x} = \frac{dx}{dt} = f(x, \mu)$$

→ PARAMÈTRES.

$$= a \cdot x + b \cdot \mu \rightarrow$$

ENTRÉE(S)

→ VARIABLE(S)

$$\dot{x} = f(x)$$

SYSTÈME FERMÉ

$$\dot{x} = f(x, \mu)$$

SYSTÈME OUVERT.

$$\dot{x} = \sin(x)$$

$f(x)$ NON-LINÉAIRES!

$$\dot{x} = x^2 + \mu$$

$$\dot{x} = \sqrt{x}$$

$$\dot{x} = a \cdot x, a \text{ PARAMÈTRE.}$$

Linéaires

$$\dot{x} = a \cdot x + b \mu, a, b \text{ PARAMÈTRES}$$

$$\dot{x} = f(x)$$

~~RÉSOLVER? $\rightarrow x(t)$~~

↳ MÉTHODES QUANTITATIVES.

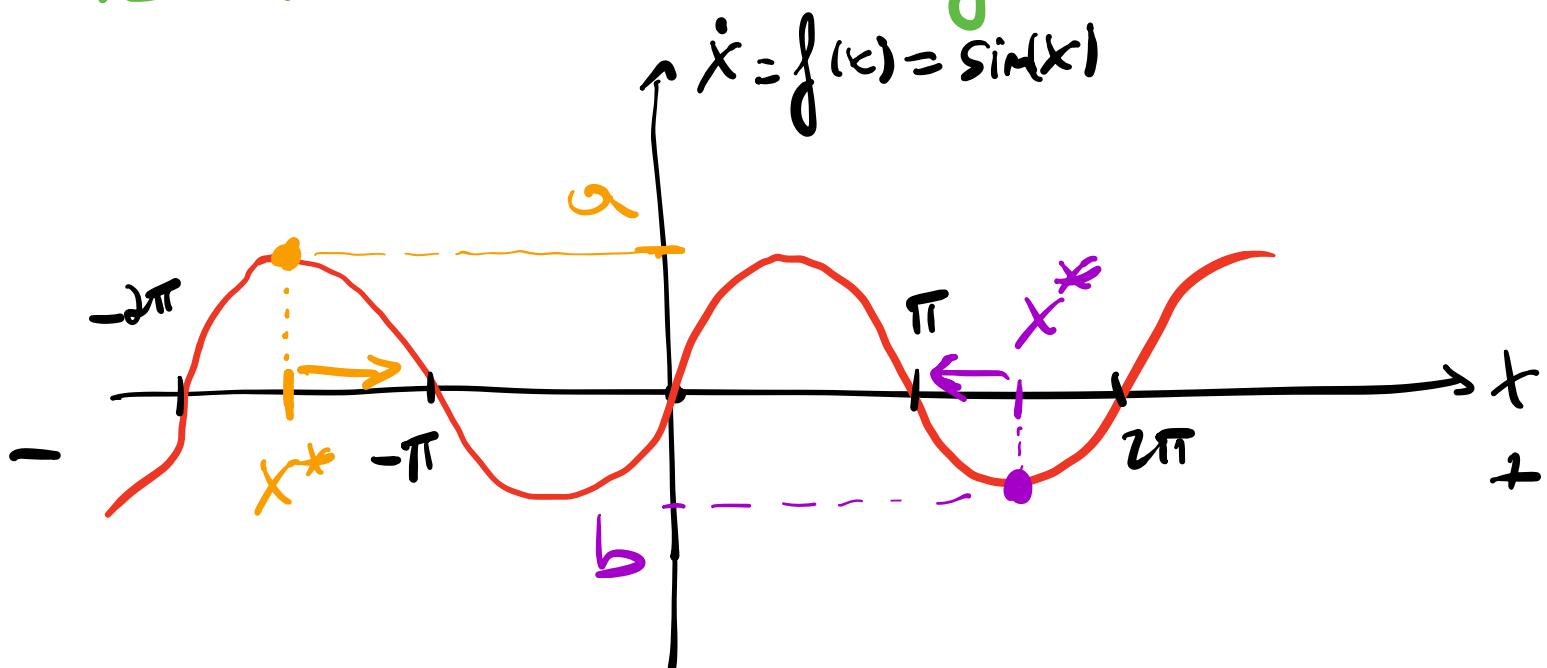
Ex: $\dot{x} = \sin(x)$ [NON LINÉAIRE].

↳ ① Si $x_0 = \frac{\pi}{4}$, vers où x va converger?

↳ ② Pour toute C.I.? $x \rightarrow t \rightarrow +\infty$?

↳ PORTRAIT DE PHASE!

10: TRACER \dot{x} VS $x \Leftrightarrow f(x)$ VS x

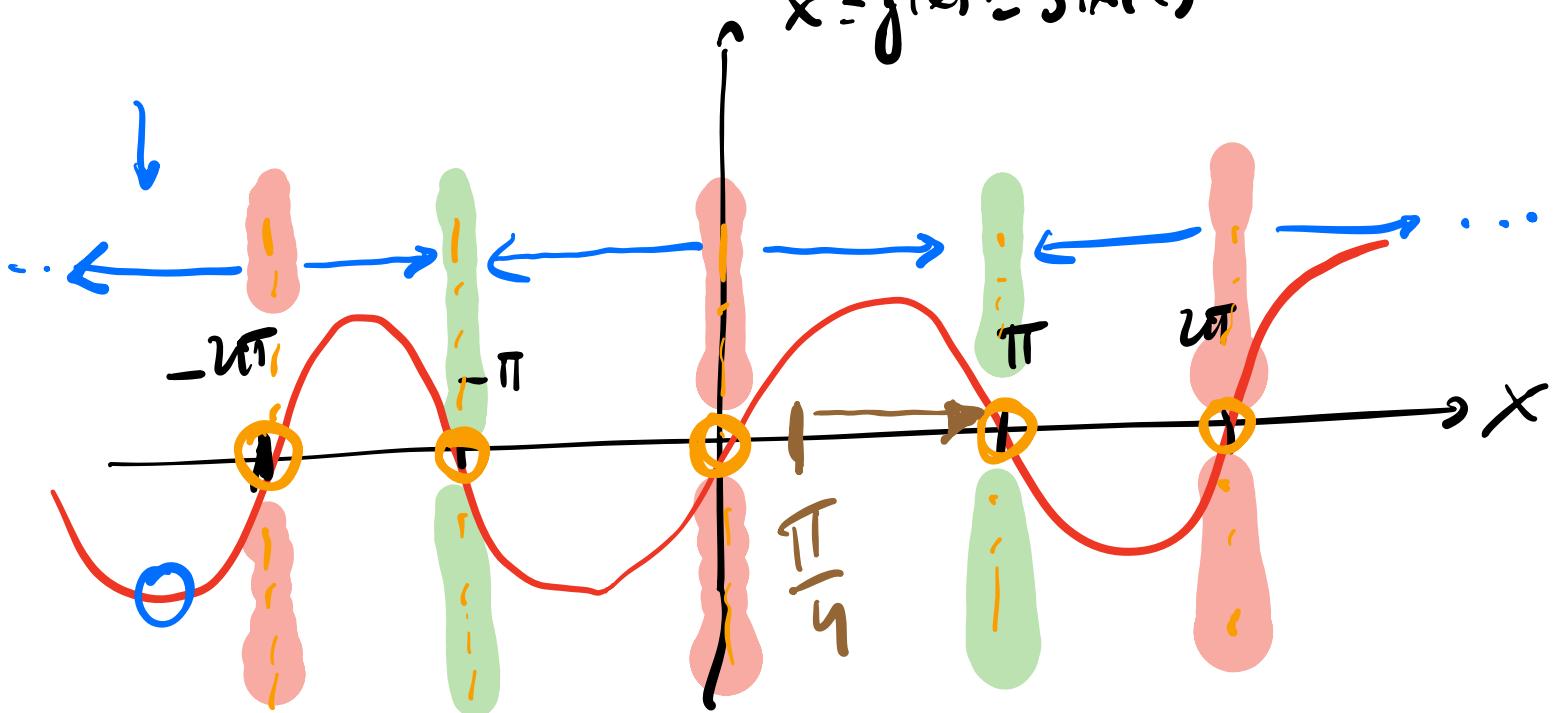


↳ $f(x) = \sin(x)$ DÉTERMINE L'ÉVOLUTION TEMPORALE DE x EN TOUT POINT.

- En x^* , $f(x^*) = a > 0$
 $\hookrightarrow \dot{x} > 0, \frac{dx}{dt} > 0, x \uparrow$
- En x^* , $f(x^*) = b < 0$
 $\hookrightarrow \dot{x} < 0, \frac{dx}{dt} < 0, x \downarrow$
- En \bar{x} , $f(\bar{x}) = 0$
 $\hookrightarrow \dot{x} = 0, \frac{dx}{dt} = 0, x \longrightarrow$
 EQUILIBRE / POINT FIXE.

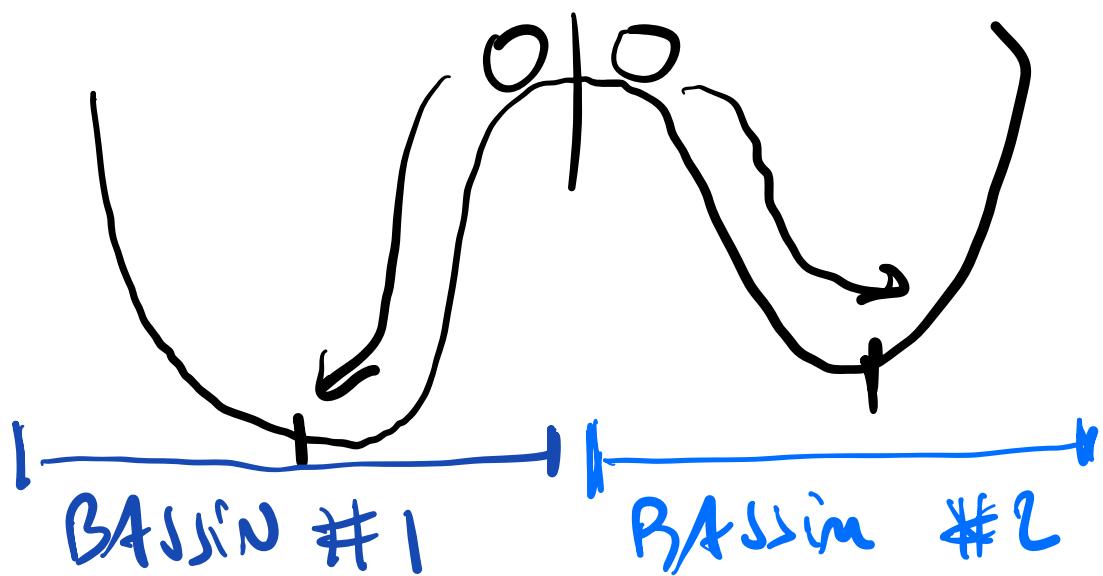
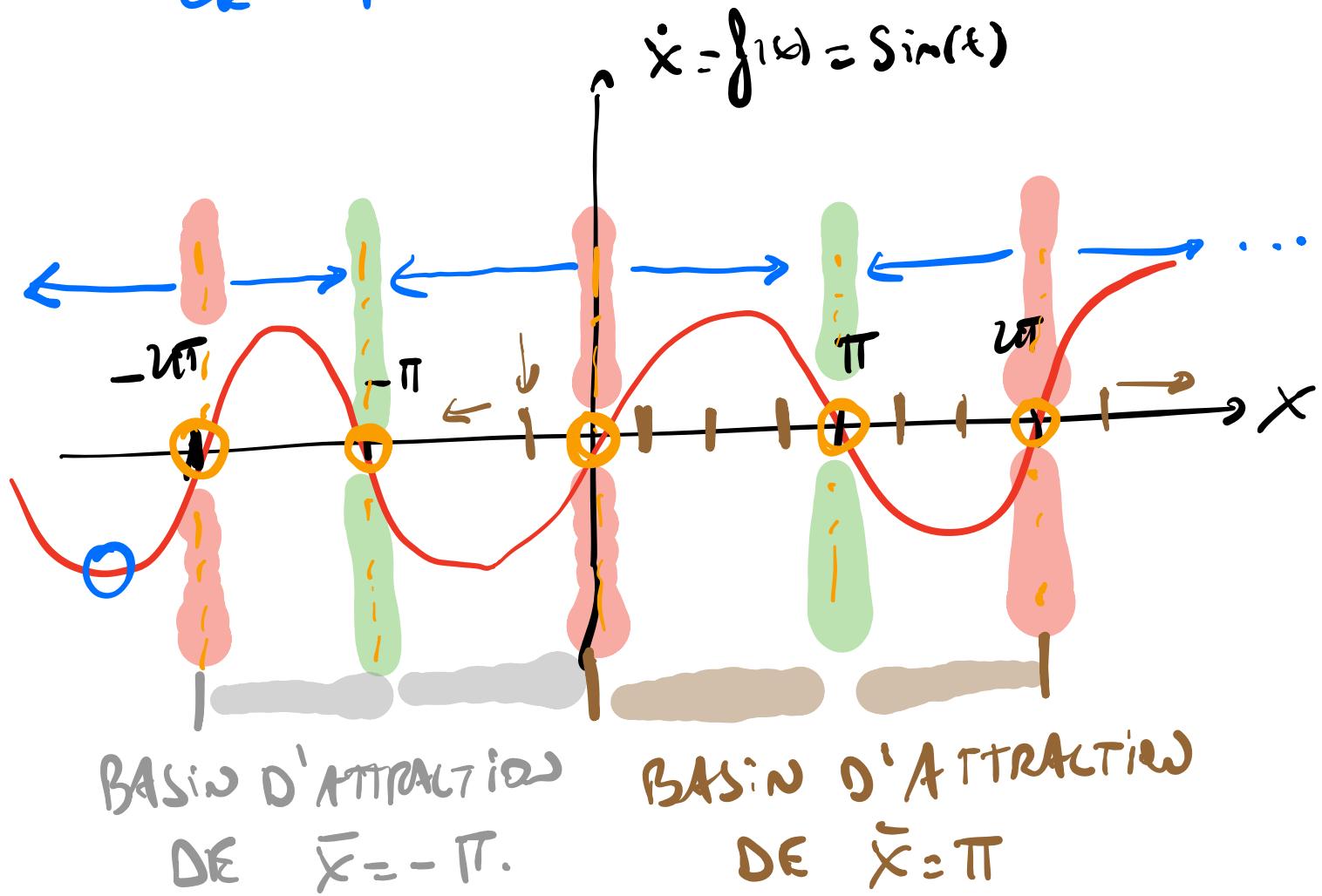
ANALYSE DU PORTRAIT DE PHASE

$$\dot{x} = f(x) = \sin(x)$$

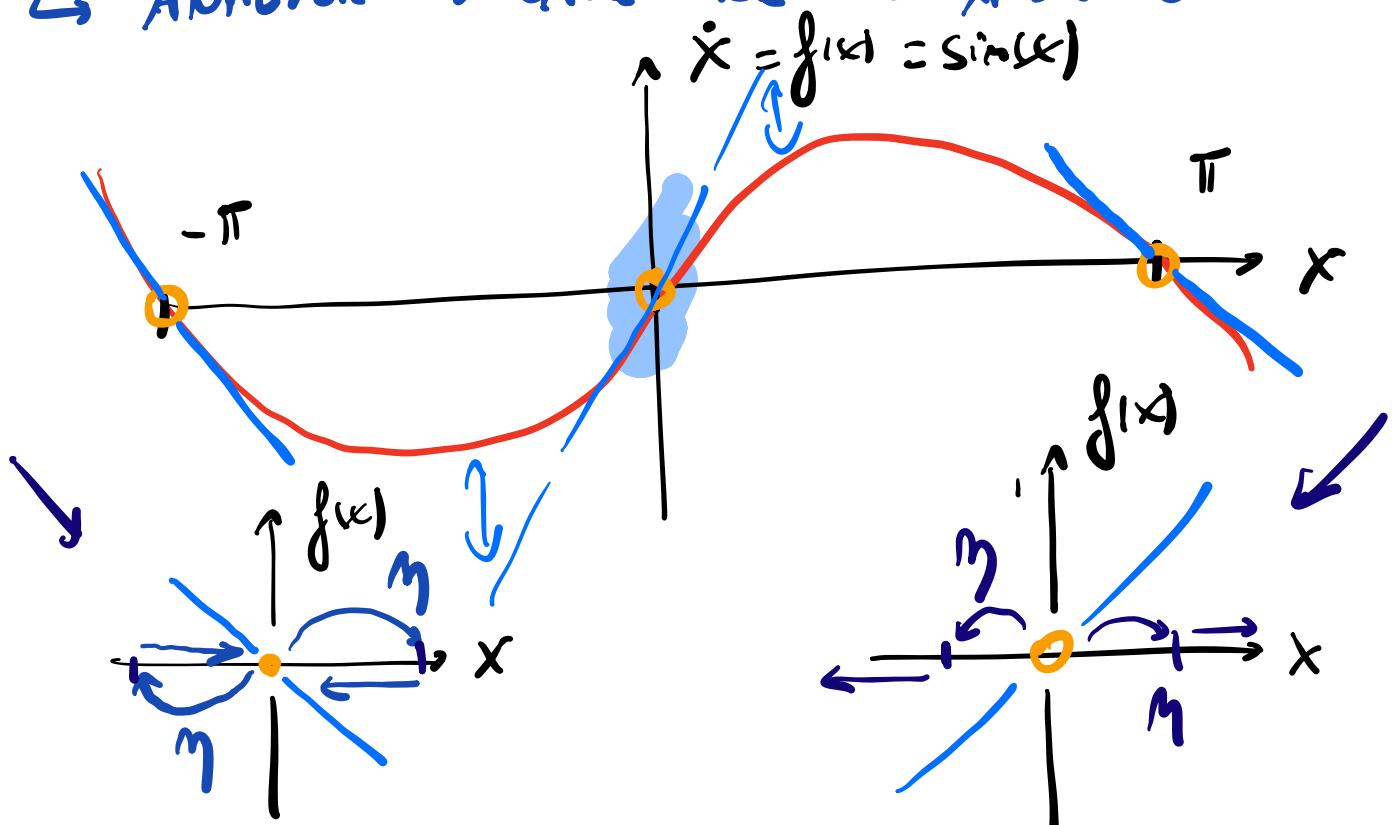


↪ POUR TOUTE C.I.? BASSIN D'ATTRACTION
[D'UN POINT FIXE STABUE]

≡ LES C.I. QUI VONT CONVERGER VERS
CE POINT.



↳ ANALYSE LOCALE DE STABILITÉ.



⇒ PENTE < 0
→ STABLE!

⇒ PENTE > 0
→ INSTABLE!

$$\text{PENTE } f'(x) \Big|_x$$

↳ LINÉARISATIONS!

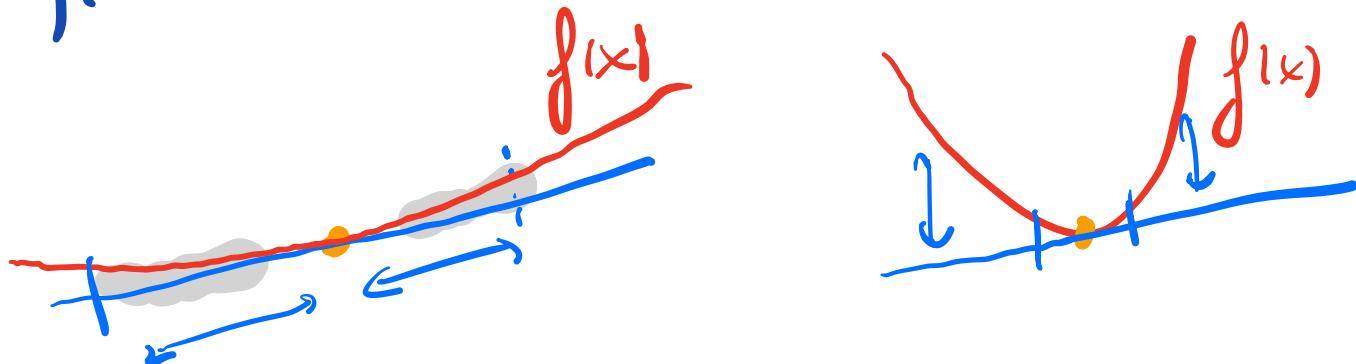
LOCAL!

AUTOUR D'UN POINT!

LINEARISATION AUTOUR DE \bar{x} :

↳ Si \bar{x} : POINT FIXE ET $\gamma(t) = \underline{x(t) - \bar{x}}$

$\gamma(t)$: PETITE PERTURBATION AUTOUR DE \bar{x} .



Ⓐ ↳ $\dot{\gamma} = \frac{d}{dt}(x - \bar{x}) = \frac{dx}{dt} = f(x) = f(\bar{x} + \gamma)$

→ EXPANSION DE TAYLOR

Ⓑ $f(\bar{x} + \gamma) \simeq f(\bar{x}) + \gamma \cdot \frac{\partial f(\bar{x})}{\partial x} + O(\gamma^2)$

\simeq TERME DOMINANT

Si γ PETIT

$\frac{\partial f(\bar{x})}{\partial x}$

PENTE DE $f(x)$ EVALUÉ EN $\bar{x} = a$

$\dot{\gamma} = f(\bar{x} + \gamma) \simeq \gamma \cdot \frac{\partial f(\bar{x})}{\partial x}$

$\simeq \gamma \cdot a$

$$\rightarrow \dot{\gamma} = \alpha \cdot \gamma \quad ; \quad \alpha = \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}}$$

PARAMÈTRE.

$$\hookrightarrow \dot{\gamma} = f(\gamma) \text{ où } f(\gamma) = \alpha \cdot \gamma$$

→ LINÉAIRE.

$$\left. \begin{array}{l} \dot{\gamma} = \alpha \cdot \gamma \\ \gamma(0) = \gamma_0 \end{array} \right. ; \quad \alpha = \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}}$$

$$\hookrightarrow \gamma(t) = \gamma_0 e^{\alpha t}$$

at $\begin{cases} \alpha > 0 \\ \alpha < 0 \end{cases} \rightarrow \begin{cases} \text{Exp} \\ \text{Exp} \end{cases}$

$$! \alpha = 0 ? \rightarrow \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}} = 0$$

DOMINANT
Si $\alpha = 0$!

$$\hookrightarrow f(\bar{x} + \gamma) \approx \underbrace{f(\bar{x})}_{=0} + \gamma \cdot \left. \frac{\partial f(x)}{\partial x} \right|_{\bar{x}} + O(\gamma^2)$$

