Deep Learning for Developers

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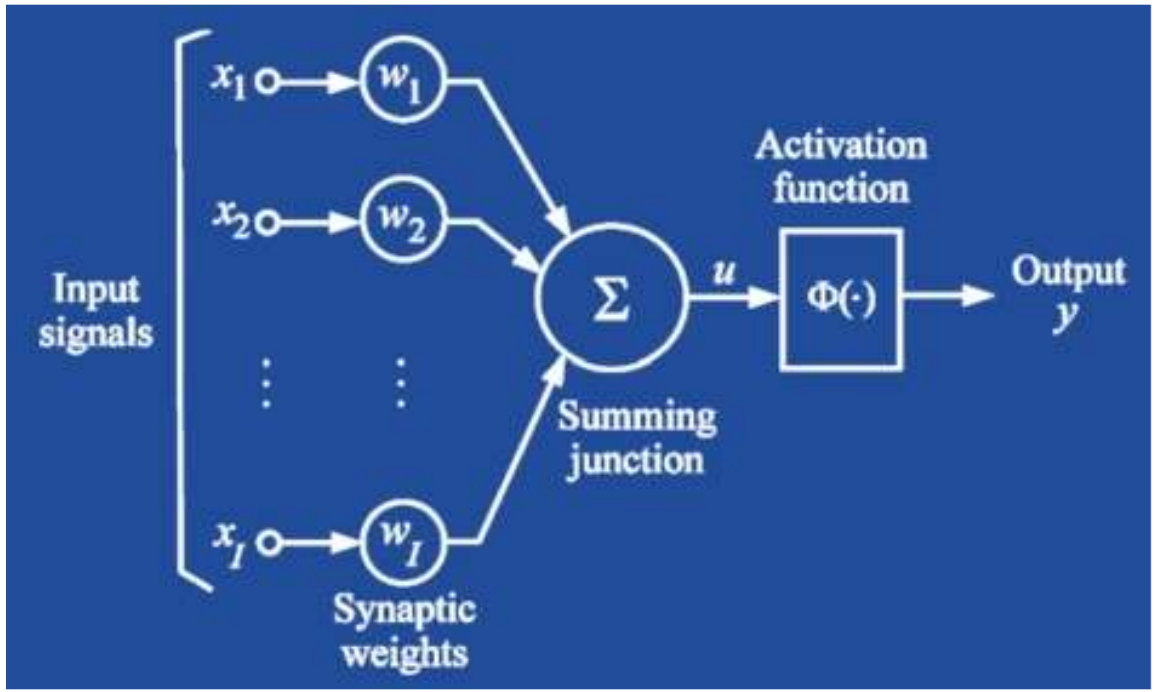
The neuron



$$\sum_{i=1}^{I} x_i * w_i = u$$

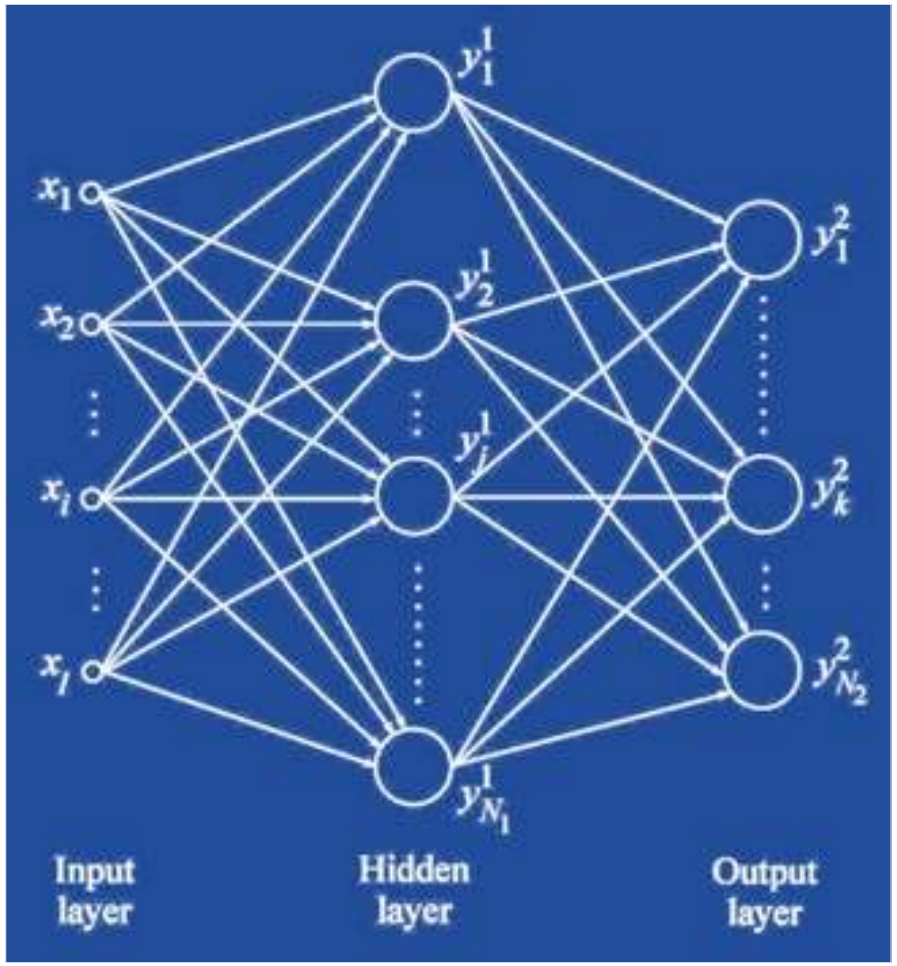
”Multiply and Accumulate”

Activation functions

Name	Plot	Equation
Identity		$f(x) = x$
Binary step		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$
Logistic (a.k.a. Soft step)		$f(x) = \frac{1}{1 + e^{-x}}$
TanH		$f(x) = \tanh(x) = \frac{2}{1 + e^{-2x}} - 1$
ArcTan		$f(x) = \tan^{-1}(x)$
Softsign [7][8]		$f(x) = \frac{x}{1 + \lvert x \rvert}$
Rectified linear unit (ReLU)[9]		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$

Source: Wikipedia

Neural networks



l features

$$x = \begin{bmatrix} x_{11}, x_{12}, \ldots x_{1l} \\ x_{21}, x_{22}, \ldots x_{2l} \\ \ldots \ldots \ldots \\ x_{m1}, x_{m2}, \ldots x_{ml} \end{bmatrix}$$

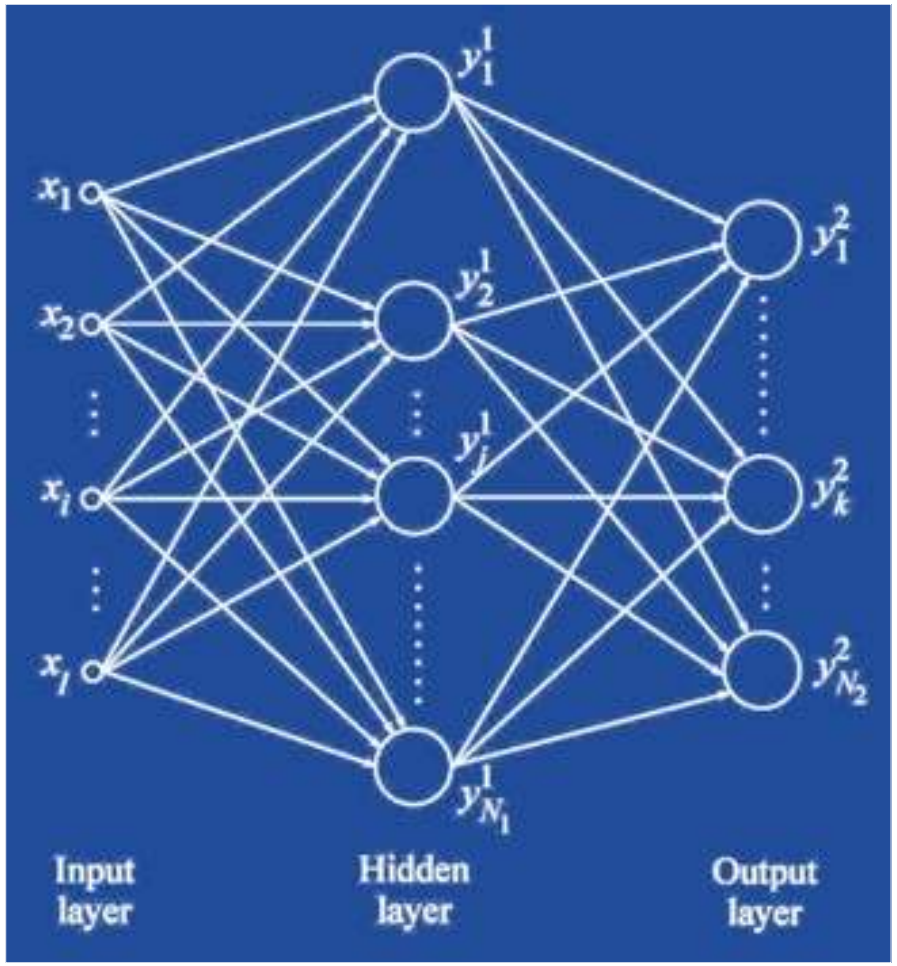
m samples

$$y = \begin{bmatrix} 2 \\ 0 \\ \ldots \\ 4 \end{bmatrix} \quad \begin{bmatrix} 0,0,1,0,0,\ldots,0 \\ 1,0,0,0,0,\ldots,0 \\ \ldots \\ 0,0,0,0,1,\ldots,0 \end{bmatrix}$$

One-hot encoding

m labels,
N_2 categories

Neural networks



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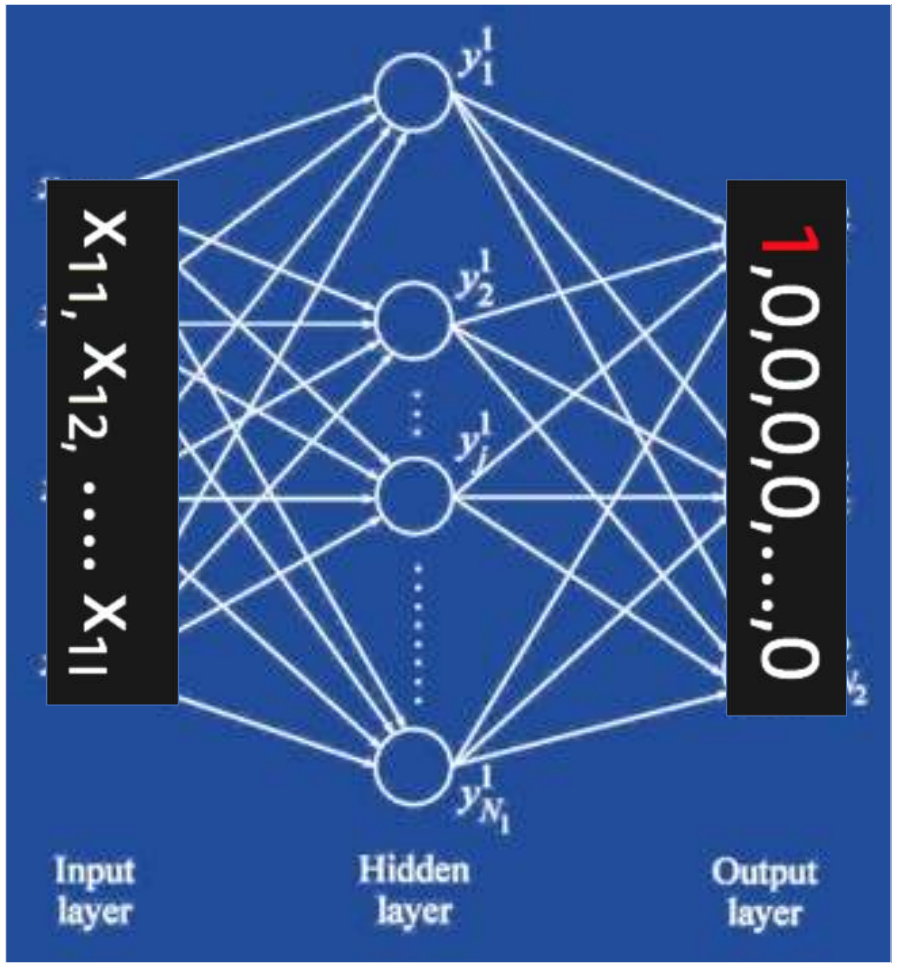
m labels,
N_2 categories

One-hot encoding

$$\text{Accuracy} = \frac{\text{Number of correct predictions}}{\text{Total number of predictions}}$$

Neural networks



Initially, the network will not predict correctly

$f(X_1) = Y'_1$

A loss function measures the difference between the real label Y_1 and the predicted label Y'_1

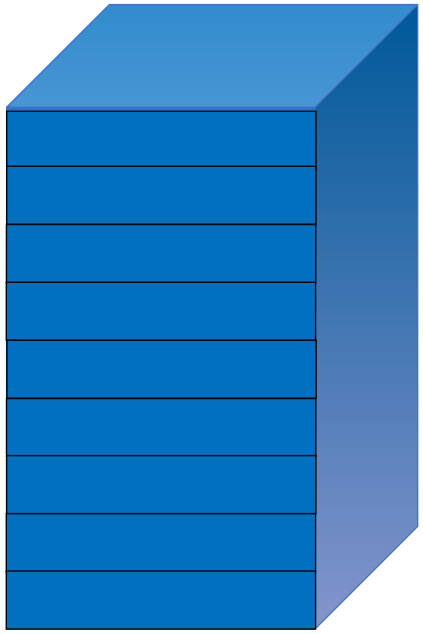
$error = loss(Y_1, Y'_1)$

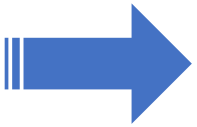
For a batch of samples:

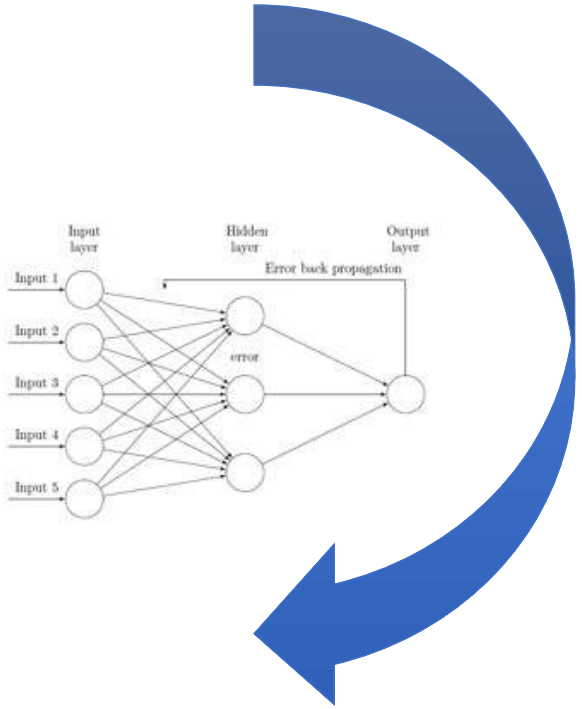
$$\sum_{i=1}^{batch\ size} loss(Y_i, Y'_i) = \text{batch error}$$

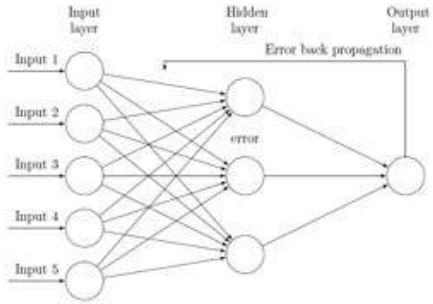
The purpose of the training process is to minimize loss by gradually adjusting weights

Training









Training data set

Backpropagation

Trained neural network

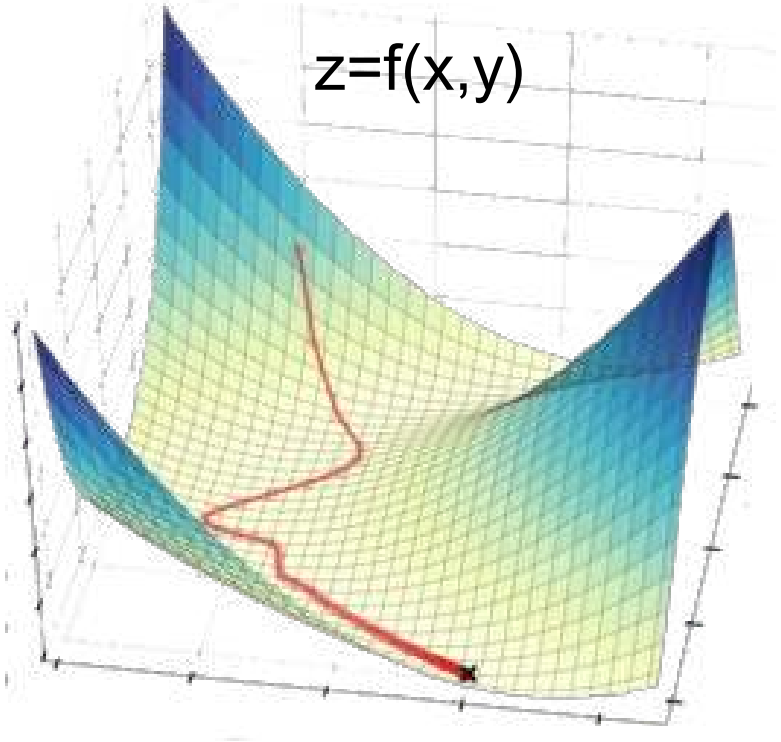
Batch size
Learning rate
Number of epochs

Hyper parameters

Stochastic Gradient Descent (SGD)

Imagine you stand on top of a mountain with skis strapped to your feet. You want to get down to the valley as quickly as possible, but there is fog and you can only see your immediate surroundings. How can you get down the mountain as quickly as possible? You look around and identify the steepest path down, go down that path for a bit, again look around and find the new steepest path, go down that path, and repeat—this is exactly what gradient descent does.

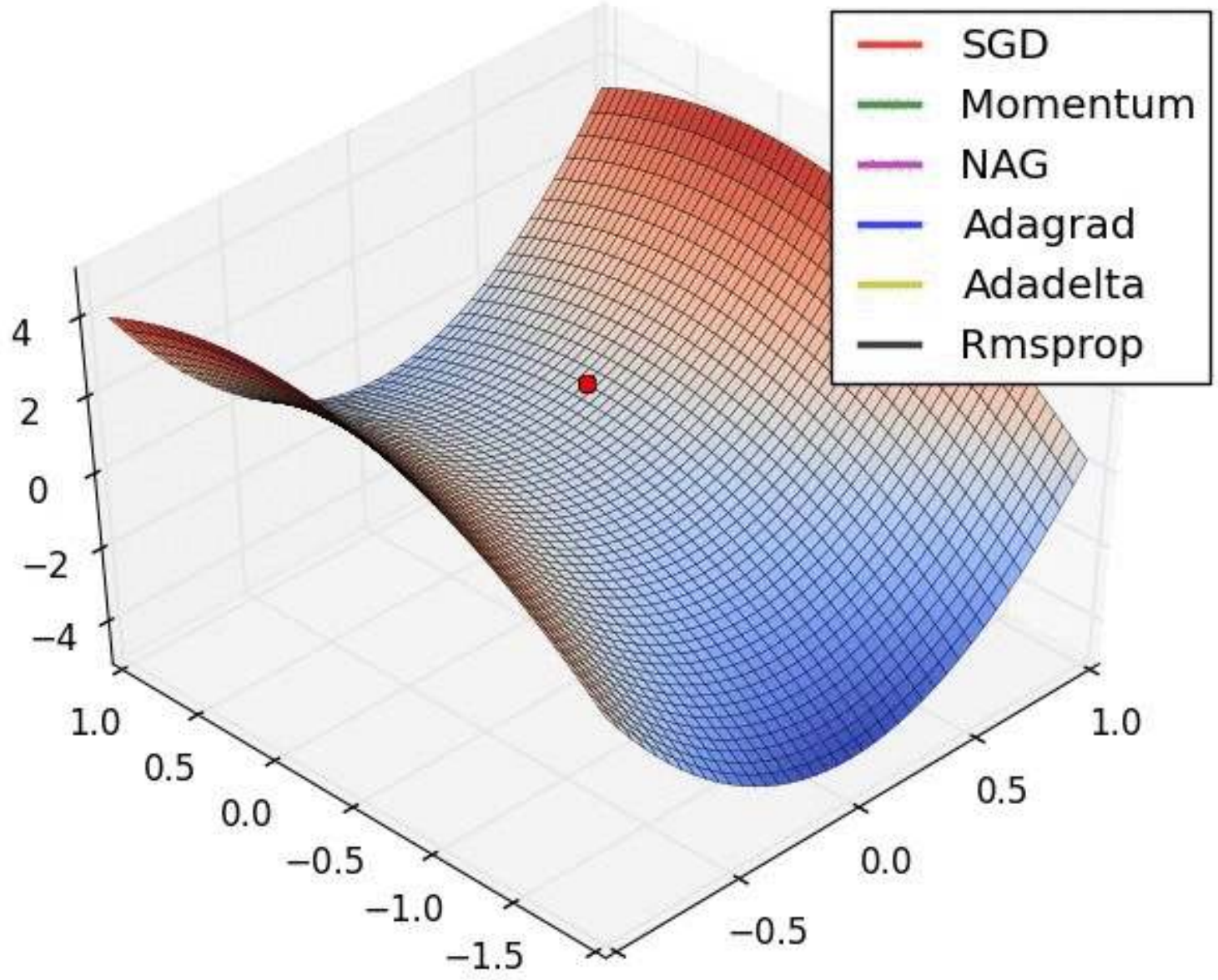
Tim Dettmers
University of Lugano
2015



The « step size » is called the learning rate

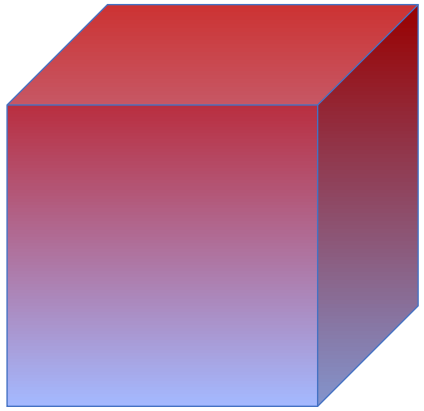
https://devblogs.nvidia.com/parallelforall/deep-learning-nutshell-history-training/

Optimizers

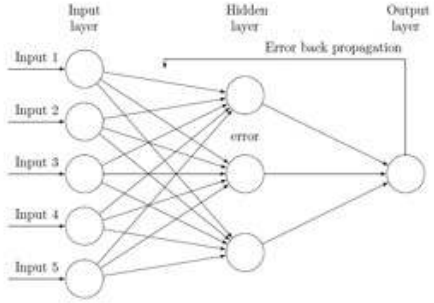


https://medium.cim/@julsimon/tumbling-down-the-sgd-rabbit-hole-part-1-740fa402f0d7

Validation



Validation data set

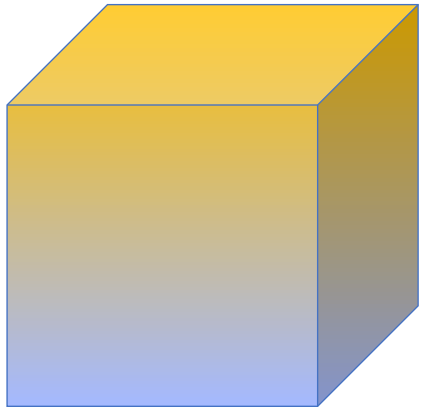


Trained neural network

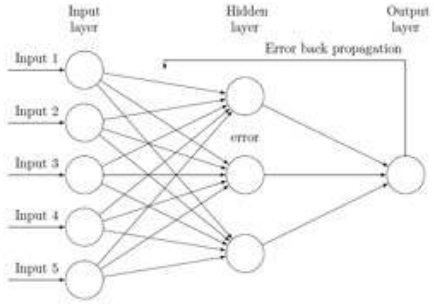
Prediction at the end of each epoch

Validation accuracy

Test



Test data set



Fully trained neural network

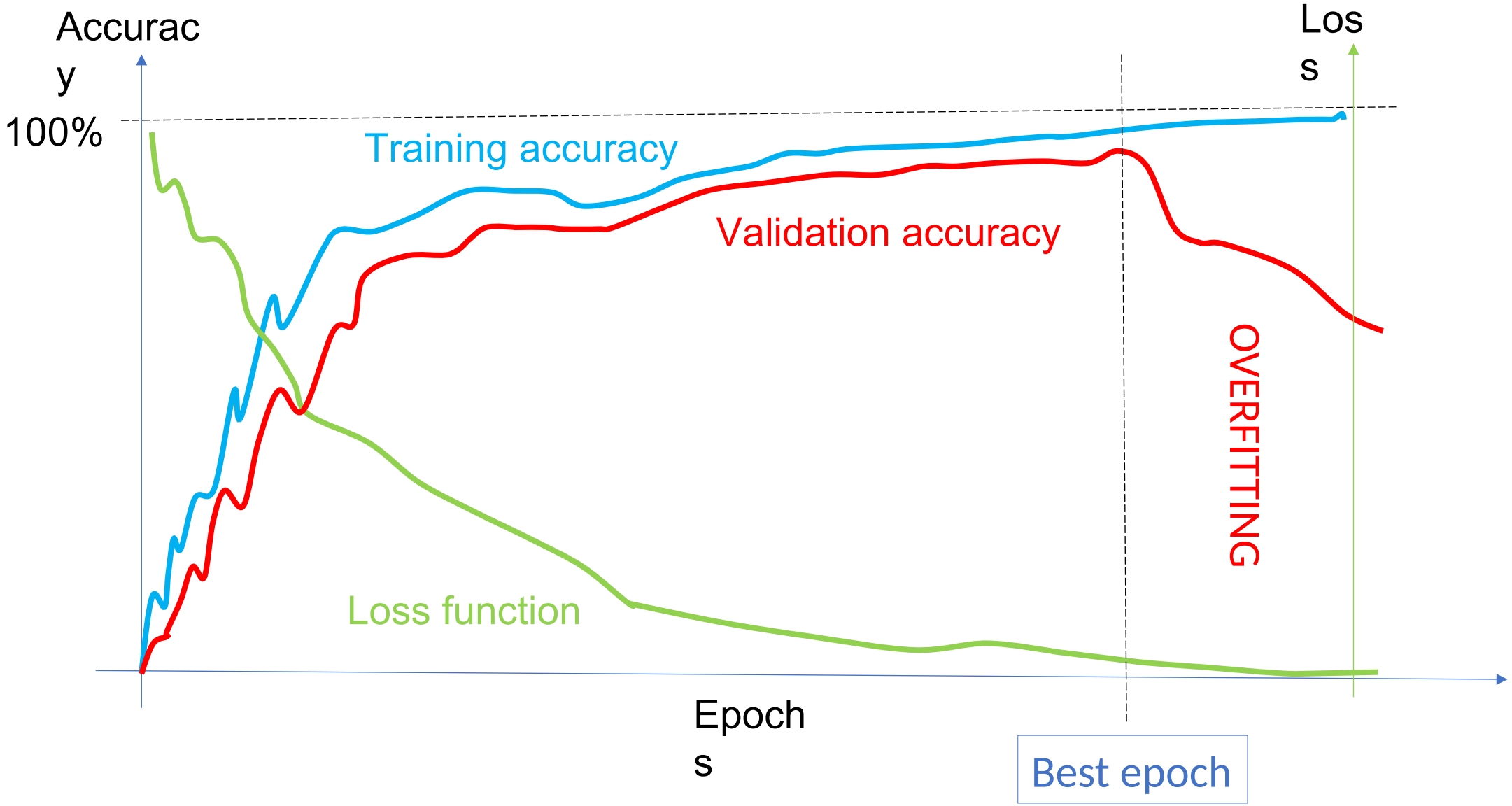
Prediction at the end of experimentation

Test accuracy

This data set must have the same distribution as real-life samples, or else test accuracy won't reflect real-life accuracy.

Early stopping

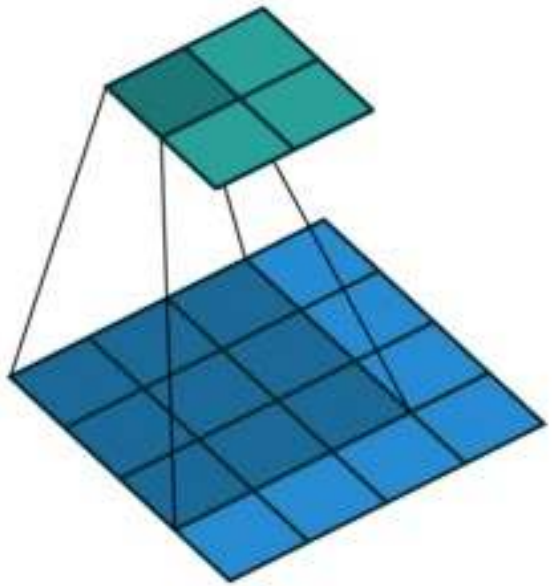
« *Deep Learning ultimately is about finding a minimum that generalizes well, with bonus points for finding one fast and reliably* », Sebastian Ruder

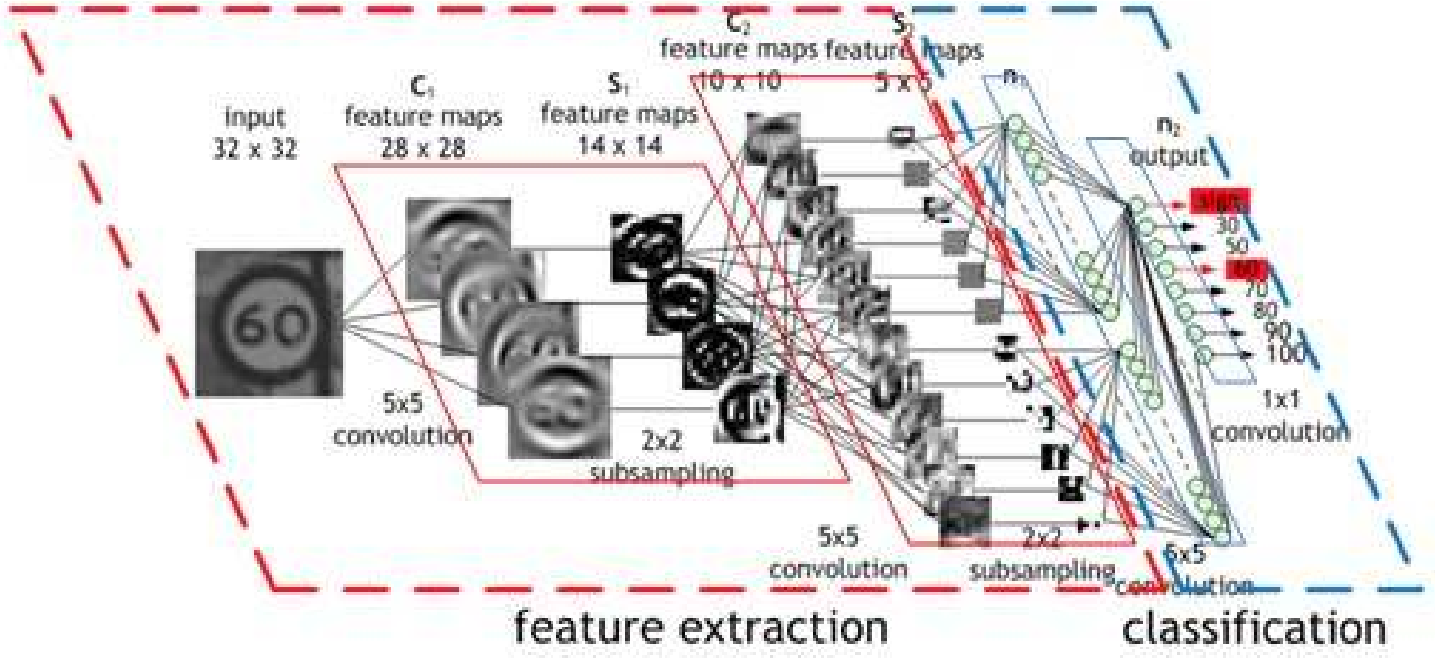


Demo: fully connected network

Convolutional Neural Networks (CNN)

Le Cun, 1998: handwritten digit recognition, 32x32 pixels

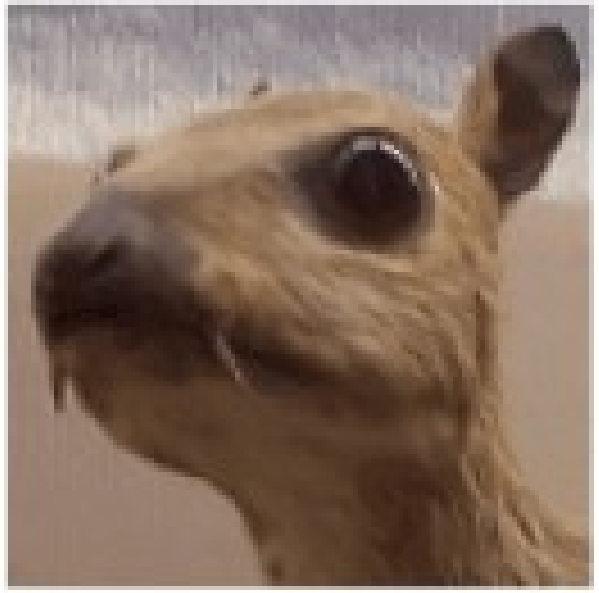




https://devblogs.nvidia.com/parallelforall/deep-learning-nutshell-core-concepts/

Extracting features with convolution

Input image



Convolution Kernel

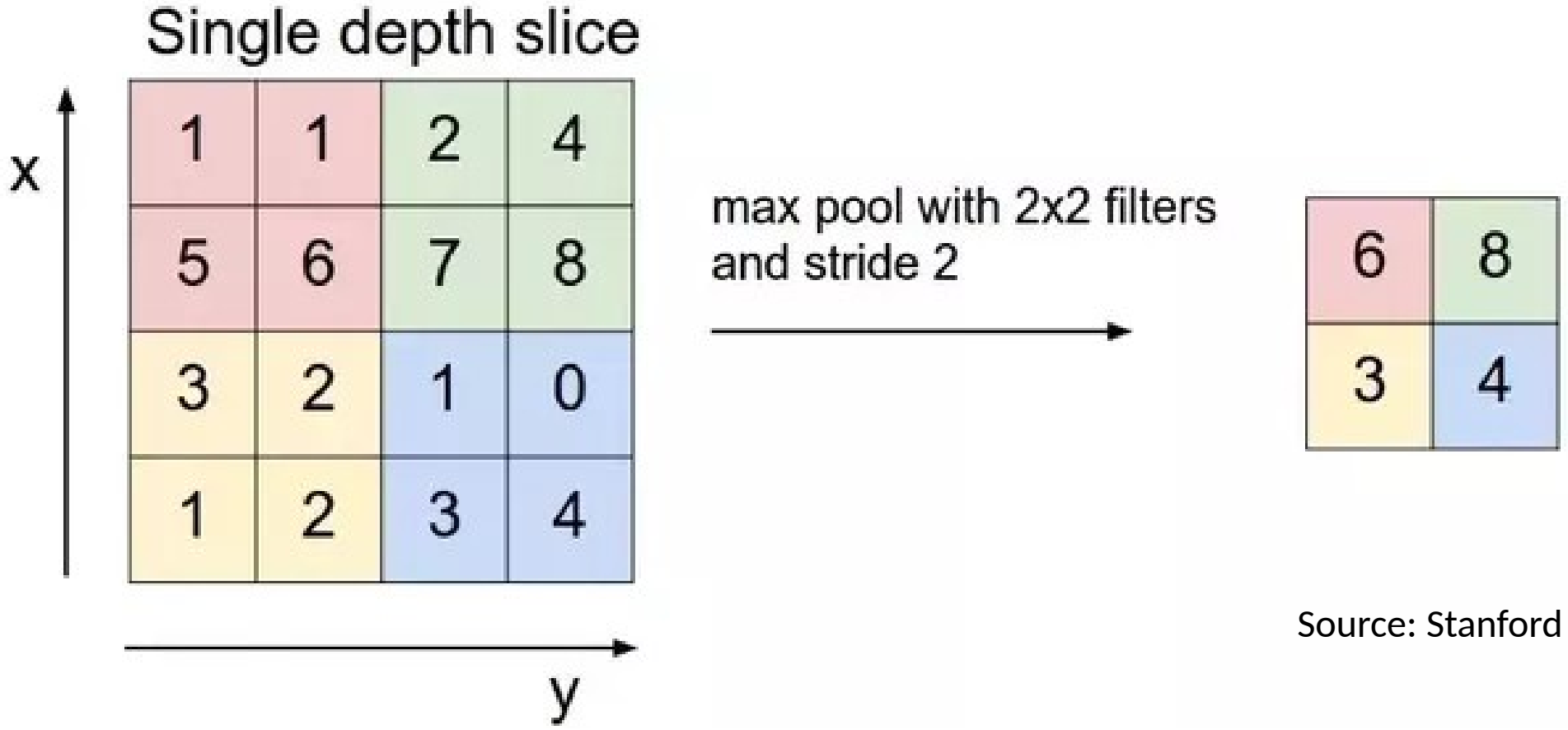
$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

Feature map

Source: http://timdettmers.com

Convolution extracts features automatically.
Kernel parameters are learned during the training process.

Downsampling images with pooling



Source: Stanford University

Pooling shrinks images while preserving significant information.

Demo: convolutional network

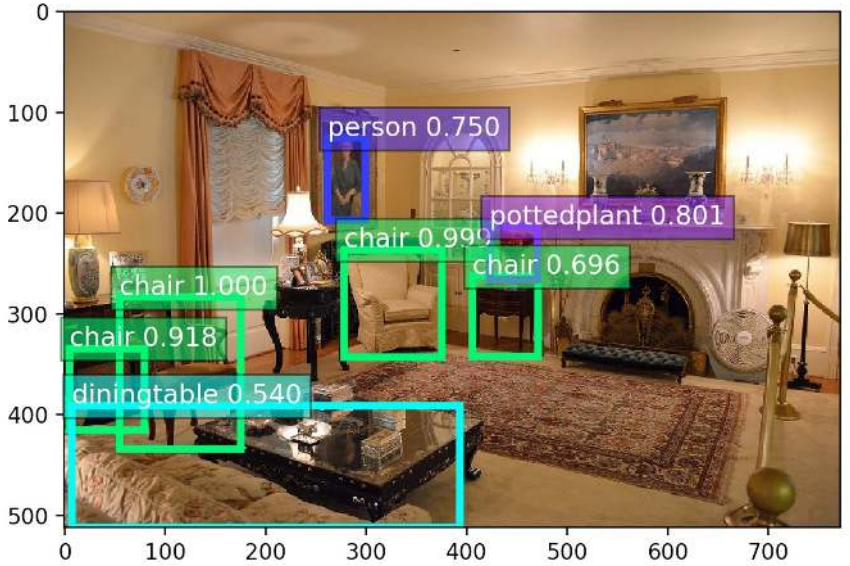
Gluon CV: state of the art pre-trained models

MXNet

Classification

[electric_guitar],
with probability 0.671

Detection



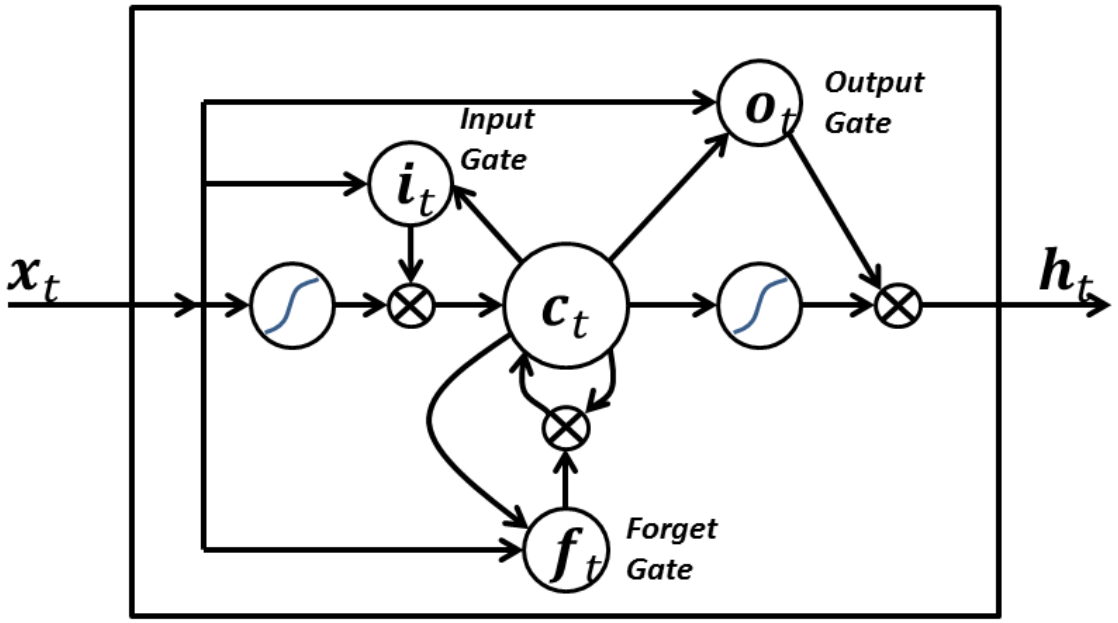
Segmentation

https://github.com/dmlc/gluon-cv

Demo: Gluon CV

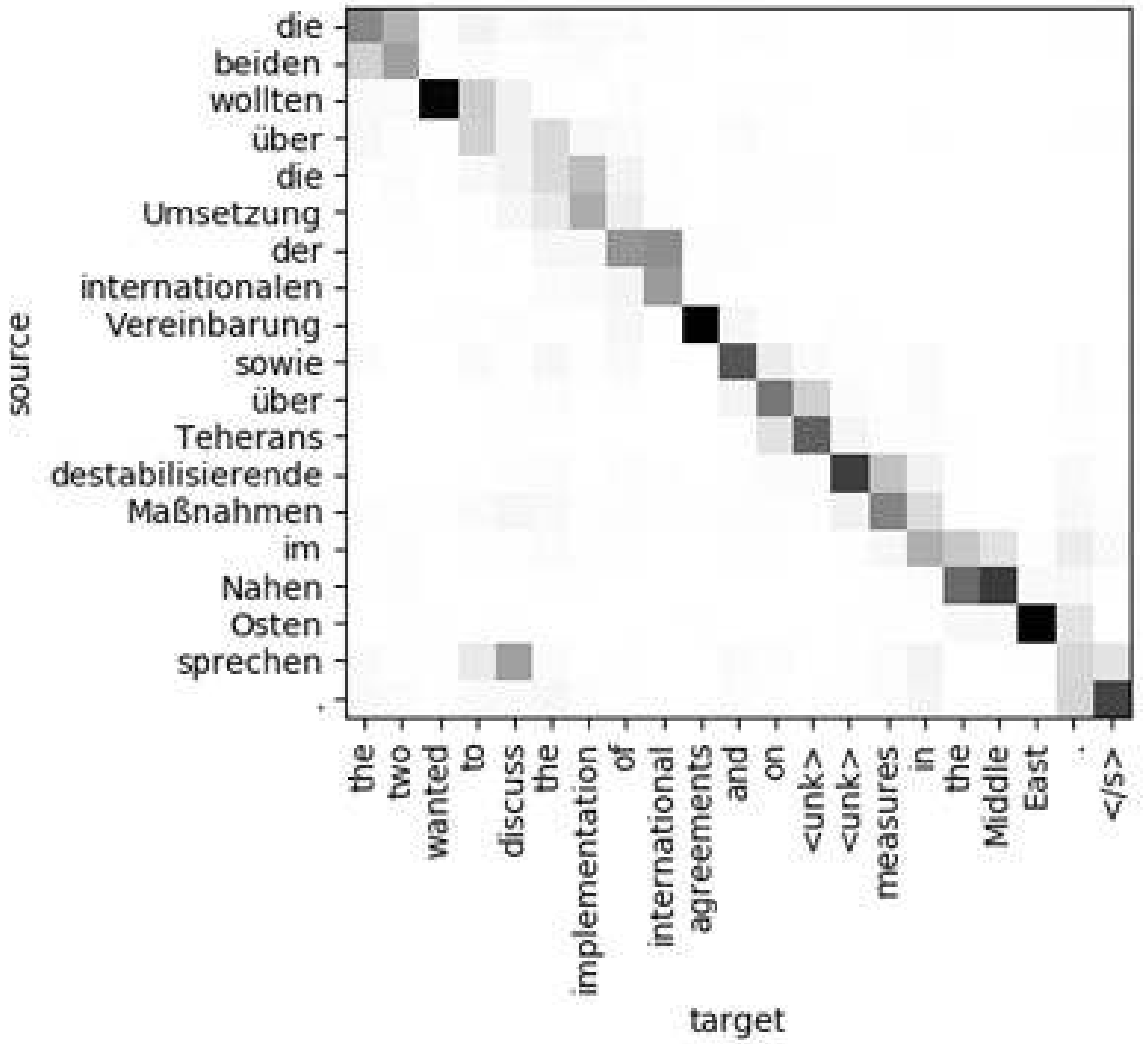
Long Short Term Memory Networks (LSTM)

- A LSTM neuron computes the output based on the input and a previous state
- LSTM networks have memory
- They're great at predicting sequences, e.g. machine translation



MXNet

Machine Translation



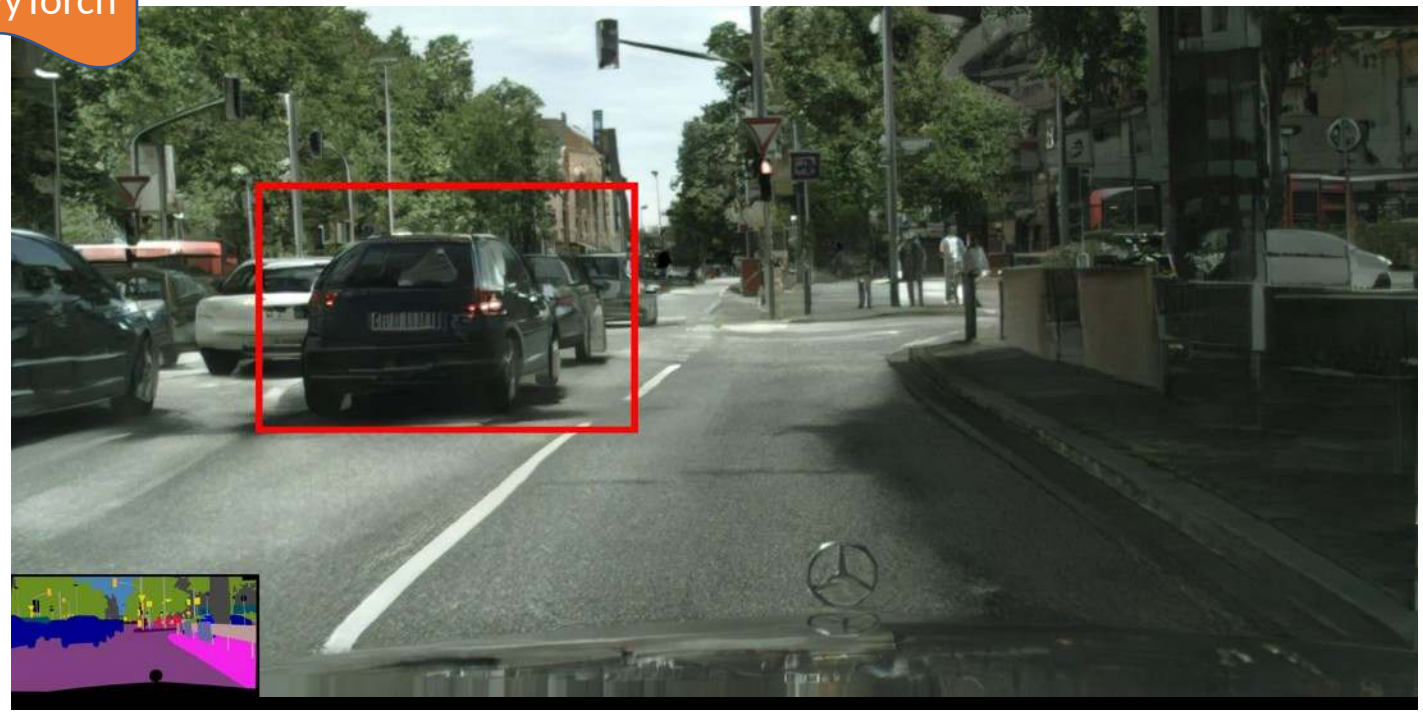
https://github.com/awslabs/sockeye

GAN: Welcome to the (un)real world, Neo

TF

Generating new ”celebrity” faceshttps://github.com/tkarras/progressive_growing_of_gans

PyTorch

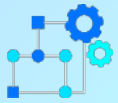


From semantic map to 2048x1024 picture
https://tcwang0509.github.io/pix2pixHD/

Scalable training on AWS

Amazon SageMaker

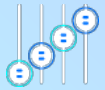
Pre-built notebooks for common problems



Built-in, high-performance algorithms

Build

One-click training



Hyperparameter optimization

Train

One-click deployment

Fully managed hosting with auto-scaling

Deploy

AWS Deep Learning AMI

TensorFlow

Keras

Microsoft CNTK

mxnet

GLUON

PYTORCH

Chainer

Caffe2

torch

Amazon EC2

c5

p3

Getting started

https://ml.aws | https://aws.amazon.com/blogs/machine-learning/

https://mxnet.incubator.apache.org | https://github.com/apache/incubator-mxnet

https://gluon.mxnet.io | https://github.com/gluon-api | https://github.com/dmlc/gluon-cv

https://aws.amazon.com/sagemaker

https://github.com/awslabs/amazon-sagemaker-examples

https://github.com/aws/sagemaker-python-sdk | https://github.com/aws/sagemaker-spark

https://medium.com/@julsimon

https://youtube.com/juliensimonfr

https://gitlab.com/juliensimon/dlnotebooks

Thank you!

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