

# Status Masterarbeit

- Kalibrierung (Priorität, RANSAC)
- Registration
- Gliederung Arbeit
- Titel Arbeit
  - “Deep Learning in Laryngological Stereo Endoscopy”
- Zeitplan

The *random sample consensus* is a paradigm for model fitting, which takes the presence of outliers in the underlying data set into account. It was first proposed by [6] and has since then widely been used [2nd source]. Outliers, which are points in the data set, are present if either

- their location deviates significantly from the ground truth, or
- their correspondence to a subset of the data set is wrong.

Why does this apply to our case -> explanation

Why can we not simply remove outliers -> explanation

The RANSAC can be described as an algorithm that follows the steps:

1. Draw samples uniformly and at random from the input data set.
2. Cardinality of sample set is the **smallest size** sufficient to estimate the model parameters.
3. Compute the model parameters for each element of the sample data.
4. Evaluate the quality of the hypothetical models on the full data set.
  - Cost function for the evaluation of the quality of the model
  - Inliers: data points which agree with the model within an error tolerance
5. The hypothesis which gets the most support from the data set is taken as the best estimate.

- precise = false -> 2 points of 2 rays (4 points)
- precise = true -> 2 points of 2 rays (4 points)  
+ 1 point of each left over ray

Previously: Approximation  
Now: Interpolation with support

number of samples

$$n = \frac{\log(1 - p)}{\log(1 - (1 - \epsilon)^s)}$$

probability outlier free  
desired

sample size

probability outlier present

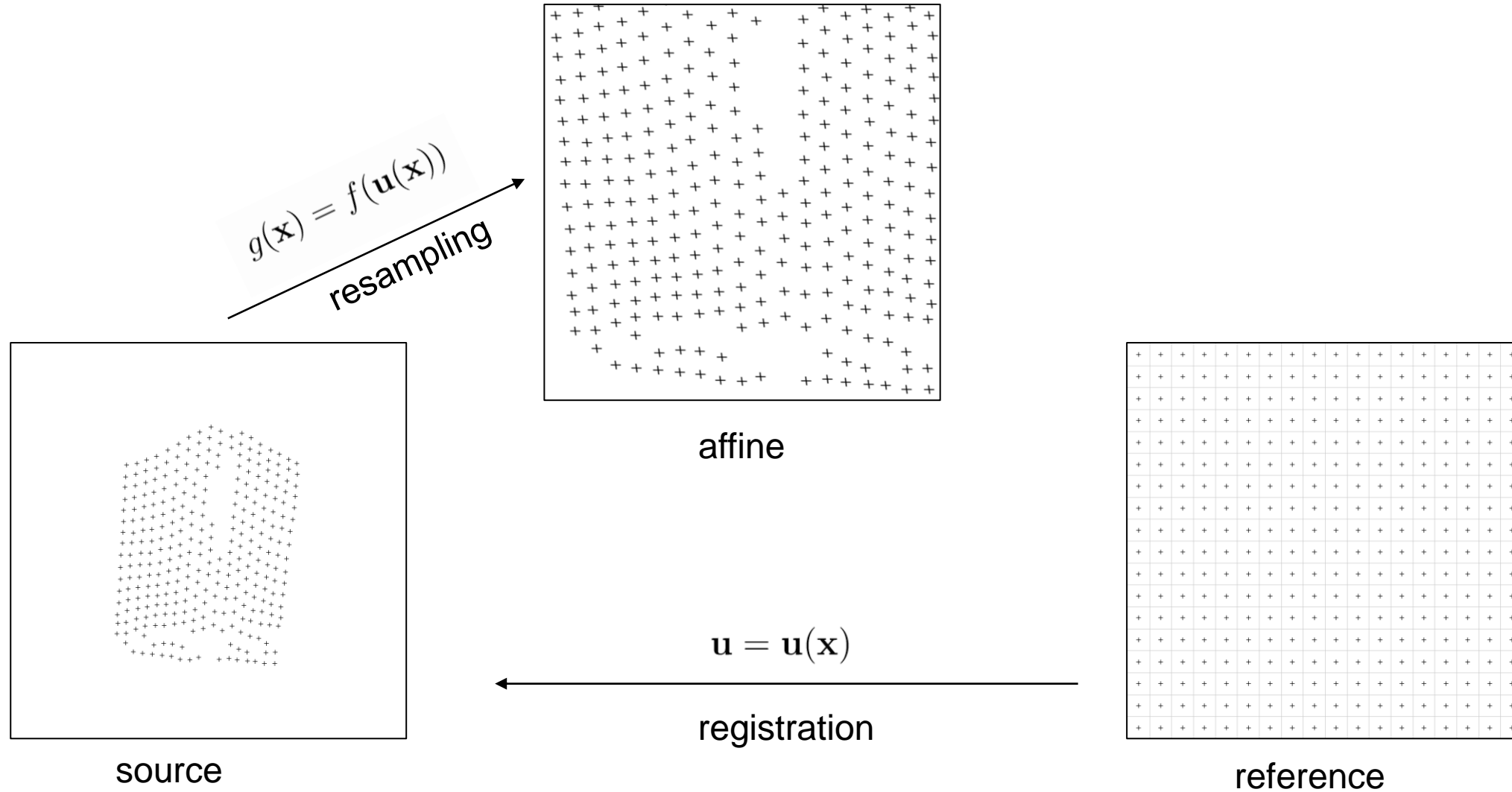
The goal of image registration is to find a spatial transform for a *source image* such that the highest similarity to a *reference image* is achieved. The measure of similarity between two images can be described with an objective function, which is then optimized. In [?] the first couple of chapters profoundly explain image registration. Concluding from this work, image registration has a strong presence in medical image processing. Amongst other problems it is used to

- assist in image segmentation,
- overlay preprocessed data from brain atlases,
- match functional and anatomical images to localize for example brain activity in  $^1fMRI$  or metastasis in  $^2PET/CT$ ,
- identify long term shape changes in brain tissue or to
- perform spatial normalization.

1. *within-modalities* where images have a linear relation between their intensities or
2. *between-modalities* where no relation between images' intensities is present.


1. *label-based* or
2. *intensity-based*

# Linear Registration



1. linear or

2. non-linear


$$\mathbf{y}(\mathbf{x}_i, \boldsymbol{\alpha}) = \sum_{m=1}^M \alpha_m \boldsymbol{\phi}_m(\mathbf{x}_i)$$

1. small or

2. large



## Projektplan: Key Point Detection using Neural Networks for Endoscopic 3D Reconstruction

Bearbeiter: Julian Zilker																																													
Betreuung: Andreas Kist																																													
Datum: 4/7/2020																																													
						Mar-20				Apr-20				May-20				Jun-20				Jul-20				Aug-20				Sep-20				Oct-20											
Phase	Nr.	Arbeitsabschnitt	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44								
Defintion	01	Orientierung																																											
	02	Methoden zur Erkennung und Registrierung erarbeiten																																											
	03	Kalibrierungsalgorithmus anpassen																																											
	04	Glabel Programm entwickeln																																											
Entwurf	05	Netzwerke implementieren																																											
	06	Daten Labeln																																											
Realisierung	07	Netzwerke trainieren																																											
	08	Bildverarbeitungskette aufbauen																																											
	09	Kalibrierungsalgorithmus einfügen																																											
	10	Rekonstruktionsalgorithmus einfügen																																											
Dokumentation	10	Software dokumentieren																																											
	11	Masterarbeit erstellen																																											
	12	Präsentation erstellen																																											
Begleitprozesse	13	Literaturrecherche																																											