

Fig a)

Para preguntar

→ Pinza atuador ( $\hat{z}$ )?

→ Figura B no 10º abaixo?

$R_x \quad T_x \quad R_z \quad T_z$  theta variable.

0	0	90°	0	101 → 111
90°	L <sub>1</sub>	0	0	111 → 121
0	L <sub>2</sub>	0	0	121 → 131
0	L <sub>3</sub>	0	0	131 → 141

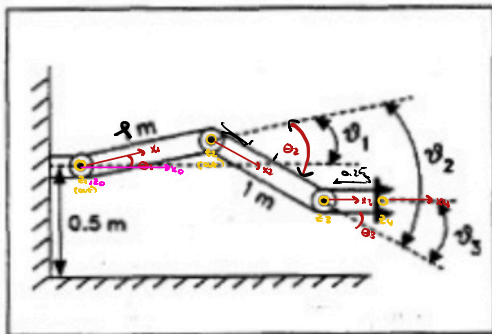


Fig b)

$R_x \quad T_x \quad R_z \quad T_z$  tenir en compte que  $\theta_2 = -90^\circ$

0	0	$\theta_1$	0	101 → 111
0	0	$-\theta_2$	0	111 → 121
0	1	$\theta_3$	0	121 → 131
0	0.25	0	0	131 → 141

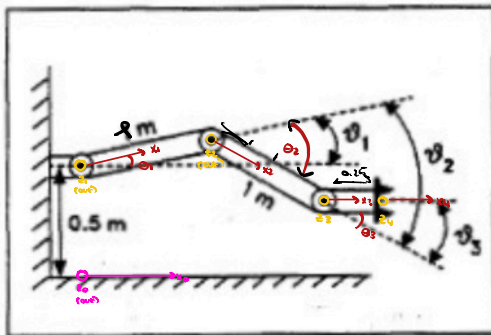


Fig b) 2.0.

$R_x \quad T_x \quad R_z \quad T_z$

0	0	$\theta_1$	0	101 → 111
0	0	$-\theta_2$	0	111 → 121
0	1	$\theta_3$	0	121 → 131
0	0.25	0	0	131 → 141

??