Partial Differential Equations in Finance

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May 22, 2025

Overview of Topics

- Charting theory and nature of boundary and initial conditions
- Explicit solutions, including original Black-Scholes formula
- Special problems arising when there are free boundaries

Key Questions in Financial PDEs

- Physical interpretation of the equations?
- ▶ Mathematical properties of the solution?
- Techniques for obtaining explicit solutions?

PDEs in finance:

- Fundamental equations (e.g., Black-Scholes)
- Linear vs. nonlinear problems

Considerations for PDEs in Finance

- 1. Does the equation make sense as a well-posed problem?
 - ► Appropriate boundary or initial/final conditions?
 - Nature of the mathematical problem?
 - Smooth or discontinuous solutions?
- 2. Can we develop analytical tools to solve the equation?
- 3. How should we solve the equation numerically if necessary?

First Order Linear PDE

Consider the equation:

$$\alpha(s,t)\frac{\partial u}{\partial s} + \beta(s,t)\frac{\partial u}{\partial t} = \gamma(s,t)u(t)$$

Linearity Property

If u_1, u_2 are solutions, then $c_1u_1 + c_2u_2$ is also a solution for constants c_1, c_2 .

Proof.

Substitute $u = c_1u_1 + c_2u_2$ into the PDE and use linearity of derivatives.

Constant Coefficient Case

When α, β are constants and $\gamma \equiv 0$:

$$\alpha_0 \frac{\partial u}{\partial s} + \beta_0 \frac{\partial u}{\partial t} = 0 \quad (4.2)$$

Define the vector $\vec{v} = (\alpha_0, \beta_0)$ with $\beta_0 \alpha_0 \neq 0$. The directional derivative:

$$\nabla_{\vec{v}} u = \langle \alpha_0, \beta_0 \rangle \cdot \langle \frac{\partial u}{\partial s}, \frac{\partial u}{\partial t} \rangle$$

Thus, (4.2)
$$\Leftrightarrow \nabla_{\vec{v}} u \equiv 0$$

Characteristic Coordinates

Introduce new coordinates:

$$\xi = \beta_0 s + \alpha_0 t, \quad \zeta = \beta_0 s - \alpha_0 t$$

The Jacobian determinant:

$$\begin{vmatrix} \beta_0 & \alpha_0 \\ \beta_0 & -\alpha_0 \end{vmatrix} = -2\alpha_0\beta_0 \neq 0$$

Computing $\frac{\partial u}{\partial \xi}$:

$$\frac{\partial u}{\partial \xi} = \beta_0 \frac{\partial u}{\partial s} + \alpha_0 \frac{\partial u}{\partial t} \equiv 0$$

Therefore, u depends only on ζ : $u = F(\zeta)$

Characteristics and Information Propagation

- $\xi = \beta_0 s \alpha_0 t$ is called a **characteristic**
- Characteristics represent directions in which information propagates
- Analogous to constants of integration in ODEs

Important Note

Without boundary conditions, the solution remains arbitrary (like the constant ${\it C}$ in ODEs)

General Second-Order Linear PDE

Consider the general form in two variables:

$$a(x,t)u_{xx}+2b(x,t)u_{xt}+c(x,t)u_{tt}+d(x,t)u_{x}+e(x,t)u_{t}+f(x,t)u=g(x,t)u_{xt}+g(x,t)u_{$$

where $a,b,c,d,e,f,g:\mathbb{R}\times\mathbb{R}\to\mathbb{R}$ are coefficient functions.

Principal Part

The highest-order terms form the principal part:

$$L_p(u) = au_{xx} + 2bu_{xt} + cu_{tt}$$

Classification of PDEs

Define the discriminant:

$$\Delta(L) = b^2 - ac : (x, t) \mapsto b(x, t)^2 - a(x, t)c(x, t)$$

The PDE is classified as:

- ▶ **Hyperbolic** if $\Delta(L) > 0$ (e.g., wave equation)
- ▶ **Parabolic** if $\Delta(L) = 0$ (e.g., heat equation)
- ▶ **Elliptic** if $\Delta(L)$ < 0 (e.g., Laplace equation)

Coordinate Transformations

Definition

A transformation $(\xi, \eta) = (\xi(x, t), \eta(x, t))$ is called a change of coordinates if the Jacobian is non-zero:

$$J := \xi_x \eta_t - \xi_t \eta_x \neq 0$$

Theorem

The type of a linear second-order PDE in two variables is invariant under a change of coordinates.

Proof of Invariance

Under transformation (ξ, η) , the principal part becomes:

$$Au_{\xi\xi} + 2Bu_{\xi\eta} + Cu_{\eta\eta}$$

where:

$$A = a\xi_x^2 + 2b\xi_x\xi_t + c\xi_t^2$$

$$B = a\xi_x\eta_x + b(\xi_x\eta_t + \xi_t\eta_x) + c\xi_t\eta_t$$

$$C = a\eta_x^2 + 2b\eta_x\eta_t + c\eta_t^2$$

The new discriminant satisfies:

$$\Delta_{new} = AC - B^2 = J^2(b^2 - ac) = J^2\Delta_{original}$$

Canonical Forms

- **Hyperbolic**: $u_{\xi\xi} u_{\eta\eta} = \text{lower order terms (wave equation)}$
- **Parabolic**: $u_{\xi\xi} = \text{lower order terms (heat equation)}$
- **Elliptic**: $u_{\xi\xi} + u_{\eta\eta} = \text{lower order terms (Laplace equation)}$

Examples

- Wave equation: $u_{tt} = c^2(u_{xx} + u_{yy})$
- ▶ Heat equation: $u_t = k(u_{xx} + u_{yy})$
- ► Laplace equation: $u_{xx} + u_{yy} = 0$

Simplification Through Coordinates

A proper linear change of coordinates can transform:

- Hyperbolic equations to $u_{\xi\eta}=0$
- ▶ Parabolic equations to $u_{\xi\xi} = 0$
- ▶ Elliptic equations to $u_{\xi\xi} + u_{\eta\eta} = 0$

Important Note

The classification determines:

- Nature of characteristics
- Appropriate boundary conditions
- Solution techniques

Heat Equation

The fundamental heat equation:

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

Physical interpretation:

- u(x, t) represents temperature distribution along a thin insulated rod
- Models heat diffusion over time

Mathematical Properties

Key characteristics:

- Linear equation (superposition principle applies)
- Second order in space (x)
- First order in time (t)
- Parabolic type (discriminant $\Delta = 0$)

Analytic Solutions

Solutions are analytic functions of x:

- For any $t^* > 0$ and $a < x_0 < b$
- $u(x, t^*)$ can be expressed as a convergent power series in $(x x_0)$

Solution Behavior

Important features:

- Smoothing property: Solutions become instantly smooth for t > 0
- Infinite propagation speed: Initial disturbances spread infinitely fast
- Maximum principle: Extreme values occur only at initial/boundary conditions

Financial Interpretation

Analogous to:

- Diffusion of volatility in option pricing
- ► Smoothing of price shocks over time

Dirichlet Boundary Value Problem

Heat equation on finite interval:

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}, \quad -L < x < L, \ t > 0$$

With conditions:

- lnitial condition: $u(x,0) = u_0(x)$
- Boundary conditions:
 - $u(-L, t) = g_1(t)$ (left end temperature)
 - $u(L, t) = g_2(t)$ (right end temperature)

Physical Interpretation

Models heat diffusion in a finite rod with controlled end temperatures

Neumann Boundary Value Problem

Same heat equation with flux conditions:

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}, \quad -L < x < L, \ t > 0$$

With conditions:

- ▶ Initial condition: $u(x,0) = u_0(x)$
- ► Flux boundary conditions:
 - $-\frac{\partial u}{\partial x}(-L,t) = h_1(t)$ (left end flux)
 - $ightharpoonup rac{\partial u}{\partial x}(L,t) = h_2(t)$ (right end flux)

Physical Interpretation

Models heat diffusion with controlled heat flow at boundaries

Infinite Domain Problem

Taking $L \to \infty$:

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}, \quad x \in \mathbb{R}, \ t > 0$$

With initial condition:

$$u(x,0)=u_0(x)$$

Growth Conditions

For well-posedness:

- $ightharpoonup u_0(x)$ piecewise continuous (finite jumps allowed)

Semi-Infinite Domain with Mixed Conditions

Example problem:

$$u_t = u_{xx}, \quad 0 < x < \infty, \ t > 0$$

With conditions:

- ▶ Initial condition: $u(x,0) = u_0(x)$ (sufficiently smooth)
- ▶ Boundary condition: u(0, t) = g(t)
- Growth conditions at infinity

Well-Posedness

The problem is well-posed when:

- ▶ Initial/boundary conditions are compatible
- Growth conditions are satisfied
- Solution exists, is unique, and depends continuously on data