Handling Missing Data in Decision Trees: A Probabilistic Approach

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Overview

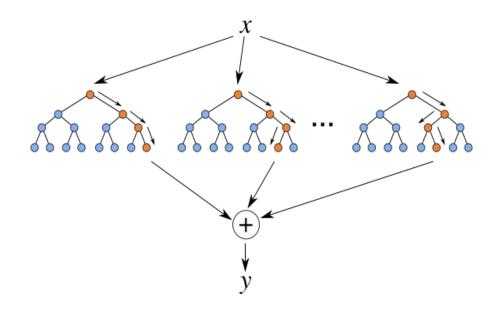
- Missing values common occurrence in machine Learning
 - Hinders performance of discriminative models
 - Generative models can handle missing values but not as good in discriminating (classification/regression).
- Decision trees are a popular family of models

 This paper: learning parameters of decision trees from missing data, using tractable density estimators.

Decision Trees/ Random Forests

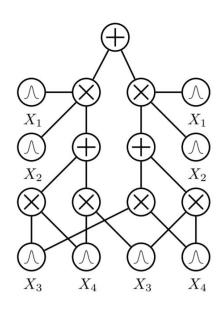
Popular models:

- Scalability
- Interpretability
- Ability to handle mixed types of features (discrete vs real)
- Used for both regression and classification



Probabilistic Circuits

- Can be thought of as "deep mixture models"
 - Expressive density estimators
 - Tractable probabilistic queries such as exact marginalization on any subset of features in linear time
 - Both structure and parameters can be learned from missing data
 - They are a computation graph, so can differentiate



Expected loss minimization

$$\mathcal{L}(\Theta; \mathsf{D}_{\mathsf{train}}) = \frac{1}{|\mathsf{D}_{\mathsf{train}}|} \sum_{\mathbf{x}^o, y \in \mathsf{D}_{\mathsf{train}}} \mathbb{E}_{p_{\Phi}(\mathbf{X}^m | \mathbf{x}^o)} \big[l(y, f_{\Theta}(\mathbf{x})) \big]$$

For one tree and using loss = MSE, can be computed exactly:

$$\theta_{\ell}^* = \frac{\sum_{\mathbf{x}^o, y \in \mathsf{D}_{\mathsf{train}}} y \cdot p_{\ell}(\mathbf{x}^o) / p(\mathbf{x}^o)}{\sum_{\mathbf{x}^o, y \in \mathsf{D}_{\mathsf{train}}} p_{\ell}(\mathbf{x}^o) / p(\mathbf{x}^o)}$$

More scenarios such as bagging/boosting in the paper.

Preliminary Experiments



