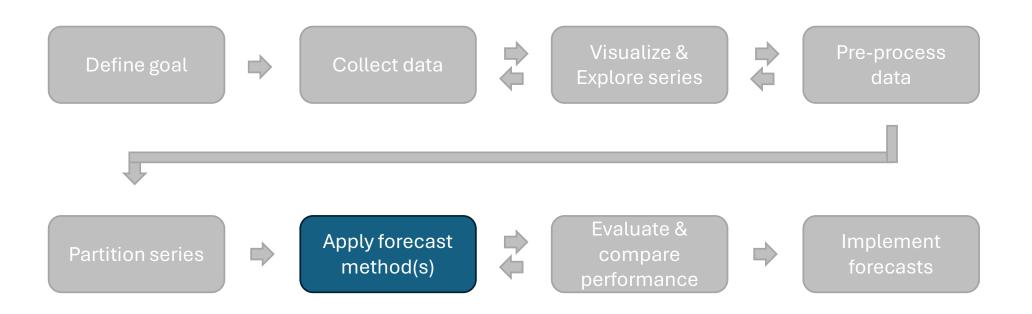
Time series Forecasting

Part 2: Smoothing Methods

The forecasting process



Components of a Time Series - Recap

- 1. Level (always present)
- 2. Trend: steady increase/decrease over time.
- **3. Seasonality**: pattern that repeats itself every season
- 4. Random **noise** (always present)

Reminder: Modeling Principles

Time series Analysis

Reasonableness and parsimony

Goodness of fit (residual analysis)

Time series Forecasting

Forecast accuracy

Parsimony and reasonableness

Why so many different methods?

Model-based methods

Linear regression

Autoregressive models

ARIMA

Logistic regression

Econometrics models

Data-driven methods

Naïve forecast

Smoothing methods

Neural nets



Structural changes
Assumptions
Amount of data
User inputs required
Global/local patterns

Smoothing methods

Moving average

Exponential smoothing

- Smoothing methods are useful for
 - Data visualization
 - Removing seasonality and computing seasonal indexes
 - Forecasting

The Moving Average Method

The Idea:

Forecast future points by using an average of several past points

Uses:

Time series visualisation Computing seasonal indexes Forecasting

Advantages:

Simple, popular

Disadvantages:

Forecast only in series that lack seasonality and trend

Key concept:

Width of window

Notation

t = 1,2,3,...

An index denoting the time period of interest.

t = 1 is the first period in a series.

 $y_1, y_2, y_3, \cdots, y_n$

A series of n values measured over n time periods, where y_t denotes the series value at time t.

 F_t

The forecasted value for time period t.

 F_{t+k}

The \$k\$-step-ahead forecast.

 e_t

The forecast error for time period t, which is the difference between the actual value and the forecast at time t, and equal to $y_t - F_t$.

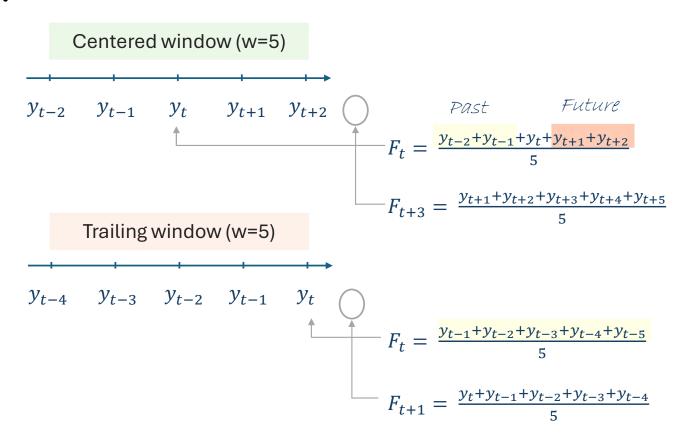
Two types of windows

Centered moving average:

based on a window <u>centered</u> around time *t*

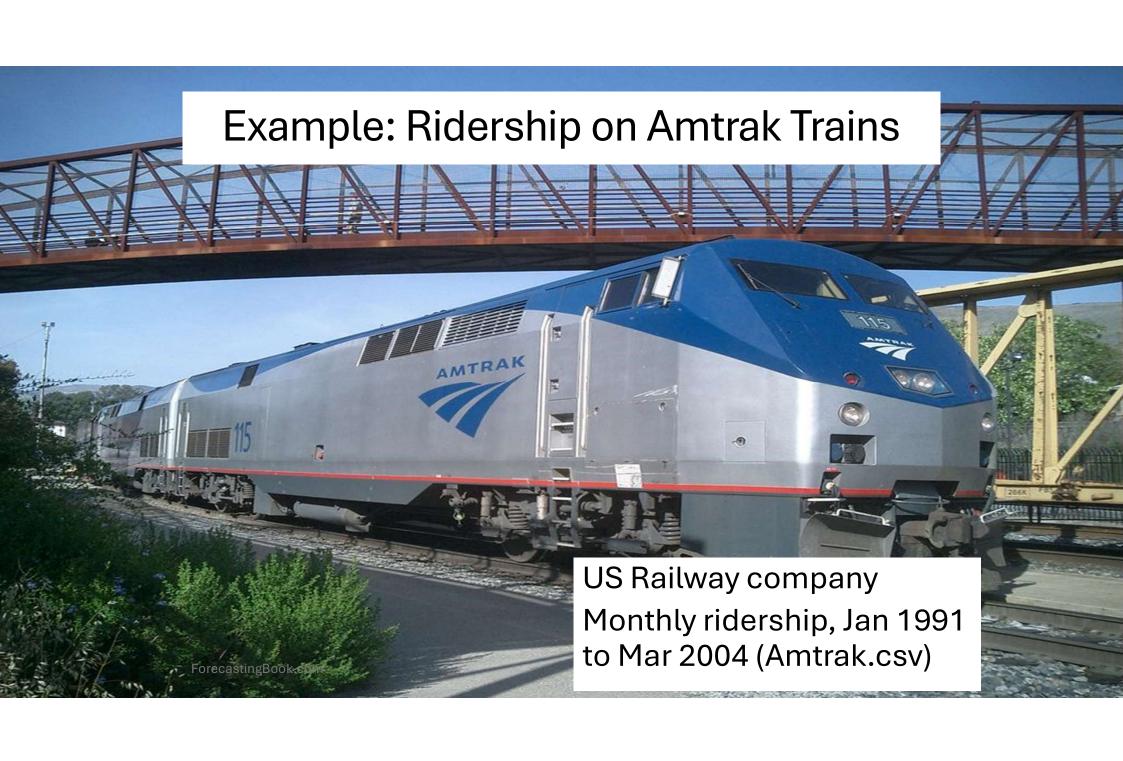
Trailing moving average:

based on a window from time *t* and backwards



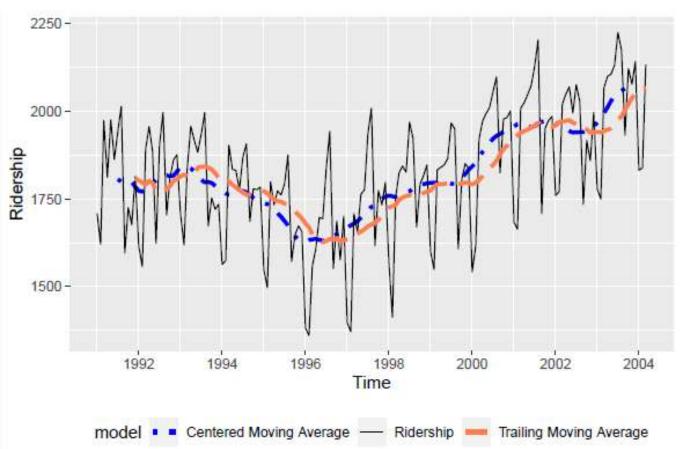
Moving averages for visualizing time series

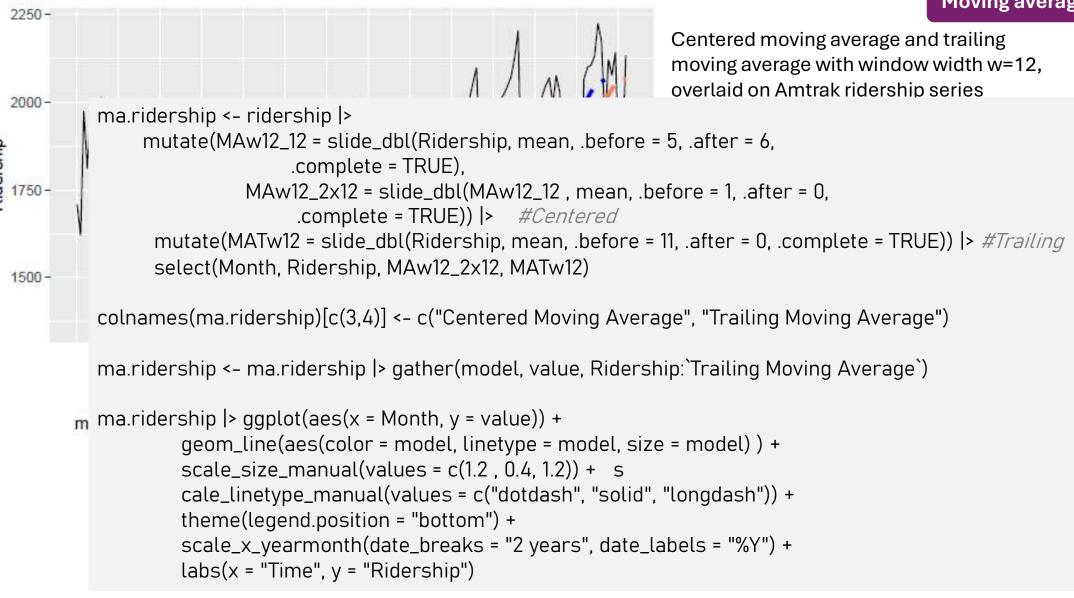
A time-plot of the **moving averages** can help reveal the LEVEL and TREND of a series, by filtering out the seasonal and random components



Moving average

Centered moving average and trailing moving average with window width w=12, overlaid on Amtrak ridership series

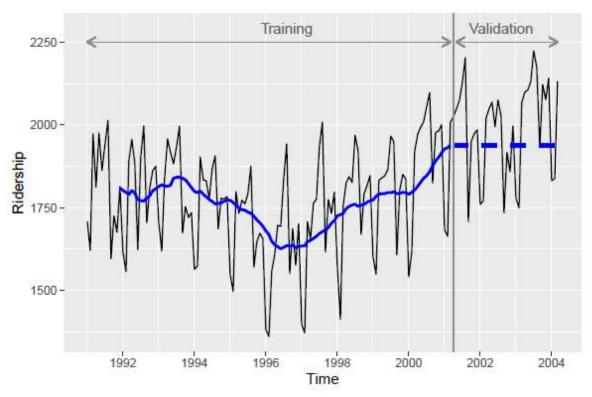




Centered moving average with an even window

$$\begin{aligned} \mathit{MAw} 12_2x 12 &= \frac{1}{2} \left[\frac{1}{12} \left(y_{t-5} + y_{t-4} + y_{t-3} + y_{t-2} + y_{t-1} + y_t + y_{t+1} + y_{t+2} + y_{t+3} + y_{t+4} + y_{t+5} + y_{t+6} \right) + \right. \\ &\left. \frac{1}{12} \left(y_{t-6} + y_{t-5} + y_{t-4} + y_{t-3} + y_{t-2} + y_{t-1} + y_t + y_{t+1} + y_{t+2} + y_{t+3} + y_{t+4} + y_{t+5} \right) \right] \\ &\left. = \frac{1}{24} y_{t-6} + \frac{1}{12} y_{t-5} + \frac{1}{12} y_{t-4} + \frac{1}{12} y_{t-3} + \frac{1}{12} y_{t-2} + \frac{1}{12} y_{t-1} + \frac{1}{12} y_t + \frac{1}{12} y_{t+1} + \frac{1}{12} y_{t+2} + \frac{1}{12} y_{t+3} + \frac{1}{12} y_{t+4} + \frac{1}{12} y_{t+5} + \frac{1}{24} y_{t+6} \end{aligned}$$

The Moving Average Method



Trailing moving average forecaster with w=12 applied to Amtrak ridership series.

The Moving Average Method

```
Trailing moving average forecaster with
            train.ridership <- ridership |> filter_index(~ "2001 Mar")
            valid.ridership <- ridership |> filter_index("2001 Apr" ~ .)
  2000 -
            ma.trailing <- train.ridership |>
Ridership
1750 -
                     mutate(MATw12 = slide_dbl(Ridership, mean, .before = 11, .complete = TRUE))
            last.ma <- tail(ma.trailing, 1)
            ma.pred <- bind_cols(valid.ridership, rep(last.ma$MATw12, nrow(valid.ridership))) |>
                     select(-"Ridership")
  1500 -
            names(ma.pred)[2] <- "fitted"
            ridership |> autoplot(Ridership) +
                     geom_line(aes(y = MATw12), data = ma.trailing, size = 1.0, colour = "blue1") +
                     autolayer(ma.pred, alpha = 0.5, level = NULL, linetype = "dashed", size = 1.25, colour = "blue1") +
                      xlab("Time") + ylab("Ridership") +
                     theme(legend.position = "none")
```

Choosing window width (w)

- Balance over- and under-smoothing
- Wide window global trend, narrow window reveal local trend
- If no seasonality, use a narrow window (under-smoothing)

Test yourself

For a seasonal series, what window width should you use?

- 1. Smaller than the # seasons
- 2. Larger than the # seasons
- 3. Equal to the # seasons

Hands-On # 2.1

- Fortified wine has the largest market share of the six types of wine.
 You are asked to focus on fortified wine sales alone
- Fit moving average model with a window of size 5 and size 12
- What patterns do these models suggest?
- (Hint: don't forget to split the data into training and validation sets)

Removing trend and/or seasonality

Differencing:

Taking the difference between two consecutive observations.

Usage

Removing a trend and/or seasonality from a time series

Lag - 1 difference: $y_t - y_{t-1}$

Removing trend

E.g., monthly seasonality m=12, daily seasonality m=7

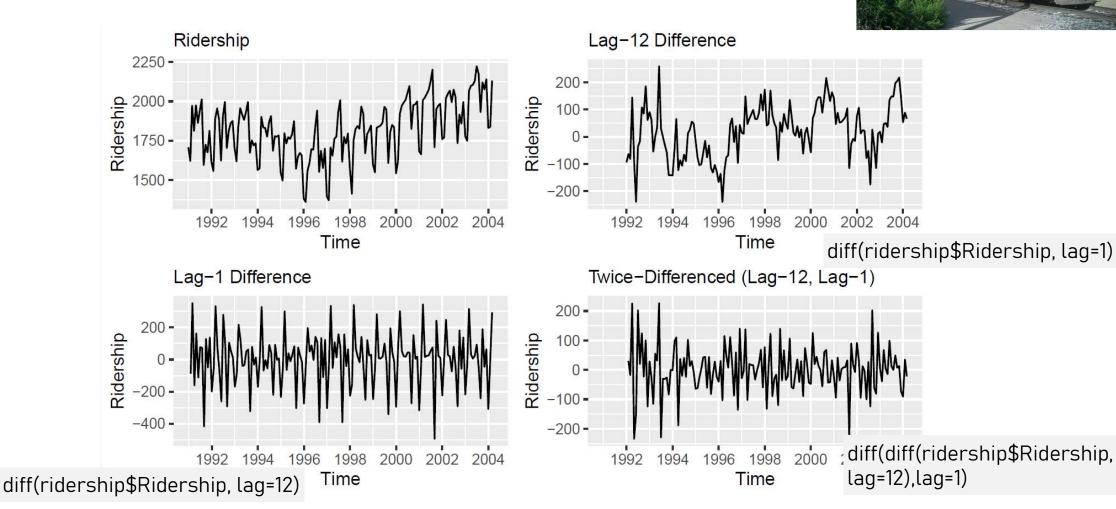
Lag - m difference: $y_t - y_{t-m}$

Removing seasonality with m seasons

Double-differencing: difference the differenced series







Methods require no trend and/or seasonality

- Moving average
- (Simple) Exponential smoothing

The simple exponential smoothing Method

The Idea:

Forecast future points by using an exponential weighted average of several past points

Uses:

Forecasting
Automated forecasting
Capture well for local patterns
Visualization
Creating seasonal indexes

Advantages:

Simple to understand

Gives more influence on recent information Storage/computation efficient (we only need to store the last forecast and most recent observation)

Disadvantages:

Forecast only in series that lack seasonality and trend*

Forecast into the future & one-step-ahead forecast the same

Key concept:

Smoothing constant α

Exponential smoothing

Types of exponential smoothing

Simple exponential smoothing (no trend or seasonality)

Advance exponential smoothing (trend and/or seasonality)

Holt's method (with trend but no seasonality)

Winter's method (with trend and seasonality)

Simple exponential smoothing

• Assume that the series has only level (L_t) and noise (unpredictable)

$$F_{t+1} = L_t$$

Forecasts are estimated as level at the most recent time

$$L_t = \alpha y_t + (1 - \alpha) y_{t-1}$$

Exp smoothing is an adaptive algorithm.

It adjust the most resent forecast (level) based on actual data

$$0 < \alpha < 1$$

 α = the smoothing constant

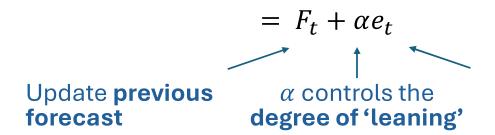
Initialization: $F_t = L_1 = y_1$

Why 'exponential smoothing'?

• Let's examine $F_{t+1} = L_t$ where $L_t = \alpha y_t + (1 - \alpha)L_{t-1}$

$$\begin{split} F_{t+1} &= L_t \\ &= \alpha y_t + (1-\alpha)[\alpha y_{t-1} + (1-\alpha)L_{t-2}] = \\ &= \alpha y_t + \alpha (1-\alpha)y_{t-1} + (1-\alpha)^2 L_{t-2} = \\ &= \alpha y_t + \alpha (1-\alpha)y_{t-1} + \alpha (1-\alpha)^2 y_{t-2} + \cdots \end{split}$$

Weights decrease exponentially into the past!



Active learner!

See page 94

By an amount that depends on the **error** in the previous forecast

The smoothing constant α

Controls the degree of 'leaning'

 $0 \leftarrow \alpha \rightarrow 1$

Past obs. Slow learner

Fast learner

Have a large

Have little to no

influence on the

influence forecasts

forecast

Over-smoothing

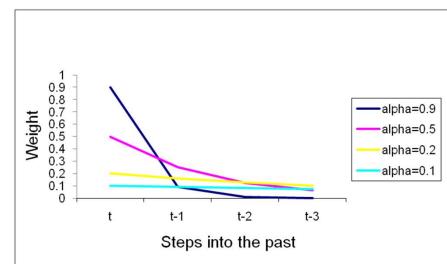
Under-smoothing

• Selecting α

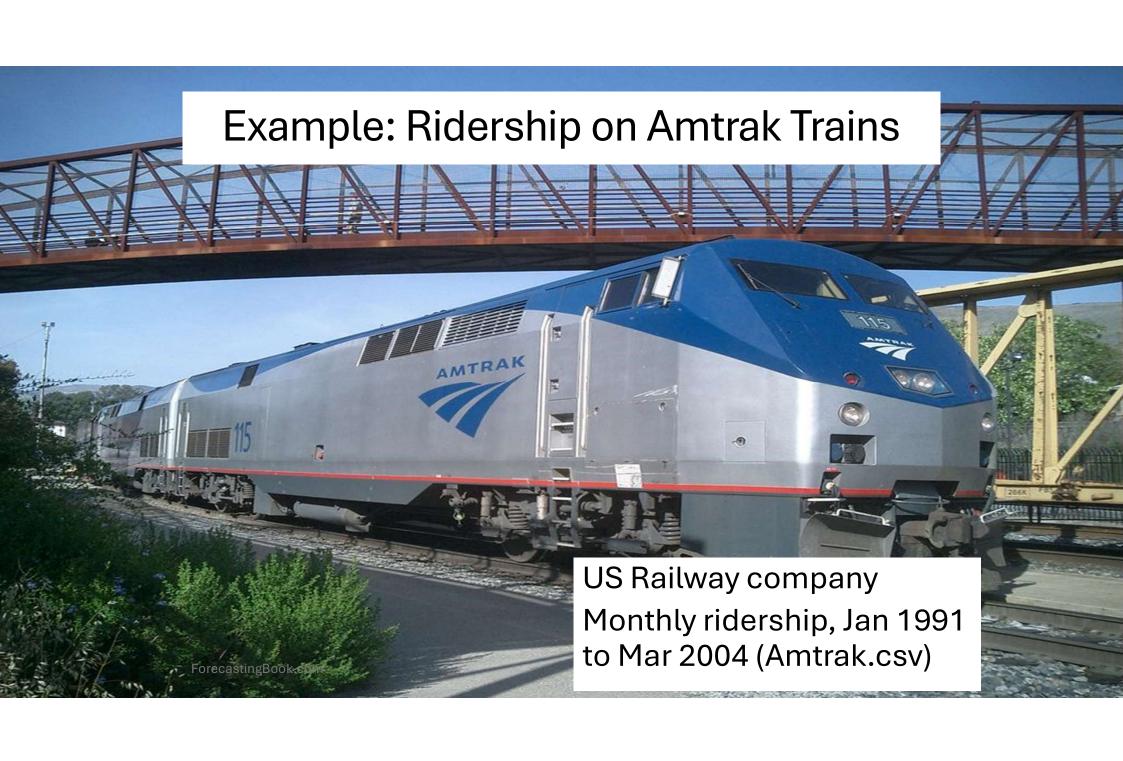
Common values: 0.1 or 0.2

Trail & error: effect on visualisation

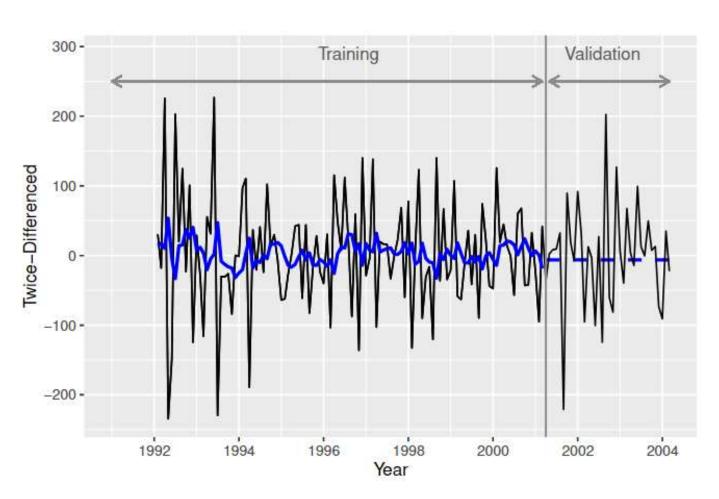
Minimise RMSE or MAPE of training data



α	α (1- α)	$\alpha(1-\alpha)^2$	$\alpha(1-\alpha)^3$
0.9	0.09	0.009	0.0009
0.5	0.25	0.125	0.0625
0.2	0.16	0.128	0.1024
0.1	0.09	0.081	0.0729



Exponential smoothing



Exp Smoothing (α =0.2) applied to twice-differenced Amtrak series

Exponential smoothing

Hands on activity – generate auto ETS

```
300 -
                              Training
                                                       Validation
         | lag_data <- ridership |>
                                      mutate(dif1 = Ridership - lag(Ridership, 1),
               dif12 = Ridership - lag(Ridership, 12),
   200 -
          dif12_1 = dif12 - lag(dif12, 1))
Twice-Differenced
   100 -
          train.ridership <- lag_data |> filter_index("1992 Feb" ~ "2001 Mar")
          valid.ridership <- lag_data |> filter_index("2001 Apr" ~ .)
    0-
                                          model(ets = ETS(dif12_1 \sim error("A") + trend("N", alpha = 0.2) + season("N")))
          fit.ets <- train.ridership |>
  -100 -
          fc.ets <- fit.ets |> forecast(h=dim(valid.ridership)[1])
  -200 -
          fc.ets |>
                    autoplot(train.ridership, level = NULL, size = 1, linetype = "dashed") +
                              geom_line(aes(y = dif12_1), data = lag_data, size = 0.5) +
                              geom_line(aes(y = .fitted), data = fitted.values(fit.ets), size = 1, colour = "blue1") +
                              xlab("Year") + ylab("Twice-Differenced")
```

Some useful commands

report(fit.ets)

```
> report(fit.ets)
Series: dif12_1
Model: ETS(A,N,N)
  Smoothing parameters:
    alpha = 0.2
  Initial states:
    1[0]
 14.35123
  sigma^2: 8401.487
     AIC
             AICC
                       BIC
1513.012 1513.125 1518.413
```

Some useful commands

- Forecasted values for the training data
- pred.values.ets <- fitted.values(fit.ets)
- View(pred.values.ets)



Some useful commands

- Forecasted values for the validation data
- fc.ets

```
> fc.ets
# A fable: 36 x 4 [1M]
# Key:
         .model [1]
  .model Month
                       dif12 1 .mean
  <chr> <mth>
                         <dist> <db1>
1 ets 2001 Apr N(-6.3, 8401) -6.35
2 ets 2001 May N(-6.3, 8738) -6.35
3 ets 2001 Jun N(-6.3, 9074) -6.35
4 ets 2001 Jul N(-6.3, 9410) -6.35
5 ets 2001 Aug N(-6.3, 9746) -6.35
6 ets 2001 Sep N(-6.3, 10082) -6.35
7 ets 2001 Oct N(-6.3, 10418) -6.35
8 ets 2001 Nov N(-6.3, 10754) -6.35
9 ets 2001 Dec N(-6.3, 11090) -6.35
10 ets
         2002 Jan N(-6.3, 11426) -6.35
# i 26 more rows
# i Use `print(n = ...)` to see more rows
```

Exponential smoothing – link to moving average

Moving average with $w=\frac{2}{\alpha}-1$ will provide (approximately) equal result to the result of exponential smoothing with smoothing constant α .

Advanced exponential smoothing

Double exponential smoothing, Holt's method. Additive trend

$$F_{t+k} = L_t + kT_t$$

$$L_t = \alpha y_t + (1 - \alpha)(L_{t-1} + T_{t-1})$$

$$T_t = \beta (L_{t-} - L_{t-1}) + (1 - \beta)T_{t-1}$$

$$0 < \alpha \le 1$$

$$0 < \beta \le 1$$

Assume a trend that can change over time (local trend). The level changes from one period to next by a fix amount

Level estimate at time t, a weighted average of observation at time t and the level in the previous period adjusted for trend

Trend estimate at time t, a weighted average of most recent info on the change in level and the trend in the previous period adjusted for trend

Smoothing constants determine the rate of learning. As closer both to 1 as faster the learning (more weight to more recent obs.)

Advanced exponential smoothing

Two types of errors (additive trend)

Additive error

$$y_t = L_t + T_t + e_t$$

The error has a similar magnitude irrespective of the current level and/or trend of the series

Multiplicative error

$$y_t = (L_t + T_t)(1 + e_t)$$

The error proportionally increases (decrease) with level and/or trend changes.

Advanced exponential smoothing

Multiplicative trend

$$F_{t+1} = L_t \times T_t^k$$

$$L_t = \alpha y_t + (1 - \alpha)(L_{t-1} \times T_{t-1})$$

$$T_t = \beta(L_{t-}/L_{t-1}) + (1 - \beta)T_{t-1}$$

$$0 < \alpha \le 1$$

 $0 < \beta \le 1$

Assume a trend that can change over time (local trend). The level changes from one period to the next by a fix amount factor

Updating equation for level at time t

Updating equation for trend at time *t*

Smoothing constants determine the rate of learning. As closer both to 1 as faster the learning (more weight to more recent obs.)

Two types of errors (Multiplicative trend)

Additive error

$$y_t = L_t \times T_t + e_t$$

The error has a similar magnitude irrespective of the current level and/or trend of the series

Multiplicative error

$$y_t = (L_t \times T_t)(1 + e_t)$$

The error proportionally increases (decrease) with level and/or trend changes.

Holt-Winter's exponential smoothing. Additive seasonality

$$F_{t+k} = L_t + kT_t + S_{t+k-m}$$

Seasonal adjusted value

Assume a trend that can change over time (local trend). The level changes from one period to the next by a fixed amount. The values of different seasons differ by a fix amount

$$L_{t} = \alpha(y_{t} - S_{t-m}) + (1 - \alpha)(L_{t-1} + T_{t-1})$$

Updating equation for level at time t

$$T_t = \beta(L_t - L_{t-1}) + (1 - \beta)T_{t-1}$$

Updating equation for trend at time t

$$S_t = \gamma (y_t - L_t) + (1 - \gamma) S_{t-m}$$

Updating equation for seasonality at time t

Trend adjusted value

Smoothing constants determine the rate of learning.

$$0 < \alpha \le 1$$
 $0 < \beta \le 1$

Holt-Winter's exponential smoothing. Multiplicative seasonality

$$F_{t+k} = (L_t + kT_t) \times S_{t+k-m}$$

Seasonal adjusted value

Assume a trend that can change over time (local trend). The level changes from one period to the next by a fixed amount. The values of different seasons differ by percentage amount

$$L_{t} = \alpha(y_{t}/S_{t-m}) + (1 - \alpha)(L_{t-1} + T_{t-1})$$

Updating equation for level at time t

$$T_t = \beta (L_{t-} - L_{t-1}) + (1 - \beta)T_{t-1}$$

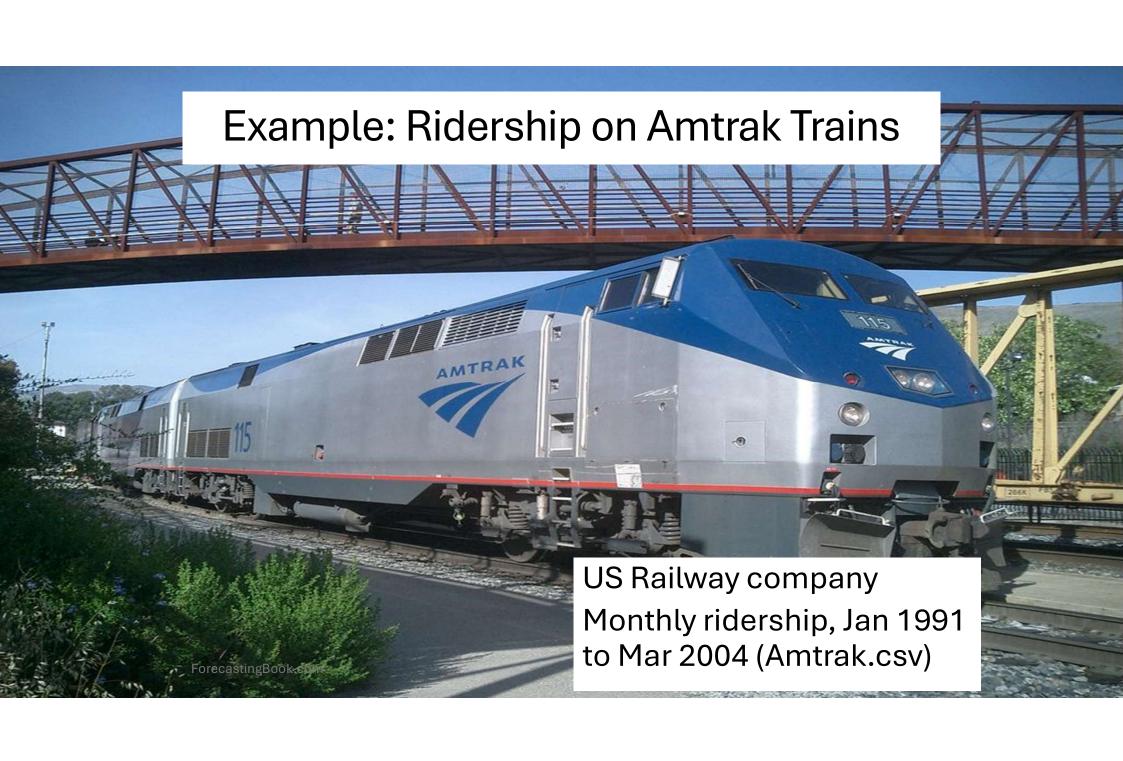
Updating equation for trend at time t

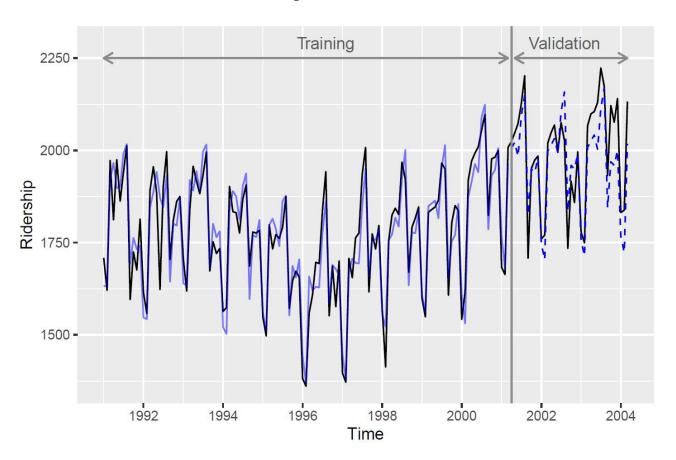
$$S_t = \gamma (y_t/L_t) + (1 - \gamma)S_{t-m}$$

Updating equation for seasonality at time t

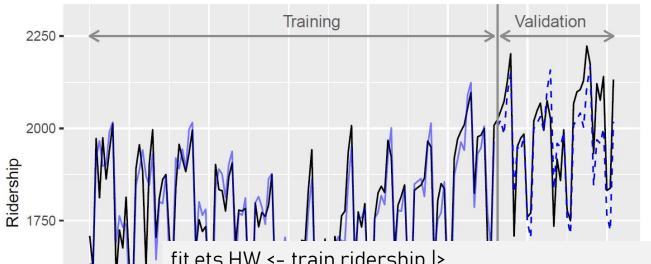
Trend adjusted value $0 < \alpha \le 1 \quad 0 < \beta \le 1$

Smoothing constants determine the rate of learning.





Forecasts from the Holt-Winter's exponential smoothing applied to the Amtrak ridership series.



1500 -

Forecasts from the Holt-Winter's exponential smoothing applied to the Amtrak ridership series.

```
fit.ets.HW <- train.ridership |>
    model(ets = ETS(Ridership ~ error("M") + trend("A") + season("A")))

fc.ets.HW <- fit.ets.HW |> forecast(h = nrow(valid.ridership))

ridership |> autoplot(Ridership) +
    geom_line(aes(y = .mean), data = fc.ets.HW, colour = "blue1", linetype = "dashed") +
    autolayer(fitted.values(fit.ets.HW), alpha = 0.5, level = NULL, colour = "blue1") +
    xlab("Time") + ylab("Ridership")
```

```
> report(fit.ets.HW)
                    _ error("M") + trend("A") + season("A")))
Series: Ridership
Model: ETS(M,A,A) *
       Smoothing parameters:
         alpha = 0.5517889
         beta = 0.0001119929
         gamma = 0.0001186167
        Initial states:
         [0]
                  b[0]
                       s[0] s[-1] s[-2] s[-3] s[-4] s[-5] s[-6]
         1838.577 0.8081064 28.44536 -11.21868 -0.533687 -124.2766 200.1969 146.8103 36.59075
         s[-7] s[-8] s[-9] s[-10] s[-11]
          76.04396 60.15303 44.17906 -249.4682 -206.9221
        sigma^2: 0.0012
         AIC
                 AICc
                          BIC
         1617.596 1623.424 1665.403
```

```
# Final states:
> n <- nrow(components(fit.ets.HW))</pre>
> components(fit.ets.HW)[n, c("level", "slope")] # level and trend
# A tibble: 1 x 2
       level
               slope
        <dbl> <dbl>1
        1945. 0.810
> t(components(fit.ets.HW)[(n-11):n, c("season")]) # s1 to s12
                                                                                   [.9]
                [,2] [,3] [,4] [,5] [,6] [,7] [,8]
        [.1]
season 60.13771 76.05659 36.58921 146.8106 200.1936 -124.2748 -0.5324645 -11.21618 28.44364
        [,10] [,11] [,12]
season -206.9249 -249.471 44.1899
```

The ETS() function

• Provide 18 model choices, combination of:

	Seasonality			
Trend	None	Additive	Multiplicative	
None	ZNN	ZNA	ZNM	
Additive	ZAN	ZAA	ZAM	
Multiplicative	ZMN	ZMA	ZMM	

where Z can be set to A or M corresponding to additive or multiplicative error, respectively.

train.ridership |> model(ets = ETS(Ridership ~ error("M") + trend("A") + season("A")))

Automated exponential smoothing

- If you do not know which model to choose, you can use the ETS function to do automated model selection.
- It will fit all the models and select the one that minimised Akaike's Information Criterion (AIC),
- AIC combines fit to the training data with a penalty for the number of smoothing parameters.

Trend	None	Additive	Multiplicative
None	ZNN	ZNA	ZNM
Additive	ZAN	ZAA	AZAM
Multiplicative	ZMN	ZMA	ZMM

Automated exponential smoothing

- To include the restricted models when searching for a model, include the options restrict = FALSE in the ETS function.
- You can automatically select a model from a subset of prespecified models.
- For example, train.ridership |> model(ets= ETS(Ridership ~ error("M")) will consider all the models with multiplicative error except the MMA model (unless you include restrict = FALSE).

Automated exponential smoothing - example

```
fit.ets.auto <- train.ridership |> model(ets = ETS(Ridership))
pred.values.ets.auto <- fitted.values(fit.ets.auto)
fc.ets.auto <- fit.ets.auto |> forecast(h=dim(valid.ridership)[1])
```

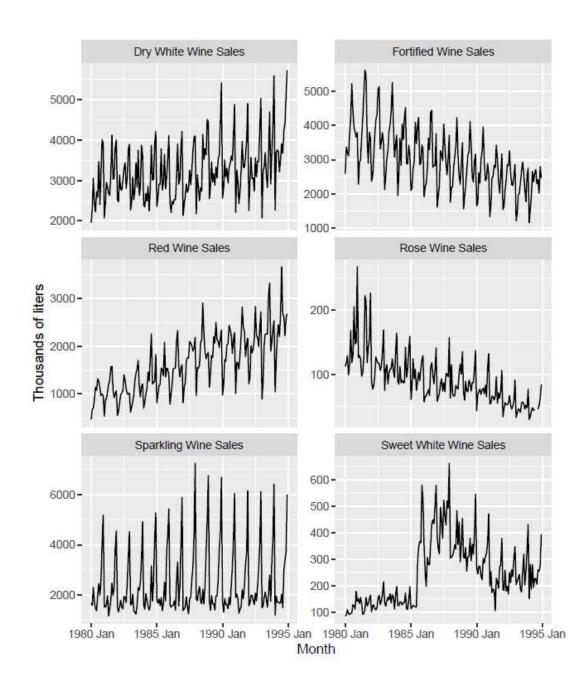
```
error("M"),
trend("N"),
season("A")
```

```
> report(fit.ets.auto)
Series: Ridership
Model: ETS(M,N,A)
  Smoothing parameters:
    alpha = 0.5550234
    gamma = 0.0001000004
  Initial states:
                       s[-1]
                                  s[-2]
                                             s[-3]
                                                     s[-4]
                                                              s[-5]
 1807.921 27.01543 -11.25932 0.01014284 -121.9422 199.759 149.5166 37.72519 75.45785
             s[-9]
    s[-8]
 59.73486 47.18978 -252.1883 -211.019
  sigma^2: 0.0012
     AIC
             AICC
                       BIC
1615.746 1620.232 1657.929
```



Hands-on

Which smoothing method would you choose if you had to choose the same method for all series? Why?



Hands-on (#2.2)

 Apply Holt-Winter's exponential smoothing (with multiplicative seasonality) to sales of fortified wine.

Use the training data to fit your model.

Measuring forecasting accuracy

Forecast accuracy (or predictive accuracy) describes how closely forecasts are to the actual values. Hence, we compare the actual and forecast values and look directly at forecast errors.

Forecast error:
$$e_t = y_t - F_t$$

- It is common to examine the predictive accuracy on the validation period data
- Several measures of predictive accuracy are commonly used:

Average error	$\frac{1}{v} \sum_{i=1}^{v} e_t$	MAE or MAD (mean absolute error/deviation)	$\frac{1}{v} \sum_{i=1}^{v} \left \frac{e_t}{y_t} \right \times 100$
MAPE (mean absolute percentage error)	$\frac{1}{v} \sum\nolimits_{i=1}^{v} e_t $	RMSE (root mean squared error)	$\sqrt{\frac{1}{v} \sum\nolimits_{i=1}^{v} e_t^2}$

Measuring forecasting accuracy

accuracy(model estimate object) – Gives many accuracy measurements for training dataset.

accuracy(forecast object, data set object) – Gives many accuracy measurements for the forecasting dataset.

<chr> <db1> <db1> <db1> <db1> <db1> <db1> <db1> <db1> <db1>

33.7 76.7 62.2 1.58 3.12 0.754 0.772 0.617