

# Constructing the bayesian maps

Juliette Lavoie

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## 1 Bayes' rules

I build this probability from 38 WT embryos in the time window 40-44min.  
This comes from

DataPetkova/Data/Gap/gap\_data\_raw\_dorsal\_wt.mat

$P(x * | h_i) = \frac{P(\{h_i\}|x*)P_x(x*)}{Z(\{h_i\})}$  is the probability of being at  $x^*$  for given  $h_i$ s.  
This is the function P<sub>xh</sub>() in my code.

$P(\{h_i\}|x) = \frac{e^{-\chi_K^2(\{h_i\},x)/2}}{\sqrt{(2\pi)^K \det(C(x))}}$  where K is the number of  $h_i$ s (=2) and C is the covariant matrix. This is the function Ph<sub>x</sub>() in my code. It is called the bayesian posterior. h1s and h2s are array with all possible hidden nodes in this time window(40-44 min). avg1 and avg2 are the averages of these array.

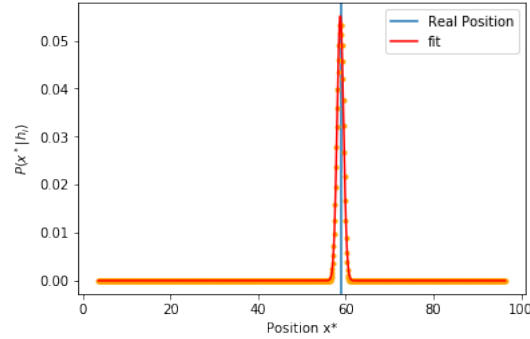
$P_x$  is constant. The probability of being at any position is 1/length of position array.

$Z = \sum_x P(\{h_i\}|x)P_x$  is the normalization. The sum of  $P(x * | h_i)$  for all  $x^*$  should be 1.

## 2 Building the distribution

If you want to find the position  $x$  for given  $h_i$ . You need to calculate  $P(x * | h_i)$  for all  $x^*$  along the AP axis.

You can plot all the probability for each  $x^*$ . This distribution should look gaussian( most of the time). By fitting the gaussian, you get the standard deviation. The mean std for all  $x$  and all embryos should be around 1.



### 3 Building the map

Code in commonFunctions.py in function makeAvgMap().

The map all the distributions for each x on the same image. Hence, we plot x vs x\* with  $P(x^* | h_i(x))$  as the 3rd dimension on the colormap.

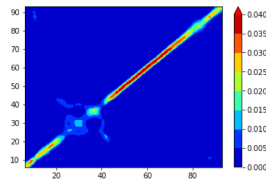
To decode, you should use the map for a single embryo. However, Petkova( and I) plot average maps for all embryos.

pseudo code:

```

For loop on embryos
  for loop on x
    Calculate hidden nodes for this x
      for loop on x* (called y in code)
        Calculate  $P(x^* | \{h_i\})$ 
        fit the distribution found in previous loop
        Save (in allRow) the distribution( called row even if it will be a column, my bad)
      Calculate mean of std of all the fits
      Save each individual map( called allRow)
    Calculate mean of std of all position
  Average all individual map to create an average map

```



## 4 Building mutant/different time window maps

Use  $P(x * |h_i)$  from WT around 42 min, but put in  $h_i$  from your new data set.