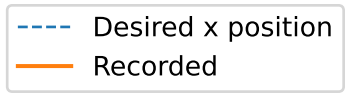
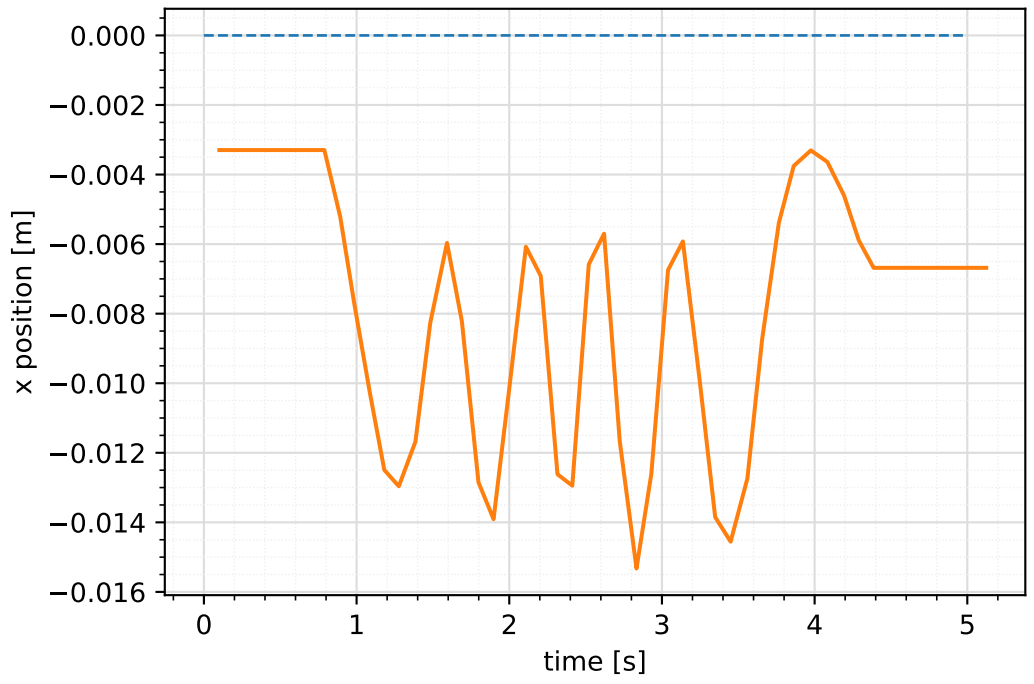
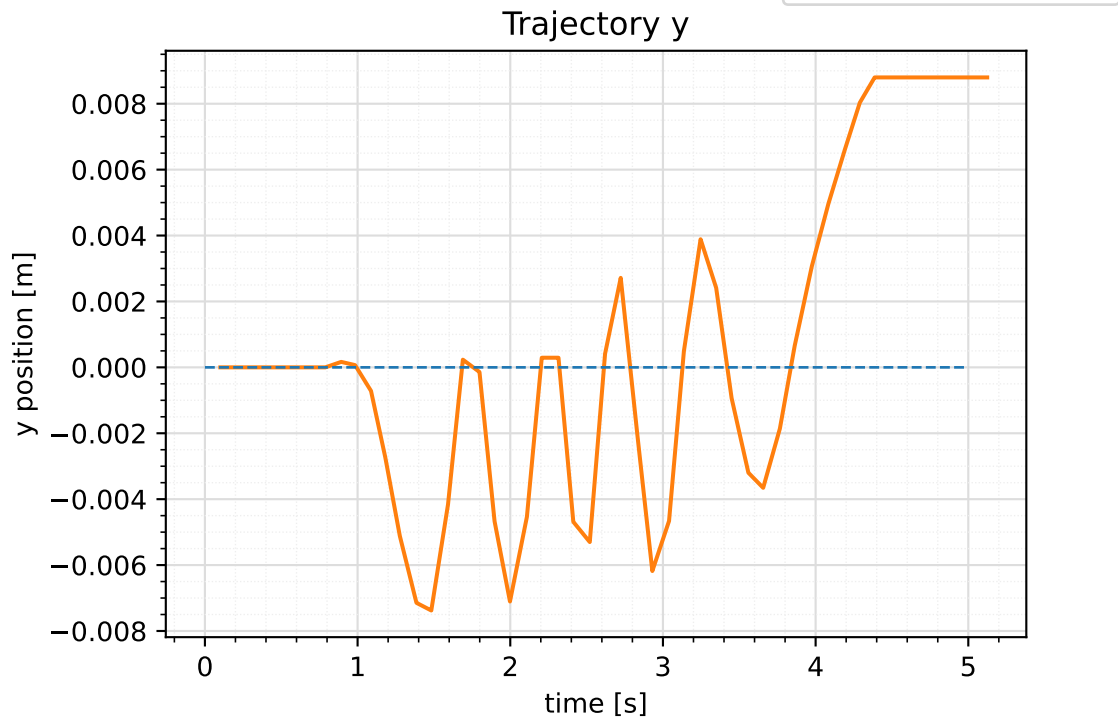


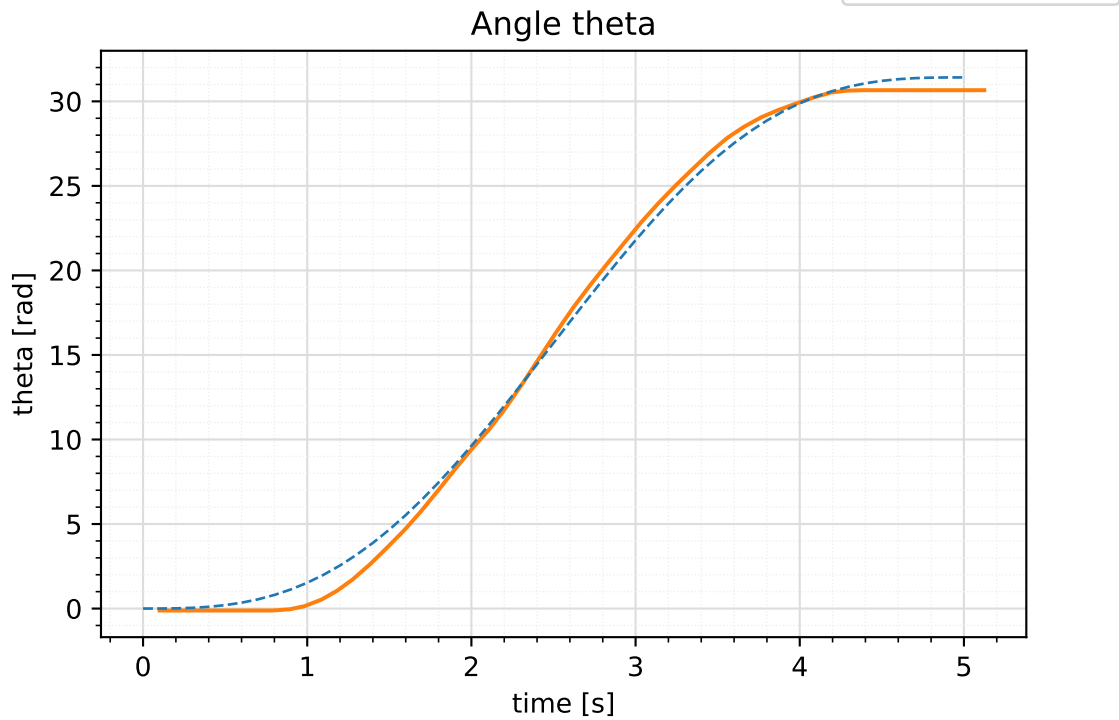
Pololu 3pi+ trajectory test (straight line)
trajectory: rotation.json
file name : rot_0_0_29.json
 $K_x = 1$ $K_y = 3$ $K_{\text{theta}} = 3$



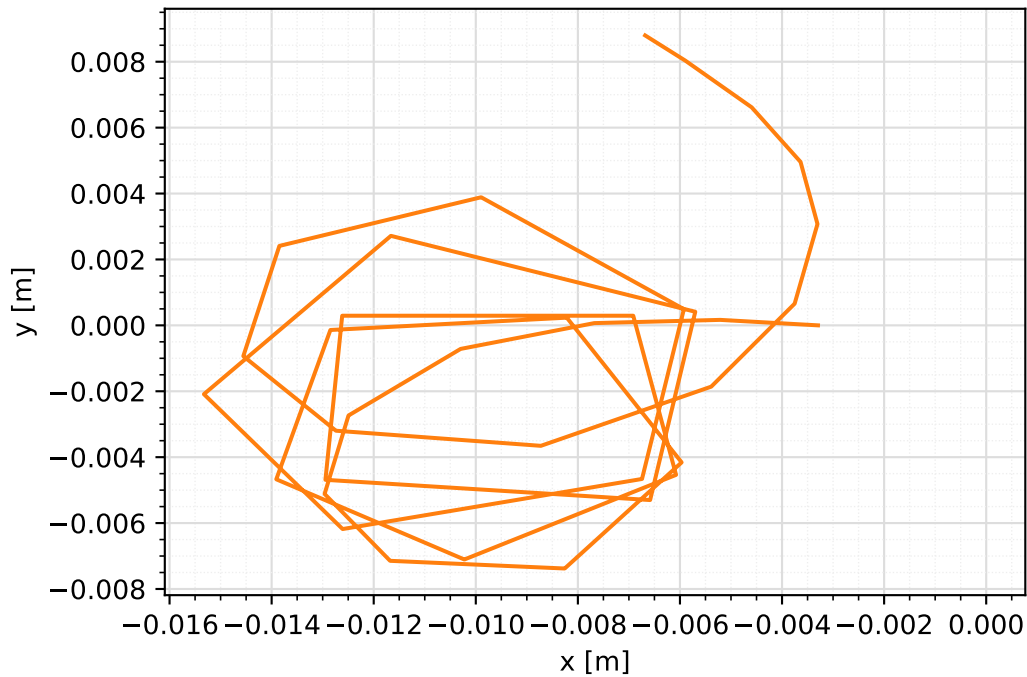
Trajectory x

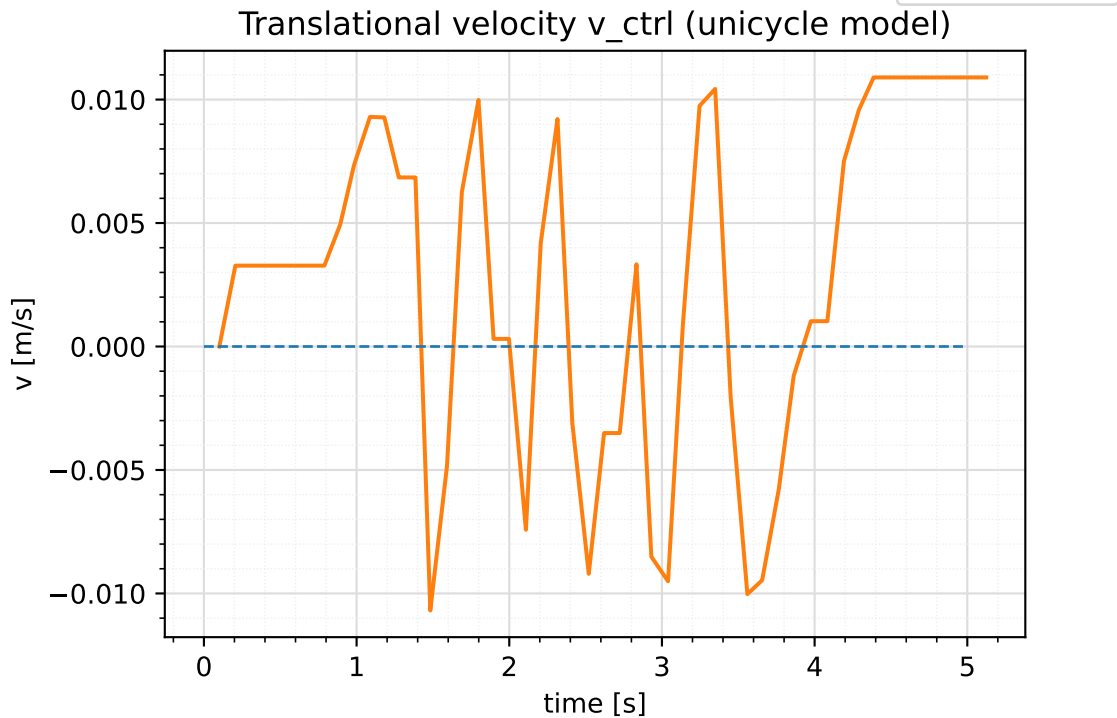


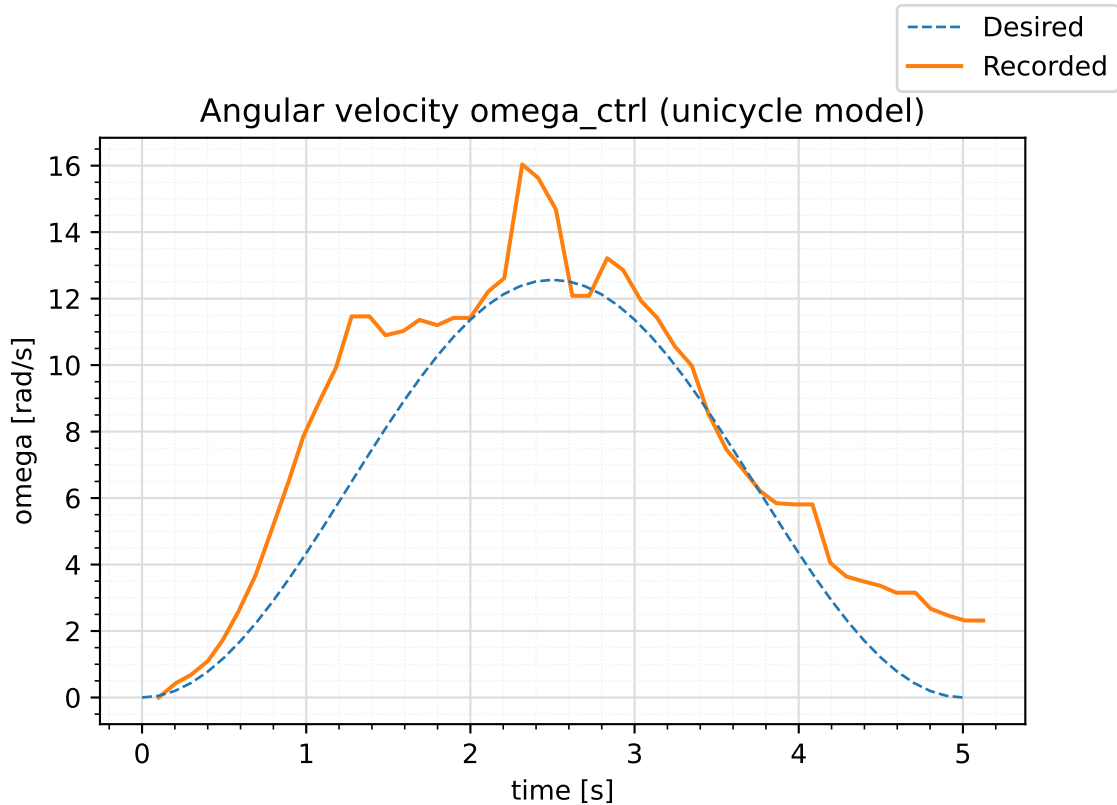




2D visualization







Left and right wheel angular velocities u_L & u_R

— Desired
— Recorded

