



UNIVERSITÄT
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ZUKUNFT
SEIT 1386

Advanced Macroeconomics

Tutorial 7: Empirical Business Cycles & Stochastic Processes

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A time series is a collection of observations indexed by the date of each observation. Usually, we have collected data beginning at some particular date (say, $t = 1$) and ending at another (say, $t = T$):

$$(y_1, y_2, \dots, y_T)$$

- The first lag of a time series Y_t is Y_{t-1} ; its j th lag is Y_{t-j} .
- The first difference of a series, ΔY_t , is its change between periods $t - 1$ and t , that is, $\Delta Y_t = Y_t - Y_{t-1}$.
- The first difference of the logarithm of Y_t is $\Delta \ln(Y_t) = \ln(Y_t) - \ln(Y_{t-1})$.

Covariance Stationarity (Weak Stationarity)

A time series Y_t is weakly stationary if:

1. $\mathbb{E}[Y_t] = \mu_t = \mu < \infty$ for all t
2. $\text{Cov}(Y_t, Y_{t-j}) = \gamma_{j,t} = \gamma_j < \infty$ for all t and all j .

That is, a covariance stationary time series has no trend.

Example: Consider the AR(1) $Y_t = \rho Y_{t-1} + \varepsilon_t$ where $\varepsilon_t \sim \mathcal{N}(0, 1)$ and $\rho < 1$.

When allowing for a **deterministic trend**, a process is called trend stationary

$$Y_t = \mu + \beta t + \varepsilon_t$$

since taking the deterministic trend off Y_t , we are left with a stationary model.

Question 1

Download data for GDP, consumption, and investment for Germany. Choose quarterly data for at least 10 years (for example, from 1996 to 2023). A reliable source for aggregate time series is provided by **FRED** or **Eurostat**. Make sure to choose *real* (at constant prices) and *seasonally-adjusted* time series. For the following exercises, you might use the software package of your choice (e.g., Matlab, Stata, R).

Transformation of time series: Why look at $\log(GDP_t)$ and not GDP_t ?

Question 1.1

Take the logarithm of the series before detrending the data. Why is the logarithm a useful transformation?

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Suppose the growth rate of GDP is g : $Y_{t+1} = (1 + g)Y_t$

A simple derivation yields a useful approximation: The log difference is (approximately) equal to the growth rate

$$\begin{aligned}\log(Y_{t+1}) &= \log((1 + g)Y_t) \\ &= \log(1 + g) + \log(Y_t) \\ &\approx g + \log(Y_t) \Rightarrow \log(Y_{t+1}) - \log(Y_t) \approx g\end{aligned}$$

Motivation: How can we see the business cycle in the data?

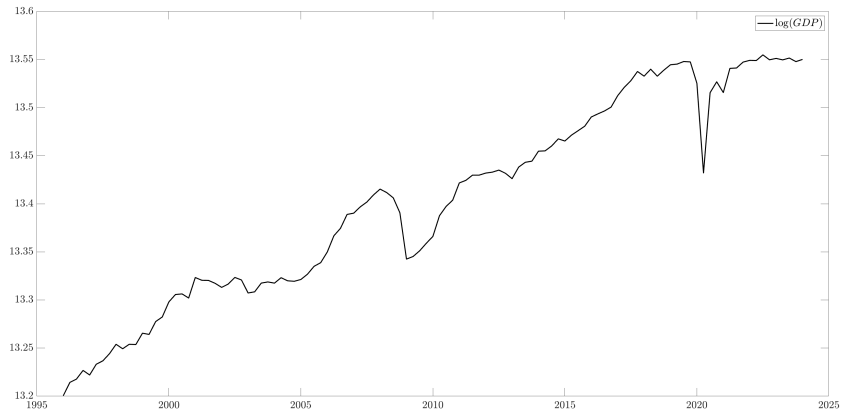


Figure 1: Real German GDP (seasonally-adjusted) as a measure of real activity.

Question 1.2

Using time series data on German GDP, estimate a linear trend model using ordinary least squares (OLS). Once you have estimated the linear trend, plot the observed GDP values and the fitted trend line on the same graph. Briefly discuss the limitations of using a linear trend model to capture GDP fluctuations over time

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Decompose $\log(\text{GDP})$ into a trend (z_t) and cyclical (c_t) component:

$$\log(\text{GDP}_t) = y_t = z_t + c_t$$

We could simply estimate a linear (deterministic) trend

$$\log(\text{GDP}_t) = \beta_0 + \beta_1 t + \varepsilon_t$$

where β_1 is the trend growth rate and ε_t are the deviations from the trend.

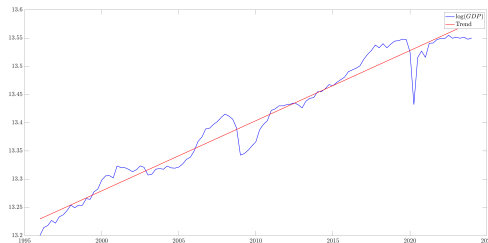


Figure 2: Estimated linear trend for German GDP.

Estimating a linear trend: Result depends on the sample over which we estimate the trend

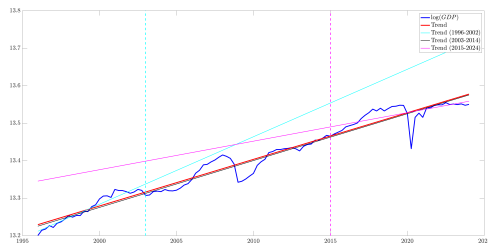


Figure 3: Different estimated linear trends for German GDP.

- Structural changes in the economy can affect the trend growth rate (e.g., population growth may change, pandemic)
- To capture structural factors, we need to allow for time variation in the trend growth rate
- Define the trend growth rate

$$\frac{Z_t - Z_{t-1}}{Z_{t-1}} = \frac{Z_t}{Z_{t-1}} - 1 \simeq \log \frac{Z_t}{Z_{t-1}} = z_t - z_{t-1}$$

Denote the change of the trend growth rate by v_t

$$(z_t - z_{t-1}) - (z_{t-1} - z_{t-2}) = v_t$$

Hodrick–Prescott filter

The Hodrick–Prescott filter formally captures the tradeoff between a smooth and a time varying trend growth rate:

$$\min \sum_t c_t^2 + \lambda \sum_t v_t^2 = \min \left\{ \sum_{t=1}^T (y_t - \tau_t)^2 + \lambda \sum_{t=1}^T (\Delta z_t - \Delta z_{t-1})^2 \right\}$$

where λ captures how much one cares about the smoothness of the trend and $\Delta z_t = z_t - z_{t-1}$.

Allowing for a change in trend growth lowers $\sum_t c_t^2$ but increases $\sum_t v_t^2$

Question 1.3 and 1.4

Use the Hodrick-Prescott (1997) filter to detrend the data with a smoothing coefficient of $\lambda = 1600$ (built-in function in Matlab/Stata/EViews, otherwise available [here](#)). Plot the detrended series, the trend component, and the raw data for all three variables.

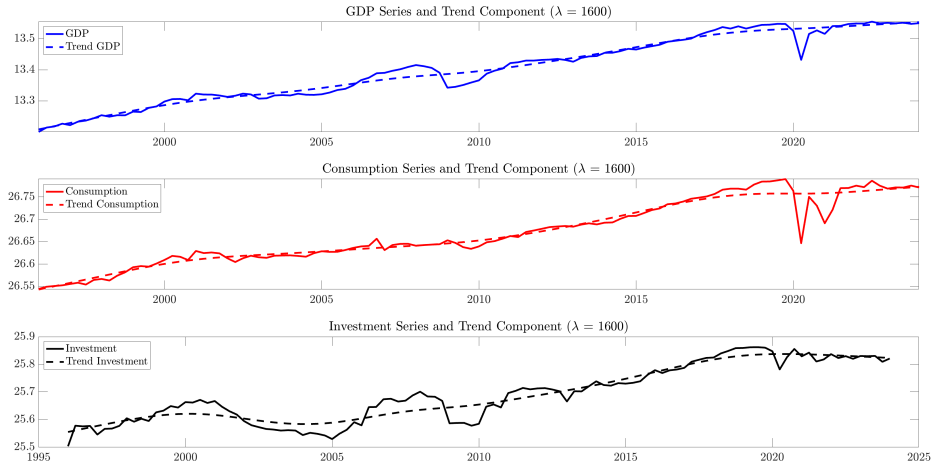


Figure 4: Time series and estimated trend.

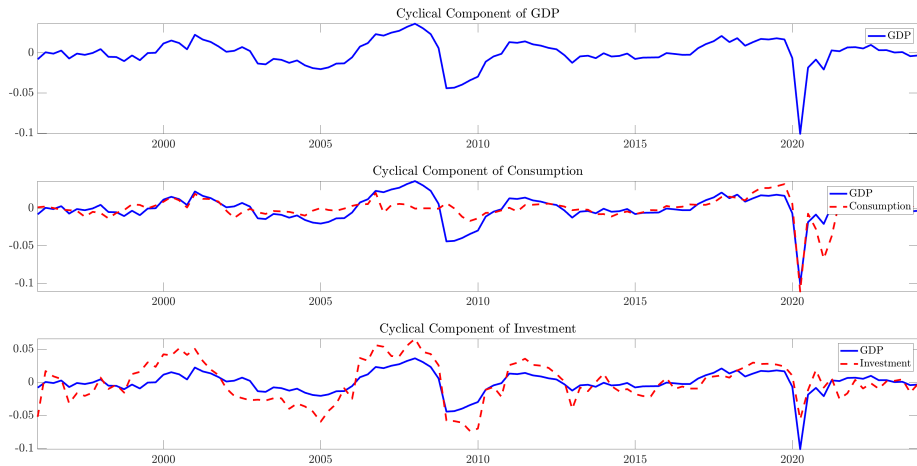


Figure 5: Estimated cyclical component.

Question 1.5

Briefly discuss the role of λ for the estimated trend. What are potential disadvantages of the Hodrick-Prescott filter?

The HP filter formally captures the tradeoff between a smooth and a time varying trend growth rate:

$$\min \sum_t c_t^2 + \lambda \sum_t v_t^2 = \min \left\{ \sum_{t=1}^T (y_t - \tau_t)^2 + \lambda \sum_{t=1}^T (\Delta z_t - \Delta z_{t-1})^2 \right\}$$

where λ captures how much one cares about the smoothness of the trend and $\Delta z_t = z_t - z_{t-1}$.

- For $\lambda \rightarrow 0$ we get

$$\sum_t (\log(Y_t) - z_t)^2$$

The time trend z_t that minimizes this loss function is simply $\log(Y_t) = z_t \Rightarrow$
There is no cycle!

- As $\lambda \rightarrow \infty$, the Hodrick-Prescott filter is a linear time trend.
- Ravn and Uhlig (2002) suggest to adjust the HP filter to the frequency of the observations: $\lambda_{\text{quarterly}} = 1600$, $\lambda_{\text{annual}} = 1600/4^4 = 6.25$ and $\lambda_{\text{monthly}} = 1600 \cdot 3^4$.

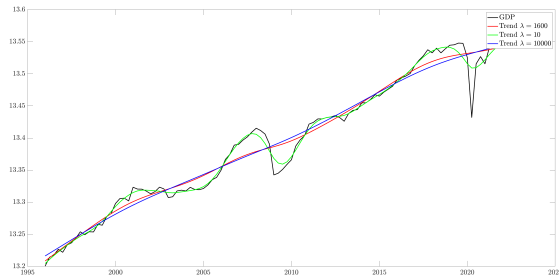


Figure 6: The effect of different λ on the estimated trend

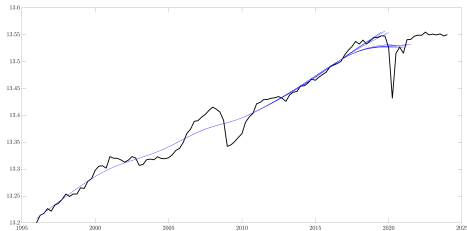


Figure 7: Instability of the HP trend at the margin - GDP trend for Germany from 2019:Q2 to 2021:Q2

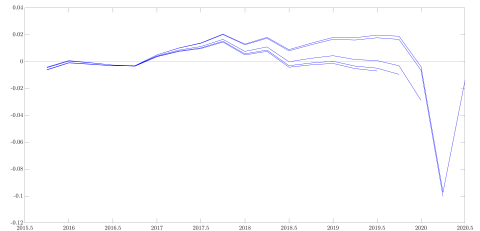


Figure 8: Instability of the HP cycle at the margin - GDP cycle for Germany from 2019:Q2 to 2020:Q3

- HP filter offers a reasonable approach to detrending GDP and is widely used but there exist other filters.
- HP filter uses unknowable future values that could not be recognized in real-time and the filter has an end-of-sample bias.
- Hamilton (2018, *Why You Should Never Use the Hodrick-Prescott Filter*) argues that the HP filter introduces spurious dynamic relations that have no basis in the underlying DGP
 - Detrending a random walk can generate spurious dynamics
 - Suppose GDP_t is $I(1)$, and the c_t would be white noise; the cycle would be random and exhibit no smooth cycles
- Hamilton (2018) proposes an alternative to isolate the cyclical component of a non-stationary time series, avoiding its drawbacks, but it can alter the variances of the different frequencies captured in an estimated cyclical component (Schüler, 2024).

How does consumption vary with the business cycle?

Question 1.6

Calculate the standard deviations of consumption and investment relative to that of GDP.

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- We get $\sigma_i = 0.0299 > \sigma_y = 0.0174 > \sigma_c = 0.016$ which yields the following ratios:

$$\frac{\sigma_c}{\sigma_y} = 0.9228 \quad \frac{\sigma_i}{\sigma_y} = 1.7193$$

- Consumption and investment are procyclical.
- Consumption is less volatile than output, investment is more volatile than output.

Question 2.1

Consider the stochastic process for technology in the baseline RBC model from the lecture given by

$$\ln A_t = \bar{A} + gt + \tilde{A}_t \quad \text{with} \quad \tilde{A}_t = \rho_A \tilde{A}_{t-1} + \varepsilon_{A,t},$$

where \bar{A} is a constant, g denotes the deterministic growth rate and $\varepsilon_{A,t} \stackrel{i.i.d.}{\sim} N(0, \sigma_A^2)$ is a technology shock. A_0 is given.

Express $\ln A_1$, $\ln A_2$ and $\ln A_3$ in terms of $\ln A_0$, $\varepsilon_{A,1}$, $\varepsilon_{A,2}$, $\varepsilon_{A,3}$, \bar{A} and g .

Question 2.2

What are the time-zero expectations of $\ln A_1$, $\ln A_2$, $\ln A_3$ and $\ln A_\infty$?

Question 2.3

Suppose that technology is only driven by the stochastic term \tilde{A}_t , i.e. set $\bar{A} = g = 0$, and assume $A_0 = 1$ and $\rho_A = 0.5$. Compute $\ln A_t$ for $t = \{1, \dots, 5\}$ given that

- a) no shock hits the economy.
- b) a one-time unity shock hits the economy in period 1, i.e. $\varepsilon_{A,1} = 1$.

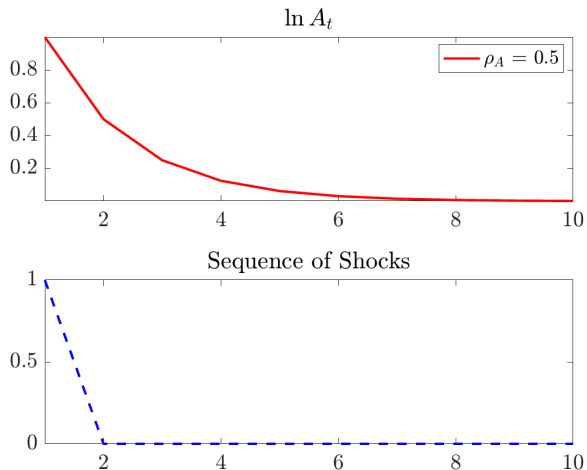


Figure 9: Stochastic process for technology for $\rho_A = 0.5$.

Question 2.4

Repeat 3b) for the cases $\rho_A = 0$, $\rho_A = 1$, $\rho_A = 1.5$.

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$\ln A_t$	$\rho_A = 0$	$\rho_A = 1$	$\rho_A = 1.5$
$\ln A_1$	1	1	1
$\ln A_2$	0	1	1.5
$\ln A_3$	0	1	2.25
$\ln A_4$	0	1	3.375
$\ln A_5$	0	1	5.0625

Question 2.4.: Role of persistence in the AR-technology process

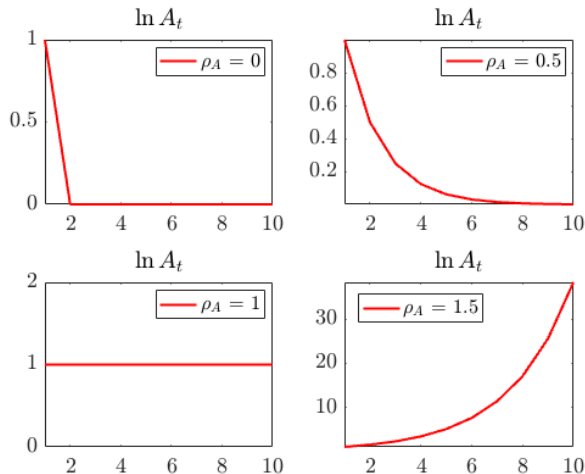


Figure 10: Stochastic process for technology for $\rho_A = 0.0$, $\rho_A = 0.5$, $\rho_A = 1$, and $\rho_A = 1.5$.

- Economic fluctuations do not underly simple repeating patterns.
- The trend observed in the data doesn't seem to be as rigid as a deterministic trend.
- We can use the HP filter to extract the trend and cycle, but you need to be careful using the HP filter.
- Investment is more volatile than output. Output is more volatile than consumption.
- In the RBC Model (Problem sets 10 and 11), we want to match the cyclicalilty of the data using a simple model.

Further Reading:

- Mitman, Kurt (2024): **Real Business Cycles**. In: **Macroeconomics**. Chapter 13.1. to 13.3.2. for a discussion of the HP filter and business cycles.
- Hansen (2023): **Econometrics**. Chapter 14.1-14.21 and 14.41 for a technical introduction of AR-processes and detrending.