

THE MIN-COST FLOW PROBLEM

Esteve Codina

Universitat Politècnica de Catalunya

Grau d'Enginyeria Informàtica **FIB**

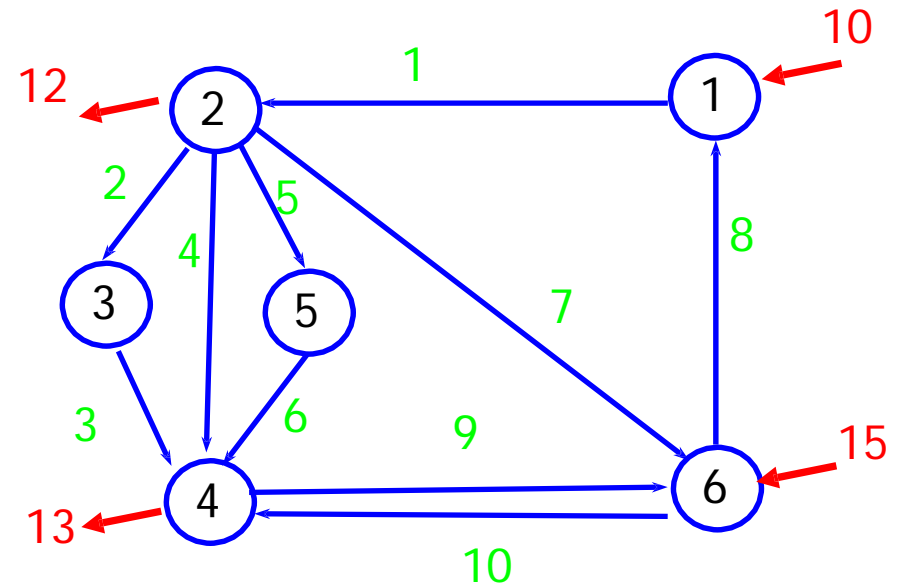
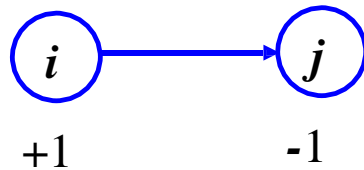
CONTENTS

- PROBLEM DEFINITION
- CONCEPT OF BASIC FEASIBLE SOLUTION (bfs)
 - Definition
 - Sets of indexes (basic, non-basic)
 - Why basic feasible solutions?
- OUTLINE OF THE ALGORITHM
- THE ALGORITHM IN DETAIL
 - Testing for optimality
 - Choosing a better bfs
 - Formal definition of the algorithm

NETWORK FLOWS

Node 1: $x_{12} - x_{61} = 10$

Node 2: $x_{23} + x_{24} + x_{25} + x_{26} - x_{12} = -12$



$$\sum_{(i,j) \in E(i)} x_{ij} - \sum_{(j,i) \in I(i)} x_{ij} = \mathbf{b}_i, \quad i \in N$$

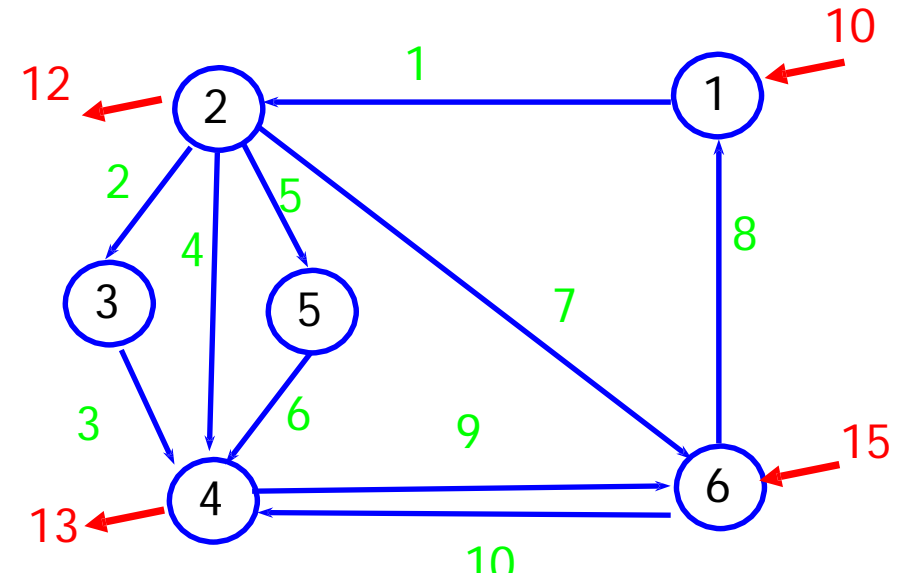
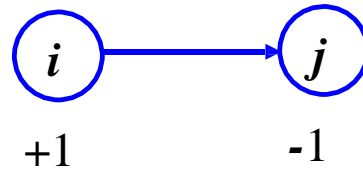
Notice that, for a feasible problem, $\sum_{i \in N} \mathbf{b}_i = 0$

NETWORK FLOWS

Nudo 1: $x_1 - x_8 = 10$

Nudo 2: $x_2 + x_4 + x_5 + x_7 - x_1 = -12$

...



$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ -1 & 1 & 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & -1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & -1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_9 \\ x_{10} \end{pmatrix} = \begin{pmatrix} 10 \\ -12 \\ 0 \\ -13 \\ 0 \\ 15 \end{pmatrix}$$

NODE-LINK INCIDENCE MATRIX D

**FLOW
VECTOR x**

INP./OUTP. b

$$x_i \geq 0, \quad i = 1, \dots, 10$$

Sometimes upper bounds are required on the flows: $x_i \leq u_i$

MIN-COST FLOW PROBLEM: DEFINITION

D - **NODE-LINK INCIDENCE MATRIX**

x - **FLOW VECTOR (DECISION VARIABLES)**

b - **INJECTIONS/EXTRACTIONS VECTOR**

l, u - **LOWER-UPPER BOUNDS VECTORS**

$$\text{Min}_x c^\top x$$

$$Dx = b$$

$$l \leq x \leq u$$

Typically $l = 0$;

if $l \neq 0$ the problema can be easily reformulated using new decision variables $y = x - l$

Exercise: reformulate the problem with the new variables y

Typically $c \geq 0$;

In this case the Solution set F^* is bounded:

There exists r in \mathbb{R} , so that any solution x^* verifies $|x^*| \leq r$

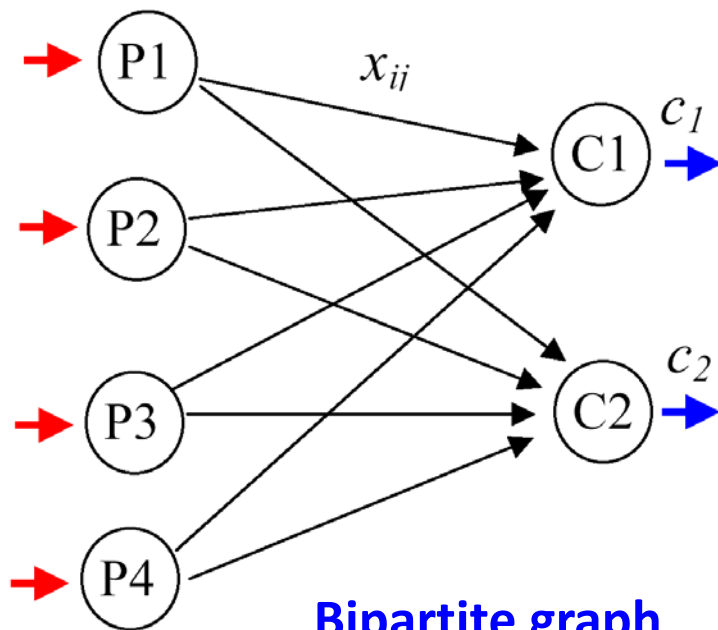
Exercise: find one such r

$$\text{Min}_x \sum_{i=1}^{n_p} \sum_{j=1}^{n_c} t_{i,j} x_{i,j}$$

$$\sum_{j=1}^{n_c} x_{ij} = p_i \quad i = 1, 2, \dots, n_p$$

$$\sum_{i=1}^{n_p} x_{ij} = c_j, \quad j = 1, 2, \dots, n_c$$

$$x_{i,j} \geq 0$$

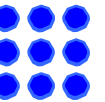


Bipartite graph

BALANCED PROBLEM

$$\sum_{j=1}^{n_p} p_j = \sum_{i=1}^{n_c} c_i$$

See more examples solved in the
Problems and Lab Sessions



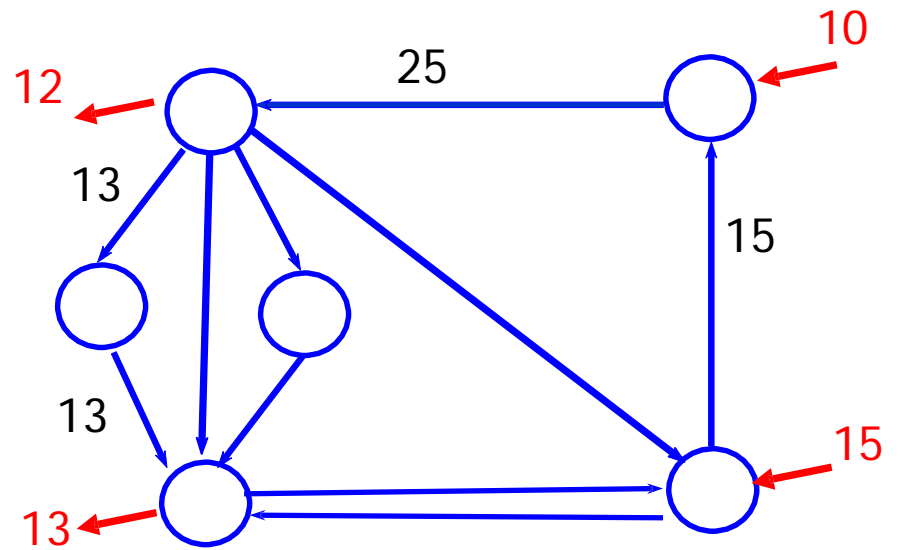
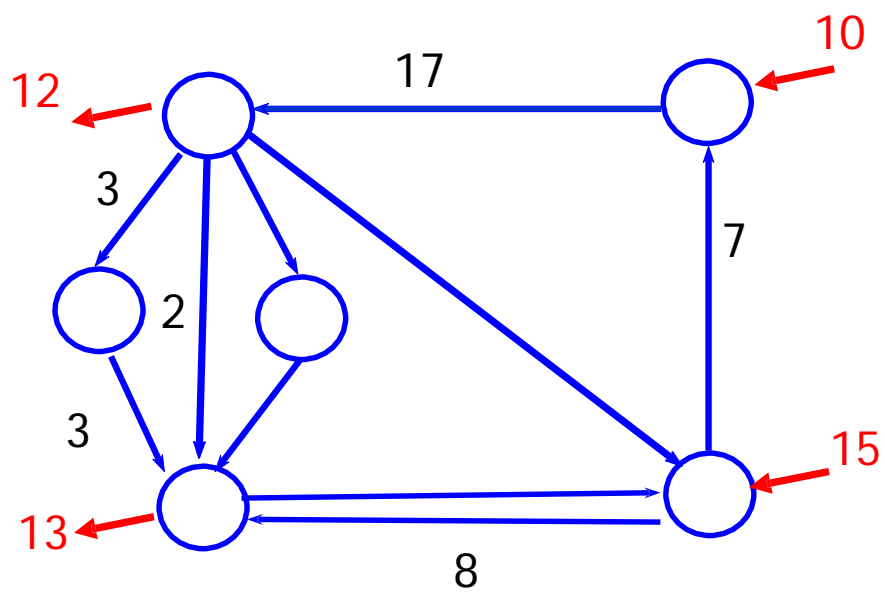
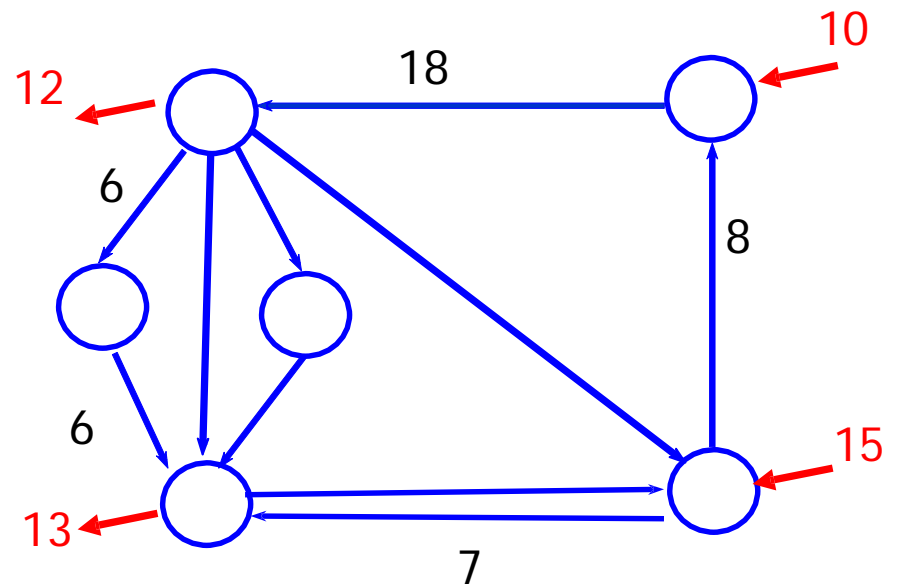
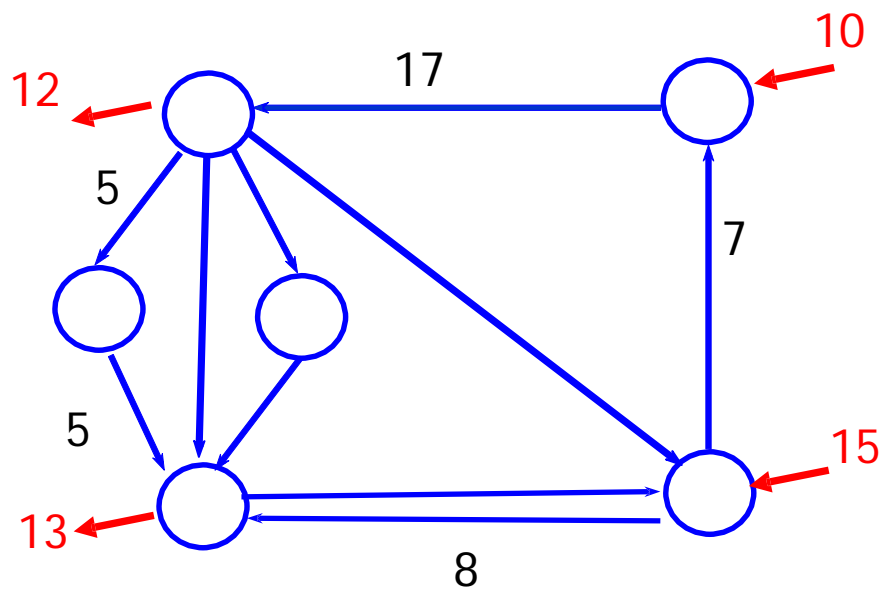
UPC

AMPL LANGUAGE: DECLARATIONS NODE, ARC

```
set CIUDADES;  
set ARCOS within (CIUDADES cross CIUDADES);  
  
param oferta {CIUDADES} >= 0;    # injections  
param demanda {CIUDADES} >= 0;    # extractions  
  
param coste {ARCOS} >= 0; # costs    of transp.  
  
minimize Total_Coste;  
  
node Nodo {k in CIUDADES}: net_in=demanda[k]-oferta[k];  
  
arc enlace {(i,j) in ARCOS} >= 0,  
    from Nodo[i], to Nodo[j], obj Total_Coste coste[i,j];  
  
check: sum {i in CIUDADES}  
    oferta[i] = sum {j in CIUDADES}    demanda[j];
```

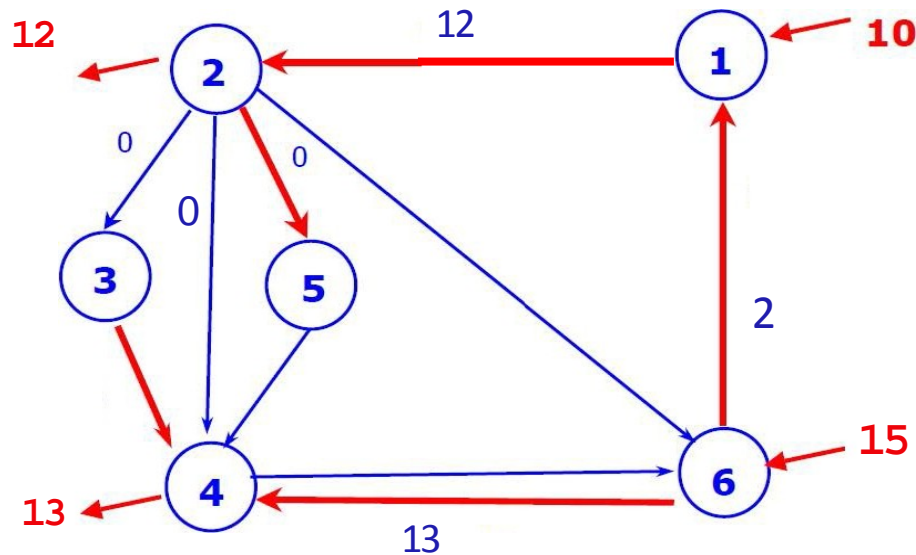

CONTENTS

- PROBLEM DEFINITION
- **CONCEPT OF BASIC FEASIBLE SOLUTION (bfs)**
 - Definition
 - Sets of indexes (basic, non-basic)
 - Why basic feasible solutions?
- OUTLINE OF THE ALGORITHM
- THE ALGORITHM IN DETAIL
 - Testing for optimality
 - Choosing a better bfs
 - Formal definition of the algorithm



Examples of feasible flows

BASIC FEASIBLE FLOWS



Some feasible flow vectors are specially relevant for the simplex algorithm. We will refer to them as **basic** feasible flows

The components x_{ij} (indexes (i,j)) of a basic feasible flow vector x can be regrouped into 2 (3) sets of components (indexes)

	Type of Problem	
	<u>No upper bounds</u>	<u>With upper bounds</u>
Basic set	I_B	I_B
Non-basic set(s)	I_N	I_{N+}, I_{N-}

IDENTIFYING A BASIC FEASIBLE FLOW

Let $G = (N, A)$. Let $x_{i,j}$, $(i,j) \in A$ be a feasible flow.

$x_{i,j}$, $(i,j) \in A$ is basic feasible flow

0. It is feasible (i.e., verifies the problem constraints)

1. $|I_B| = |N| - 1$

$$(i,j) \in I_B \longrightarrow x_{i,j} = 0, x_{i,j} = u_{i,j} \text{ or } 0 < x_{i,j} < u_{i,j}$$

2. Links in I_B build up a Spanning Tree

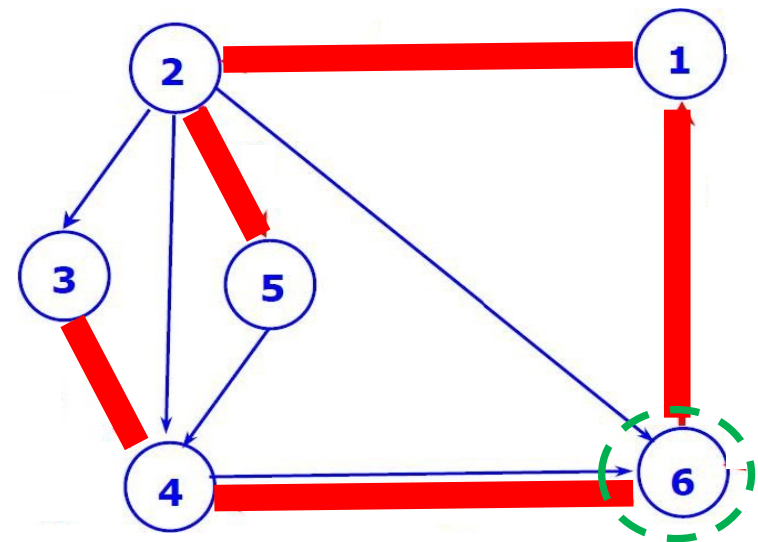
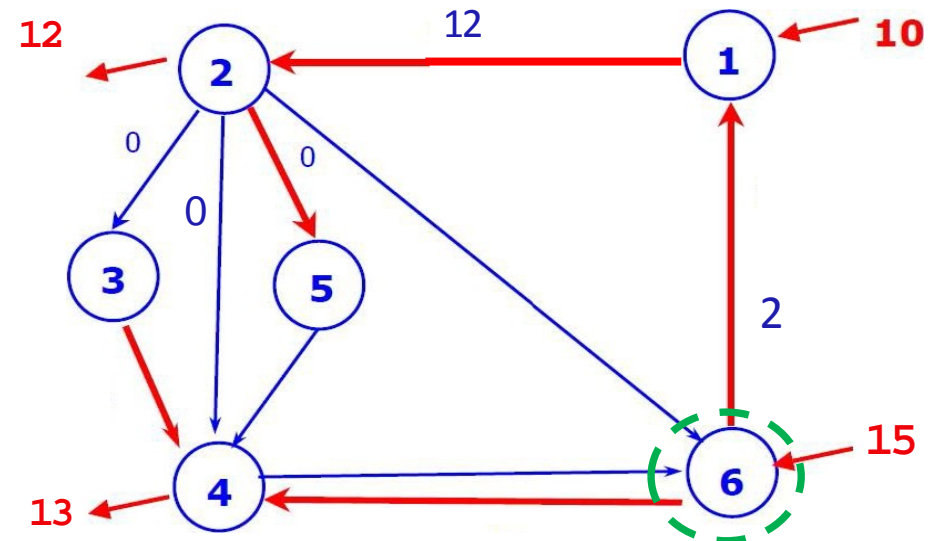
3. $(i,j) \in I_{N-} \longrightarrow x_{i,j} = 0$

4. $(i,j) \in I_{N+} \longrightarrow x_{i,j} = u_{i,j}$

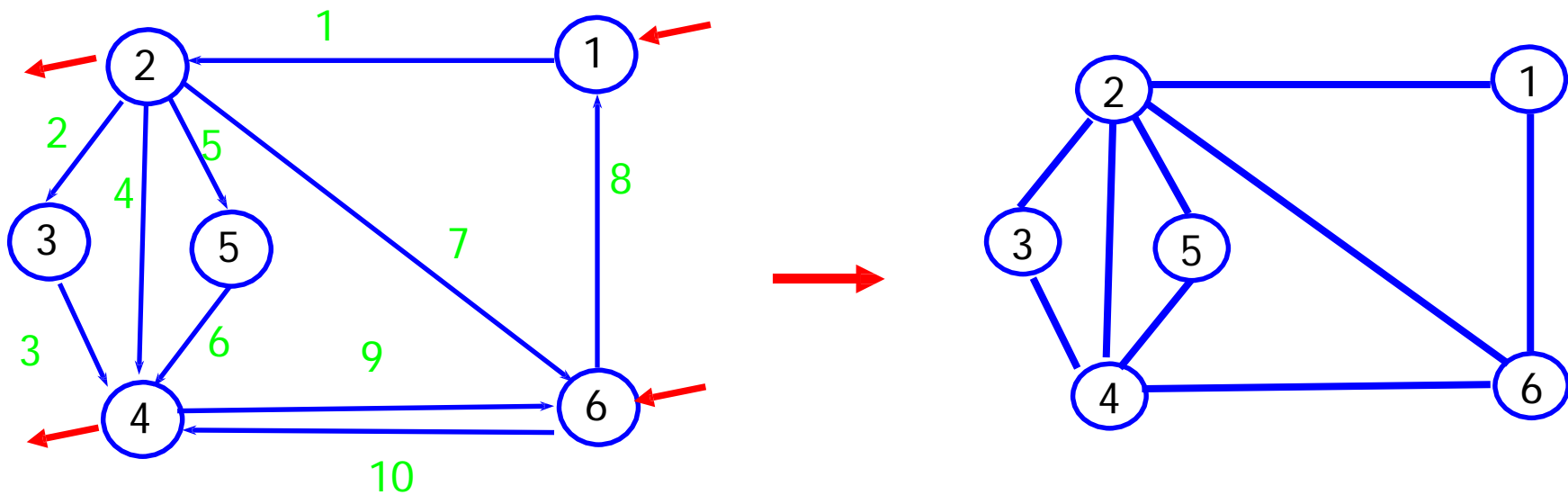
$$I_{N+} = \{ a \notin I_B, | x_a = u_a \} \quad I_{N-} = \{ a \notin I_B, | x_a = 0 \}$$

BUILDING UP A BASIC SET

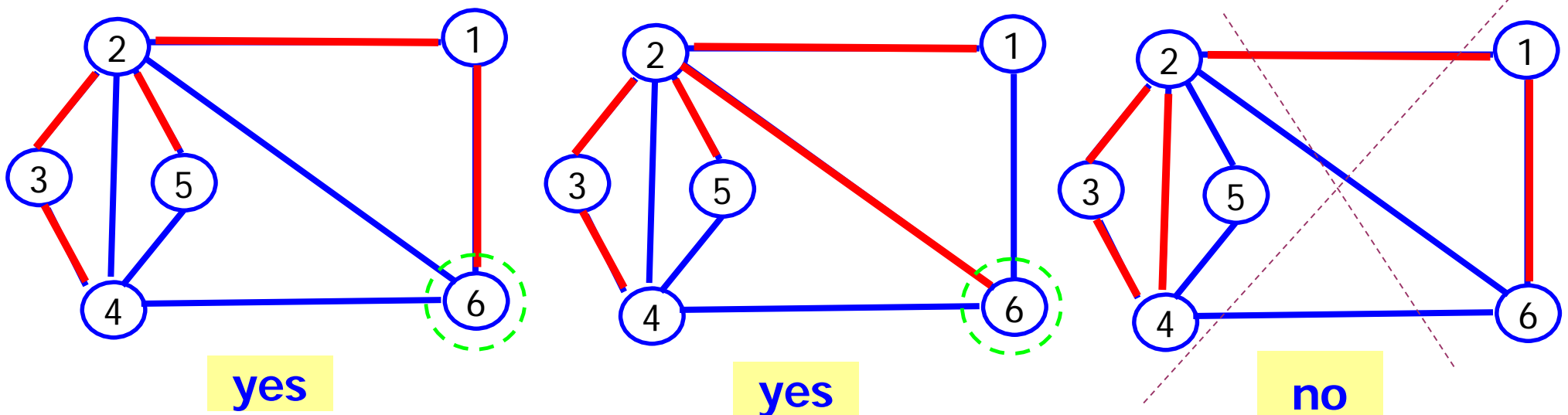
- The basic set of a basic feasible solution is made up by $|N| - 1$ links;
- The set of associated undirected links must form a spanning tree.
- One of the nodes is arbitrarily chosen as the root node
- A spanning tree is a subgraph of the original graph containing no cycles
- Notice that any node can be accessed by the root node through the spanning tree

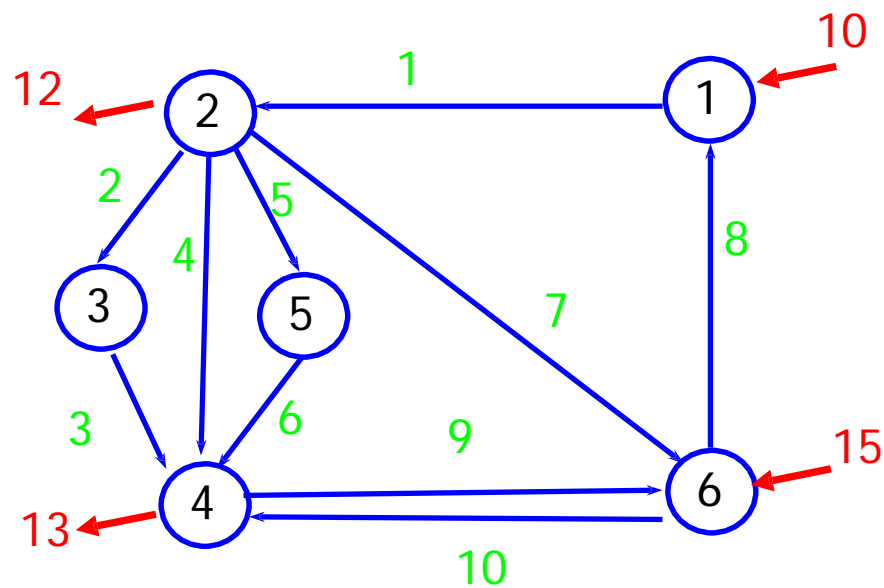
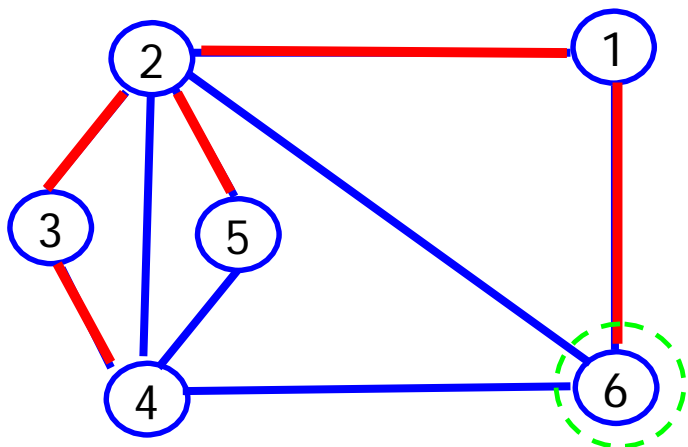


MORE EXAMPLES.



SPANNING TREE: $m-1$ links; no cycles; select a node as the root of the tree.





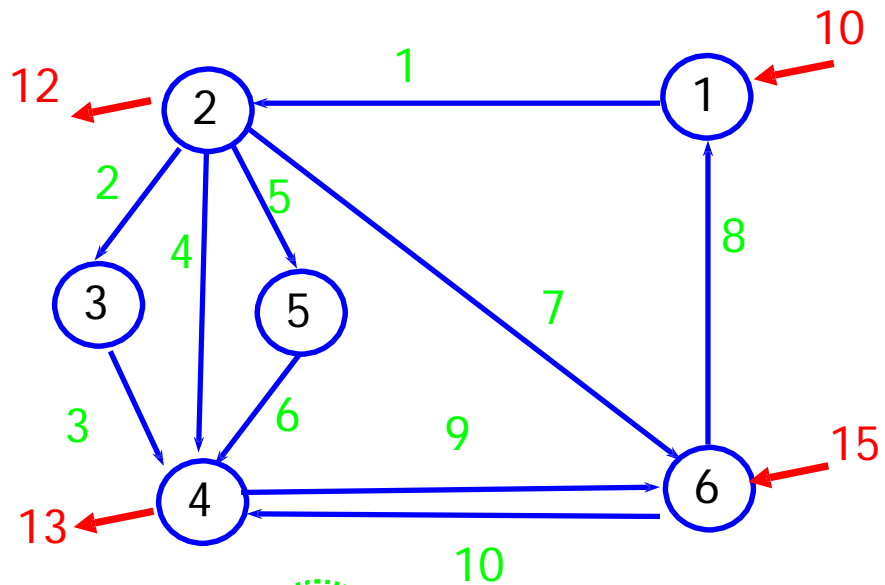
$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ -1 & 1 & 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & -1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & -1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & -1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & -1 \\ -1 & 1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} \rightarrow B = \begin{pmatrix} 1 & 0 & 0 & 0 & -1 \\ -1 & 1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix}$$

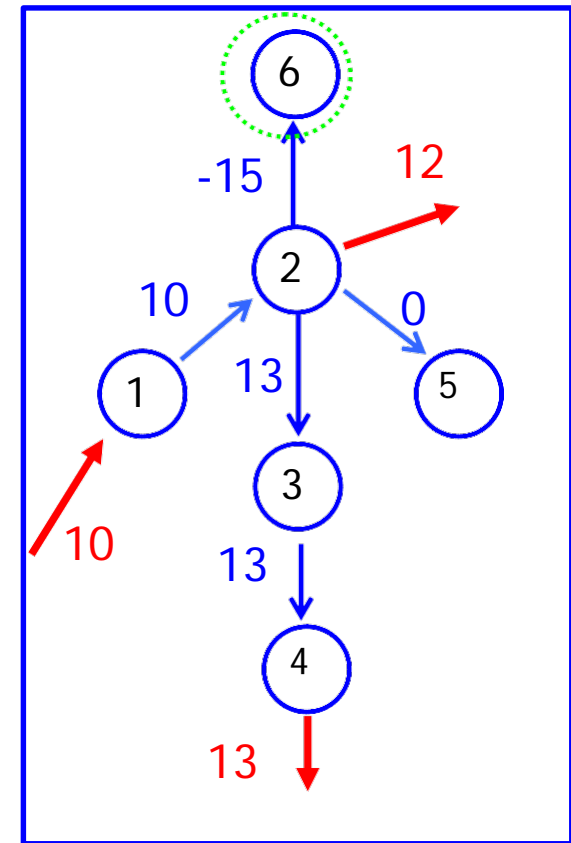
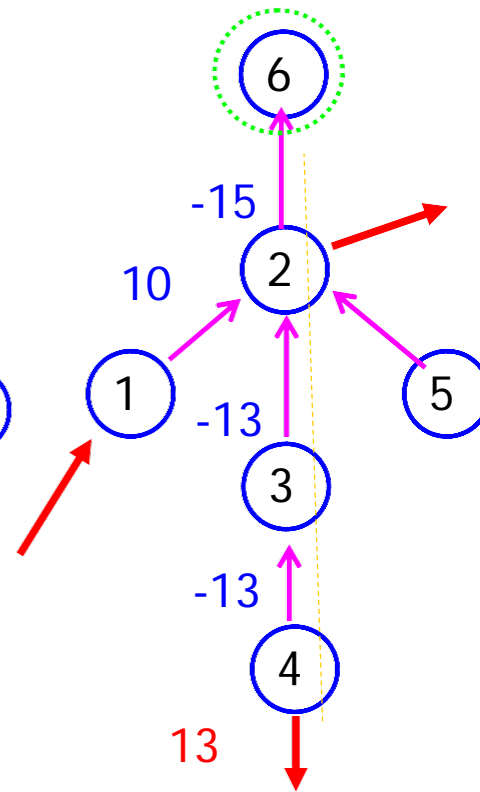
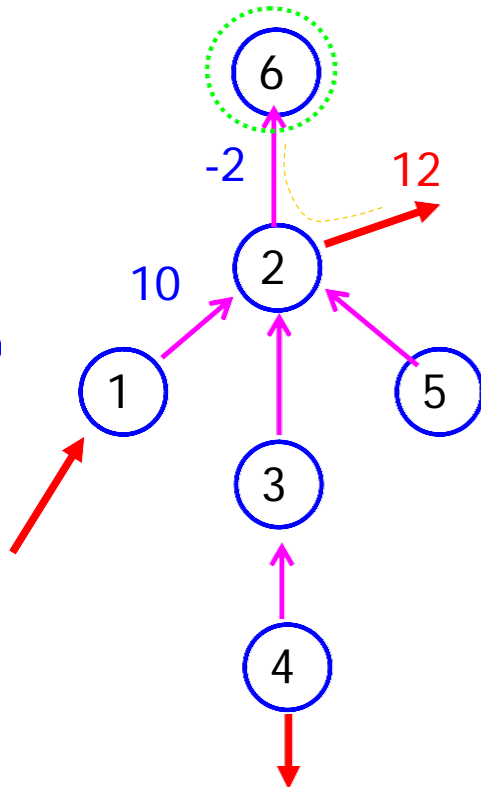
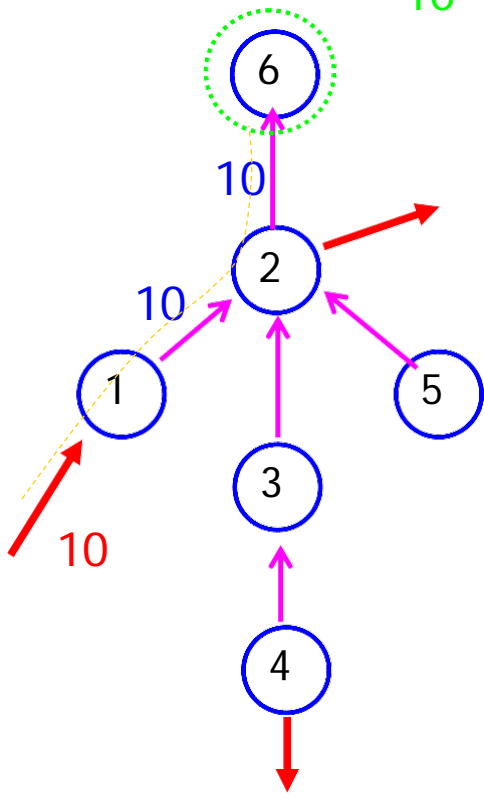
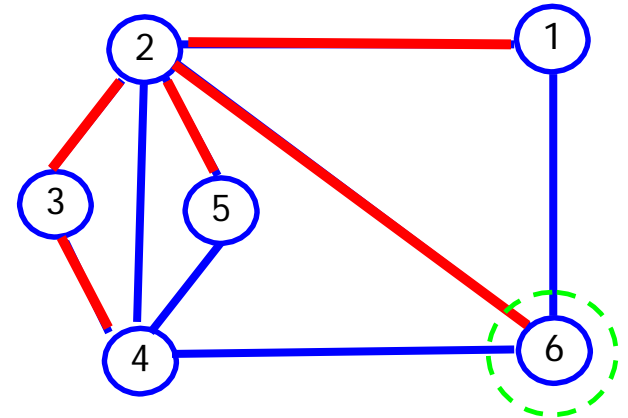
$$\begin{pmatrix} 1 & 0 & 0 & 0 & -1 \\ -1 & 1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix}$$

**A Basic Solution formed by this procedure
(building a spanning tree) is
called a basic feasible solution (bfs) if the following
condition is met:**

$$\mathbf{B}^{-1} \mathbf{b} \geq 0$$



NON-FEASIBLE BASIS



PROBLEMS WITH NO UPPER BOUNDS: CHECKING THE FEASIBILITY

Why basic feasible solutions?

FUNDAMENTAL THEOREM OF LINEAR PROGRAMMING.

IF A LINEAR PROGRAM ACHIEVES A FINITE SOLUTION (in other words, the optimal objective function value is finite),



THEN THERE EXISTS, AT LEAST, A BASIC FEASIBLE SOLUTION WHERE THE OBJECTIVE FUNCTION ACHIEVES ITS OPTIMAL VALUE (in other words, these basic feasible solutions are optimal).

Because of that it makes sense to look for a bfs

AND

identify a method that, from a bfs, gets another one with better objective function (and repeat until no further enhancement is possible)

CONTENTS

- PROBLEM DEFINITION
- CONCEPT OF BASIC FEASIBLE SOLUTION (bsf)
 - Definition
 - Sets of indexes (basic, non-basic)
 - Why basic feasible solutions?
- **OUTLINE OF THE ALGORITHM**
- THE ALGORITHM IN DETAIL
 - Testing for optimality
 - Choosing a better bfs
 - Formal definition of the algorithm

OUTLINE OF THE ALGORITHM

- 0) Find an initial **bfs**
- 1) Evaluate the obj.f. on the current **bfs**
- 2) TEST: is the current **bfs** optimal?
 - 1) YES: STOP
 - 2) NO: Find a better **bfs**
- 3) GOTO 1

CONTENTS

- PROBLEM DEFINITION
- CONCEPT OF BASIC FEASIBLE SOLUTION (bsf)
 - Definition
 - Sets of indexes (basic, non-basic)
 - Why basic feasible solutions?
- OUTLINE OF THE ALGORITHM
- **THE ALGORITHM IN DETAIL**
 - Testing for optimality:
 - dual variables; reduced costs; optimality conditons
 - Choosing a better bfs
 - Problems with upper bounds.
The case $I_{N+} \leftrightarrow I_{N-}$. The case $I_{N+} \leftrightarrow I_B$
 - Formal definition of the algorithm

DUAL VARIABLES ASSOCIATED TO AN INDEX SET I_B

MEANING AND INTERPRETATION OF DUAL VARIABLES IN THE MIN-COST FLOW PROBLEM

Once a basic feasible solution is determined,
(or equivalently, a **Spanning Tree** and a **root node** has been determined)

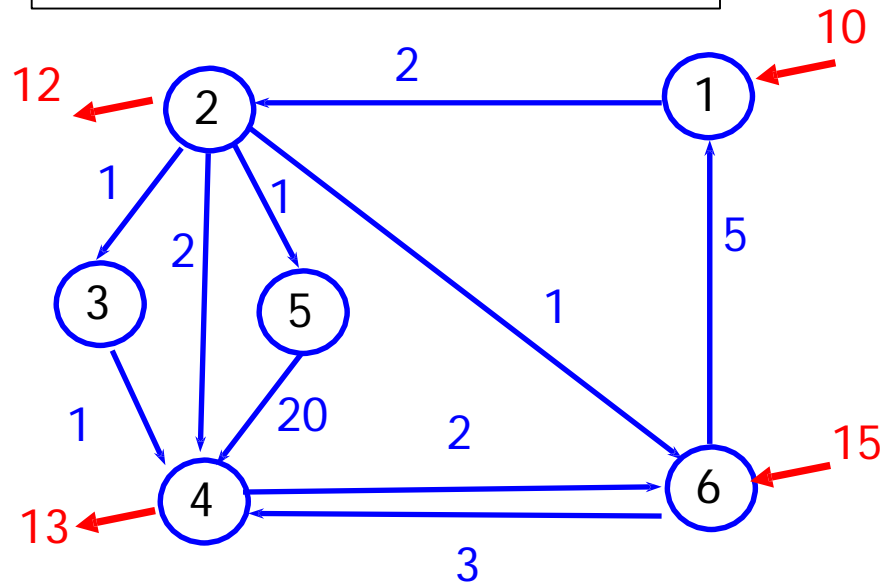
- The dual variable λ_i for a node i is the ‘- cost’ to reach that node i from the root node, using the paths marked by the spanning tree.
(In order to adjust to standard mathematical formulations the - is adopted)
- By convention, the dual variable λ_r of the root node r is set to $\lambda_r = 0$
- **Dual variables are associated to the structure marked by I_B**

If another basic feasible solution is considered, dual variables are different.

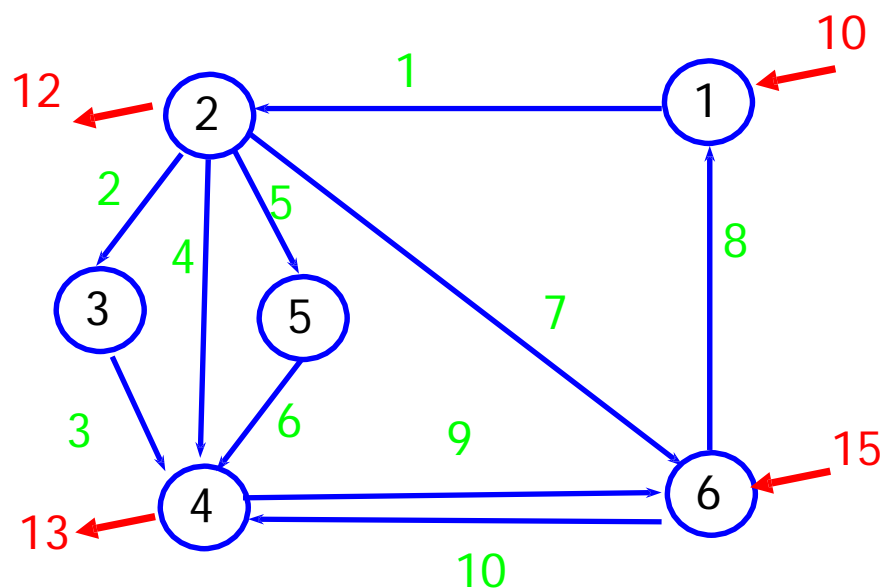
DUAL VARIABLES ASSOCIATED TO AN INDEX SET I_B

$$c^T = (2, 1, 1, 2, 1, 20, 1, 5, 2, 3)$$

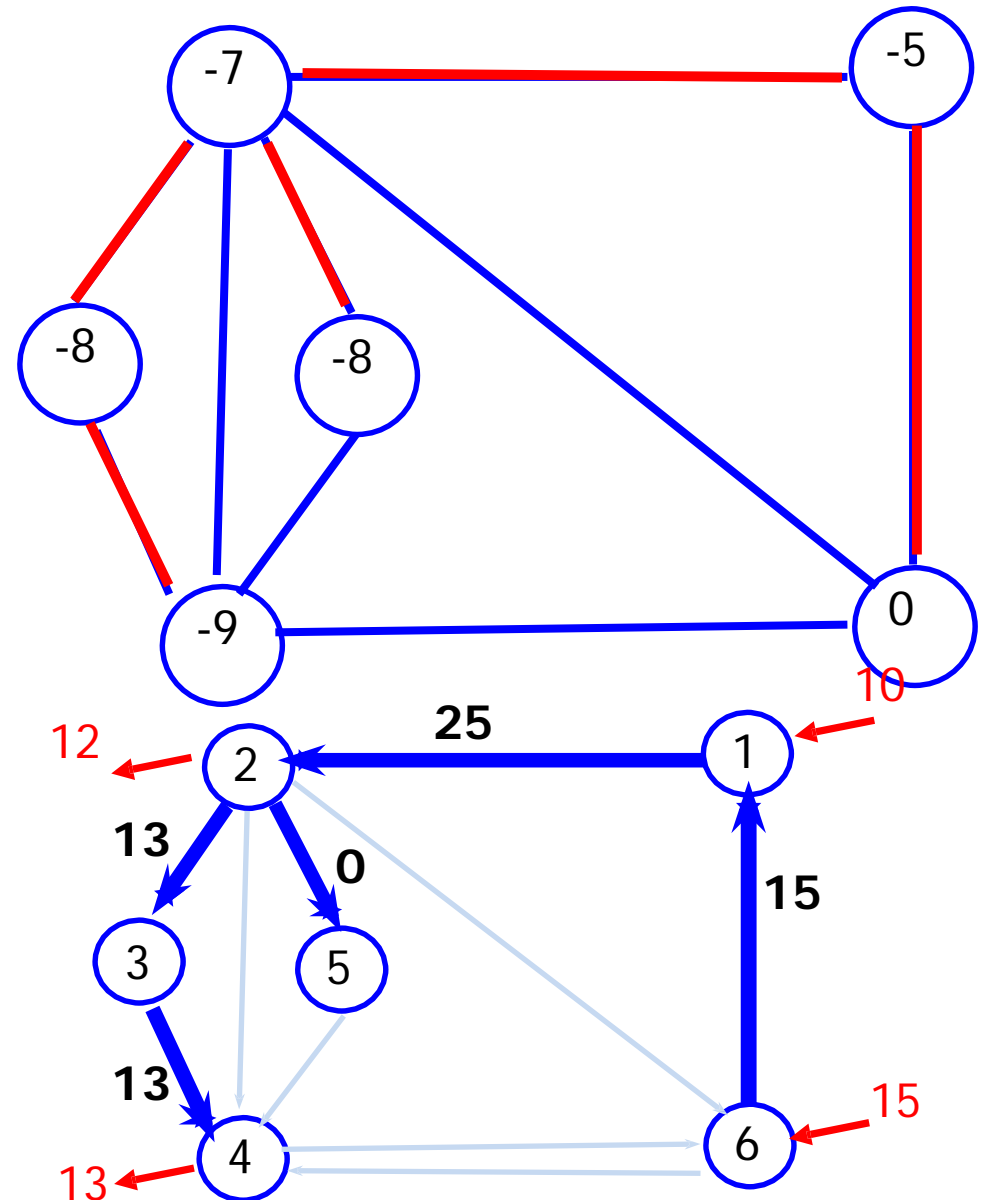
Link Costs



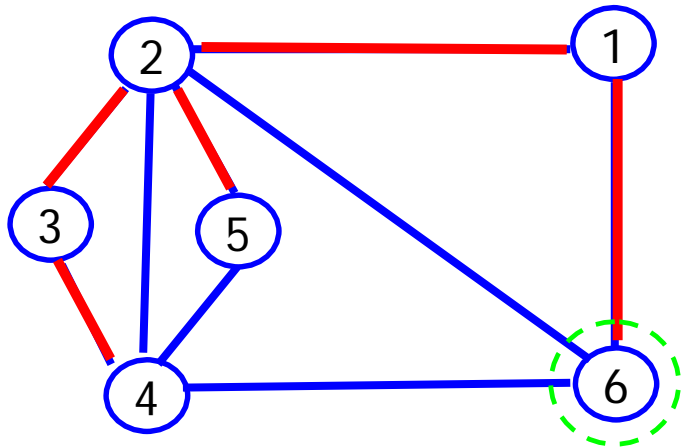
Link Number



Dual variables using the Spanning Tree

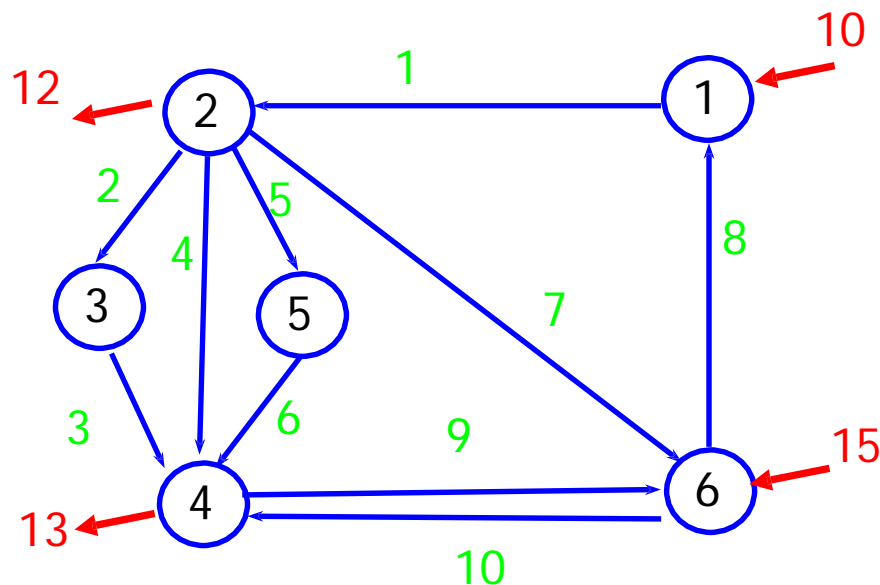


DUAL VARIABLES ASSOCIATED TO AN INDEX SET I_B



$$B^T \lambda = c_B$$

$$\begin{pmatrix} -1 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \lambda_4 \\ \lambda_5 \end{pmatrix} = \begin{pmatrix} c_{61} \\ c_{12} \\ c_{23} \\ c_{34} \\ c_{25} \end{pmatrix}$$



**Feasible
basis**

$$\lambda_1 = -c_{61}$$

$$\lambda_2 = -c_{61} - c_{12}$$

$$\lambda_3 = -c_{61} - c_{12} - c_{23}$$

$$\lambda_5 = -c_{61} - c_{12} - c_{25}$$

$$\lambda_4 = -c_{61} - c_{12} - c_{23} - c_{34}$$

$$(\lambda_6 = 0)$$

$\lambda_i = -$ Unit cost from root $\rightarrow i$

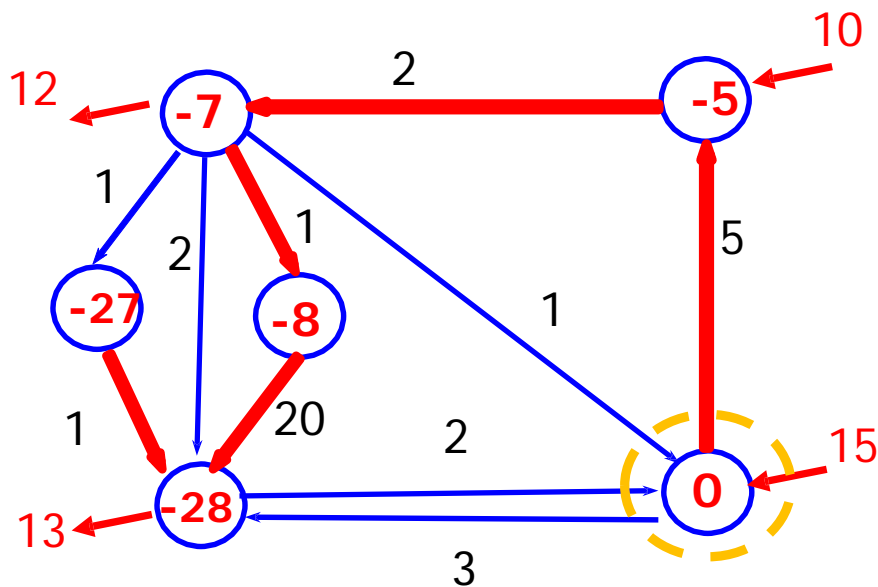
Algebraic calculation

REDUCED COSTS ASSOCIATED TO AN INDEX SET I_B

Looking for a better BFS

Let us focus on node **4**. Currently, it is accessed through node 3 (using the Spanning Tree) with a cost of 9.

If link **(2,3)** is dropped from the current basis and link **(5,4)** is added to form a new basis ...
Would things go better??

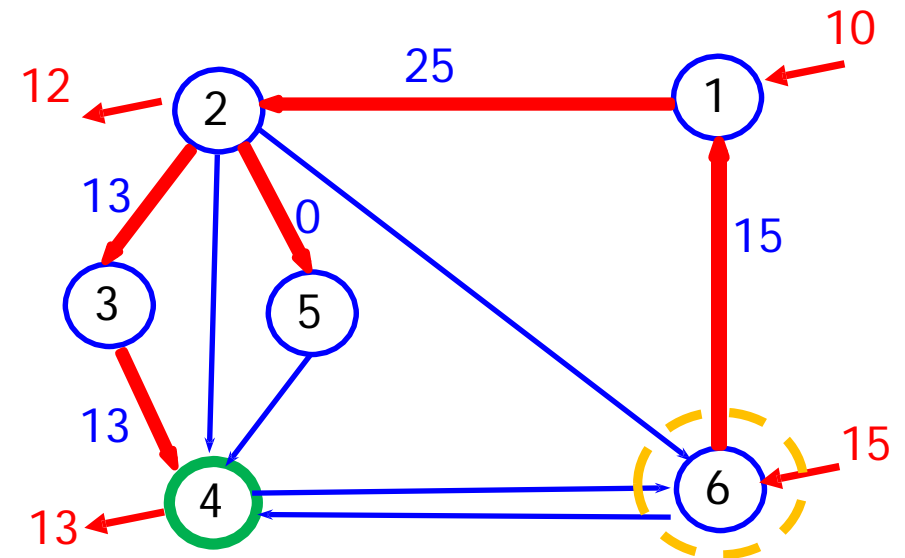


The decrease per unit of flow reaching node 4 would be:

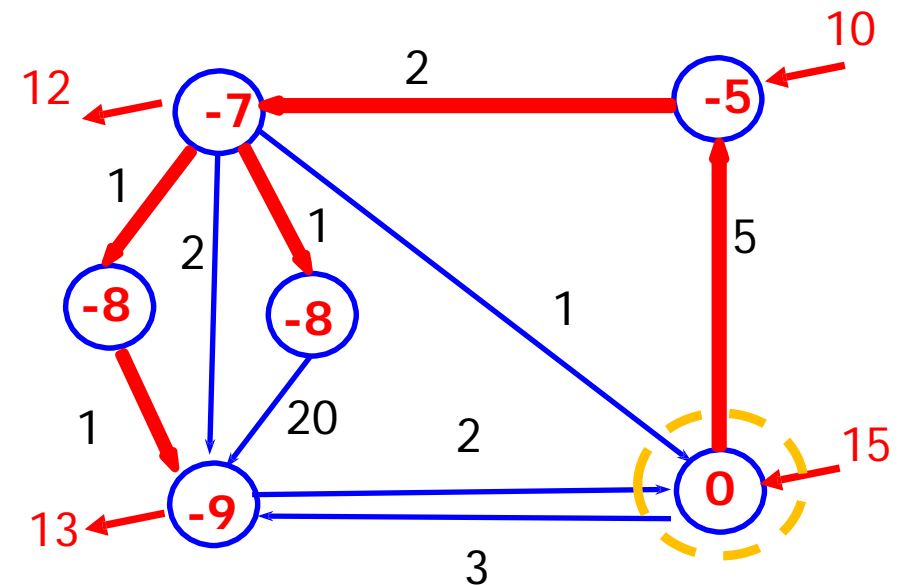
$$9 - 28 = -19$$

Clearly, it is a bad option!

Obj.Function value = 151



Link Flows



Link costs & dual variables

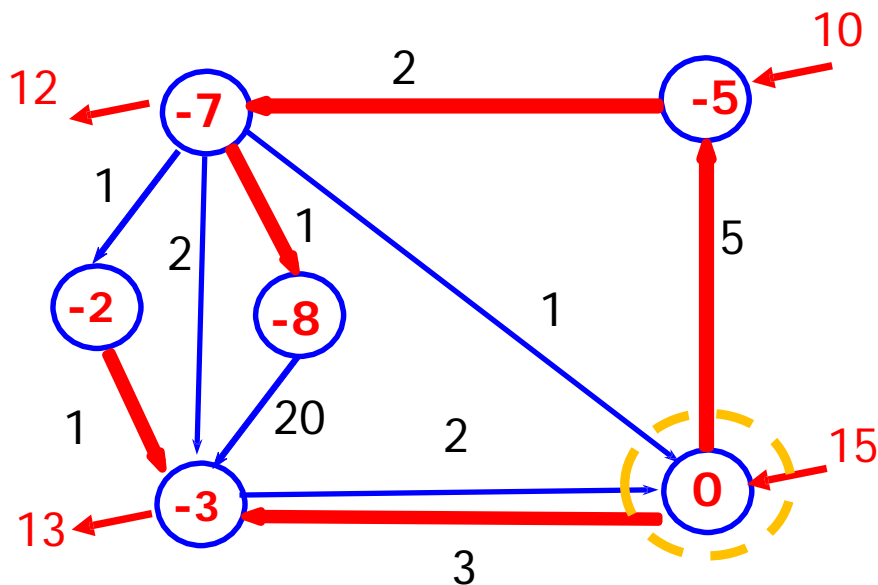
REDUCED COSTS ASSOCIATED TO AN INDEX SET I_B

Looking for a better BFS

Let us focus on node **4**. Currently, it is accessed through node 3 (using the Spanning Tree) with a cost of 9.

If link **(2,3)** is dropped from the current basis and link **(6,4)** is added to form a new basis ...

Would things go better??

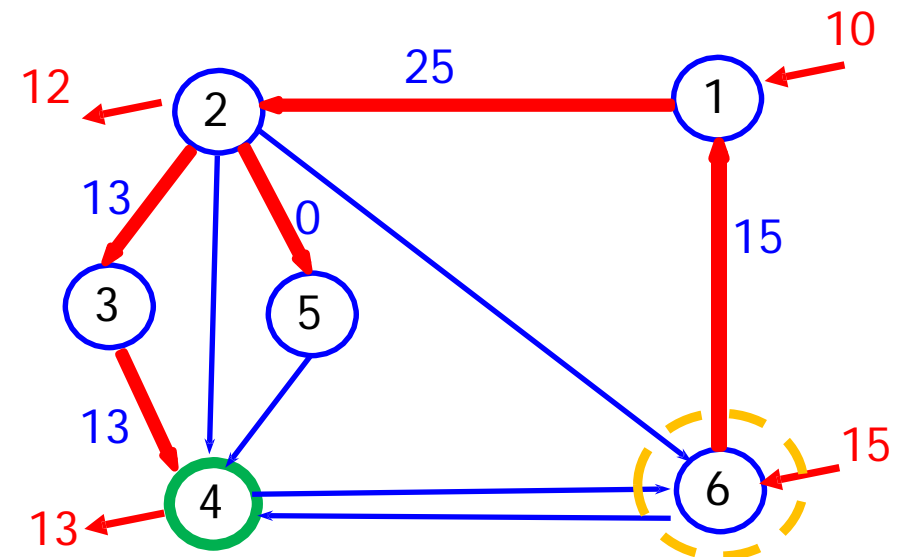


The decrease per unit of flow reaching node 4 would be: $9 - 3 = 6$

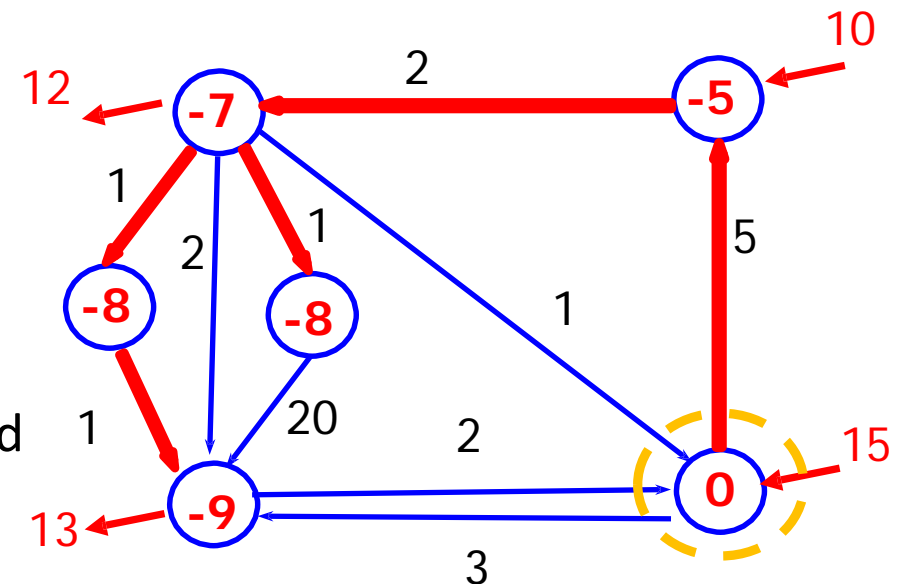
Clearly, it is a good option!

(Provided that flows can be accommodated on the new basis)

Obj.Function value = 151



Link Flows



Link costs & dual variables

REDUCED COSTS ASSOCIATED TO AN INDEX SET I_B

Reduced costs calculation

Let link $a_k = (i, j)$, $k \in I_N$:

$$r_k = c_k - (\lambda_i - \lambda_j)$$

$$c^T = (2, 1, 1, 2, 1, 20, 1, 5, 2, 3)$$

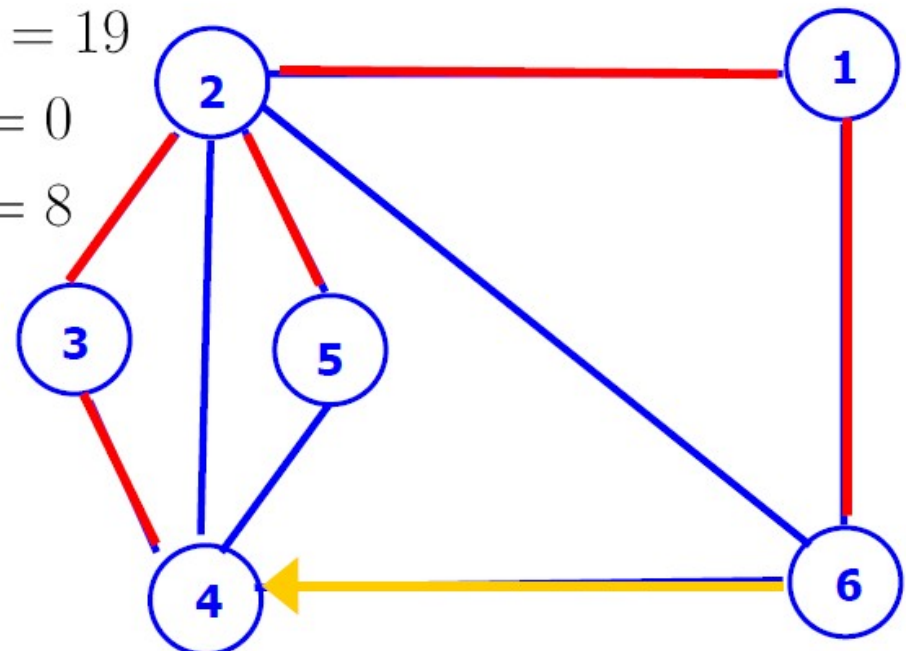
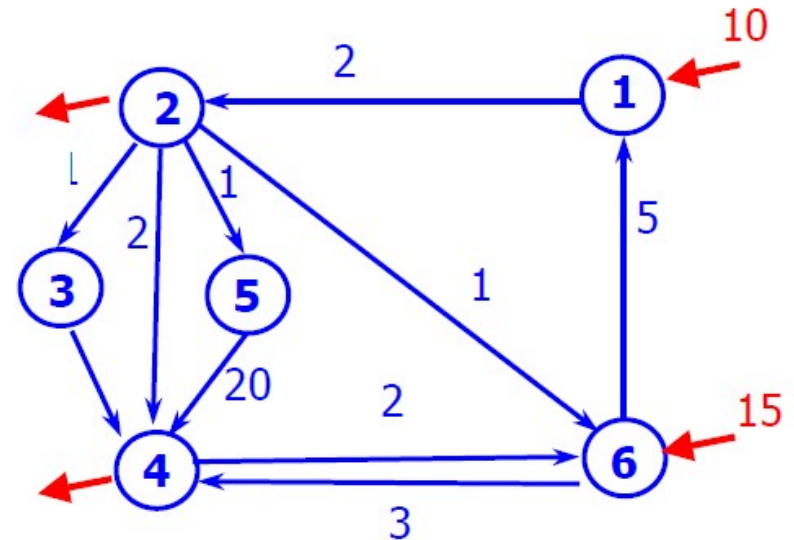
$$r_{64} = c_{64} - (\lambda_6 - \lambda_4) = 3 - (0 + 9) = -6$$

$$r_{46} = c_{46} - (\lambda_4 - \lambda_6) = 2 - (-9 - 0) = 11$$

$$r_{54} = c_{54} - (\lambda_5 - \lambda_4) = 20 - (-8 + 9) = 19$$

$$r_{24} = c_{24} - (\lambda_2 - \lambda_4) = 2 - (-7 + 9) = 0$$

$$r_{26} = c_{26} - (\lambda_2 - \lambda_6) = 1 - (-7 + 0) = 8$$



DETERMINING AN ENTERING NON-BASIC VARIABLE

CONDITIONS FOR AN OPTIMAL INDEX SET I_B

Let I_B a set of feasible basic indices associated with matrix B .

$$I_{N+} = \{ a \notin I_B, | x_a = u_a \}$$

$$I_{N-} = \{ a \notin I_B, | x_a = 0 \}$$

An optimal basic solution is characterized by:

- If $a \in I_B$ then $r_a = 0$
- If $a \in I_{N+}$ then $r_a \leq 0$ ← Why this condition??
- If $a \in I_{N-}$ then $r_a \geq 0$

CONDITIONS FOR A *UNIQUE* SOLUTION OF THE PROBLEM

Let I_B a set of feasible basic indices associated with matrix B .

$$I_{N^+} = \{ a \notin I_B, \mid x_a = u_a \}$$

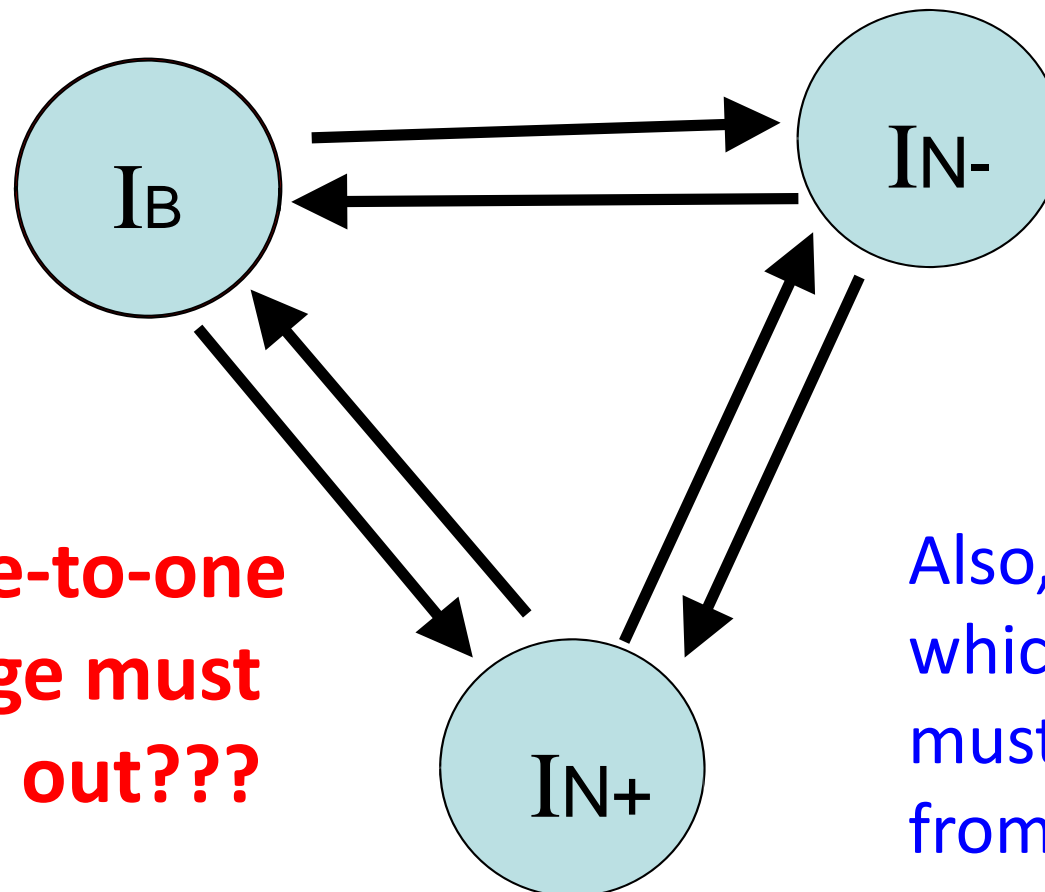
$$I_{N^-} = \{ a \notin I_B, \mid x_a = 0 \}$$

Then, if it verifies the following conditions, is the *unique* solution of the problem

- If $a \in I_B$ then $r_a = 0$
- If $a \in I_{N^+}$ then $r_a < 0$ ← Why this condition??
- If $a \in I_{N^-}$ then $r_a > 0$

By now we know how to identify indices I_B, I_{N+}, I_{N-} defining an optimal solution.

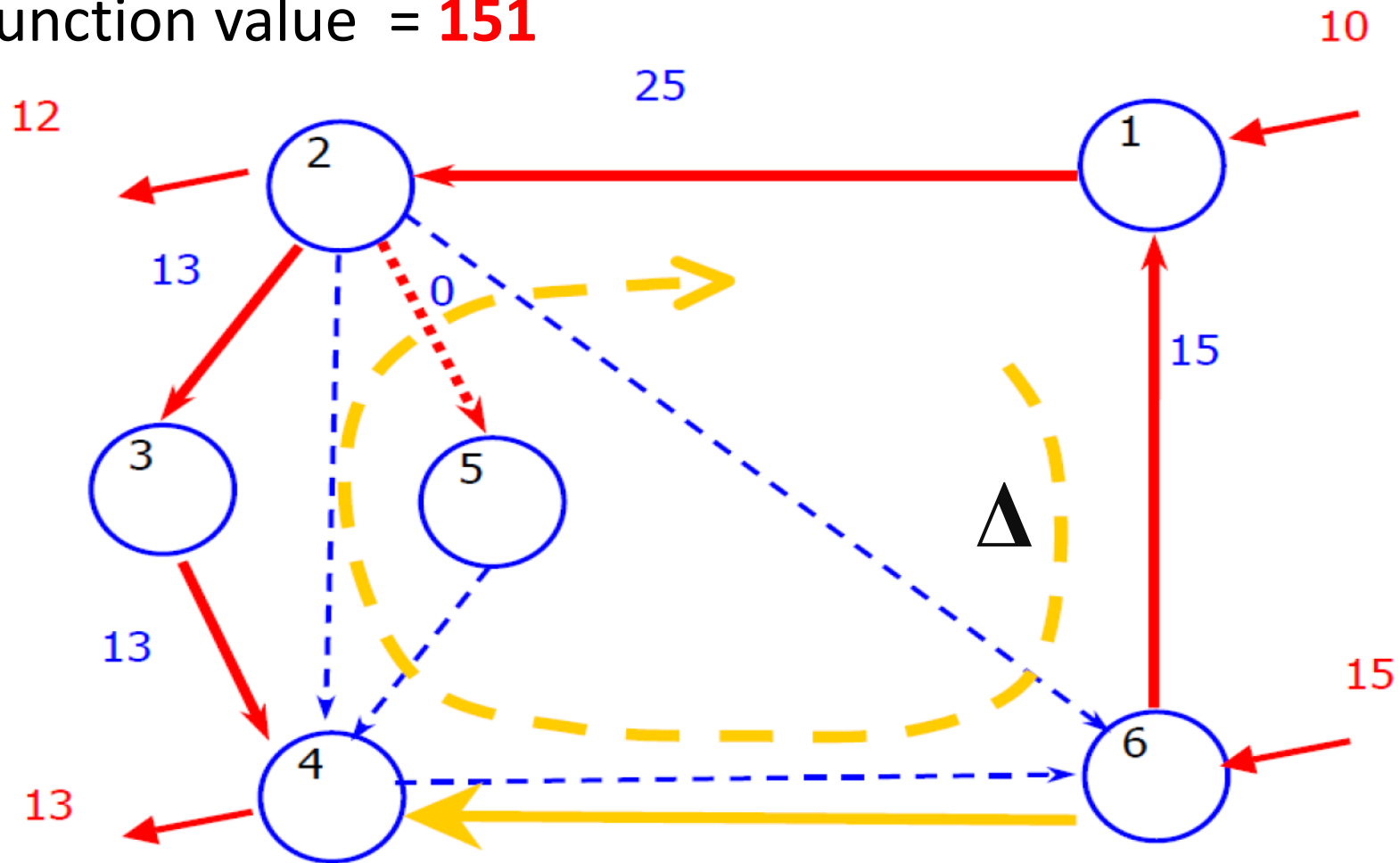
If the current solution is not optimal, the following **one-to-one interchanges** between sets I_B, I_{N+}, I_{N-} may occur in order to obtain new sets I_B, I_{N+}, I_{N-} .



How a one-to-one interchange must be carried out???

Also, we know which links (i,j) must be chosen from the non-basic sets !!

Obj. Function value = **151**



$$\Delta = x_{6,4} = \text{Min} \{ 13, 13, 25, 15 \} = 13$$

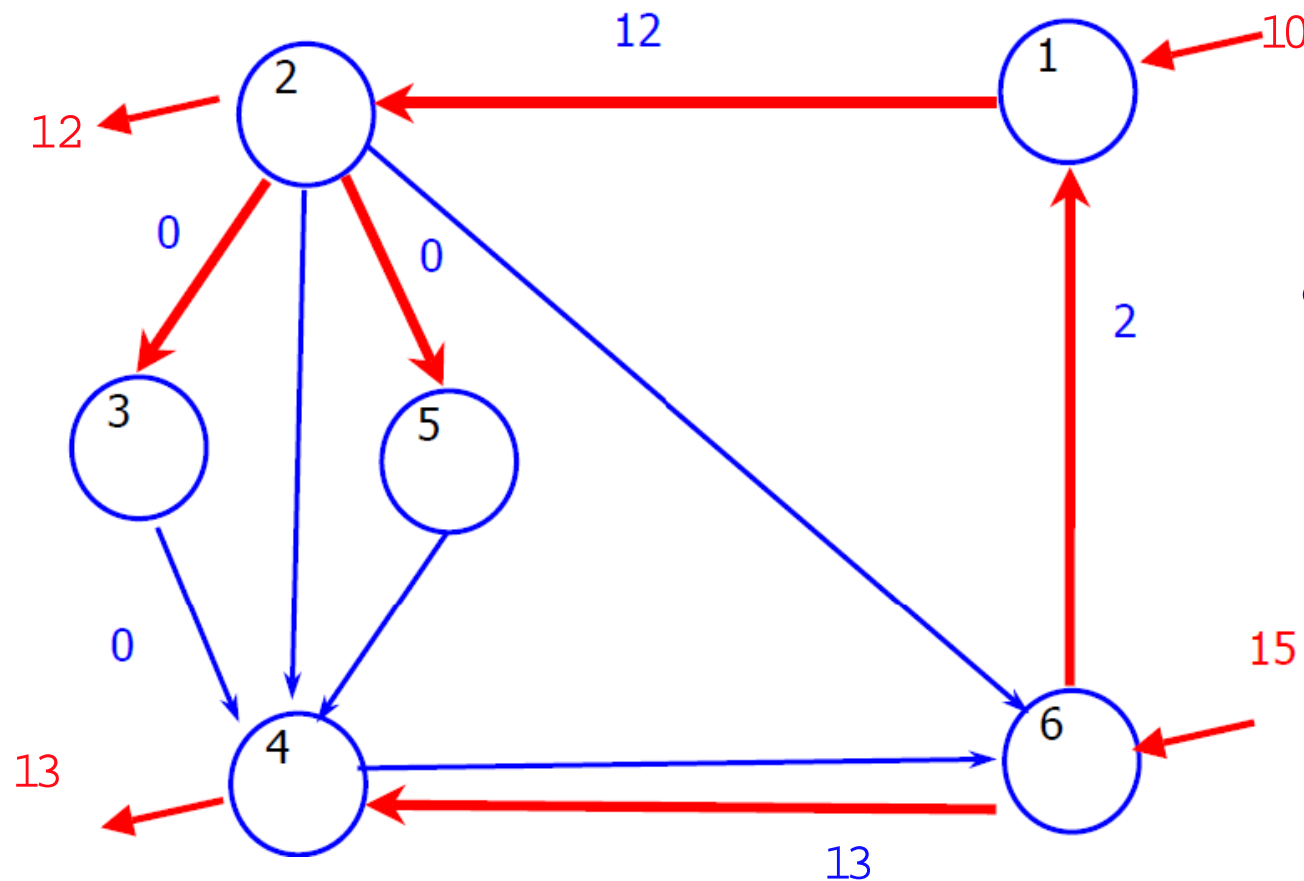
EXITING BASIC VARIABLE: (3,4) or (2,3) (Tie!)

Notice the sign (+)
that will be
applied to Δ !!!

New Obj. Function value = $2 \times 5 + 2 \times 12 + 3 \times 13 = \mathbf{73}$

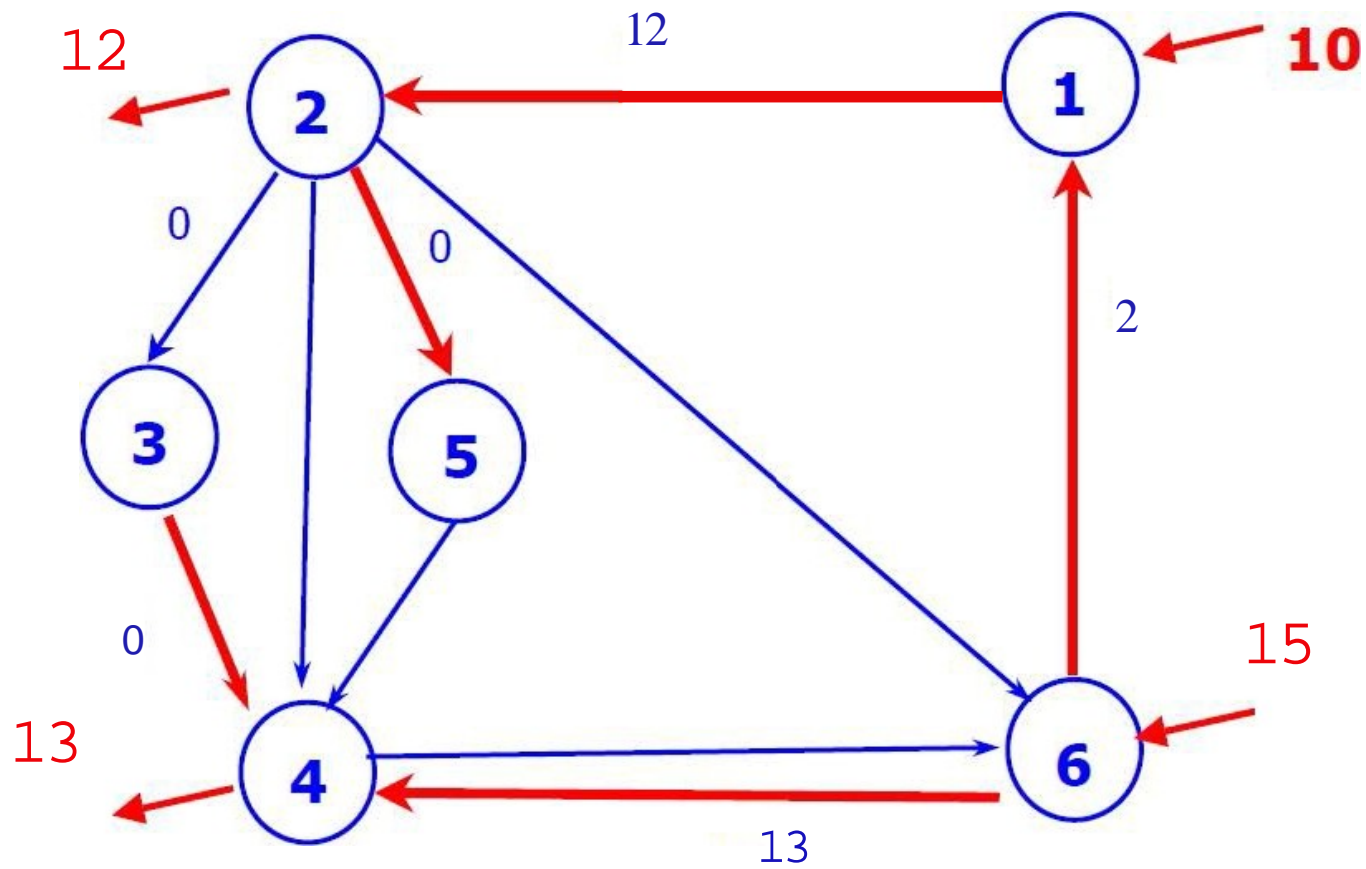
New Obj. Function value =

= Previous value + (reduced cost r_{ij} of entering non-basic variable (i,j)) $\times (+\Delta) =$
= $\mathbf{151} + (-6) \times 13 = 151 - 78 = \mathbf{73}$



Notice the sign (+)
applied to Δ !!!

NEW BASIC FEASIBLE SOLUTION

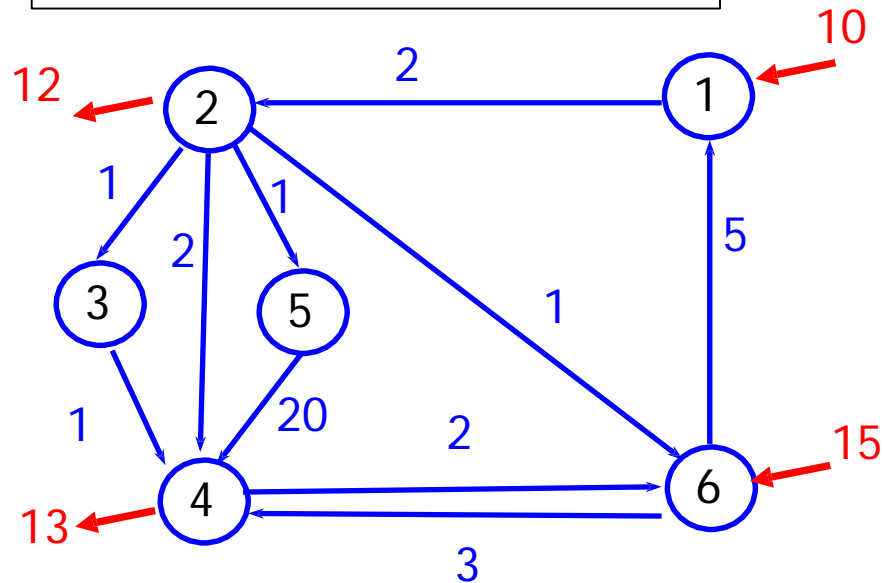


ALTERNATIVE BASIC SOLUTION

PROBLEMS with UPPER BOUNDS. $I_{N+} \leftrightarrow I_{N-}$

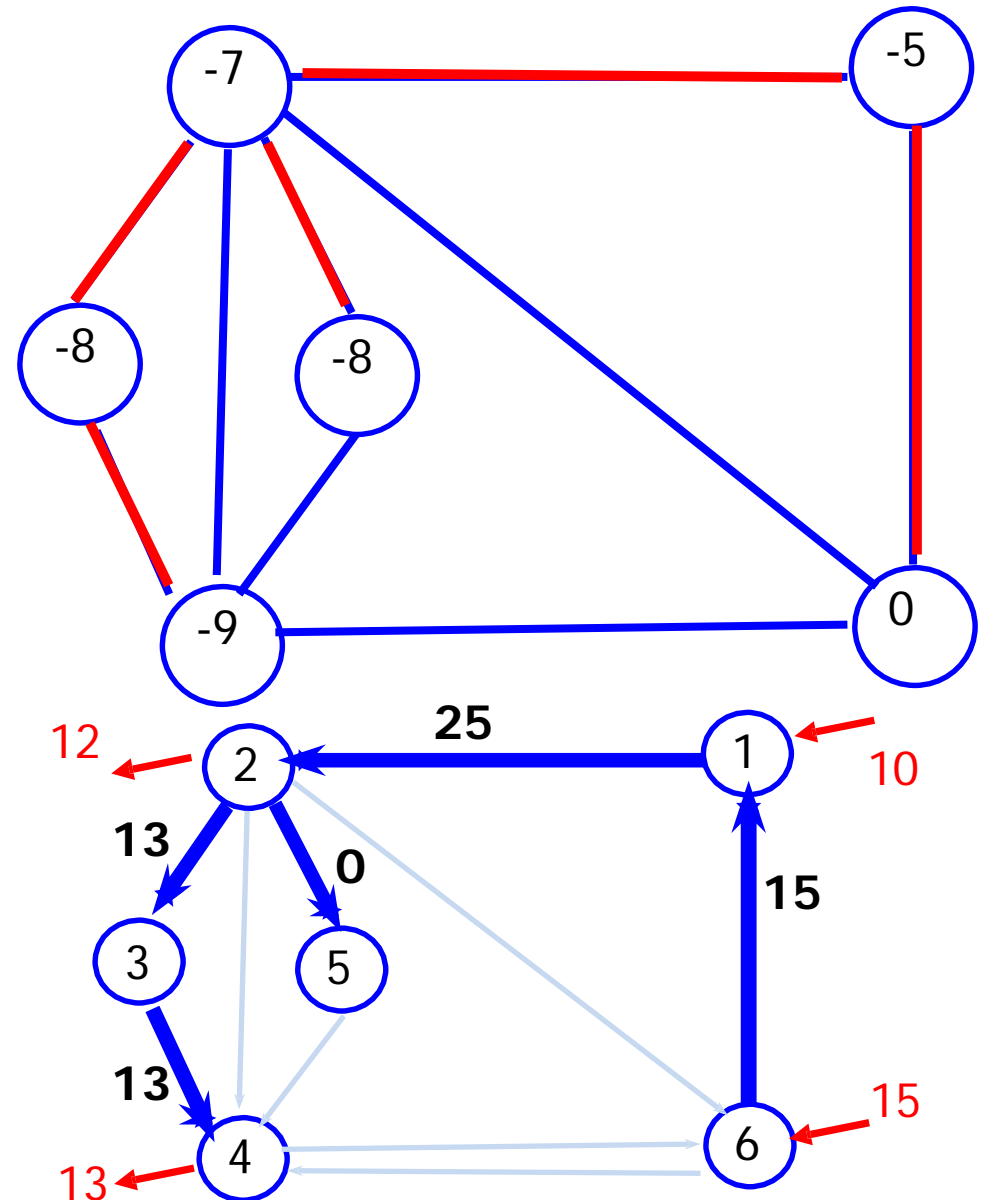
$$c^T = (2, 1, 1, 2, 1, 20, 1, 5, 2, 3)$$

Link Costs



Assume now that $x_{64} \leq 10$ and try to find the optimal solution

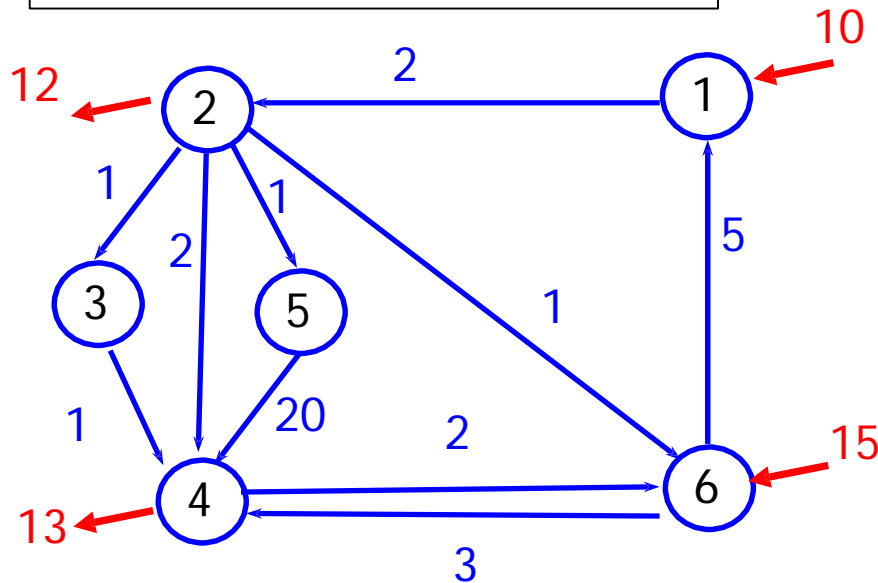
Dual variables using the Spanning Tree



PROBLEMS with UPPER BOUNDS. $I_{N+} \leftrightarrow I_{N-}$

$$c^T = (2, 1, 1, 2, 1, 20, 1, 5, 2, 3)$$

Link Costs

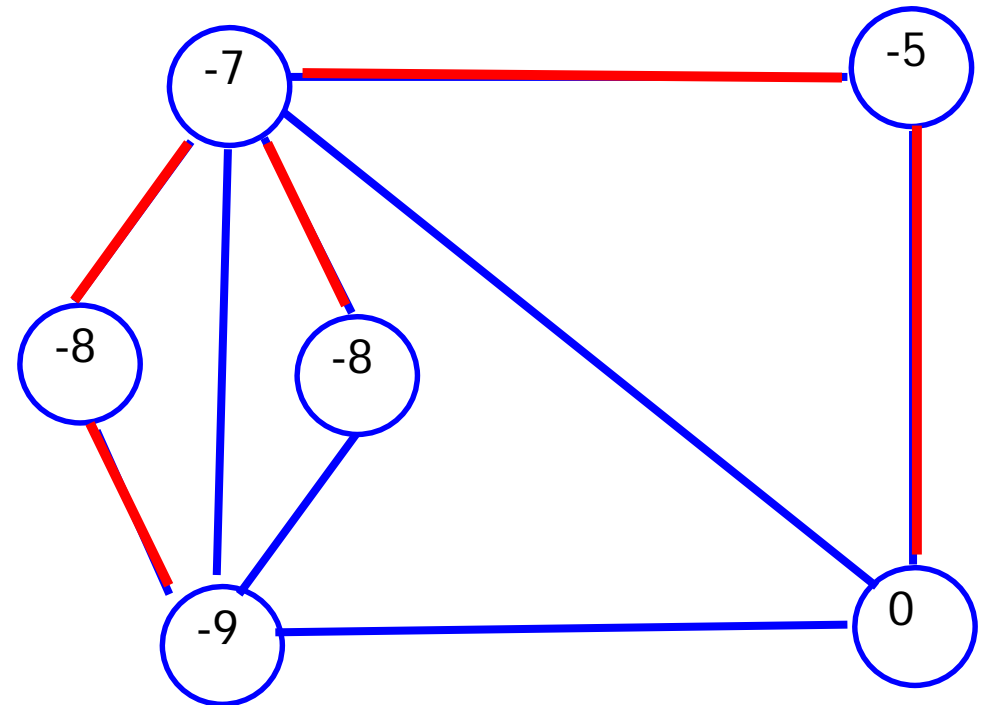


$$I_B = \{ (6,1), (1,2), (2,3), (3,4), (2,5) \}$$

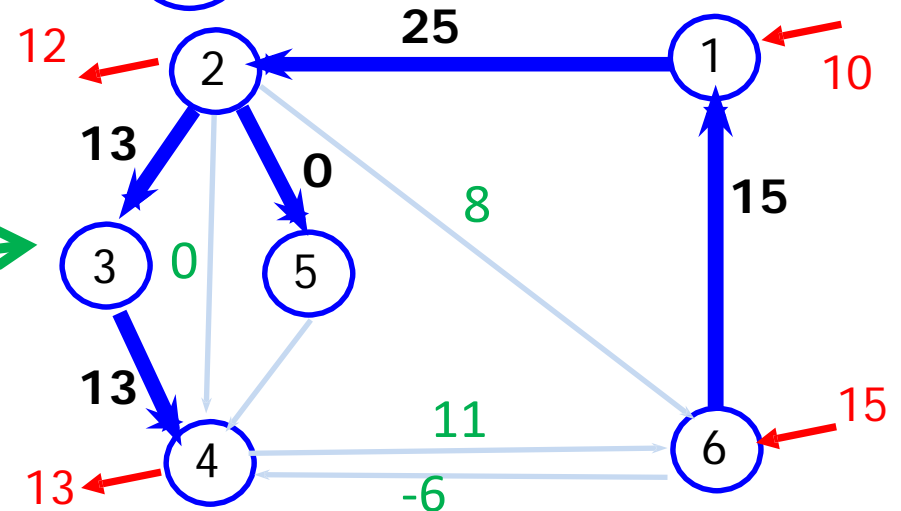
$I_{N+} = \text{empty}$

$I_{N-} = \text{the remaining links}$

Dual variables using the Spanning Tree



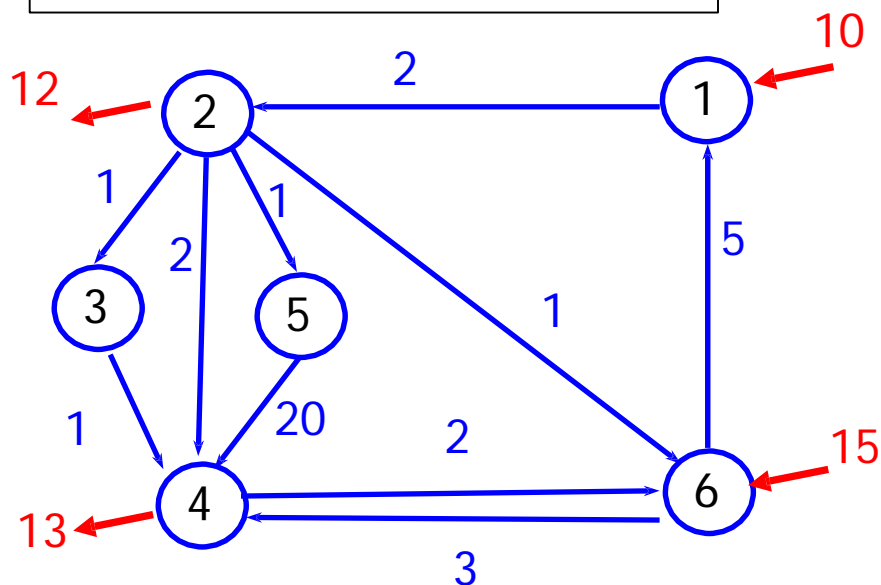
Reduced costs



PROBLEMS with UPPER BOUNDS. $I_{N+} \leftrightarrow I_{N-}$

$$c^T = (2, 1, 1, 2, 1, 20, 1, 5, 2, 3)$$

Link Costs



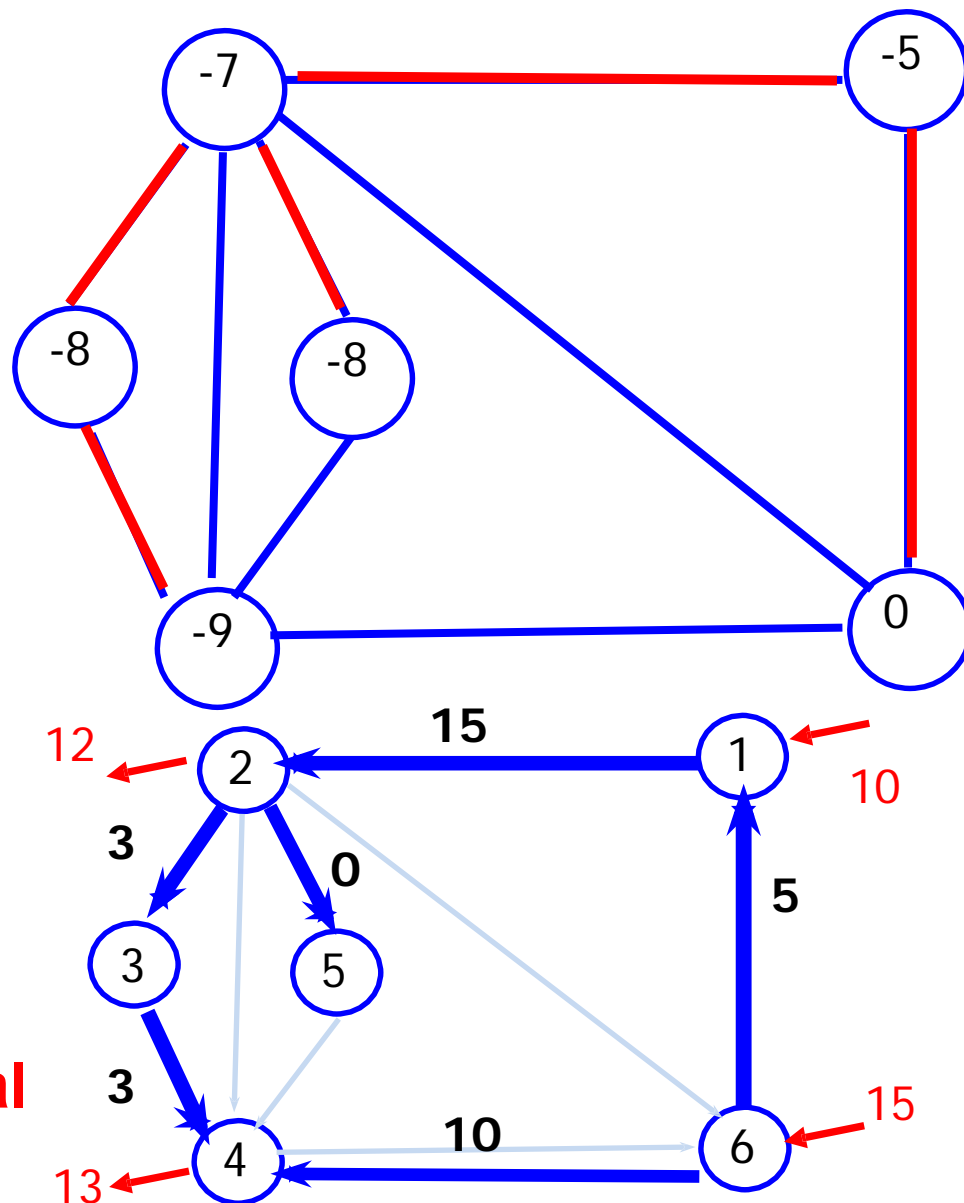
$$I_B = \{ (6,1), (1,2), (2,3), (3,4), (2,5) \}$$

$$I_{N+} = \{ (6,4) \}$$

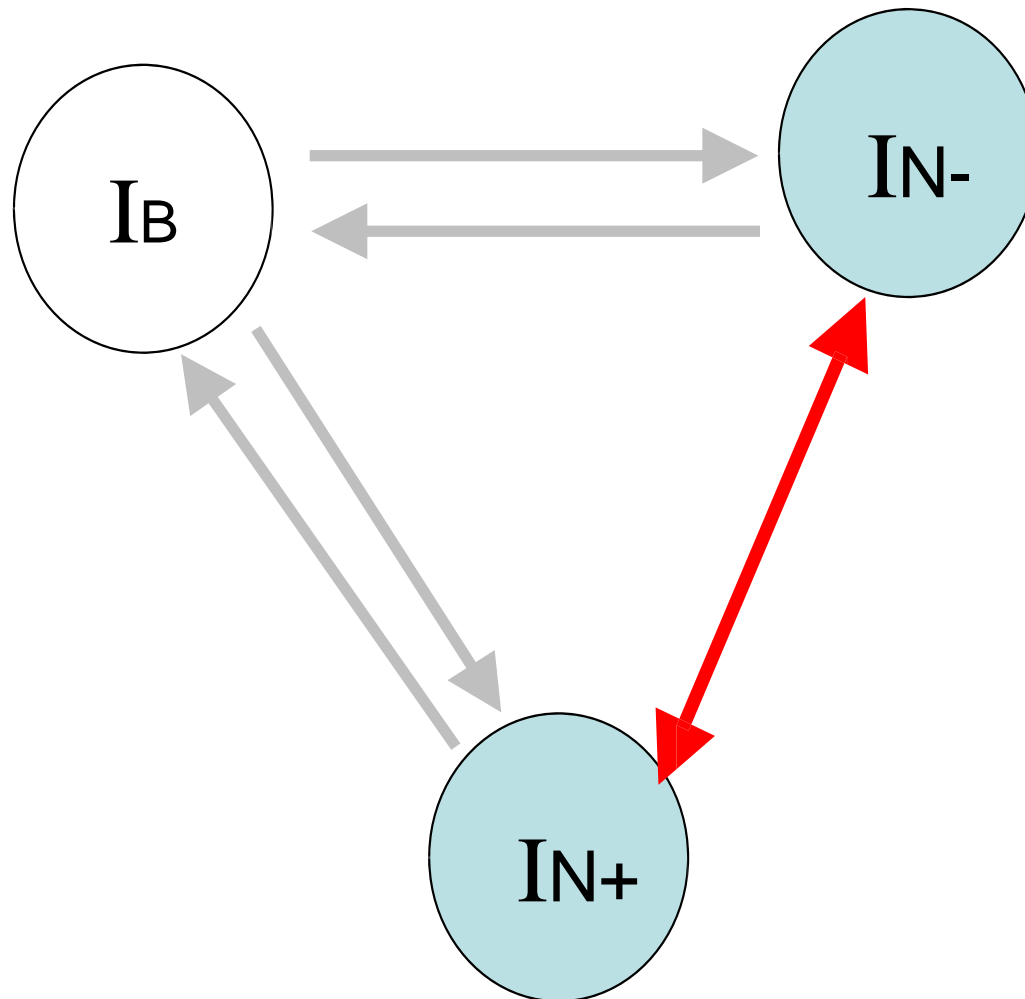
I_{N-} = the remaining links

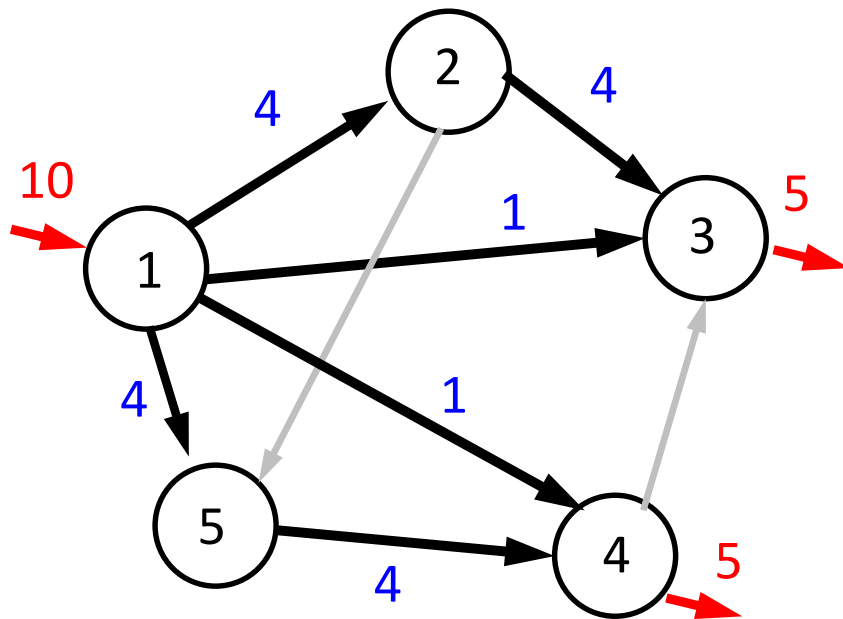
Check that this solution is optimal

Dual variables using the Spanning Tree



- Interchange $I_{N+} \leftrightarrow I_{N-}$





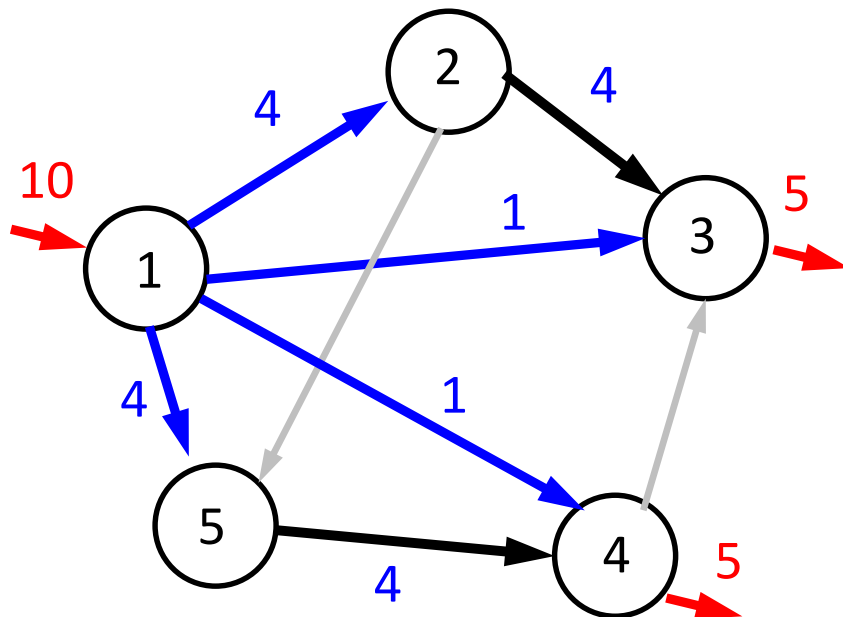
Assume the Min-Cost Flow problem defined by $c_i=1$, $u_{ij}=4$

Consider the initial feasible solution shown here. Try to find the optimal solution of the problema.

- State which are the set of basic indices I_B
- Id. Non-basic I_{N+} , I_{N-}

PROBLEMS with UPPER BOUNDS.

An example for the interchange $I_{N+} \leftrightarrow I_B$



Assume the Min-Cost Flow problem defined by $c_i=1$, $u_{ij}=4$

Consider the initial feasible solution shown here. Try to find the optimal solution of the problema.

- State which are the set of basic indices I_B
- Id. Non-basic I_{N+} , I_{N-}

$$I_B = \{(1,2), (1,3), (1,4), (1,5)\}$$

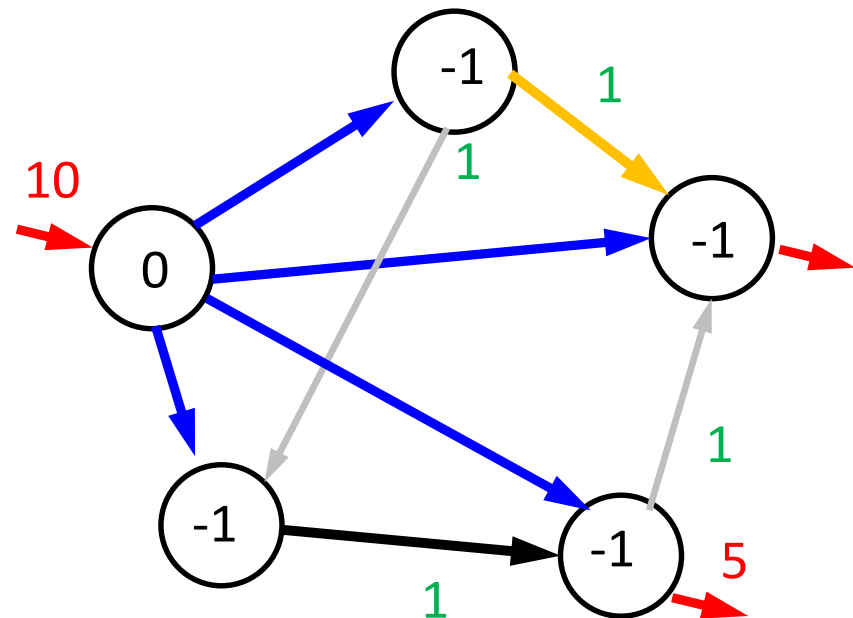
$$I_{N+} = \{(2,3), (5,4)\}$$

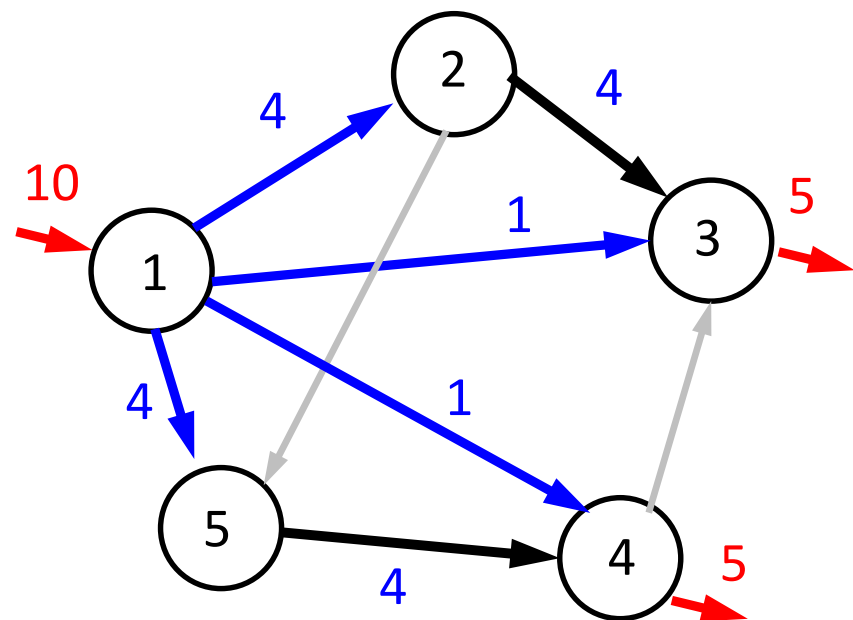
$$I_{N-} = \{(2,5), (4,3)\}$$

Current Obj.F. Value = 18

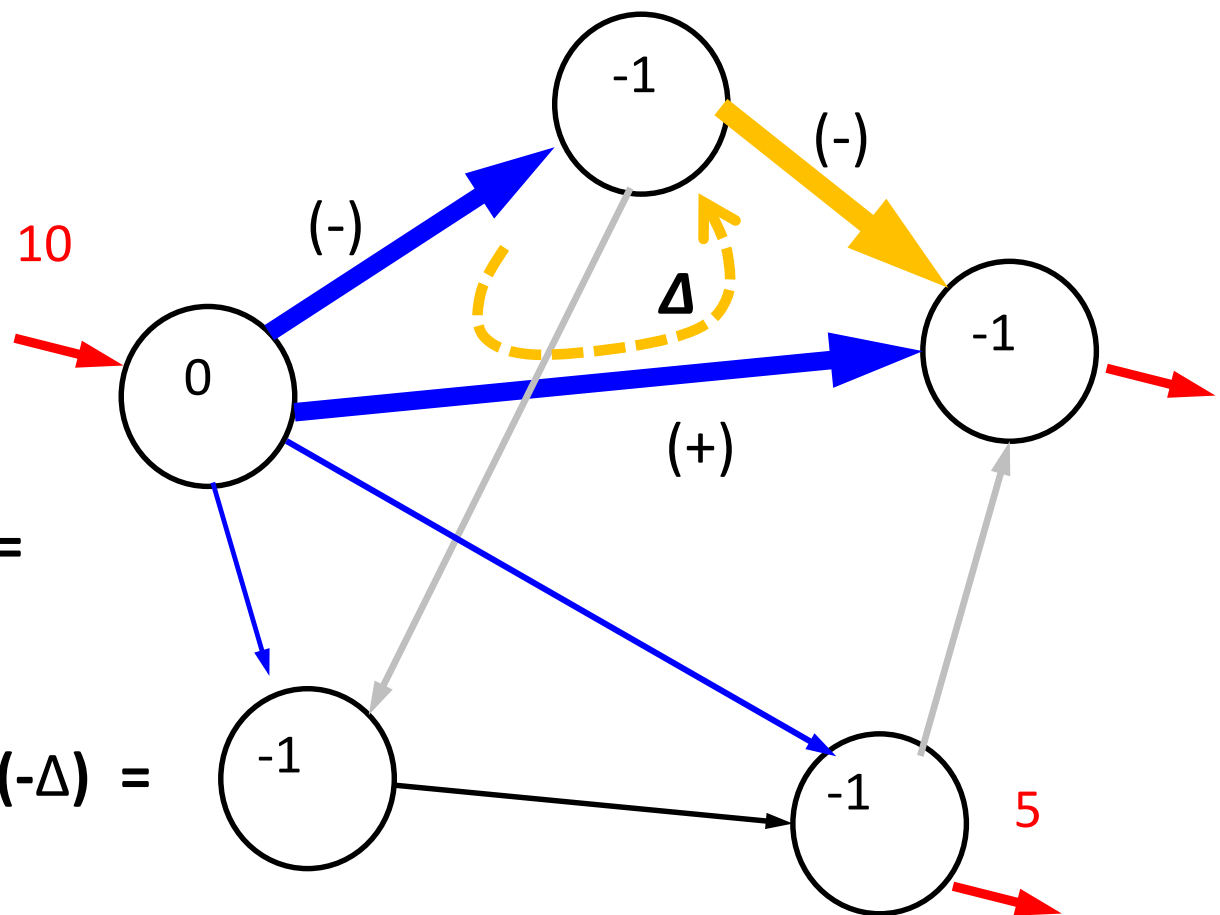
Either (2,3) or (5,4) may leave I_{N+} providing a better obj. Function value.

- (2,3) is chosen





How much can be the
recirculating flow Δ ??

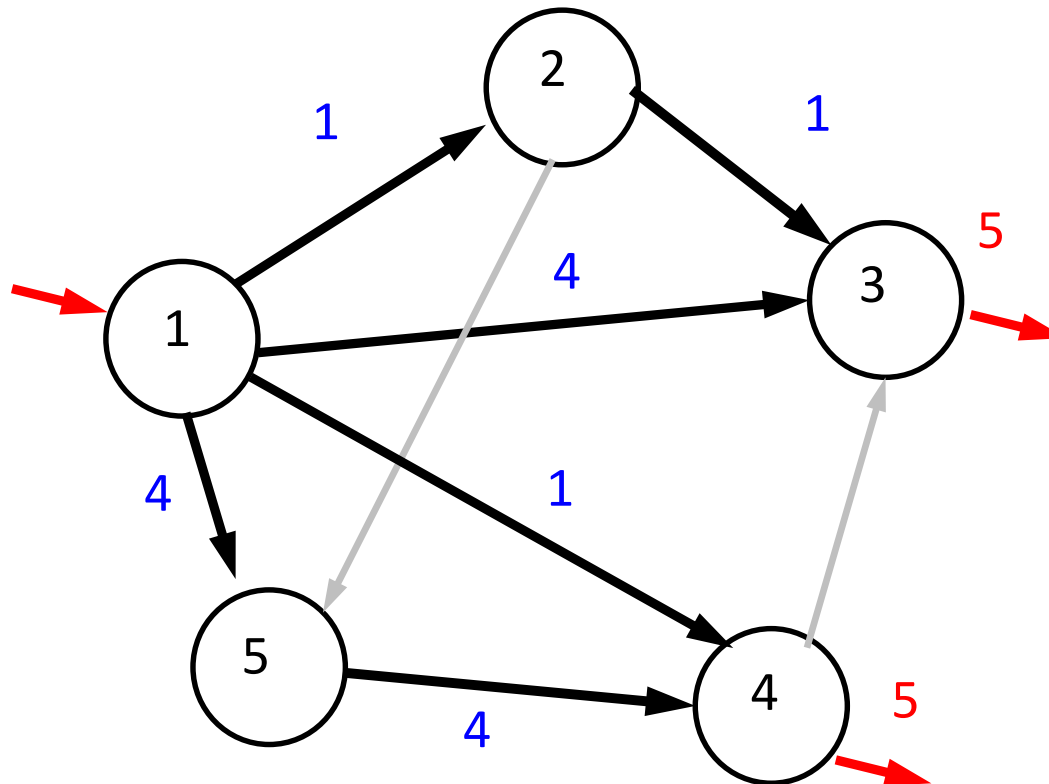


$$\Delta = \text{Min}\{ u_{13} - x_{13}, x_{23}, x_{12} \} = \text{Min}\{ 3, 4, 4 \} = 3$$

$$\text{New Obj.F} = \text{Old Obj.F} + r_{23} (-\Delta) = 18 + 1 \times (-3) = 15$$

New feasible solution.

Can you identify the new index sets I_B , I_{N+} , $I_{N+}???$

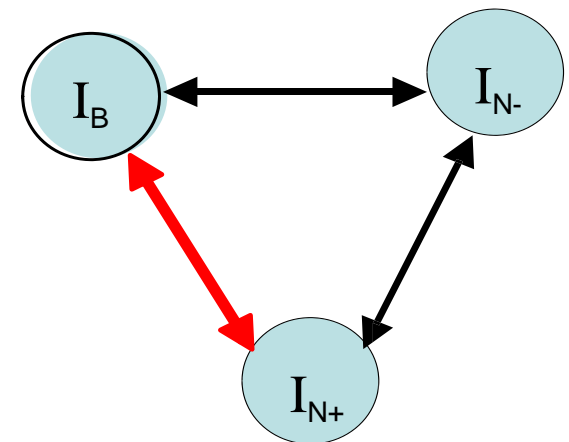
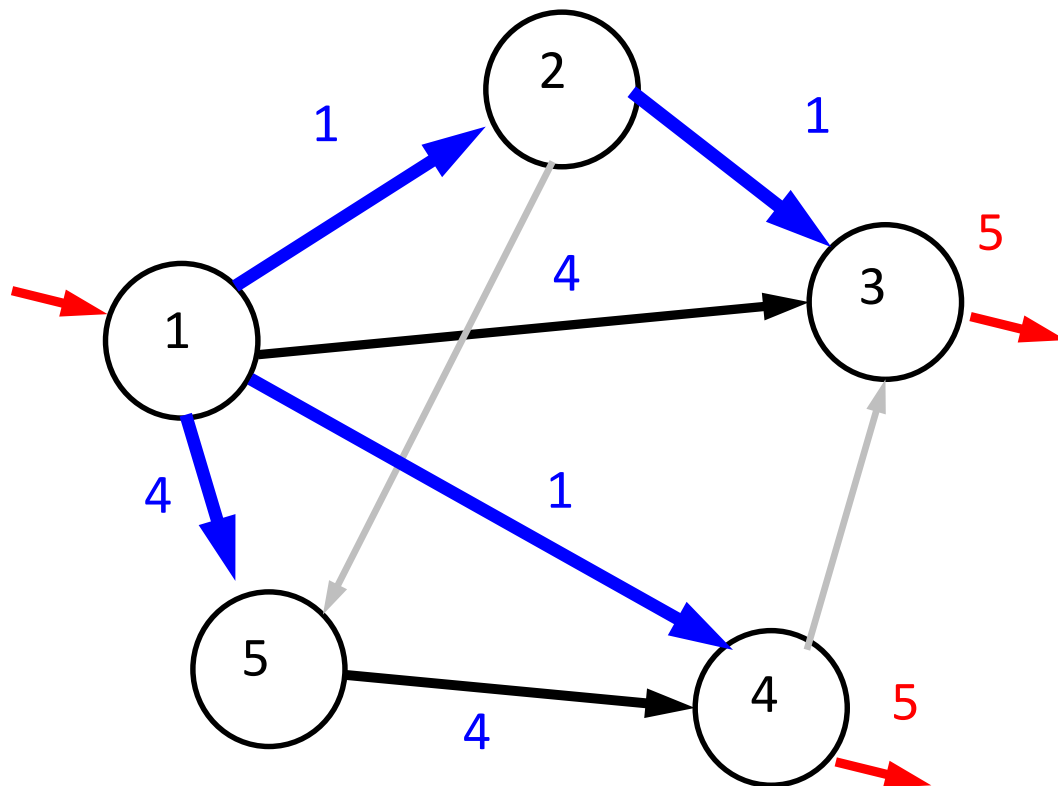


New feasible solution:

$I_B = \{(1,2), (2,3), (1,5), (1,4)\},$

$I_{N+} = \{(1,3), (5,4)\}, I_{N-} = \{(2,5), (4,5)\}$

Why???



$$I_{N+} = \{ a \notin I_B, | x_a = u_a \}, \quad I_{N-} = \{ a \notin I_B, | x_a = 0 \}$$

SIMPLEX Algorithm for Network Flow Problems (with upper bounds)

0. Find an initial Feasible Basic Solution.

Fix a node as the root node and set its dual variable to 0.

1. - Calculate dual variables $\lambda_i, i \in N$, for the current basis I_B
(Remember: for basic links $a = (i, j) \in I_B, c_{ij} = \lambda_i - \lambda_j$)

2. - Evaluate reduced costs for non-basic links:

$$r_{i,j} = c_{i,j} - (\lambda_i - \lambda_j), (i, j) \in I_{N+} \cup I_{N-}$$

3. **IF** (OPTIMALITY CRITERION) IS **NOT** MET

a) Find some $a \in I_{N+}$ with $r_a > 0$ **OR** some $a \in I_{N-}$ with $r_a < 0$

b) Consider such $a = (i, j)$; identify a cycle.

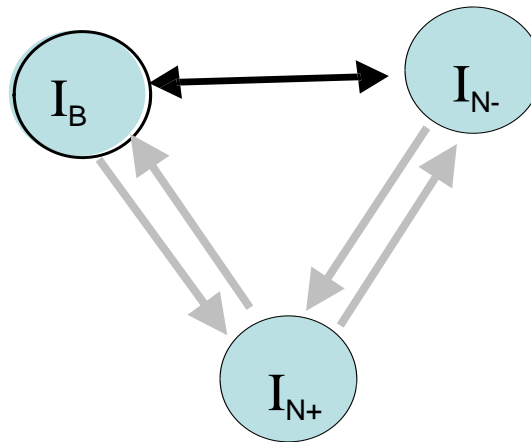
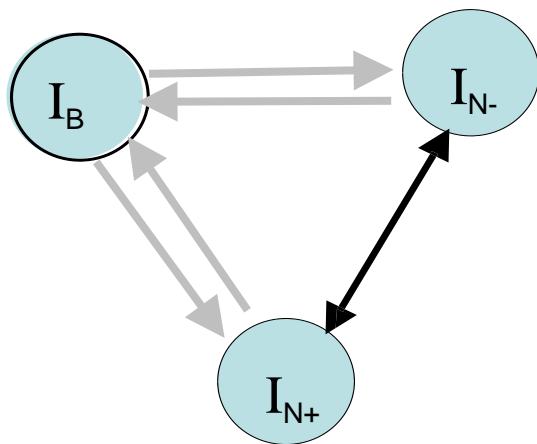
c) Calculate the max. incr./decr. flow on that cycle ($(i, j) \in I_{N-} / (i, j) \in I_{N+}$).

d) Calculate new flows and index sets I_B, I_{N+}, I_{N-}

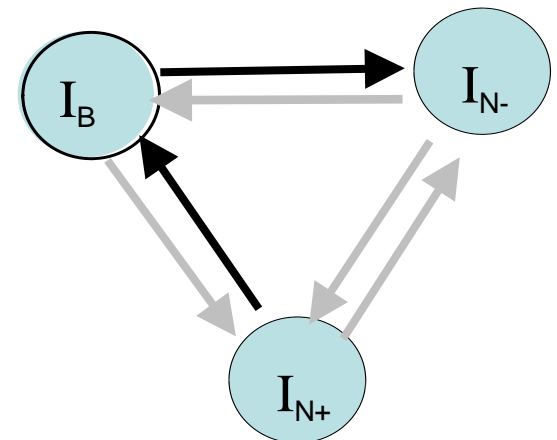
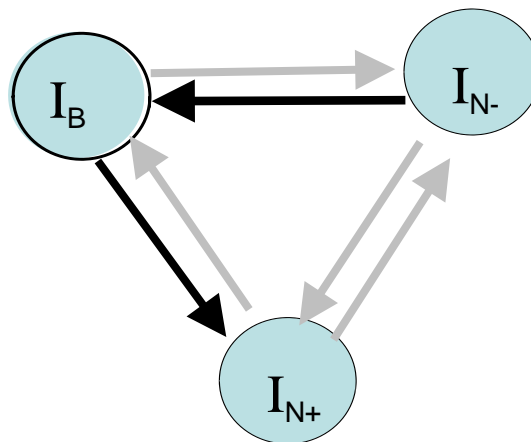
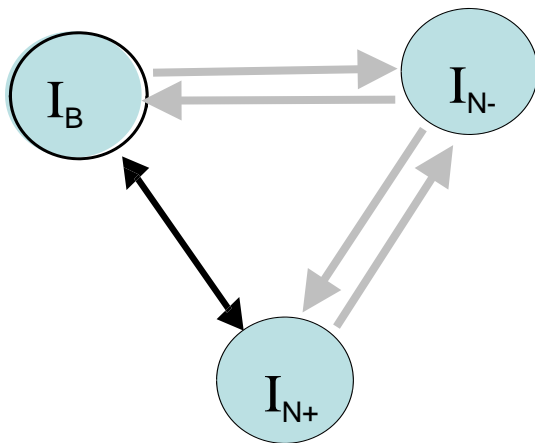
4. Go To 1

OPTIMALITY CRITERION =

$$= r_a \leq 0, \forall a \in I_{N+} \text{ **AND** } r_a \geq 0 \text{ } a \in I_{N-}, \forall a \in I_{N-}$$

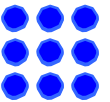
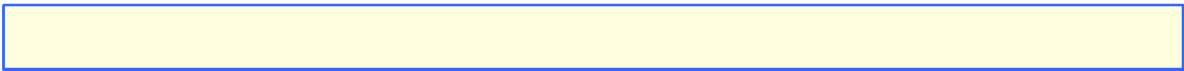
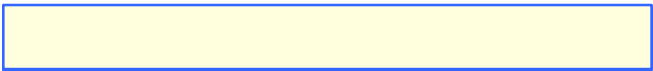


Always $|I_B| = |N| - 1$

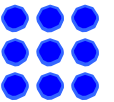


- Step 3.d in the SIMPLEX with upper bounds:

Possible interchanges for a chosen link (i, j) found at step 3.a



UPC



U P C