Lecture 6-1

Softmax classification: Multinomial classification

Sung Kim <hunkim+mr@gmail.com>

Linear 하기 때문에 0이나 1로 고르는 것에 적합하지 않았어

$$H_{L}(x) = \underbrace{Wx}_{X} \left(\frac{1}{2} \right) = \begin{cases} 1 & \text{if } \\ 2 & \text{if } \end{cases}$$

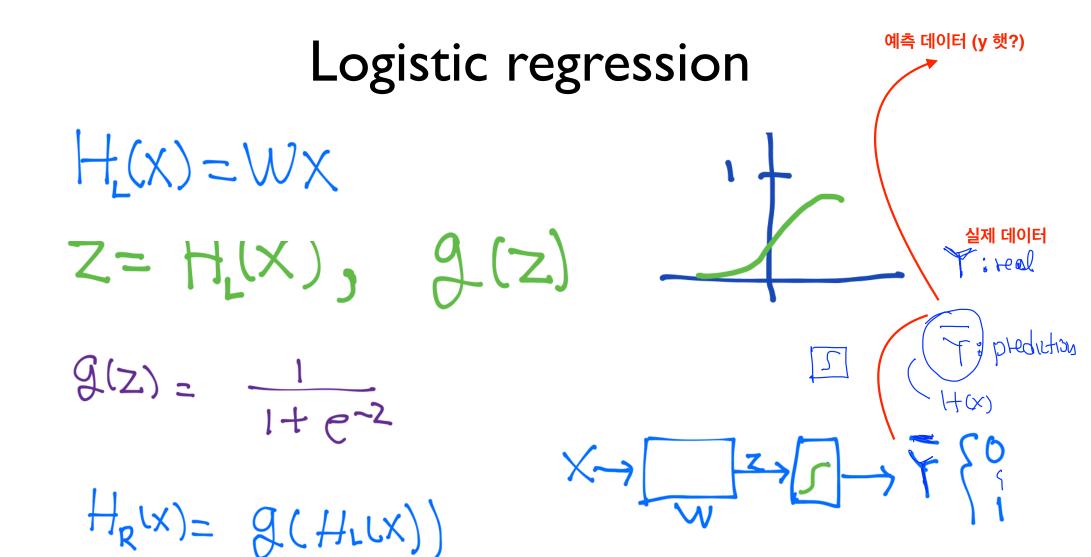
$$Z = H_{L}(x), \quad 2(z) = \begin{cases} 1 & \text{if } \\ 2 & \text{if } \end{cases}$$

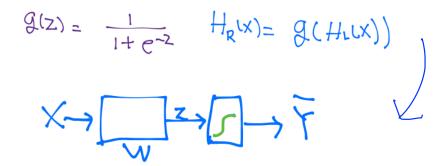
$$H_{L}(X) = WX$$

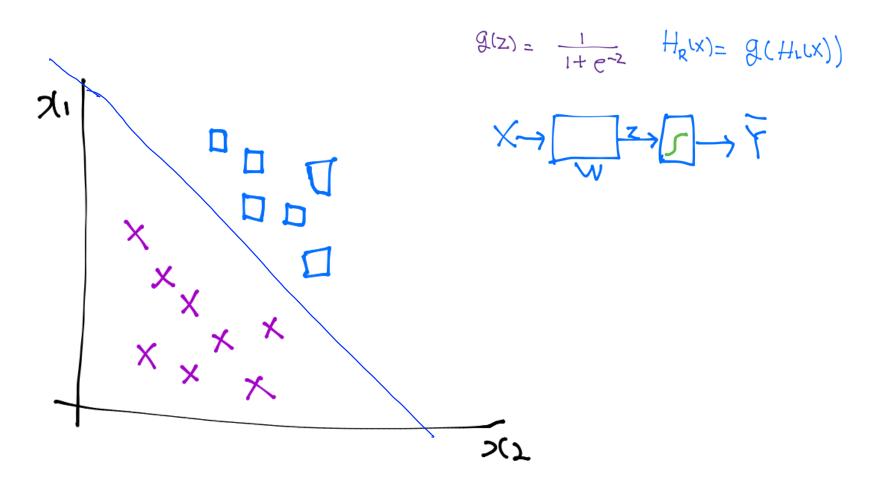
$$Z = H_{L}(X), \quad \mathcal{J}(Z)$$

$$\mathcal{J}(Z) = \frac{1}{1 + e^{-2}} \quad \text{logistic } \mathcal{L} = \text{sigmod } \mathcal{L} = \mathcal{L}$$

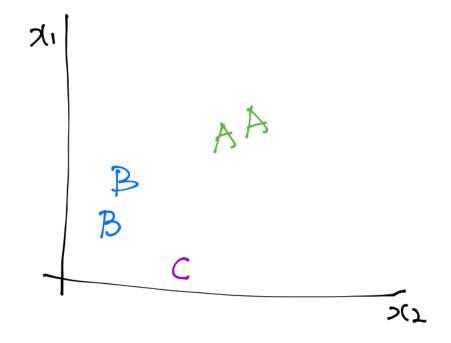
$$H_{R}(X) = \mathcal{J}(H_{L}(X))$$

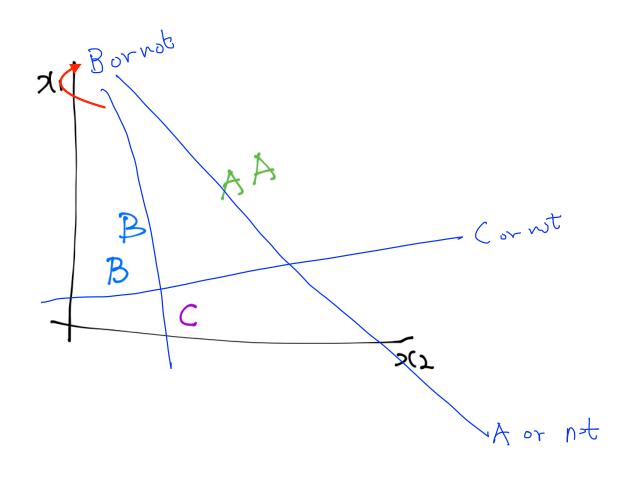






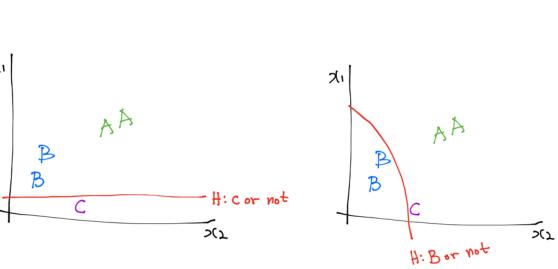
| x1 (hours) | x2 (attendance) | y (grade) |
|------------|--------------------|-----------|
| 10 | 5 | А |
| 9 | 5 | А |
| 3 | 2 | В |
| 2 | 4 | В |
| 11 | 1 | С |

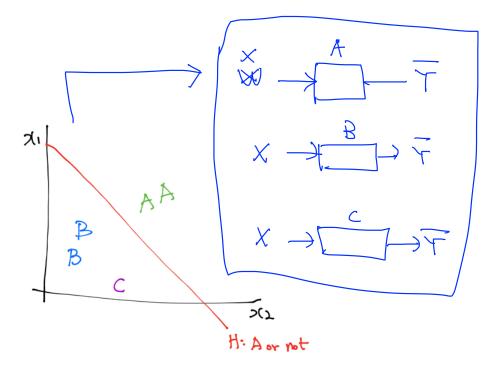


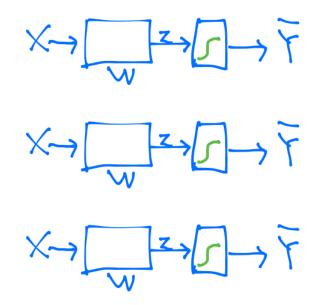


Multinomial classification अर निप्रकृष्ट मा यथ

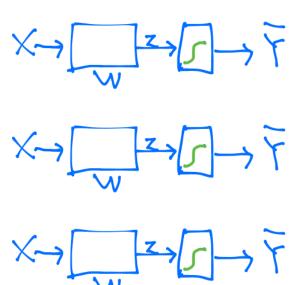
x가 주어졌을 때 각각 A, B, C 인지 아닌지 판단하는 독립된 classifier





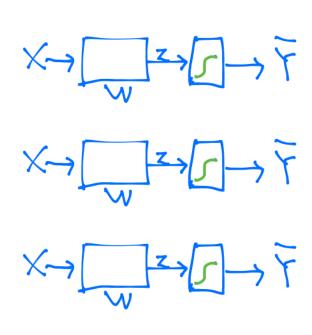


실제로 구현할 때는 행렬로

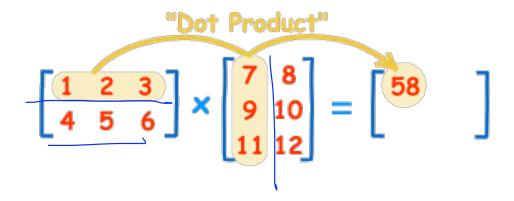


각각 구현하면 복잡해서 하나로 합친 후 구현

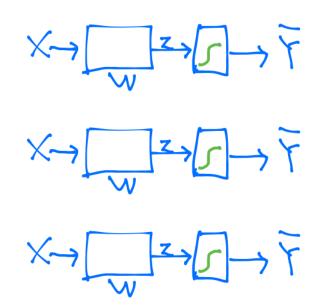
$$\begin{bmatrix} w_1 & w_2 & w_3 \\ w_4 & w_5 \\ w_{B_1} & w_{B_2} & w_{B_3} \\ w_{C1} & w_{C2} & w_{C3} \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_2 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_1 x_1 + w_2 x_3 + w_3 x_4 \\ x_3 \end{bmatrix}$$

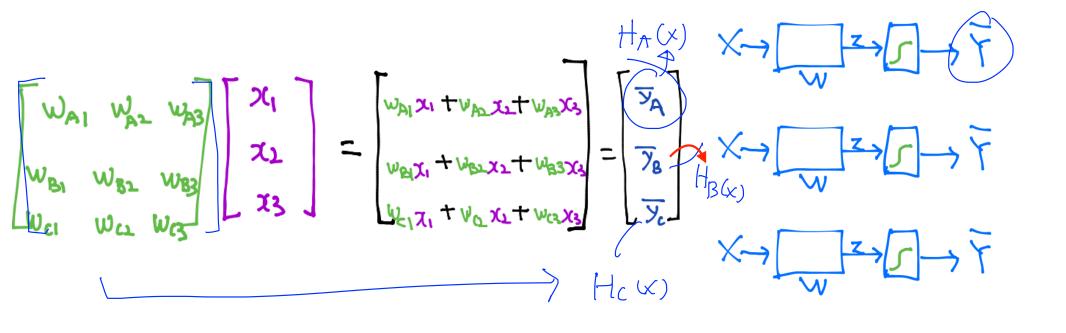


Matrix multiplication



https://www.mathsisfun.com/algebra/matrix-multiplying.html





Where is sigmoid?

