

# Real-life reinforcement learning

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# Types of Machine Learning

## Supervised learning

- Run an algorithm on a **labeled data set**.
- The model learns how to correctly predict the right answer.
- Regression and classification are examples of supervised learning.

## Unsupervised learning

- Run an algorithm on an **unlabeled data set**.
- The model learns patterns and organizes samples accordingly.
- Clustering and topic modeling are examples of unsupervised learning.

# Building a dataset is not always an option

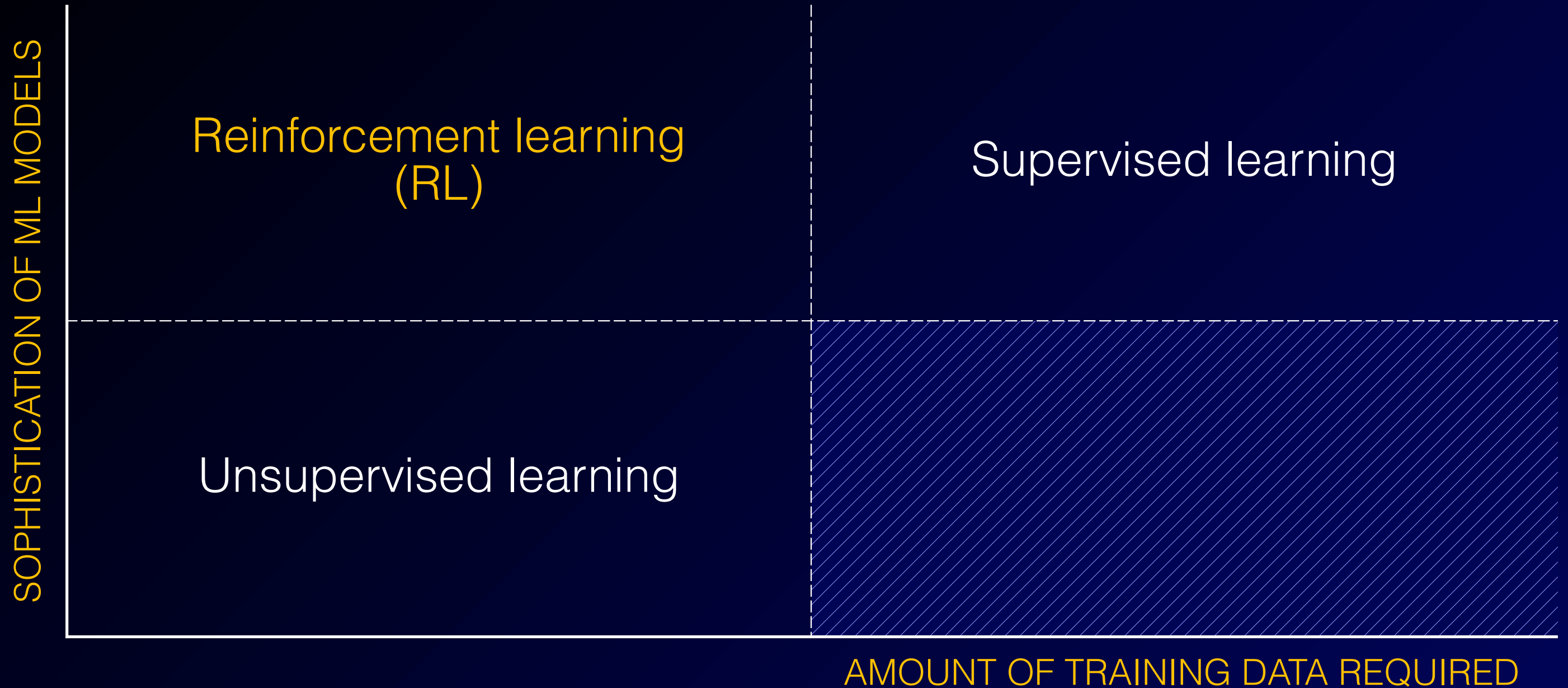
Large, complex problems

Uncertain, chaotic environments

Continuous learning

Supply chain management, HVAC systems, industrial robotics, autonomous vehicles, portfolio management, oil exploration, etc.

# Types of Machine Learning

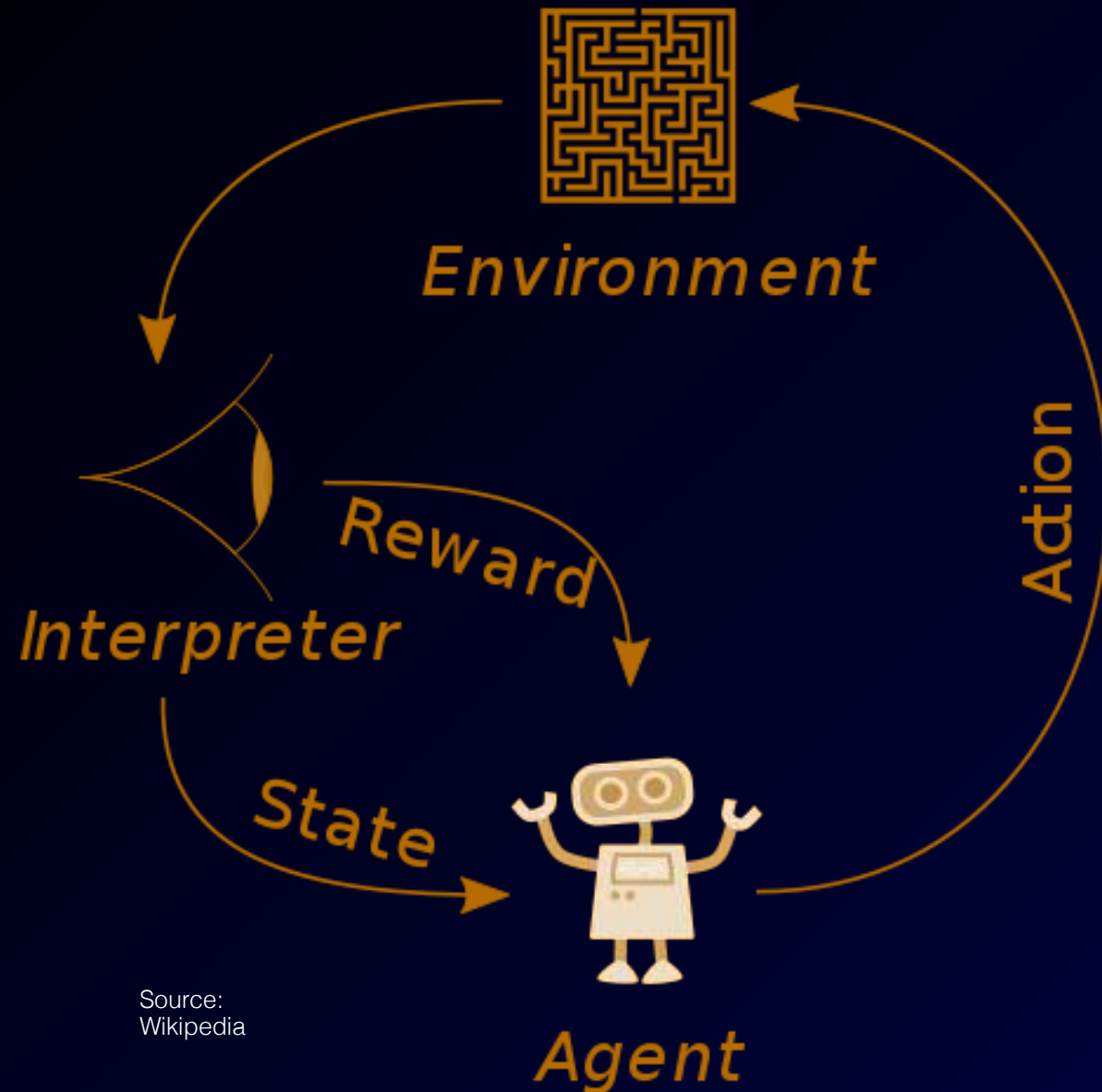




# Learning without any data: we've all done it!



# Reinforcement Learning



Source:  
Wikipedia

An **agent** interacts with its **environment**.

The agent receives positive or negative **rewards** for its actions: rewards are computed by a **user-defined function** which outputs a numeric representation of the actions that should be incentivized.

By trying to **maximize the accumulation of rewards**, the agent learns an optimal strategy (aka **policy**) for decision making.

# Learning to walk

[https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement\\_learning/rl\\_robot\\_school\\_ray](https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement_learning/rl_robot_school_ray)

# The players

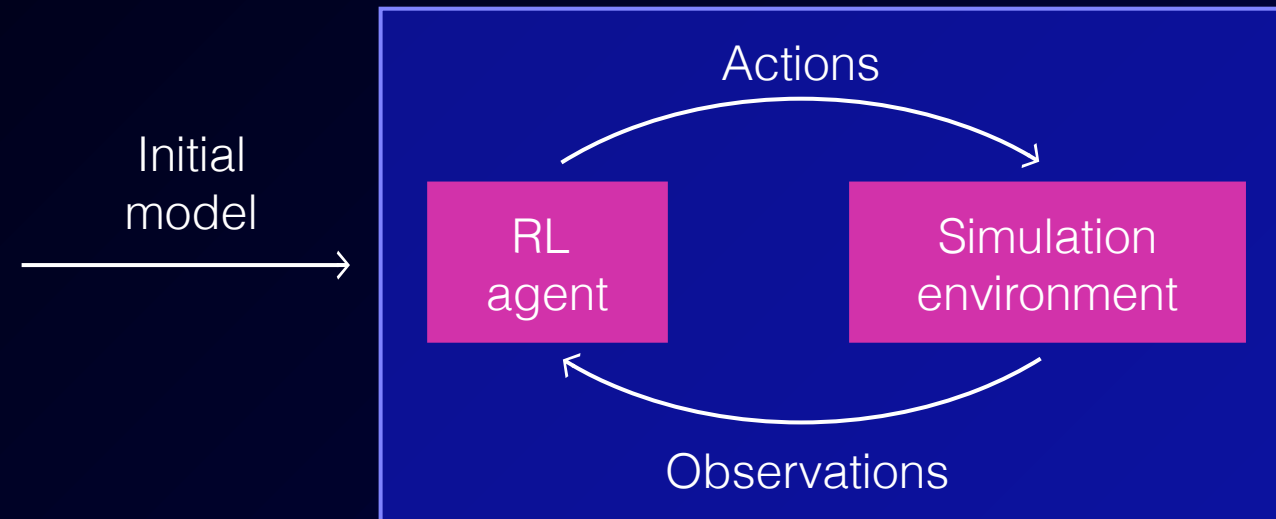




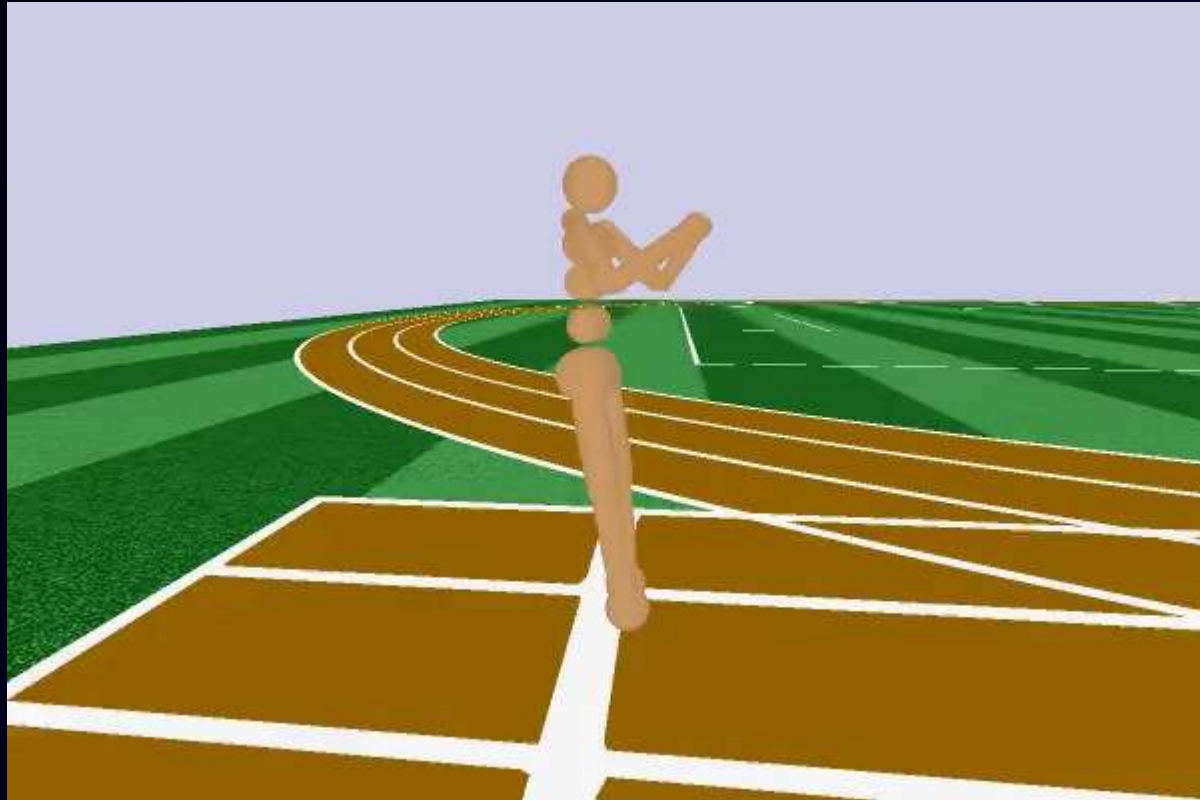
# At first, the agent can't even stand up



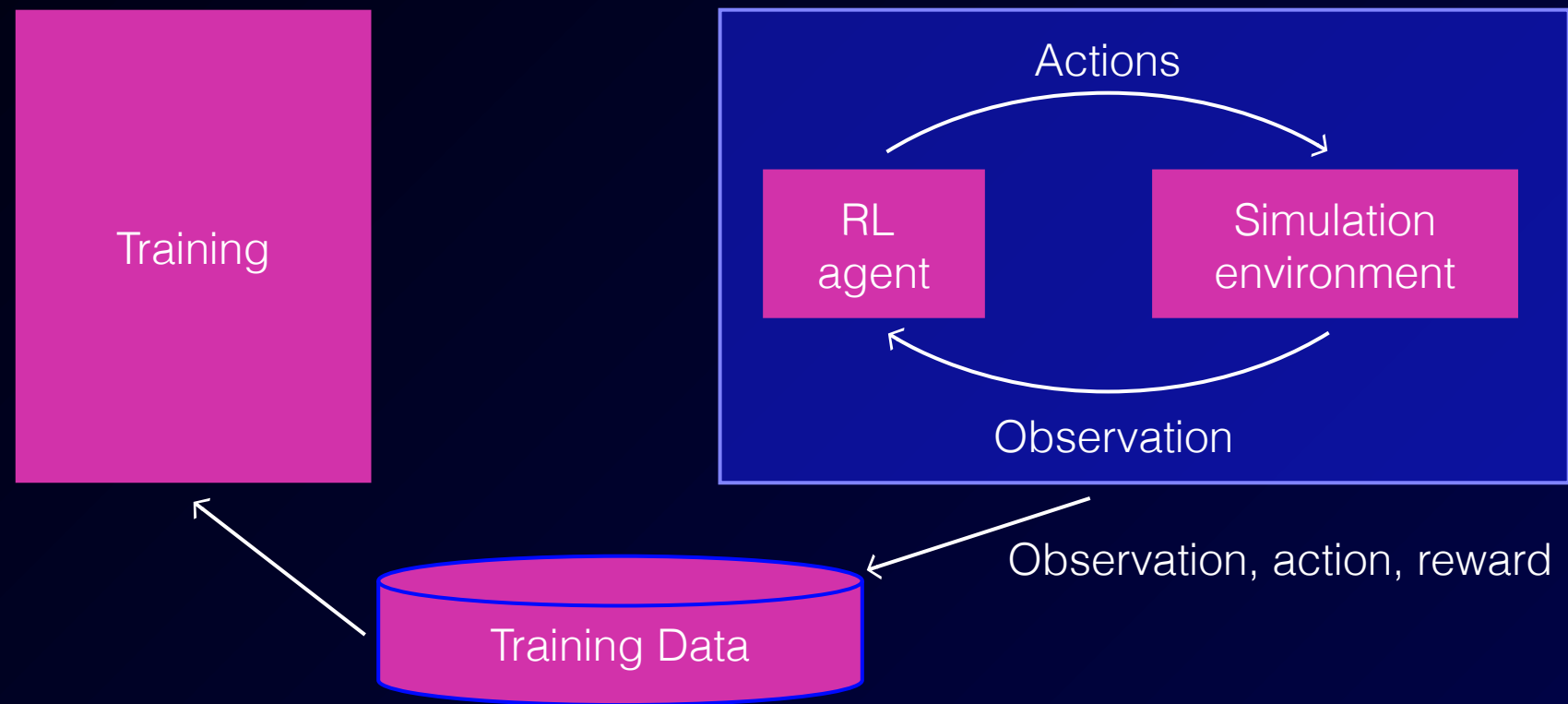
# Actions and observations



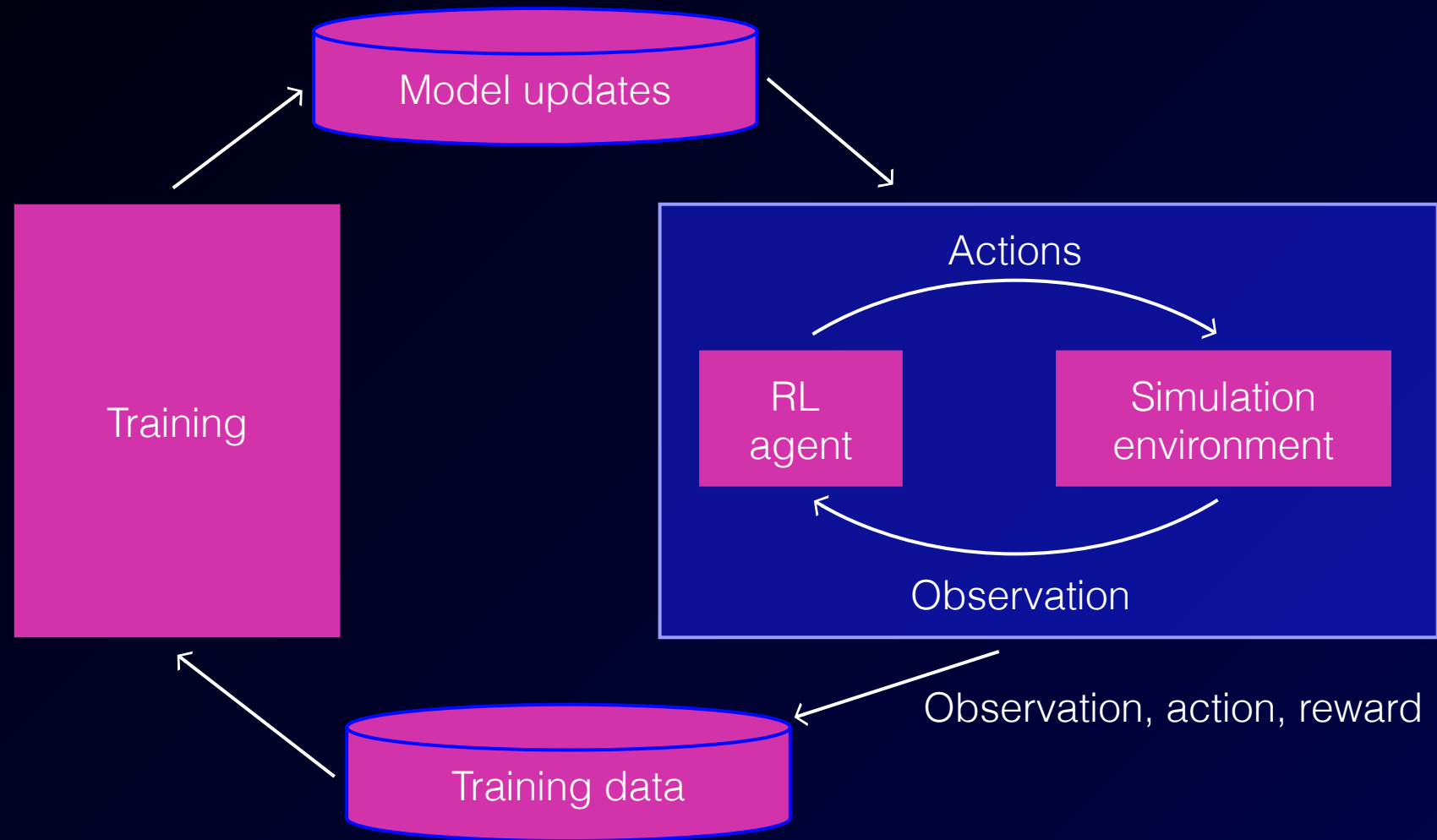
# The model learns through actions and observations



# Interactions generate training data



# Training results in model updates

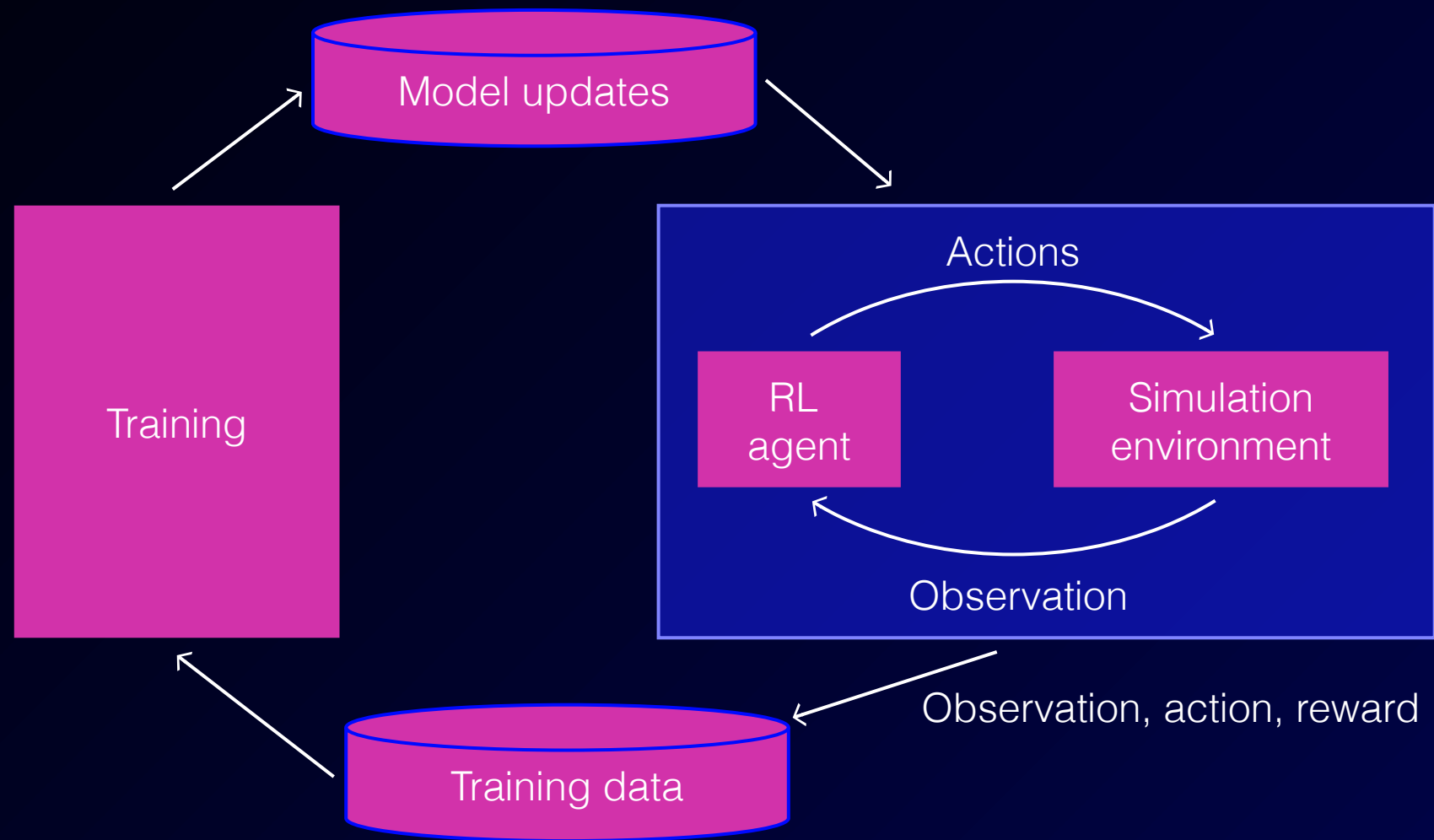




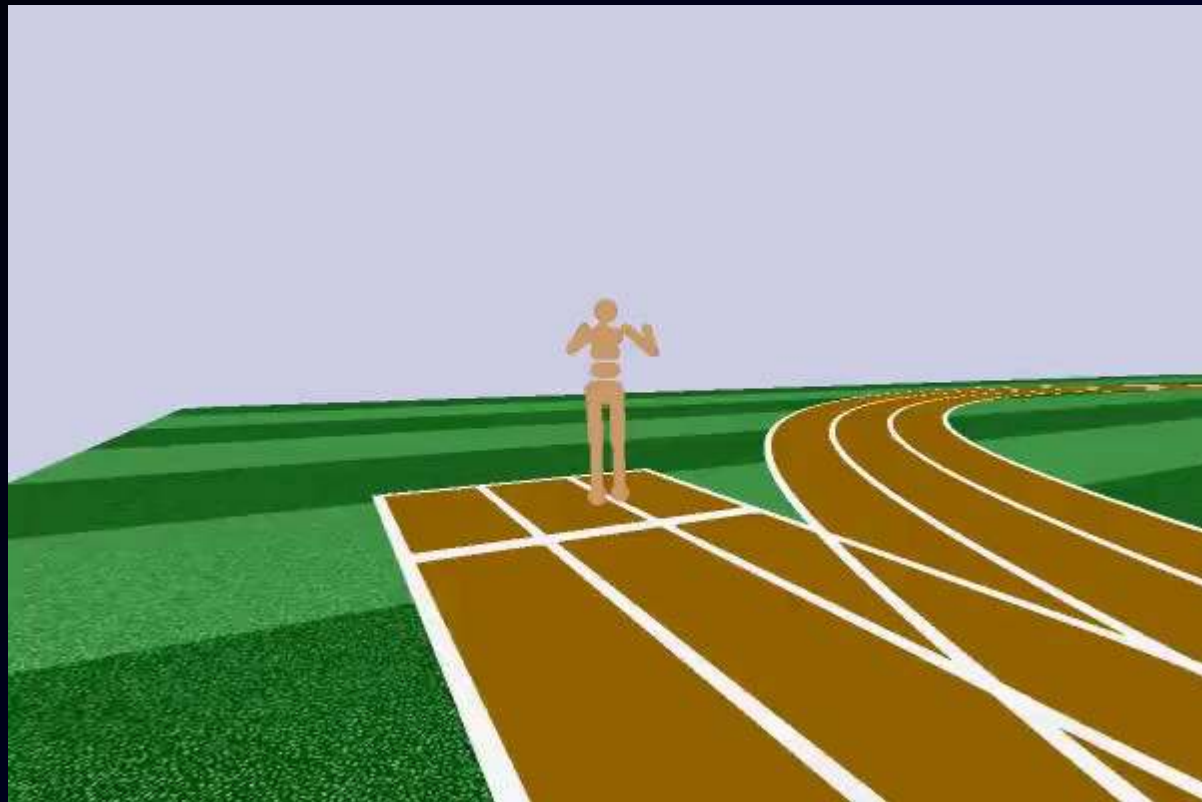
# The agent learns to stand and step



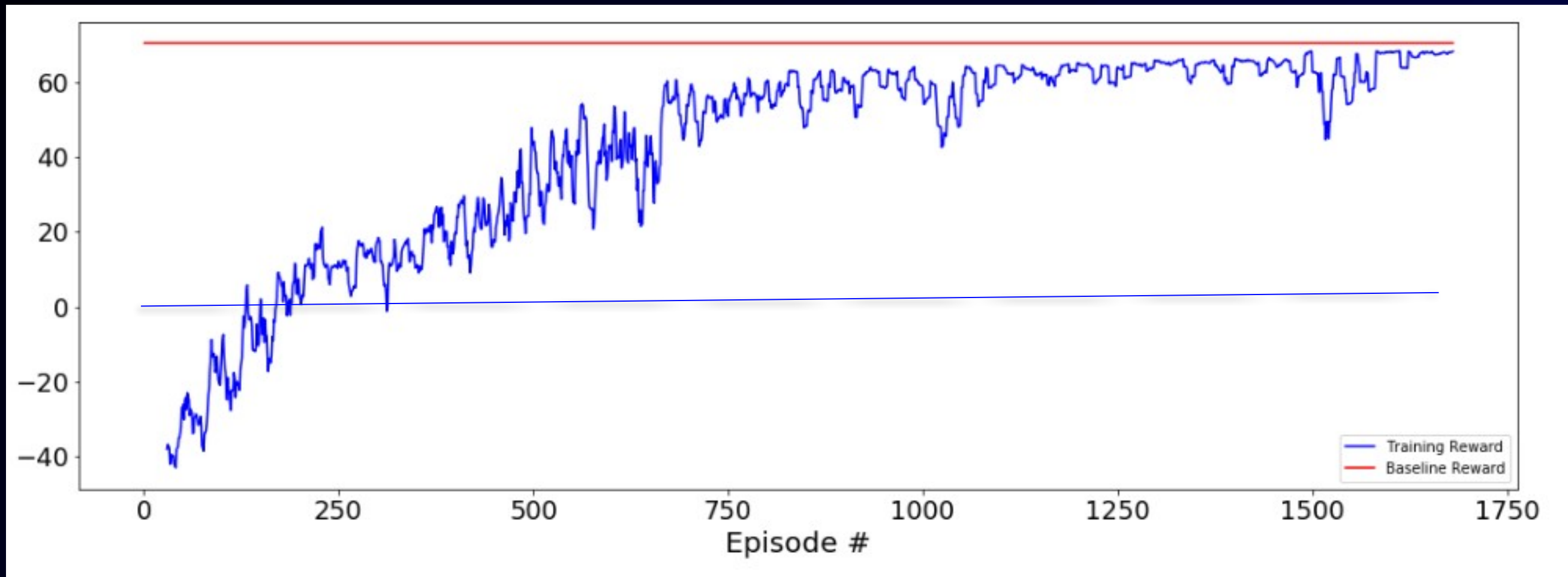
# Multiple training episodes improve learning



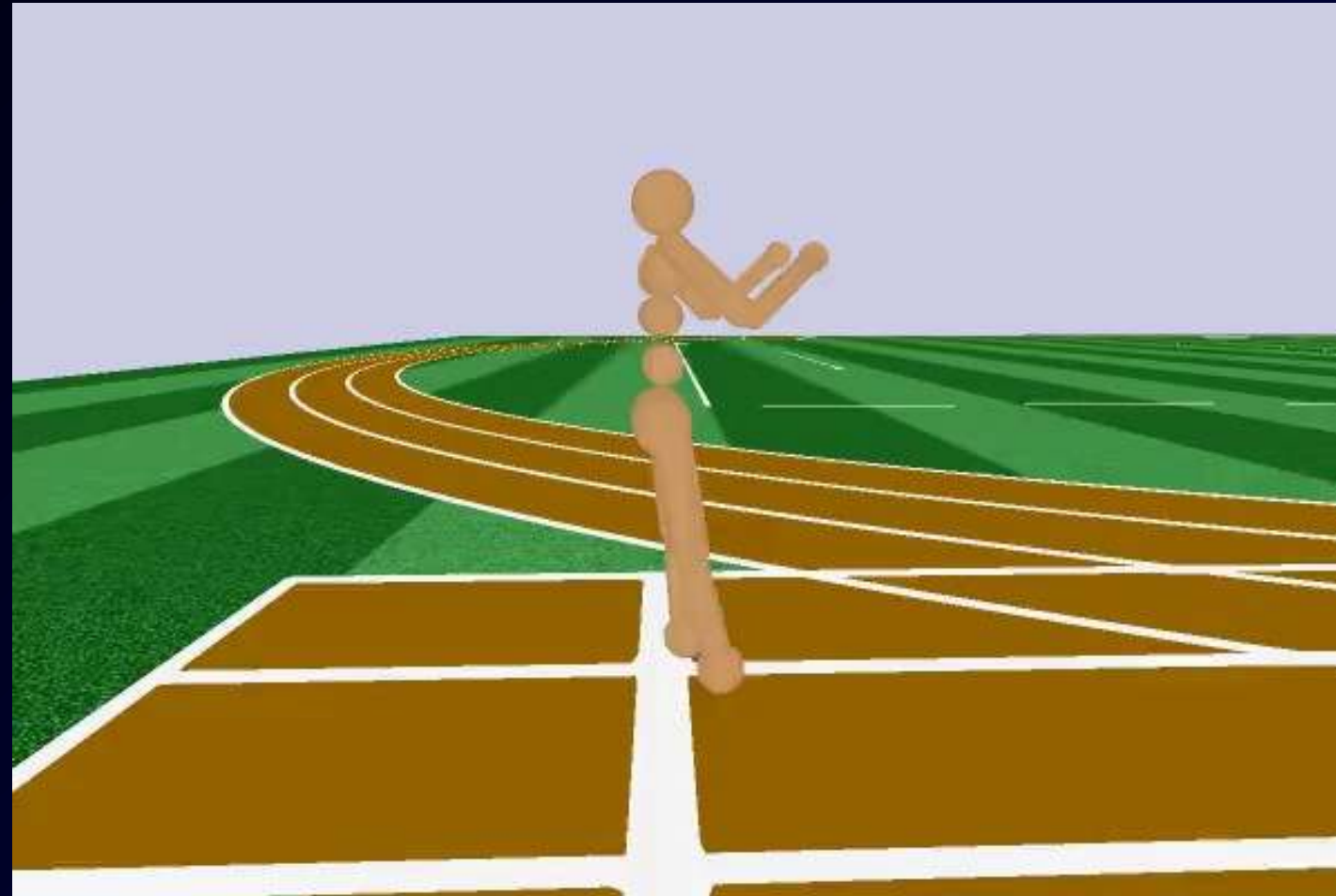
# Making progress



# RL agents try to maximize rewards

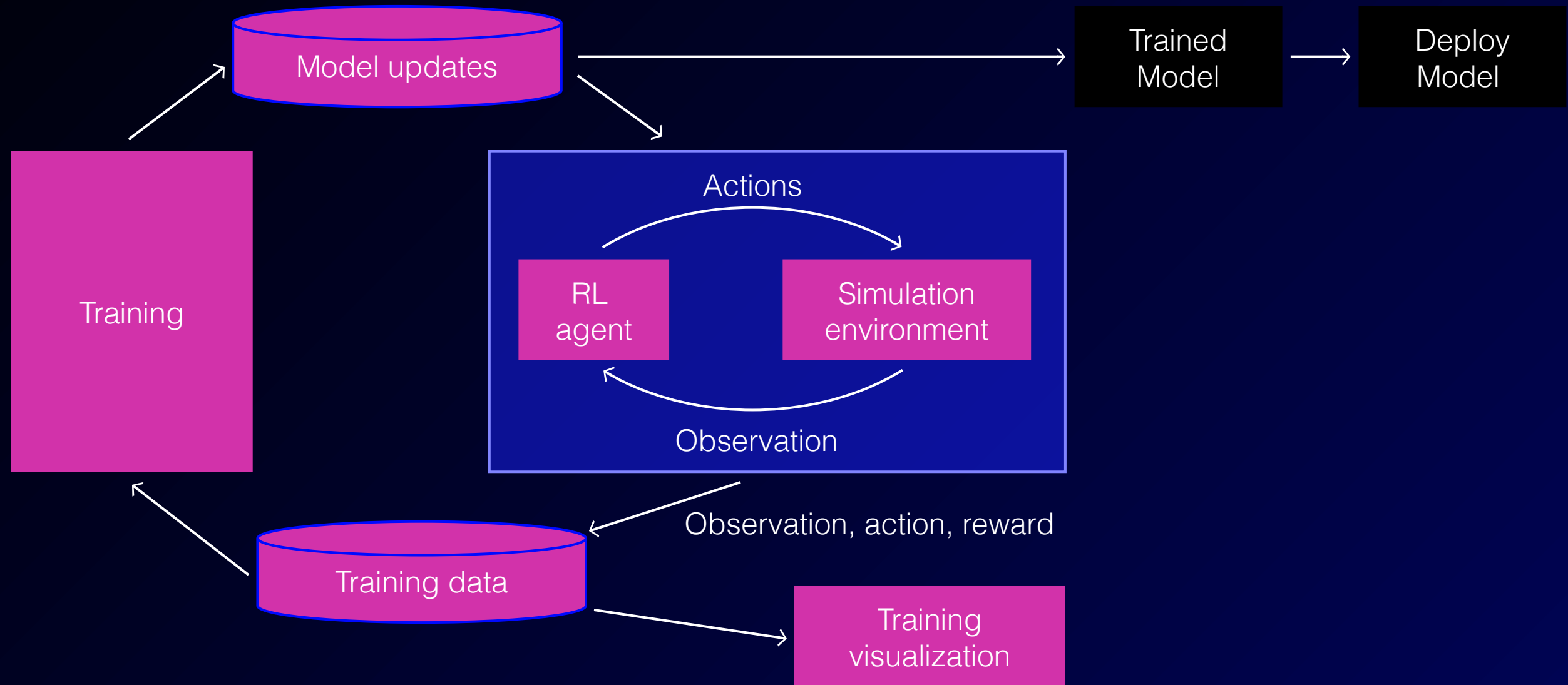


# Eventually, the model learns how to walk and run





# Evaluate and deploy trained models



# Customers are using RL on AWS



GE Healthcare

**HONDA**

**SIXT**

mixi

amazon

SyntheticGestalt

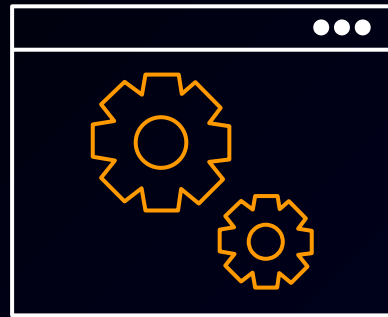
Scientific Research by Artificially Intelligent Agents



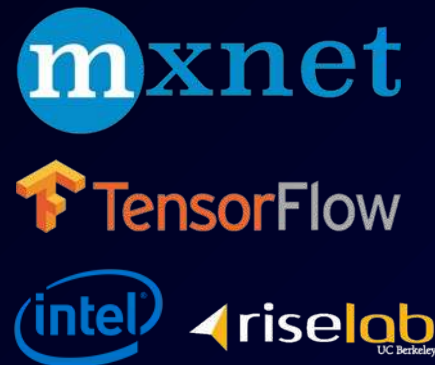
Tradelegs

# Amazon SageMaker RL

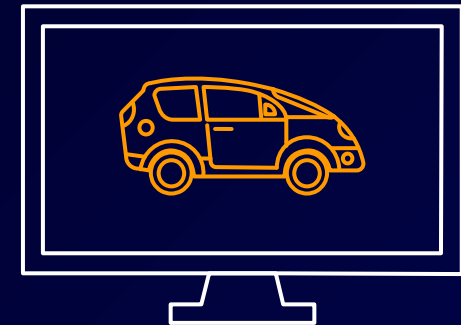
Reinforcement learning for every developer and data scientist



Fully  
managed



Broad support  
for frameworks



Broad support for simulation  
environments including  
SimuLink and MatLab

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## KEY FEATURES

TensorFlow, Apache  
MXNet, Intel Coach,  
and Ray RL support

2D & 3D physics  
environments and  
OpenAI Gym support

Supports Amazon Sumerian and  
Amazon RoboMaker

Example notebooks  
and tutorials

# Robotics



# Financial portfolio management



**Objective** Maximize the value of a financial portfolio

**STATE** Current stock portfolio, price history

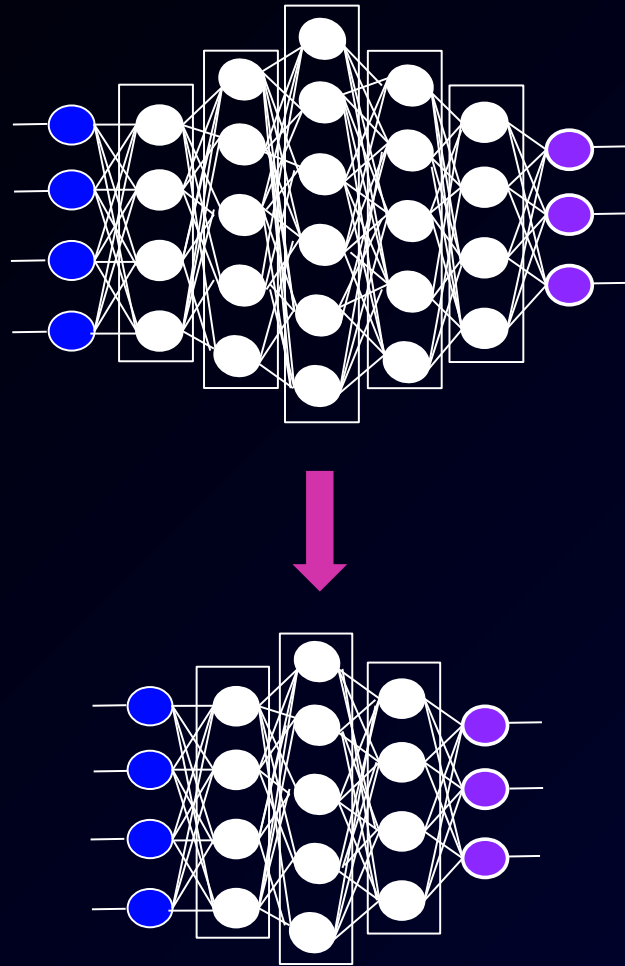
**ACTION** Buy, sell stocks

**REWARD** Positive when return is positive  
Negative when return is negative  
« A deep reinforcement learning framework for the financial portfolio management problem. »  
arXiv:1706.05912v1 [cs.LG] 2017

[https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement\\_learning/rl\\_portfolio\\_management\\_coach\\_customEnv](https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement_learning/rl_portfolio_management_coach_customEnv)



# Compressing deep learning models



**Compress model without losing**

**Objective accuracy**

**STATE** Layers

**ACTION** Remove or shrink a layer

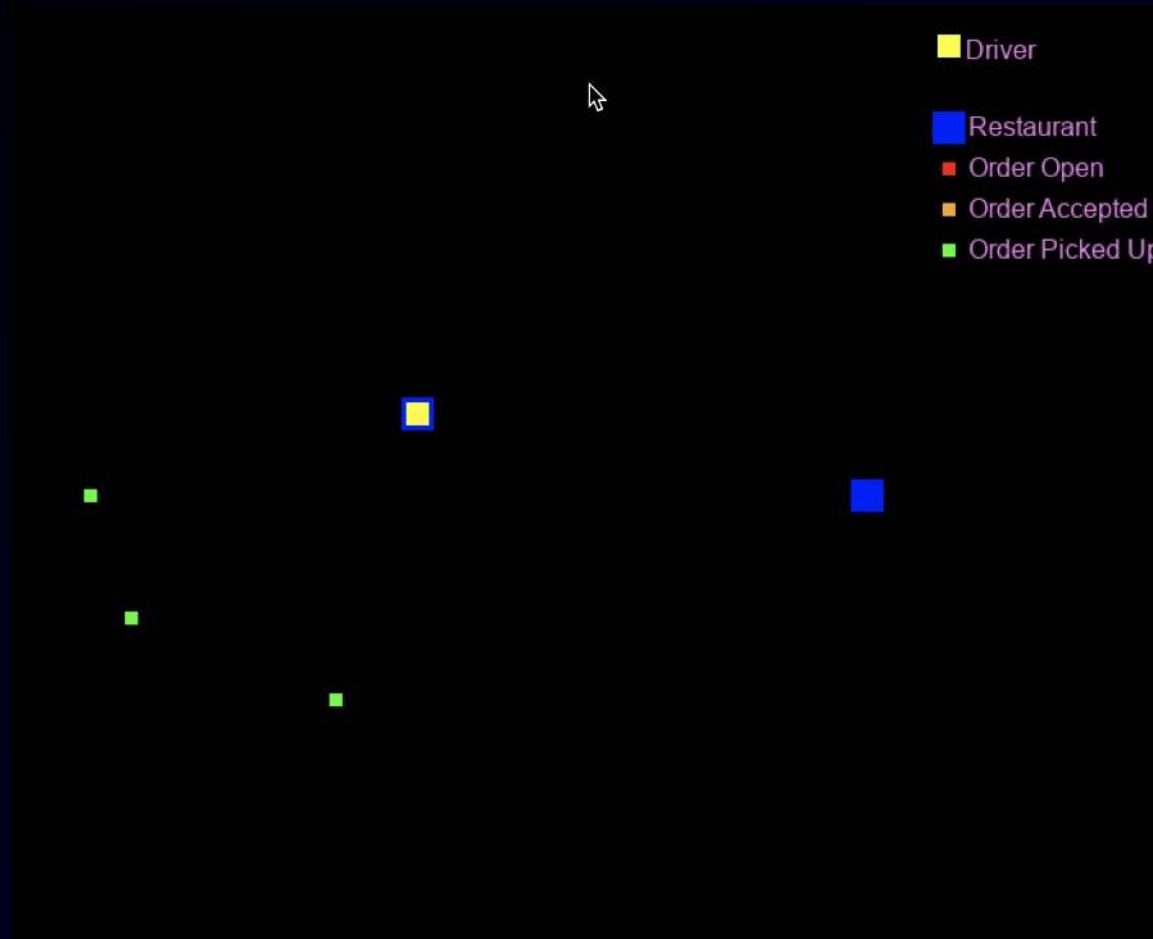
**REWARD** A combination of compression ratio and accuracy.

Dishok, Anubhav, Nicholas Rhinehart, Fares Beainy, and Kris M. Kitani

"N2N learning: network to network compression via policy gradient reinforcement learning." *arXiv:1709.06030 (2017).*

[https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement\\_learning/rl\\_network\\_compression\\_ray\\_custom](https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement_learning/rl_network_compression_ray_custom)

# Vehicle routing



## Objective

e

**Fulfill customer orders**

## STATE

Current location, distance from homes

## ACTION

Accept, pick up, and deliver order

## REWARD

Positive when we deliver on time

D

Negative when we fail to deliver on time

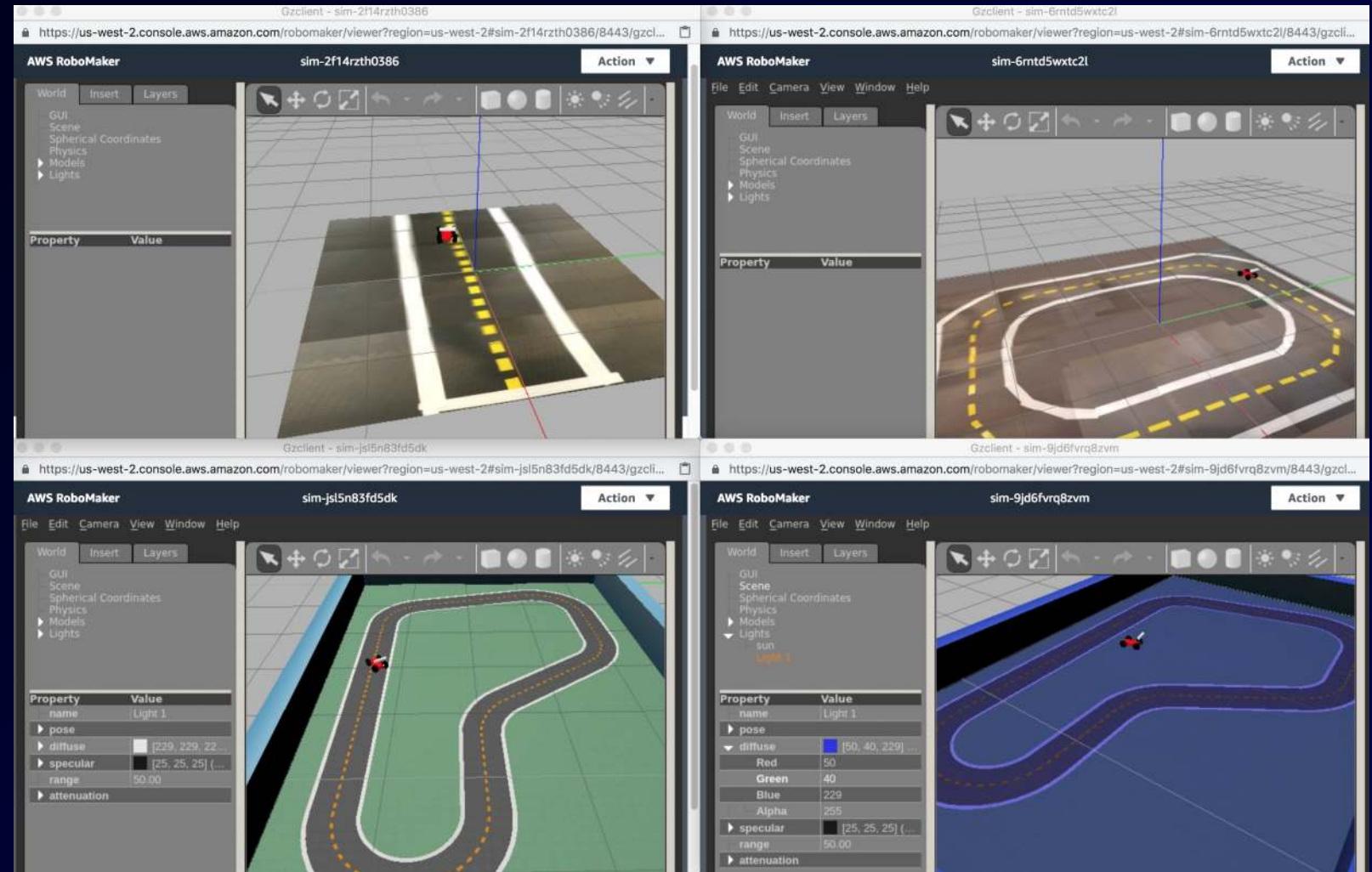
[https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement\\_learning/rl\\_traveling\\_salesman\\_vehicle\\_routing\\_coach](https://github.com/aws-labs/amazon-sagemaker-examples/tree/master/reinforcement_learning/rl_traveling_salesman_vehicle_routing_coach)

# Autonomous driving



AWS DeepRacer

1/18<sup>th</sup> scale autonomous vehicle



Amazon RoboMaker

# Getting started

<http://aws.amazon.com/free>

<https://ml.aws>

<https://aws.amazon.com/sagemaker>

<https://github.com/aws-labs/amazon-sagemaker-examples>

<https://aws.amazon.com/blogs/aws/amazon-sagemaker-rl-managed-reinforcement-learning-with-amazon-sagemaker/>

<https://aws.amazon.com/deepracer/>

<https://medium.com/@julsimon>

# Thank you!

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