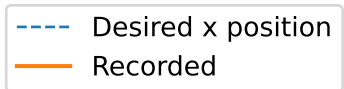
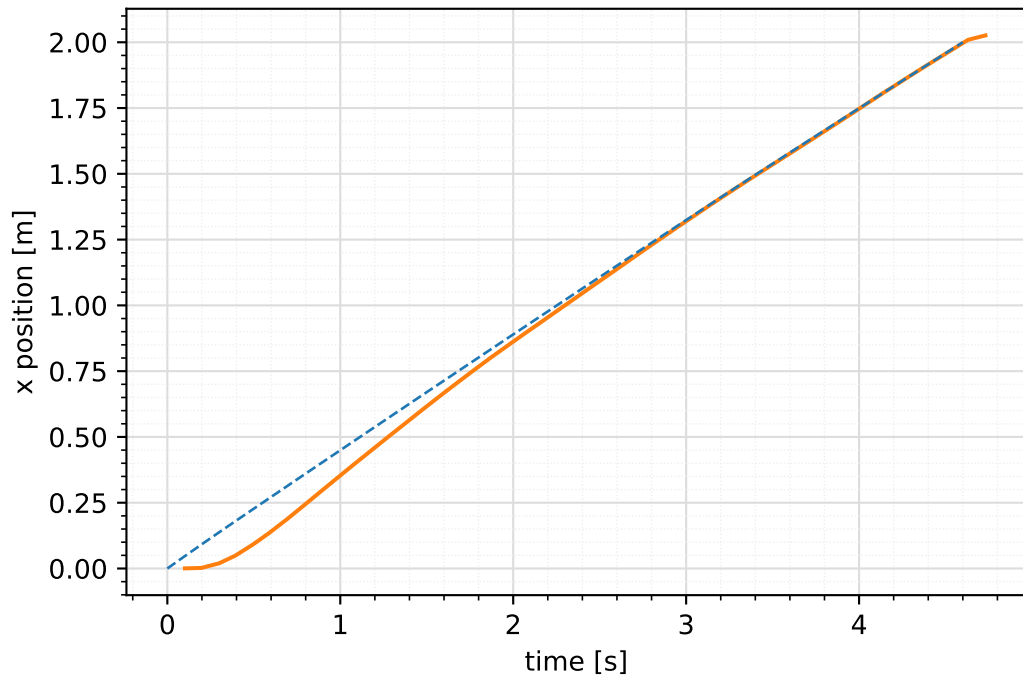
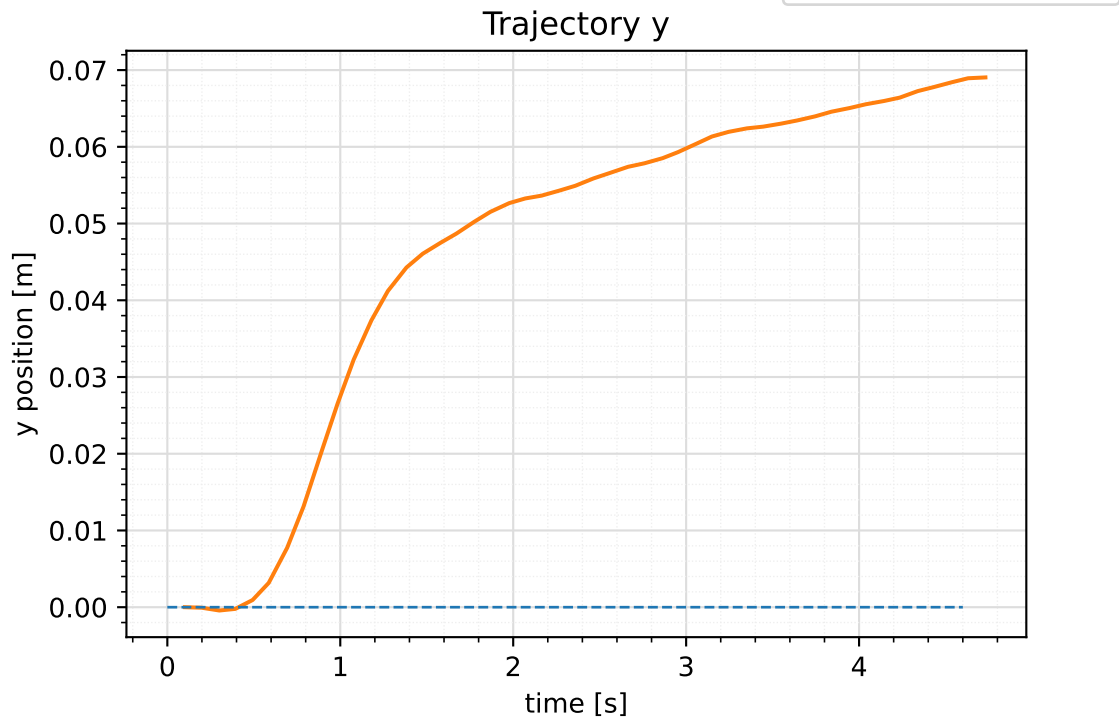


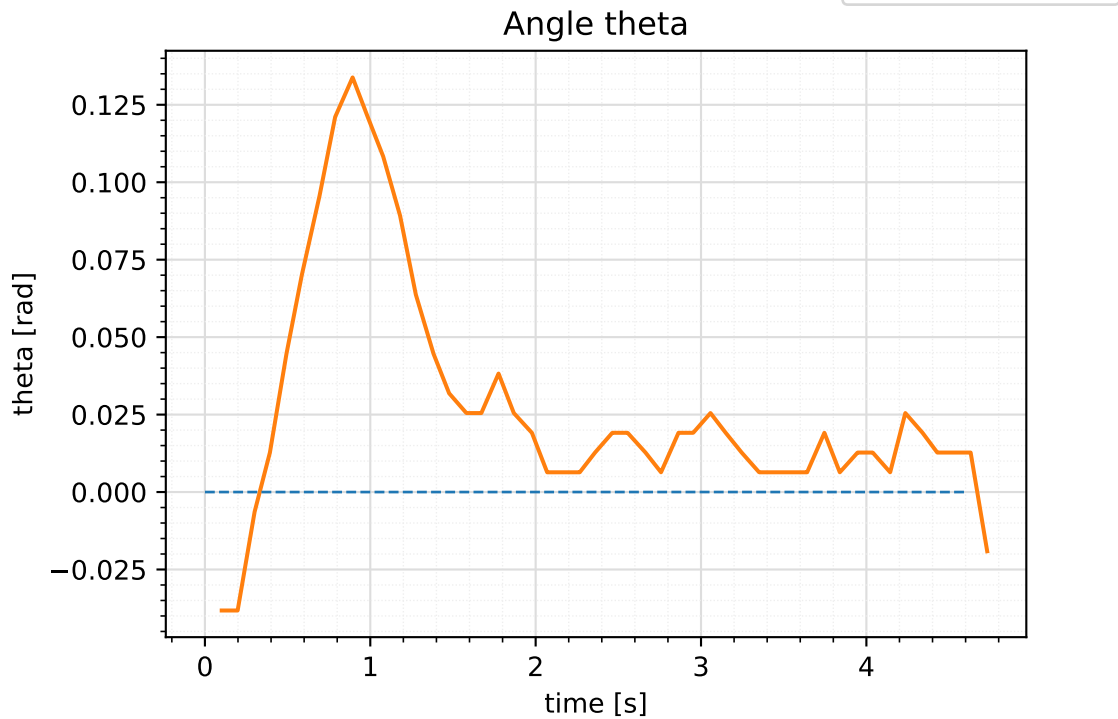
Pololu 3pi+ trajectory test (straight line)  
trajectory: line.json  
file name : lin\_0\_0\_59.json  
 $K_x = 1$     $K_y = 4$     $K_{\theta} = 4$



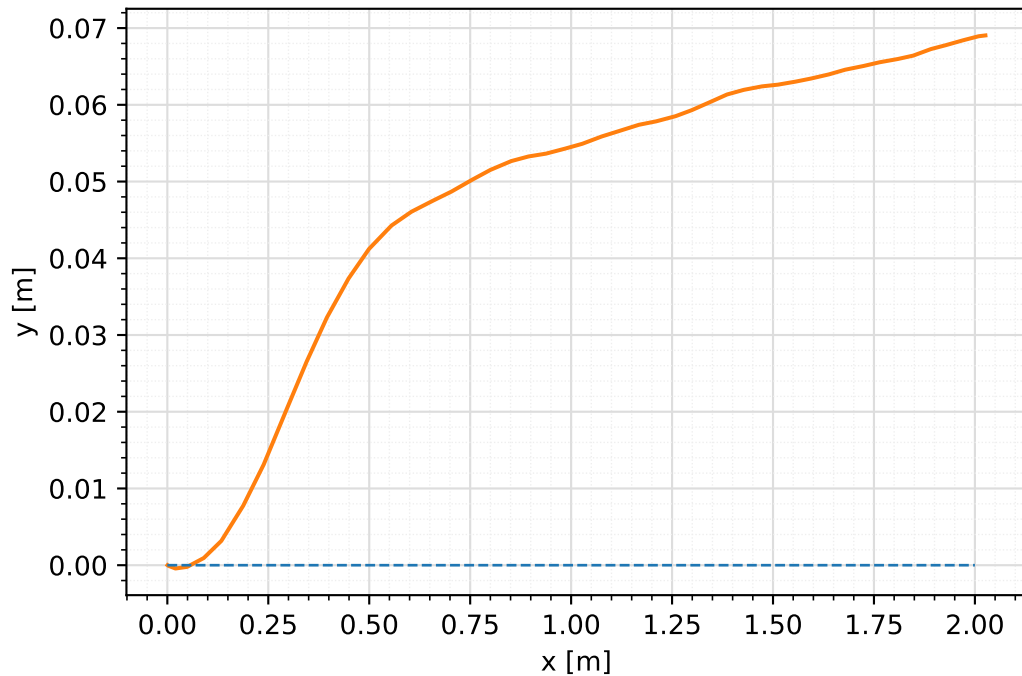
Trajectory x

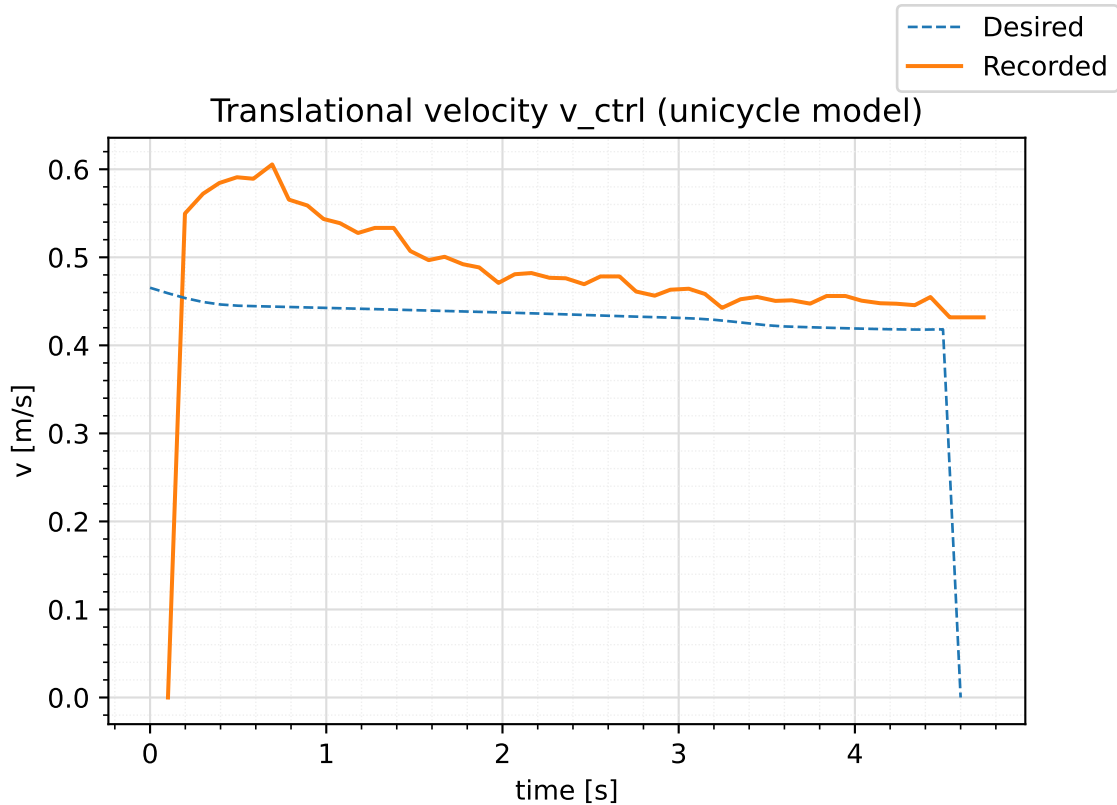


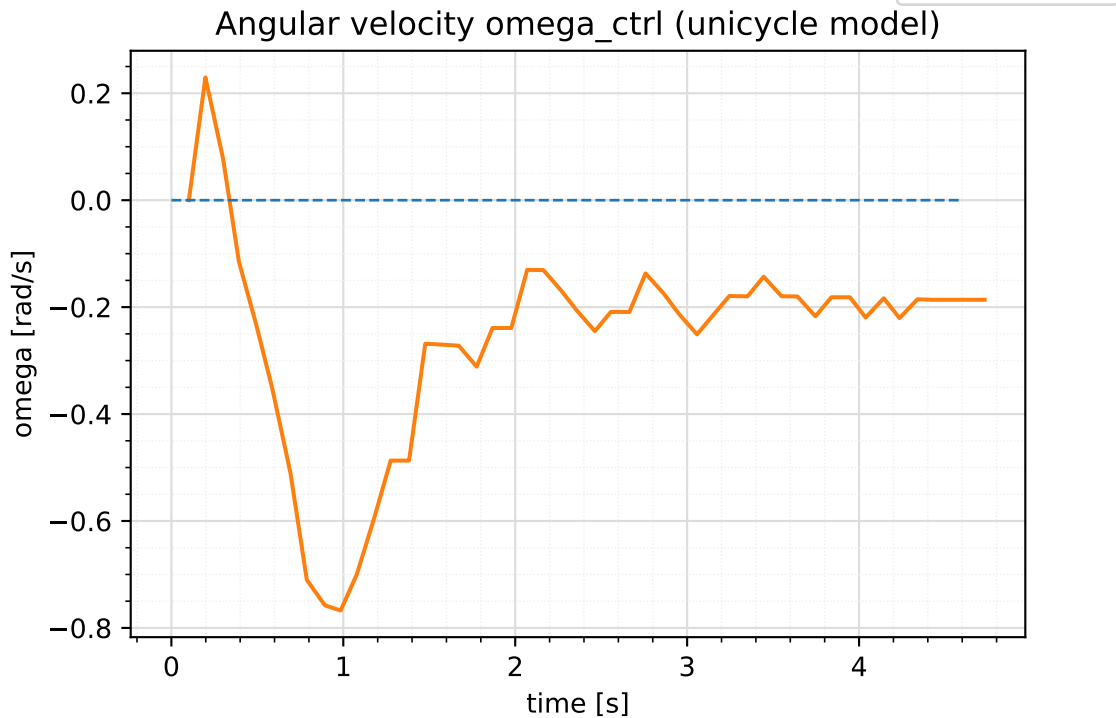




2D visualization







Left and right wheel angular velocities  $u_L$  &  $u_R$

Desired  
Recorded

