Static Analysis by Abstract Interpretation and Decision Procedures

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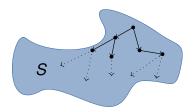
Static Analysis

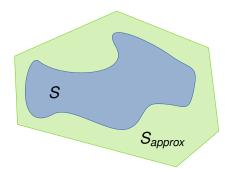
Objective:

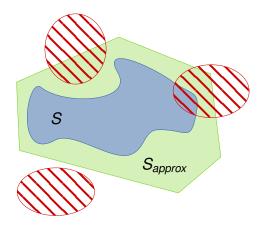
- Discover properties on programs (invariants)
- Find possible bugs, or prove their absence.

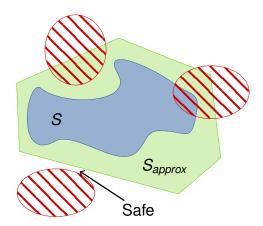
Principle:

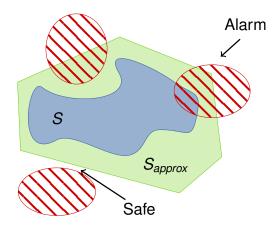
Statically compute a set containing the reachable states of the program.

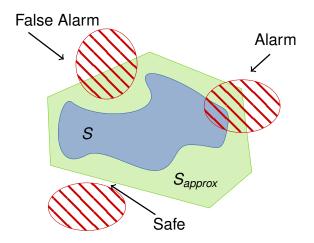












Example - PAGAI Screenshot

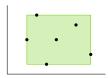
```
File Edit View Search Terminal Help
t cat example.c
                                                  ± pagai -i example.c
#include "../../pagai assert.h"
                                                  // analysis: Alopt
                                                  /* processing Function main */
int input();
                                                  #include "../../pagai assert.h"
int main()
                                                 int input();
 int x=1; int y=1;
                                                  int main()
 while(input()) {
   int t1 = x:
                                                   int x=1; int y=1;
                                                   /* reachable */
   int t2 = v;
   x = t1 + t2:
                                                   while(/* invariant:
   y = t1 + t2;
                                                         -x+v = 0
                                                         2147483647-x >= 0
                                                         -1+x >= 0
 assert(y >= 1);
 return 0;
                                                         input()) {
                                                     int t1 = x;
                                                     int t2 = y;
                                                     // unsafe: possible undefined behavior
                                                     x = t1 + t2:
                                                     // safe
                                                     v = t1 + t2;
                                                   /* assert OK */
                                                   assert(y >= 1);
                                                   /* reachable */
                                                   return 0:
```

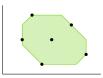
Summary

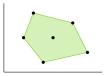
- Introduction
- Improving Abstract Interpretation using SMT
- Modular Static Analysis
- 4 The PAGAI Static Analyzer
- 5 Application: Worst-Case Execution Time (WCET) estimation

Cousot & Cousot 1977

Abstract domain to represent sets of states:







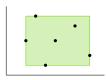
Intervals:
$$\pm x \leq C$$

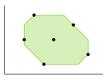
Octagons:
$$\pm x \pm y \leq C$$

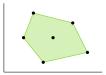
Convex Polyhedra:
$$\sum \alpha_i x_i \leq C$$

Cousot & Cousot 1977

Abstract domain to represent sets of states:







Intervals:
$$\pm x < C$$

Octagons:
$$\pm x \pm y \leq C$$

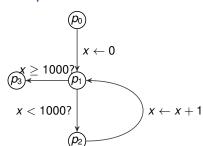
Convex Polyhedra:
$$\sum \alpha_i x_i \leq C$$

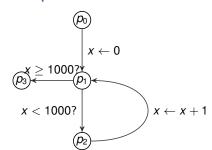
⇒ Over-approximation of the set of states

Summary

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```
x = 0;
while (x < 1000)
{
    x++;
}</pre>
```

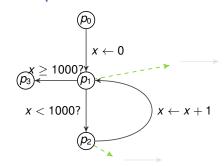




$$X_1 = \{x \mid x = 0 \lor \exists x' \in X_2, x = x' + 1\}$$

 $X_2 = \{x \mid x \in X_1 \land x < 1000\}$

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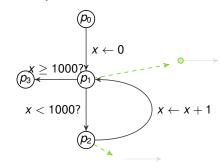


- All abstract values initialized to Ø
- Update until the ⊆ is correct

$$X_1 = \{x \mid x = 0 \lor \exists x' \in X_2, x = x' + 1\} \subseteq \emptyset$$

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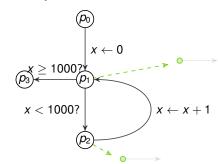


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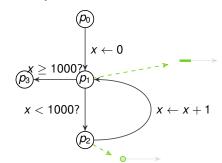


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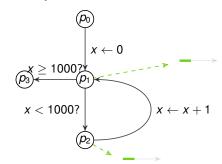


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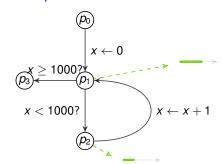
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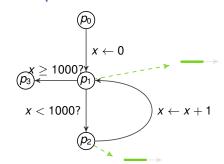
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$$X_1 = \{x \mid x = 0 \lor \exists x' \in X_2, x = x' + 1\} \subseteq [0, 2]$$

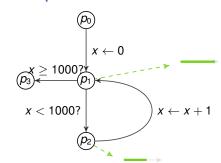
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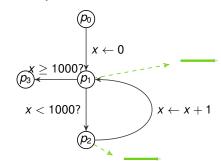


- All abstract values initialized to Ø
- Update until the ⊆ is correct

$$X_1 = \{x \mid x = 0 \lor \exists x' \in X_2, x = x' + 1\} \subseteq [0, 3]$$

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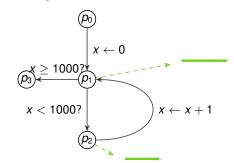
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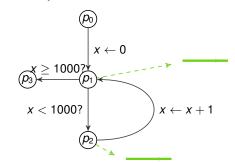
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- All abstract values initialized to Ø
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$$X_1 = \{x \mid x = 0 \lor \exists x' \in X_2, x = x' + 1\} \subseteq [0, 4]$$

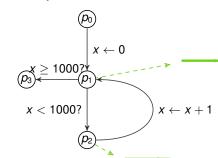
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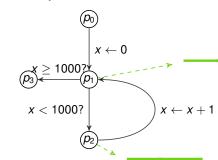
Fixpoint computation:

- All abstract values initialized to Ø
- Update until the \subseteq is correct

WIDENING

$$X_1 = \{x \mid x = 0 \lor \exists x' \in X_2, x = x' + 1\} \subseteq [0, +\infty[$$

 $X_2 = \{x \mid x \in X_1 \land x < 1000\} \subseteq [0, 4]$



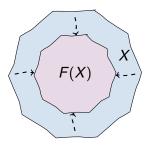
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Narrowing

An inductive invariant has been found: $F(X) \subseteq X$, we can recover precision by iterating once more:

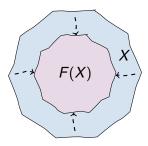


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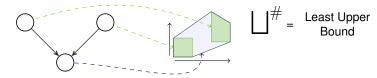
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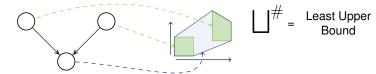
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In this thesis

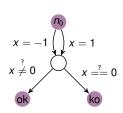
Improve precision of the analysis by limiting the bad effects of widenings and least upper bounds

Summary

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- Improving Abstract Interpretation using SMT
- Modular Static Analysis
- The PAGAI Static Analyzer
- 5 Application: Worst-Case Execution Time (WCET) estimation

Example

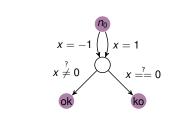
```
if (input())
    x = 1;
else
    x = -1;
    // (here)
if (x == 0)
    abort();
else
    OK();
```

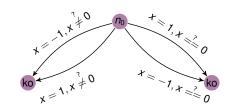


- x can be 1 or -1
- Least upper bound yields $x \in [-1, 1]$ at point (here)
- if (x == 0) seems feasible with traditional Al

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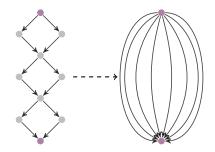




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Path Focusing (Monniaux & Gonnord SAS11)

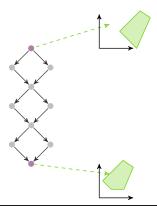
Idea: delay control-flow merges



- Expand and distinguish every paths inside loops
- Abstraction only at the loop headers
- Succinctly represent the set of paths using a logical formula (SMT)

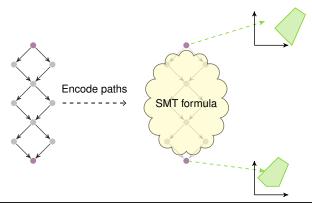
Algorithm: update an abstract value X until it becomes an inductive invariant: $F(X) \subseteq X$.





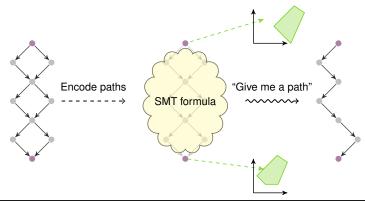
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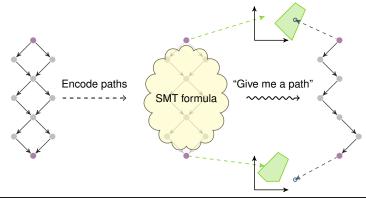
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Using SMT-solving for Choosing Paths

SMT formula ρ expressing the semantics of the program paths:

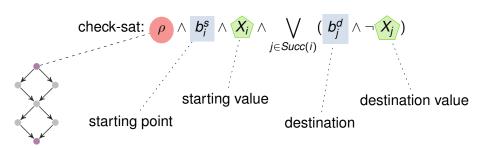
- Control-Flow encoded using Booleans
- Over-approximation of the instructions semantics in LIRA

Using SMT-solving for Choosing Paths

SMT formula ρ expressing the semantics of the program paths:

- Control-Flow encoded using Booleans
- Over-approximation of the instructions semantics in LIRA

"Does there exist a path starting inside the candidate invariant, that goes to a state outside the candidate invariant?"



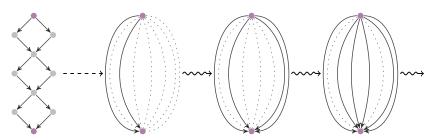
SAS'12: "Succinct Representations for Abstract Interpretation"

Imprecision due to widening spreads



Apply narrowing **before** it is too late

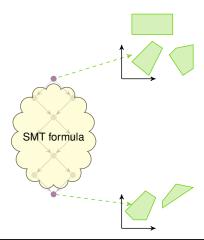
 \rightarrow before an invariant for the entire program is found



Compute **precise** invariants for a sequence of subprograms

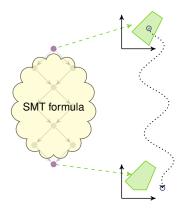
Extensions:

Disjunctive Invariants



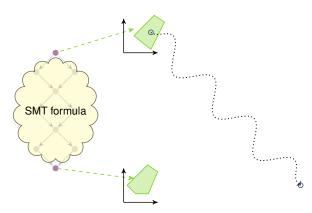
Extensions:

- Disjunctive Invariants
- 2 "Interesting traces" far from the current abstract value



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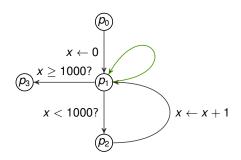
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Improve the Decreasing Sequence (Halbwachs & Henry)

SAS'12: "When the Decreasing Sequence Fails"

Decreasing sequence does not always work



$$X_1 = \{x \mid x = 0 \lor \exists x' \in X_2, x = x' + 1 \lor x \in X_1\} \subseteq [0, +\infty)$$

 $X_2 = \{x \mid x \in X_1 \land x < 1000\} \subseteq [0, 999]$

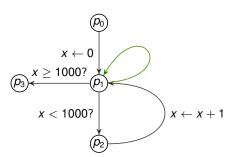
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Restart an analysis from a different, **well chosen**, initial value



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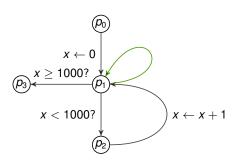
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Summary

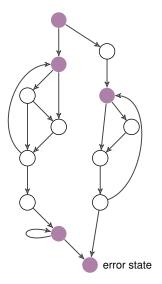
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Incremental Analysis

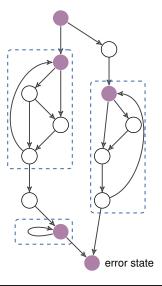
- Abstract Interpretation can be parametrized in many ways
- From very cheap to very expensive techniques/abstract domains



Run cheap techniques first, and refine program portions if needed

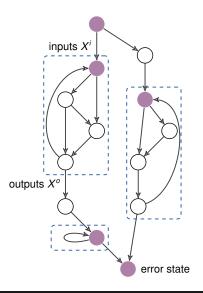


Complicated CFG



Select blocks/portions to be abstracted:

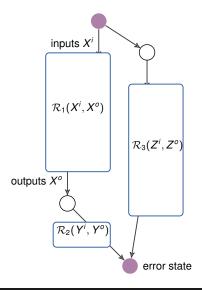
- Loops,
- Function calls,
- Complicated program portions



Select blocks/portions to be abstracted:

- Loops,
- Function calls,
- Complicated program portions

Each block has input and output variables

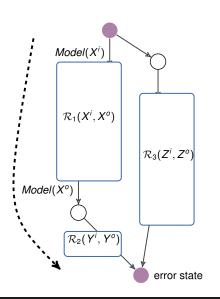


Abstract each block by a logical formula.

 $\mathcal{R}_1(X^i,X^o)$ is a formula involving inputs and outputs

Example: $x^i > 0 \Rightarrow x^o = x^i + 1$

Initialized to true (= safe over-approximation)

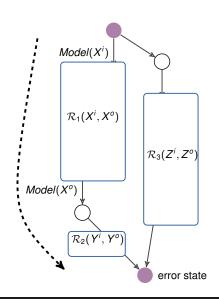


SMT query:

"Is there a path to the error state?"

$$Model(X^i) \land Model(X^o) \land \mathcal{R}_1(X^i, X^o)$$

is SAT

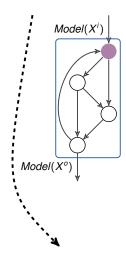


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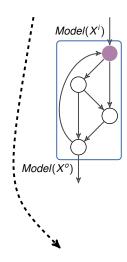
$$Model(X^{i}) \land Model(X^{o}) \land \mathcal{R}_{1}(X^{i}, X^{o})$$
 is SAT

 \rightarrow Improve precision of $\mathcal{R}_1(X^i, X^o)$ s.t. above formula becomes UNSAT



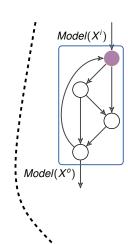
Compute a new relation for the block, with the knowledge of the input context $Model(X^i)$

Of the form: $Model(X^i) \Rightarrow \mathcal{F}(X^i, X^o)$



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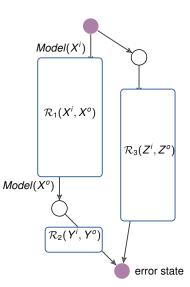
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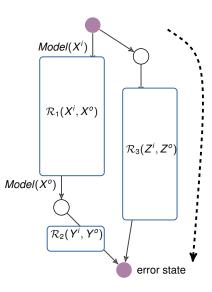
Generalize the valid context during analysis:

$$C(X^i) \Rightarrow \mathcal{F}(X^i, X^o)$$

Model $(X^i) \Rightarrow C(X^i)$

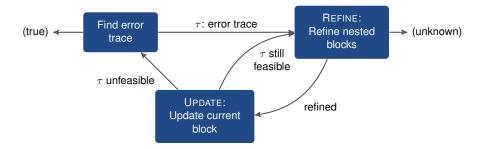


Continue and search for new error trace



Continue and search for new error trace

Modular Static Analysis: Overview



Summary

- The PAGAI Static Analyzer

PAGAI, in one slide

TAPAS'12: "PAGAI: a path sensitive static analyser"

Static analyzer for LLVM IR, written in C++, > 20.000 LOC

- Most of the techniques described here are implemented
- PAGAL checks:
 - array out-of-bounds
 - integer overflows
 - assert statements
- Handles real C programs & SV-Comp benchmarks
- Already used outside Verimag

Comparisons of Various Techniques

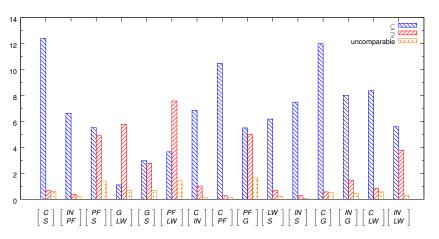
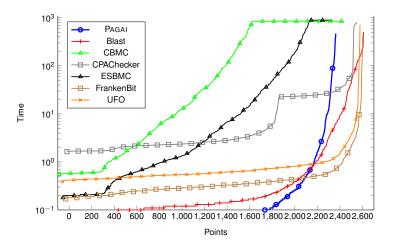


Figure: Malärdalen benchmarks

http://www.mrtc.mdh.se/projects/wcet/benchmarks.html

Software-Verification Competition



Summary

- Application: Worst-Case Execution Time (WCET) estimation

Target: Reactive Control Systems



1 "big" infinite loop

 \sim Loop-free body

Goal: WCET for 1 loop iteration < some bound

Our Method

LCTES'14: "How to Compute Worst-Case Execution Time by Optimization Modulo Theory and a Clever Encoding of Program Semantics"

Input:

- Loop-free control-flow graph of the loop body
- timings for basic blocks (# clock cycles)
 - given by an external tool, e.g. OTAWA
 - runs a panel of static analysis, considering micro-architecture

Principle: Encode the problem into SMT and optimize a cost function

Output:

WCET for the entire CFG + Worst Case path

Optimization modulo Theory:

We search for the trace maximizing the variable cost.

Using any off-the-shelf SMT solver

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Dichotomy strategy:

Maintain an interval containing the WCET

Initial interval [0, 100]

0 100

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Using any off-the-shelf SMT solver

Dichotomy strategy:

- Initial interval [0, 100]
- Is there a trace where *cost* > 50? Yes, 70



Optimization modulo Theory:

We search for the trace maximizing the variable cost.

Using any off-the-shelf SMT solver

Dichotomy strategy:

- Initial interval [0, 100]
- Is there a trace where cost > 50? Yes, 70
- new interval [70, 100]



Optimization modulo Theory:

We search for the trace maximizing the variable cost.

Using any off-the-shelf SMT solver

Dichotomy strategy:

- Initial interval [0, 100]
- Is there a trace where *cost* > 50? Yes, 70
- new interval [70, 100]
- Is there a trace where cost > 85? No



Optimization modulo Theory:

We search for the trace maximizing the variable cost.

Using any off-the-shelf SMT solver

Dichotomy strategy:

- Initial interval [0, 100]
- Is there a trace where cost > 50? Yes, 70
- new interval [70, 100]
- Is there a trace where cost > 85? No
- new interval [70,85]



Optimization modulo Theory:

We search for the trace maximizing the variable cost.

Using any off-the-shelf SMT solver

Dichotomy strategy:

Maintain an interval containing the WCET

- Initial interval [0, 100]
- Is there a trace where cost > 50? Yes, 70
- new interval [70, 100]
- Is there a trace where cost > 85? No
- new interval [70,85]
- ..

100

A Really Simple Example

 b_1, \ldots, b_n unconstrained Booleans, **xi**'s and **yi**'s are the timing costs

```
if (b_1) { /*c1=2*/ } else { /*c1=3*/ } //cost c1 if (b_1) { /*c1'=3*/ } else { /*c1'=2*/ } //cost c1' ... if (b_n) { /*cn=2*/ } else { /*cn=3*/ } //cost cn if (b_n) { /*cn'=3*/ } else { /*cn'=2*/ } //cost cn'
```

"Obviously" all traces take time (3+2)n = 5n.

 b_1, \ldots, b_n unconstrained Booleans, **xi**'s and **yi**'s are the timing costs

```
if (b_1) { /*c1=2*/ } else { /*c1=3*/ } //cost c1
if (b_1) \{ /*c1' = 3*/ \} else \{ /*c1' = 2*/ \} //cost c1'
if (b_n) { /*cn=2*/ } else { /*cn=3*/ } //cost cn
if (b_n) \{ /*cn' = 3*/ \} else \{ /*cn' = 2*/ \} //cost cn'
```

"Obviously" all traces take time (3+2)n=5n.

SMT approach (using DPLL(T)) will find 5n, but in exponential time...

Why such high cost?

$$\begin{array}{l} (b_1 \Rightarrow c_1 = 2) \wedge (\neg b_1 \Rightarrow c_1 = 3) \wedge (b_1 \Rightarrow c_1' = 3) \wedge (\neg b_1 \Rightarrow c_1' = 2) \wedge \\ \cdots \wedge \\ (b_n \Rightarrow c_n = 2) \wedge (\neg b_n \Rightarrow c_n = 3) \wedge (b_n \Rightarrow c_n' = 3) \wedge (\neg b_n \Rightarrow c_n' = 2) \wedge \\ c_1 + c_1' + \cdots + c_n + c_n' > 5n \end{array}$$

A SMT-solver based on "DPLL(\mathcal{T})":

- enumerates a Boolean choice tree over b_1, \ldots, b_n
- cuts branches when encountering inconsistent numerical constraints.

What are the inconsistent numerical constraints here (**blocking clauses**)?

Take the satisfying assignment where all the b_i 's are set to true (the c_i 's = 2 and c_i 's = 3)

THEORY ATOMS

$$c_1 \leq 2$$
 $c_n \leq 2$

$$c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$$

$$\neg (c_1' \leq 2) \qquad \neg (c_n' \leq 2)$$

$$c_1' \leq 3$$
 $c_n' \leq 3$

$$c_1 + c'_1 + \cdots + c_n + c'_n > 5n$$

BLOCKING CLAUSE

Take the satisfying assignment where all the b_i 's are set to true (the c_i 's = 2 and c'_i 's = 3)

THEORY ATOMS

$$c_1 < 2$$

$$c_1 \leq 2$$
 $c_n \leq 2$

$$c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$$

$$c_n < 3$$

$$\neg (c_1' \leq 2) \qquad \neg (c_n' \leq 2)$$

$$\neg (c'_n < 2)$$

$$c_1' < 3$$

$$c_1' \leq 3$$
 $c_n' \leq 3$

$$c_1 + c'_1 + \cdots + c_n + c'_n > 5n$$

BLOCKING CLAUSE

$$c_1 < 2$$

$$c_1 \leq 2$$
 $c_n \leq 2$

$$c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$$

$$c_n < 3$$

$$\neg (c_1' \leq 2)$$
 $\neg (c_n' \leq 2)$

$$\frac{1}{1}(c_n^2 < 2)$$

$$c_1' \leq 3$$
 $c_n' \leq 3$

$$c_{n}' < 3$$

$$c_1 + c'_1 + \cdots + c_n + c'_n > 5n$$

Only cuts one single program trace...

Take the satisfying assignment where all the b_i 's are set to true (the c_i 's = 2 and c_i 's = 3)

THEORY ATOMS $c_1 \leq 2 \qquad c_n \leq 2$ $c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$ $c_1 \leq 2 \qquad \cdots \qquad c_n \leq 3$ $c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$ $c_1 \leq 2 \qquad \cdots \qquad c_n \leq 3$ $c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$ $c_1 \leq 3 \qquad c_n \leq 2$ $c_1 \leq 3 \qquad c_n \leq 3$ $c_1 \leq 3 \qquad c_n \leq 3$

Only cuts one single program trace... 2^n of them. The solver has to prove them inconsistent one by one.

Untractability Issue

SMT solvers miss "obvious" properties

```
if (b_i) { /* ci=2 */ } else { /* ci=3*/ } if (b_i) { /* ci'=3 */ } else { /* ci'=2*/ }
```

Human remark: "**obviously**, $c_i + c_i' \le 5$ "

"Normal" DPLL(T)-based SMT solvers do not invent new atomic predicates: they can't learn it...

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```

Human remark: "**obviously**, $c_i + c_i' \le 5$ "

"Normal" DPLL(T)-based SMT solvers do not invent new atomic predicates: they can't learn it...



What if we simply conjoin these predicates to the SMT formula?

Again, take the satisfying assignment where all the b_i 's are set to true (the c_i 's = 2 and c_i 's = 3)

THEORY ATOMS

$$c_1 \leq 2$$
 $c_n \leq 2$

$$c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$$

$$\neg (c_1' \leq 2) \qquad \neg (c_n' \leq 2)$$

$$c_1' \leq 3$$
 $c_n' \leq 3$

$$c_1+c_1'\leq 5 \qquad c_n+c_n'\leq 5$$

$$c_1 + c'_1 + \cdots + c_n + c'_n > 5n$$

BLOCKING CLAUSE

Again, take the satisfying assignment where all the b_i 's are set to true (the c_i 's = 2 and c'_i 's = 3)

THEORY ATOMS

$$c_1 \leq 2$$

$$c_n \leq 2$$

$$c_1 \leq 3$$
 \cdots $c_n \leq 3$

$$c_n \leq 3$$

$$\neg (c_1' \leq 2) \qquad \neg (c_n' \leq 2)$$

$$c_1' \leq 3$$
 $c_n' \leq 3$

$$c_1 + c_2' < 5$$

$$c_1+c_1'\leq 5 \qquad c_n+c_n'\leq 5$$

$$c_1 + c'_1 + \cdots + c_n + c'_n > 5n$$

BLOCKING CLAUSE

$$\alpha < 2$$

$$c_1 < 2$$
 $c_n < 2$

$$c_1 \leq 3 \qquad \cdots \qquad c_n \leq 3$$

$$\neg (c_1' \leq 2) \qquad \neg (c_n' \leq 2)$$

$$c_1 \leq 3$$
 $c_2 \leq 3$

$$c_1 + c_1' < 5$$

$$c_1 + c_1' \le 5$$
 $c_n + c_n' \le 5$

$$c_1 + c'_1 + \cdots + c_n + c'_n > 5n$$

Prunes all the 2ⁿ traces at once.

Solution

- Distinguish "portions" in the program.
- Compute upper bound B_i on WCET for each portion i (recursive call or rougher bound)
- Conjoin these constraints to the previous SMT formula $c_1 + \cdots + c_5 < B_1$, $c_6 + \cdots + c_{10} < B_2$, etc.
- The obtained formula is equivalent
- Do the binary search as before

Solving time from "nonterminating after one night" to "a few seconds".

Experiments with ARMv7

OTAWA for Basic Block timings Z3 SMT solver

Cuts: only syntactic criterion

	WCET bounds (#cycles)			Analysis time (seconds)		
Benchmark name	ILP IPET	SMT	diff	with cuts	no cuts	#cuts
statemate	3297	3211	2.6%	943.5	+∞	143
nsichneu (1 iteration)	17242	13298	22.7%	6hours	$+\infty$	378
cruise-control	881	873	0.9%	0.1	0.2	13
digital-stopwatch	1012	954	5.7%	0.6	2104.2	53
autopilot	12663	5734	54.7%	1808.8	$+\infty$	498
fly-by-wire	6361	5848	8.0%	10.8	$+\infty$	163
miniflight	17980	14752	18.0%	40.9	$+\infty$	251
tdf	5789	5727	1.0%	13.0	$+\infty$	254

- Malardalen WCET Benchmarks
- Scade designs
- Industrial Code

Conclusion

SMT can be used for static analysis in many ways:

- Improve precision of abstract interpreters (least upper bounds)
- Find program traces that violate some property
- Counter-Example Guided approaches
- Worst-Case Execution Time estimation using optimization

PAGAI static analyzer for LLVM IR, open-source

- Checks array out-of-bounds & integer overflows
- Proves assert statements over numerical variables
- Binaries for Linux/Mac and source code:

http://pagai.forge.imag.fr