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2 CONTENTS

Chapter 1

Some PL topology

In this chapter we will collect some basic facts from the piecewise-linear category. Most of the proofs are omitted and can be found in standard references like [1], [2]. If the reader is already familiar with basics from PL topology, the chapter may be skipped without loss of continuity.

Definition 1. Let $v_0, ..., v_k \in \mathbb{R}^n$ be points in some affine space such that $\{v_1 - v_0, ..., v_k - v_0\}$ is a set of linearly independent vectors. We call

$$[v_0,...,v_k] := \left\{ \lambda_0 v_0 + ... + \lambda_k v_k \middle| \sum_{i=0}^k \lambda_i = 1 \text{ and } \lambda_i \ge 0 \text{ for all } i \right\}$$

the simplex spanned by $\{v_0, ..., v_k\}$. Its dimension is k and we call it a k-simplex for short. The points that span a simplex are called vertices. For a simplex σ we say that τ is a **face** of σ if τ is a simplex spanned by a nonempty subset of the vertices of σ and we abbreviate this by writing $\tau < \sigma$.

Definition 2. A simplicial complex K is a set of simplices that satisfies the following conditions:

- Every face of a simplex in K is also contained in K.
- The intersection of any two simplices $\sigma, \tau \in K$ is either empty or a face of both σ and τ .

We define the **plyhedron** of K by $|K| := \bigcup \{\sigma | \sigma \in K\}$. The **p-skeleton** of K is given by $K^{(p)} = \{\sigma \in K | dim(\sigma) \leq p\}$. A **subcomplex** of K is a subset $L \subset K$ such that L itself is a simplicial complex. We denote the set

of vertices of K by V(K). The **dimension** of K is the largest dimension of any simplex contained in K. If no such maximum exists, we say that K is of dimension ∞ . K is said to be of **pure dimension** n if every simplex of K is a face of some n-simplex in K.

Definition 3. Let K be a simplicial complex of pure dimension n. The **boundary** Bd(K) of K is defined to be the (possibly empty) subcomplex of K of pure dimension n-1, whose (n-1)-simplices are those (n-1)-simplices of K which are incident to precisely one n-simplex in K.

Definition 4. For a simplicial complex K and a simplex $\sigma \in K$, we call

$$St(\sigma, K) = \{ \rho \in K | \rho < \tau, \sigma < \tau \text{ for some } \tau \in K \}$$

the star of σ in K. The link of σ in K is given by

$$Lk(\sigma, K) = \{ \rho \in St(\sigma, K) | \sigma \cap \rho = \emptyset \}.$$

Definition 5. Suppose that there are two simplicial complexes K and K' such that |K| = |K'|. If every simplex of K' is contained in some simplex of K, we say that K' is a **subdivision** of K and write $K' \triangleleft K$.

Example 1. Given a simplicial complex K there is always an inductive process that produces a subdivision of K. Assume that $K^{(p-1)}$ has already been subdivided and let $\sigma = [v_0, ..., v_p]$ be a p-simplex in K. The point $\hat{\sigma} = \frac{1}{p+1} \sum_{i=0}^p v_i$ lies in the interior of σ and is called its **barycenter**. The **barycentric subdivision** of σ is the decomposition of σ into the p-simplices $[\hat{\sigma}, w_0, ..., w_{p-1}]$ where, inductively, $[w_0, ..., w_{p-1}]$ is a (p-1)-simplex in the barycentric subdivision of a face $[v_0, ..., \overline{v_i}, ..., v_p]$. (In this notation, the vertex v_i is omitted.) Continuing this procedure for every p-simplex σ leads to a decomposition of all simplices in $K^{(p)}$. The induction starts at p=0 when the barycentric subdivision of a 0-simplex $[v_0]$ is just $[v_0]$ itself. It is guaranteed that this process delivers a subdivision $K^1 \triangleleft K$, called the **first barycentric subdivision** of K. For details, see [2]. More generally, the r-th barycentric subdivision is inductively given by $K^r = (K^{r-1})^1$.

Definition 6. A topological space X is said to be **triangulable** if there exists a simplicial complex T and a homeomorphism $\phi: |T| \to X$. The triple (T, X, ϕ) is called a **triangulation** of X. In this situation we will simply say that T is a triangulation of X, by abuse of notation.

Definition 7. A **PL** space is a pair (X, \mathcal{T}) consisting of a topological space X and a class \mathcal{T} of locally finite triangulations of X which satisfies the following conditions:

- If $T \in \mathcal{T}$ then $T' \in \mathcal{T}$ for any subdivision $T' \triangleleft T$.
- If $T, T' \in \mathcal{T}$ then there exists $T'' \in \mathcal{T}$ such that both $T'' \triangleleft T$ and $T'' \triangleleft T'$.

We will simply write X for a PL space (X, \mathcal{T}) if there is no danger of confusion. A **closed PL subspace** of X is a subcomplex of a suitable triangulation of X.

Definition 8. Given simplicial complexes K and L we call a map $f: |K| \to |L|$ simplicial if f maps each simplex of K linearly onto some simplex of L. A map $g: |K| \to |L|$ between PL spaces is said to be a PL map if there exist subdivisions $K' \lhd K$ and $L' \lhd L$ such that $g: K' \to L'$ is simplicial.

Note that a simplicial map $f: K \to L$ is given by linear extension of a (set-theoretic) function $V(K) \to V(L)$.

Definition 9. A simplicial isomorphism between two simplicial complexes K and L is given by a bijection $f: V(K) \to V(L)$ such that $[v_0, ..., v_k]$ is a k-simplex in K if and only if $[f(v_0), ..., f(v_k)]$ is a k-simplex in L. In particular, extending f linearly yields a homeomorphism between the underlying polyhedra |K| and |L|. A map $g: |K| \to |L|$ between PL spaces is a PL isomorphism if there exist subdivisions $K' \lhd K$ and $L' \lhd L$ such that $g: |K'| \to |L'|$ is a simplicial isomorphism.

Theorem 1. (Simplicial Approximation Theorem). Let $f: |K| \to |L|$ be a map between polyhedra. Then there exist subdivisions $K' \lhd K$ and $L' \lhd L$ and a simplicial map $g: |K'| \to |L'|$ which is ϵ -homotopic to f, i.e. if $\epsilon: |L| \to (0, \infty)$ is a map, then there is a map $H: |K| \times [0, 1] \to |L|$ with $H(|K| \times \{0\}) = f$, $H(|K| \times \{1\}) = g$ and $diam(H(\{x\} \times [0, 1])) < \epsilon(f(x))$.

Proof. See
$$[3]$$
, e.g.

JOIN DIMENSION PL MANIFOLDS

Definition 10. A 0-dimensional PL stratified pseudomanifold is a countable set of points with the discrete topology. An n-dimensional PL stratified pseudomanifold X is a PL space together with a filtration of closed PL subspaces

$$X = X_n \supset X_{n-1} = X_{n-2} \supset \dots \supset X_0 \supset X_{-1} = \emptyset$$

such that the following conditions are satisfied:

- Every $X_{n-k} X_{n-k-1}$ is a (possibly empty) PL manifold of dimension n-k.
- $X X_{n-2}$ is dense in X.
- Local normal triviality: For every point $x \in X_{n-k} X_{n-k-1}$ there exists an open neighborhood U of x in X and a compact PL stratified pseudomanifold L of dimension k-1 with filtration

$$L = L_{k-1} \supset L_{k-3} \supset \dots \supset L_0 \supset L_{-1} = \emptyset$$

and a PL isomorphism

$$\phi: U \to \mathbb{R}^{n-k} \times c^{\circ}L$$

(where c° denotes the open cone) which restricts to PL isomorphism $\phi_{|}: U \cap X_{n-l} \to \mathbb{R}^{n-k} \times c^{\circ}L_{k-l-1}$. We say that ϕ is **stratum**-preserving.

Chapter 2

A bordism approach to homology theories

The purpose of this chapter is to give a geometric treatment of homology theories, as described by S. Buoncristiano, C. Rourke and B. Sanderson in [5]. First we use local link properties to determine a class of polyhedra. Then, in an analogous manner to ordinary bordism theory, we define groups of bordism classes of maps, whose domains lie in the polyhedral class defined before. We observe that interesting examples of generalized homology theories can be interpreted in this way, including ordinary homology, $(\mathbb{Z}/2)$ -homology and PL bordism theory.

For the rest of this chapter we make the convention that every polyhedron is PL and of pure dimension.

Definition 11. Suppose we are given a class \mathcal{L}_n of (n-1)-polyhedra which is closed under PL isomorphism. Then a **closed** \mathcal{L}_n -manifold is a polyhedron M such that the link of each vertex of M lies in \mathcal{L}_n .

Definition 12. A theory with singularities \mathcal{L} consists of a class \mathcal{L}_n of (n-1)-polyhedra for every n=0,1,... which satisfy the following compatibility conditions:

- 1. each member of \mathcal{L}_n is a closed \mathcal{L}_{n-1} -manifold.
- 2. $S\mathcal{L}_{n-1} \subset \mathcal{L}_n$ (i.e. the suspension of an (n-1)-link is always an n-link).
- 3. $c\mathcal{L}_{n-1} \cap \mathcal{L}_n = \emptyset$ (i.e. the cone of an (n-1)-link is never an n-link).
- 4. $S(c\mathcal{L}_{n-2}), c(c\mathcal{L}_{n-2}) \subset c\mathcal{L}_{n-1}$.

Then an \mathcal{L}_n -manifold with boundary consists of a polyhedron whose links of vertices lie either in \mathcal{L}_n or in $c\mathcal{L}_{n-1}$. The boundary consists of the subpolyhedron spanned by vertices whose links lie in the latter class.

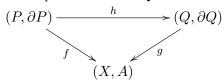
Proposition 1. Let W be an \mathcal{L}_n -manifold with boundary in a fixed theory with singularities \mathcal{L} . Then the boundary of W, denoted by ∂W , is well-defined and is itself a closed \mathcal{L}_{n-1} -manifold.

Proof. By the third requirement of Def. 12, the link of a vertex in W is contained in $c\mathcal{L}_{n-1}$ if and only if it is not contained in \mathcal{L}_n . This shows that ∂W is well-defined. For the second statement, note that ∂W is a subpolyhedron by definition and that if v is a vertex in ∂W with Lk(v,W) = cL for some $L \in \mathcal{L}_{n-1}$, then $Lk(v,\partial W) = L$.

DEFINITION BERARBEITEN:
LINKS STABIL BZGL SUBDIVISION?
KOMPAKTE POLYEDER
ORIENTIERUNGEN
EVTL ORIENTIERUNGSERHALTENDE ISOMORPHISMEN

Definition 13. Let \mathcal{L} be a theory with singularities and let (X, A) be a pair of topological spaces (i.e. $A \subset X$ is a subspace). For two compact, oriented \mathcal{L}_i -manifolds (possibly with boundary) P, Q assume that we are given continuous maps $f:(P,\partial P)\to (X,A)$ and $g:(Q,\partial Q)\to (X,A)$. An **oriented** bordism between f and g is a triple (F,W,Z), where W is a compact, oriented \mathcal{L}_{i+1} -manifold with boundary, s.t. $\partial W\cong P\sqcup -Q\cup Z$, Z is a compact, oriented \mathcal{L}_i -manifold (possibly with boundary), s.t. $\partial Z\cong \partial P\sqcup -\partial Q$ and $F:(W,Z)\to (X,A)$ is a continuous map with $F|_P=f$ and $F|_Q=g$. If there exists a bordism between them, f and g are said to be bordant and we abbreviate this by writing $f\sim_{bord} g$. We call F a null-bordism for f if $Q=\emptyset$ and we say that f is null-bordant if there exists a null-bordism for f.

Definition 14. With the notation as in the previous definition, $f:(P, \partial P) \to (X, A)$ and $g:(Q, \partial Q) \to (X, A)$ are called **isomorphic** if there exists a PL isomorphism $h: P \to Q$ s.t. the diagram



commutes. Let $Isom_i^{\mathcal{L}}(X,A)$ be the set of isomorphism classes of maps

 $f:(P,\partial P)\to (X,A)$, where P varies over all compact \mathcal{L}_i -manifolds of a fixed theory \mathcal{L} .

Proposition 2. The relation \sim_{bord} is an equivalence relation on $Isom_i^{\mathcal{L}}(X,A)$.

Proof. Let $[f:(P,\partial P)\to (X,A)]\in Isom_i^{\mathcal{L}}(X,A)$ and let I=[0,1] denote the closed interval. The only links in I are S^0 and pt, and so there are four types of links in $P \times I$, namely $S^0 * L \cong SL$, $pt * L \cong cL$, $S^0 * cL' \cong S(cL')$ and $pt.*cL' \cong c(cL')$, where $L \in \mathcal{L}_i$ and $L' \in \mathcal{L}_{i-1}$ are some links of P. The first statement of Def. 12 ensures that the first type of links is contained in \mathcal{L}_{i+1} and by the fourth statement all other types of links lie in $c\mathcal{L}_i$. There exists a canonical orientation of $P \times I$ s.t. $\partial (P \times I) = P \sqcup -P \cup \partial P \times I$. So, $P \times I$ is an oriented \mathcal{L}_{i+1} -manifold and we define $F:(P\times I,\partial(P\times I))\to(X,A)$ by F(x,s) = f(x) for every $s \in I$. Then $f \sim_{bord} f$ via F and this bordism is well-defined on the isomorphism class of f, which shows reflexivity. For symmetry, we only need to obersve that disjoint union commutes, up to isomorphism. Now suppose $f \sim_{bord} g$ and $g \sim_{bord} h$ via bordisms F and G, respectively, where $g:(Q,\partial Q)\to (X,A), F:(W,Z)\to (X,A)$ and $G: (W', Z') \to (X, A)$. If $W \cup_Q W'$ denotes the space obtained by glueing W and W' along Q, we let $H: W \cup_Q W' \to X$ be the unique map with $H_{|W} = F$ and $H_{|W'}=G$. If v is any vertex in Q, we have Lk(v,W)=cLk(v,Q)=cLk(v,Q)Lk(v, W'), and therefore $Lk(v, W \cup_Q W') = SLk(v, Q)$, which lies in \mathcal{L}_{i+1} , by definition. Since the links of all other vertices remain unaltered, we see that $W \cup_Q W'$ is in fact an \mathcal{L}_{i+1} -manifold, which clearly is compact, as W and W' are. Moreover, we have $\partial(W \cup_Q W') = dom(f) \sqcup -dom(h) \cup (Z \cup_{\partial Q} Z')$ with $\partial(Z \cup_{\partial Q} Z') = \partial(dom(f)) \sqcup -\partial(dom(h))$, and the same argument as before shows that $Z \cup_{\partial Q} Z'$ is an \mathcal{L}_i -manifold. We conclude $f \sim_{bord} h$ via $H: (W \cup_Q W', Z \cup_{\partial Q} Z') \to (X, A)$, and again H is a well-defined bordism on isomorphism classes of f and h. This shows transitivity and completes the proof.

Definition 15. For a theory with singularities \mathcal{L} , we let

$$\Omega_i^{\mathcal{L}}(X,A) = Isom_i^{\mathcal{L}}(X,A) / \sim_{bord}$$

and call it the *i*-th (relative) \mathcal{L} -bordism set with base (X, A). Moreover, we define

$$\Omega_i^{\mathcal{L}}(X) = \Omega_i^{\mathcal{L}}(X,\emptyset)$$

and call it the *i*-th (absolute) \mathcal{L} -bordism set with base X.

Remark 1. 1. There is an obvious notion of unoriented \mathcal{L} -bordism by removing all references to orientations.

2. For the absolute case, note that $\Omega_i^{\mathcal{L}}(X)$ consists of bordism classes of maps $f: P \to X$, where P is a, necessarily closed \mathcal{L}_i -manifold. For some $g: Q \to X$, the bordism relation between f and g reduces to the existence of some compact, oriented \mathcal{L}_{i+1} -manifold W with $\partial W \cong P \sqcup -Q$ and a map $F: W \to X$ s.t. $F|_P = f$ and $F|_Q = g$.

So far, we have not discussed interactions of two \mathcal{L} -manifolds with each other. For example, the product of two \mathcal{L}_i -manifolds is not an \mathcal{L}_i -manifold, in general. However, the following is true:

Proposition 3. $\Omega_i^{\mathcal{L}}(X,A)$ is an abelian group with respect to disjoint union.

Proof. Let $[f:(P,\partial P) \to (X,A)], [g:(Q,\partial Q) \to (X,A)] \in \Omega_i^{\mathcal{L}}(X,A)$. Then $P \sqcup Q$ is an \mathcal{L}_i -manifold, as the links are unaltered by disjoint union, and so $f \sqcup g:(P \sqcup Q,\partial P \sqcup \partial Q) \to (X,A)$ represents a class in $\Omega_i^{\mathcal{L}}(X,A)$. Consequently, we let $[f] \sqcup [g] := [f \sqcup g]$. Suppose that f' and g' are representatives of [f] and [g], respectively, via bordisms F and G. Then $F \sqcup G$ is a bordism between $f \sqcup g$ and $f' \sqcup g'$, which shows that the above definition is a well-defined operation. Associativity and commutativity clearly hold. The identity element is given by the class of the empty map (and so by the class of any null-bordant map). If [-f] denotes the class of f with reversed orientation of its domain, we observe once again that $F:(P \times I, \partial(P \times I)) \to (X,A)$ with F(x,s) = f(x) is a bordism between f and -f. We conclude

$$[f] \sqcup [-f] = [f \sqcup -f] = 0$$

and so the inverse of [f] is given by [-f]. In the unoriented setting, we can remark that every class is self-inverse.

Chapter 3

The basic sets $Q_i^{\overline{p}}$

In this chapter we will define and study the so called "basic sets", originally introduced by M. Goresky and R. McPherson in [4]. Given a stratified PL pseudomanifold X and a perversity \bar{p} , we construct subpolyhedra $Q_i^{\bar{p}}$ of X for every $i \geq 0$. They are designed to give a connection between ordinary homology groups of these basic sets and the intersection homology groups of the whole space X.

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